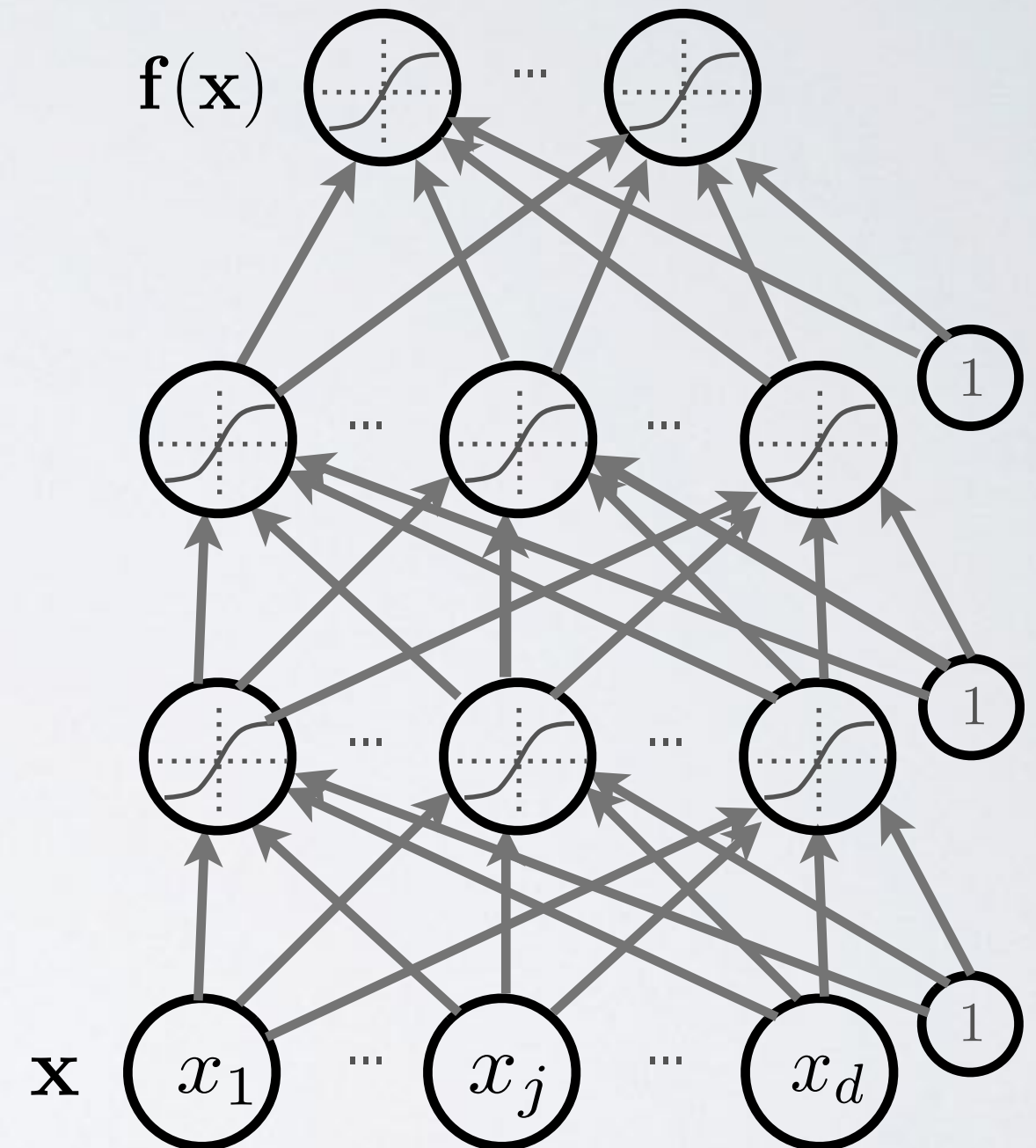


Neural Networks

Hugo Larochelle (@hugo_larochelle)
Google Brain

NEURAL NETWORKS

- What we'll cover
 - ▶ types of learning problems
 - definitions of popular learning problems
 - how to define an architecture for a learning problem
 - ▶ unintuitive properties of neural networks
 - adversarial examples
 - optimization landscape of neural networks



Neural Networks

Types of learning problems

SUPERVISED LEARNING

Topics: supervised learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

• Example

▶ classification

▶ regression

UNSUPERVISED LEARNING

Topics: unsupervised learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)} \sim p(\mathbf{x})$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)} \sim p(\mathbf{x})$$

• Example

▶ distribution estimation

▶ dimensionality reduction

SEMI-SUPERVISED LEARNING

Topics: semi-supervised learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

$$\{\mathbf{x}^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

$$\mathbf{x}^{(t)} \sim p(\mathbf{x})$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

MULTITASK LEARNING

Topics: multitask learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)} \sim p(\mathbf{x}, y_1, \dots, y_M)$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)}\}$$

▶ setting :

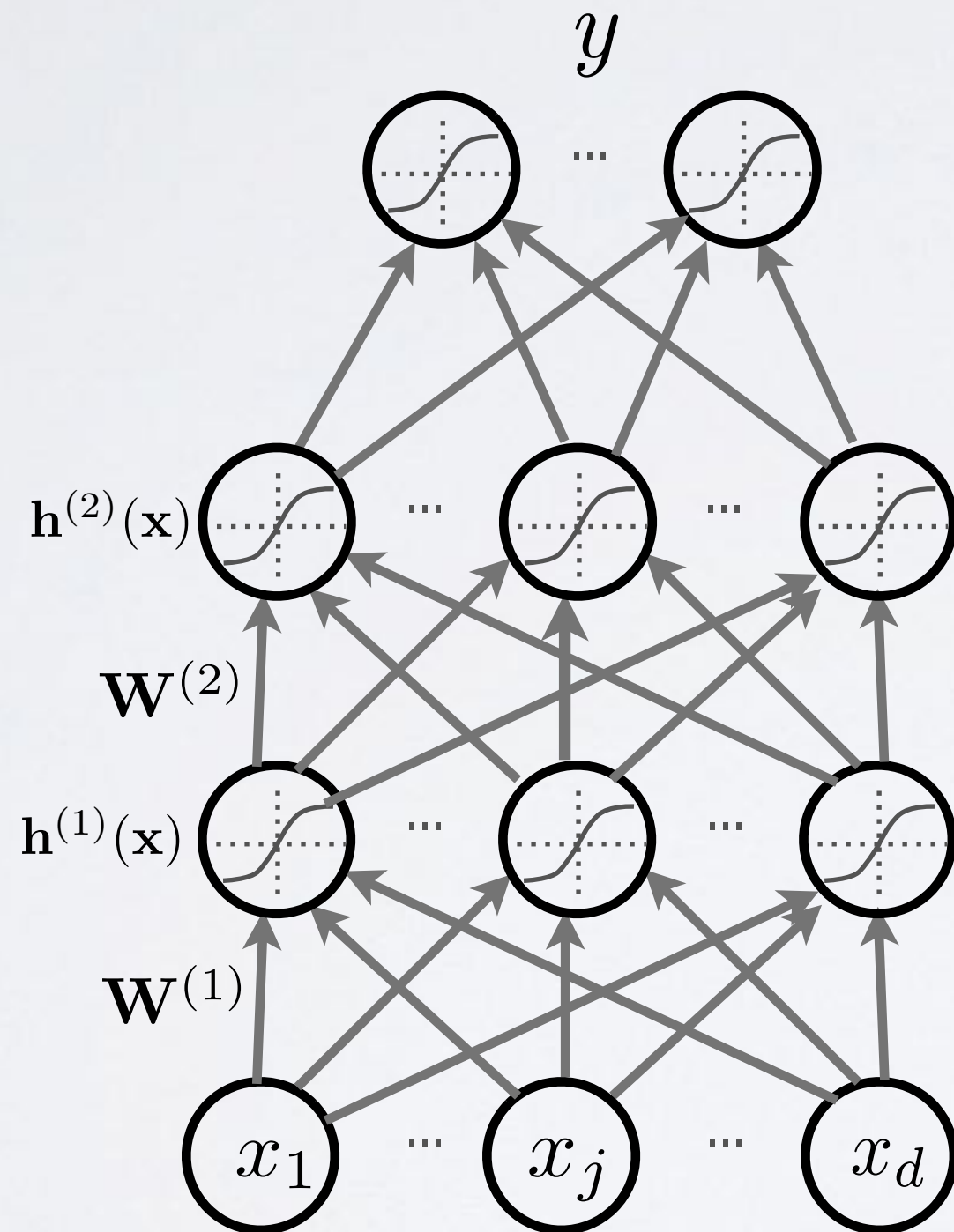
$$\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)} \sim p(\mathbf{x}, y_1, \dots, y_M)$$

• Example

▶ object recognition in images with multiple objects

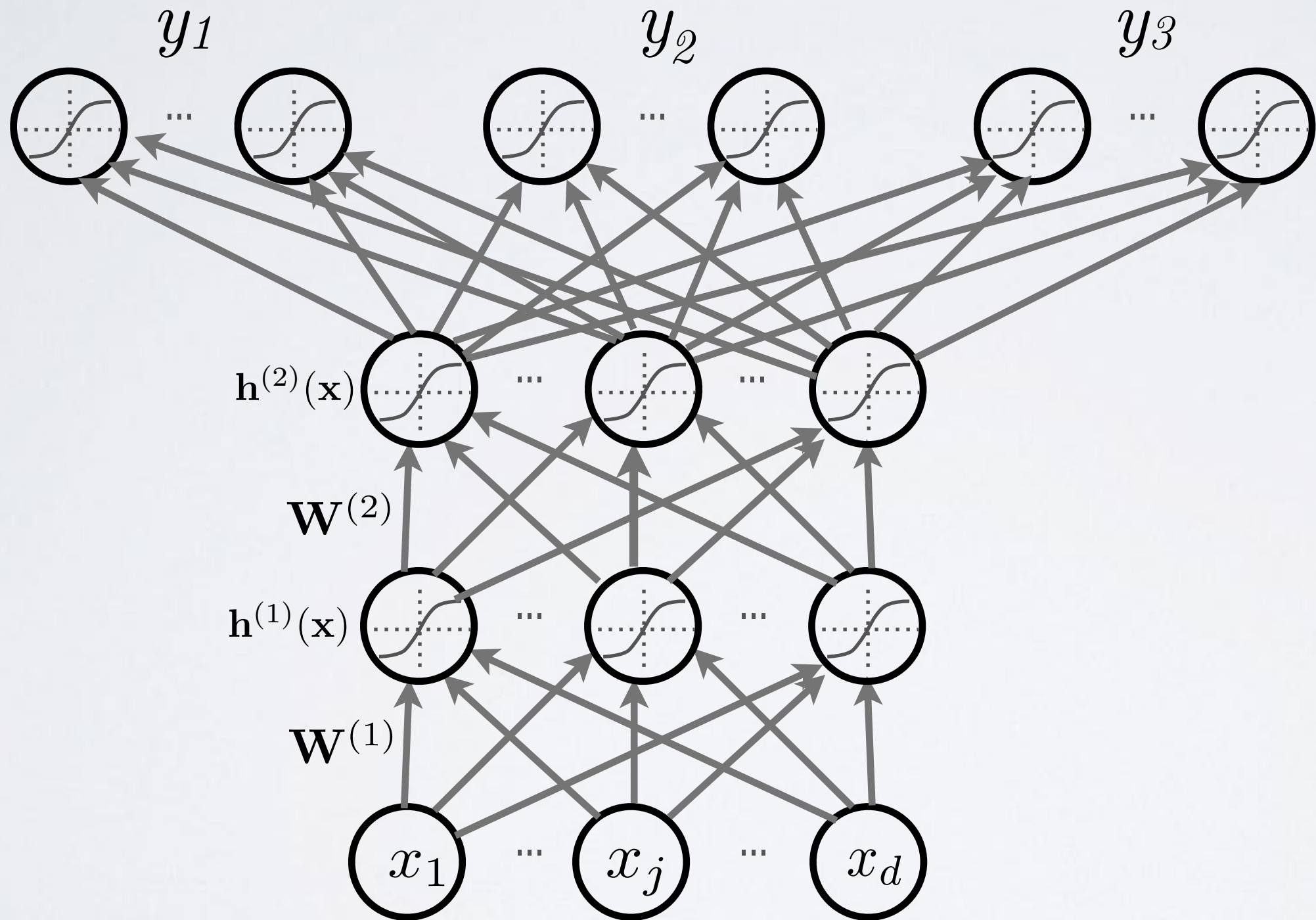
MULTITASK LEARNING

Topics: multitask learning



MULTITASK LEARNING

Topics: multitask learning



TRANSFER LEARNING

Topics: transfer learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y_1^{(t)}, \dots, y_M^{(t)} \sim p(\mathbf{x}, y_1, \dots, y_M)$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, y_1^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y_1^{(t)} \sim p(\mathbf{x}, y_1)$$

STRUCTURED OUTPUT PREDICTION

Topics: structured output prediction

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, \mathbf{y}^{(t)}\}$$

↙ of arbitrary structure
(vector, sequence, graph)

▶ setting :

$$\mathbf{x}^{(t)}, \mathbf{y}^{(t)} \sim p(\mathbf{x}, \mathbf{y})$$

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, \mathbf{y}^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, \mathbf{y}^{(t)} \sim p(\mathbf{x}, \mathbf{y})$$

• Example

- ▶ image caption generation
- ▶ machine translation

DOMAIN ADAPTATION

Topics: domain adaptation, covariate shift

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

$$\{\bar{\mathbf{x}}^{(t')}\}$$

▶ setting :

$$\mathbf{x}^{(t)} \sim p(\mathbf{x})$$

$$y^{(t)} \sim p(y|\mathbf{x}^{(t)})$$

$$\bar{\mathbf{x}}^{(t)} \sim q(\mathbf{x}) \approx p(\mathbf{x})$$

• Test time

▶ data :

$$\{\bar{\mathbf{x}}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\bar{\mathbf{x}}^{(t)} \sim q(\mathbf{x})$$

$$y^{(t)} \sim p(y|\bar{\mathbf{x}}^{(t)})$$

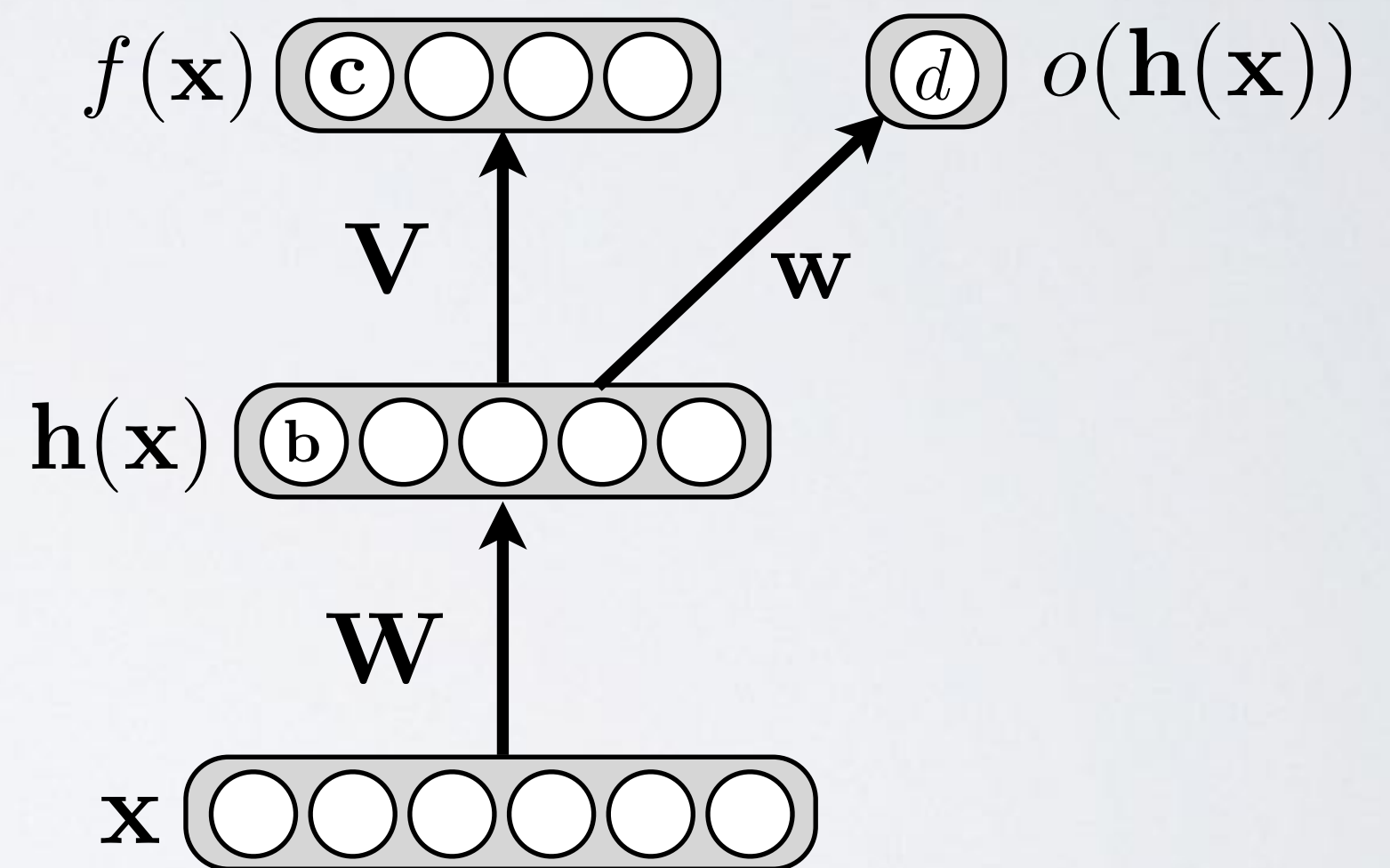
• Example

- ▶ classify sentiment in reviews of different products
- ▶ training on synthetic data but testing on real data (sim2real)

DOMAIN ADAPTATION

Topics: domain adaptation, covariate shift

- Domain-adversarial networks (Ganin et al. 2015) train hidden layer representation to be
 1. **predictive** of the target class
 2. **indiscriminate** of the domain
- Trained by stochastic gradient descent
 - ▶ for each random pair $\mathbf{x}^{(t)}, \bar{\mathbf{x}}^{(t')}$
 1. update $\mathbf{W}, \mathbf{V}, \mathbf{b}, \mathbf{c}$ in opposite direction of gradient
 2. update \mathbf{w}, d in direction of gradient



DOMAIN ADAPTATION

Topics: domain adaptation, covariate shift

- Domain-adversarial networks (Ganin et al. 2015) train hidden layer representation to be

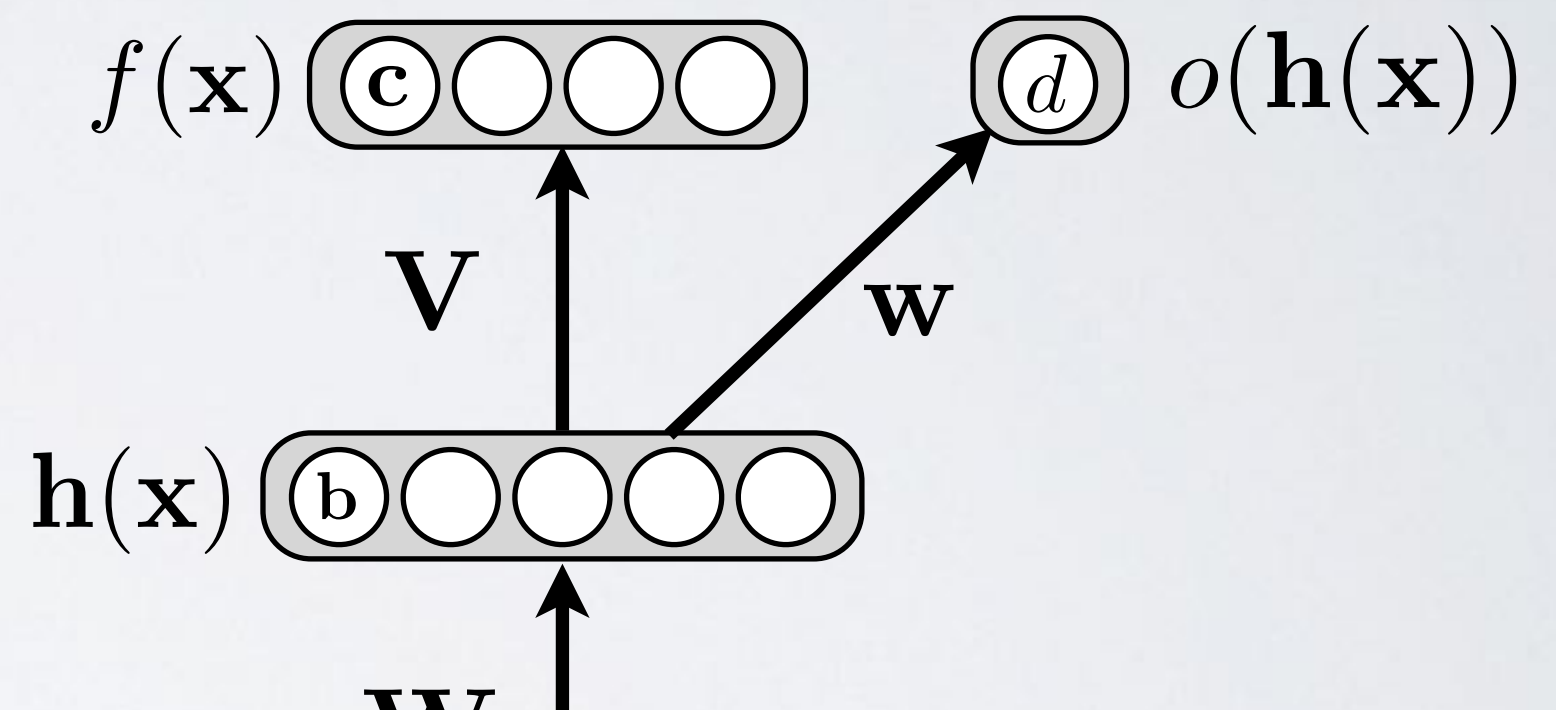
1. **predictive** of the target class
2. **indiscriminate** of the domain

- Trained by stochastic gradient descent

- ▶ for each random pair $\mathbf{x}^{(t)}, \bar{\mathbf{x}}^{(t')}$

1. update $\mathbf{W}, \mathbf{V}, \mathbf{b}, \mathbf{c}$ i

2. update \mathbf{w}, d in dire



May also be used to promote
fair and **unbiased** models ...

ONE-SHOT LEARNING

Topics: one-shot learning

• Training time

- ▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

- ▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

subject to $y^{(t)} \in \{1, \dots, C\}$

• Test time

- ▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

- ▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

subject to $y^{(t)} \in \{C + 1, \dots, C + M\}$

- ▶ side information :

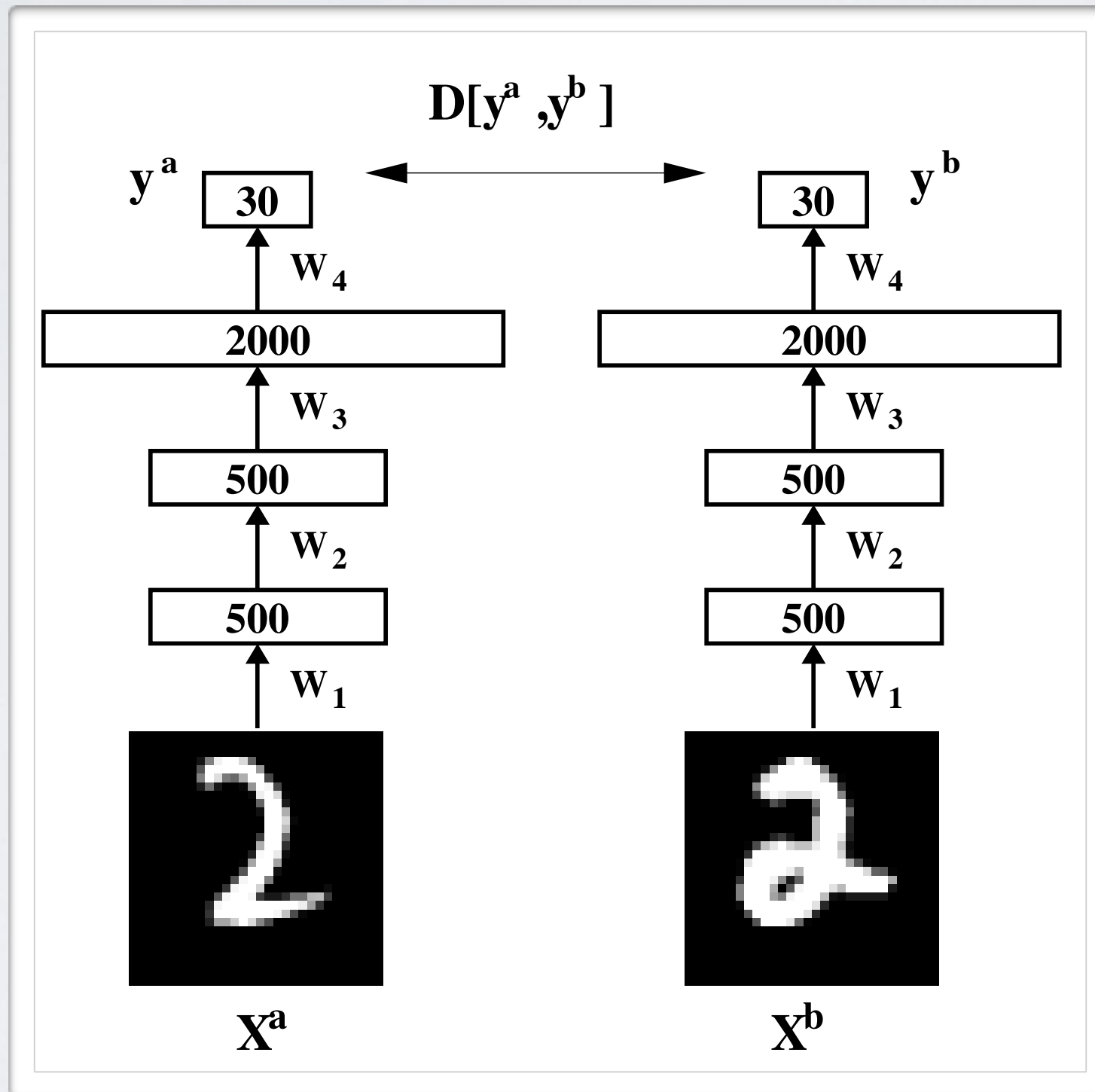
- a single labeled example from each of the M new classes

• Example

- ▶ recognizing a person based on a single picture of him/her

ONE-SHOT LEARNING

Topics: one-shot learning



Siamese architecture
(figure taken from Salakhutdinov
and Hinton, 2007)

ZERO-SHOT LEARNING

Topics: zero-shot learning, zero-data learning

• Training time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

subject to $y^{(t)} \in \{1, \dots, C\}$

▶ side information :

- description vector \mathbf{z}_c of each of the C classes

• Test time

▶ data :

$$\{\mathbf{x}^{(t)}, y^{(t)}\}$$

▶ setting :

$$\mathbf{x}^{(t)}, y^{(t)} \sim p(\mathbf{x}, y)$$

subject to $y^{(t)} \in \{C + 1, \dots, C + M\}$

▶ side information :

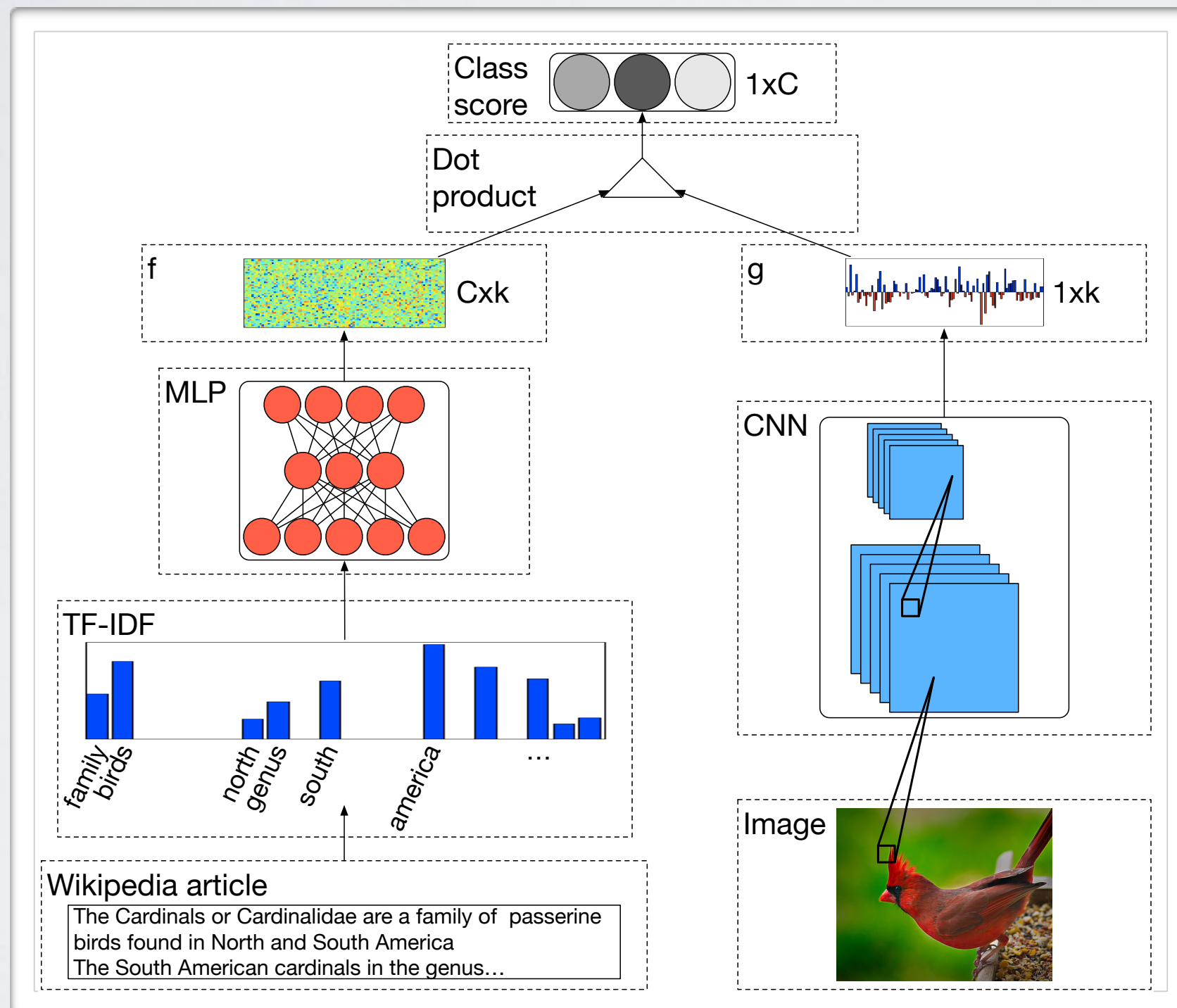
- description vector \mathbf{z}_c of each of the new M classes

• Example

- ▶ recognizing an object based on a worded description of it

ZERO-SHOT LEARNING

Topics: zero-shot learning, zero-data learning



Ba, Swersky, Fidler, Salakhutdinov
arxiv 2015

DESIGNING NEW ARCHITECTURES

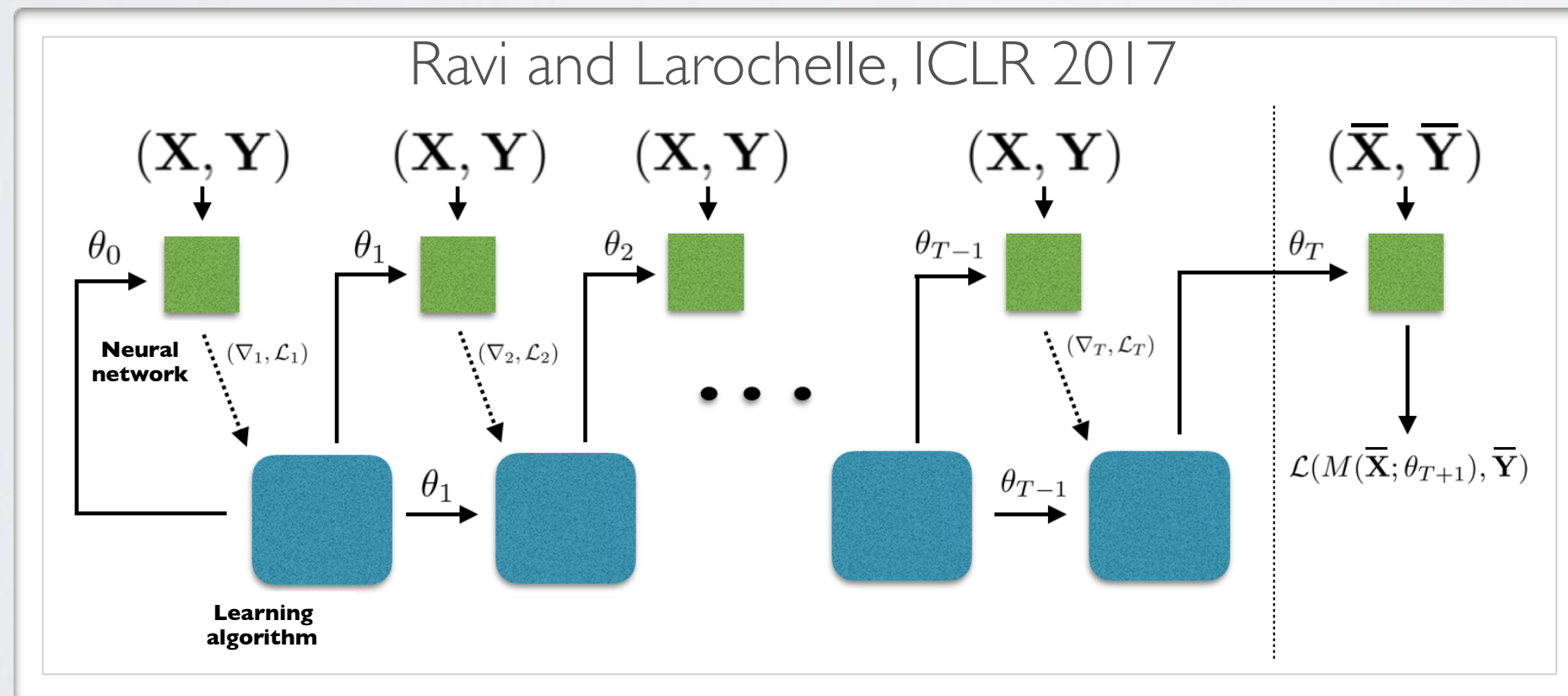
Topics: designing new architectures

- Tackling a new learning problem often requires designing an adapted neural architecture
- Approach 1: use our intuition for how a human would reason about the problem
- Approach 2: take an existing algorithm/procedure and turn it into a neural network

DESIGNING NEW ARCHITECTURES

Topics: designing new architectures

- Many other examples
 - ▶ structured prediction by unrolling probabilistic inference in an MRF
 - ▶ planning by unrolling the value iteration algorithm (Tamar et al., NIPS 2016)
 - ▶ few-shot learning by unrolling gradient descent on small training set



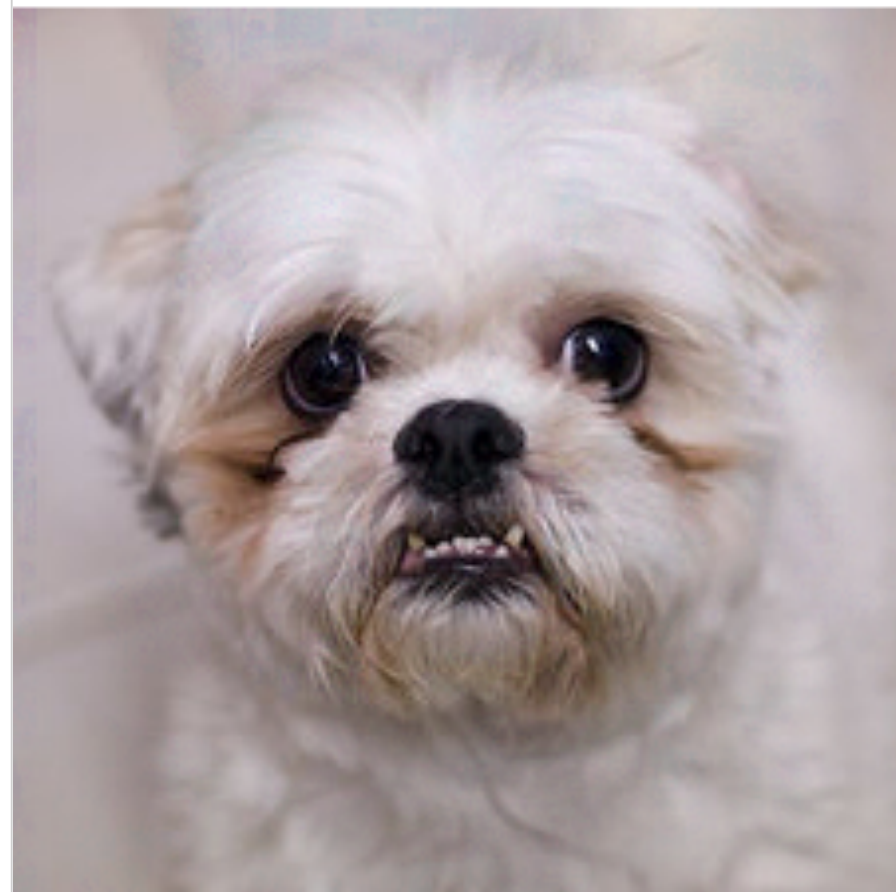
Neural networks

Unintuitive properties of neural networks

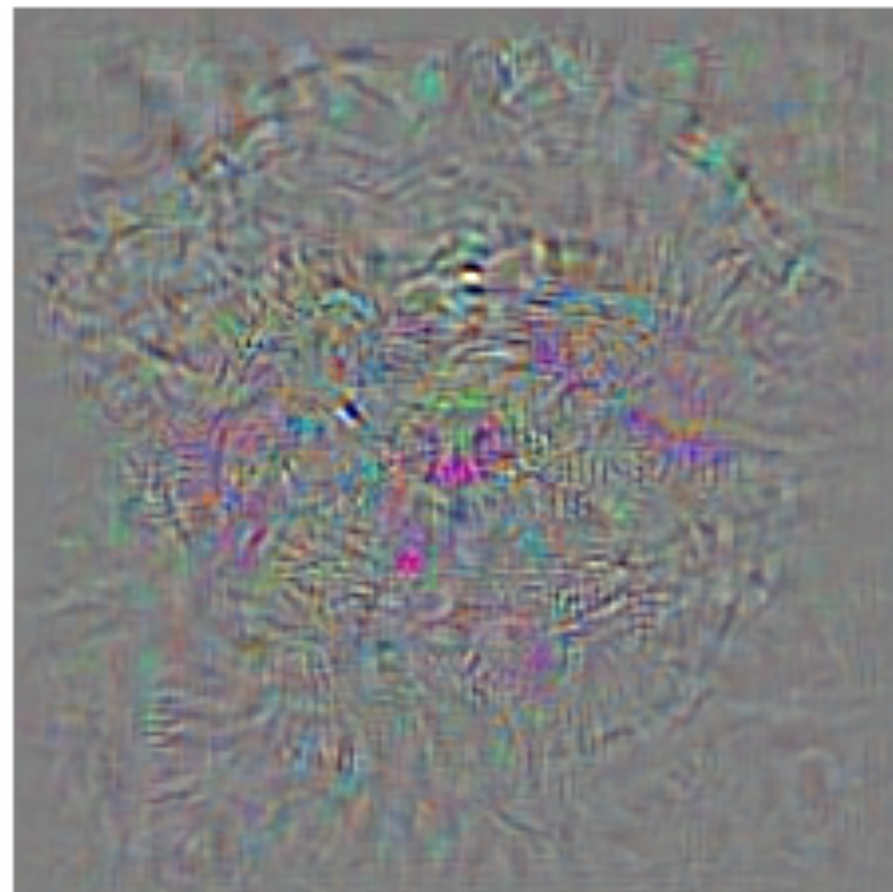
THEY CAN MAKE DUMB ERRORS

Topics: adversarial examples

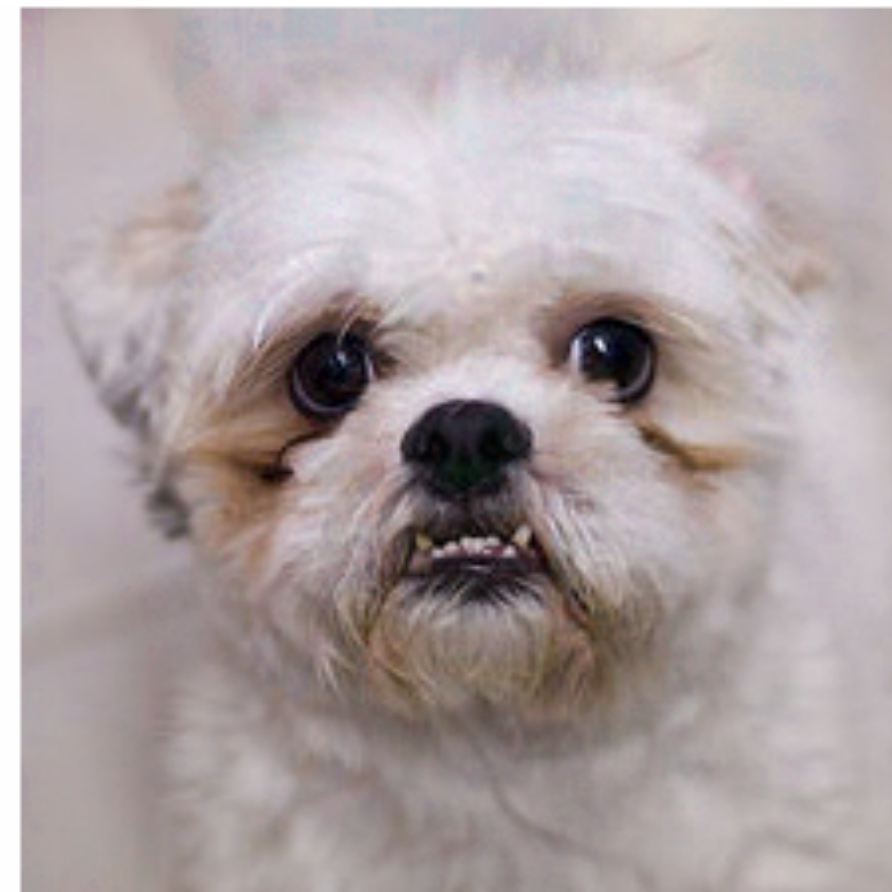
- *Intriguing Properties of Neural Networks*
Szegedy, Zaremba, Sutskever, Bruna, Erhan, Goodfellow, Fergus, ICLR 2014



Correctly
classified



Difference



Badly
classified

THEY CAN MAKE DUMB ERRORS

Topics: adversarial examples

- Humans have adversarial examples too



- However they don't match those of neural networks

THEY CAN MAKE DUMB ERRORS

Topics: adversarial examples

- Humans have adversarial examples too

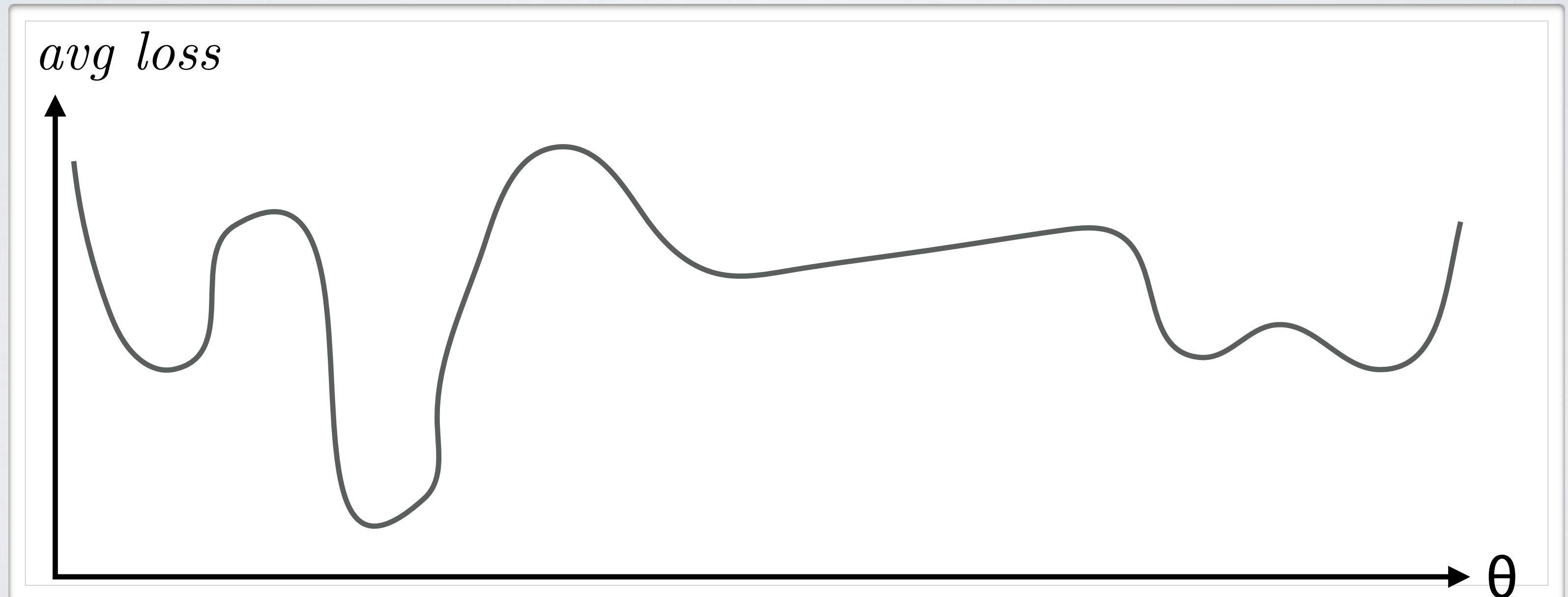


- However they don't match those of neural networks

THEY ARE STRANGELY NON-CONVEX

Topics: non-convexity, saddle points

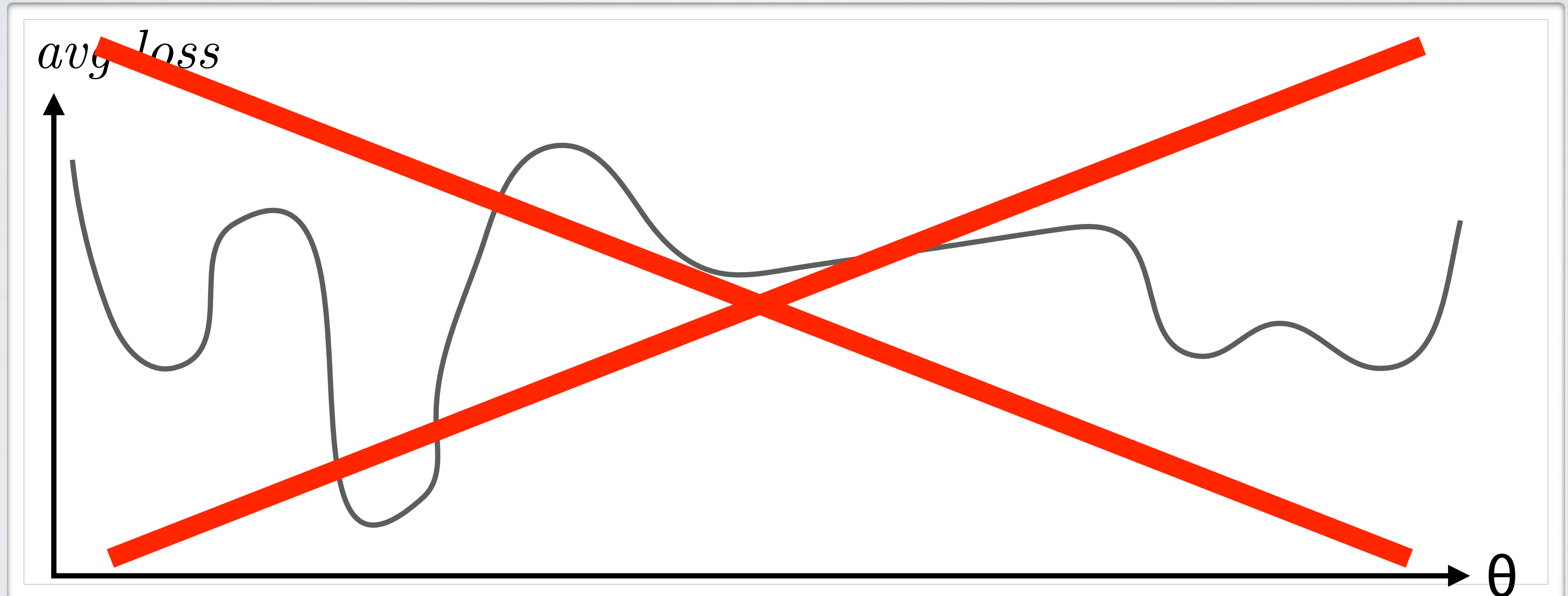
- *Identifying and attacking the saddle point problem in high-dimensional non-convex optimization*
Dauphin, Pascanu, Gulcehre, Cho, Ganguli, Bengio, NIPS 2014



THEY ARE STRANGELY NON-CONVEX

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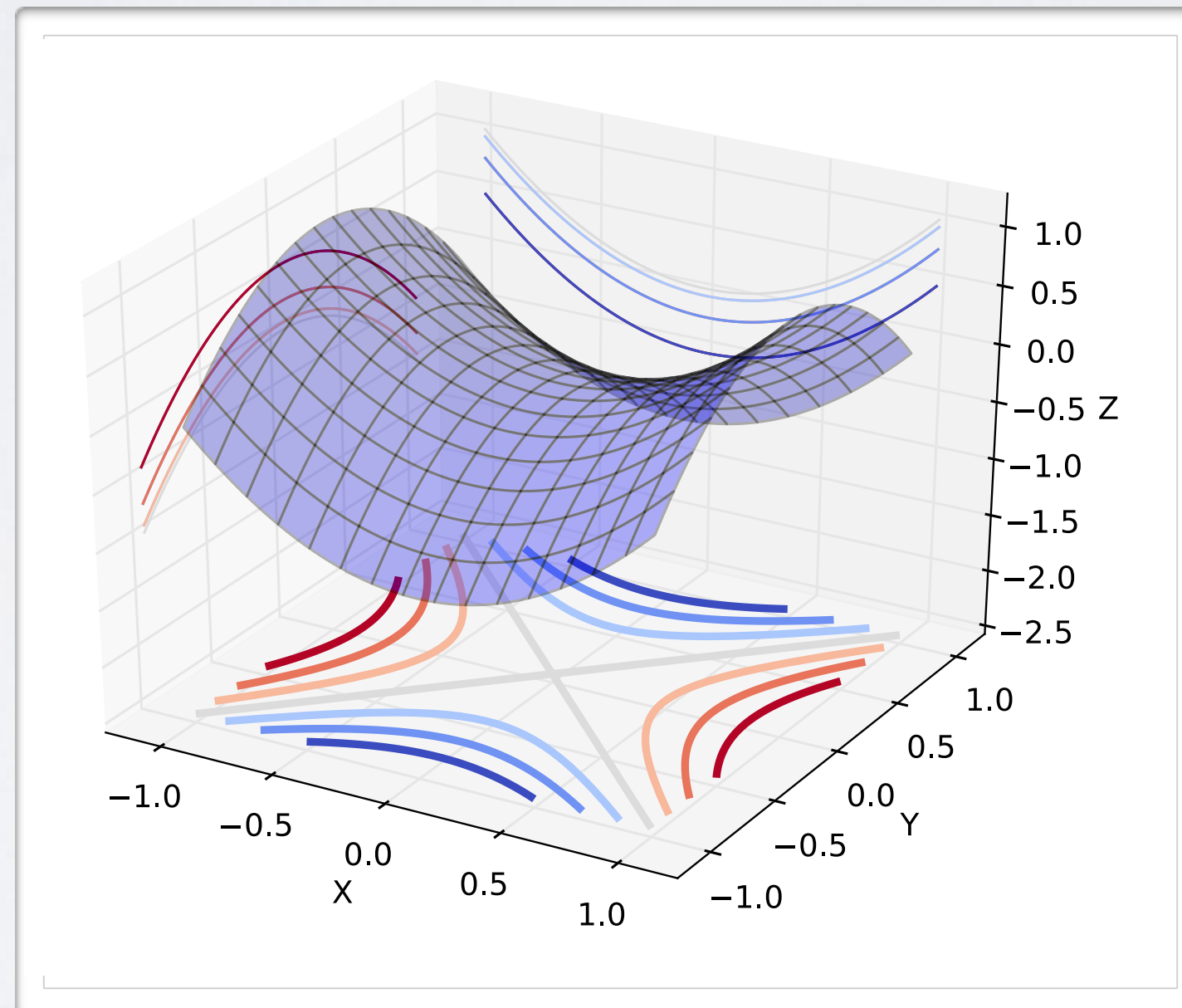
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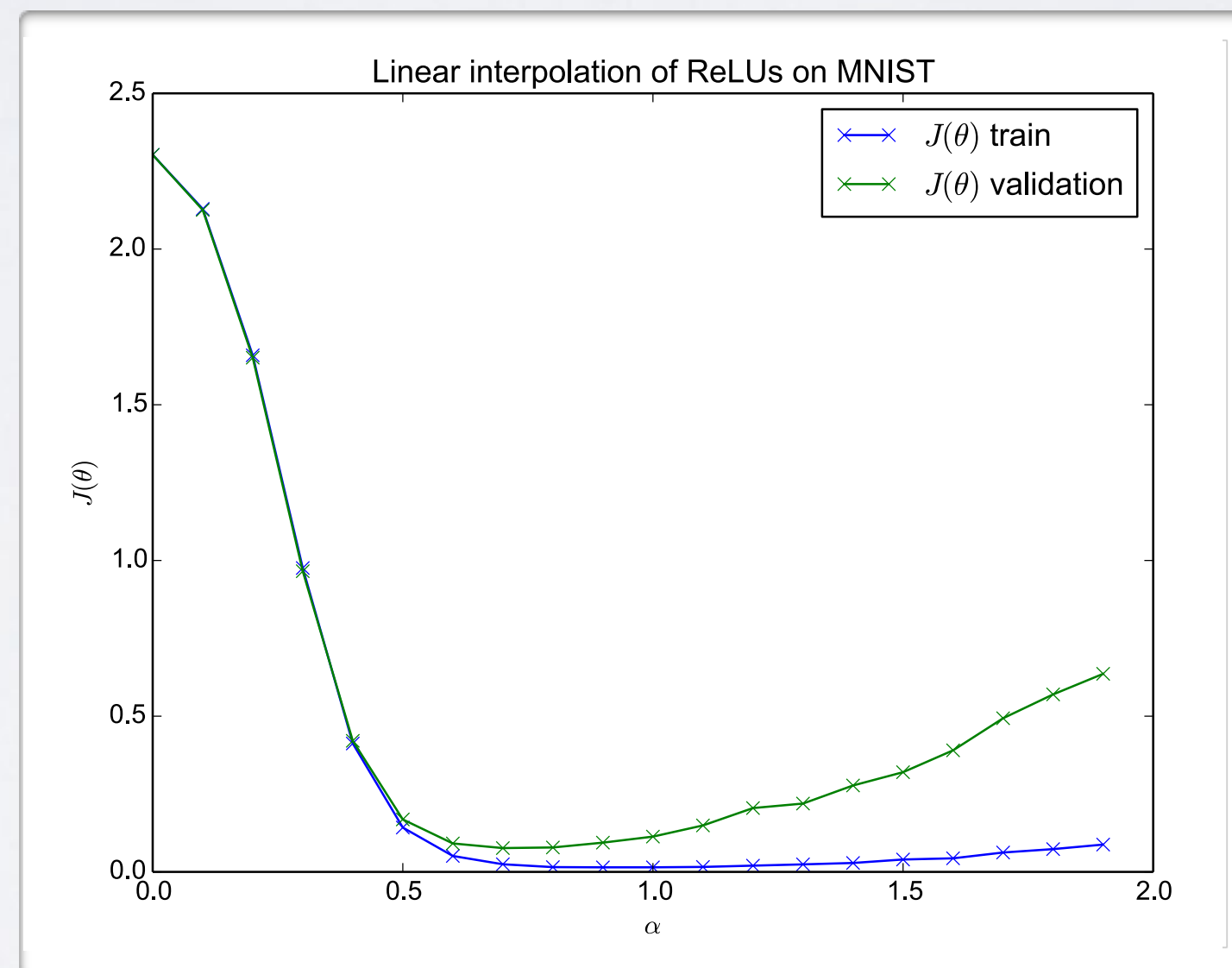
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Dauphin, Pascanu, Gulcehre, Cho, Ganguli, Bengio, NIPS 2014



THEY ARE STRANGELY NON-CONVEX

Topics: non-convexity, saddle points

- *Qualitatively Characterizing Neural Network Optimization Problems*
Goodfellow, Vinyals, Saxe, ICLR 2015



THEY ARE STRANGELY NON-CONVEX

Topics: non-convexity, saddle points

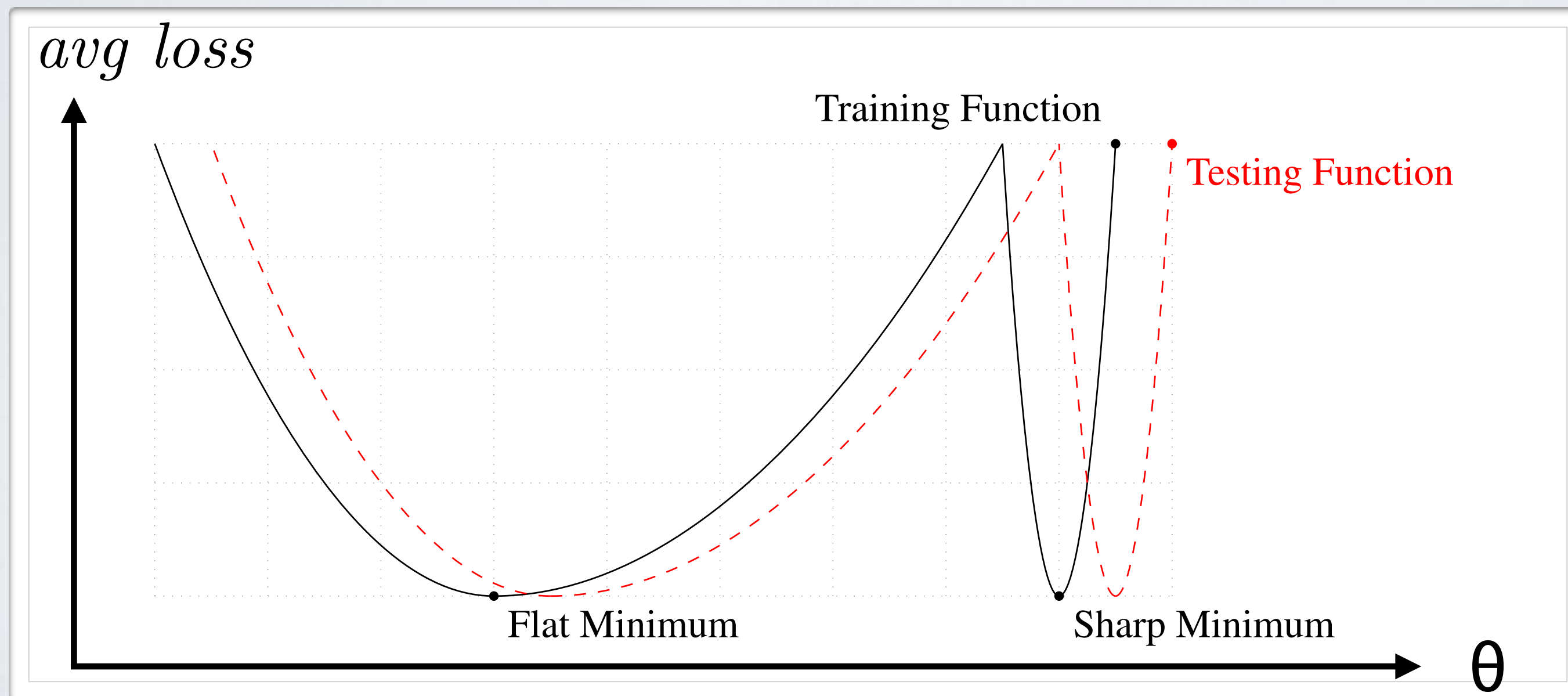
- If dataset is created by labeling points using a N -hidden units neural network
 - ▶ training another N -hidden units network is likely to fail
 - ▶ but training a larger neural network is more likely to work!
(saddle points seem to be a blessing)

THEY WORK BEST WHEN BADLY TRAINED

Topics: sharp vs. flat minimum

- *Flat Minima*

Hochreiter, Schmidhuber, Neural Computation 1997



THEY WORK BEST WHEN BADLY TRAINED

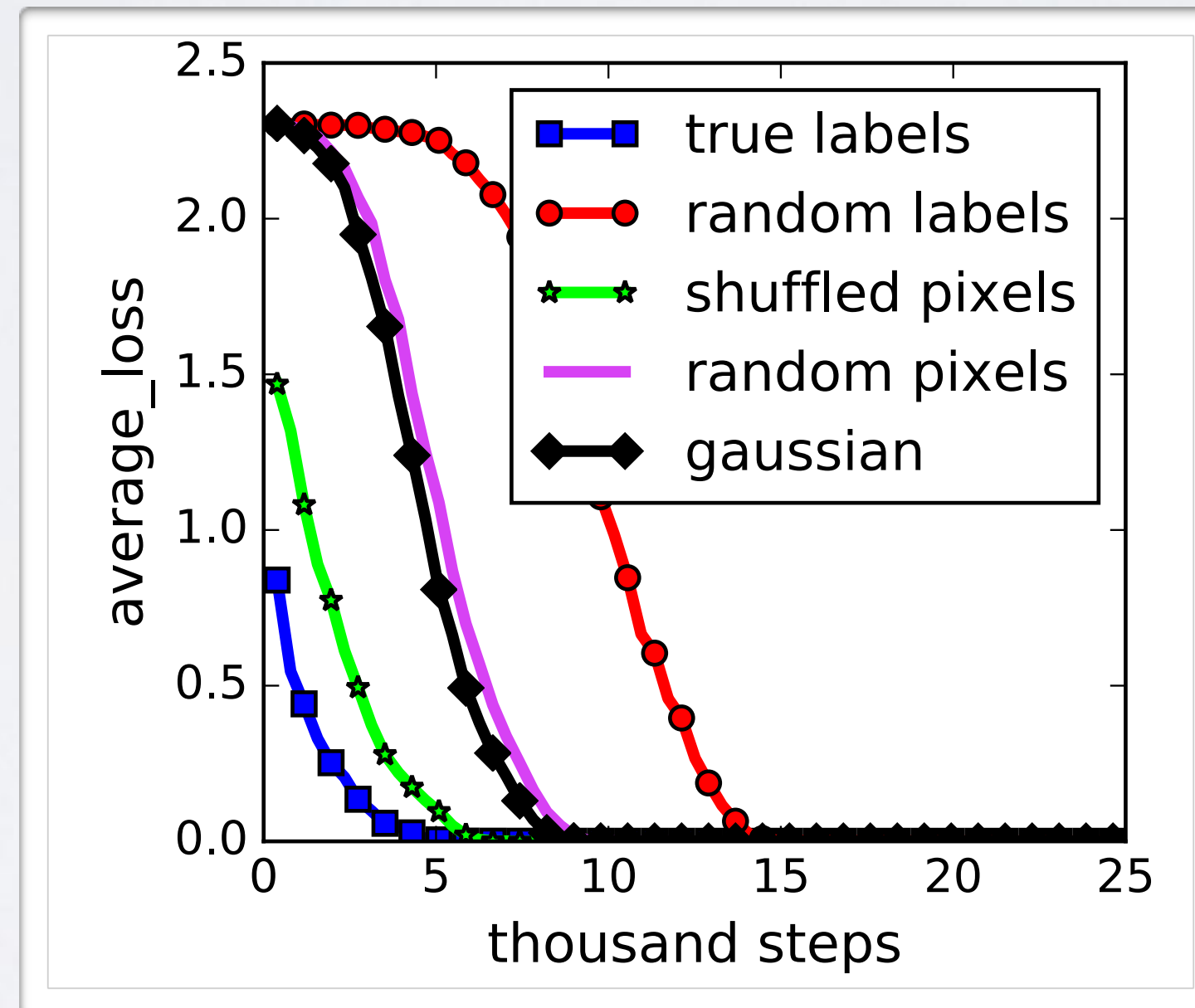
Topics: sharp vs. flat minima

- *On Large-Batch Training for Deep Learning: Generalization Gap and Sharp Minima*
Keskar, Mudigere, Nocedal, Smelyanskiy, Tang, ICLR 2017
 - found that using large batch sizes tends to find sharper minima and generalize worse
- This means that we can't talk about generalization without taking the training algorithm into account

THEY CAN EASILY MEMORIZE

Topics: model capacity vs. training algorithm

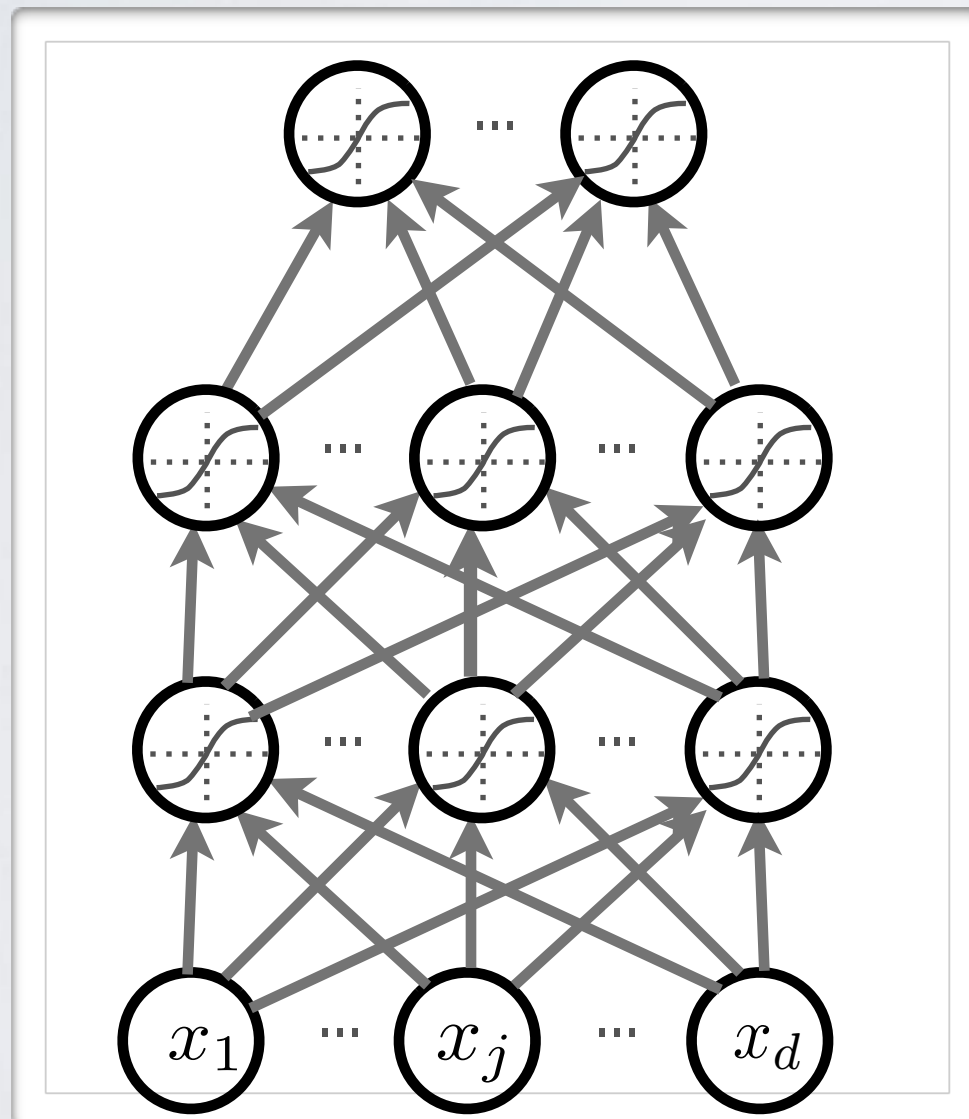
- *Understanding Deep Learning Requires Rethinking Generalization*
Zhang, Bengio, Hardt, Recht, Vinyals, ICLR 2017



THEY CAN BE COMPRESSED

Topics: knowledge distillation

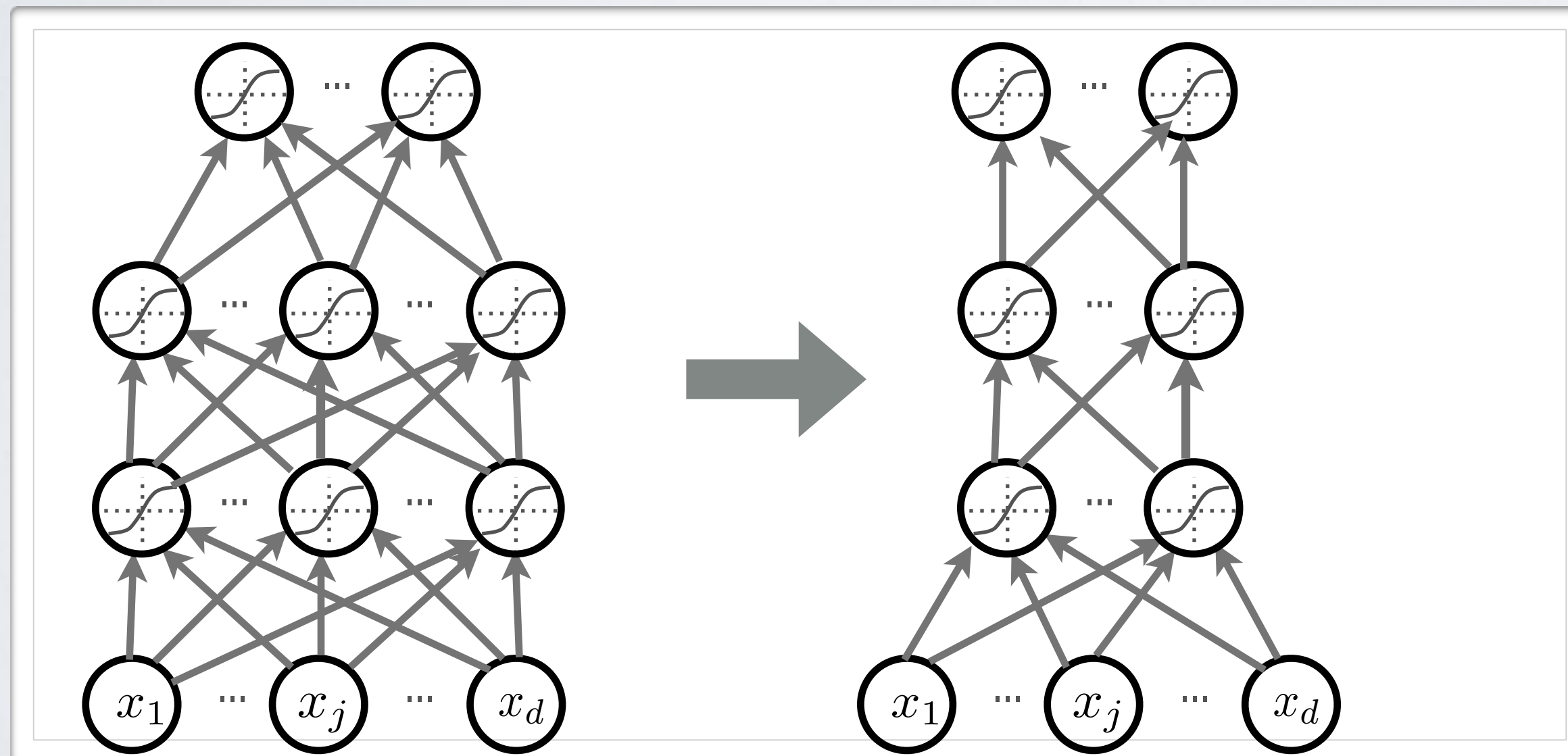
- *Distilling the Knowledge in a Neural Network*
Hinton, Vinyals, Dean, arXiv 2015



THEY CAN BE COMPRESSED

Topics: knowledge distillation

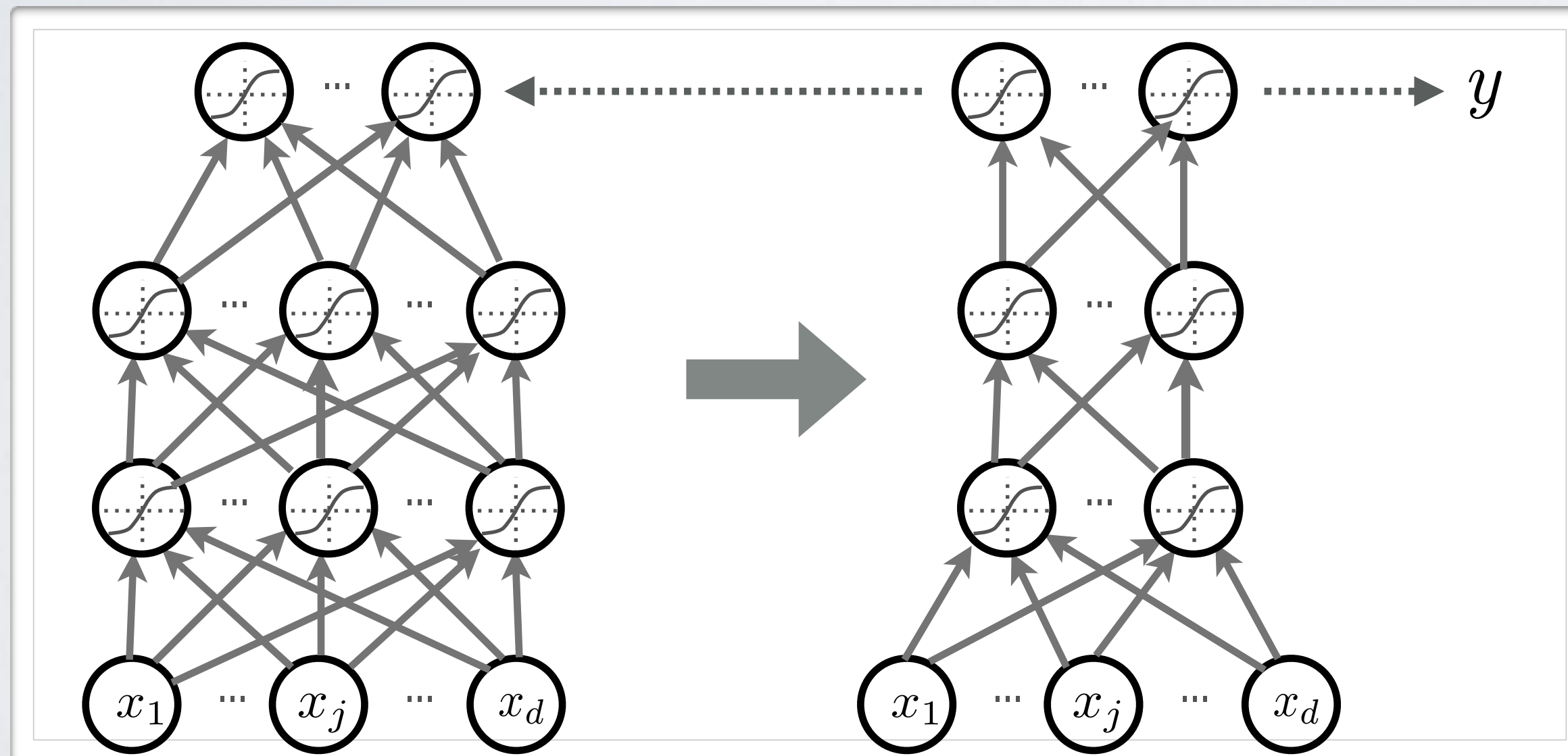
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THEY CAN BE COMPRESSED

Topics: knowledge distillation

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THEY CAN BE COMPRESSED

Topics: knowledge distillation

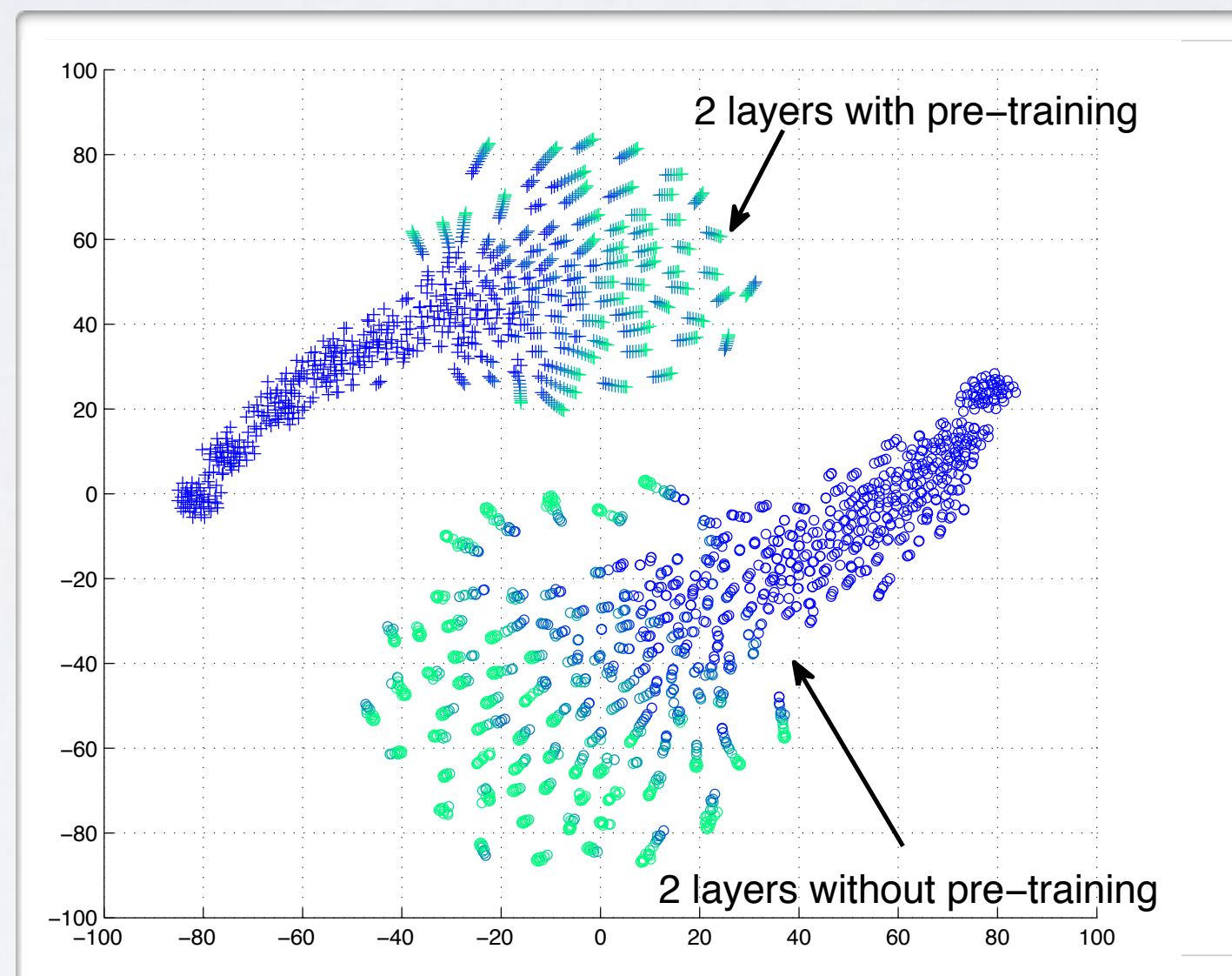
- Can successfully distill
 - ▶ a large neural network
 - ▶ an ensemble of neural network

- Works better than training it from scratch!
 - ▶ *Do Deep Nets Really Need to be Deep?*
Jimmy Ba, Rich Caruana, NIPS 2014

THEY ARE INFLUENCED BY INITIALIZATION

Topics: impact of initialization

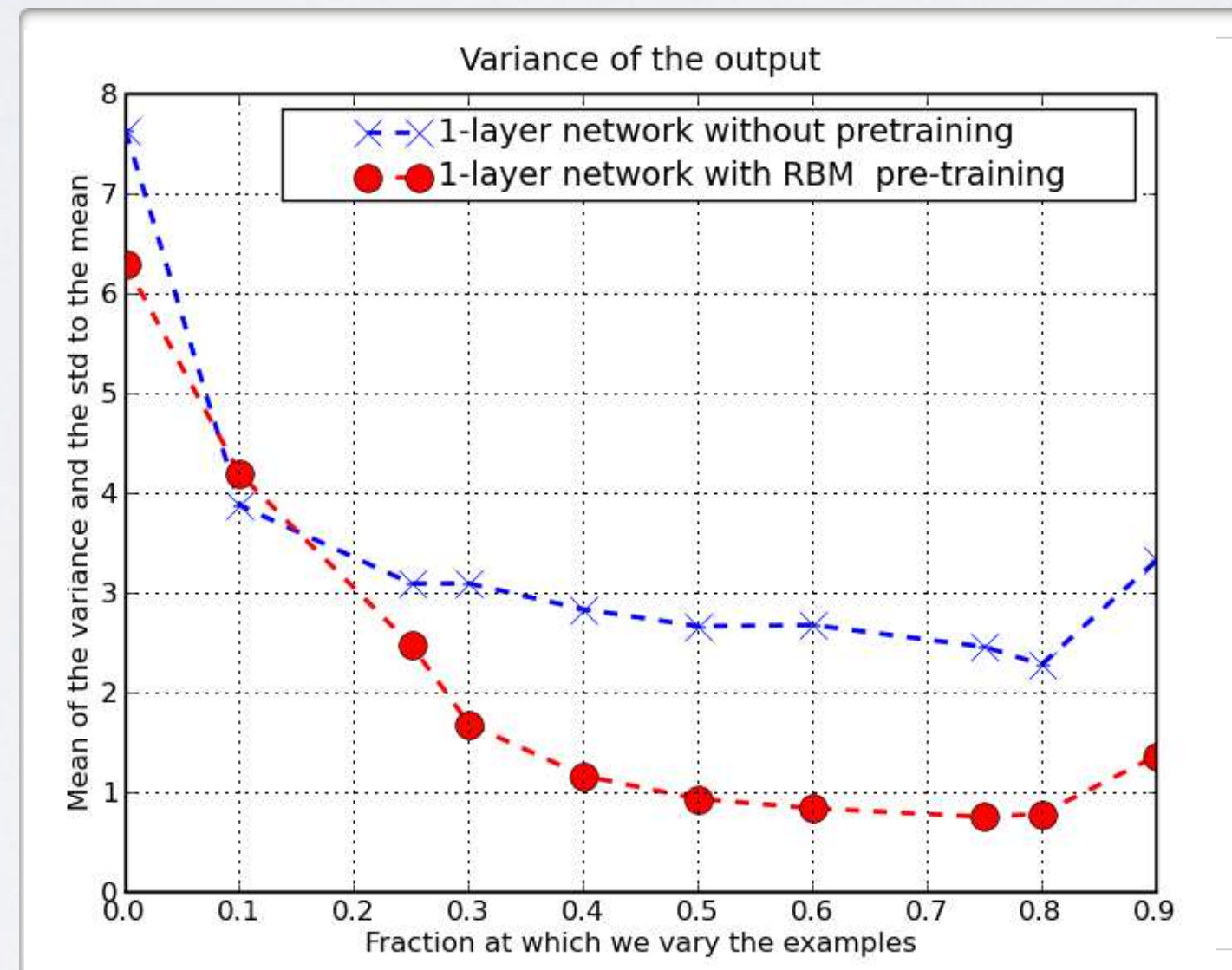
- *Why Does Unsupervised Pre-Training Help Deep Learning*
Erhan, Bengio, Courville, Manzagol, Vincent, JMLR 2010



THEY ARE INFLUENCED BY FIRST EXAMPLES

Topics: impact of early examples

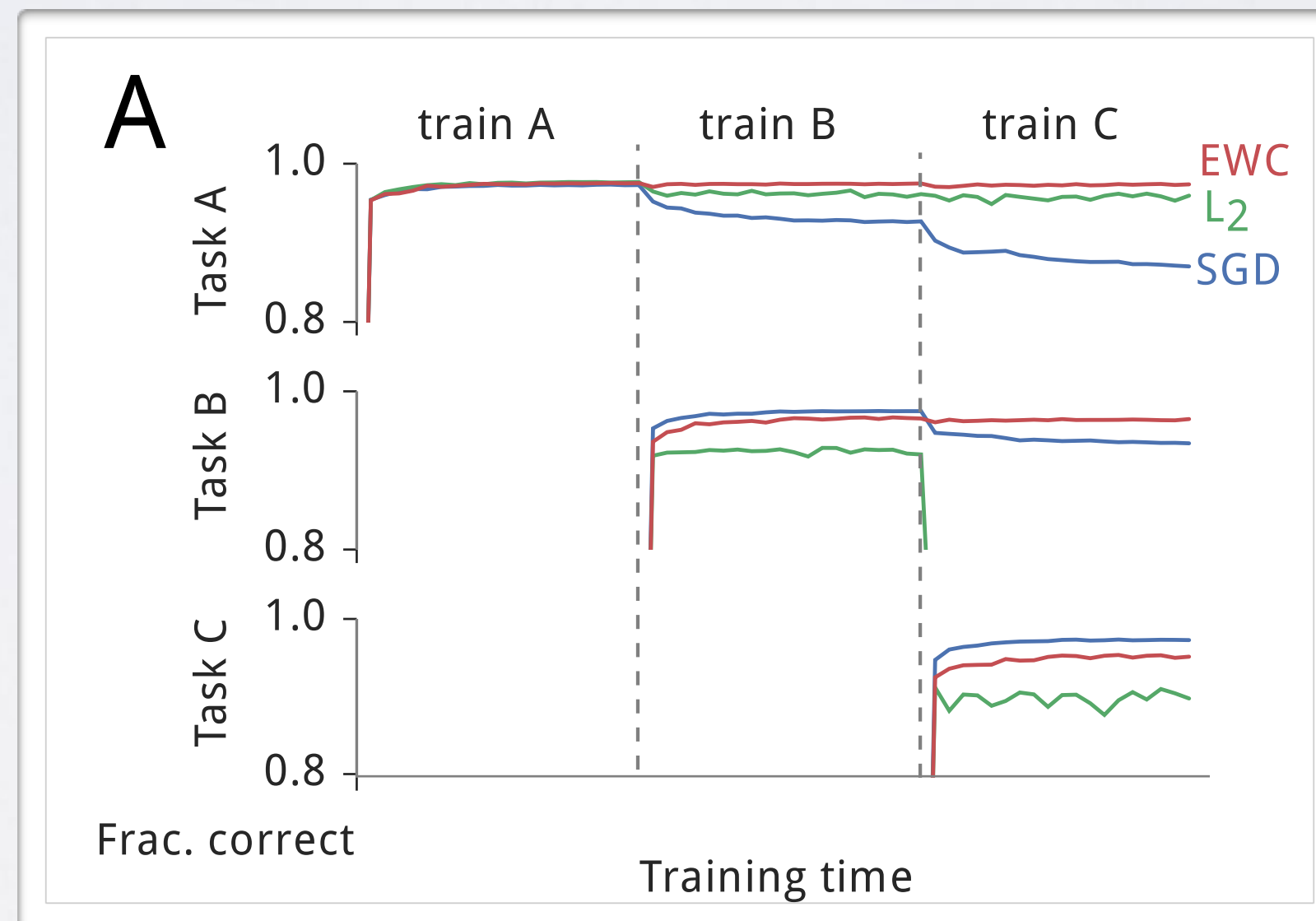
- *Why Does Unsupervised Pre-Training Help Deep Learning*
Erhan, Bengio, Courville, Manzagol, Vincent, JMLR 2010



YET THEY FORGET WHAT THEY LEARNED

Topics: lifelong learning, continual learning

- *Overcoming Catastrophic Forgetting in Neural Networks*
Kirkpatrick et al. PNAS 2017



SO THERE IS A LOT
MORE TO UNDERSTAND!!

MERCI!