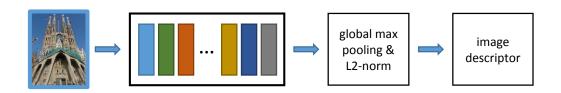


Filip Radenović Giorgos Tolias Ondřej Chum

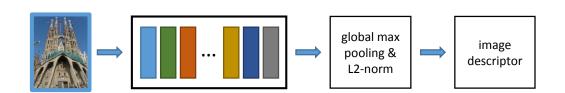
Center for Machine Perception, CTU in Prague

CNN Image Retrieval compact image descriptors
Nearest Neighbor search



#### **CNN Image Retrieval**

compact image descriptors Nearest Neighbor search

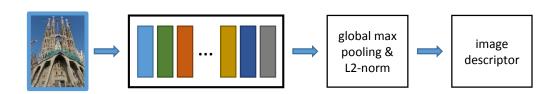


#### **CNN** Learning (Fine-Tuning)

start with CNN trained for different but similar task (reasonable parameters) re-train with data relevant to your task

#### **CNN Image Retrieval**

compact image descriptors Nearest Neighbor search

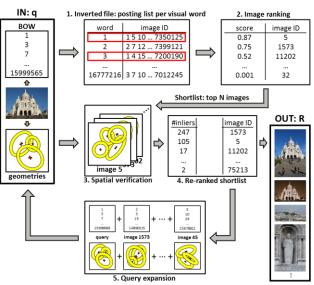


#### **CNN** Learning (Fine-Tuning)

start with CNN trained for different but similar task (reasonable parameters) re-train with data relevant to your task

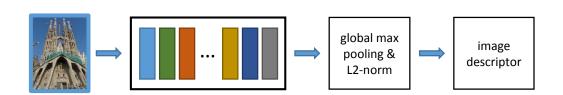
#### Bag of Words

state-of-the-art retrieval performance couples well with SfM



#### **CNN Image Retrieval**

compact image descriptors Nearest Neighbor search



#### **CNN** Learning (Fine-Tuning)

start with CNN trained for different but similar task (reasonable parameters) re-train with data relevant to your task

#### **Bag of Words**

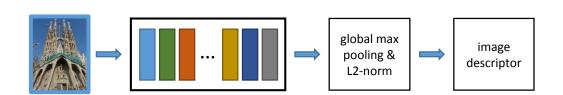
state-of-the-art retrieval performance couples well with SfM

#### Unsupervised training data generation

no human interaction

#### **CNN Image Retrieval**

compact image descriptors Nearest Neighbor search



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#### **Bag of Words**

state-of-the-art retrieval performance couples well with SfM

#### Unsupervised training data generation

no human interaction

#### **Hard Examples**









hard positives

hard negatives

Significant viewpoint and/or scale change Significant illumination change

Severe occlusions

Visually similar but different objects

**BoW:** affine co-variant local features, invariant descriptors











Significant viewpoint and/or scale change

Significant illumination change

Severe occlusions

Visually similar but different objects

**BoW: color-normalized feature descriptors** 









Significant viewpoint and/or scale change Significant illumination change

Severe occlusions

Visually similar but different objects

**BoW:** locality of the features, geometric verification











Significant viewpoint and/or scale change Significant illumination change Severe occlusions



Visually similar but different objects

BoW: discriminability of the features, geometric verification









Significant viewpoint and/or scale change Significant illumination change Severe occlusions



Visually similar but different objects

**BoW:** discriminability of the features, geometric verification







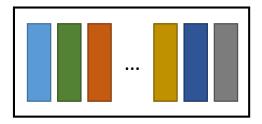




Large Internet photo collection



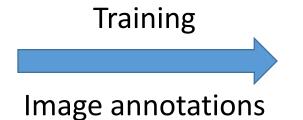
Large Internet photo collection



Convolutional Neural Network (CNN)



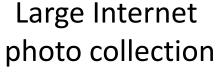
Large Internet photo collection





Convolutional Neural Network (CNN)







Not accurate

Expensive \$\$



Convolutional Neural Network (CNN)

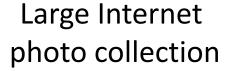
Manual cleaning of the training data done by Researchers



Very expensive \$\$\$\$



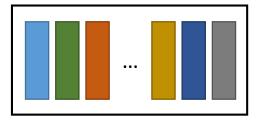






Not accurate Expensive \$\$





Convolutional Neural Network (CNN)

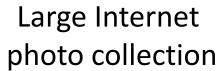
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Very expensive \$\$\$\$

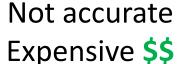
















Convolutional Neural Network (CNN)



Automated extraction of training data

Very accurate Free \$



#### Off-the-shelf CNN

- Target application: classification
- Training dataset: ImageNet
- Architecture: AlexNet & VGG



Images from ImageNet.org

#### Directly applicable to other tasks

#### Fine-grain classification









Images from ImageNet.org

#### Object detection









Images from PASCAL VOC 2012

#### Image retrieval













CNN pre-trained for classification task used for retrieval

[Gong et al. ECCV'14, Babenko et al. ICCV'15, Kalantidis et al. arXiv'15, Tolias et al. ICLR'16]

















CNN pre-trained for classification task used for retrieval

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Fine-tuned CNN using a dataset with landmark classes

















CNN pre-trained for classification task used for retrieval

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Fine-tuned CNN using a dataset with landmark classes

















 NetVLAD: Weakly supervised fine-tuned CNN using GPS tags



CNN pre-trained for classification task used for retrieval

[Gong et al. ECCV'14, Babenko et al. ICCV'15, Kalantidis et al. arXiv'15, Tolias et al. ICLR'16]

















Fine-tuned CNN using a dataset with landmark classes









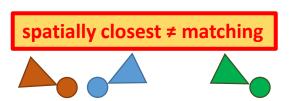








 NetVLAD: Weakly supervised fine-tuned CNN using GPS tags



We propose: automatic annotations for CNN training

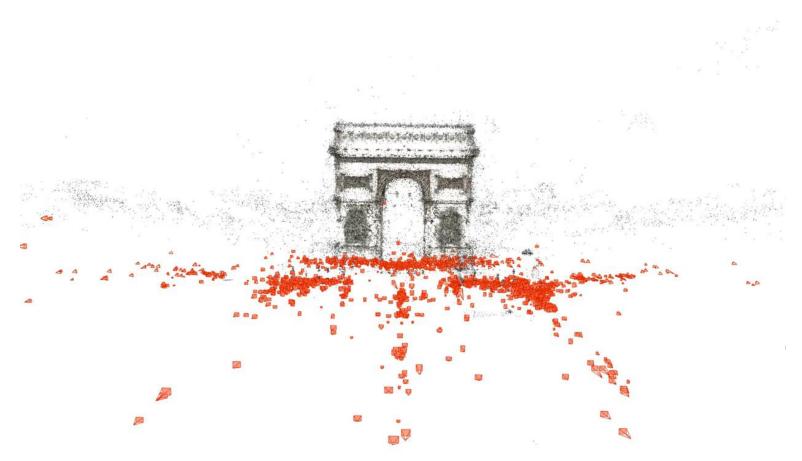








## CNN learns from BoW – Training Data



[Schonberger et al. CVPR'15] [Radenovic et al. CVPR'16]

7.4M images → 713 training 3D models

## CNN learns from BoW – Training Data

**Camera Orientation Known Number of Inliers Known** 



[Schonberger et al. CVPR'15] [Radenovic et al. CVPR'16]

7.4M images → 713 training 3D models

Negative examples: images from different 3D models than the query

Hard negatives: closest negative examples to the query

Only hard negatives: as good as using all negatives, but faster







Negative examples: images from different 3D models than the query

**Hard negatives:** closest negative examples to the query

Only hard negatives: as good as using all negatives, but faster

query

the most similar CNN descriptor











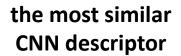


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#### increasing CNN descriptor distance to the query



naive hard negatives top k by CNN



























Negative examples: images from different 3D models than the query

**Hard negatives:** closest negative examples to the query

Only hard negatives: as good as using all negatives, but faster

#### increasing CNN descriptor distance to the query

the most similar CNN descriptor

top k by CNN

diverse hard negatives top k: one per 3D model



























**Positive examples:** images that share 3D points with the query **Hard positives:** positive examples not close enough to the query





Positive examples: images that share 3D points with the query Hard positives: positive examples not close enough to the query

query

top 1 by CNN









used in NetVLAD

**Positive examples:** images that share 3D points with the query **Hard positives:** positive examples not close enough to the query

query

top 1 by CNN

top 1 by BoW







harder positives







used in NetVLAD

**Positive examples:** images that share 3D points with the query **Hard positives:** positive examples not close enough to the query

top 1 by CNN

top 1 by BoW

random from top k by BoW









harder positives



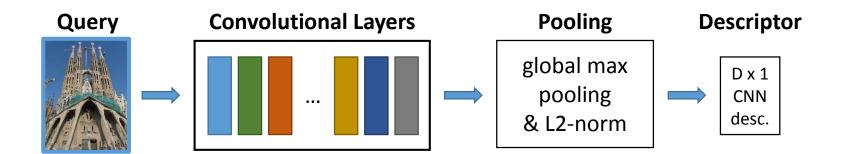




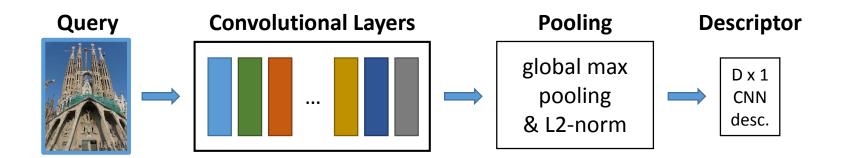


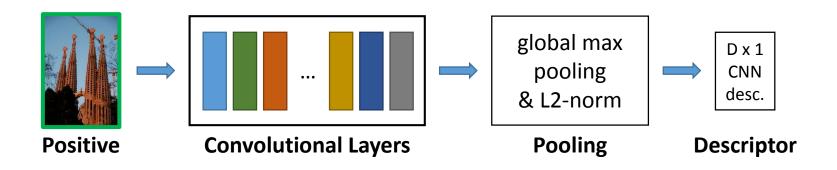
used in NetVLAD

## **CNN Siamese Learning**

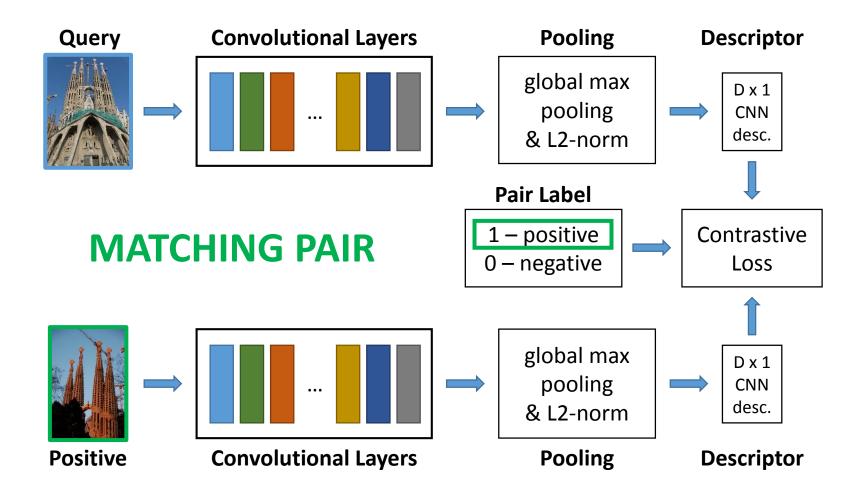


## **CNN Siamese Learning**

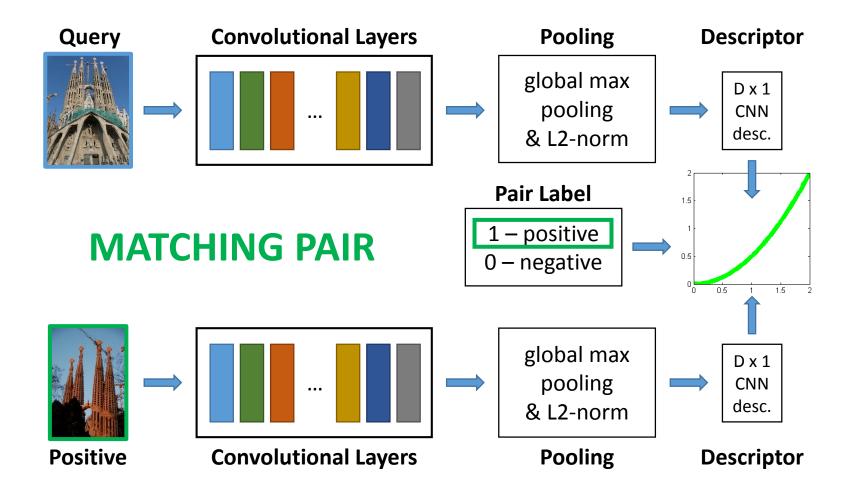




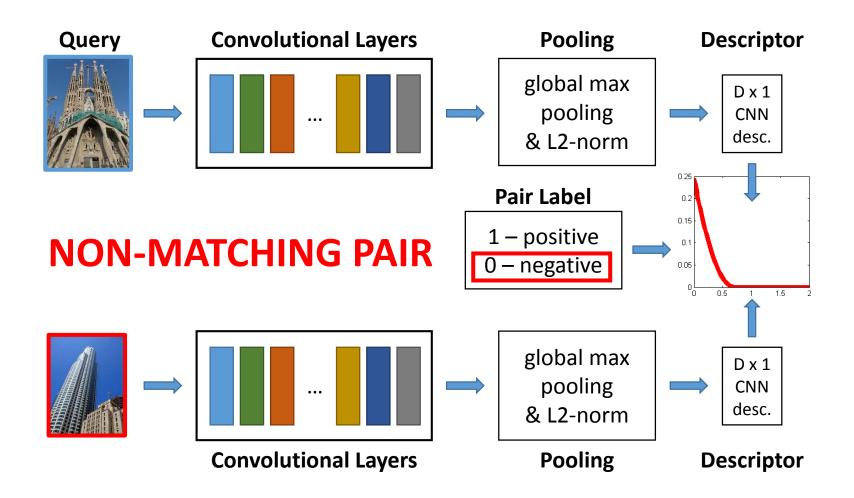
## **CNN Siamese Learning**



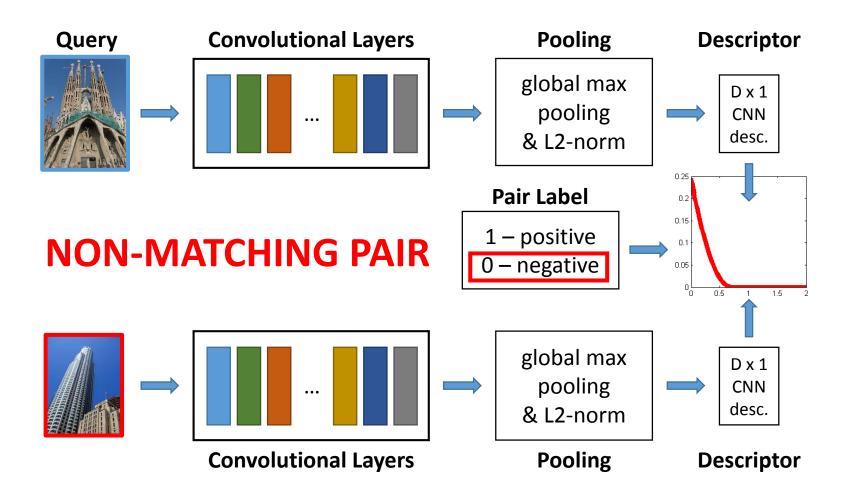
# **CNN Siamese Learning**



# **CNN Siamese Learning**

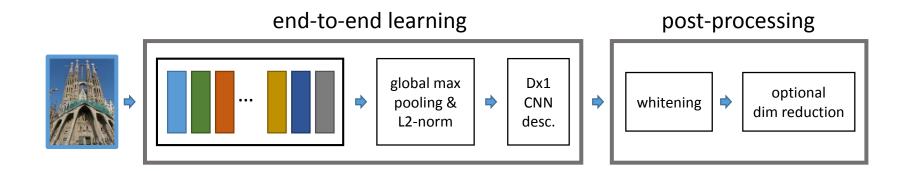


# **CNN Siamese Learning**

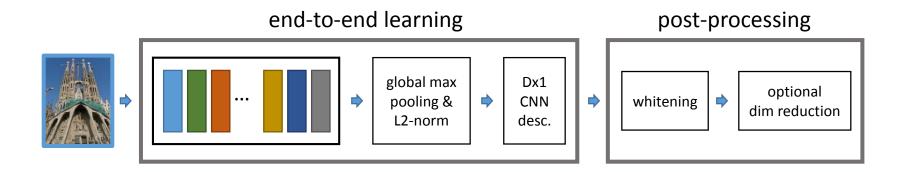


### **Contrastive vs. Triplet loss: Contrastive better with our data**

Contrastive loss more strict, requires accurate training data Triplet loss less sensitive to inaccurate annotation

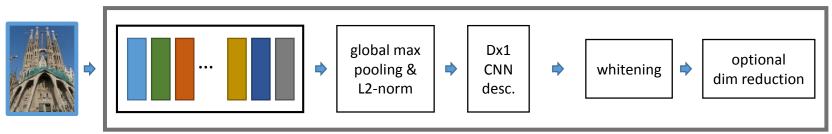


1. PCA<sub>w</sub> – PCA of an independent set of descriptors [Babenko et al. ICCV'15, Tolias et al. ICLR'16]

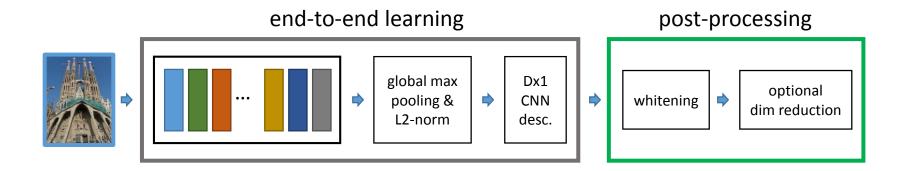


- 1. PCA<sub>w</sub> PCA of an independent set of descriptors [Babenko et al. ICCV'15, Tolias et al. ICLR'16]
- 2.  $L_w$  We propose to learn whitening using labeled training data and linear discriminant projections

end-to-end learning



- 1. PCA<sub>w</sub> PCA of an independent set of descriptors [Babenko et al. ICCV'15, Tolias et al. ICLR'16]
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- 3. End-to-end Learning Performs comparable or worse than  $L_w$ , while slowing down the convergence



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## Experiments – datasets

 Oxford 5k dataset [Philbin et al. CVPR'07]



- Paris 6k dataset
- [Philbin et al. CVPR'08]
- Holidays dataset [Jegou et al. ECCV'10]



 100k distractor dataset [Philbin et al. CVPR'07]

Protocol: mean Average Precision (mAP)

## Experiments – datasets

 Oxford 5k dataset [Philbin et al. CVPR'07]











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• Holidays dataset [Jegou et al. ECCV'10]









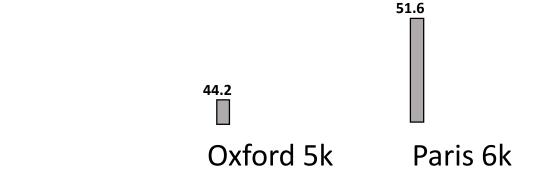


• 100k distractor dataset [Philbin et al. CVPR'07]

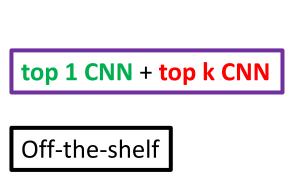
Training 3D models do not contain any landmark from these datasets

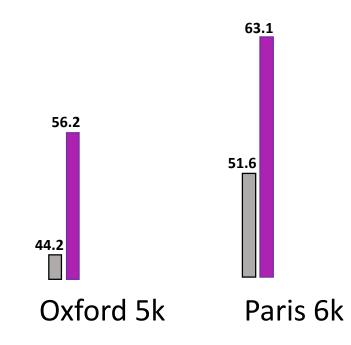
Protocol: mean Average Precision (mAP)

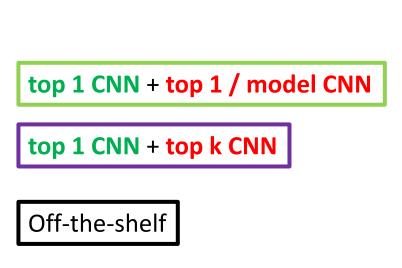
 Careful choice of positive and negative training images makes a difference

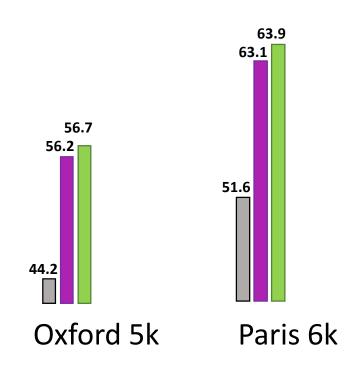


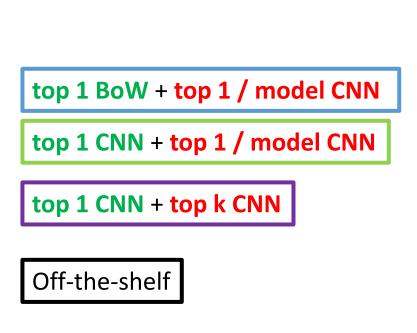
Off-the-shelf

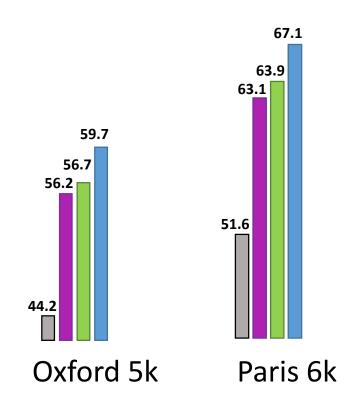


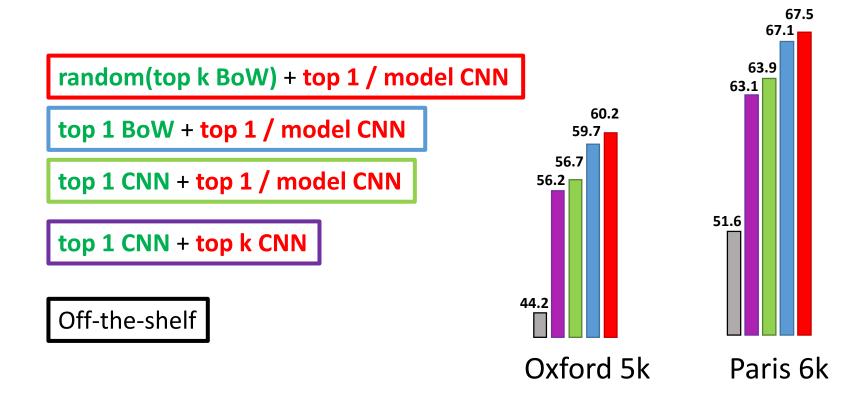


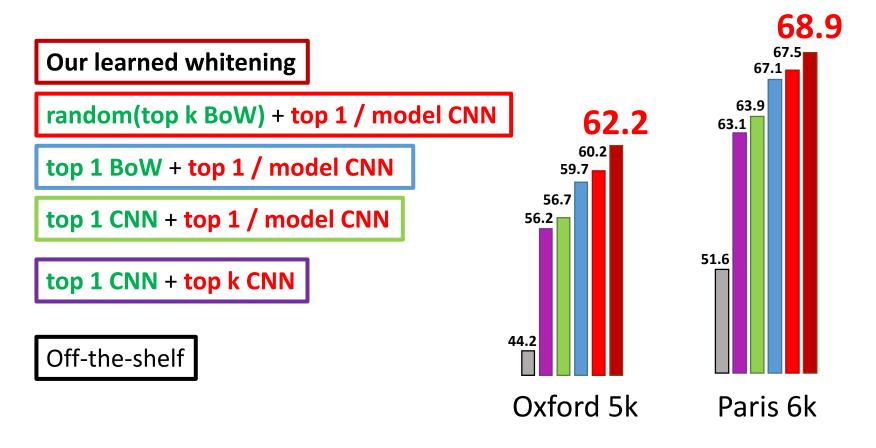








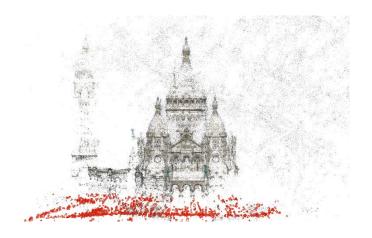




### Experiments – Over-fitting and Generalization

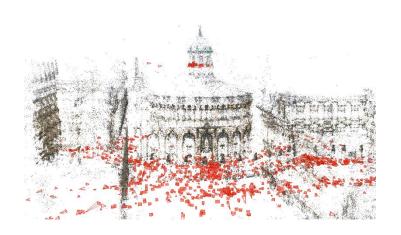
We added Oxford and Paris landmarks as 3D models and repeated fine-tuning





### Experiments – Over-fitting and Generalization

 We added Oxford and Paris landmarks as 3D models and repeated fine-tuning





Only +0.3 mAP on average over all testing datasets

# State-of-the-art

Method		$\mathbf{D}$	$O_{X}$	f5k	Oxf	105k	Pa	r6k	Par	106k	Hol	Н
Method			$\mathtt{Crop}_{\mathcal{I}}$	${\tt Crop}_{\mathcal X}$		10						
		(	Comp	act re	eprese	ntatio	ons					
mVoc/BoW [11]		128	48.8	_	41.4	_	_	_	_	_	65.6	-
Neural codes <sup>†</sup> [14]	(fA)	128	_	55.7	_	52.3	_	_	_	_	78.9	
$MAC^{\ddagger}$				55.7	43.8	45.6	69.5	70.6	53.4	55.4	72.6	56
CroW [24]	$(\mathbf{V})$	128	59.2	_	51.6	_	74.6	_	63.2	_	_	-
⋆ MAC	$(\mathbf{fV})$	128	75.8	76.8	68.6	70.8	77.6	78.8	68.0	69.0	73.2	58
★ R-MAC										71.2		
$MAC^{\ddagger}$										57.3		
SPoC [23]	$(\mathbf{V})$	256	_	53.1	_	50.1	_	_	_	_	80.2	-
R-MAC [25]			56.1	_	47.0	_	72.9	_	60.1	_	_	-
CroW [24]	$(\mathbf{V})$	256	65.4	_	59.3	_	77.9	_	67.8	_	83.1	
NetVlad [35]	$(\mathbf{V})$	256	_	55.5	_	_	_	67.7	_	_	86.0	
NetVlad [35]	$(\mathbf{fV})$	256	_	63.5	_	_	_	73.5	_	_	84.3	-
⋆ MAC	$(\mathbf{f}\mathbf{A})$	256	62.2	65.4	52.8	58.0	68.9	72.2	54.7	58.5	76.2	63
★ R-MAC										64.8		
⋆ MAC						72.6					77.3	
★ R-MAC	$(\mathbf{fV})$	256	74.9	78.2	67.5	72.1	82.3	83.5	74.1	75.6	81.4	69
MAC <sup>‡</sup>	$(\mathbf{V})$	512	56.4	58.3	47.8	49.2	72.3	72.6	58.0	59.1	76.7	62
R-MAC [25]	$(\mathbf{V})$	512	66.9	_	61.6	_	83.0	_	75.7	_	_	
CroW [24]	$(\mathbf{V})$	512	68.2	_	63.2	_	79.6	_	71.0	_	84.9	-
⋆ MAC	$(\mathbf{fV})$	512	79.7	80.0	73.9	75.1	82.4	82.9	74.6	75.3	79.5	6
★ R-MAC	$(\mathbf{fV})$	512	77.0	80.1	69.2	74.1	83.8	85.0	76.4	77.9	82.5	71
			Ext	reme	short	codes	S					
Neural codes <sup>†</sup> [14]	$\overline{(\mathbf{f}\mathbf{A})}$	16	_	41.8	_	35.4	_	_	_	_	60.9	-
⋆ MAC	$(\mathbf{fV})$	16	56.2	57.4	45.5	47.6	57.3	62.9	43.4	48.5	51.3	25
★ R-MAC	$(\mathbf{fV})$	16	46.9	52.1	37.9	41.6	<b>58.8</b>	63.2	45.6	49.6	54.4	31
Neural codes <sup>†</sup> [14]	$\overline{(\mathbf{f}\mathbf{A})}$	32	_	51.5	_	46.7	_	_	_	_	72.9	
★ MAC	$(\mathbf{fV})$	32	65.3	69.2	55.6	59.5	63.9	69.5	51.6	56.3		
★ R-MAC	$(\mathbf{fV})$									55.8		
	Re-ra	nkin	g (R)	and	query	expa	ansion	ı (QE	)			
BoW(1M)+QE [6]						_			,	_	_	
BoW(16M) + QE[50]		_	84.9	_	79.5	_	82.4	_	77.3	_	_	
HQE(65k) [8]		_	88.0	1	84.0	_	82.8	_	_	_	_	-
R-MAC+R+QE [25]	$(\mathbf{V})$	512	77.3	_	73.2	_	86.5	_	79.8	_	_	-
CroW+QE  [24]			72.2	1	67.8	_	85.5	_	79.7	_	_	-
	. ,	1		85.4	81.8	82.3	86.5	87.0	78.8	79.6	_	-
★ R-MAC+R+QE	$(\mathbf{fV})$	512	82.9	84.5	77.9	80.4	85.6	86.4	78.3	79.7	_	-

# State-of-the-art

### VS.

NetVLAD 256D

Our CNN 32D

			1 1	17.	· L	11	TT	FA	1 L	11		
		(	Comp	act re	prese	ntatio	ons					
mVoc/BoW [11]			48.8	_	41.4		_	_	_	_	65.6	_
Neural codes <sup>†</sup> [14]	(fA)	128	_	55.7	_	52.3	_	_	_	_	78.9	-
MAC <sup>‡</sup>	$(\mathbf{V})$	128				45.6	69.5	70.6	53.4	55.4	72.6	<b>56</b>
CroW [24]	$(\mathbf{V})$	128	59.2	_	51.6	_	74.6	_	63.2	_	_	_
★ MAC	$(\mathbf{fV})$	128	<b>75.8</b>	<b>76.8</b>	68.6	70.8	77.6	78.8	68.0	69.0	73.2	58
★ R-MAC	$(\mathbf{fV})$	128	72.5	76.7	64.3	69.7	<b>78.5</b>	80.3	69.3	71.2	79.3	<b>65</b>
MAC <sup>‡</sup>	$(\mathbf{V})$	256	54.7	56.9	45.6	47.8	71.5	72.4	55.7	57.3	76.5	61
SPoC [23]	$(\mathbf{V})$	256	_	53.1	_	50.1	_	_	_	_	80.2	_
R-MAC [25]	$(\mathbf{A})$	256	56.1	_	47.0	_	72.9	_	60.1	_	_	_
CroW [24]	$(\mathbf{V})$	256	65.4	_	<u>59.3</u>	_	77.9	_	67.8	_	83.1	_
NetVlad [35]	$(\mathbf{V})$	256				_	_	67.7	_	_	86.0	-
NetVlad [35]	$(\mathbf{fV})$	250	- 6	53.	5	_	_	73.5	_	_	84.3	_
* MAC	(fA)	256	(		3	58.0	68.9	72.2	54.7	58.5	76.2	63
★ R-MAC						61.2					81.5	<b>70</b>
★ MAC	(fV)	256	77.4	<b>78.2</b>	70.7	72.6	80.8	81.9	72.2	73.4	77.3	
★ R-MAC	(fV)	256	74.9	<b>78.2</b>	67.5	72.1	82.3	83.5	74.1	<b>75.6</b>	81.4	69
MAC <sup>‡</sup>	$(\mathbf{V})$	512	56.4	58.3	47.8	49.2	72.3	72.6	58.0	59.1	76.7	<b>62</b>
R-MAC [25]	$(\mathbf{V})$	512	66.9	_	61.6	_	83.0	_	75.7	_	_	-
$\operatorname{CroW}[24]$	$(\mathbf{V})$	512	68.2	_	63.2	_	79.6	_	71.0	_	84.9	_
★ MAC	(fV)	512	79.7	80.0	73.9	75.1	82.4	82.9	74.6	75.3	79.5	67
★ R-MAC	$(\mathbf{fV})$	512	77.0	80.1	69.2	74.1	83.8	<b>85.0</b>	76.4	77.9	82.5	71
			Ext	reme	short	codes	3					
Neural codes <sup>†</sup> [14]	(fA)	16		41.8		35.4		_	_	_	60.9	_
* MAC	$(\mathbf{fV})$			57.4	45.5	47.6	57.3	62.9	43.4	48.5	51.3	25
⋆ R-MAC	$(\mathbf{fV})$	16	46.9	52.1	37.9	41.6	58.8	63.2	45.6	49.6	54.4	31
Neural codes <sup>†</sup> [14]	$(\mathbf{f}\mathbf{A})$	32				46.7	_	_	_	_	72.9	_
★ MAC	$(\mathbf{fV})$	32	6	59.2	6	59.5	63.9	69.5	51.6	56.3	62.4	41
★ R-MAC	$(\mathbf{fV})$	32	L	<i>-</i>		55.1	63.9	67.4	52.7	55.8	68.0	49
	Re-ra	nkin	g (R)	and	auery	expa	nsion	(QE	)			
BoW(1M)+QE [6]		_	82.7	_	76.7		80.5		71.0	_		l –
BoW(16M) + QE [50]	]	_	84.9	_	79.5		82.4		77.3	_	_	_
HQE(65k) [8]	1	_	88.0	_	84.0		82.8		_	_	_	_
R-MAC+R+QE [25]	$(\mathbf{V})$	512			73.2		86.5		79.8	_	_	_
CroW + QE  [24]			72.2	_	67.8	I	85.5		79.7	_	_	_
★ MAC+R+QE	\	1		85.4		82.3		ı	ı	79.6	_	_
★ R-MAC+R+QE						80.4				79.7	_	_
· · · •	\ /		L				L				1	

Oxf5k

 $Crop_{\mathcal{I}}$   $Crop_{\mathcal{X}}$ 

Method

Hol

Par106k

 $Crop_{\mathcal{X}}$ 

Par6k

 $Crop_{\mathcal{I}} | Crop_{\mathcal{X}}$ 

 $Crop_{\mathcal{X}}$ 

Hol

101k

# State-of-the-art

# VS.

NetVLAD 256D

# Our CNN 32D

Concurrent work: [Gordo et al. ECCV'16]

mVoc/BoW [11] 41.4 65.6Neural codes<sup>†</sup> [14]  $({\bf f}{\bf A})|128$ 55.7 52.378.9 MAC<sup>‡</sup>  $(\mathbf{V})$  128 53.5 **55.7** 43.8 | 45.6 | 69.5 | **70.6** | 53.4 | **55.4** | 72.6 | **56.7** (V) 128 59.2 51.6 74.6 63.2 CroW [24] ★ MAC  $(\mathbf{fV})$  128 **75.8 76.8 68.6 70.8** 77.6 78.8 **68.0 69.0 73.2** 58.8 ★ R-MAC  $(\mathbf{fV})$  | 128 | 72.5 | 76.7 | 64.3 | 69.7 | **78.5 | 80.3 | 69.3 | 71.2 | 79.3 | 65.2**  $MAC^{\ddagger}$ 56.9 45.6 47.8 71.5 | 72.4 | 55.7 | **57.3** 76.5 **61.3** (V)|25653.1 50.1 80.2 SPoC [23] R-MAC [25]  $(\mathbf{A})|256|56.1$ 47.0 72.9 60.1CroW [24]  $(\mathbf{V})|256|\mathbf{65.4}$ |59.3|77.9 67.8 83.1 NetVlad [35] (V)|256|67.786.0 (fV) 25% 73.5 NetVlad [35] 84.3 58.0 | 68.9 | 72.2 | 54.7 \* MAC  $({\bf f}{\bf A})|256|$ 76.2 63.8 ⋆ R-MAC (fA)|256|62.5|68.9|53.2|61.2|74.4|76.6|61.8|64.8|81.5|70.8 ★ MAC  $(\mathbf{fV})|256|77.4|78.2|70.7|72.6|80.8|81.9|72.2$ ★ R-MAC  $(\mathbf{fV})|256|74.9|\mathbf{78.2}|67.5|72.1|\mathbf{82.3}|\mathbf{83.5}|\mathbf{74.1}|\mathbf{75.6}|81.4$ MAC<sup>‡</sup> (V) | 512 | 56.4 | 58.3 | 47.8 | 49.2 | 72.3 | 72.6 | 58.0 | 59.1 | 76.7 | 62.7 R-MAC [25]  $(\mathbf{V})|512|66.9$ 61.6 83.0 75.7  $(\mathbf{V})|512|\mathbf{68.2}|$ 63.2 79.6 CroW [24] 71.0 84.9  $(\mathbf{fV})|512|79.7|80.0|73.9|75.1|82.4|82.9|74.6|75.3|79.5|67.0$ ★ MAC ★ R-MAC  $(\mathbf{fV})|512|77.0|80.1|69.2|74.1|83.8|85.0|76.4|77.9|82.5|71.5$ Extreme short codes Neural codes<sup>†</sup> [14]  $(\mathbf{f}\mathbf{A})$ 41.8 60.9 \* IVIAC 16 **56.2 57.4 45.5 47.6** 57.3 62.9 43.4 48.5 51.3 25.6 ★ R-MAC 16 46.9 52.1 37.9 41.6 **58.8 63.2 45.6 49.6** 54.4 **31.7** Neural codes<sup>†</sup>  $(\mathbf{f}\mathbf{A})$  32 72.9 46.7 ★ MAC **59.5 63.9 69.5** 51.6 **56.3** 62.4 41.8  $(\mathbf{fV})$  32 32 55.1 **63.9** 67.4 **52.7** 55.8 68.0 **49.6** ★ R-MAC  $(\mathbf{fV})$ Re-ranking (R) and query expansion (QE)

82.7

84.9

88.0

 $(\mathbf{V})|512|77.3$ 

 $(\mathbf{V})|512|72.2$ 

76.7

79.5

84.0

73.2

67.8  $(\mathbf{fV})|512|85.0|85.4|81.8|82.3|86.5|87.0|78.8|79.6$ 

 $(\mathbf{fV})|512|82.9|84.5|77.9|80.4|85.6|86.4|78.3|$ 79.7

Oxf105k

 $\operatorname{Crop}_{\mathcal{I}}$   $\operatorname{Crop}_{\mathcal{X}}$   $\operatorname{Crop}_{\mathcal{I}}$   $\operatorname{Crop}_{\mathcal{X}}$   $\operatorname{Crop}_{\mathcal{I}}$   $\operatorname{Crop}_{\mathcal{X}}$ 

Compact representations

Oxf5k

Method

BoW(1M)+QE [6]

HQE(65k) [8]

CroW+QE [24]

★ MAC+R+QE

★ R-MAC+R+QE

BoW(16M) + QE[50]

R-MAC+R+QE [25]

Par6k

80.5

82.4

82.8

86.5

85.5

71.0

77.3

79.8

79.7

Par106k

 $Crop_{\mathcal{I}}$   $Crop_{\mathcal{X}}$ 

Hol Hol

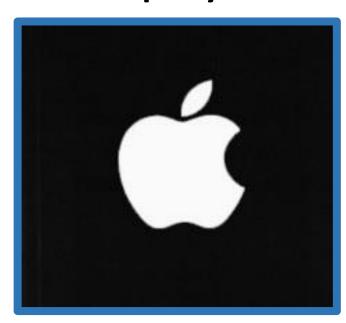
101k

Method	Oxf5k	Oxf105k	Par6k	Par106k
BoW(16M)+R+QE	84.9	79.5	82.4	77.3
CNN(512D)	79.7	73.9	82.4	74.6

Method	Oxf5k	Oxf105k	Par6k	Par106k
BoW(16M)+R+QE	84.9	79.5	82.4	77.3
CNN(512D)	79.7	73.9	82.4	74.6
CNN(512D)+R+QE	85.0	81.8	86.5	78.8

Our CNN with re-ranking (R) and query expansion(QE) surpasses its teacher on all datasets!!!

### query



### top 10 (correct | incorrect)

#### query



**BoW** 























first incorrect at rank 127

### top 10 (correct | incorrect)

#### query



























first incorrect at rank 127























query



#### query



### top 10 (correct | incorrect)



first incorrect at rank 159

### query





top 10 (correct | incorrect)





















first incorrect at rank 159

























top 10 (correct | incorrect) query **BoW Fine-tuning** at rank 159 might not be enough **CNN** 

## Conclusions

 We propose a method to generate the necessary "lots of training examples" without any human interaction

 Strong supervision for hard negative, hard positive mining, and supervised whitening

 Data and trained networks available at: cmp.felk.cvut.cz/~radenfil/projects/siamac.html

For more details about the paper visit Poster O-1A-01

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