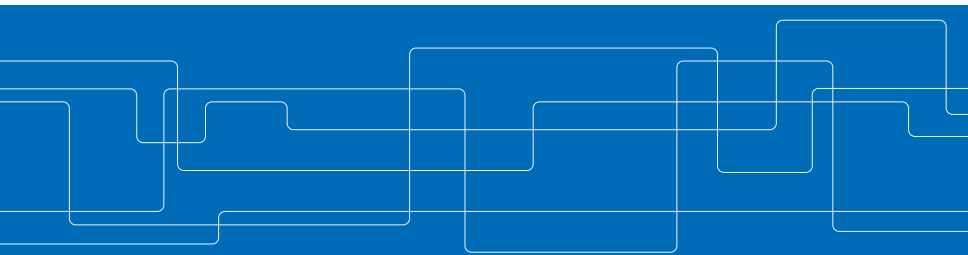


Tangency and Discriminants

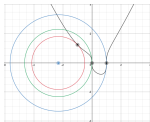
FPSAC 2019, Ljubljana

Sandra Di Rocco,



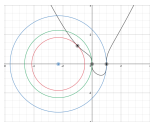


Goal





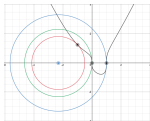
Goal



- ▶ Discriminants: tangency and duality



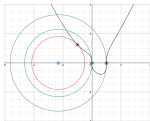
Goal



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- ▶ Discriminants: tangential intersections



Goal



- ▶ Discriminants: tangency and duality
- ▶ Discriminants: tangential intersections
- ▶ Generalized Schäfli decomposition

Natural concept

The discriminant is a concept occurring naturally in connection with the way we grasp 3D objects.

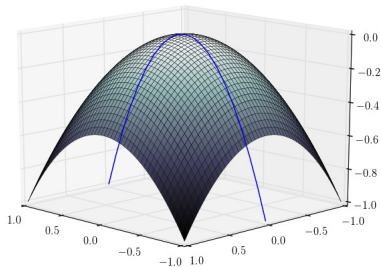


Figure: Boundary locally defined by $f(x, y, z) = 0$. The **Discriminant with respect to x** is the “plane curve” defined by the equation obtained by eliminating x from $\{f = 0, \frac{\partial f}{\partial x} = 0\}$



The discriminants of univariate polynomials



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The discriminant: gives information about the nature of the polynomial's roots.



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The discriminants of univariate polynomials

The discriminant: gives information about the nature of the polynomial's roots.

- ▶ the **discriminant** of $c_2x^2 + c_1x + c_0$ is $c_1^2 - 4c_2c_0$.
- ▶ for higher degrees the **discriminant** D_n is a $(2n - 1) \times (2n - 1)$ determinant :

$$D_n = (1/c_n) \det \begin{bmatrix} c_n & c_{n-1} & \cdots & c_0 & 0 & \cdots & 0 \\ 0 & c_n & c_{n-1} & \cdots & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ nc_n & (n-1)c_{n-1} & \cdots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 \cdots & \cdots & 2c_2 & c_1 \end{bmatrix}$$



Algebra vs Geometry



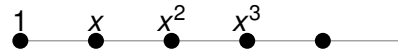
Algebra vs Geometry

Algebra: $D_n = \text{Res}(p(x), p'(x))$



Algebra vs Geometry

Algebra: $D_n = \text{Res}(p(x), p'(x))$

Geometry:  $\mathbb{P}^1 \hookrightarrow \mathbb{P}^d$
 $J_1 = \mathcal{O}_{\mathbb{P}^1}(d-1) \oplus \mathcal{O}_{\mathbb{P}^1}(d-1)$ and $\deg(c_1(J_1)) = 2d-2$

The diagram shows a horizontal line with five black dots representing points. The first four dots are labeled with the monomials 1, x, x^2, and x^3 from left to right. The fifth dot is unlabeled. To the right of the line, the text $\mathbb{P}^1 \hookrightarrow \mathbb{P}^d$ is written.



The definition of discriminant

Let $\mathcal{A} \subset \mathbb{Z}^d$ be a finite subset of lattice points:

$$\mathcal{A} = \{m_0, m_1, \dots, m_n\}$$



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A polynomial p in d variables is **supported on** \mathcal{A} if

$$p(x_1, \dots, x_d) = \sum_{m_i \in \mathcal{A}} c_i x^{m_i}$$

where $x^m = x_1^{k_1} x_2^{k_2} \dots x_d^{k_d}$ if $m = (k_1, \dots, k_d) \in \mathcal{A} \in \mathbb{Z}^d$.



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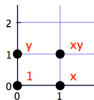


Figure: Quadrics $c_0 + c_1x + c_2y + c_3xy$



The definition of discriminant

Definition

Let $\mathcal{A} = \{m_0, m_1, \dots, m_n\} \subset \mathbb{Z}^d$. The **discriminant** of \mathcal{A} is (if it exists!) a polynomial $D_{\mathcal{A}}(c_0, \dots, c_n)$ in $n + 1$ variables vanishing whenever the corresponding polynomial $p(x) = \sum_{m_i \in \mathcal{A}} c_i x^{m_i}$ has some multiple root in $(\mathbb{C}^*)^d$.



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$$D_{\mathcal{A}}(c_0, \dots, c_n) = 0 \Leftrightarrow \begin{array}{l} \text{there is } x \in (\mathbb{C}^*)^d \text{ s.t.} \\ p(x) = \dots = \frac{\partial p}{\partial x_j}(x) = \dots = 0 \end{array}$$



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Otherwise $D_{\mathcal{A}} = 1$.

Existence does not mean an efficient algorithm and hence a formula!



Example 1

For the configuration $\mathcal{A} = \{(0, 0), (1, 0), (0, 1), (1, 1)\} \subset \mathbb{Z}^2$



The discriminant is given by an homogeneous polynomial $\Delta_{\mathcal{A}}(c_0, c_1, c_2, c_3)$ vanishing whenever the corresponding quadric has a singular point in $(\mathbb{C}^*)^2$. I

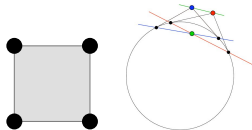
$$D_{\mathcal{A}}(c_0, c_1, c_2, c_3) = \det(M) = c_0 c_3 - c_1 c_2.$$



Geometry

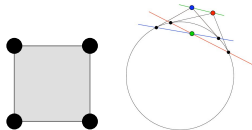


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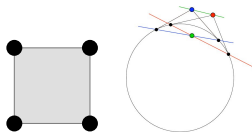
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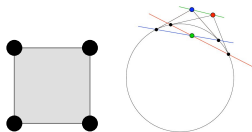
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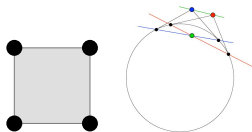
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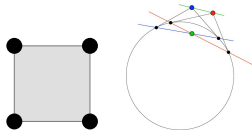


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- ▶ general tangent lines to Q do not contain the point p
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- ▶ It gives the degree of the discriminant.

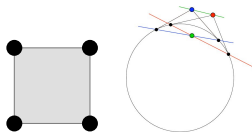


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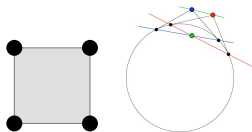
Geometry



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- ▶ P_1 on Q is a zero-cycle of degree 2.



Projective duality



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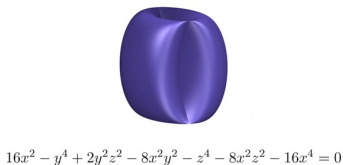
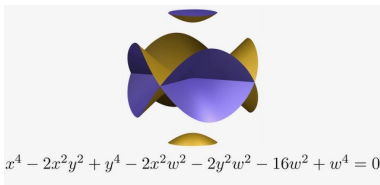
The dual variety is defined as:

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- ▶ It is defined by an irreducible polynomial D_X , called the discriminant.



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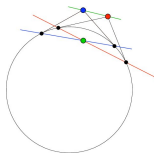


Figure: C^* is another conic, $\text{deg}(P_1(X)) = 2$



Toric projective duality = \mathcal{A} -discriminants



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$$(x, y) \rightarrow (1, x, y, xy)$$

$$3! \cdot \text{Area} - 2!(\text{perimeter}) + 4 =$$

$$6 - 8 + 4 = 2$$



Can a discriminant govern multiple roots of systems of polynomials?



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As before: Let $\mathcal{A}_1, \dots, \mathcal{A}_d$ be (finite) in \mathbb{Z}^d and let f_1, \dots, f_d be Laurent polynomials with these support sets and coefficients in an alg. cl. field K , e.g. \mathbb{C} :

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If the coefficients $c_{i,a}$ are generic then, by *Bernstein's Theorem*, the number of common solutions in the algebraic torus $(\mathbb{C}^*)^d$ equals the *mixed volume* $MV(Q_1, Q_2, \dots, Q_d)$ of the Newton polytopes $Q_i = \text{conv}(\mathcal{A}_i)$ in \mathbb{R}^d .

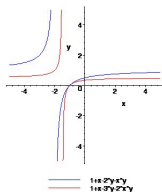
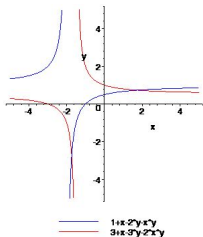


Example

Let $n = 2$ and $\mathcal{A}_1 = \mathcal{A}_2 = \{(0, 0), (1, 0), (0, 1), (1, 1)\}$ be the unit square, $f_1 = a_{00} + a_{10}x_1 + a_{01}x_2 + a_{11}x_1x_2$, $f_2 = b_{00} + b_{10}x_1 + b_{01}x_2 + b_{11}x_1x_2$.

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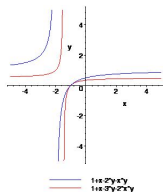
tangential intersections



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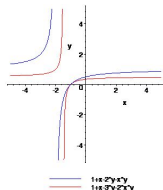
tangential intersections



Given p_{A_1}, p_{A_2} , we say that x is a tangential solution of the system $p_{A_1}(u) = p_{A_2}(u) = 0$ if x is a regular point of the hypersurfaces $p_{A_i} = 0$ and their normal lines are dependent.



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Definition

Given a system of type (A_0, \dots, A_r) . We call an isolated solution $u \in (\mathbb{C}^*)^n$ a *non-degenerate multiple root* if the $r + 1$ gradient vectors $\nabla_x p_{A_i}(u), i = 0, \dots, r$ are linearly dependent.



The mixed discriminant



The mixed discriminant

Given $\mathcal{A}_0, \dots, \mathcal{A}_r \subset \mathbb{Z}^d$

Definition

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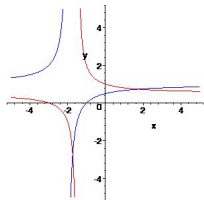
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$MD_{\mathcal{A}_0, \dots, \mathcal{A}_r}(c)$ is a polynomial in $|\mathcal{A}_0| + \dots + |\mathcal{A}_r|$ variables
When $\mathcal{A}_0 = \dots = \mathcal{A}_r = \mathcal{A}$ we denote it by $M(r, \mathcal{A})$.

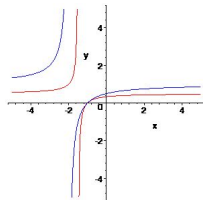


Example

Let $n = 2$ and $\mathcal{A}_1 = \mathcal{A}_2 = \{(0, 0), (1, 0), (0, 1), (1, 1)\}$ be the unit square, $f_1 = a_{00} + a_{10}x_1 + a_{01}x_2 + a_{11}x_1x_2$, $f_2 = b_{00} + b_{10}x_1 + b_{01}x_2 + b_{11}x_1x_2$.



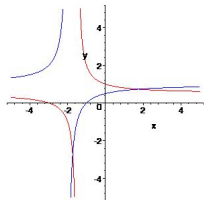
— $f_1(x,y)$
— $f_2(x,y)$



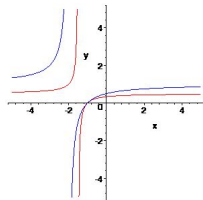
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— $1 \times 2 \times 2 \times y$
 — $3 \times 3 \times 2 \times y$



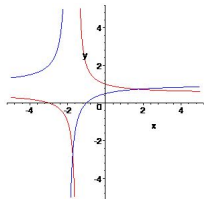
— $1 \times 2 \times 2 \times y$
 — $1 \times 3 \times 2 \times y$

$\Delta_{\mathcal{A}_1, \mathcal{A}_2}$ is the **hyperdeterminant** of format $2 \times 2 \times 2$:

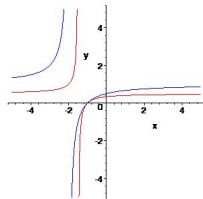
$$a_{00}^2 b_{11}^2 - 2a_{00}a_{01}b_{10}b_{11} - 2a_{00}a_{10}b_{01}b_{11} - 2a_{00}a_{11}b_{00}b_{11} + 4a_{00}a_{11}b_{01}b_{10} + a_{01}^2 b_{10}^2 + 4a_{01}a_{10}b_{00}b_{11} - 2a_{01}a_{10}b_{01}b_{10} - 2a_{01}a_{11}b_{00}b_{10} + a_{10}^2 b_{01}^2 - 2a_{10}a_{11}b_{00}b_{01} + a_{11}^2 b_{00}^2$$

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$$\text{bidegree} = (2, 2)$$



One more example: The distance to a variety



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Consider $X \subset \mathbb{R}^n$. The **Euclidian Distance Degree**, $EDD(X)$,



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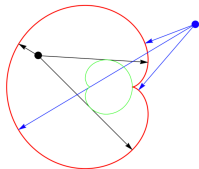
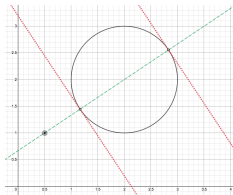
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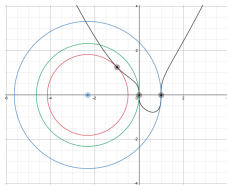
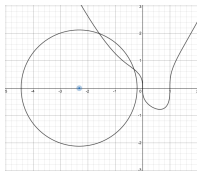
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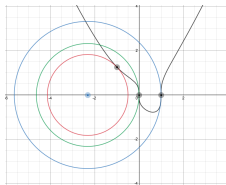
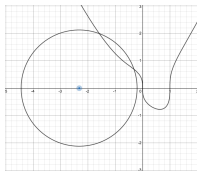
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C is a conic: 3×3 matrix $M(c_{ij})$ and the circle by the the 3×3 symmetric matrix $M(u, r)$.

The *Mixed Discriminant* is given by the $2 \times 3 \times 3$ hyperdeterminant: $H(c_{ij}, u, r)$.



This proves:

Theorem (Cayley)

Let C be an irreducible conic, then

- ▶ $EDD(\text{Circle}) = 2$
- ▶ $EDD(\text{Parabola}) = 3$
- ▶ $EDD = 4$ otherwise



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The key tool is the use of *Schläfli decomposition*

$$MD(A_1, A_2) = \text{Hyperdet}([M_1, M_2]) = \text{Disc}_t(\det(M_1 + tM_2)).$$



Singular intersection of Quadric Surfaces



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Key tools:

- ▶ Classified by the Hyperdeterminant, i.e. **discriminant of Segre embeddings**
- ▶ The hyperdeterminant can be computed by **iteration**



Two Main Questions:

- ▶ **Question 1** Can the mixed discriminant be computed via iteration?
- ▶ **Question 2** What about singular intersection of higher dimensional quadrics?



Towards an answer to question 1



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Theorem (Dickenstein-DR-Morrison 2019)

$$MD_{r,A} = \text{Delta}_{\text{Cayley}(r,A)}$$



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Theorem (Dickenstein-DR-Morrison 2019)

$$MD_{r,\mathcal{A}} = \text{Delta}_{\text{Cayley}(r,\mathcal{A})}$$

Definition

Let $\mathcal{A} \subset \mathbb{Z}^d$, such that $D_{\mathcal{A}} \neq 1$, $\deg(D_{\mathcal{A}}) = \delta$, and let $(\lambda_0, \dots, \lambda_r) \in \mathbb{C}^{r+1}$. Define the **iterated discriminant** as:

$$ID_{r,\mathcal{A}} = D_{\delta\Delta_r}(D_{\mathcal{A}}(\lambda_0 f_0 + \dots + \lambda_r f_r))$$

Abuse of notation: $f_i = (c_0^i, \dots, c_N^i)$
 $\deg(I_{r,\mathcal{A}}) = \delta(\delta - 1)(r + 1)$



Answer to question 1

Theorem (Dickenstein-DR-Morrison)



Answer to question 1

Theorem (Dickenstein-DR-Morrison)

$\mathcal{A} \subset \mathbb{Z}^d$, $D_{\mathcal{A}} \neq 1$ and $0 \leq r \leq d$. Then, the mixed discriminant $MD_{r,\mathcal{A}} \neq 1$ divides the iterated discriminant $ID_{r,\mathcal{A}}$. Moreover,



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3. If $\text{codim}_{X_{\mathcal{A}}^*}(\text{sing}(X_{\mathcal{A}}^*)) < r$, $ID_{r,\mathcal{A}} = 0$.



Answer to question 2



Answer to question 2

Theorem (Dickenstein-DR-Morrison)

Let Q_1, Q_2 be two d -dimensional quadric hypersurfaces then:

$$Q_1 \cap Q_2 \text{ singular if and only if } I_{1,2\Delta_d} = MD_{1,2\Delta_d}$$



(THANK YOU)ⁿ

$n \gg 1$