Computer Vision for HCI – From Smart Rooms to Vision for the Blind

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Computer Vision for HCI (Prof. Stiefelhagen) Institute for Anthropomatics & Robotics

Multimodal Interfaces in Alex` Labs ! (an incomplete snapshot)

- Alex also a pioneer in multimodal interfaces
- Face tracking
 - Hunke & Waibel 94, Yang & Waibel 96/98)
 - 3 papers > 1500 citations
- Lip-reading (from 1992/93)
 - Bregler, Hild, Manke, Duchnowski, Meier, Yang,
 - My first Hiwi-Job 1993 & BA-thesis 1995
- Emotions in speech
 - Dellaert, Polzin, Waibel 96 (>550 citations)
- Handwriting, NPEN, NPEN++ (from 1994)
 - Manke, Finke, Jäger, Reichert, Bodenhausen ... (>200 citations)
- Head pose and attention
 - Schiele & Waibel 1995
 - My master thesis ('96), doctoral thesis (2002)
- Multimodal dialogue, error repair, ...







AV-ASR: Bregler, Manke, Hild, Waibel 93





Multimodal Interfaces in Alex` Lab(s) (2)

- Computer-Vision for HCI team in KA (2001-2009)
 - Tracking (Bernardin), Gestures (Nickel), Face ID (Ekenel, Fischer, Gao), Head pose & attention (Voit)
- Multimodal human-robot interaction
 - SFB 588 Humanoid Robots (2001-2012)
 - AV-Tracking, face-ID, pointing gestures, gaze, speech + dialogue
- Context-Aware Rooms & Services
 - EU FP7: Computers in the Human Interaction Loop CHIL (2004-2007)
 - The Connector Context Aware Smart Office
 - Smart seminar & meeting rooms
 - CLEAR Evaluations together with NIST









Now: Computer Vision for HCI Lab

- Computer Vision for HCI Lab at KIT
 - (+ Perceptual User Interfaces Lab at Fraunhofer IOSB)
 - Visual perception of humans: tracking, identification, age, gender, facial expression, action recognition, ...
 - Interactive systems: Smart control rooms, driver monitoring, smart OP, sleeping labs / nursing homes, interaction with people with dementia
 - movie-analysis, video-surveillance
- Study Center for Visually Impaired Students (SZS)
 - Supports blind and partically sighted students at KIT
 - Provides accessibility to all courses, lecture materials, exams, math, software, …
- Mission: overcome barriers for the seeing impaired



🗾 Fraunhofer





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Computer Vision for HCI (Prof. Stiefelhagen)

Problem

- Ca. 285 Mio. visually impaired worldwide (~39 Mio. blind)
- Loss of sight leads to many difficulties
 - Orientation & mobility
 - Communication & social interaction
 - Information access, university, job
 - Activities of daily living (cooking, clothing, money, medicine, applicances, ...)

E.g. mobility:

- Three out of ten visually impaired never leave their homes alone (for elderly: 2 out of 3), 30% try to avoid unknown routes
- Reason: fear of accidents and orientation problems
- Interaction
 - Recognize who is there, who is looking at me, etc.

Computer Vision gives us new ways to assist!









Recognizing persons

Person detection and tracking

- Better, faster systems, already in use in cars
- Person identification,
- Age, gender, facial expression recognition
- Can be used

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- to support social interaction
- to avoid collisions











Object Recognition / ImageNet Challenge



- Very fast progress in object recognition
- E.g. Imagenet
- Top 5 error for 1000 class now < 5%</p>
- \rightarrow on par with human

Methods:

CNNs (of course)







Image & Video Captioning

A person riding a motorcycle on a dirt road.



Two dogs play in the grass.



A yellow school bus parked





"black and white dog jumps over bar."



"young girl in pink shirt is swinging on swing."

Methods: CNN + RNN



CNNs + RNNs

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Image & Video Question-Answering





What color are her eyes? What is the mustache made of?



Does it appear to be rainy? Does this person have 20/20 vision?

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S. Antol, et al. VQA: Visual Question Answering. In *ICCV* 2015. 03.08.2016 Computer Vision for the blind - InterACT-25 Symposium, Baden-Baden

LOTR: Return of the King

Why does Arwen wish to stay in Middle Earth?



She is too weak to travel

She wants to die on Middle Earth

Her son asked her to stay

Arwen sees her son in her visions

She likes Middle Earth

M. Tapaswi et al. MovieQA, In CVPR 2016.

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What are we going to do with it?

- Mobility and navigation support
 - Obstacles, crossings, buildings, entrances
- Social interaction support
 - Who is there, who is looking at me?
- Accessibility of lecture material
 images, diagrams, charts, ...





- How to design the interface?
 - Audio-tactile interfaces





TERRAIN: Mobility and Navigation support

- Funded by BMBF: July 2016 to June 2019
- Goal: Build a vision based assistive system for urban mobility
- Detect and tell (Computer Vision)
 - Free way vs. obstacles
 - Street lights and crossings
 - Specific buildings and entrances



- Have to investigate user interface (HCI)
 - How to tell directions, obstacles, scene information, etc.
 - Audio-tactile interfaces
 - Braille-interface
 - Smartphone as front-end











First steps: Accessible section detection



Accessible Section Detection for Visual Guidance

> MAP4VIP@ICME2013 3FPS with labeled ground truth

True PositiveTrue NegativeFalse PositiveFalse Negative

Accessible Section Detection for Visual Guidance

> MAP4VIP@ICME2013 3FPS with labeled ground truth

True PositiveTrue NegativeFalse PositiveFalse Negative

Accessible Section Detection for Visual Guidance

> MAP4VIP@ICME2013 3FPS with labeled ground truth

True Positive True Negative False Positive False Negative

Accessible Section Detection for Visual Guidance

> MAP4VIP@ICME2013 3FPS with labeled ground truth

True Positive False Positive True Negative False Negative

Zebra-Crossing Detection



- Important for safe street crossing
- In aerial images
 - To enhance Open Street Map data





Also from mobile cam



Method	Precision	Recall	Accuracy	AvgPrec.
HOG ^{30x30} -lin	74.8	93.1	92.4	94.43
HOG ^{20x20} -RBF	95.2	96.2	98.9	97.99
$LBP^{17/10}$ -lin	99.4	97.4	98.4	99.56
LBP ^{17/10} -RBF	99.7	97.0	98.3	99.56

Koester & Stiefelhagen, ICCHP 2016

Traffic lights / buttons / crossings

Collected and annotated training set

 Evaluated various features & classifiers
 HOG, LBP, LBPH, DeCaf, SVM, boosting, saliency, ...

Crop-classification works well

- Walklight: 0.97 (AUC)
- Buttons: 0.95 (AUC)
- However, not yet good enough for real application (detection)
 - Too many FP
 - Further work needed ...



walklights

buttons

Tactile vs. Audio output for obstacle avoidance

- Obstacle course 20 x 5m
- Audio vs. Tactile feedback on white cane
- Six users: 3 blind, 3 vis. impaired
- Evaluation using NASA TLX

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- Blind users (trained white cane users) strongly preferred haptic output
- Partially sighted users preferred audio







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Positioning of vibro-tactile actuators

- Wizard-of-Oz experiments
 - Find a book in the cabinet
 - Navigate through some obstacles
- Placement on palm below finger works well, also back-side between thumb and pointing finger
- Vibratation-feedback along direction to go seems mor intuitive than indicating the obstacle
- Tactile belt







Social interaction support

- BMBF funded project AVVIS
- Tell blind user who is there, who is looking at him / her
- Computer vision modules ready
- Now investigating audio-tactile output variants

- Motivated by a survey: 24 out of 25 users
 - would like to get visual information about other person
 - Would like to know when other person is looking at him/her
 - Would like to get info about facial expressions

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Some more things







Summary

- Computer vision gives new possibilities to build AT for the visually impaired
 - Rapid progress in computer vision
- Need to design and adapt the interface
 - Audio: speech, sounds, earcons, ...
 - Vibro-Tactile: positioning, which patterns, ...
 - Provide flexibility
- Important to work with your blind / vip user groups
 (not blinfolded Ph.D. students!)
- Things need to be integrated, robust, fast
- Dream: have everything run on your smart phone (affordable & cool)

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