

Beyond inspiration: Five lessons from biology on building intelligent machines

Bruno Olshausen

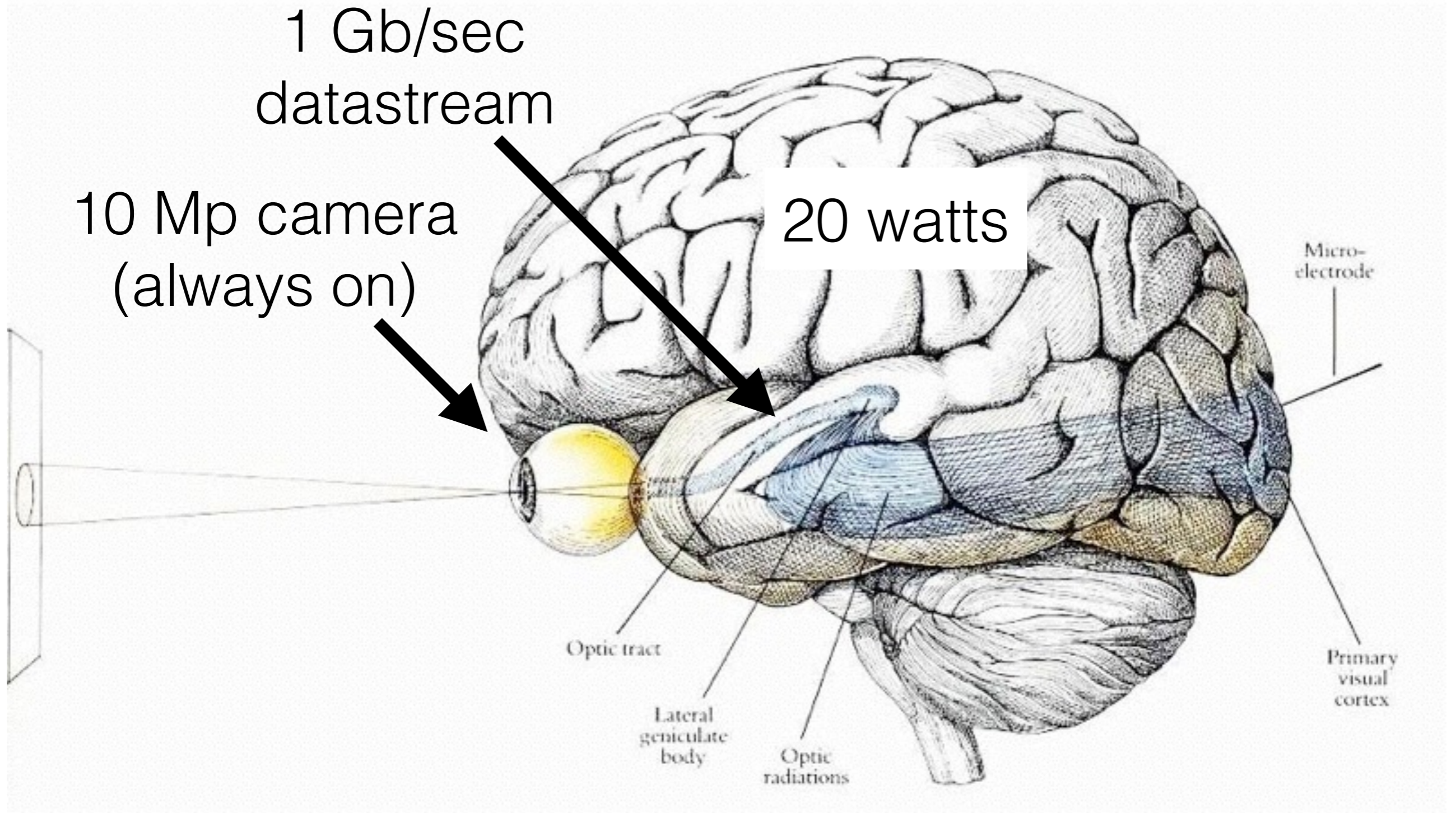
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Redwood Center for Theoretical Neuroscience
UC Berkeley



REDWOOD CENTER
for Theoretical Neuroscience



What are the principles governing information processing in this system?



Inspiration is a good start ...but not enough

Real progress will require gaining a more solid understanding of the principles of information processing at work in nervous systems.

This is both engineering *and* biology.

Five lessons from biology

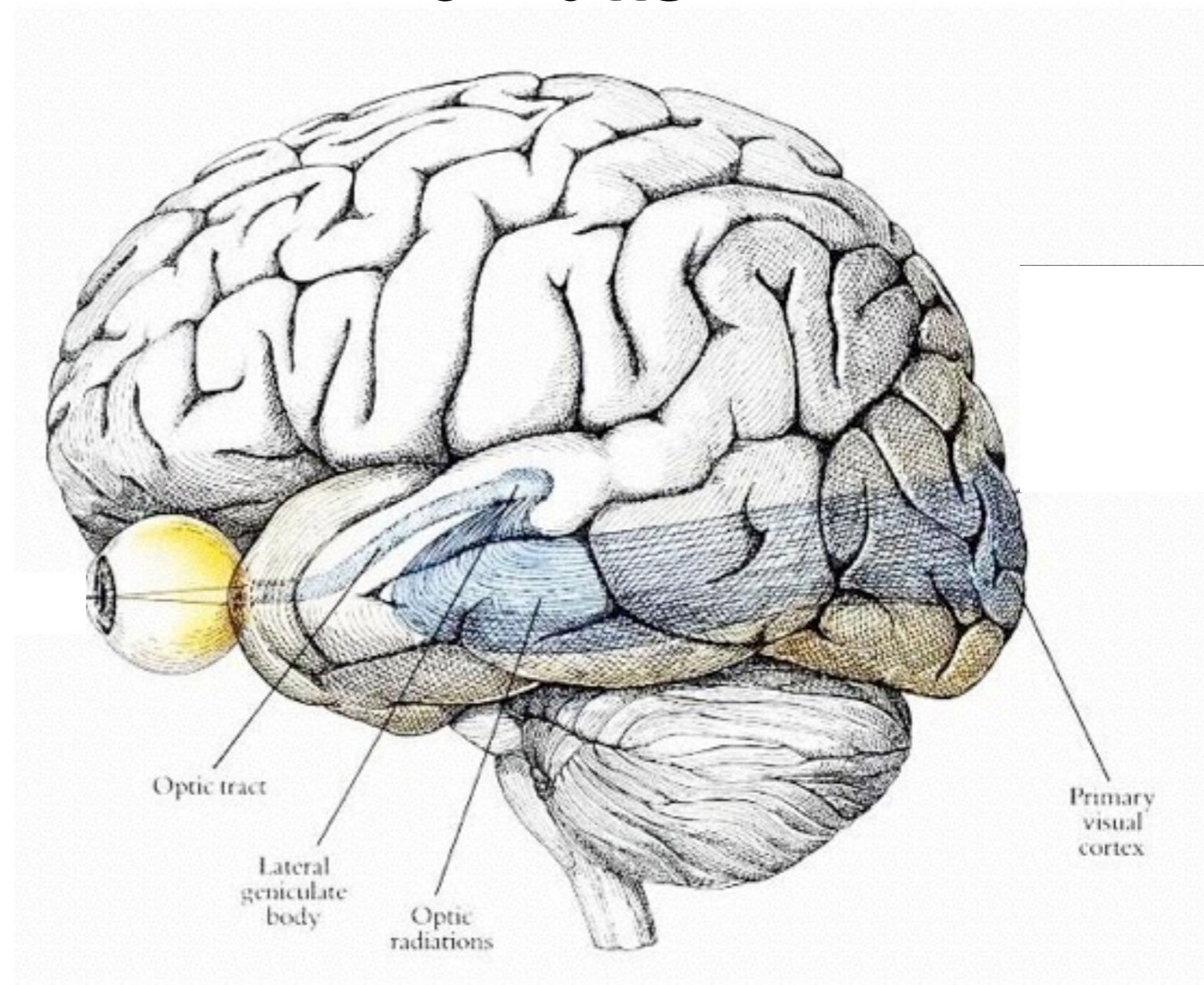
- Tiny brains
- Nonlinear processing in dendritic trees
- Sparse, overcomplete representations
- Feedback
- Active perception

1. Tiny brains

<1 million neurons
< 1 mW



86 billion neurons
20 Watts

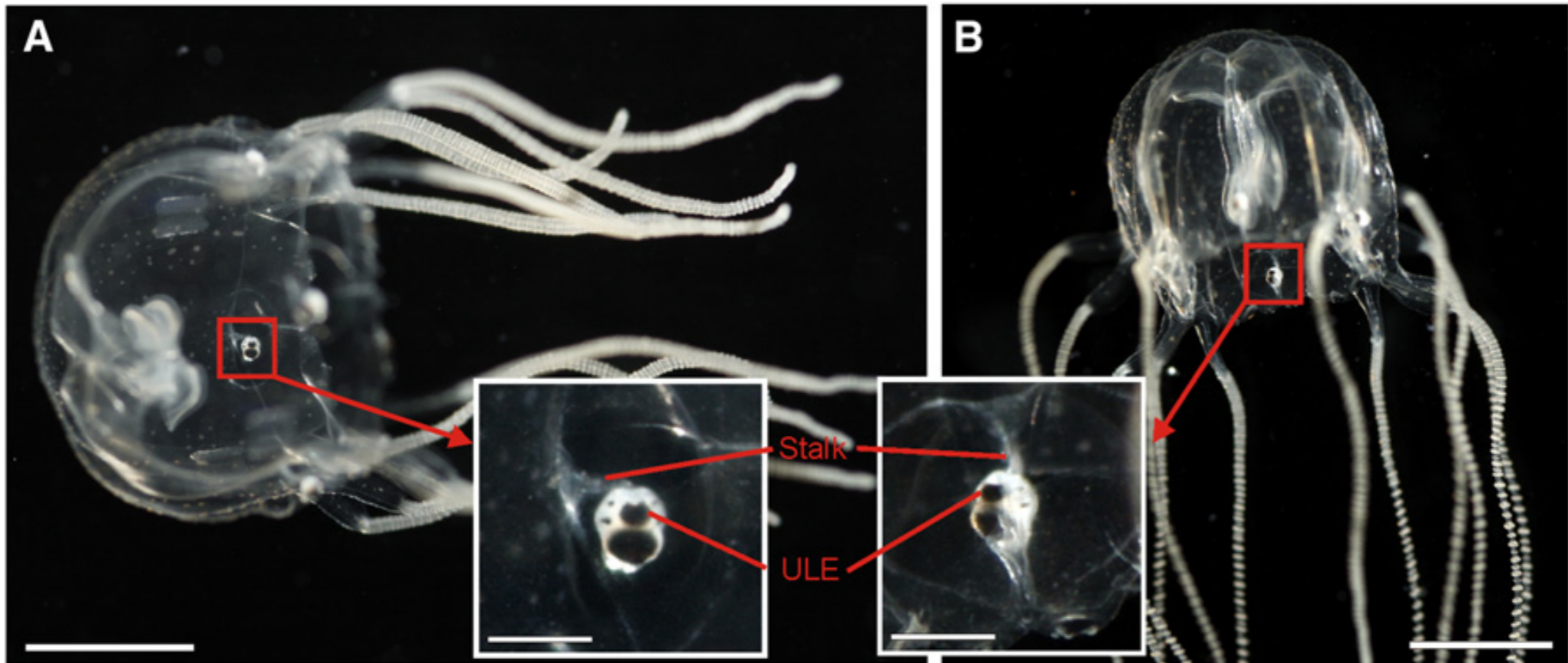




jumping spider



sand wasp



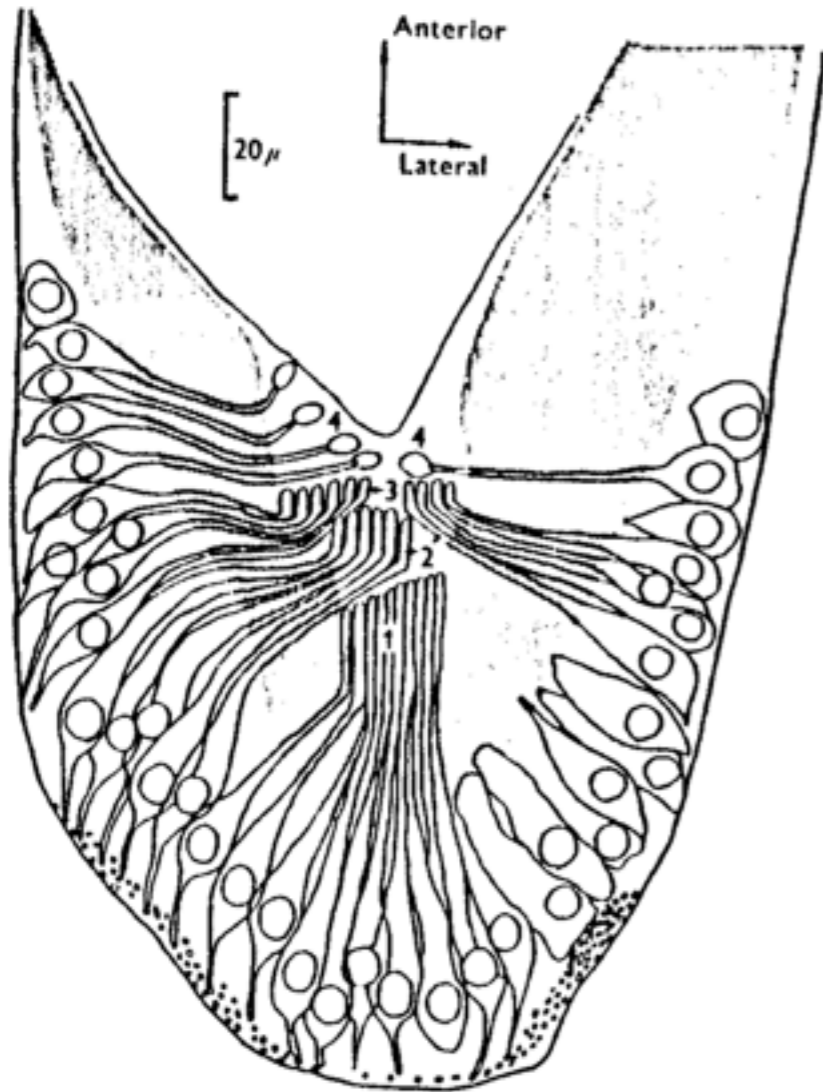
box jellyfish

Jumping spider visual system

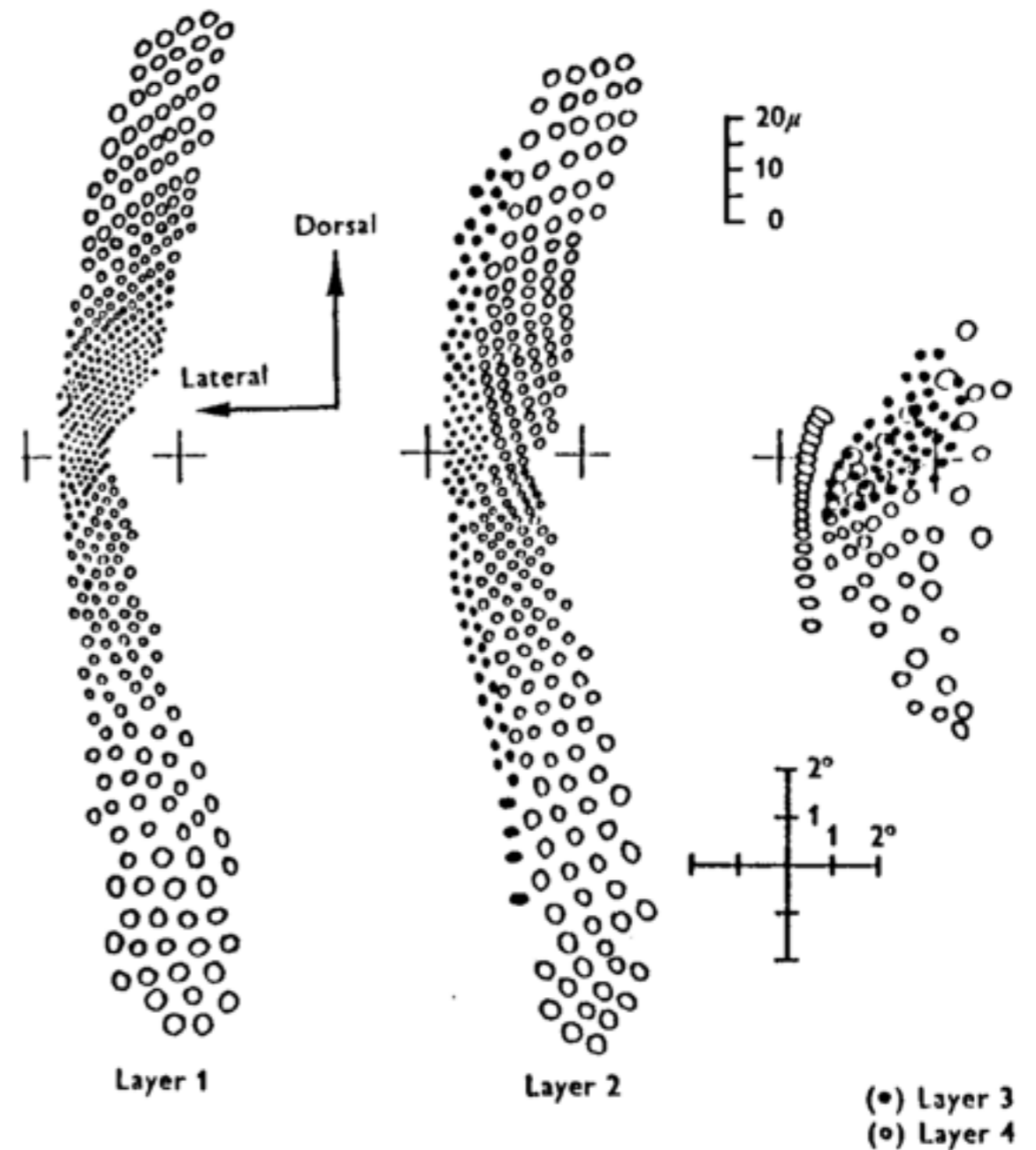


Jumping spider retina

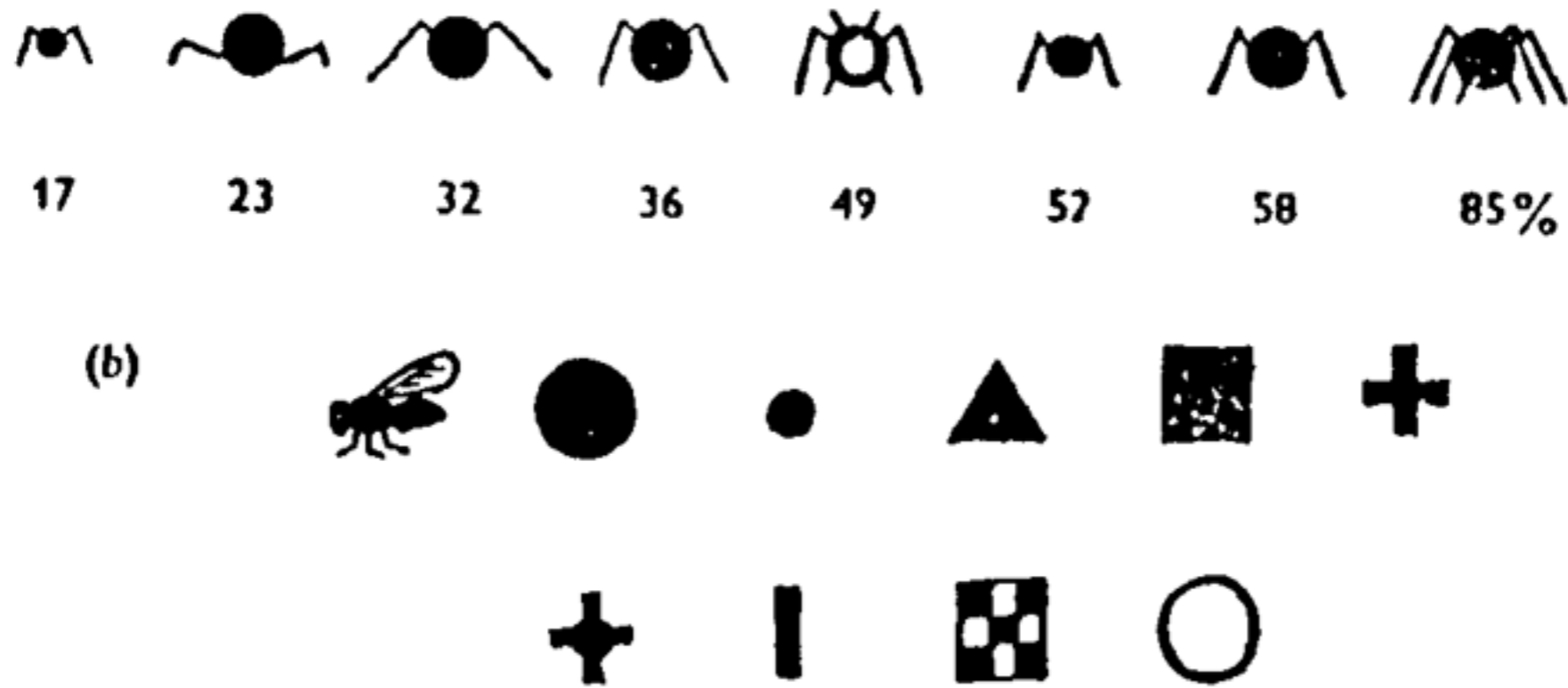
horizontal section



photoreceptor array

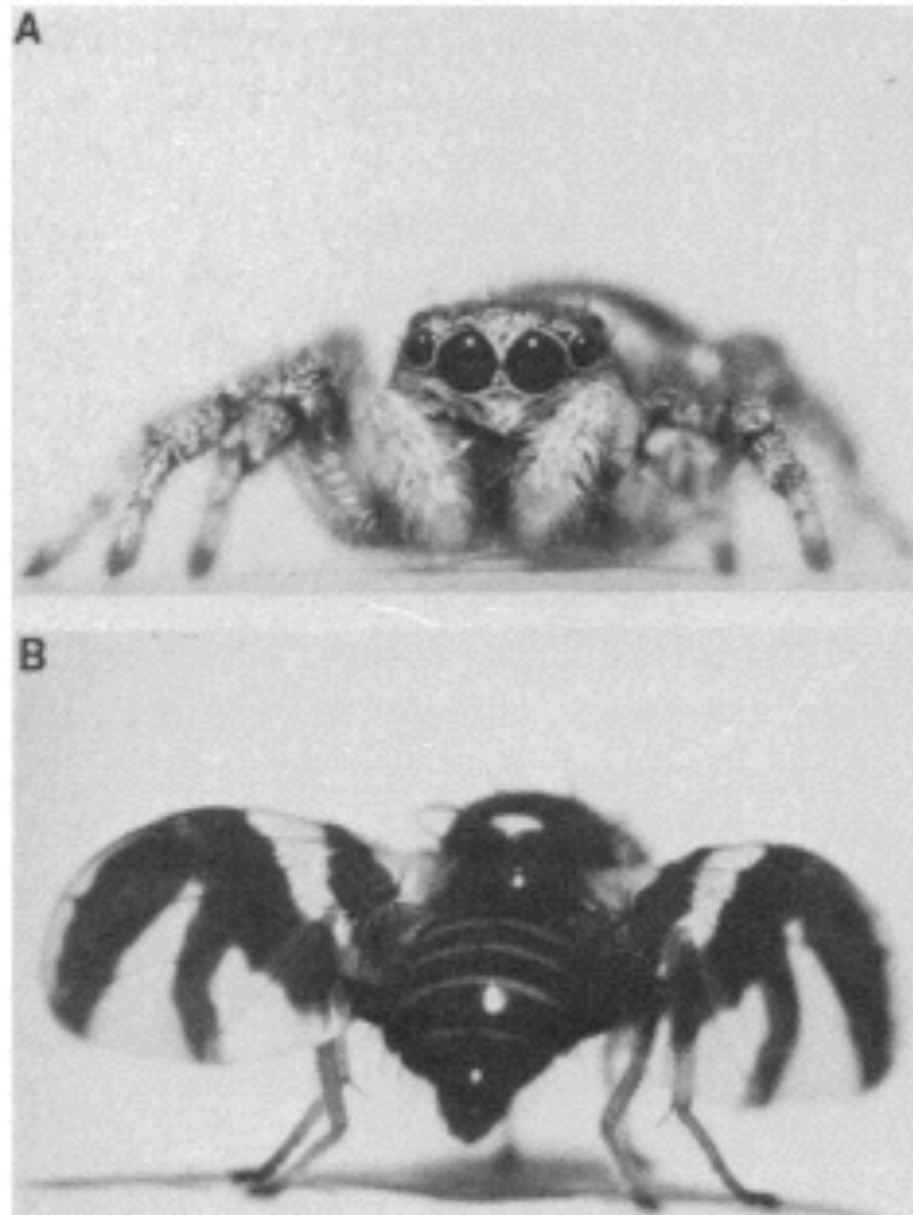


Jumping spiders do object recognition



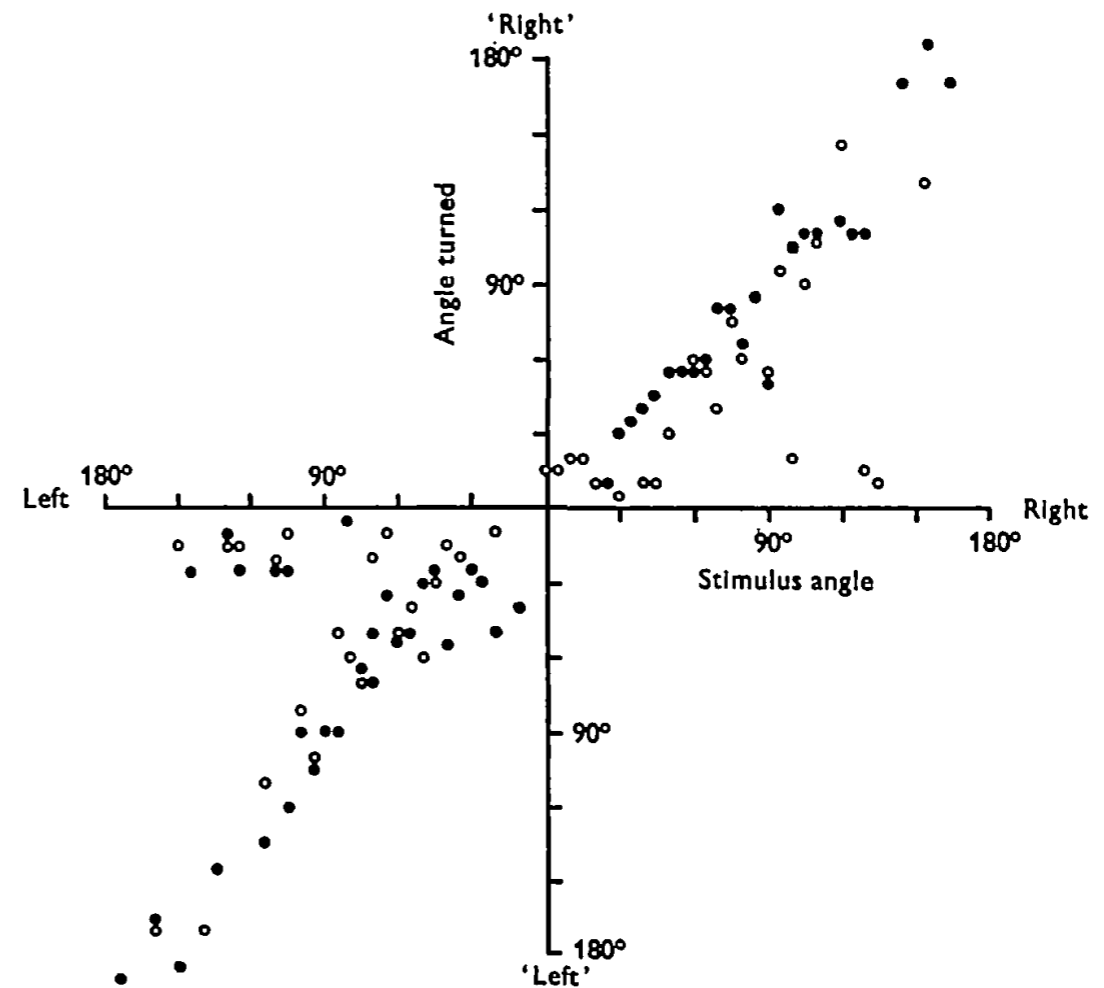
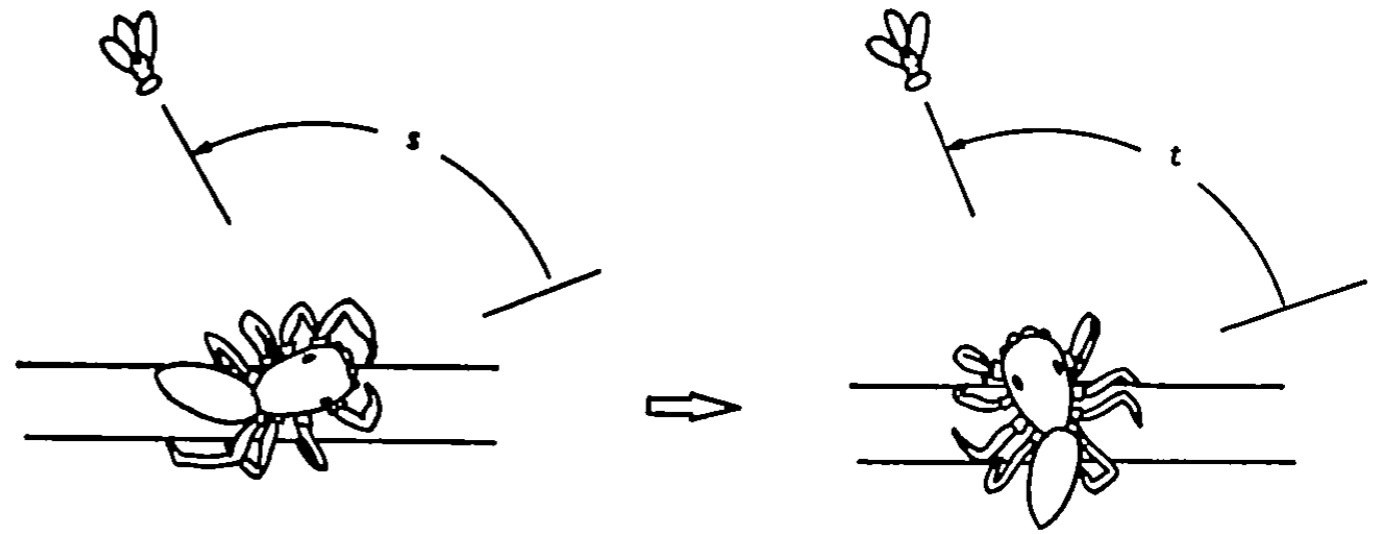
Text-fig. 12. Stimuli found by Drees to evoke courtship (a) and prey capture (b) in male jumping spiders (*Epiblemum scenicum*). The numbers beneath each figure in (a) are the percentage of trials on which courtship was evoked. After Drees (1952).

Spider mimicry in flies



Prey capture

- attention
- orienting
- tracking



Navigation

(Tarsitano & Jackson 1997)

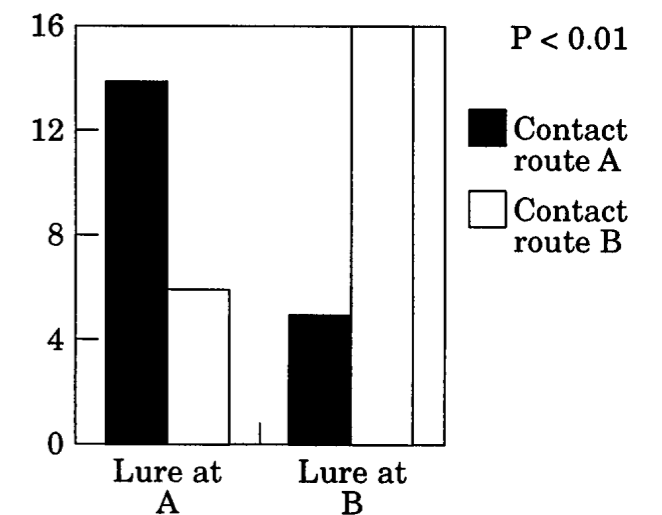
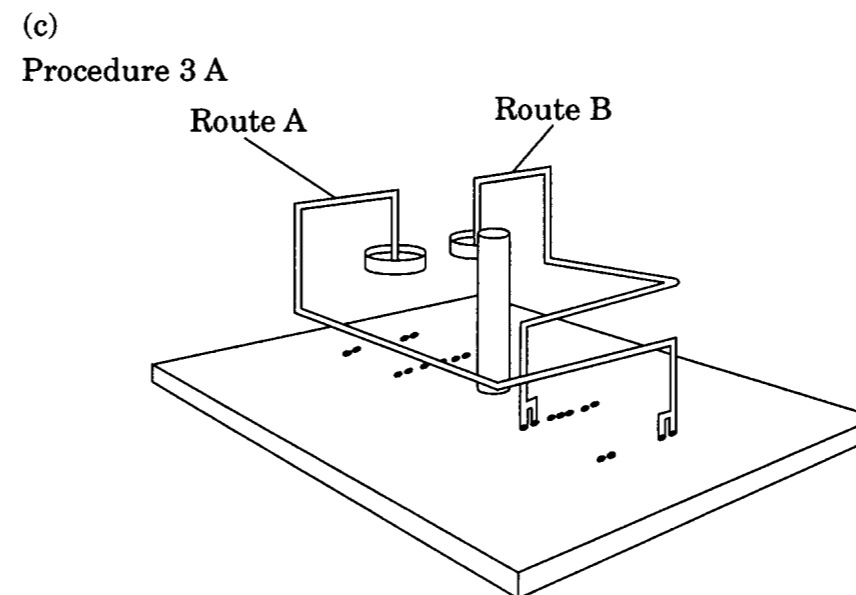
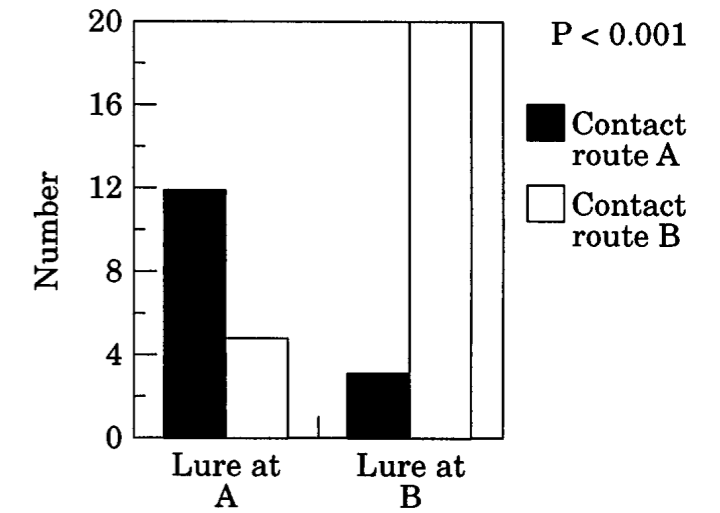
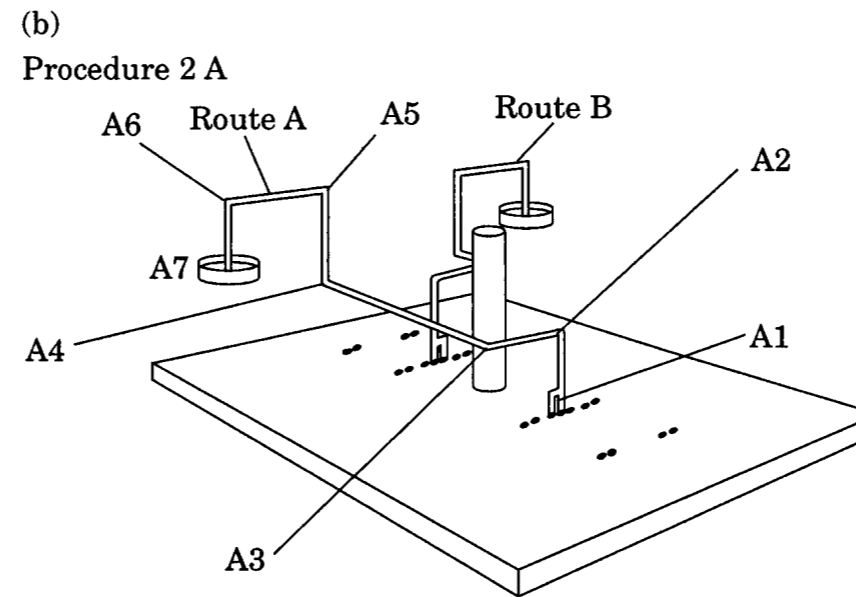
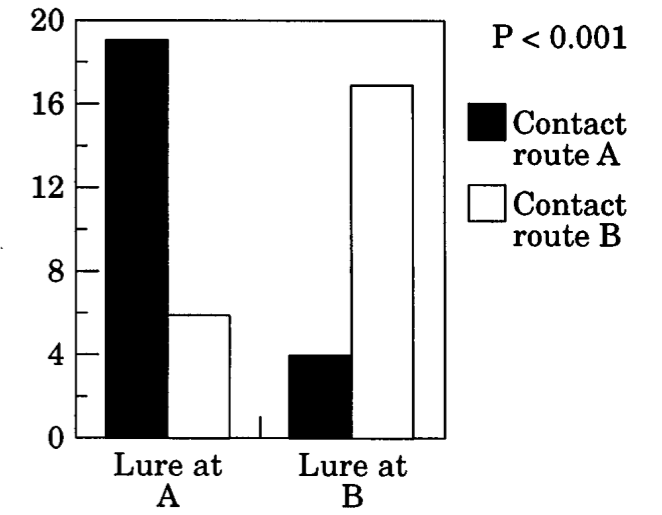
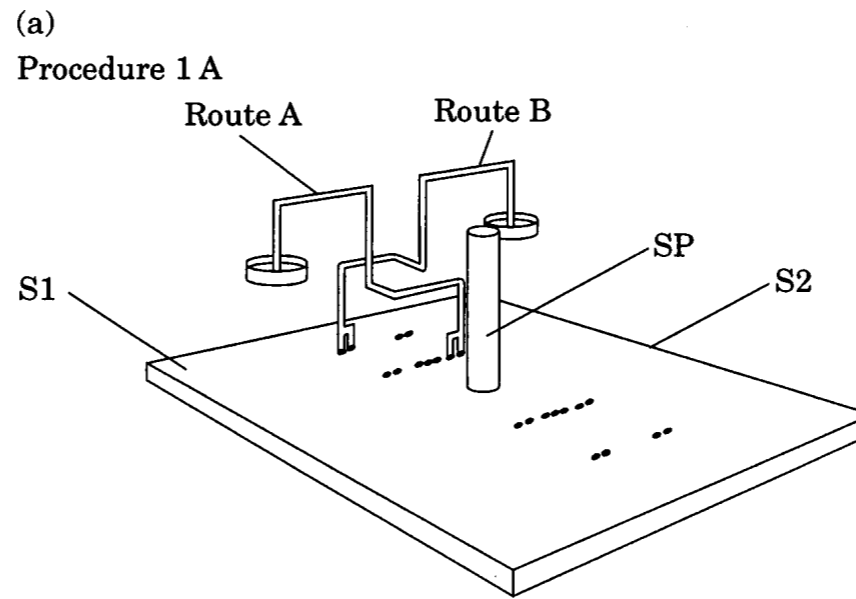
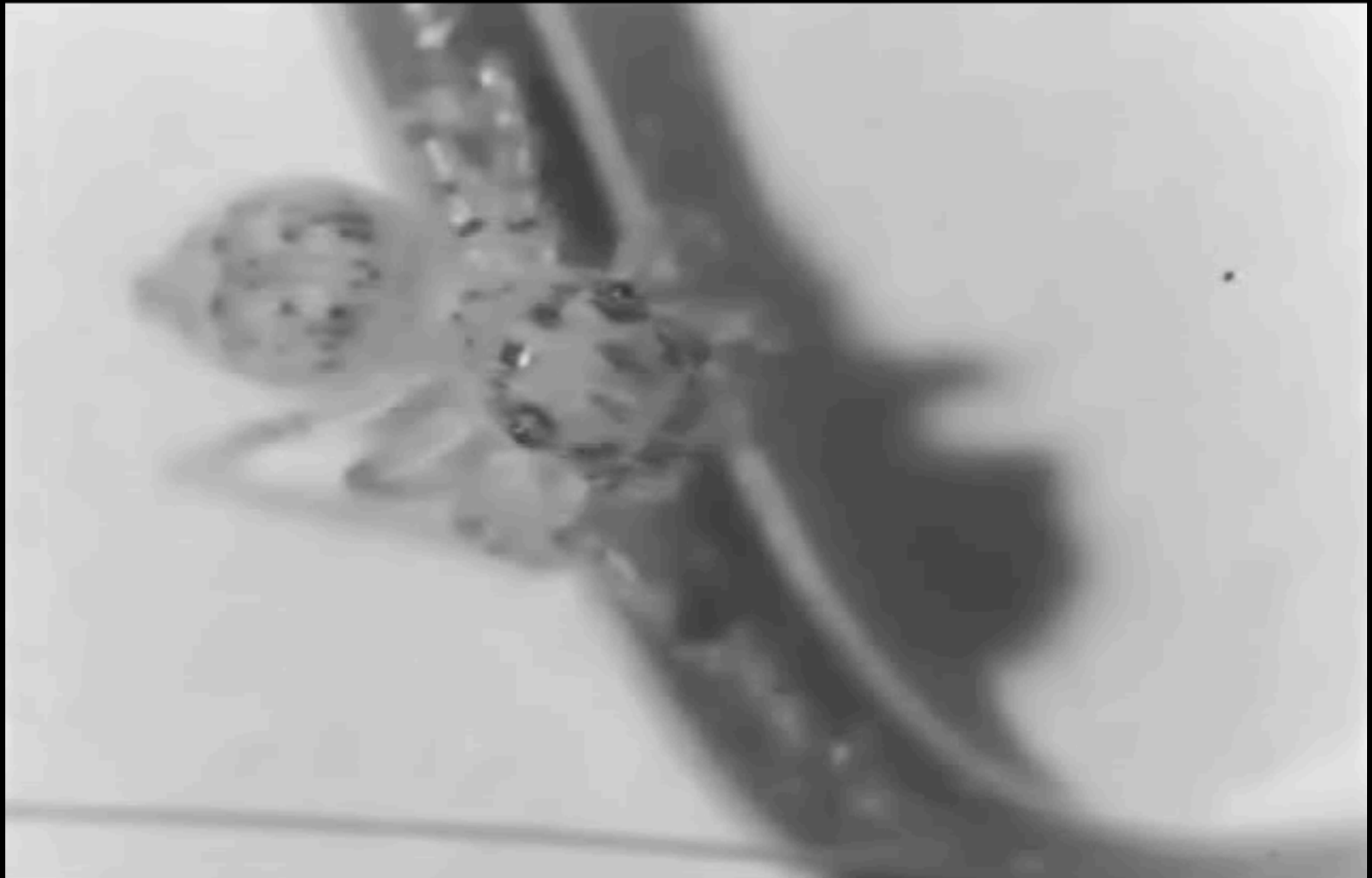


Figure 1 a-c.

One-day old jumping spider
(filmed in the Bower lab, Caltech)



One-day old jumping spider
(filmed in the Bower lab, Caltech)



One-day old jumping spider
(filmed in the Bower lab, Caltech)



One-day old jumping spider
(filmed in the Bower lab, Caltech)



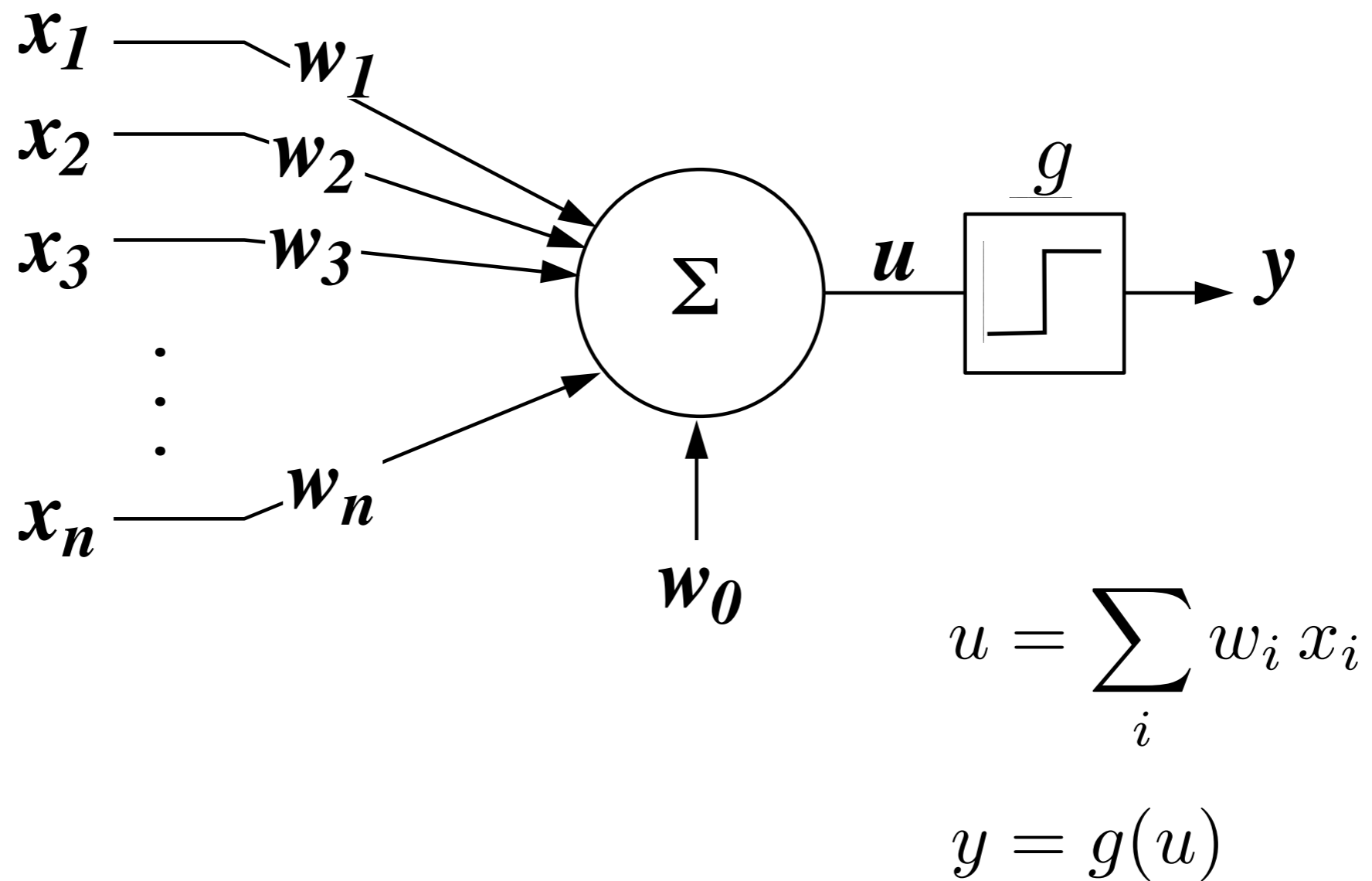
...problem solving behavior, language, expert knowledge and application, and reason, are all pretty simple once the essence of being and reacting are available. That essence is the ability to move around in a dynamic environment, sensing the surroundings to a degree sufficient to achieve the necessary maintenance of life and reproduction. This part of intelligence is where evolution has concentrated its time—it is much harder.

— Rodney Brooks, “Intelligence without representation,”
Artificial Intelligence (1991)

2. Nonlinear processing in dendritic trees

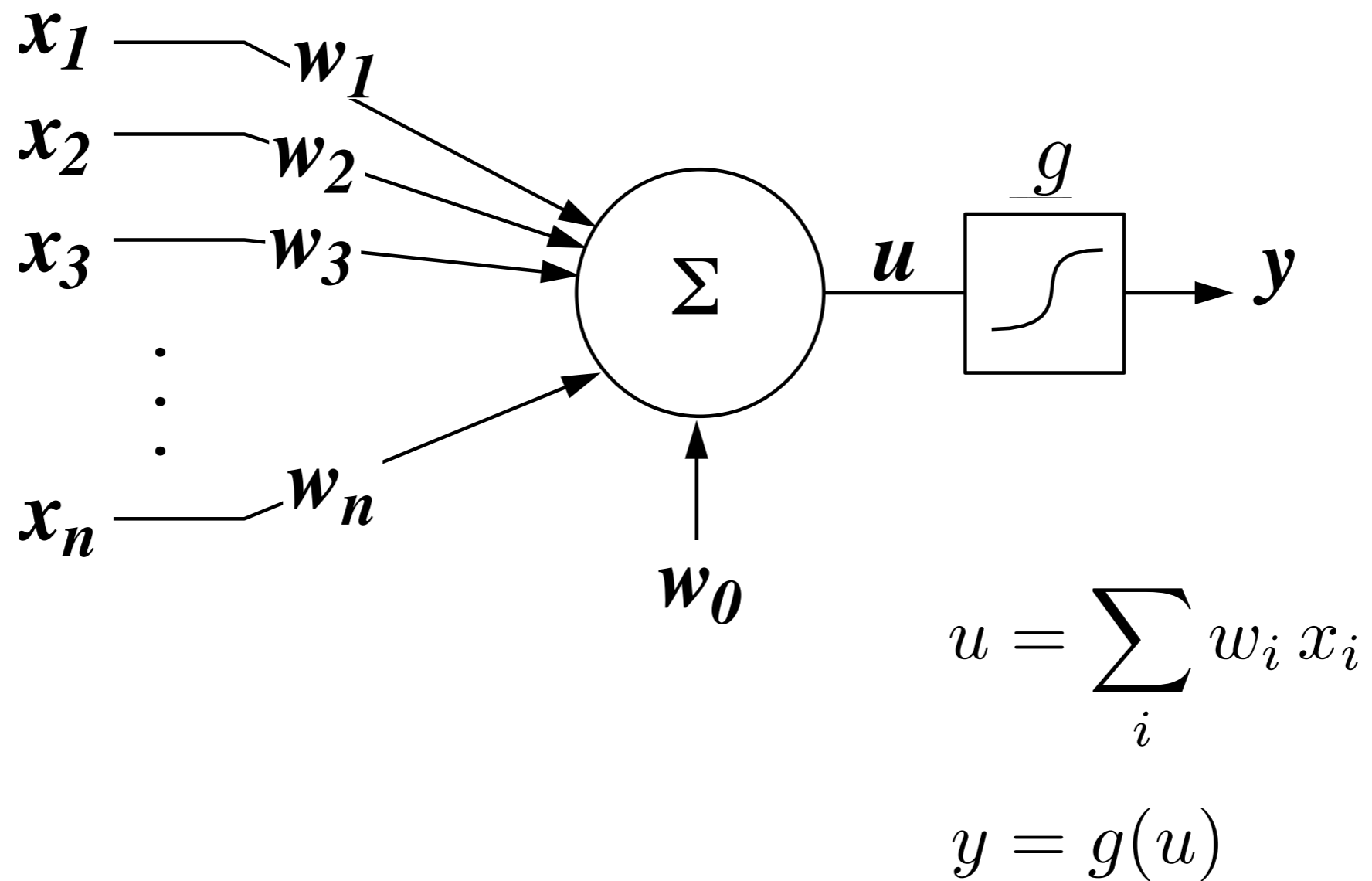
A brief history of neural networks

1960's



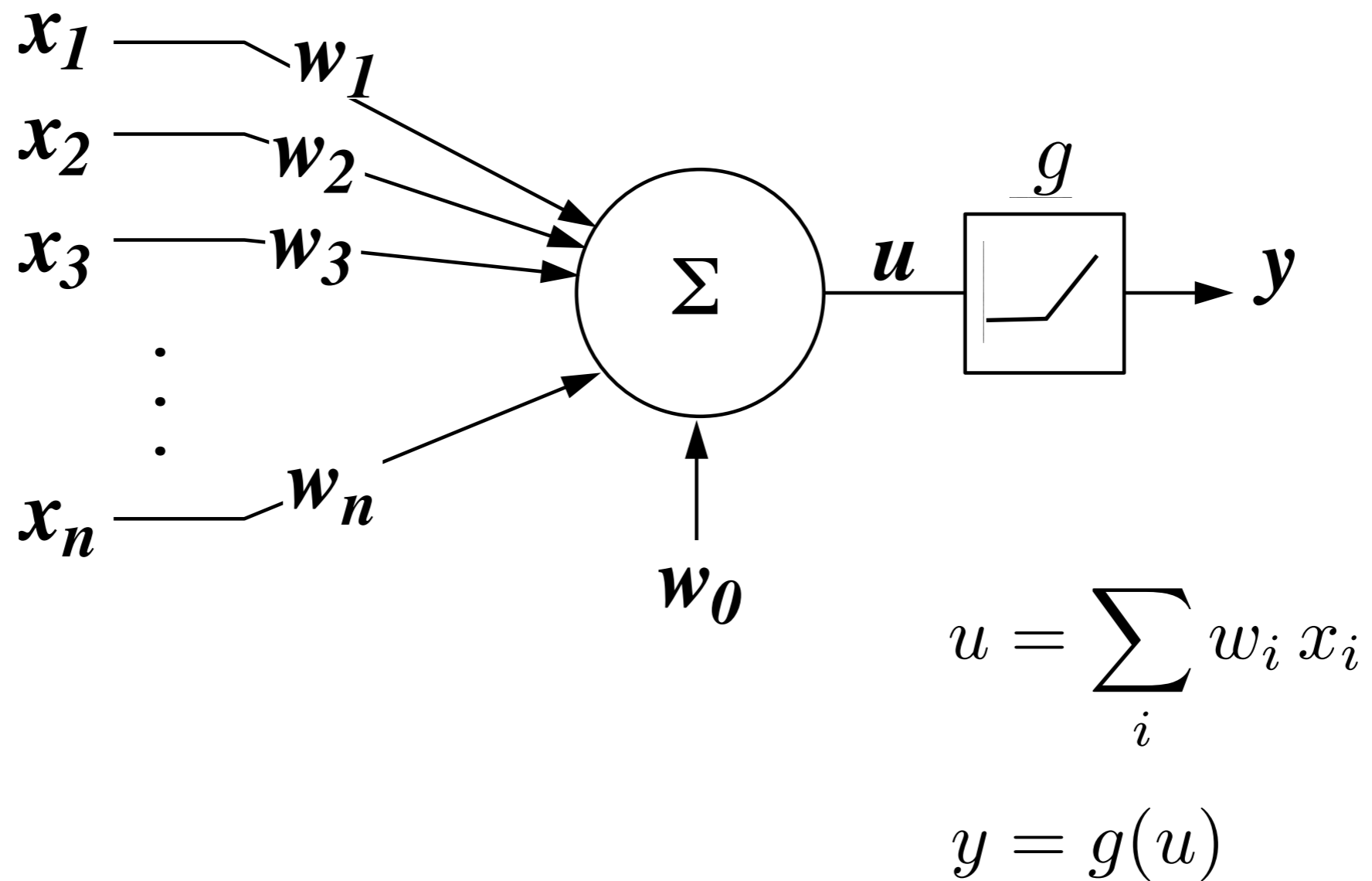
A brief history of neural networks

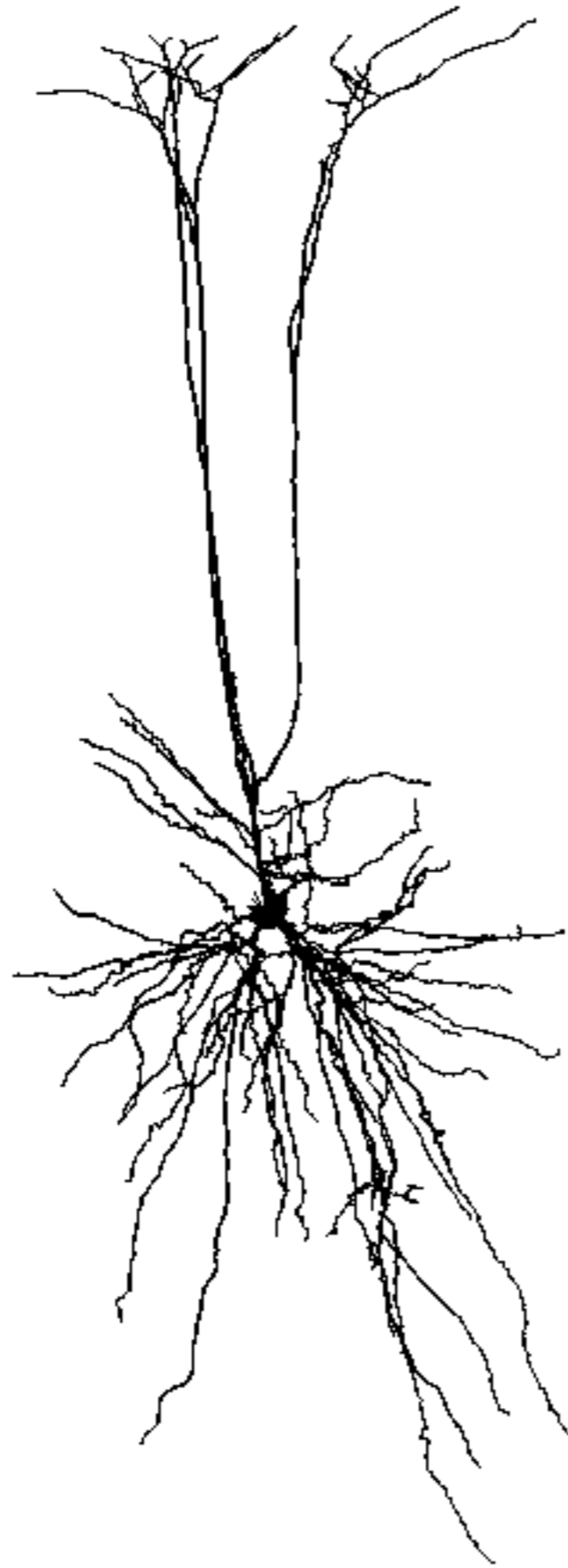
1980's



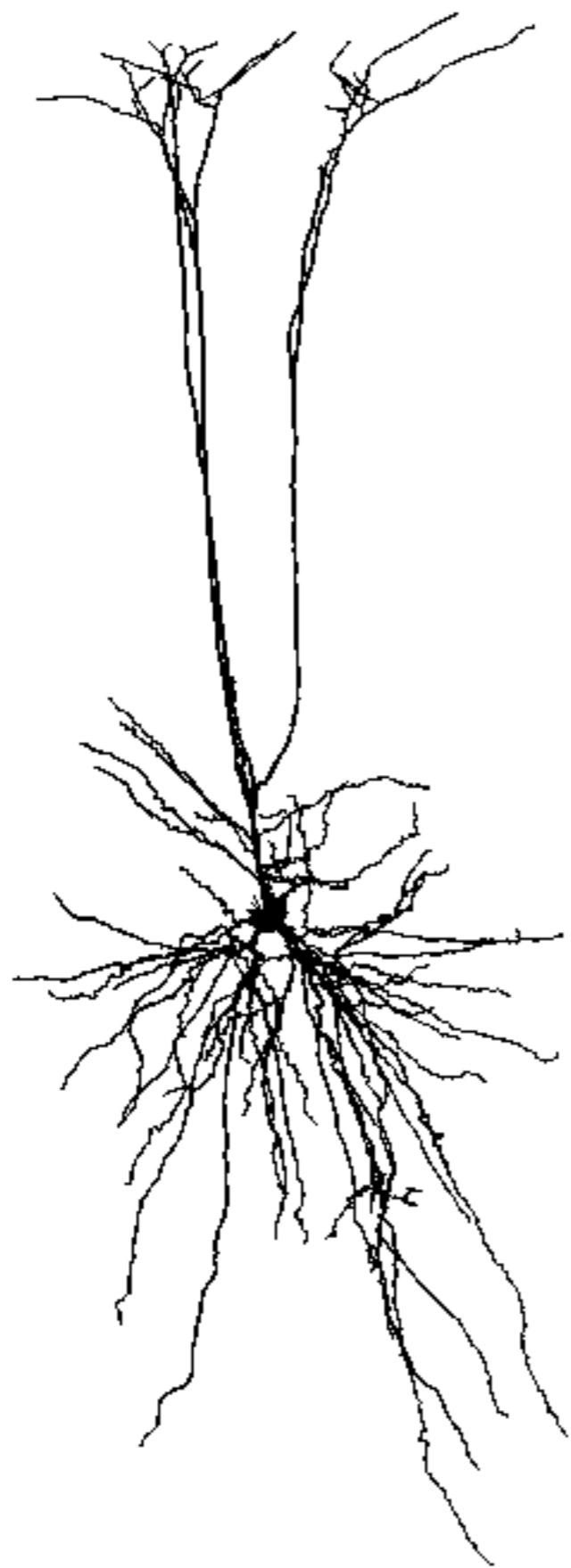
A brief history of neural networks

2000's





$$\neq g\left(\sum_i w_i x_i\right)$$



$$\sim g\left(\sum_i w_i \prod_{j \in G_i} x_j\right)$$



Bartlett Mel

Mel BW, Koch C. (1990). Sigma-pi learning: on radial basis functions and cortical associative learning. In *Advances in neural information processing systems, vol. 2*, D.S. Touretzky, (Ed.), San Mateo, CA: Morgan Kaufmann, pp. 474-481.

Mel BW. (1994). Information processing in dendritic trees. *Neural Computation, 6*, 1031-1085.

Polsky, A., Mel BW, Schiller J. (2004). Computational subunits in thin dendrites of pyramidal cells. *Nature Neuroscience, 7*, 621-627.

Hausser M, Mel B. (2003). Dendrites: bug or feature? *Current Opinion in Neurobiology, 13*, 372-83.

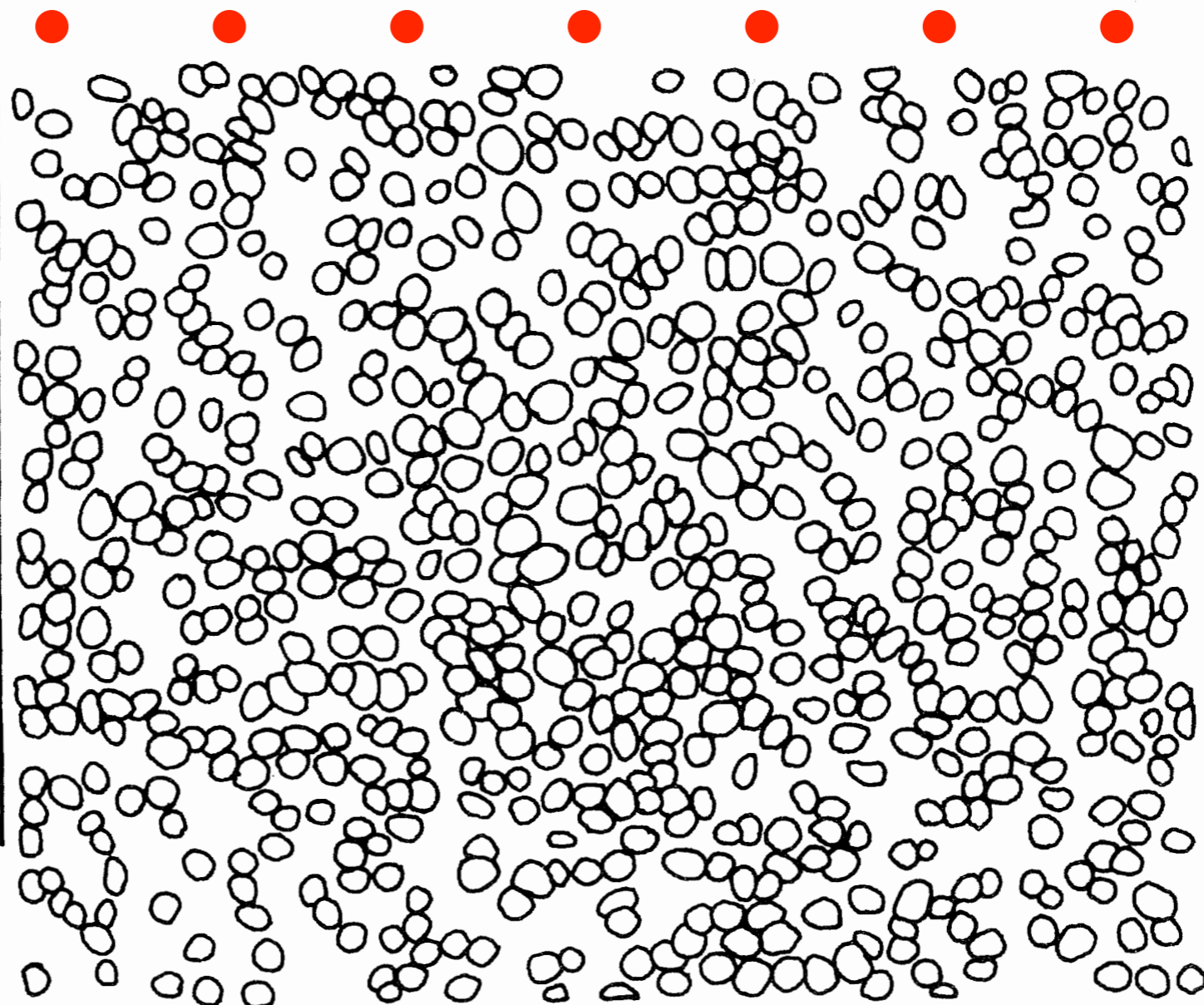
Poirazi P, Brannon T, Mel BW. (2003). Arithmetic of Subthreshold Synaptic Summation in a Model CA1 Pyramidal Cell. *Neuron, 37*, 977-987.

Poirazi P, Brannon T, Mel BW. (2003). Pyramidal Neuron as 2-Layer Neural Network. *Neuron, 37*, 989-999.

3. Sparse, overcomplete representation

VI is highly overcomplete

LGN
afferents

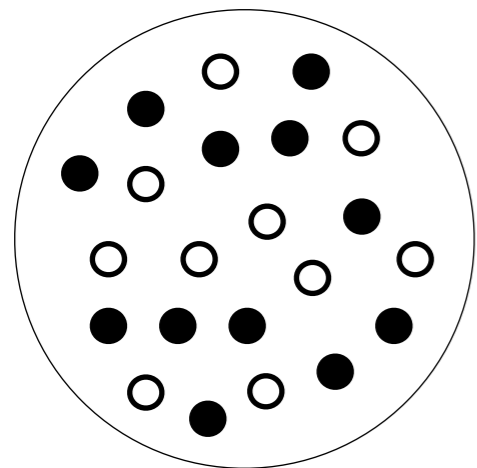


layer 4
cortex

0.1 mm

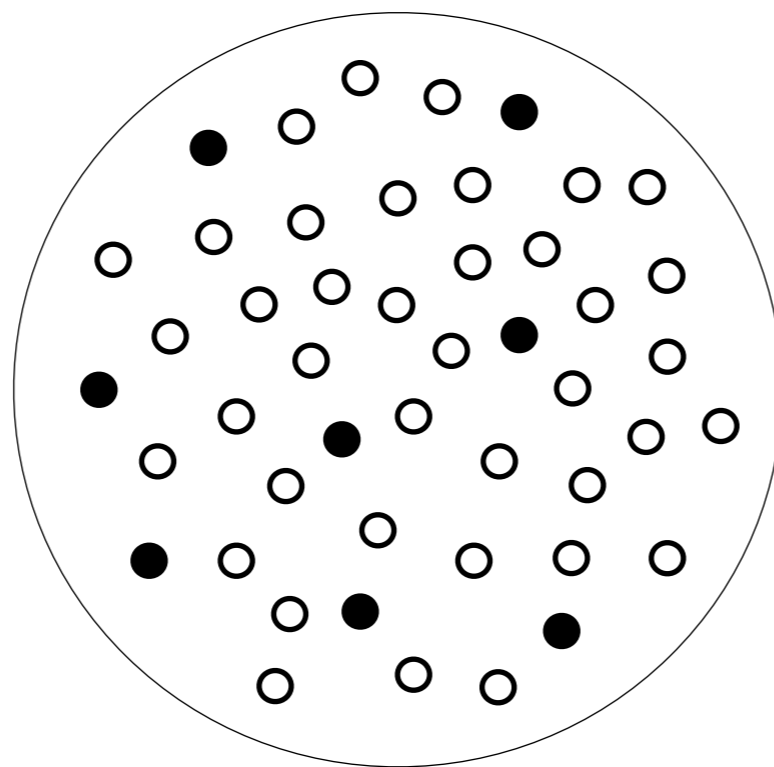
Barlow (1981)

Dense codes
(e.g., ascii)



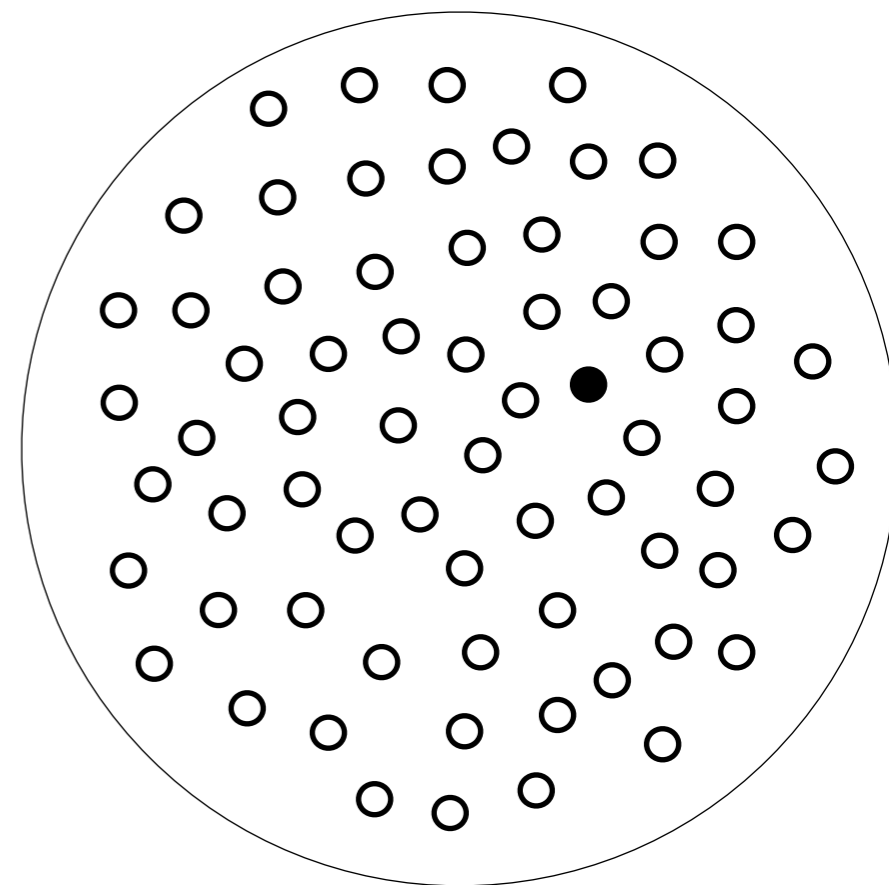
$$2^N$$

**Sparse,
distributed codes**



$$\binom{N}{K}$$

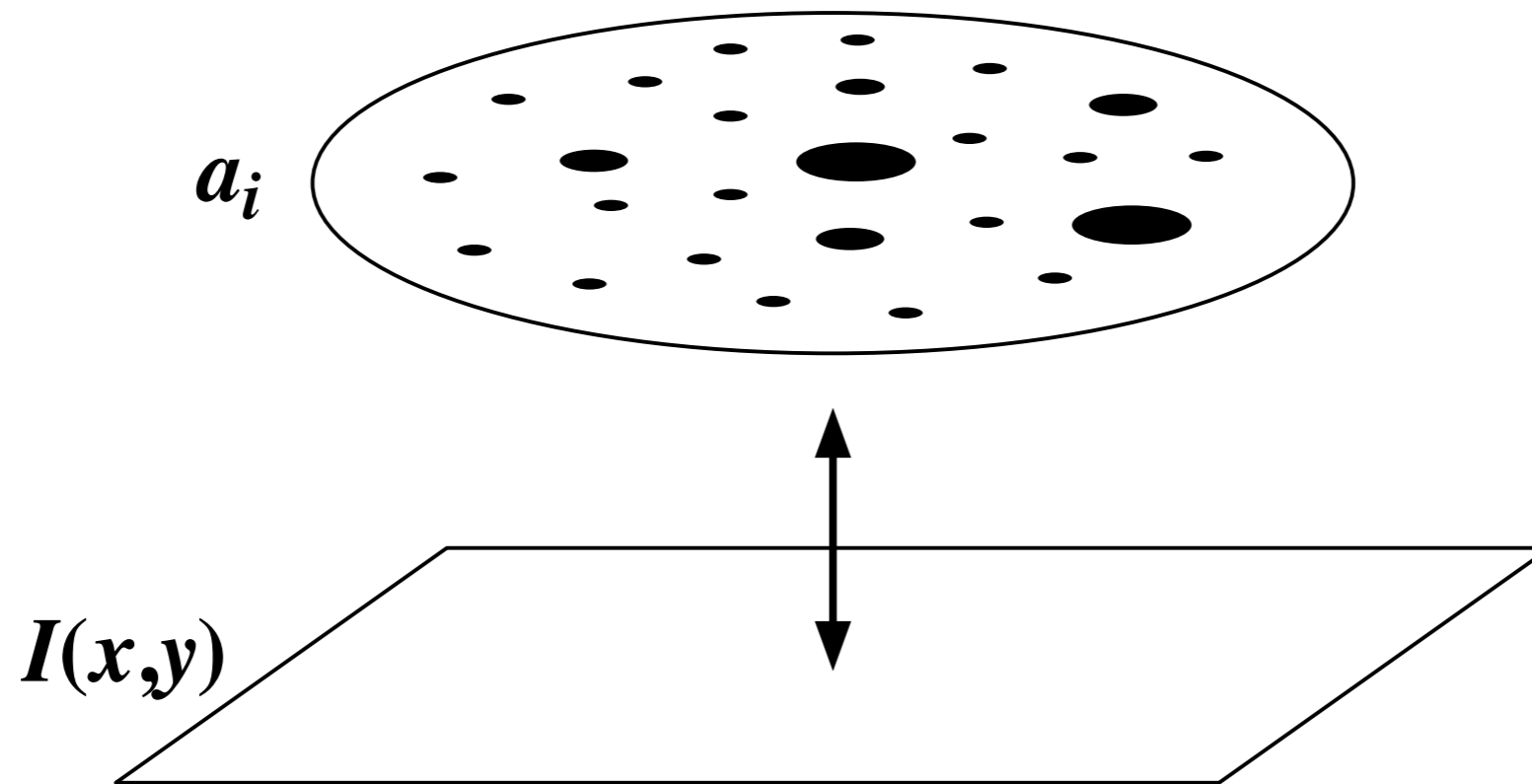
Local codes
(e.g., grandmother cells)



$$N$$

(From Foldiak & Young, 1995)

Sparse, distributed representation



$$I(x, y) = \sum_i a_i \phi_i(x, y) + \epsilon(x, y)$$

Energy function

$$E = \frac{1}{2} \|\mathbf{I} - \Phi \mathbf{a}\|^2 + \lambda \sum_i C(a_i)$$

↑
preserve information

↑
be sparse

Energy function

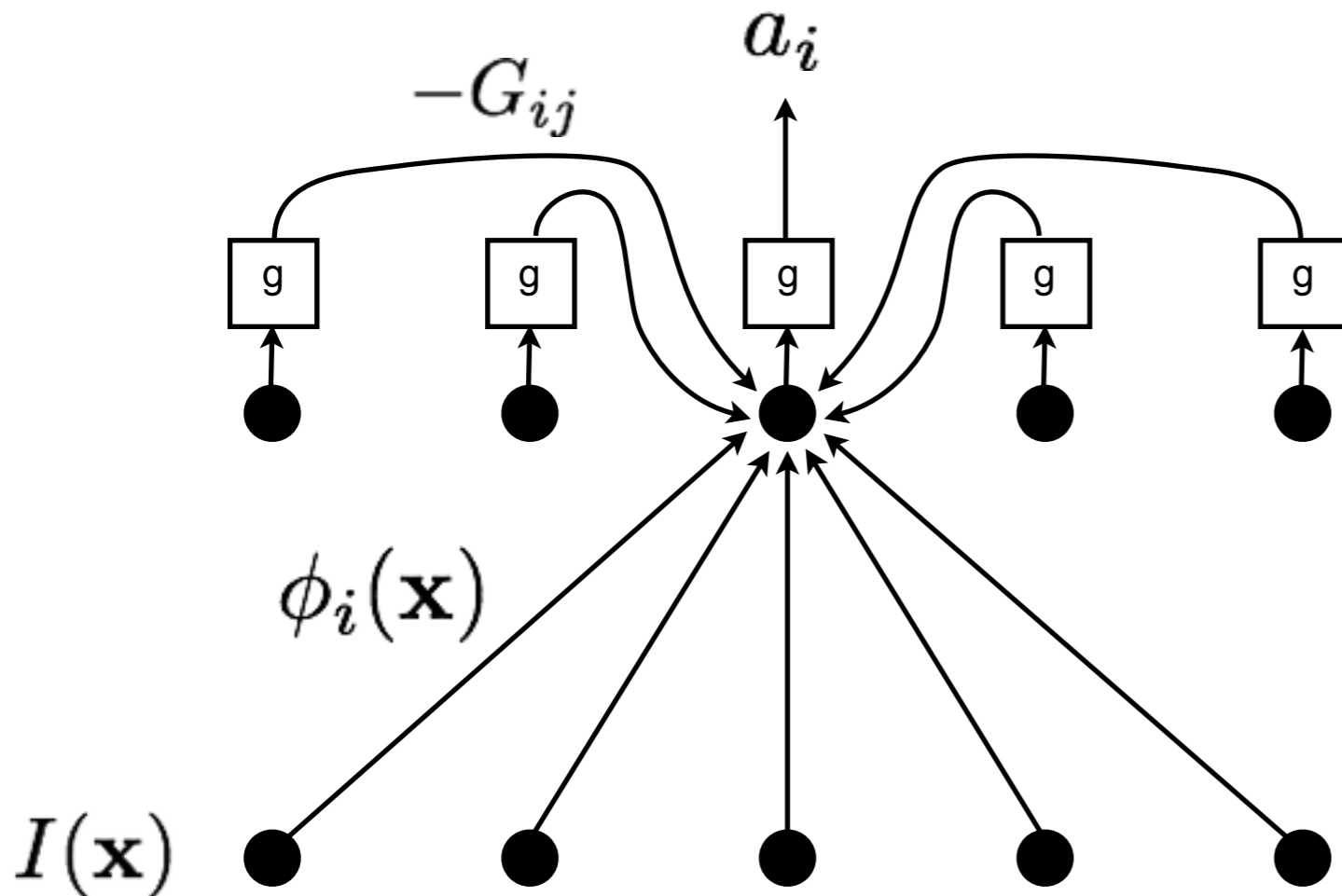
$$E = \frac{1}{2} \|\mathbf{I} - \Phi \mathbf{a}\|^2 + \lambda \sum_i C(a_i)$$

-log

$P(\mathbf{I} | \mathbf{a})$

$P(\mathbf{a})$

Coefficients a_i may be computed via
 thresholding and lateral inhibition
 ('LCA' - Rozell, Johnson, Baraniuk & Olshausen, 2008)



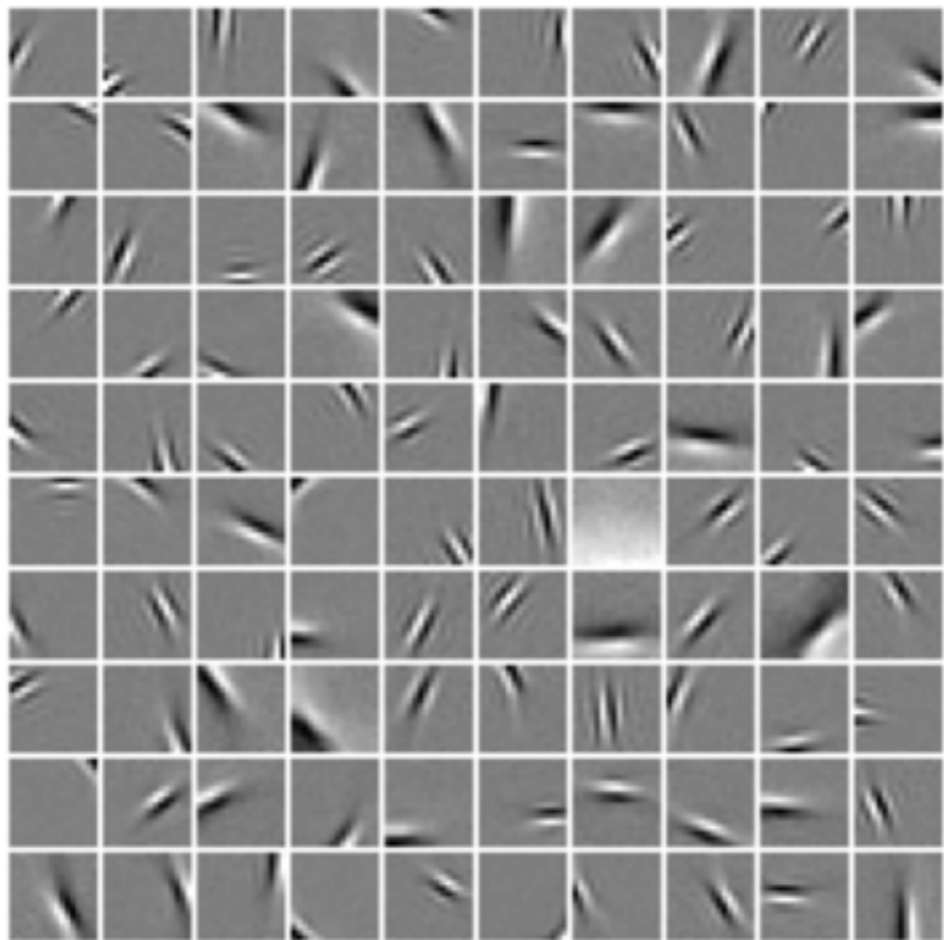
$$\tau \dot{u}_i + u_i = b_i - \sum_{j \neq i} G_{ij} a_j$$

$$a_i = g(u_i)$$

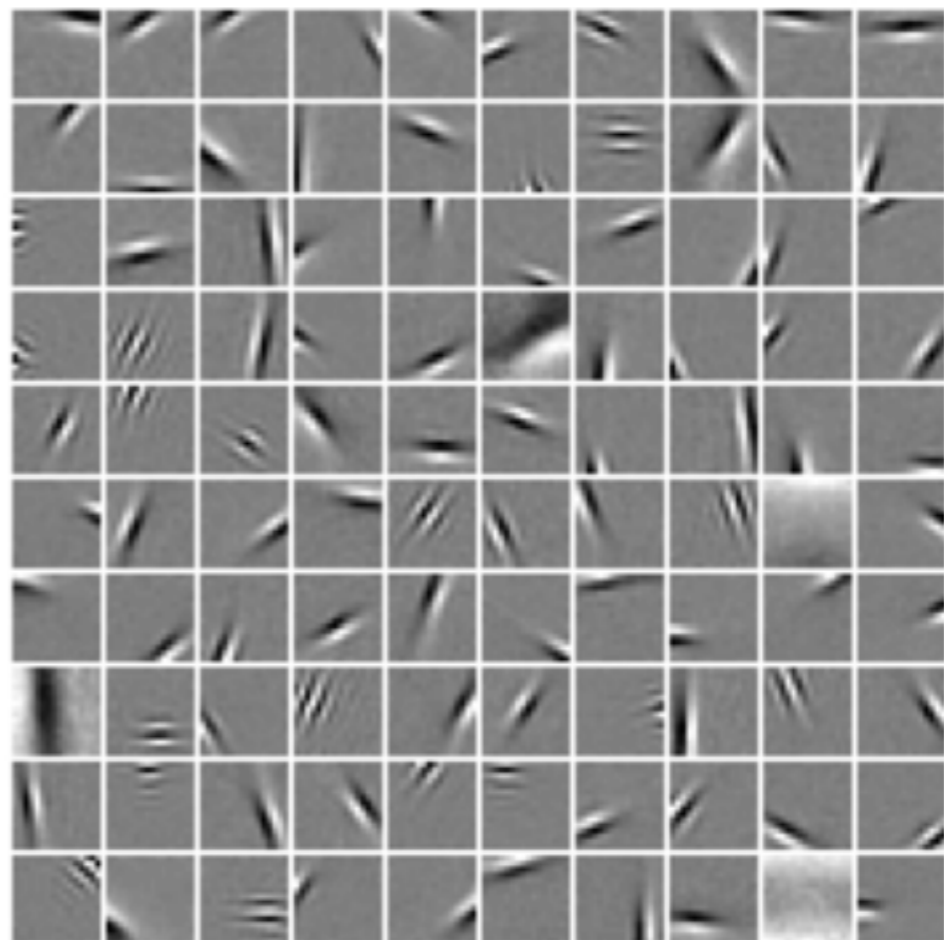
$$b_i = \sum_{\mathbf{x}} \phi_i(\mathbf{x}) I(\mathbf{x})$$

$$G_{ij} = \sum_{\mathbf{x}} \phi_i(\mathbf{x}) \phi_j(\mathbf{x})$$

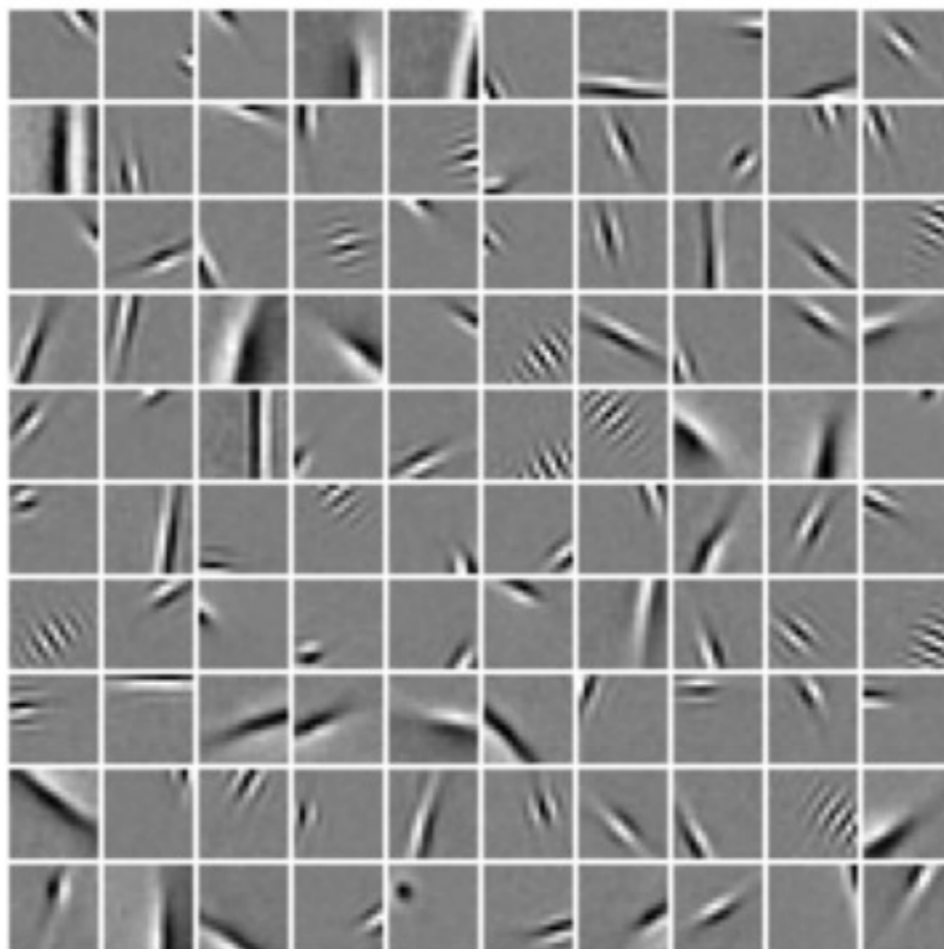
1.25x



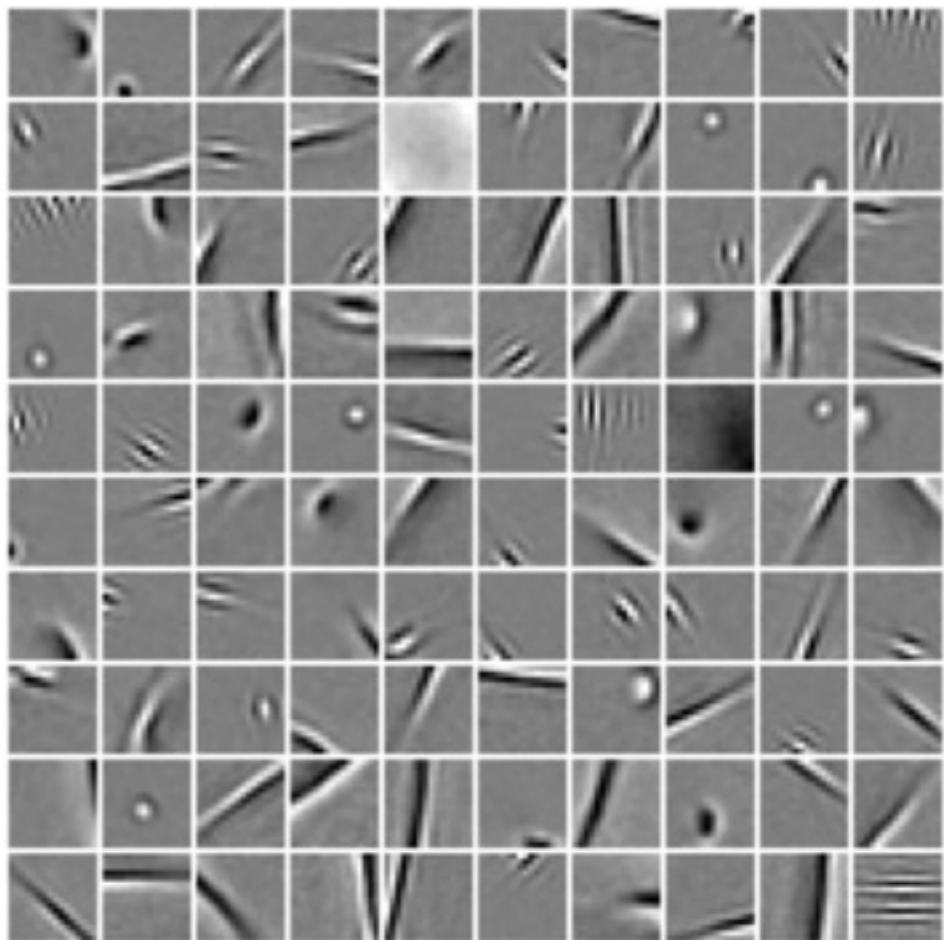
2.5x



5x

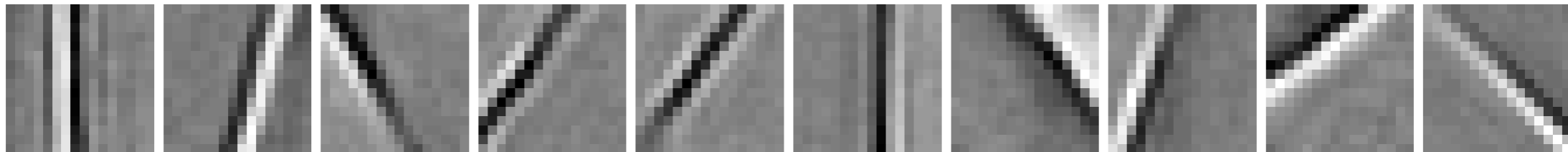


10x

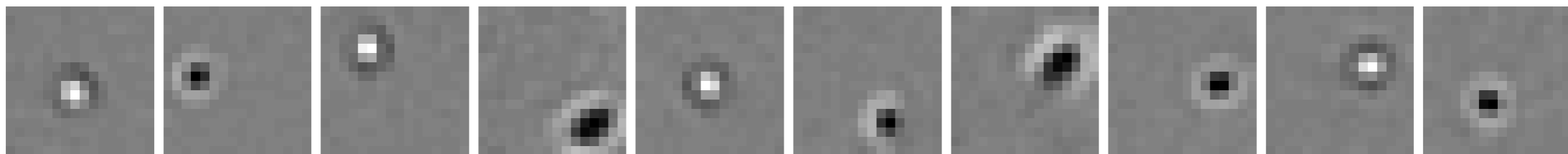


Examples from 10x dictionary (Olshausen, 2013)

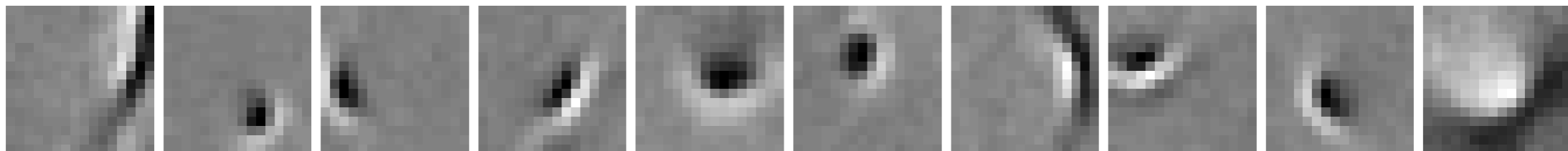
ridgelet



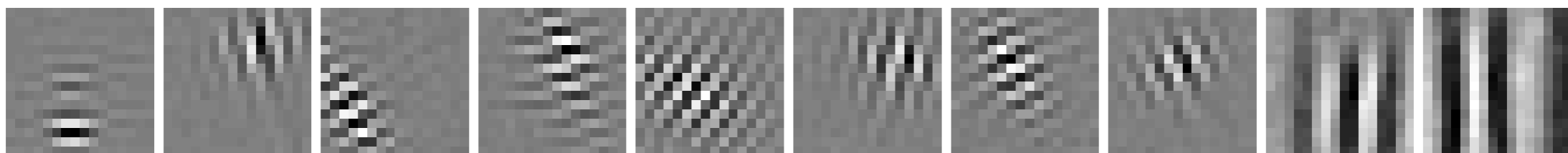
circular



curvature

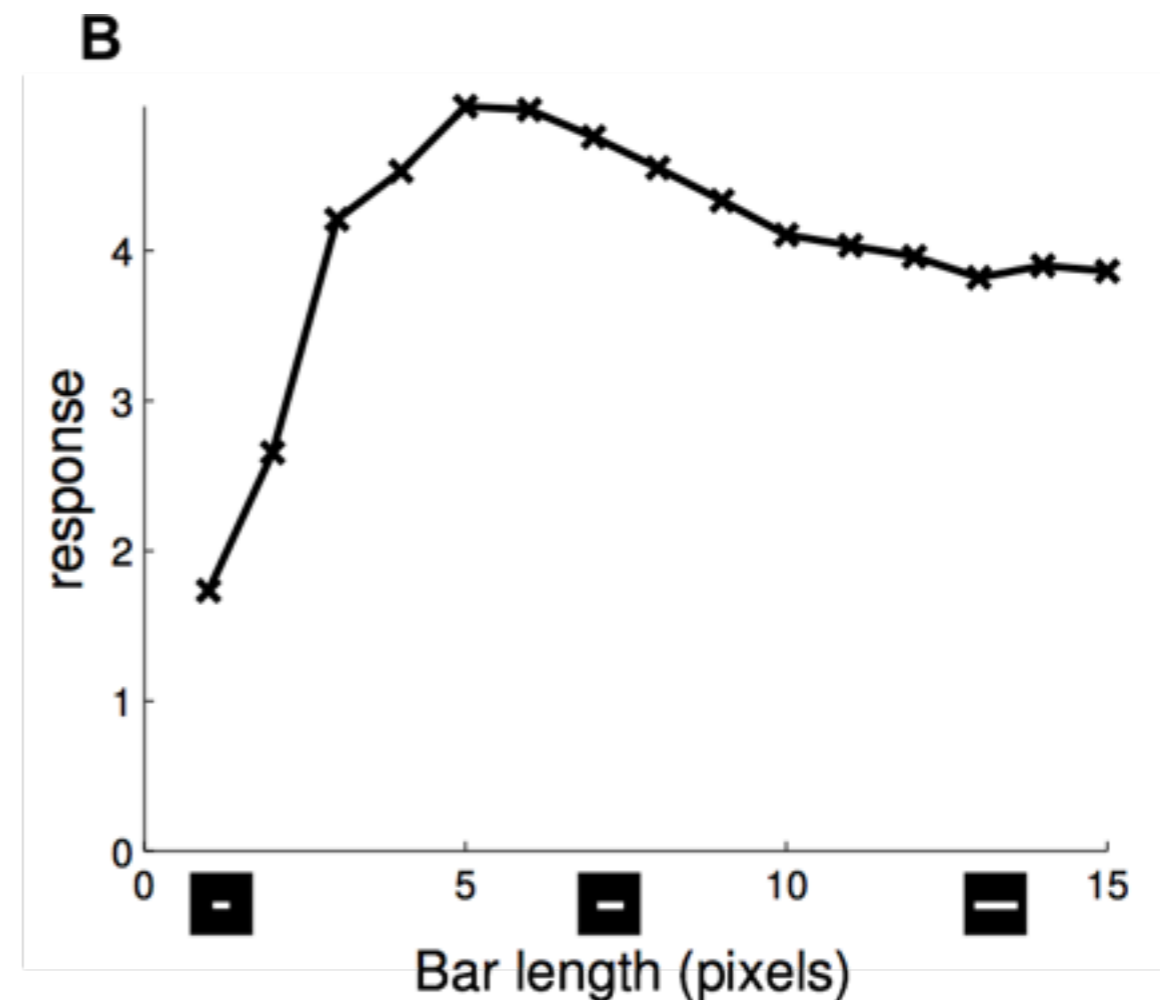
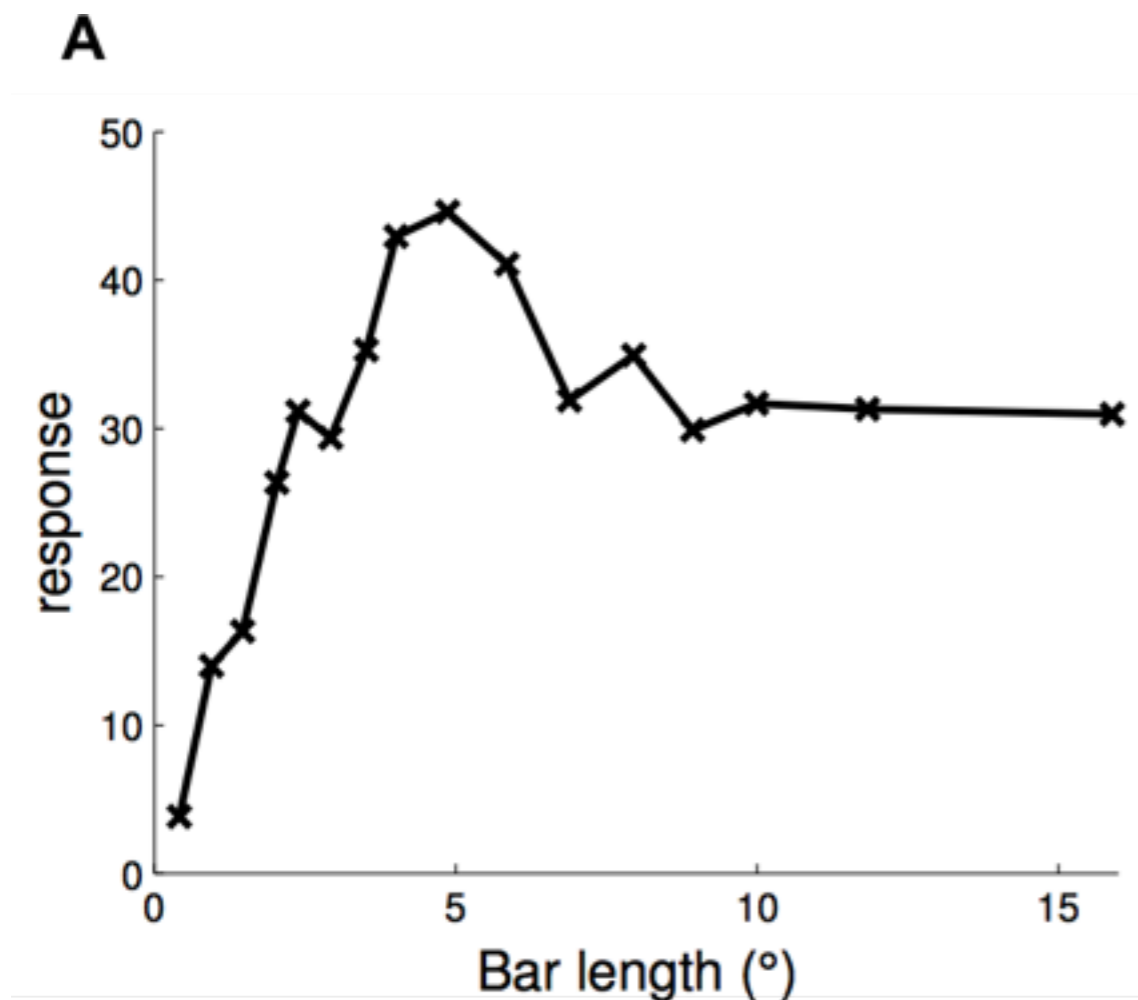


grating



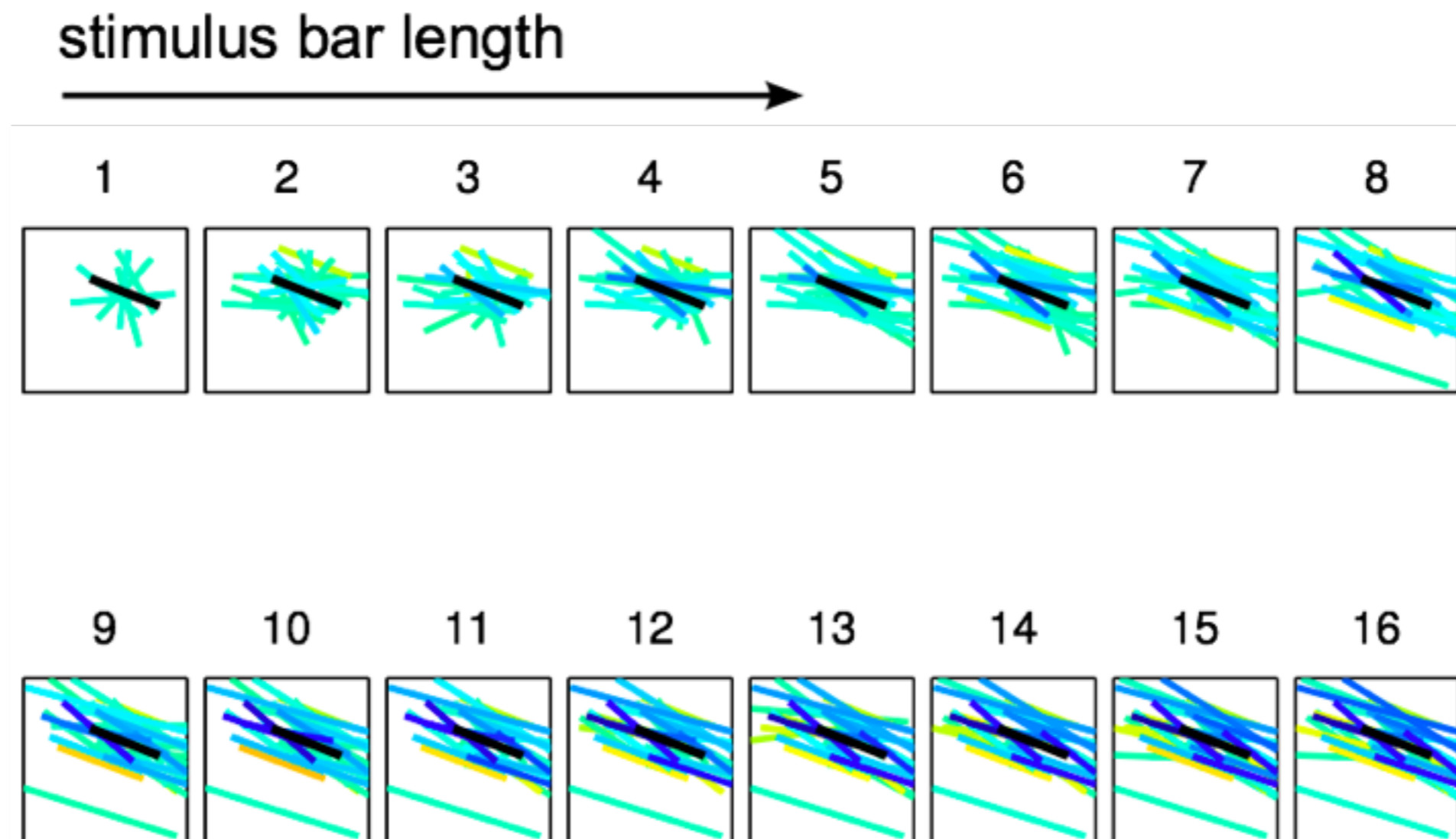
Explaining away can account for non-classical surround effects such as end-stopping

(Lee et al., 2006; Zhu & Rozell, 2013)



Explaining away can account for non-classical surround effects such as end-stopping

(Lee et al., 2006; Zhu & Rozell, 2013)

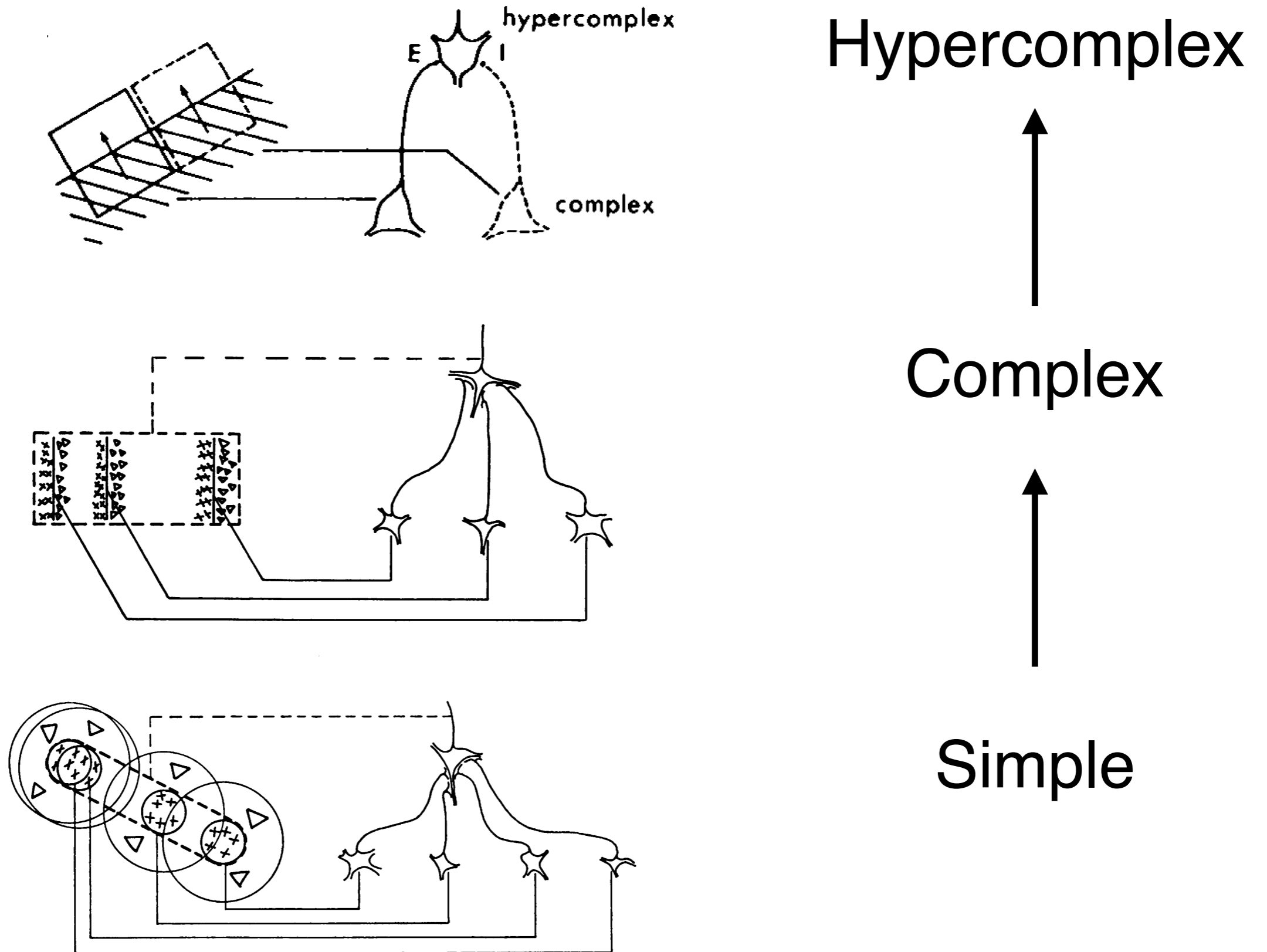


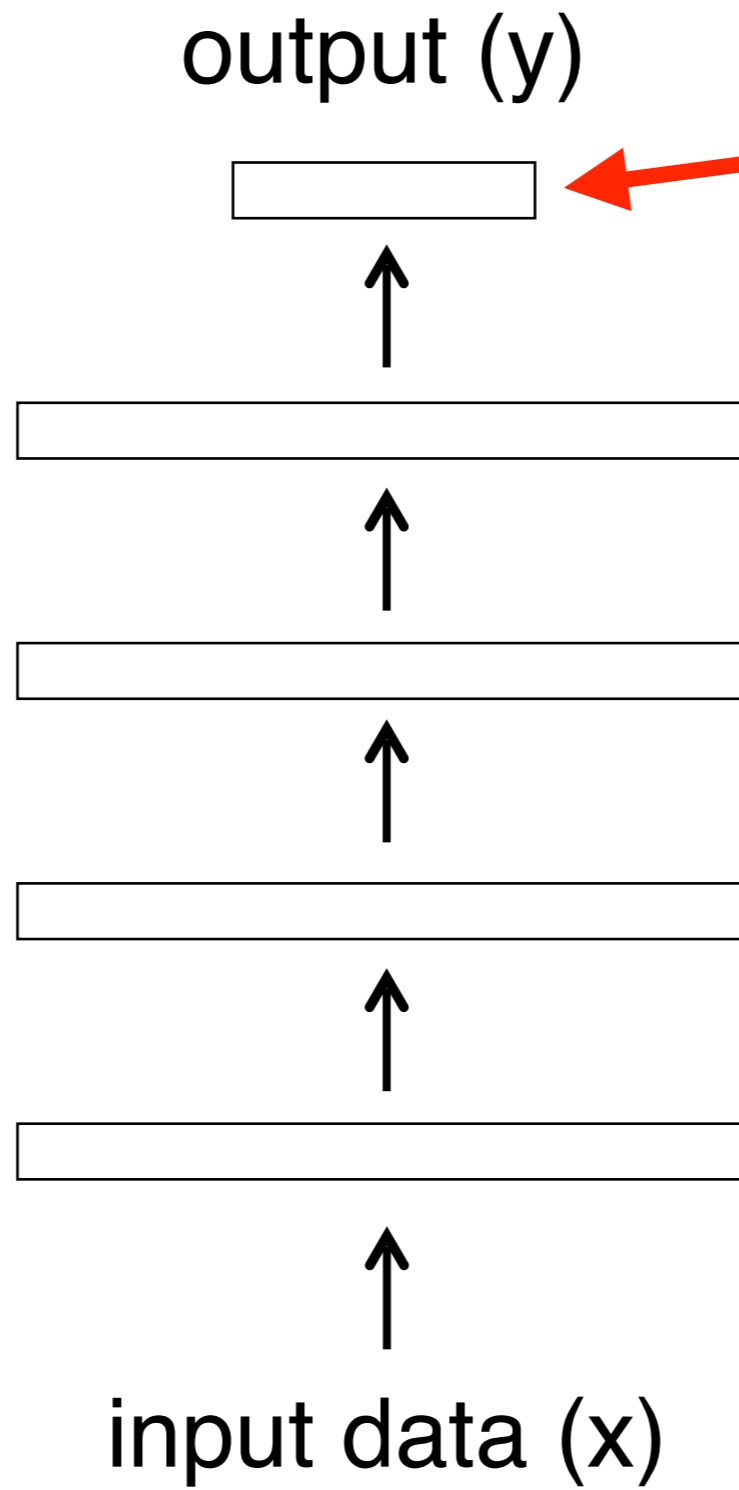
Yellow = excitatory
Blue = inhibitory

4. Feedback



Hubel & Wiesel (1962, 1965)

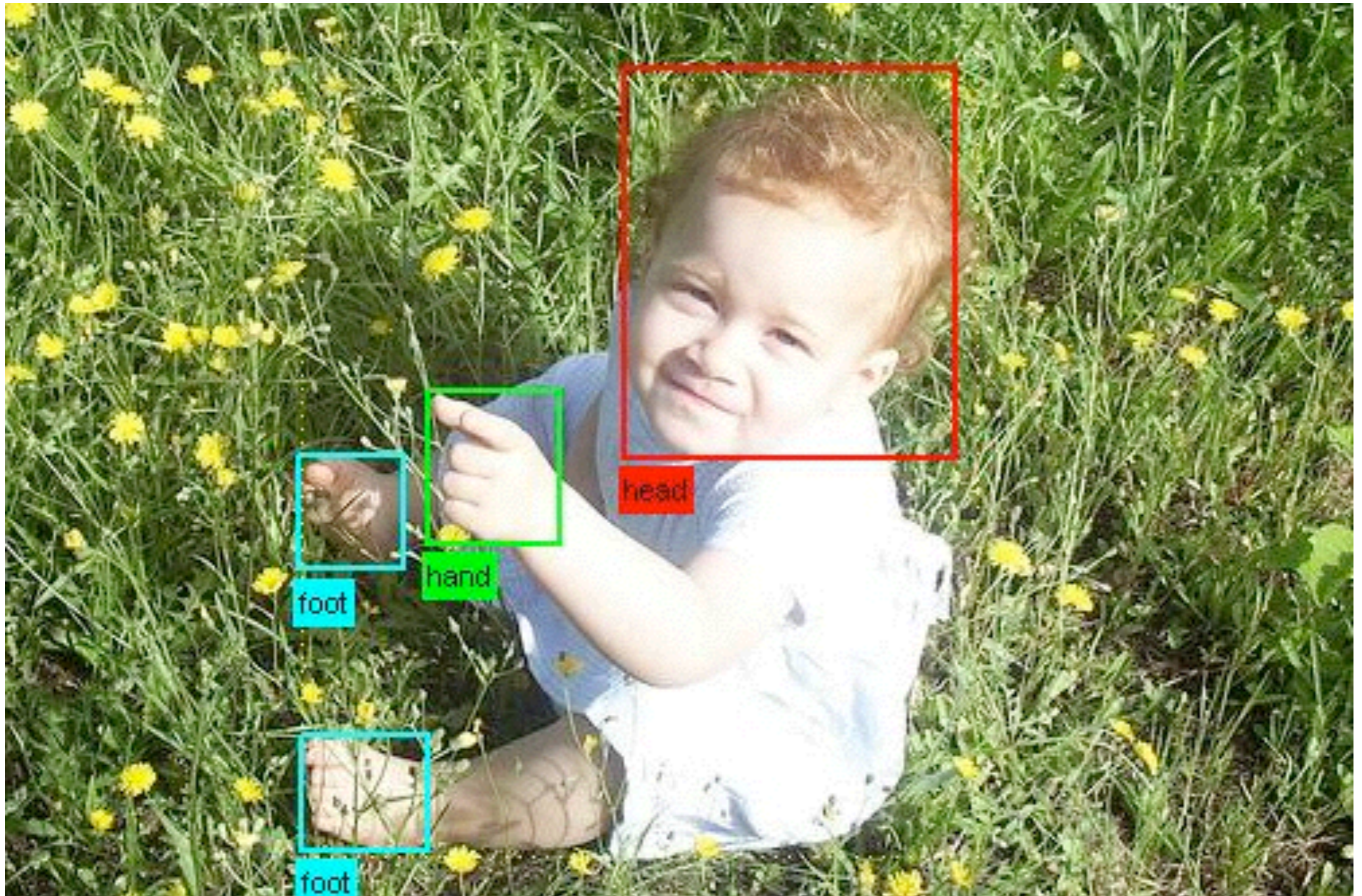


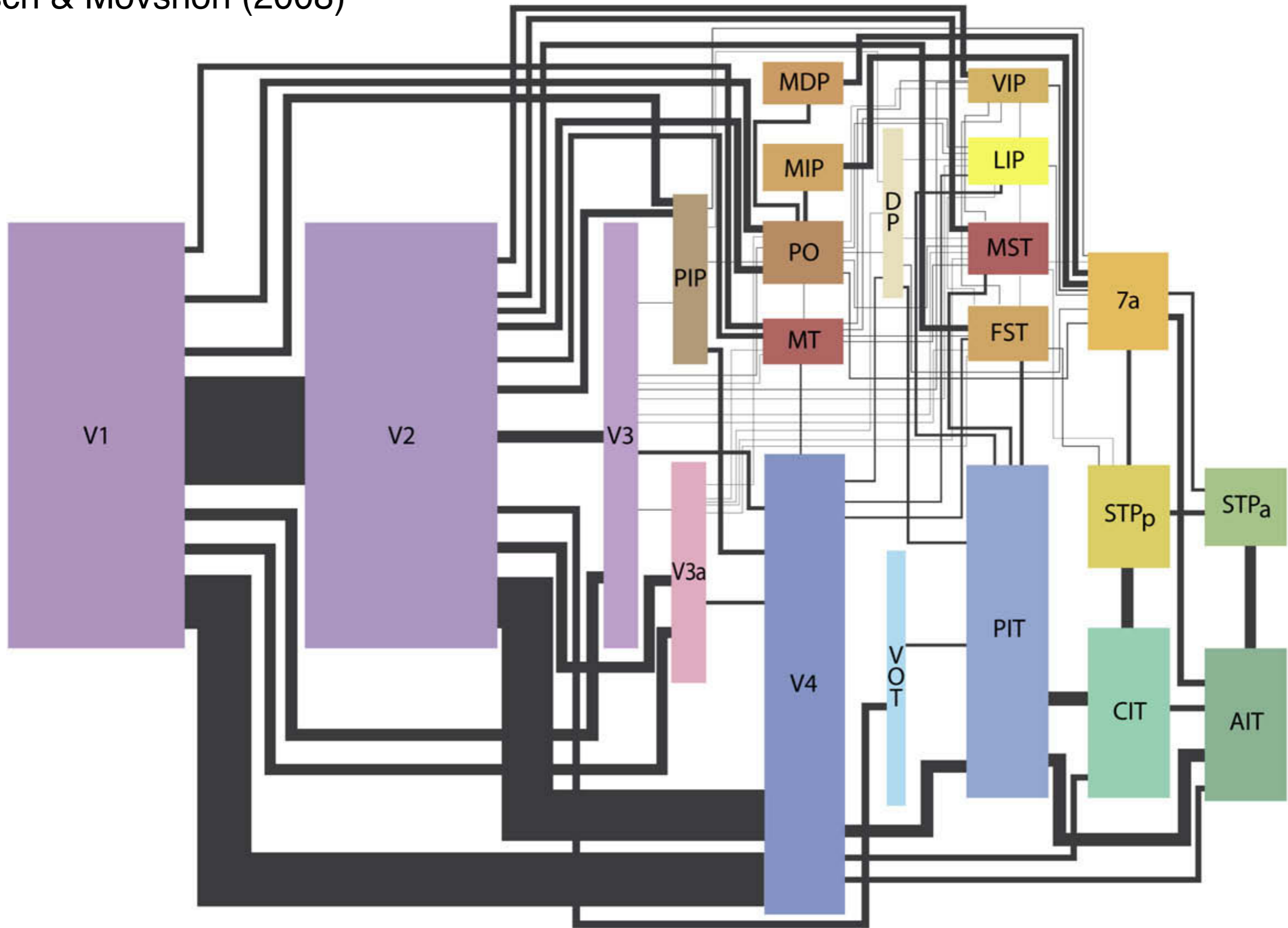


“The answer”

$$y = f(x; w)$$

Is this the goal of vision?





‘Gabor filters’

•

•

?

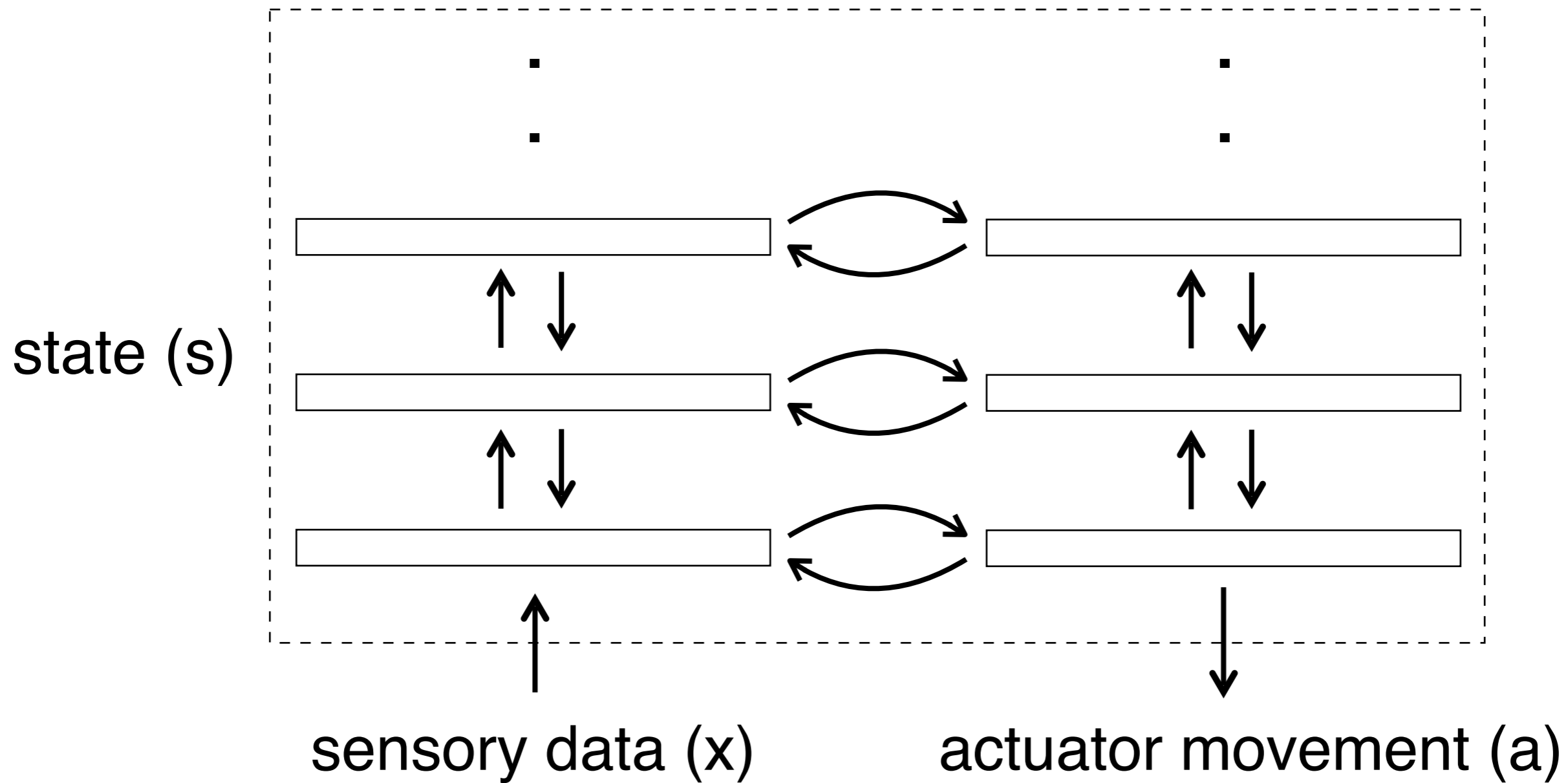
•

•

objects

•

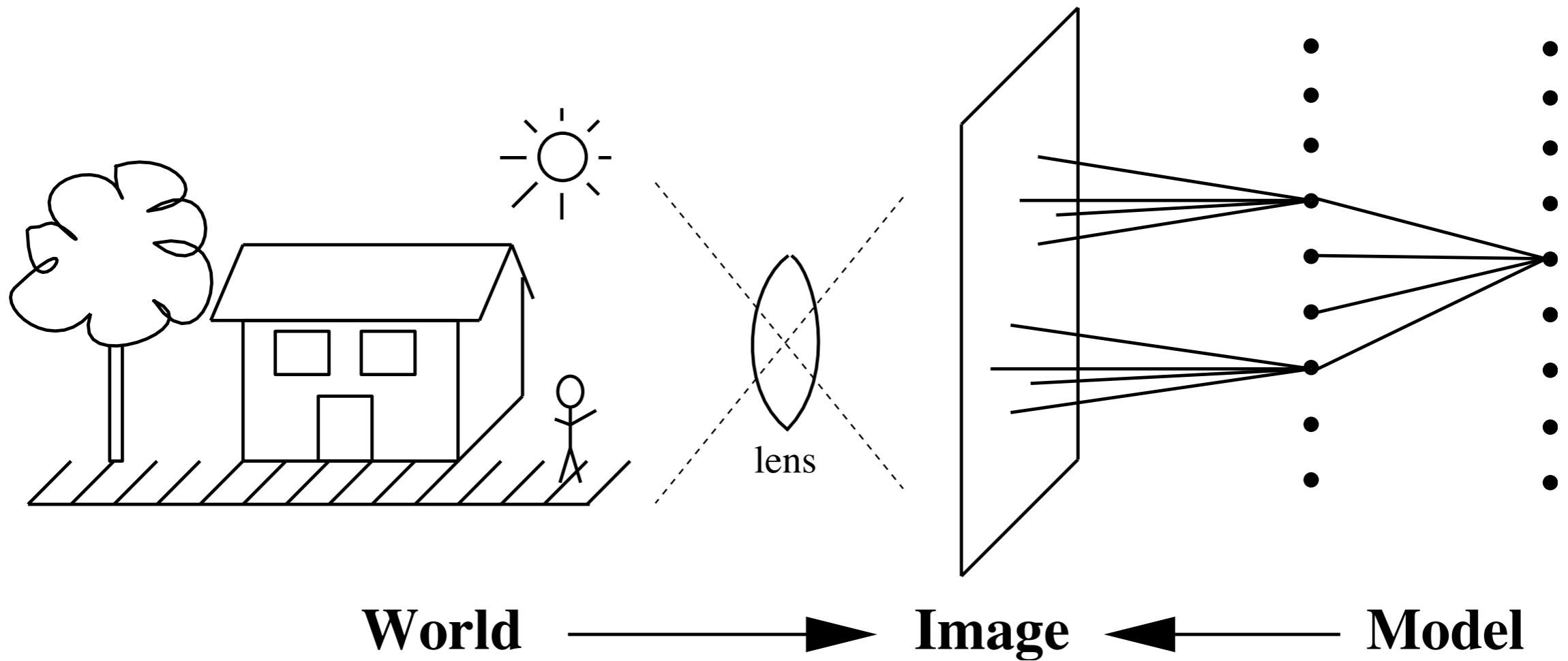
faces



$$\tau \dot{s} + s = g(s, x, a; w)$$

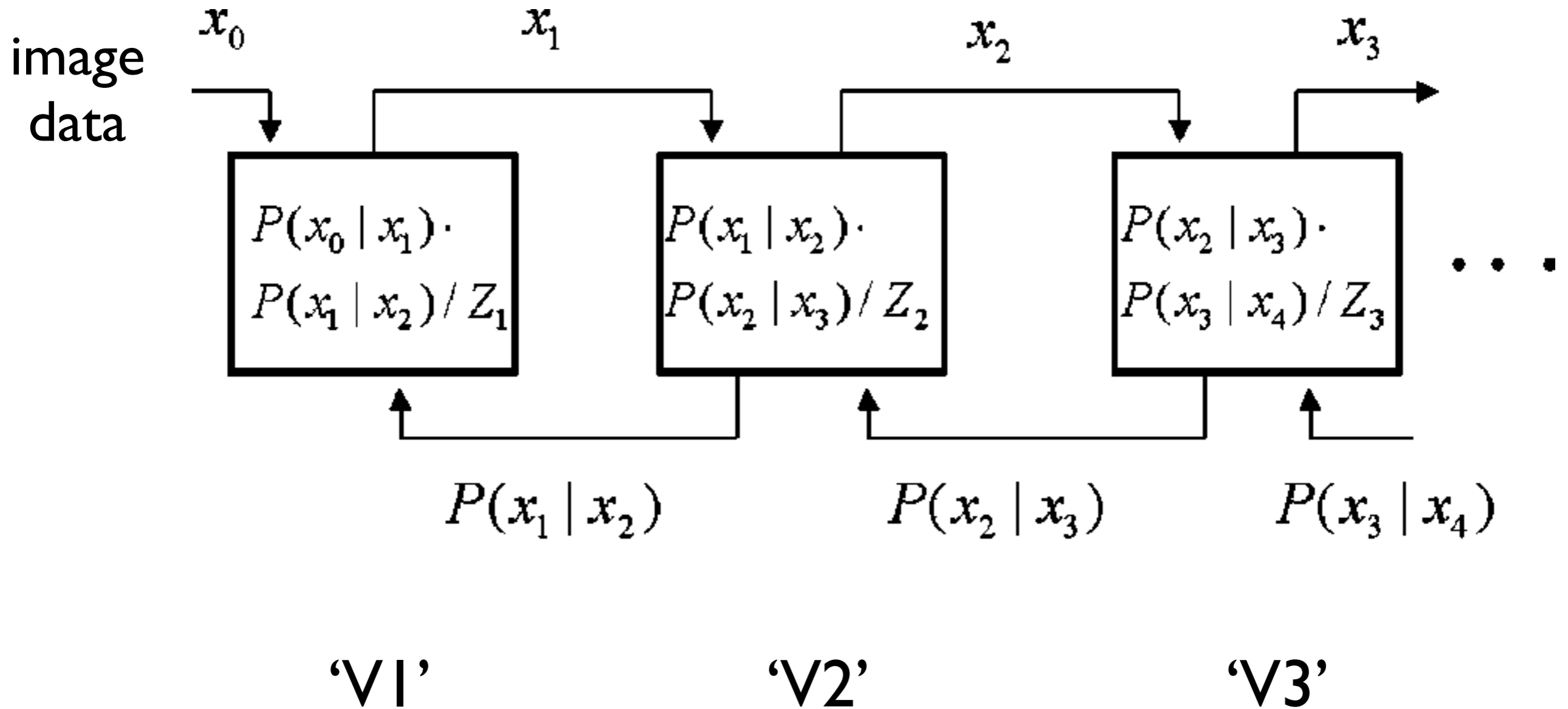
$$a = f(s)$$

Vision as inference

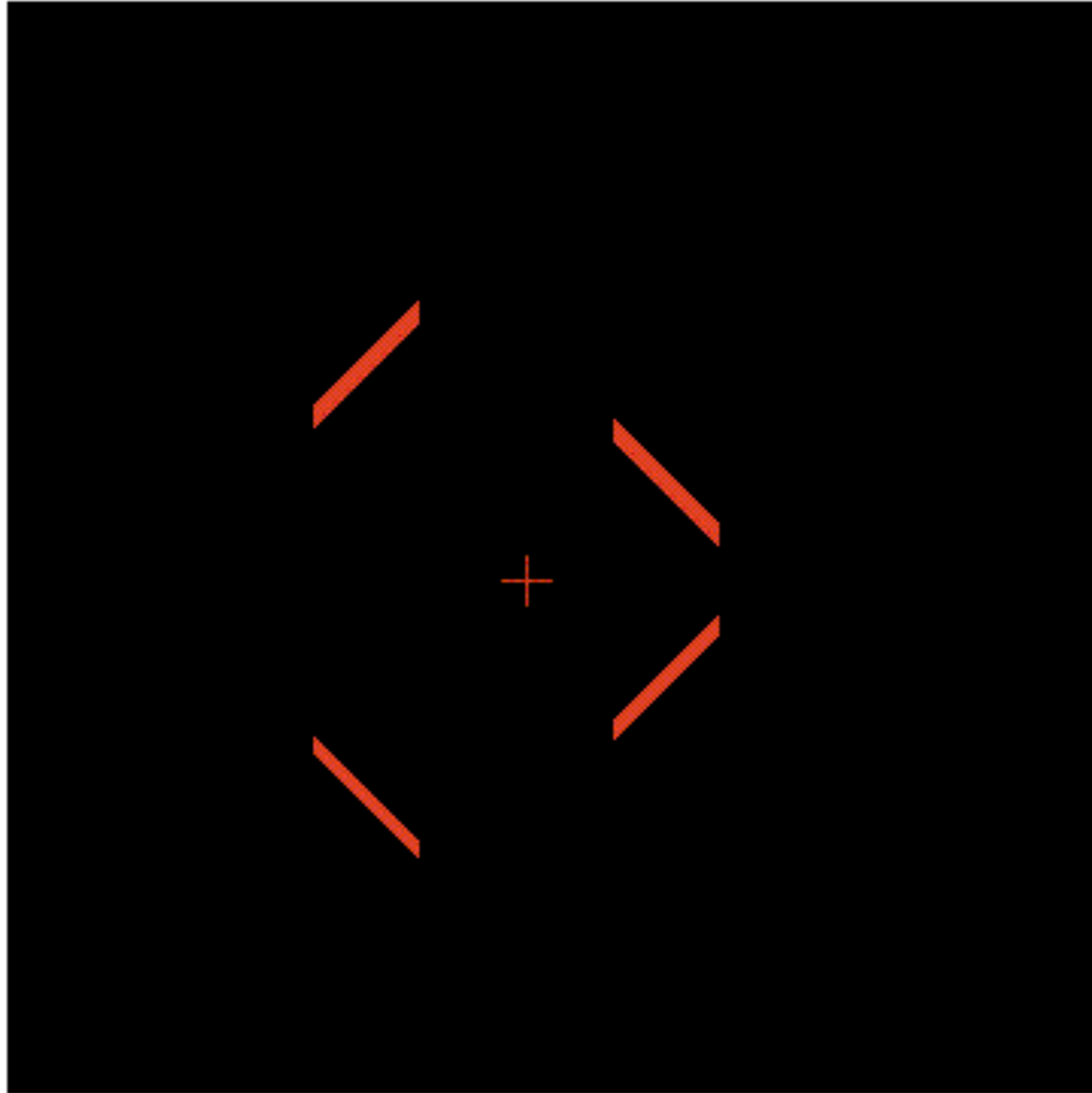


Hierarchical Bayesian inference in visual cortex

(Lee & Mumford, 2003)

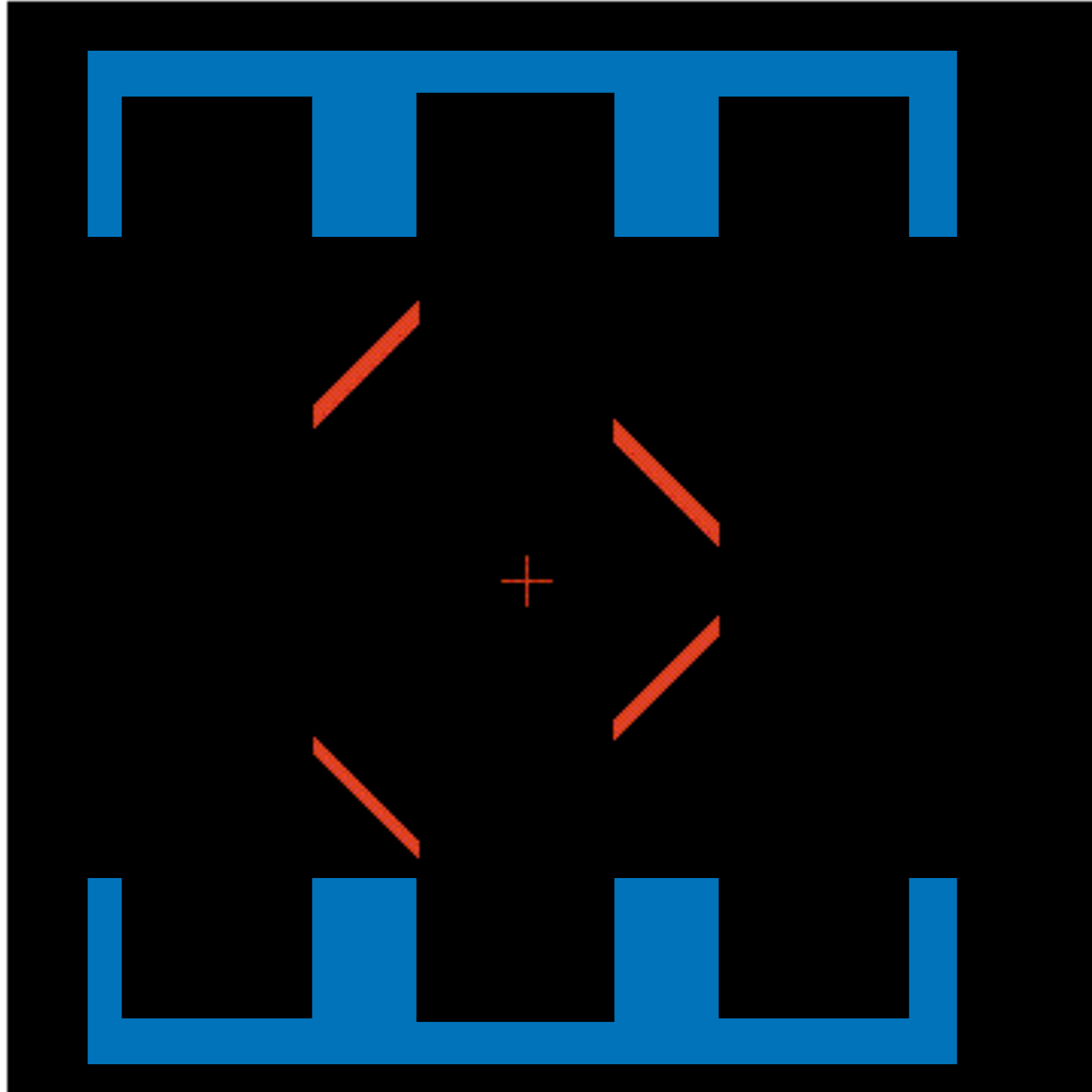


What do you see?



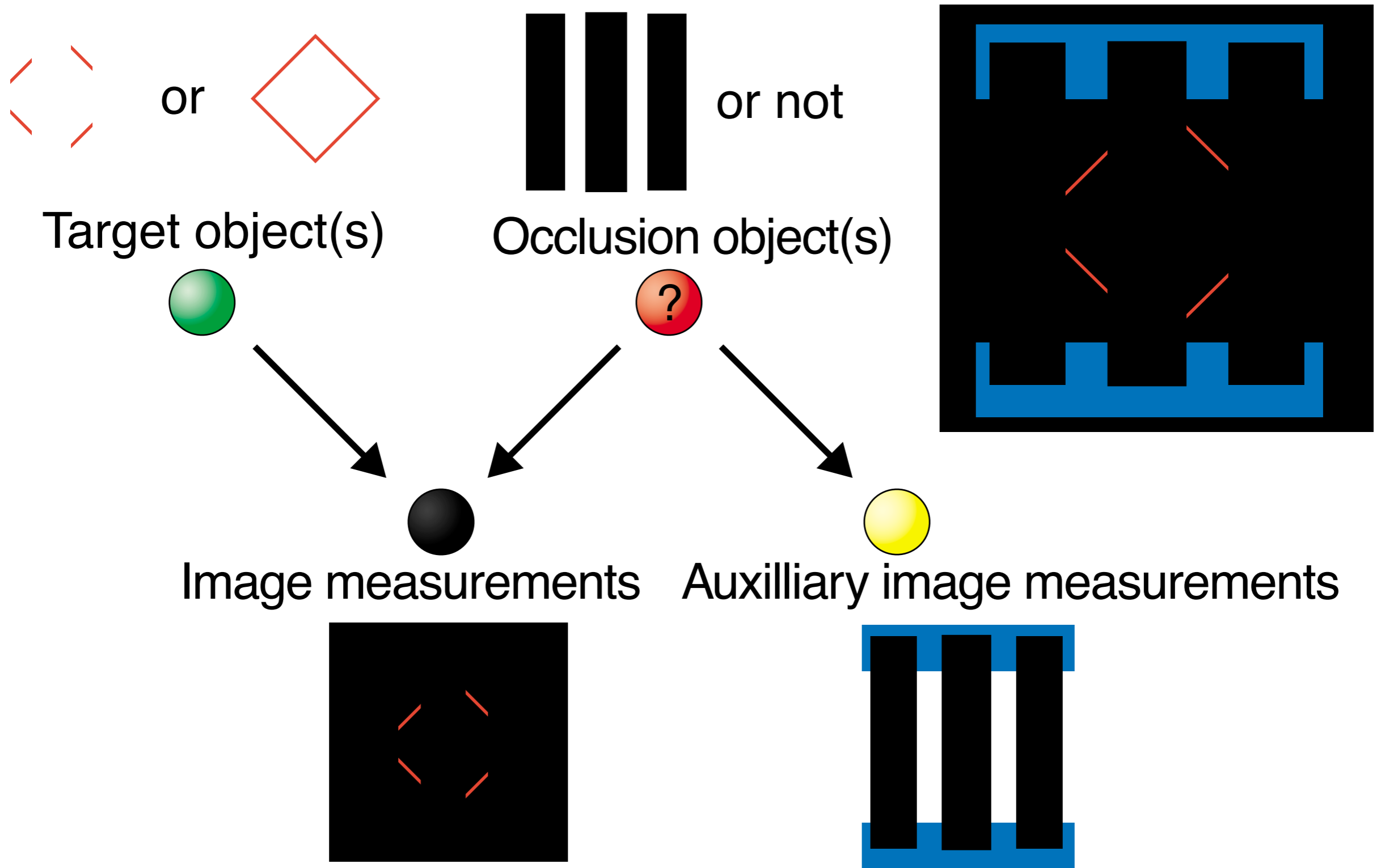
Lorenceanu & Shiffrar (1992);
Murray, Kersten, Schrater, Olshausen & Woods (2002)

What do you see?



Lorenceanu & Shiffrar (1992);
Murray, Kersten, Schrater, Olshausen & Woods (2002)

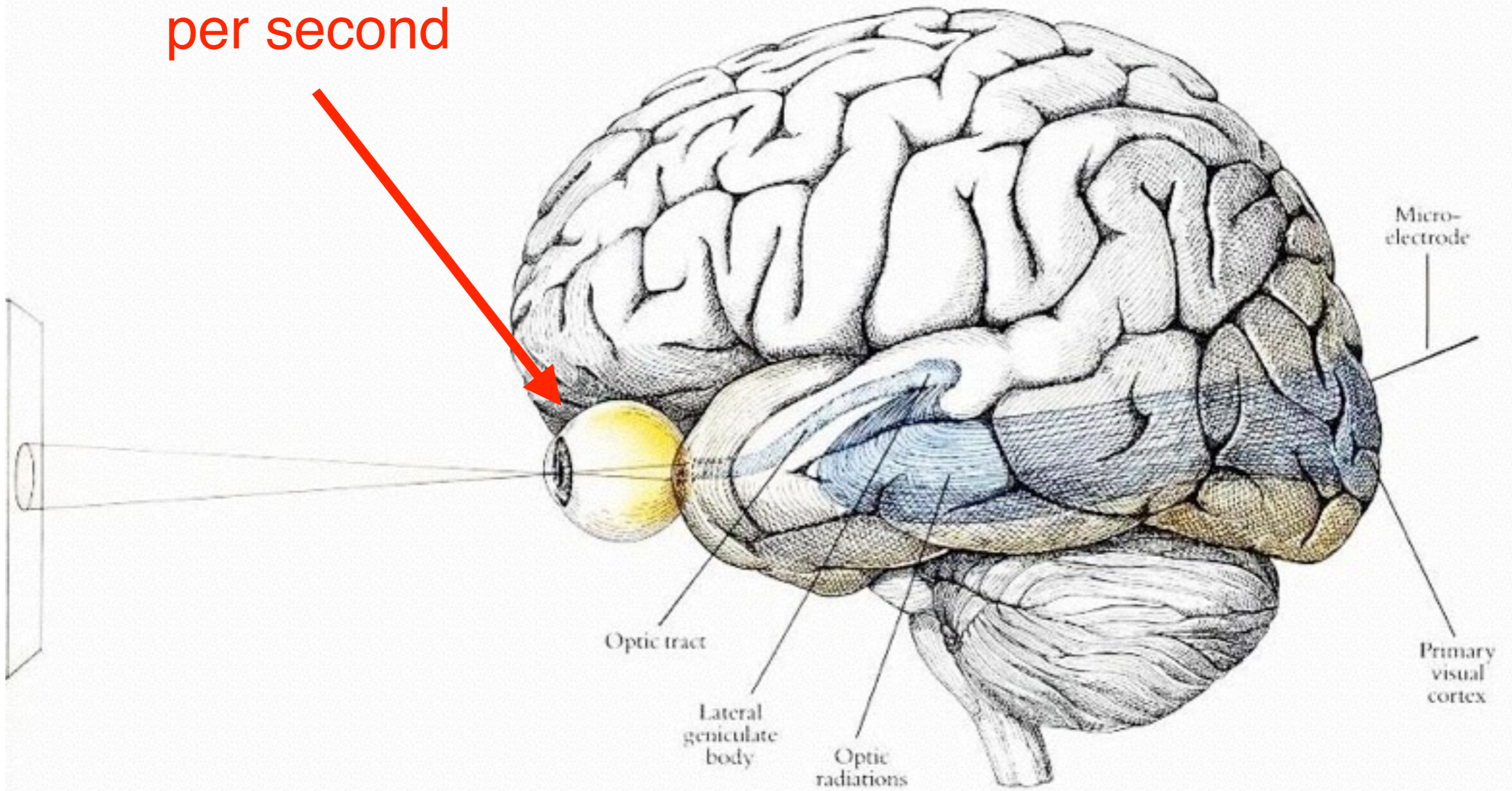
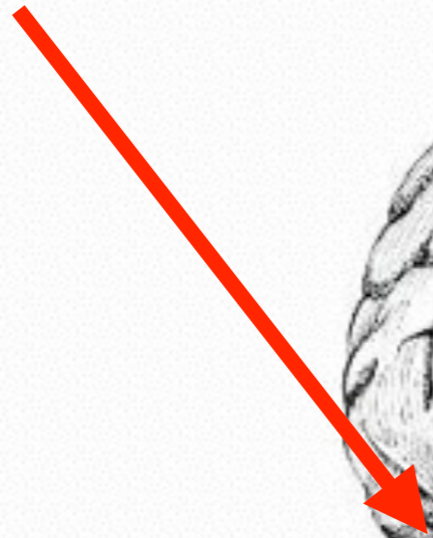
Perceptual “explaining away”



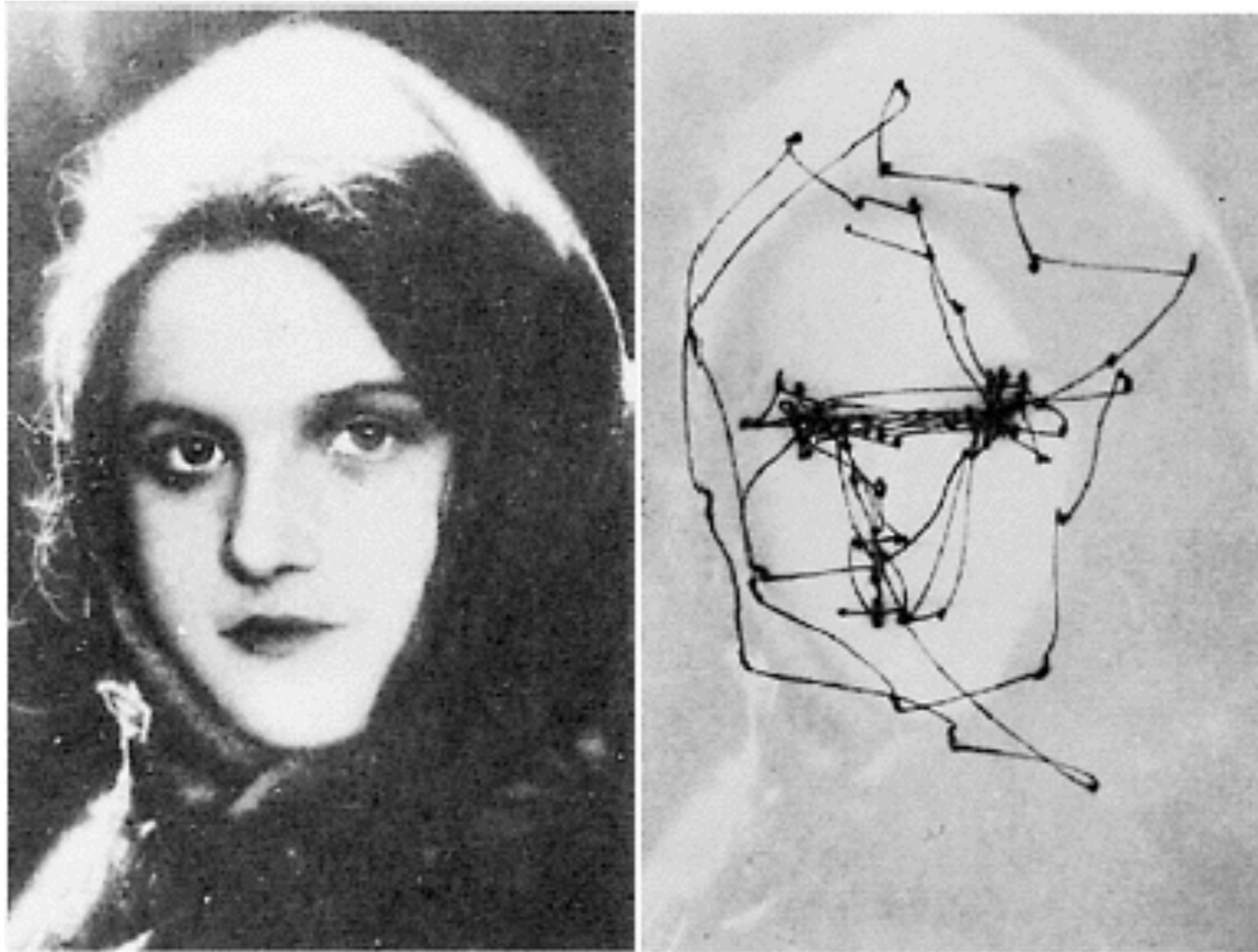
(Kersten & Yuille, 2003)

5. Active perception

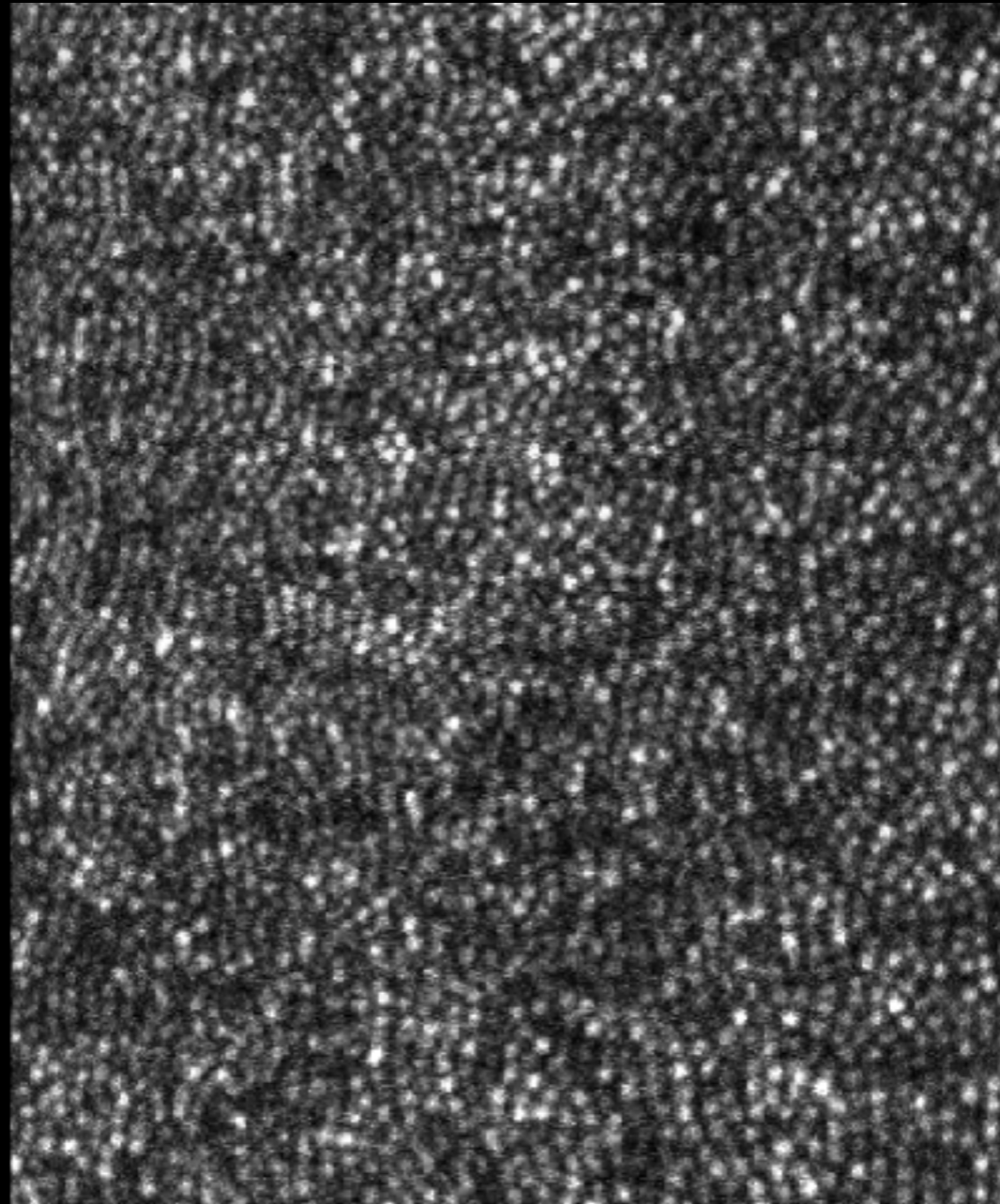
Moves 3-5 times
per second



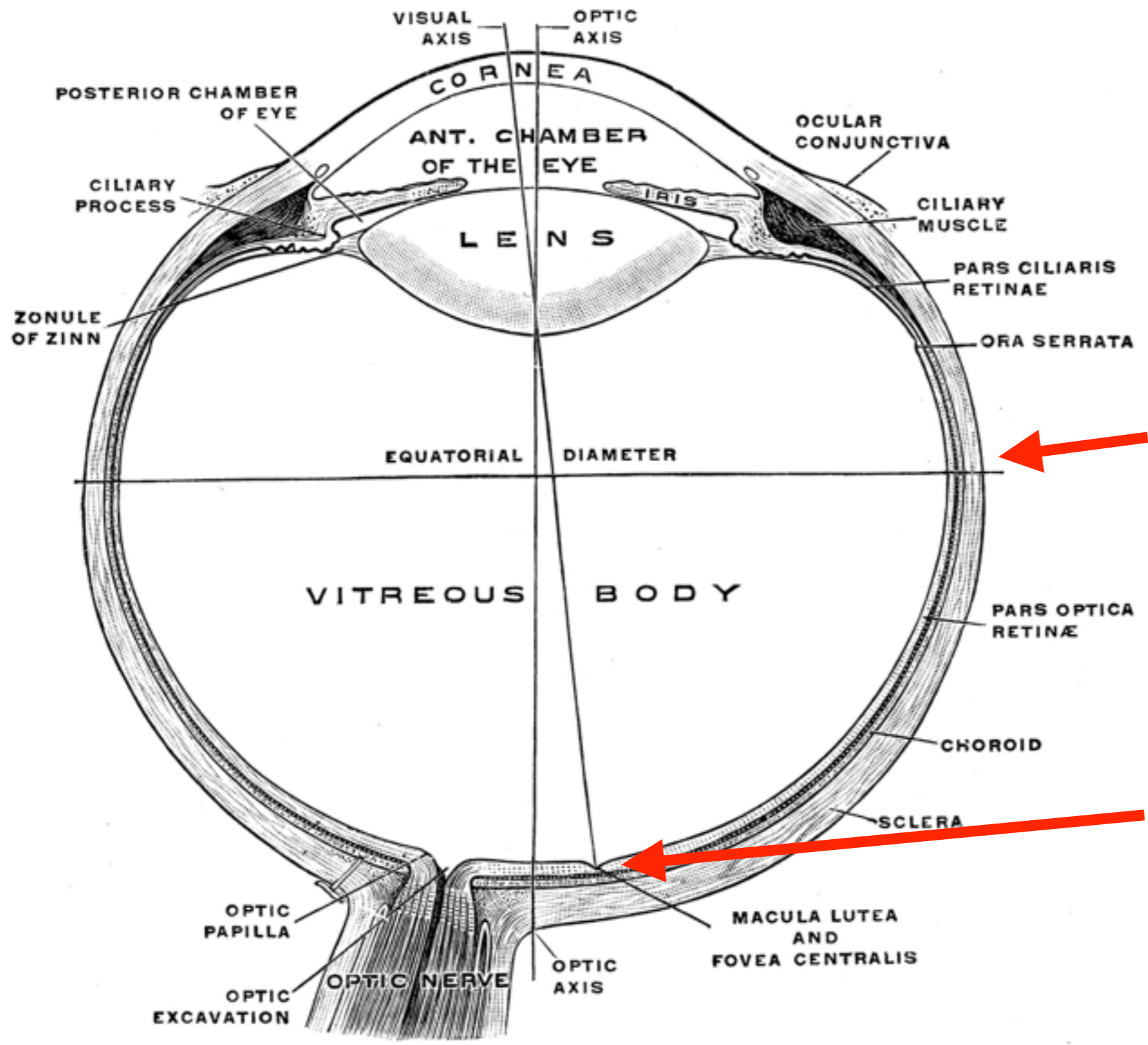
Human eye movements during viewing of an image



Fixational eye movements (drift)



(eye movement data from Austin Roorda, UC Berkeley)

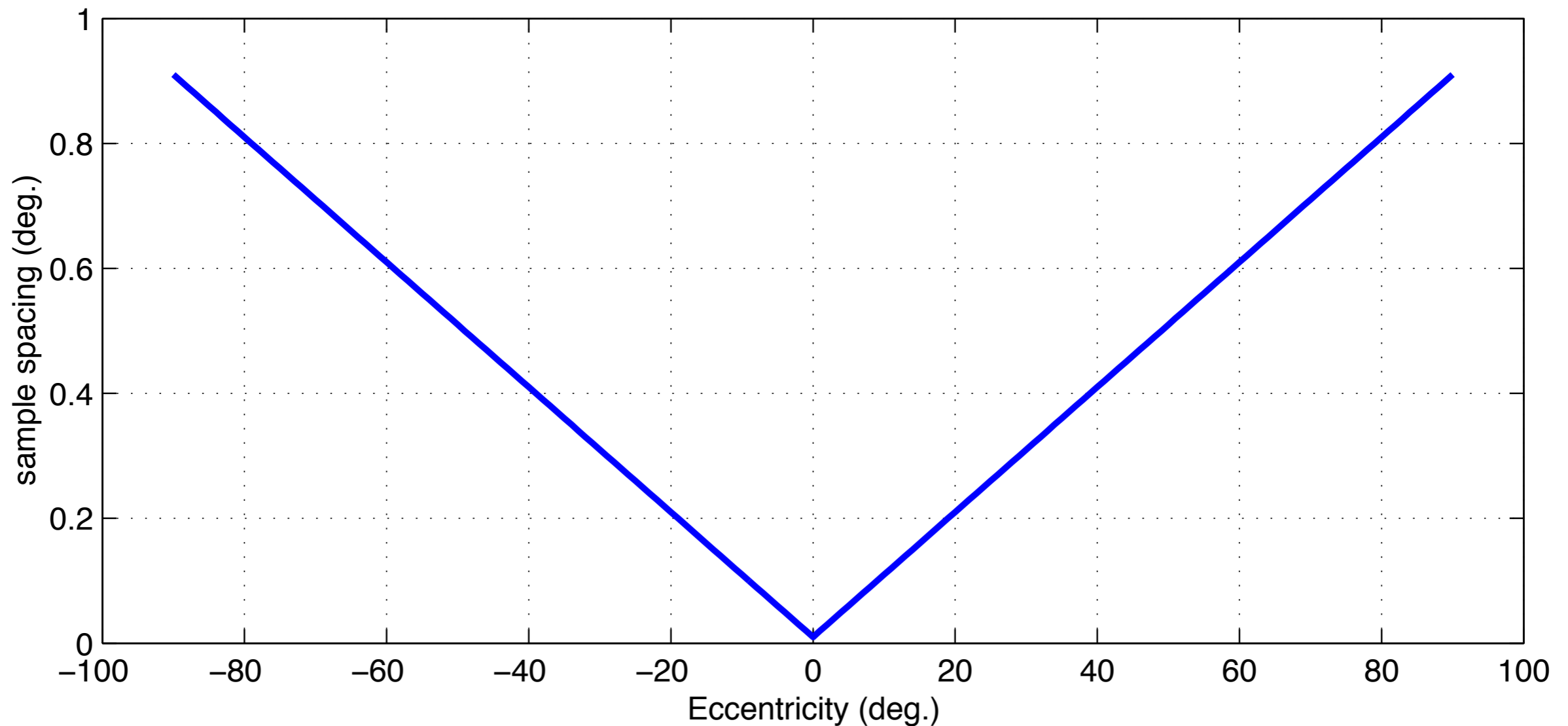


Low resolution

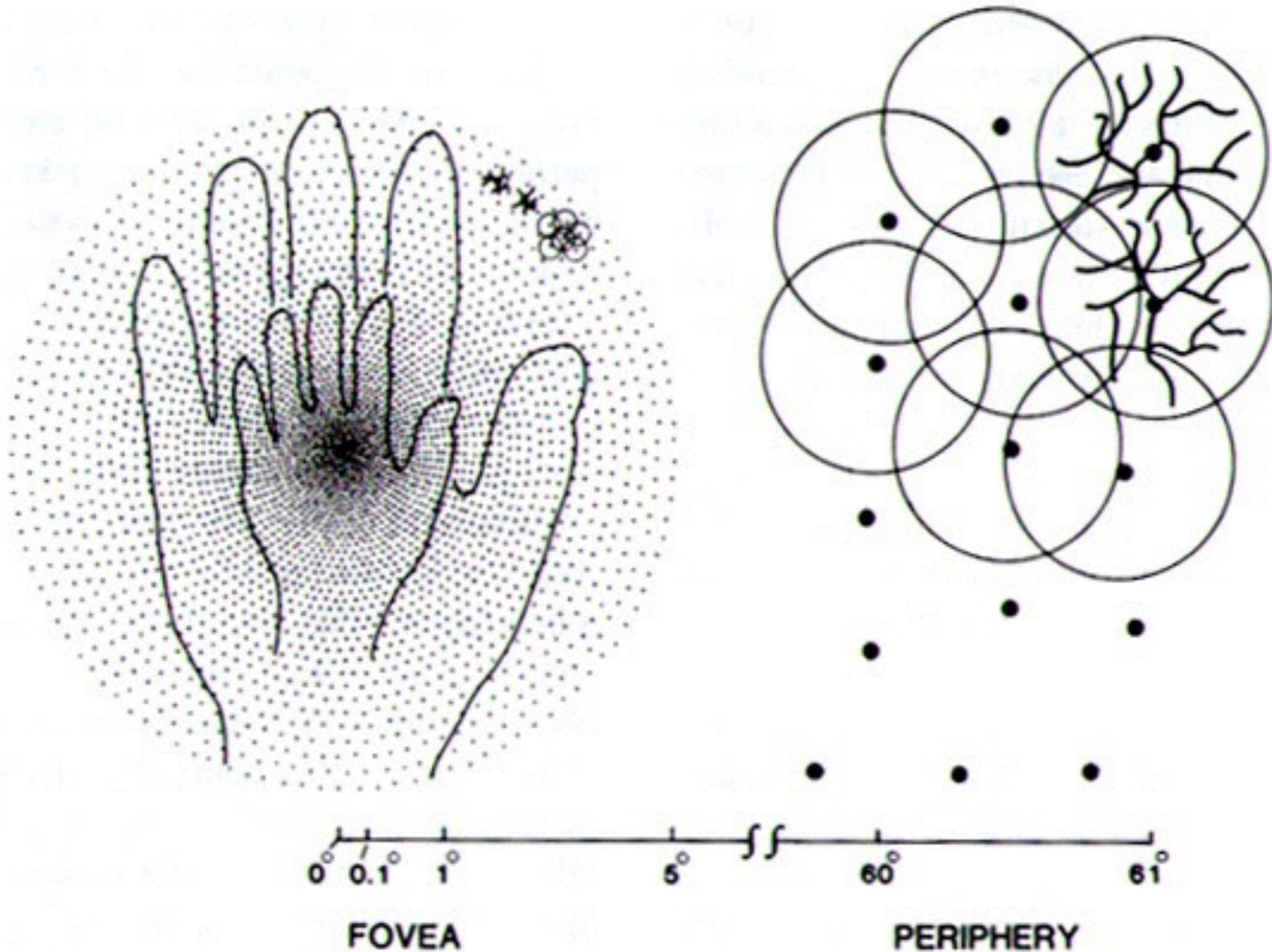
High resolution

Retinal ganglion cell spacing as a function of eccentricity

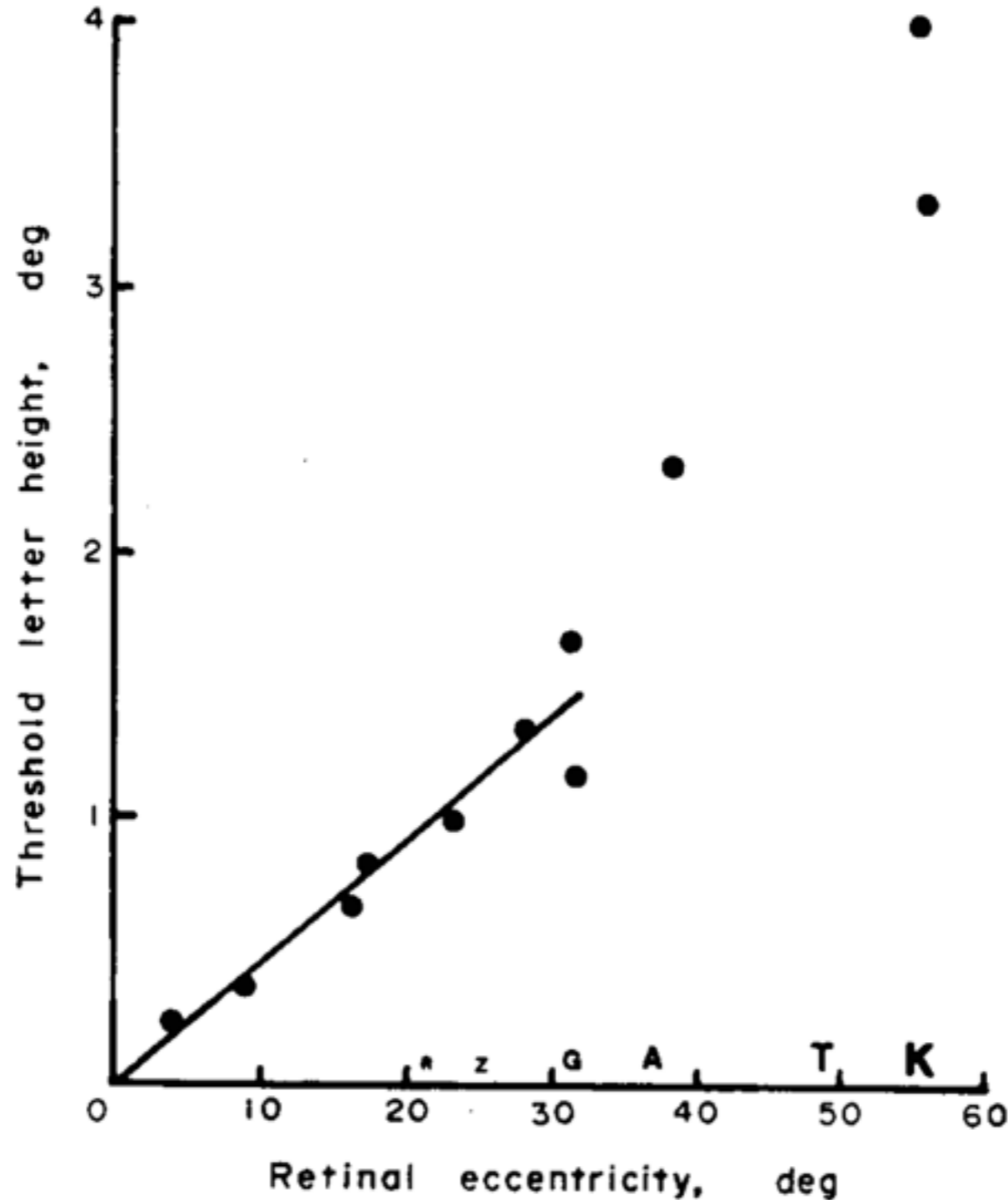
$$\Delta E \approx .01(|E| + 1)$$



Retinal ganglion cell sampling lattice (shown at one dot for every 20 ganglion cells)

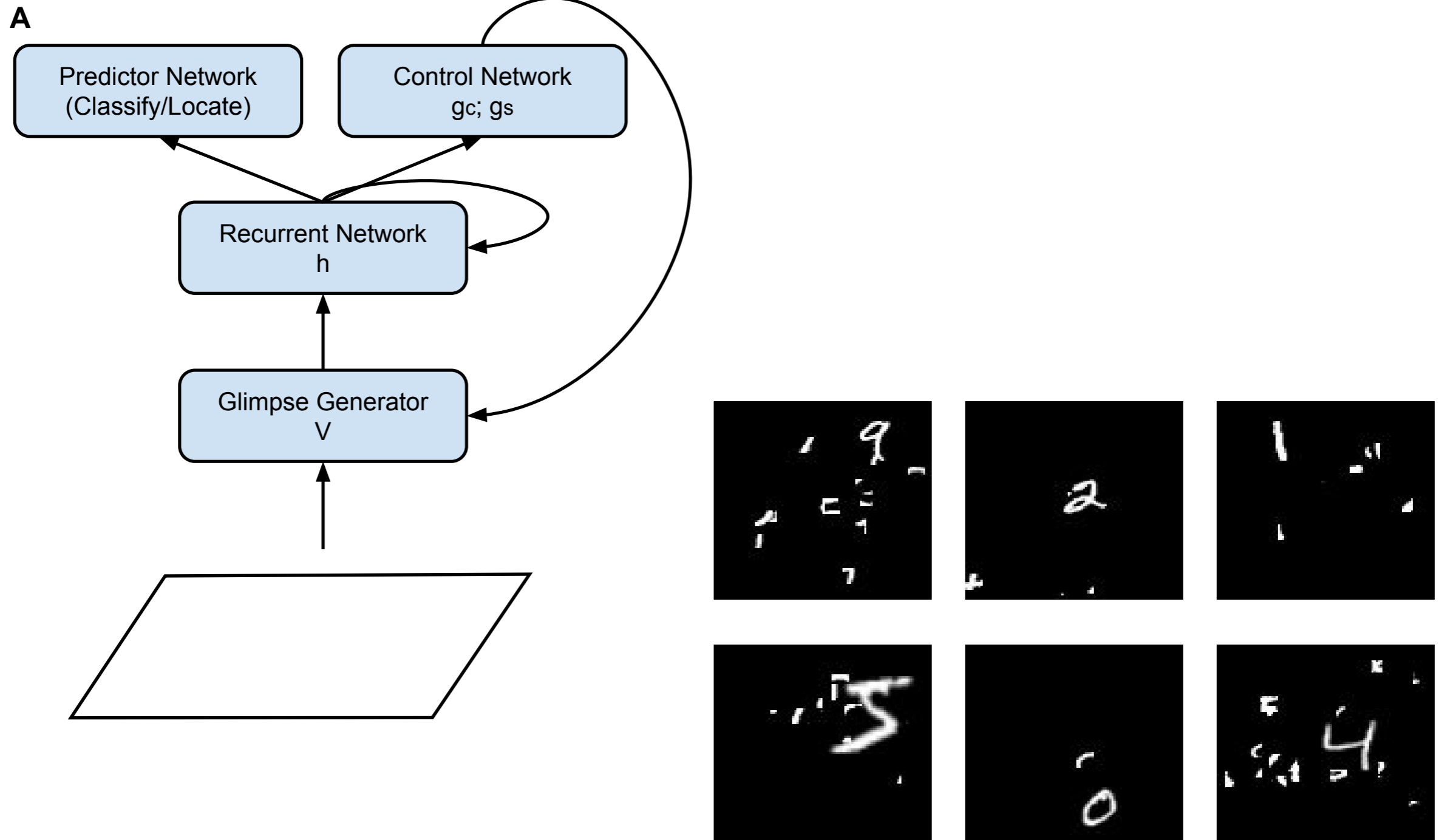


Minimal letter size required for recognition as a function of eccentricity (Anstis, 1974)



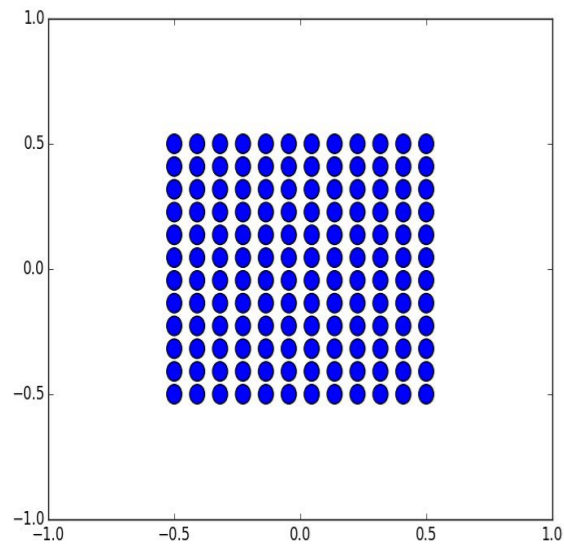
Learning the sampling lattice

(Brian Cheung, Eric Weiss)

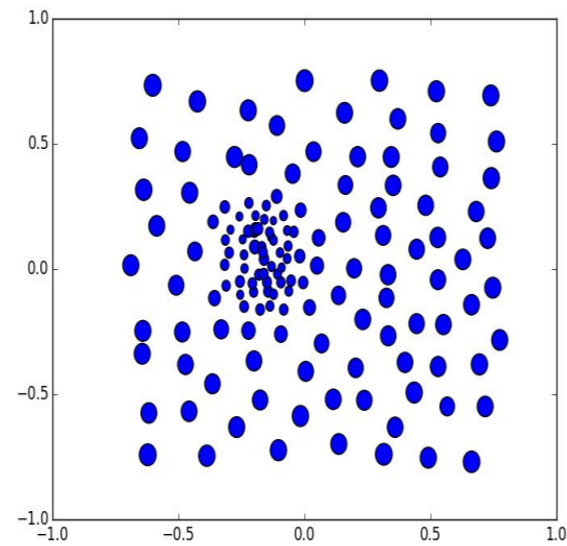


Learned glimpse window sampling lattices

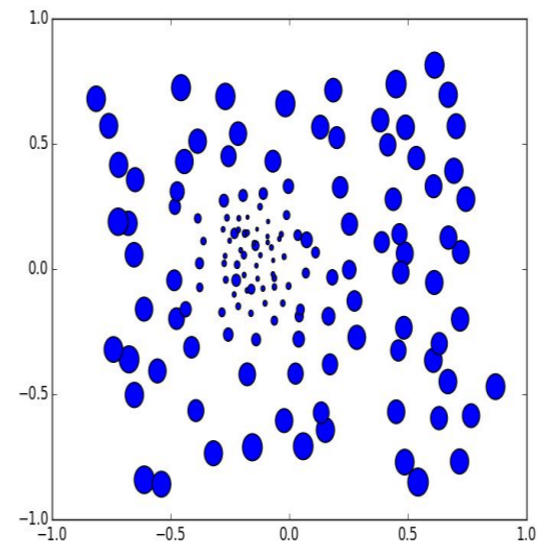
Initial Kernel Filter Layout



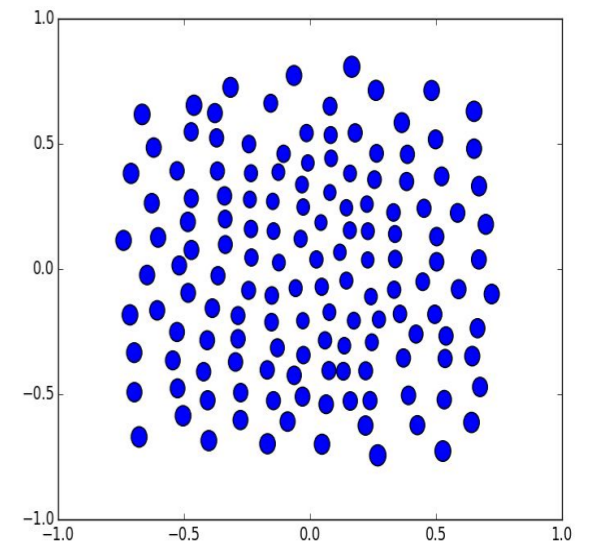
Translation Only



Translation Only (RR)



Translation and Scaling



Five lessons from biology

- Tiny brains
- Nonlinear processing in dendritic trees
- Sparse, overcomplete representations
- Feedback
- Active perception

20 years of learning about vision: Questions answered, questions unanswered, and questions not yet asked. In: *20 Years of Computational Neuroscience*. J.M. Bower, Ed. (Symposium of the CNS2010 annual meeting)

Lewicki MS, Olshausen BA, Surlykke A, Moss CF (2014) Scene analysis in the natural environment. *Frontiers in Psychology*, 5, article 199.

Olshausen BA (2014) Perception as an inference problem. In: *The Cognitive Neurosciences V*, M. Gazzaniga, R. Mangun, Eds. MIT Press.

<http://redwood.berkeley.edu/bruno>