

INFINITE RESTRICTED BOLTZMANN MACHINE

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Joint work with Hugo Larochelle

A RESEARCH AGENDA

- Deep learning successes have required a lot of labeled training data
 - ▶ collecting and labeling such data requires significant human labor
 - ▶ is that really how we'll solve AI ?
- Alternative solution : exploit other sources of data that are imperfect but plentiful
 - ▶ unlabeled data (unsupervised learning)
 - ▶ multimodal data (multimodal learning)
 - ▶ multidomain data (transfer learning, domain adaptation)

A RESEARCH AGENDA

- By far the largest source is unlabeled data
 - ▶ effectively requires algorithms for *life-long learning*
- We are currently poorly equipped to deal with this setting
 - ▶ how to do online learning for non-convex models, with a changing input distribution?
 - ▶ how to have models whose capacity adapts during training?

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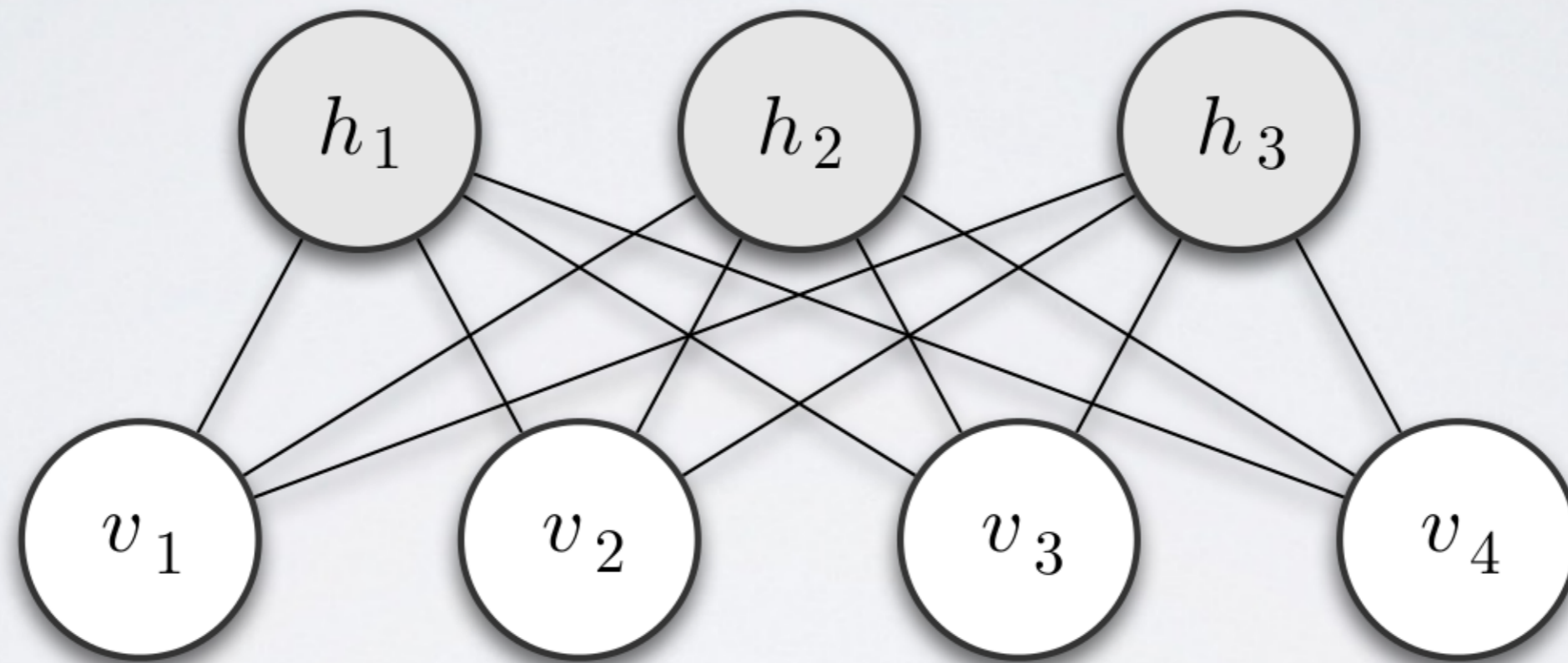
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- In this talk: an infinite restricted Boltzmann machine (iRBM)
 - ▶ RBM with capacity that can grow during training
 - ▶ growing mechanism is derived naturally from the energy function definition

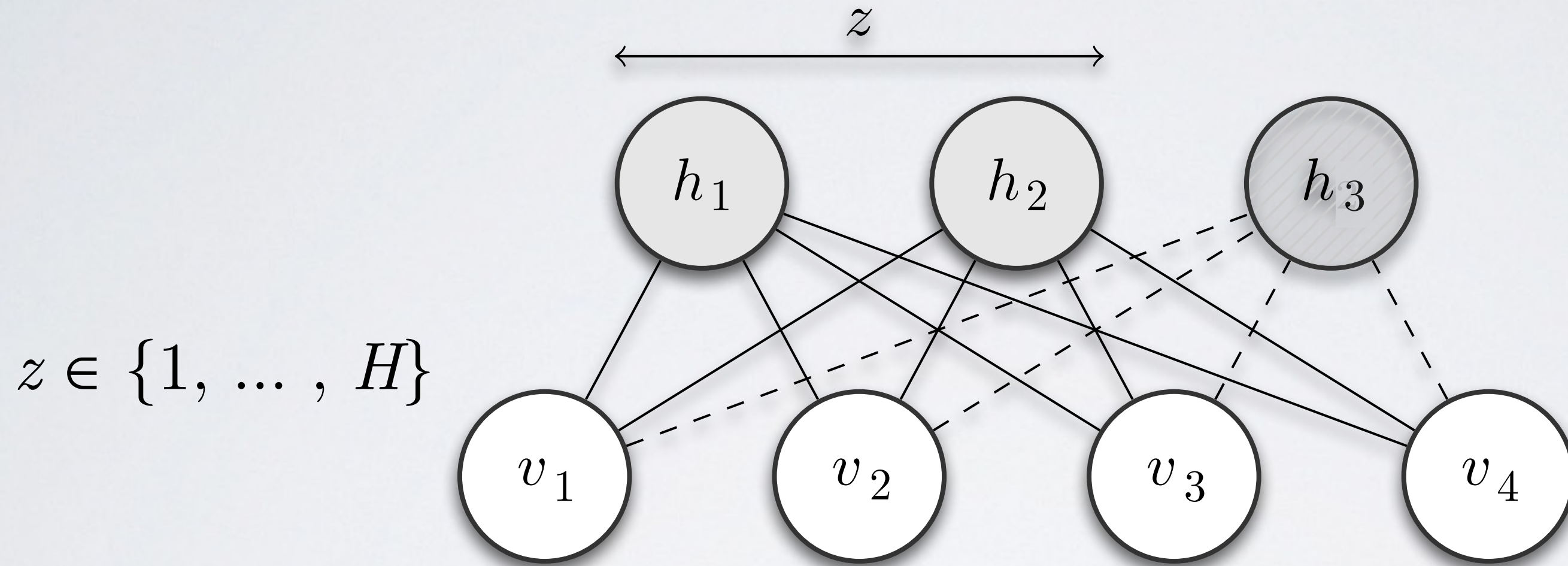
RESTRICTED BOLTZMANN MACHINE



$$E(\mathbf{v}, \mathbf{h}) = -\mathbf{h}^T \mathbf{W} \mathbf{v} - \mathbf{v}^T \mathbf{b}^v - \mathbf{h}^T \mathbf{b}^h$$

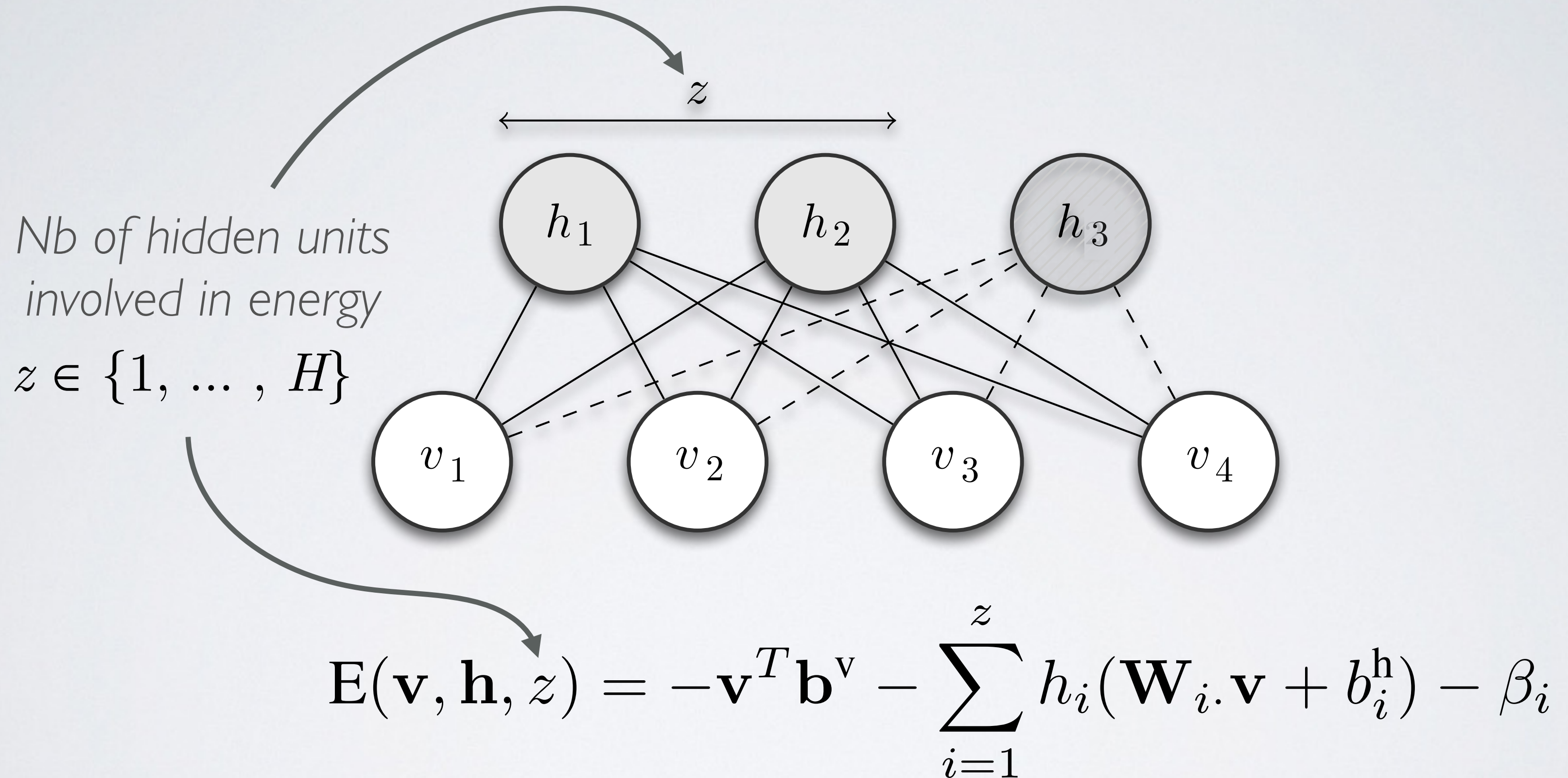
$$P(\mathbf{v}, \mathbf{h}) = e^{-E(\mathbf{v}, \mathbf{h})} / Z$$

ORDERED RESTRICTED BOLTZMANN MACHINE

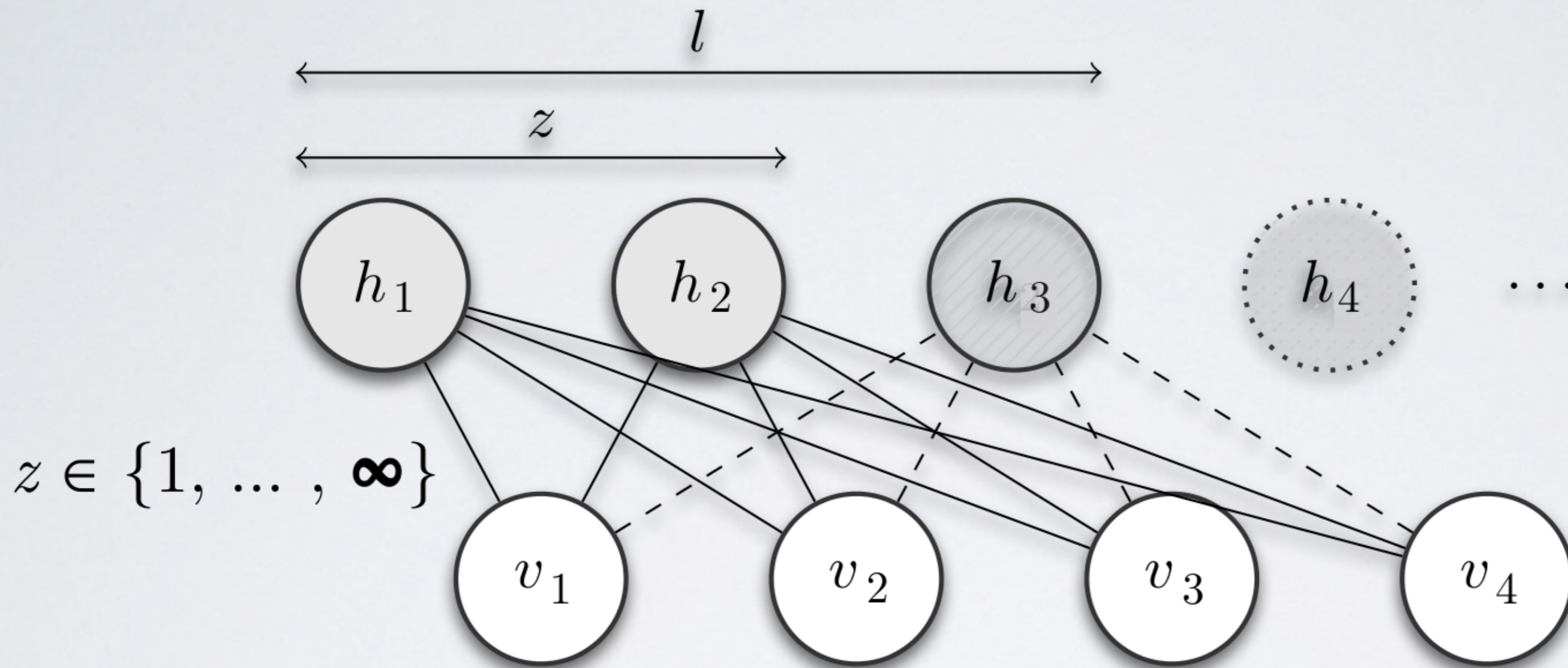


$$\mathbf{E}(\mathbf{v}, \mathbf{h}, z) = -\mathbf{v}^T \mathbf{b}^v - \sum_{i=1}^z h_i (\mathbf{W}_i \cdot \mathbf{v} + b_i^h) - \beta_i$$

ORDERED RESTRICTED BOLTZMANN MACHINE

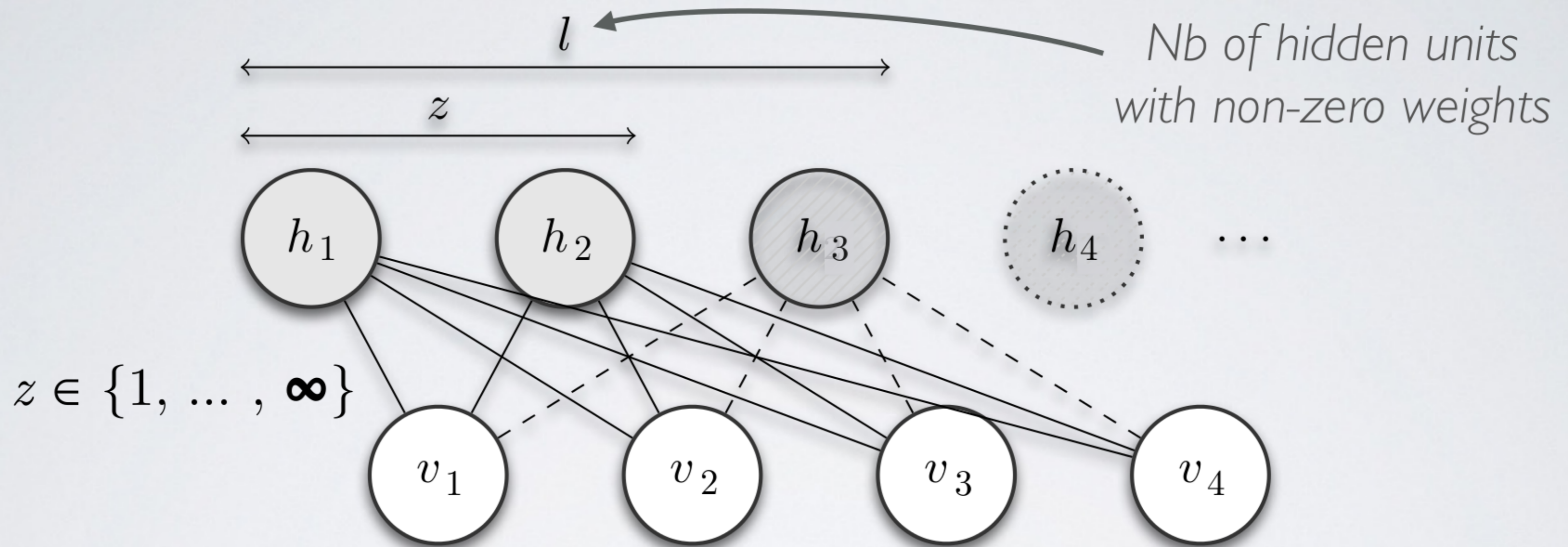


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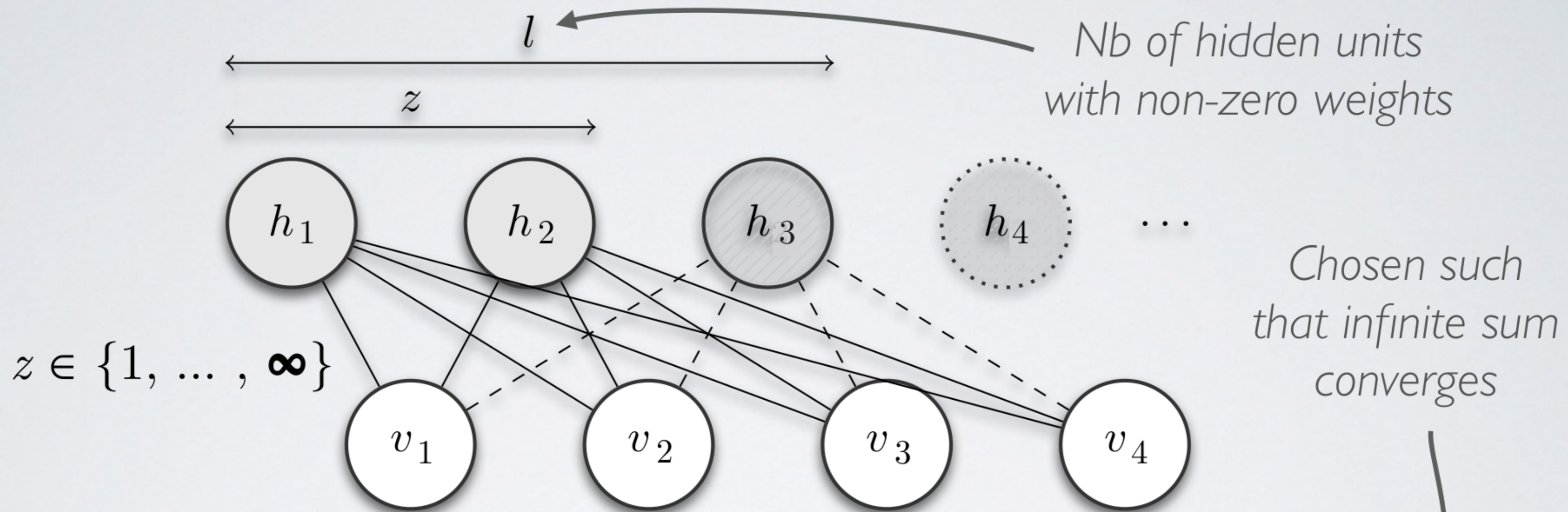
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INFINITE RESTRICTED BOLTZMANN MACHINE

- Free energy, given a certain value of z

$$F(\mathbf{v}, z) = -\mathbf{v}^T \mathbf{b}^v - \sum_{i=1}^z \text{soft}_+(\mathbf{W}_i \cdot \mathbf{v} + b_i^h) - \beta_i$$

- For the iRBM to be practical, we must be able to compute

$$P(z|\mathbf{v}) = \frac{\exp(-F(\mathbf{v}, z))}{Z(\mathbf{v})} = \frac{\exp(-F(\mathbf{v}, z))}{\sum_{z'}^{\infty} \exp(-F(\mathbf{v}, z'))}$$

INFINITE RESTRICTED BOLTZMANN MACHINE

$$\begin{aligned}
 Z(\mathbf{v}) &= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \sum_{z=l+1}^{\infty} \exp(-F(\mathbf{v}, z)) \\
 &= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \sum_{z=l+1}^{\infty} \exp\left(-F(\mathbf{v}, l) + \sum_{i=l+1}^z \text{soft}_+(\mathbf{W}_i \cdot \mathbf{v} + b_i^h) - \beta_i\right)
 \end{aligned}$$

INFINITE RESTRICTED BOLTZMANN MACHINE

$$Z(\mathbf{v}) = \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \sum_{z=l+1}^{\infty} \exp(-F(\mathbf{v}, z))$$

$$\beta_i = \beta \text{soft}_+(b_i^h)$$

$$\beta > 1$$

$$= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \sum_{z=l+1}^{\infty} \exp\left(-F(\mathbf{v}, l) + \sum_{i=l+1}^z \text{soft}_+(\mathbf{W}_i \cdot \mathbf{v} + b_i^h) - \beta_i\right)$$

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$$= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \exp(-F(\mathbf{v}, l)) \sum_{z=l+1}^{\infty} \exp\left(\sum_{i=l+1}^z (1 - \beta) \text{soft}_+(0)\right)$$

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$$= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \exp(-F(\mathbf{v}, l)) \sum_{z=1}^{\infty} \exp((1 - \beta) \text{soft}_+(0))^z$$

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$$= \sum_{z=1}^l \exp(-F(\mathbf{v}, z)) + \exp(-F(\mathbf{v}, l)) \underbrace{\sum_{z=1}^{\infty} \exp((1 - \beta) \text{soft}_+(0))^z}_{\text{Geometric series}}$$

Geometric series

INFINITE RESTRICTED BOLTZMANN MACHINE

- Can perform Gibbs sampling
 - ▶ before sampling \mathbf{h} , first sample z given \mathbf{v}

$$P(z|\mathbf{v}) = \frac{\exp(-F(\mathbf{v}, z))}{Z(\mathbf{v})}$$

$$P(h_i = 1|\mathbf{v}, z) = \begin{cases} \sigma(\mathbf{W}_i \cdot \mathbf{v} + b_i^h) & \text{if } i \leq z \\ 0 & \text{otherwise} \end{cases}$$
$$P(v_j = 1|\mathbf{h}, z) = \sigma \left(\sum_{i=1}^z W_{ij} h_i + b_j^v \right)$$

INFINITE RESTRICTED BOLTZMANN MACHINE

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- If can perform Gibbs sampling, can perform contrastive divergence CD training
 - ▶ Gibbs sampling provides negative samples for update

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 - ▶ before sampling \mathbf{h} , first sample z given \mathbf{v}
- If can perform Gibbs sampling, can perform contrastive divergence CD training
 - ▶ Gibbs sampling provides negative samples for update
- CD training is well defined
 - ▶ only selected hidden units get a non-zero gradient on their weights
 - ▶ any amount of regularization ensures that training does not diverge to infinitely many units with non-zero weights

Training of iRBM

EXPERIMENTS

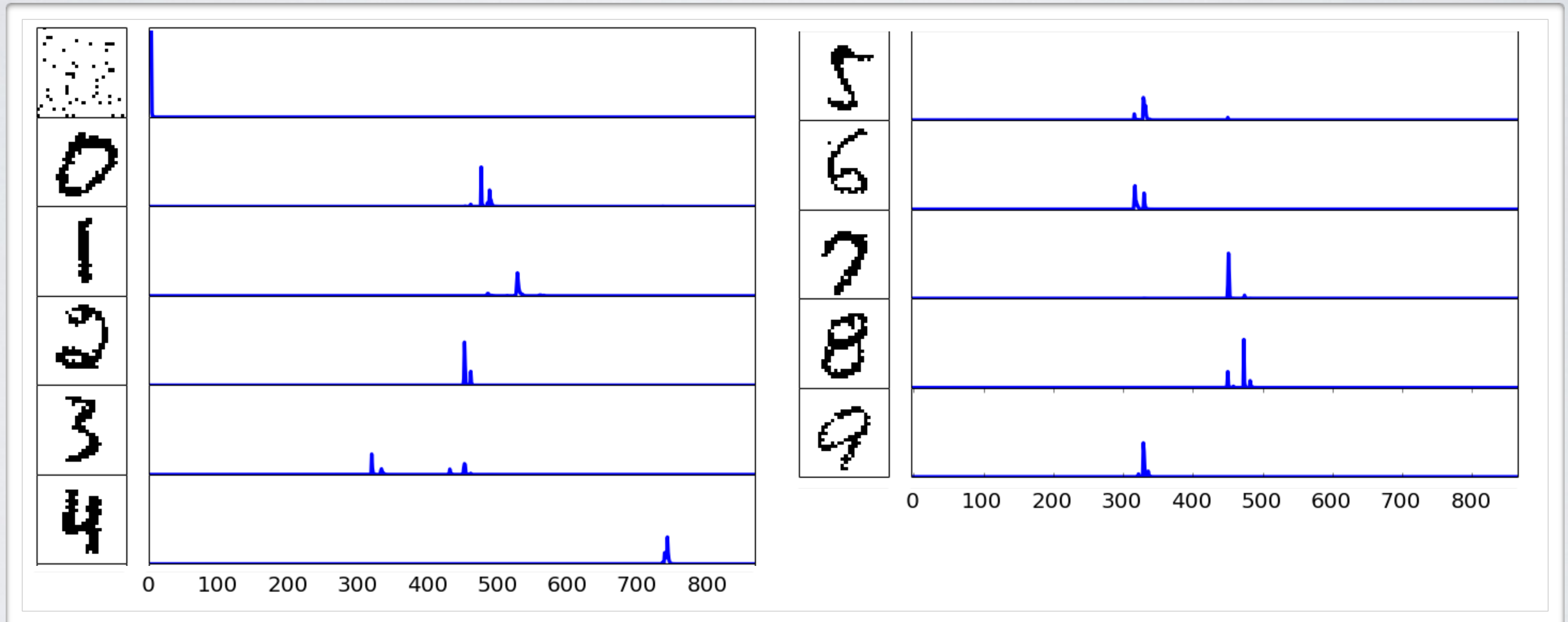
- Binarized MNIST and CalTech101 Silhouettes

MODEL	BINARIZED MNIST			CALTECH101 SILHOUETTES		
	SIZE	$\ln(\hat{Z} \pm 3\sigma)$	AVG. NLL	SIZE	$\ln(\hat{Z} \pm 3\sigma)$	AVG. NLL
RBM	100	[600.88, 600.95]	98.17 ± 0.52	100	[2511.62, 2512.56]	177.37 ± 2.81
RBM	500	[613.24, 613.31]	86.50 ± 0.44	500	[2385.68, 2386.10]	119.05 ± 2.27
RBM	2000	[1098.94, 1099.17]	85.03 ± 0.42	2000	[3349.85, 3354.15]	118.29 ± 2.25
oRBM	500	[39.90, 40.19]	88.15 ± 0.46	500	[1782.88, 1783.02]	114.99 ± 1.97
iRBM	1208	[40.03, 40.54]	85.65 ± 0.44	915	[1999.93, 2000.22]	121.47 ± 2.07

- Use adagrad for training
- Training robust to value of β
 - used 1.01 in all experiments

EXPERIMENTS

- Distribution $p(z | \mathbf{v})$ (Binarized MNIST)



FUTURE WORK

- Can be extended to other types of representations
 - ▶ feed-forward neural networks
 - ▶ RBM with softmax units, for quantization-based fast search
 - ▶ RBM with tree-based representations, for hierarchical topic modeling
 - ▶ word representations (infinite Skip-Gram, Nalisnick and Ravi, 2015)

<http://github.com/MarcCote/iRBM>
<http://arxiv.org/abs/1502.02476>

Côté & Larochelle (2016) **An Infinite Restricted Boltzmann Machine**. *Neural Computation*

MERCI !

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