

EPFL

ICT4SM ict4sm.epfl.ch/

Connecting the Dots in Smart Circular Manufacturing

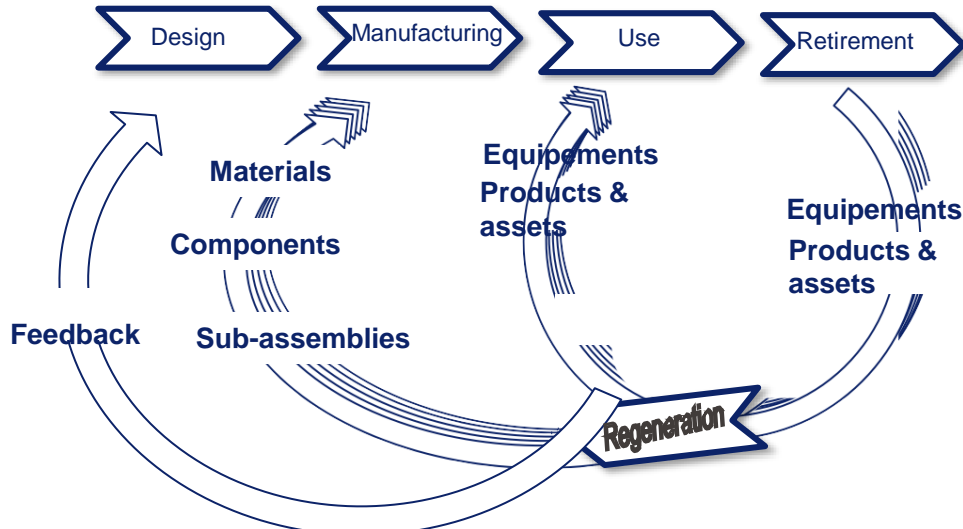
Closed Loop Lifecycle Management

Dimitris Kiritsis (Kyritsis)
ICT for Sustainable Manufacturing

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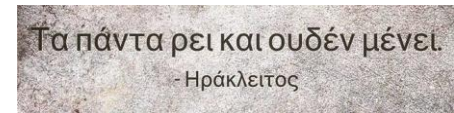
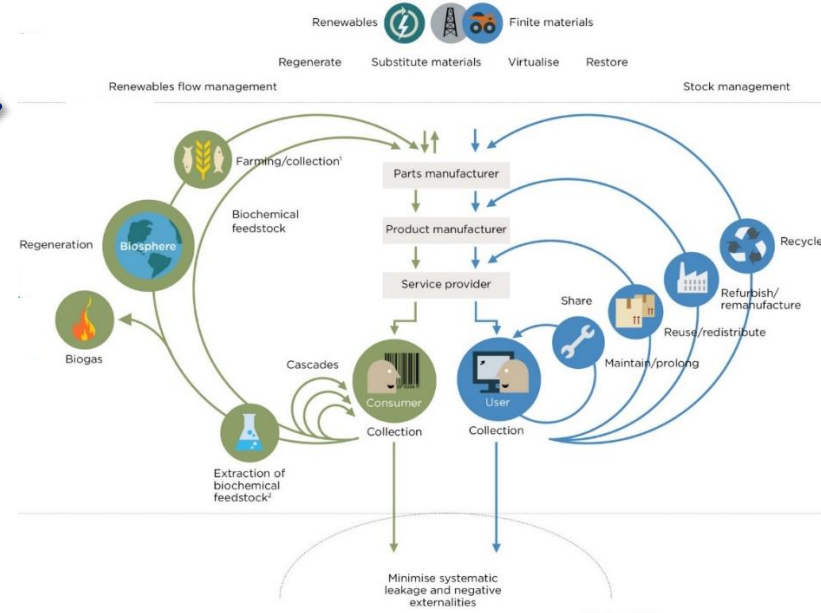
Closed-Loop Lifecycle Management

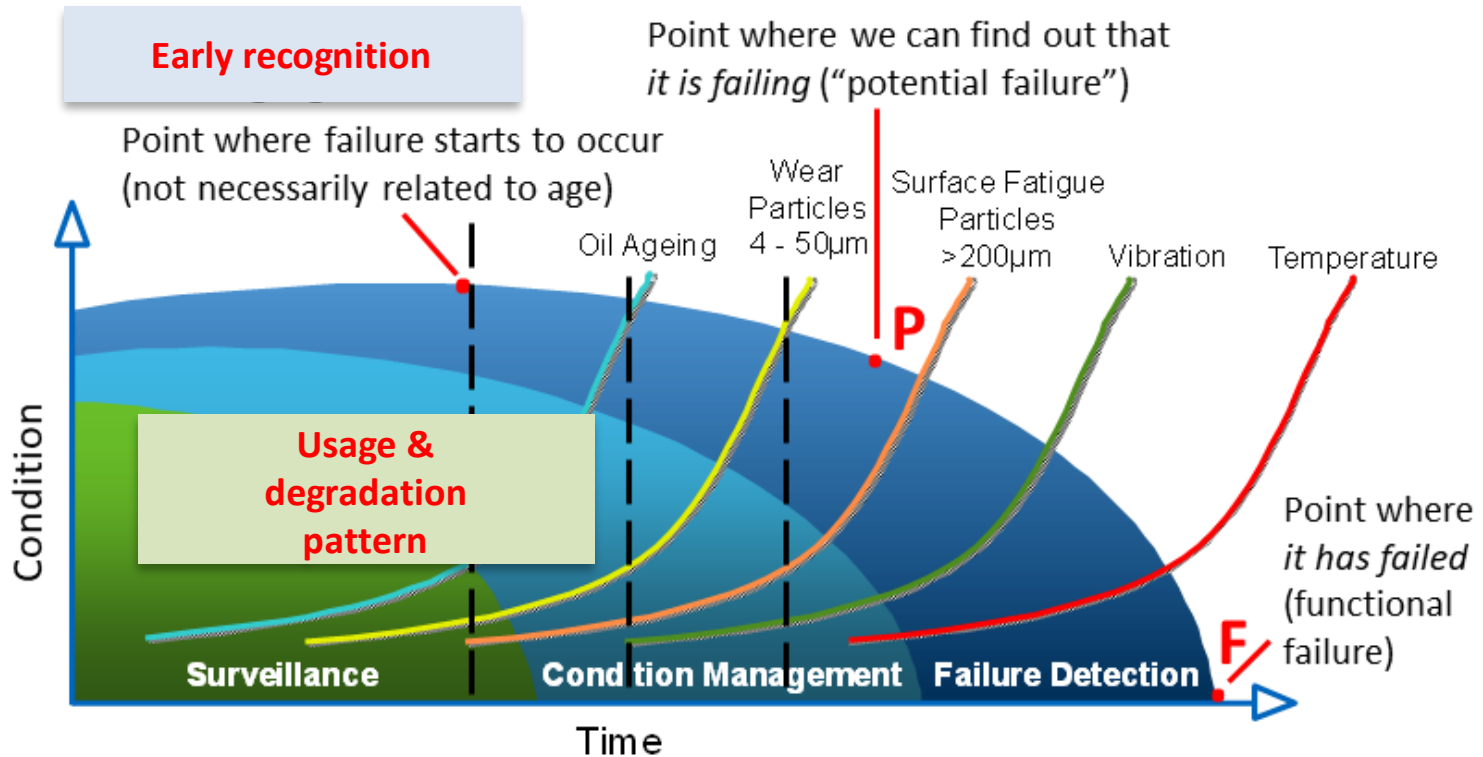


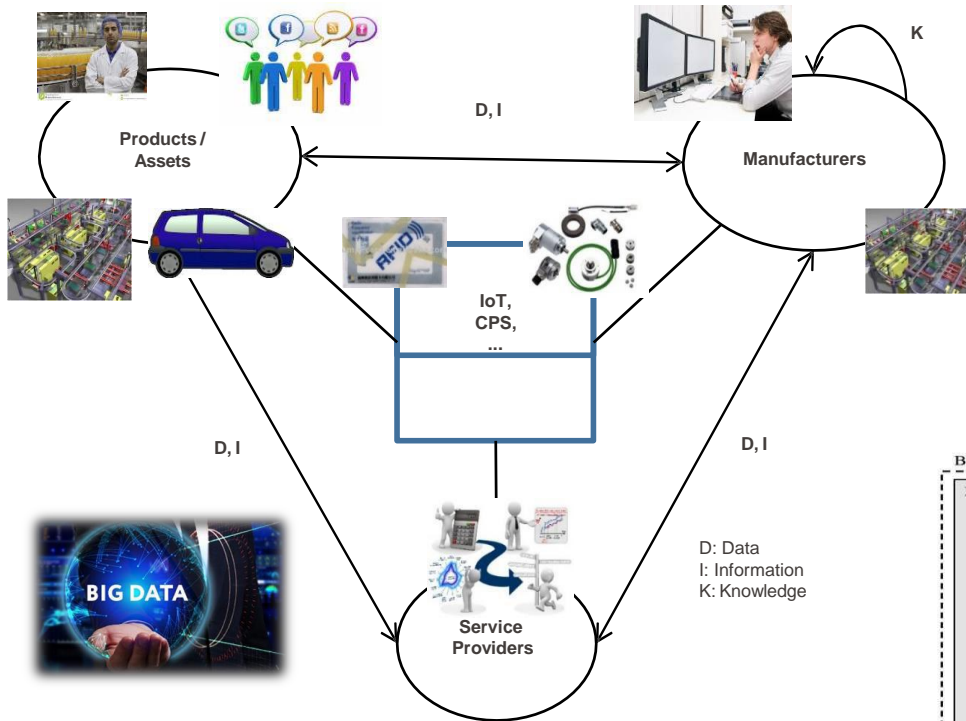
How to set up closed loops in the technical sphere?

- Take into account several cycles of use
 - **Loops** (exploitation - regeneration - exploitation / manufacture)
 - **Types of products** (equipment, subassemblies, components, materials)

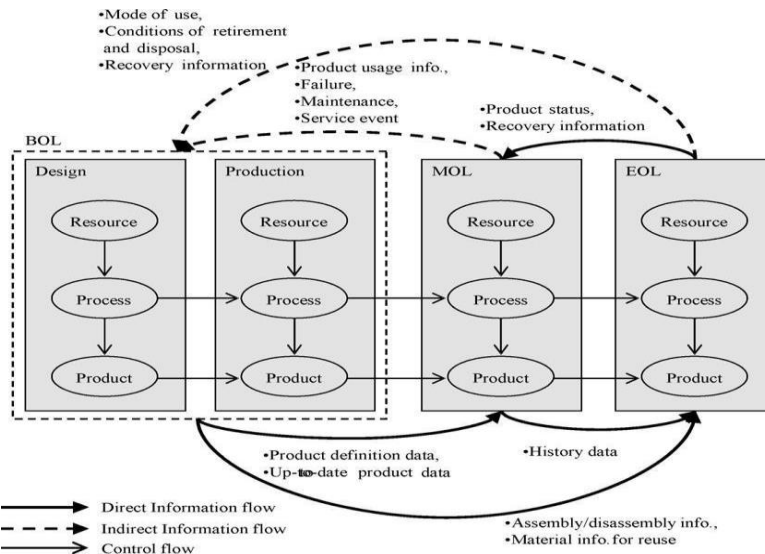
Figure adapted from PhD Thesis Laëtitia Diez, University of Lorraine







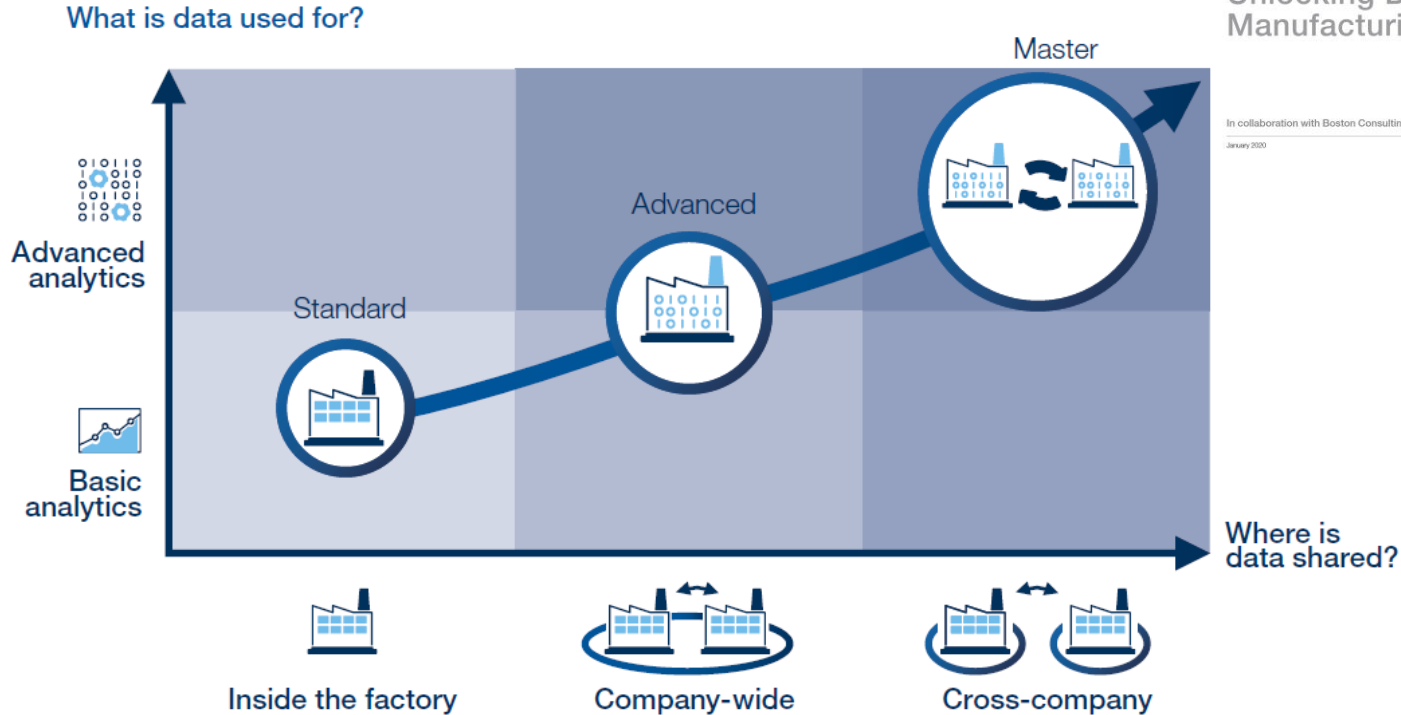
- Closed-Loop Life cycle Data-Information-Knowledge Transformations
- Semantic Model-Based Systems Engineering for Industrial Data Analytics



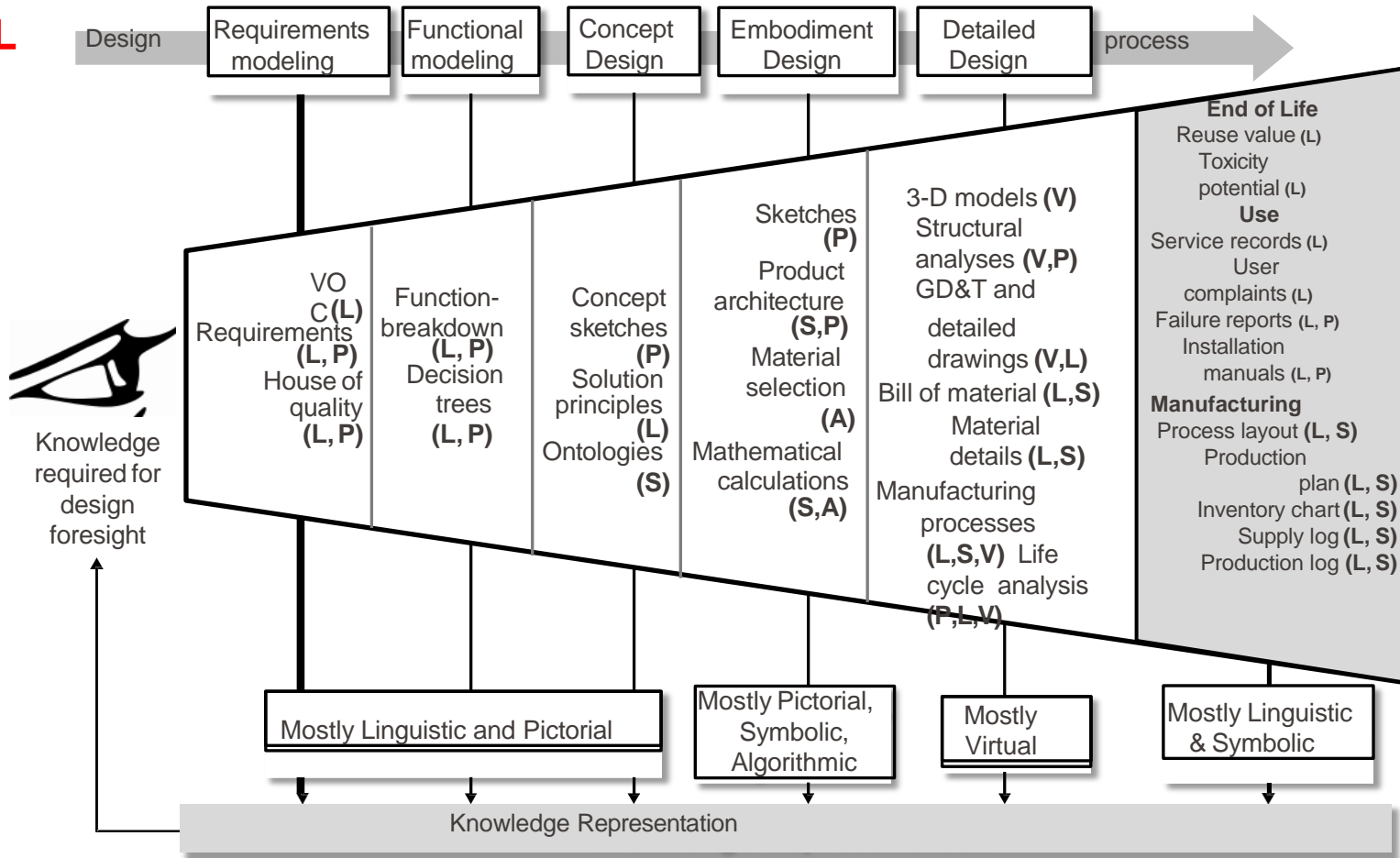
White Paper

Share to Gain: Unlocking Data Value in Manufacturing

In collaboration with Boston Consulting Group
January 2020



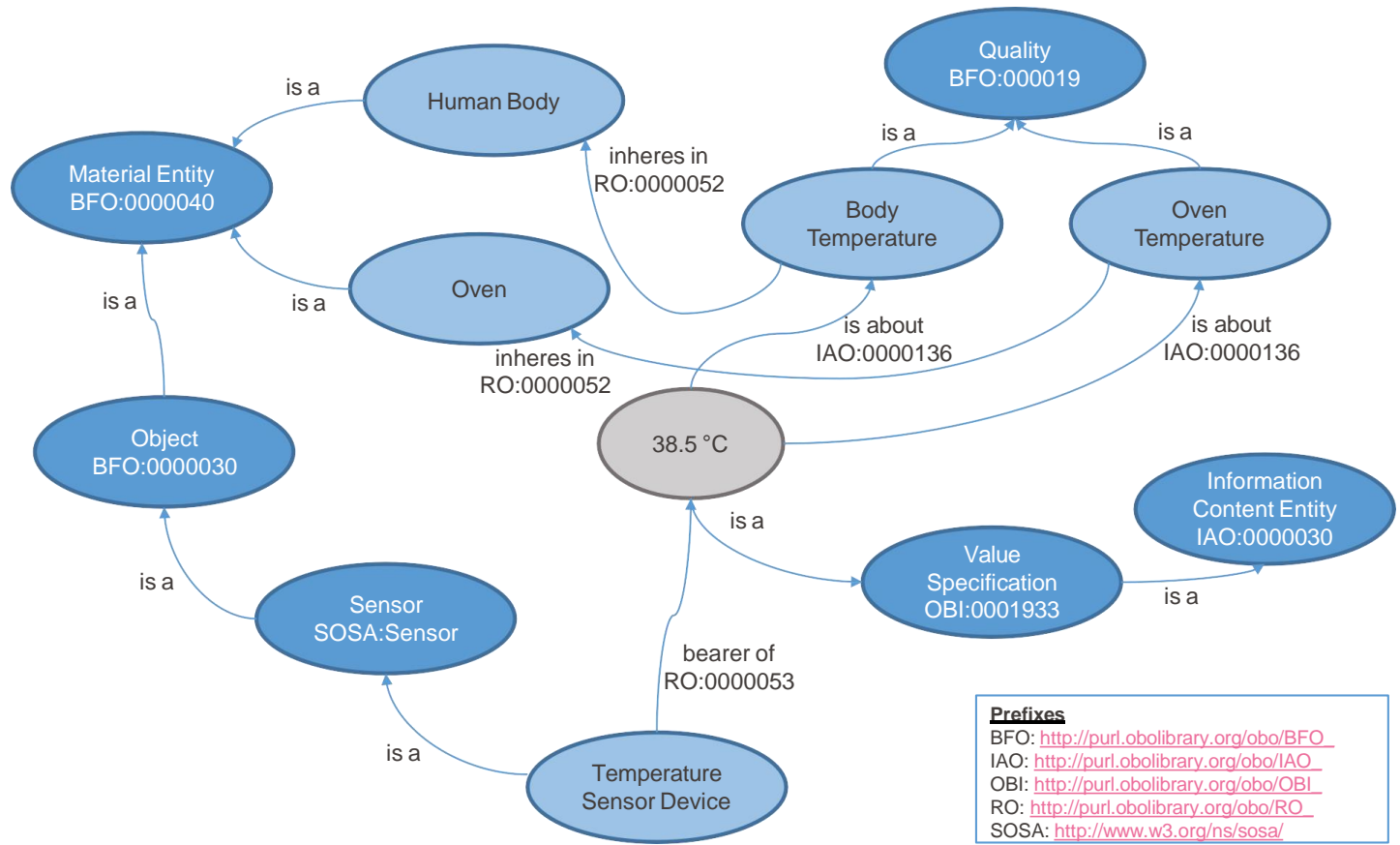
http://www3.weforum.org/docs/WEF_Share_to_Gain_Report.pdf



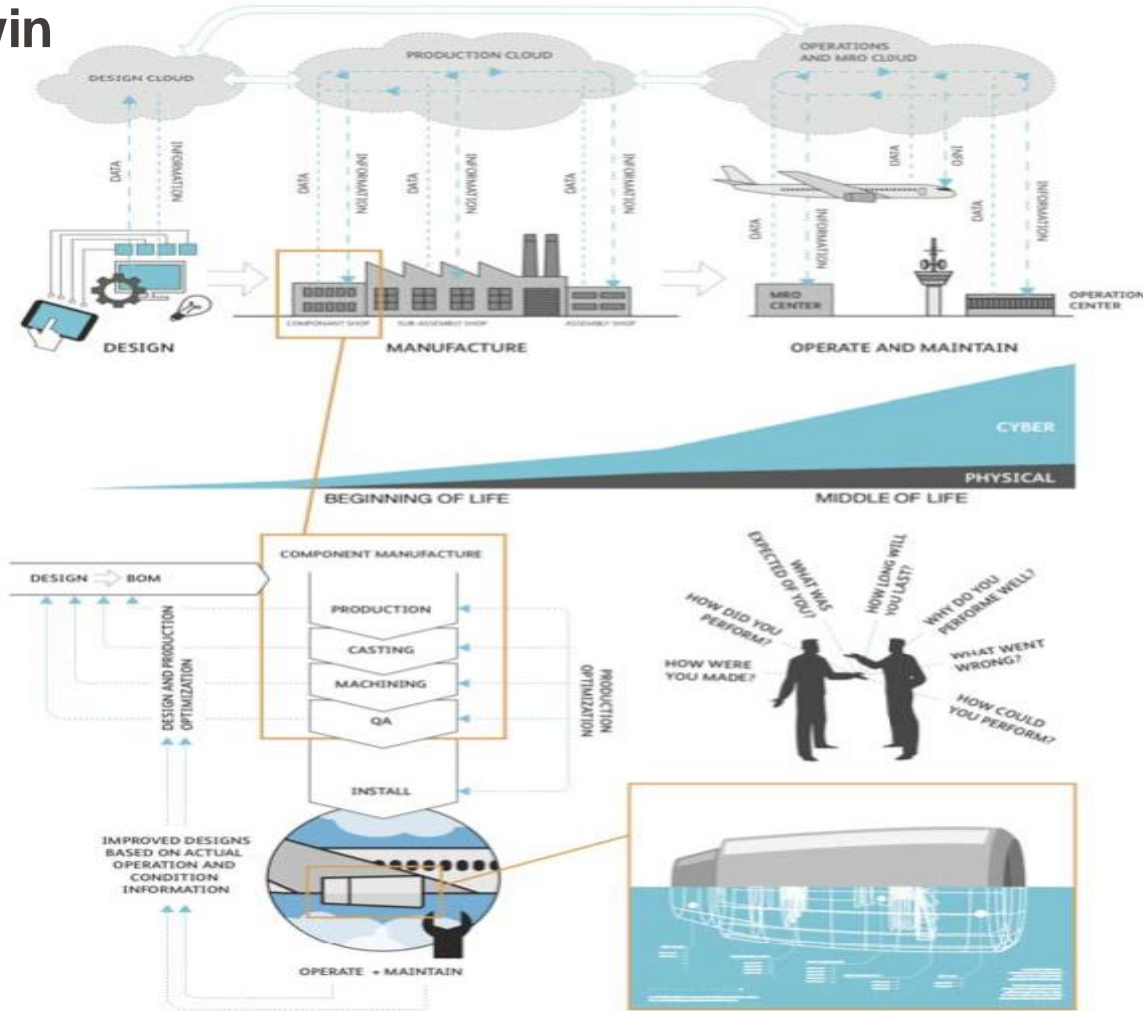
Legend: (P) pictorial (L) linguistic (V) virtual (A) algorithmic (S) symbolic



Knowledge required for design foresight



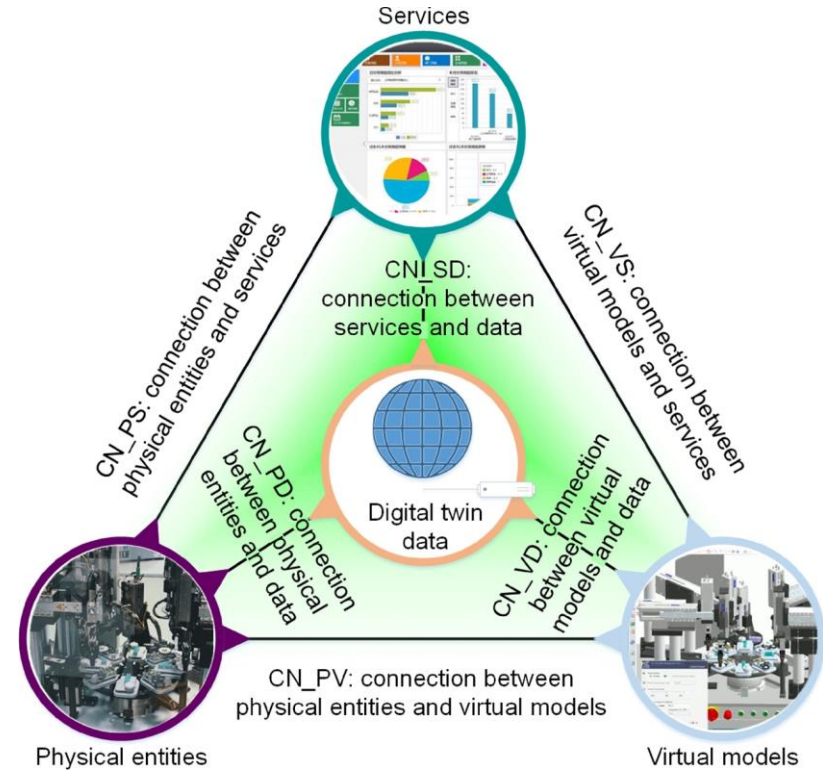
Prefixes
 BFO: <http://purl.obolibrary.org/obo/BFO>
 IAO: <http://purl.obolibrary.org/obo/IAO>
 OBI: <http://purl.obolibrary.org/obo/OBI>
 RO: <http://purl.obolibrary.org/obo/RO>
 SOSA: <http://www.w3.org/ns/sosa/>



- “A Digital Twin is a **virtual instance** of a **physical system** that is **continually updated** with the latter’s performance, maintenance, and health status **data** throughout the physical system’s life cycle.”^a

- Key elements:

- Physical entities
- Virtual instances
- DT data
- Services
- Connections

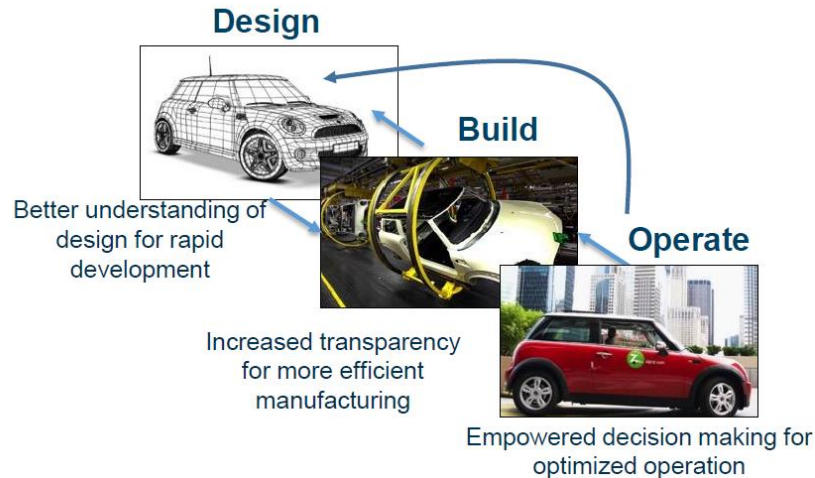


Five-dimension digital twin model ^b

^a Madni et.al., Leveraging digital twin technology in model-based systems engineering, Systems, 2019

^b Qi et.al., Enabling technologies and tools for digital twin, Journal of Manufacturing Systems, 2019

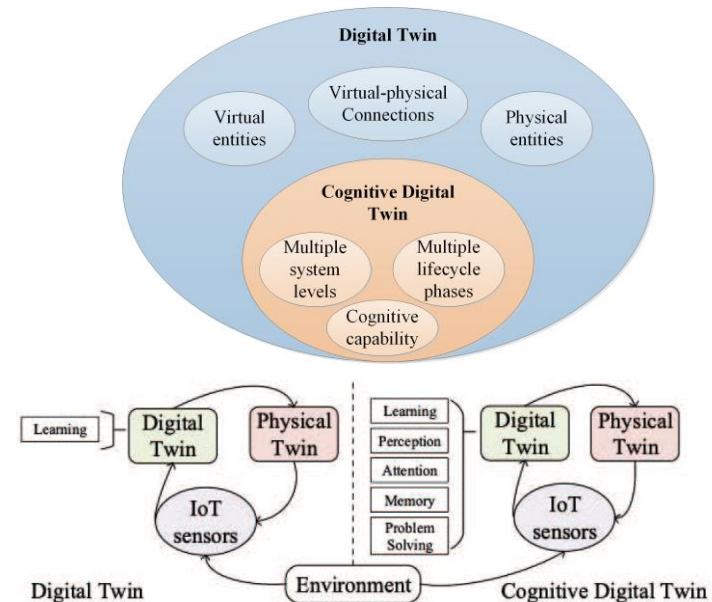
- High complexity of modern industrial systems
- Heterogeneous DT models corresponding to
 - related systems, subsystems and components
 - different lifecycle phases
 - different stakeholders, protocols and standards
- Lack of unified platform for integrating all relevant DT models



- Cognitive Digital Twin (CDT) is a **digital representation** of a physical system that is augmented with certain **cognitive capabilities**; comprises a set of **semantically interlinked digital models** related to different **lifecycle phases** of the physical system including its subsystems and components; **evolves continuously** with the physical system across the entire lifecycle; and support to execute **autonomous lifecycle activities**.

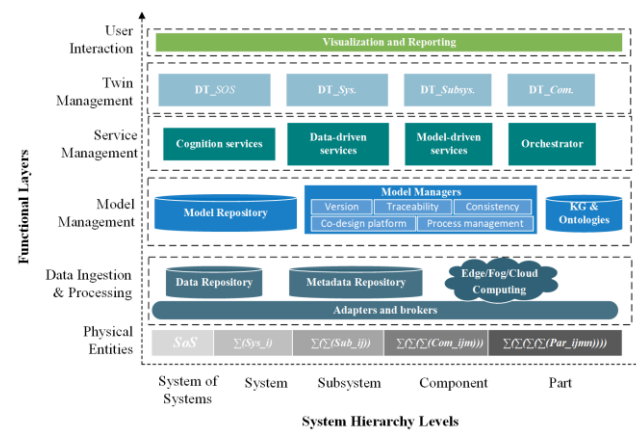
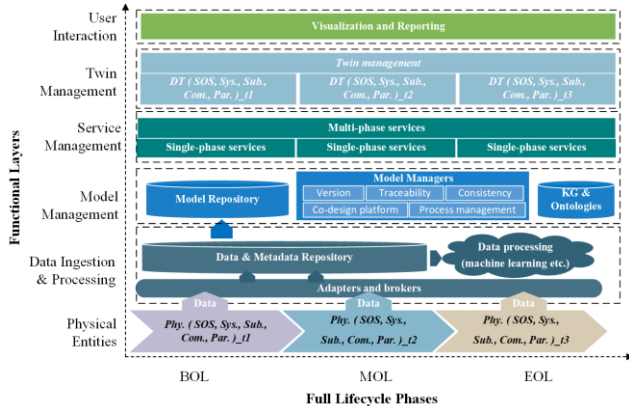
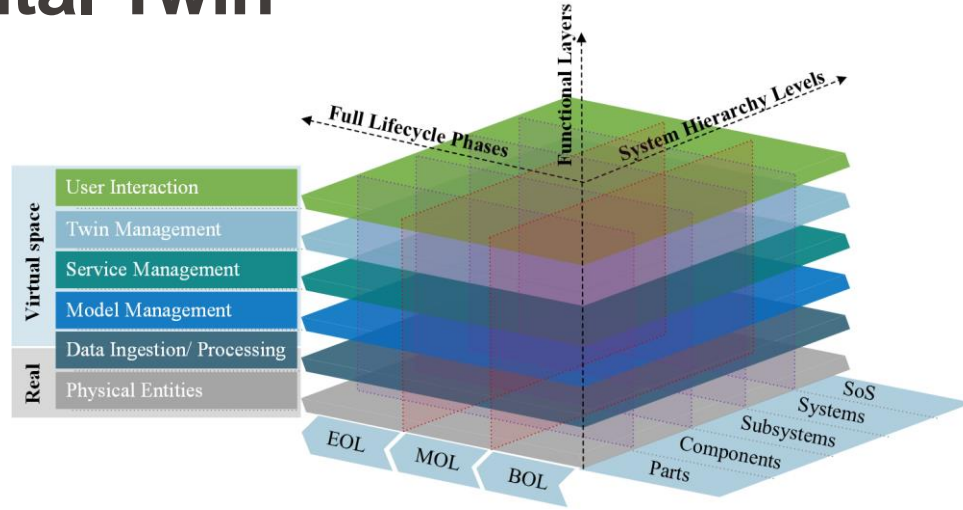
- Characteristics :**

- Based on Digital Twin
 - CDT is a subset of DT
- Cognitive capabilities
 - attention, perception, comprehension, memory, reasoning, prediction, decision-making etc.
- Autonomy capability
 - conduct autonomous activities without human assistance or minimum level of human intervention
- Cross lifecycle phases & cross system levels
- Continuous evolving
 - Multi-levels and multi-lifecycle phases interaction



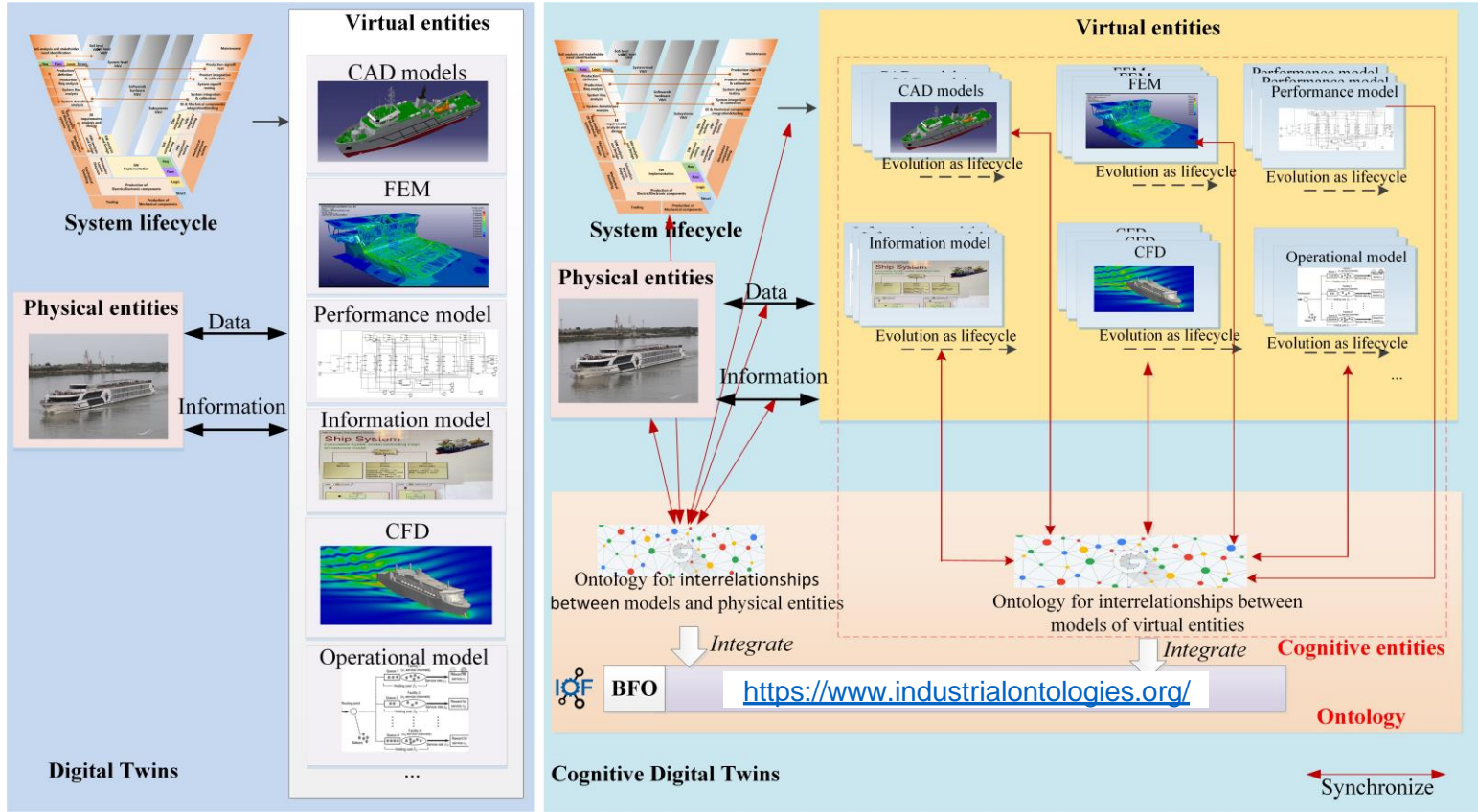
Reference Architecture

- Full lifecycle phases
- System Hierarchy levels
- Functional layers



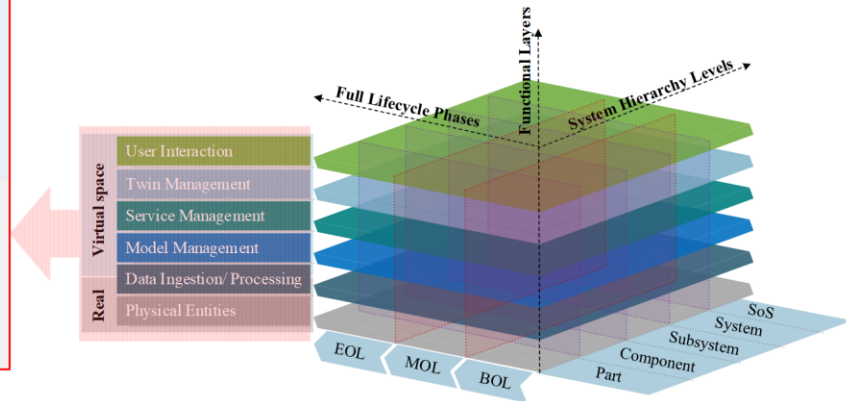
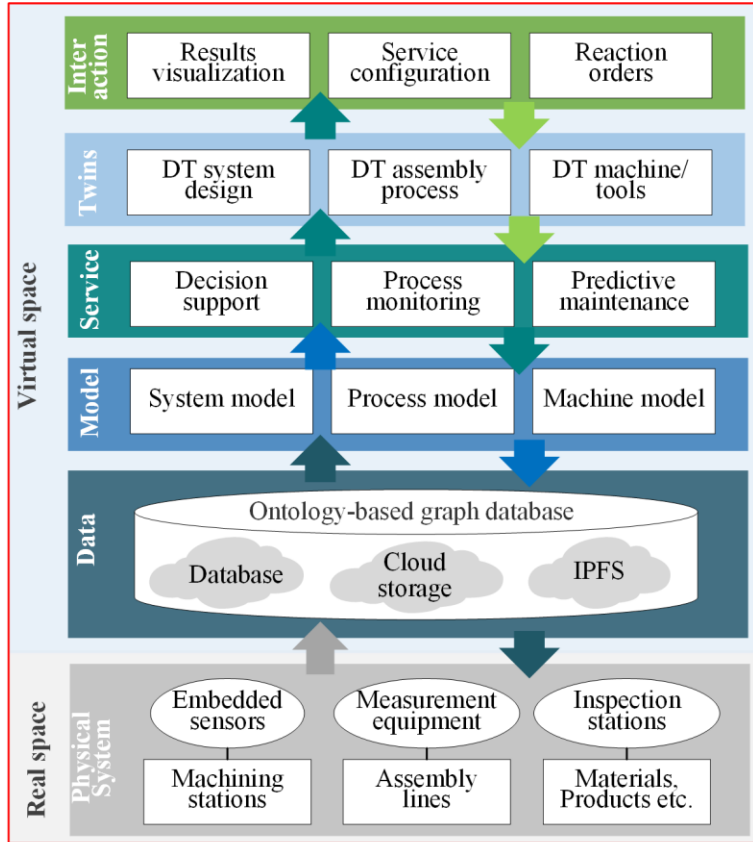
Cognitive Digital Twin

- DT vs CDT

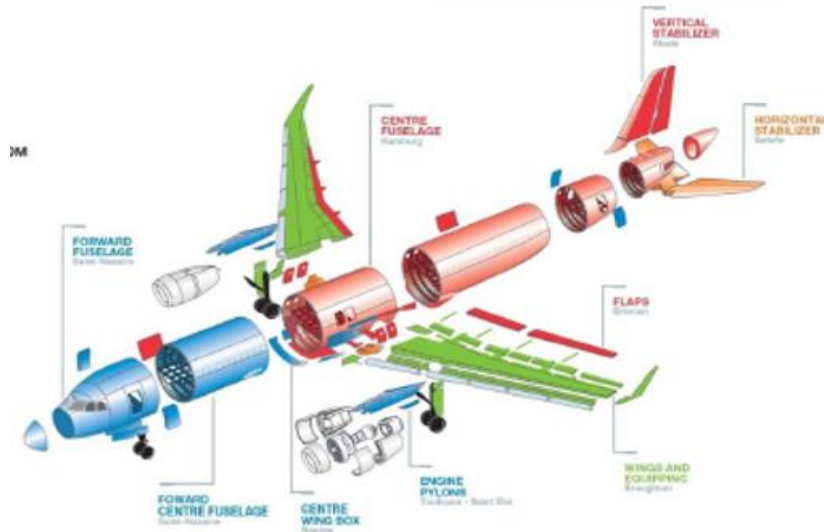


<https://www.tandfonline.com/doi/full/10.1080/00207543.2021.2014591>

- Multiple lifecycle phases:

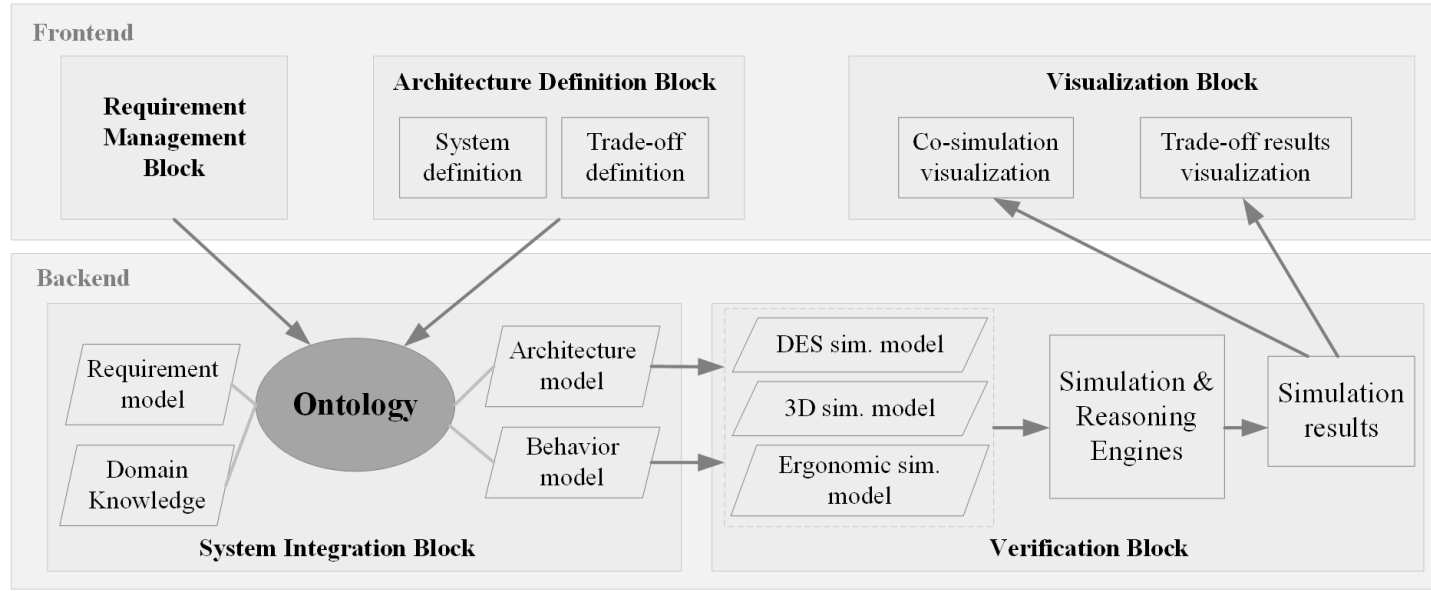


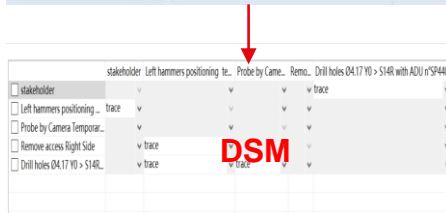
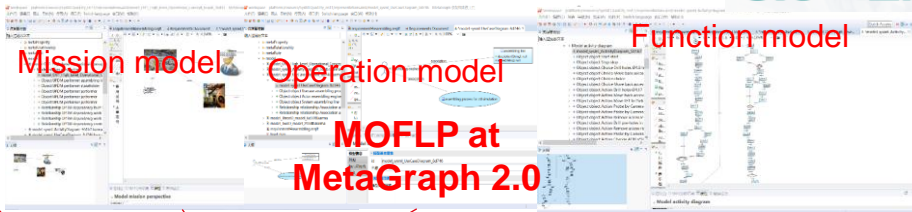
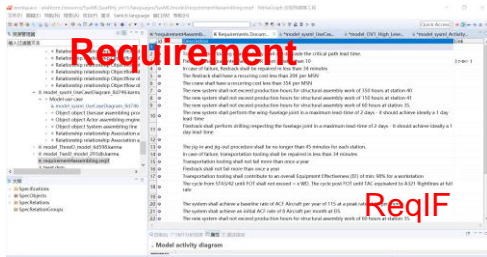
- CDT supports aircraft industrial system design
 - Focuses on the R&D phase of the assembly line for a new model of aircraft
 - Fuselage orbital junction process for a given assembly station of a Final Assembly Line (FAL) for the new aircraft model



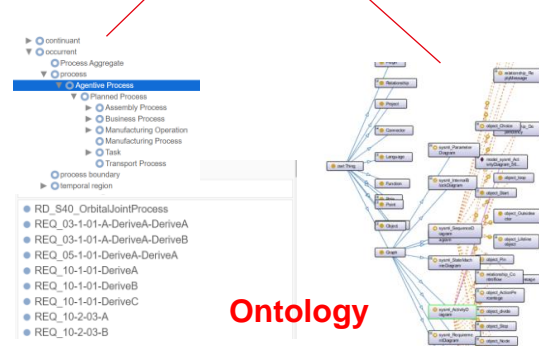
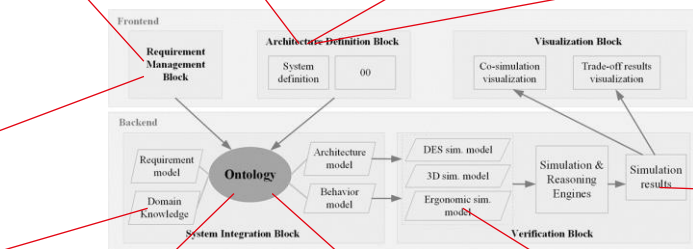
<https://atcnews.org/2016/05/31/rwandairs-ubumwe-now-on-the-airbus-assembly-line/>

- CDT supports aircraft industrial system design
 - Supports automatic trade-off among different performance parameters under different industrial scenarios
 - Key functional block of the trade space framework for system integration, e.g. requirement model, architecture models and behavioral models etc.



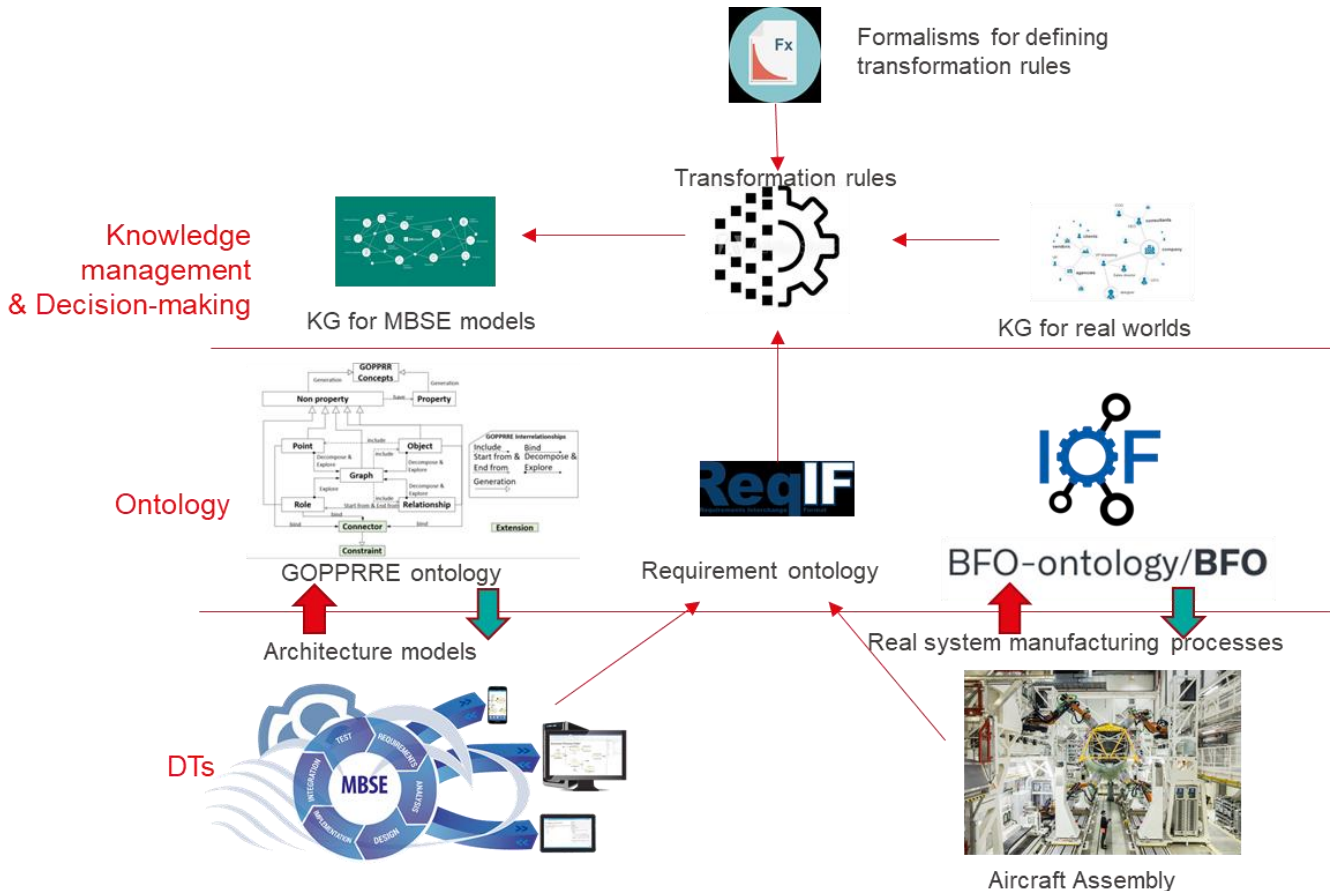


Task Name	Duration	Predecessors	Resource Name
Drilling Stronger 4.132	10 mins	18	CS Oppor_3
Demolish LPT and coils	15 mins	19, 21	CS Oppor_3_LPT
Set up the fixtures (LPT) (Use on both) (stronger 4.132)	30 mins	20	CS Oppor_3
Finalize stronging and 8 part of stronging 4.132	30 mins	21	CS Oppor_3
Mounting buttopps and stabiliser L22 (2) (4.132)	75 mins	22	CS Oppor_3
Disassemble L22 CS Oppor 3H	30 mins	23	CS Oppor_3
Load (10) (10) Stronging the Stronging 4.132 (L22)	30 mins	24, 25	CS Oppor_3
10.200.045	30 mins	9	LPT Robot copper
10.200.046	30 mins	26	LPT Robot copper
10.200.016	15 mins	31	LPT Robot copper
10.200.015	30 mins	29	LPT Robot copper
10.200.014	30 mins	28	LPT Robot copper
10.200.013	30 mins	27	LPT Robot copper



Graphical rep. of 2D/3D models in MetaGraph 2.0

Domain Knowledge



Digital Twins: Concept, Technologies & Applications

Ontology development



Digital Twins: Concept, Technologies & Applications

Knowledge source 1: Historical Orbital Joint Process specifications.

Resources

- S40_R_C35 Lower Left_1
- S40_R_C35 Lower Left_2
- S40_R_C35 Lower Right
- S40_R_C35 Rail
- S40_R_C35 Upper_1
- S40_R_C35 Upper_2
- S40_R_C35 Upper_3
- S40_R_LFT Robot Lower
- S40_R_LFT Robot Upper

Materials

- S40_M_Buttstrap4,8
- S40_M_Buttstrap1
- S40_M_Buttstrap2
- S40_M_buttstrapstringers
- 1/2/3/6/9/14/18
- S40_M_Camera
- S40_M_Drilling template
- S40_M_Fixations LGP/Hi-Lite

Relationships

- hasPredecessors
- hasPredecessors
- max_time
- min_time
- op_duration
- op_type
- requiresResource
- requiresResource

Operations

- S40_OrbitalJointProcess
- S40_R_C35 Lower Left_1
- S40_R_C35 Lower Left_2
- S40_R_C35 Lower Right
- S40_R_C35 Rail
- S40_R_C35 Upper_1
- S40_011_Camera at stating holes_1
- S40_012_Set in position temporary
- S40_013_Drilling buttstrap 4,8 + complement orbital Left
- S40_014_Drilling Stringer 4,17(1)
- S40_015_Camera at stating holes_2
- S40_016_Set in position temporary
- S40_017_Drilling buttstrap 4,8 + complement orbital Right
- S40_018_Drilling Stringer 4,17(2)
- S40_019_Uninstall LFT and rails
- S40_020_Set up the fixations LGP/Hi-Lite
- S40_011_Camera at stating holes_1
- S40_012_Set in position temporary f
- S40_013_Drilling buttstrap 4,8 + cor
- S40_014_Drilling Stringer 4,17(1)
- S40_015_Camera at stating holes_2

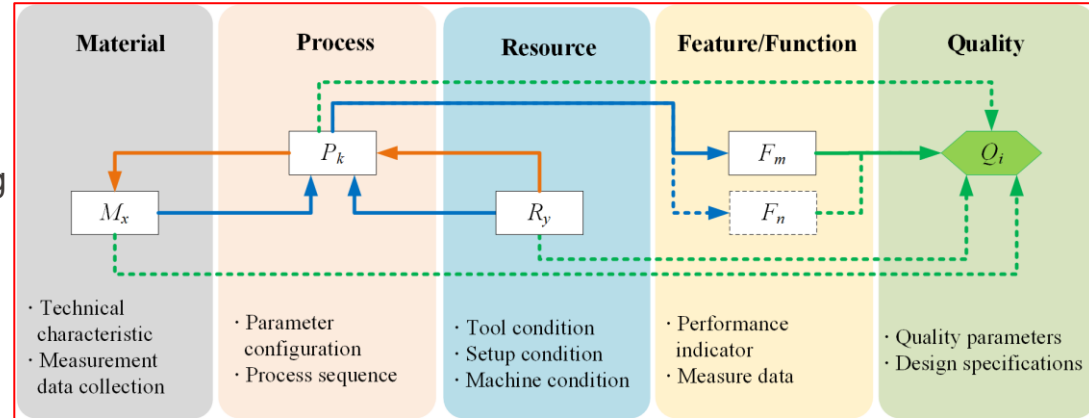
Task Name	Duration	Predecessors	Resource Names
: Drilling Stringer 4,17(2)	50 mins	18	C35 Upper_1
: Deinstall LFT and rails	15 mins	15,31	C35 Upper_1, LFT1
: Set up the fixations LGP/Hi-Lite on buttstrap/stringers 1/2/3/6/9/14/18 Left	90 mins	20	C35 Upper_1
: Finalize remaining serial & part of stringers on 1+1 Left	90 mins	21	C35 Upper_1
: Riveting buttstraps and stabiliser 11/2/3/6/9/14/18 Left	75 mins	22	C35 Upper_1
: Inspection L2 C35 Upper INT	15 mins	23	C35 Upper_1
: Load P265 DMT/Fixing the buttstraps 14-5,7-8,10-12,13 Left	95 mins	24F5+10 mins	C35 Upper_1
: S1 20G-18G	15 mins	4	LFT Robot Upper
: S2 20G-18G	15 mins	26	LFT Robot Upper
: S3 20G-16G	15 mins	11	LFT Robot Upper
: S4 20G-16G	80 mins	28	LFT Robot Upper
: S6 20G-16G	15 mins	29	LFT Robot Upper
: S7 20G-16G	80 mins	30	LFT Robot Upper

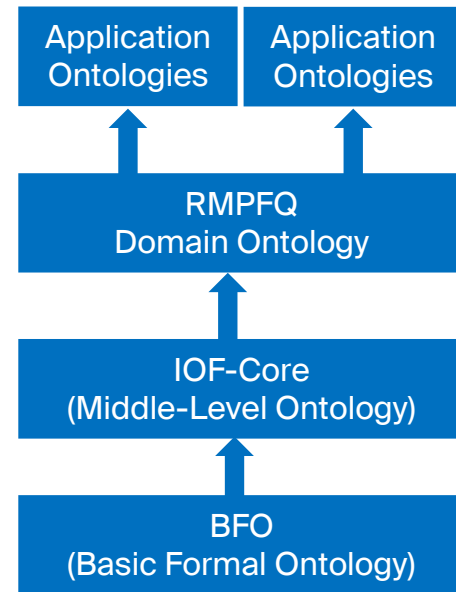
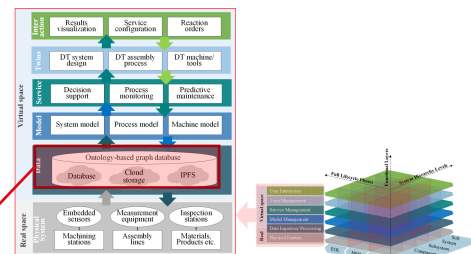
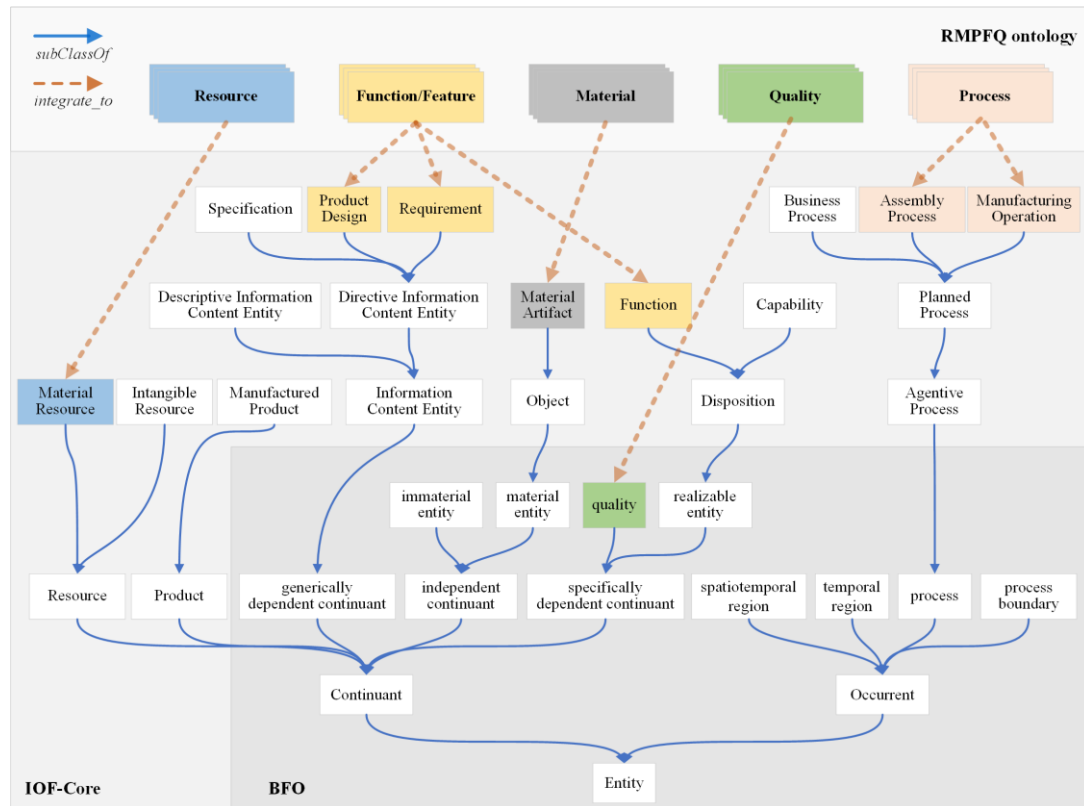
Knowledge source 2: Domain experts' knowledge.

Material	Process	Resource	Feature/Function	Quality
M_x	P_t	R_y	F_m F_n	Q_u
<ul style="list-style-type: none"> Technical characteristic Measurement data collection 	<ul style="list-style-type: none"> Parameter configuration Process sequence 	<ul style="list-style-type: none"> Tool condition Setup condition Machine condition 	<ul style="list-style-type: none"> Performance indicator Measure data 	<ul style="list-style-type: none"> Quality parameters Design specifications

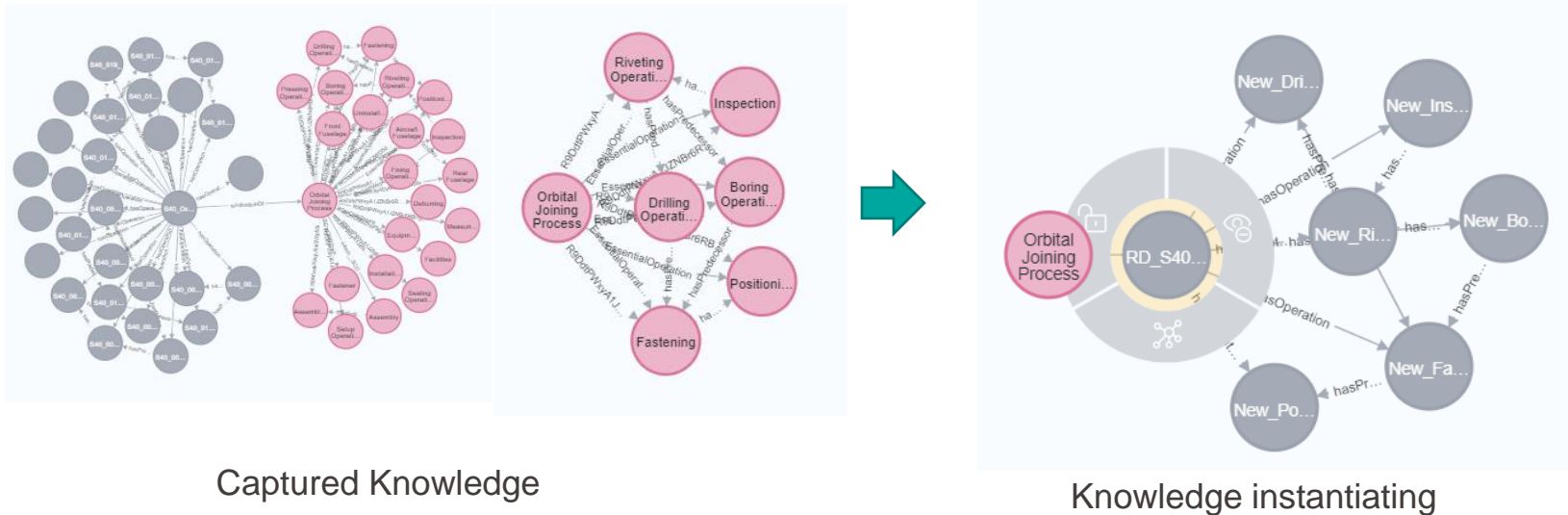
RMPFQ-model:

- **Resource:** devices, tools and means to produce goods and services, except raw material and product components [ISO 15531].
- **Material:** raw materials, product components and assemblies etc., that is needed to produce a certain product.
- **Processes:** processing and transforming materials into the final goods by using machines, tools and human labour.
- **Functions/Features:** distinguished characteristics of a product, e.g. functionalities like specific tasks, actions or processes that the product is able to perform; and/or other features like performance
- **Quality:** the degree of conformance of final product functions and features to designed requirements [ISO 9000].





- Knowledge captured from the existing orbital joining process is represented in the ontology by a generalized class which contains necessary operation classes and their relationships
- When designing a new Orbital Joint Process, the new instance (e.g. Individual RD_S40_OrbitalJointProcess) automatically inherit the predefined properties (operations).
- It provides starting point for Industrial System Engineer for new system design



neo4j@bolt://localhost:7687/orbitaljoint - Neo4j Browser

File Edit View Window Help Developer

```
1 MATCH (operatorin)-[relationship]-(entity) WHERE operatorin.name STARTS WITH 'N'  
2 RETURN *;
```



Graph



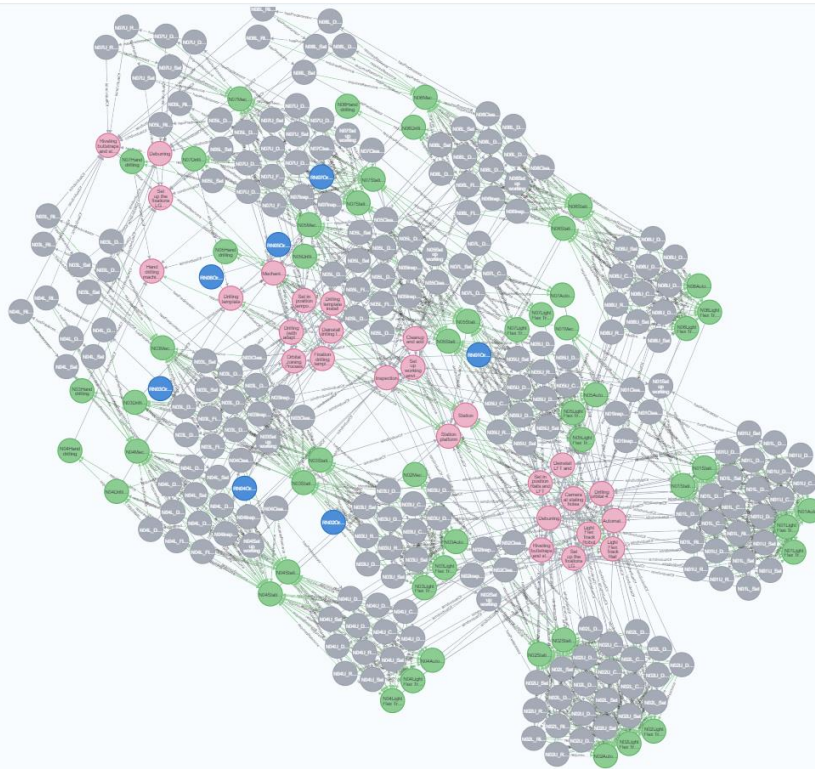
Table



Text



Code



Overview

Node labels



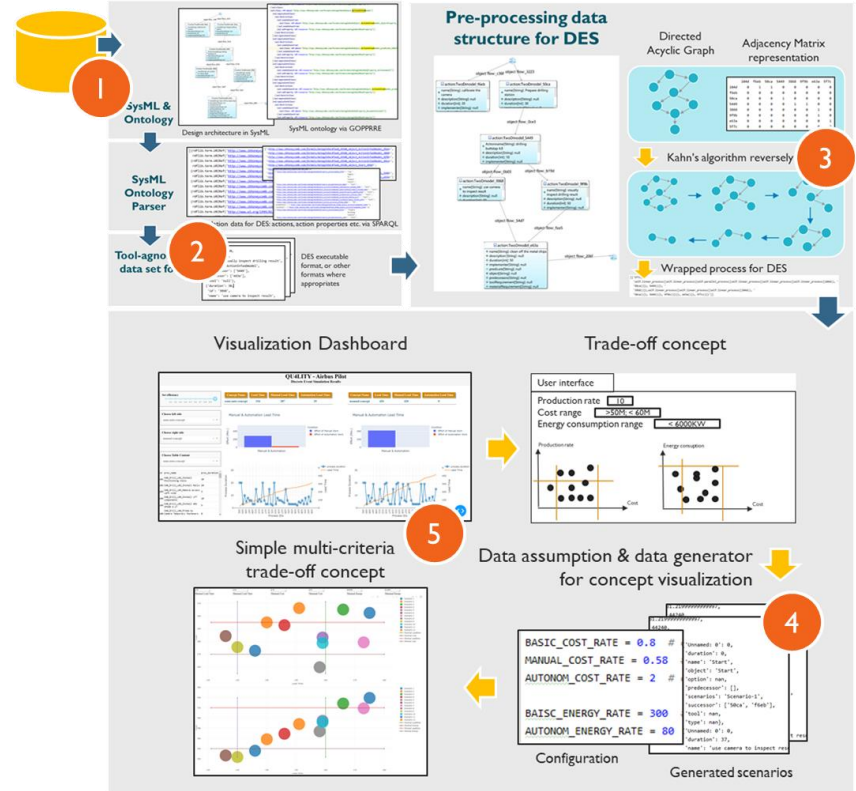
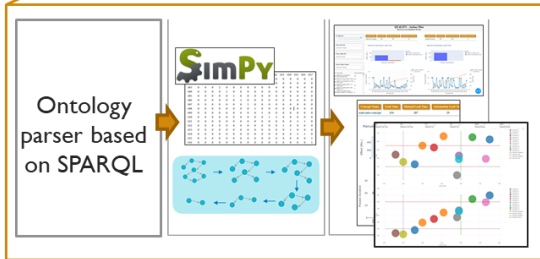
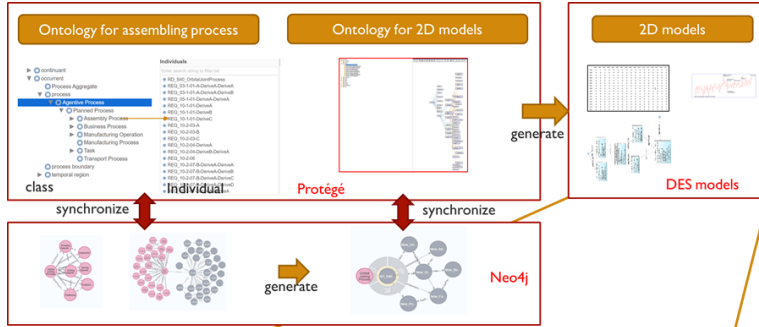
Relationship Types



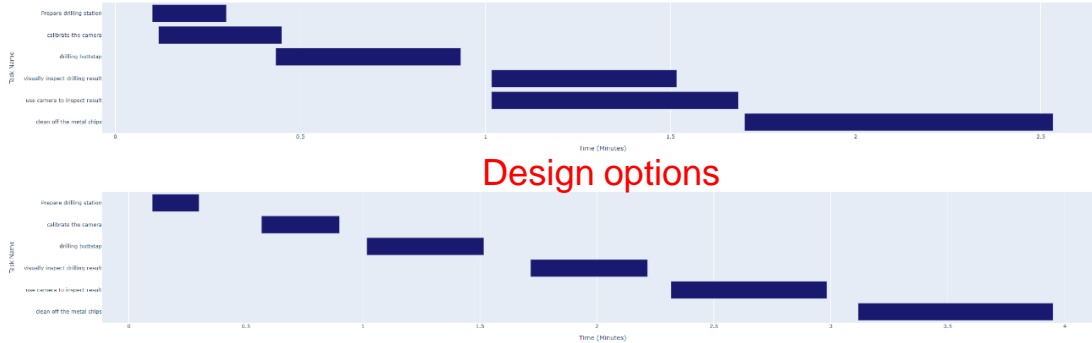
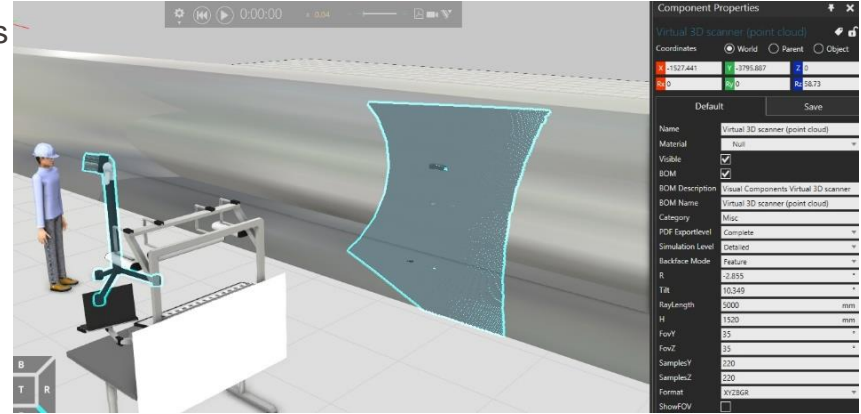
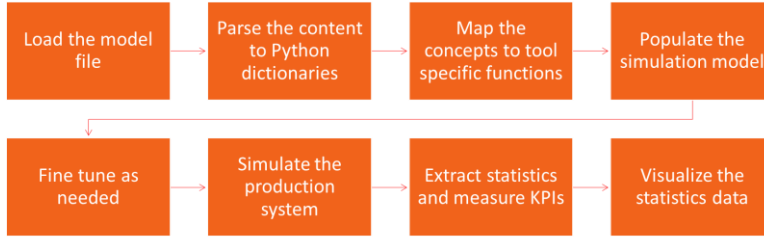
Displaying 300 nodes, 1,386 relationships.

2D Simulation

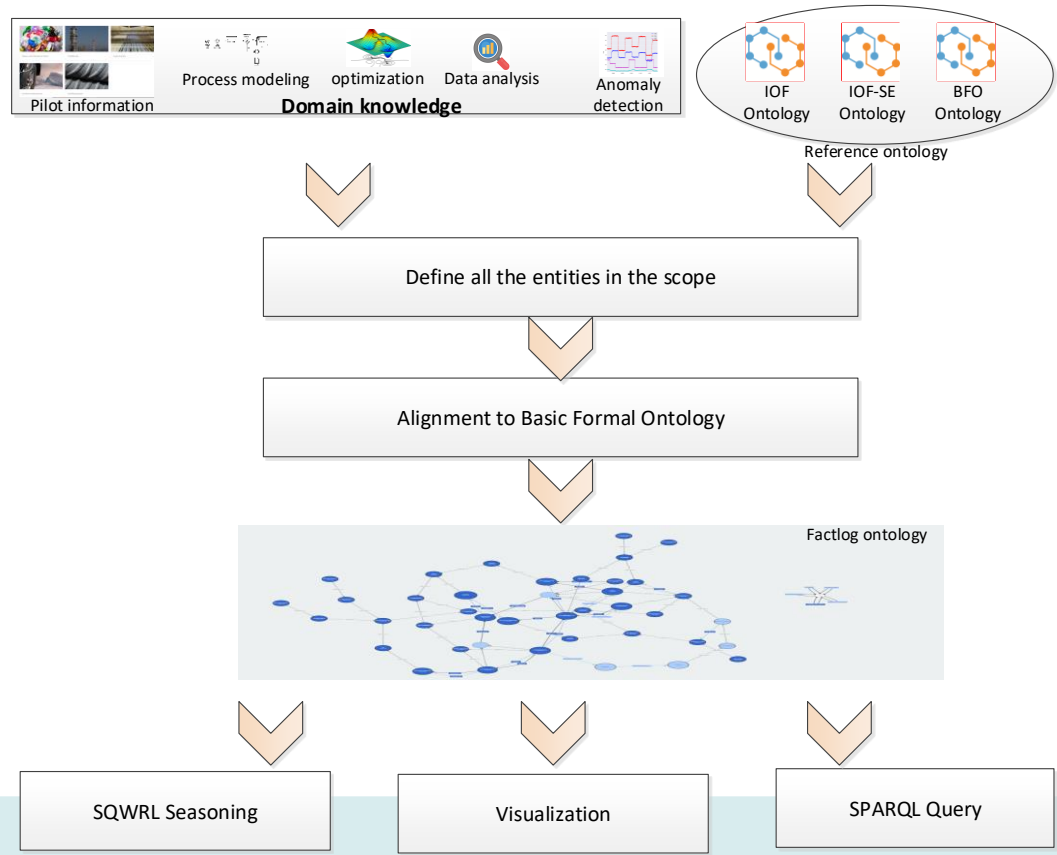
- Generate Discrete Event Simulation (DES) model from application ontology, which describes a design architecture
- Automatic generation covering different scenarios for assembly process designing
- Achieve decision supports with DES and data analysis during industrial system design



- Once created the virtual scenario faster validation, allows using 3D simulation from the initial design steps
- Easy validation of different cases (workers, resources,..), independent of the facility
- Mapping from Ontology to Simulation:



Research methodology



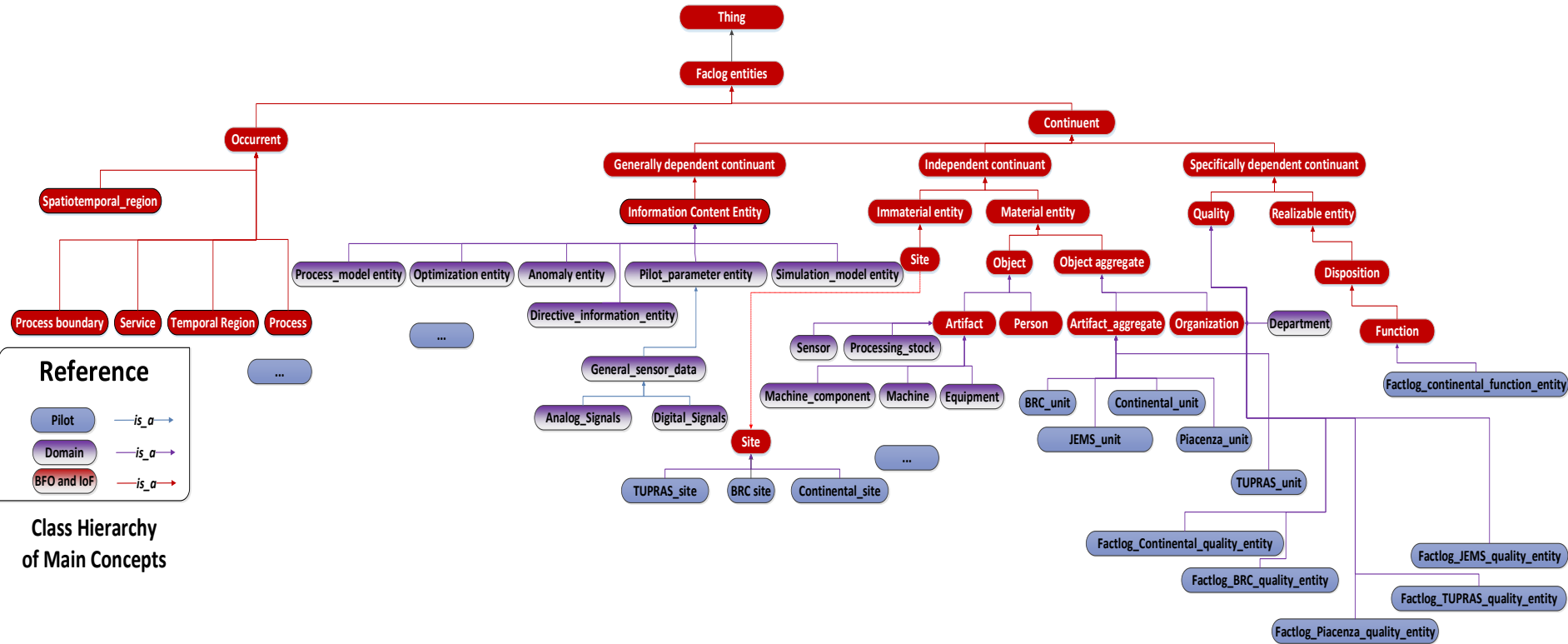
Unified description of digital twins and information across FACTLOG platform

Anomaly detection for cognition

- NEO4J for KG representation
- CYPHER for query

Visualization of the interrelationships of all the ontology entities and individuals

Ontology framework



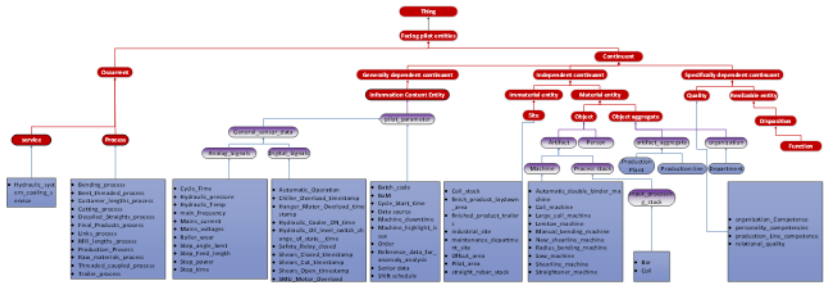
Reference

- Pilot — is_a →
- Domain — is_a →
- BFO and lot — is_a →

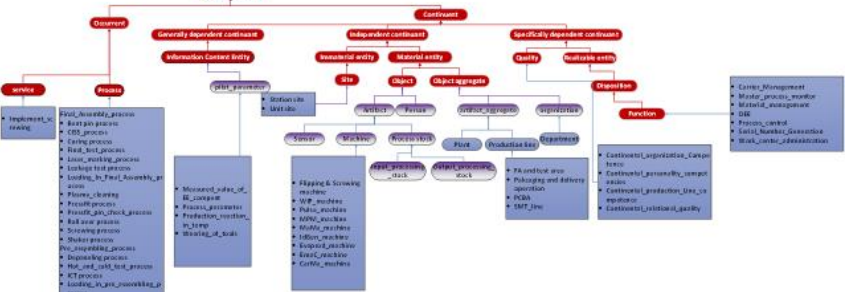
Class Hierarchy of Main Concepts

Factlog Pilot Ontology

Ontology



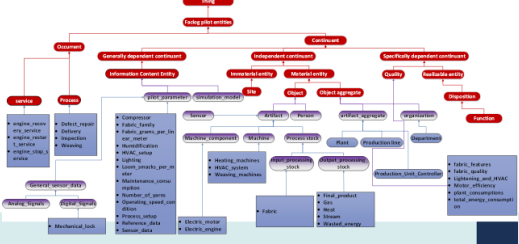
Ontology



BRC

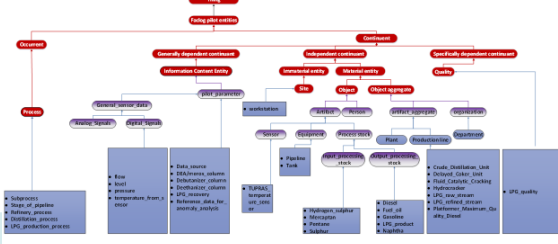
Continental

Ontology



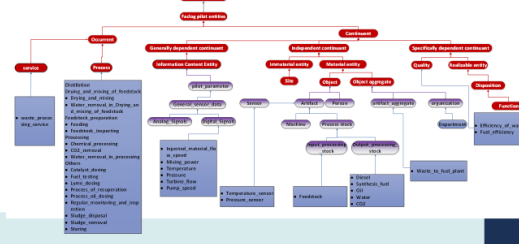
Piacenza

Ontology



TUPRAS

Ontology



JEMS

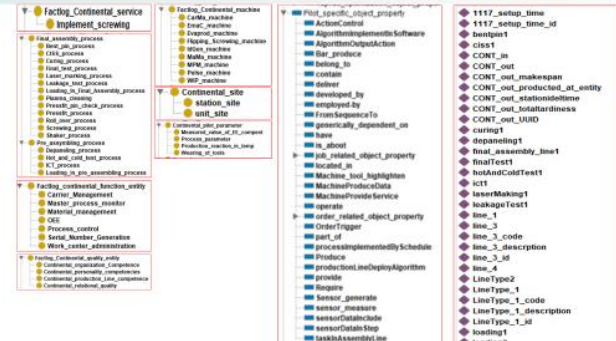
Factlog Pilot KG models

Knowledge graph model



BRC

Knowledge graph model



Continental

Knowledge graph model



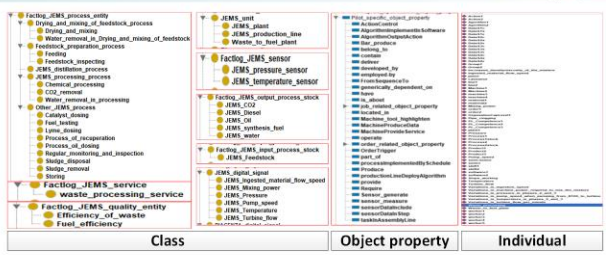
Piacenza

Knowledge graph model



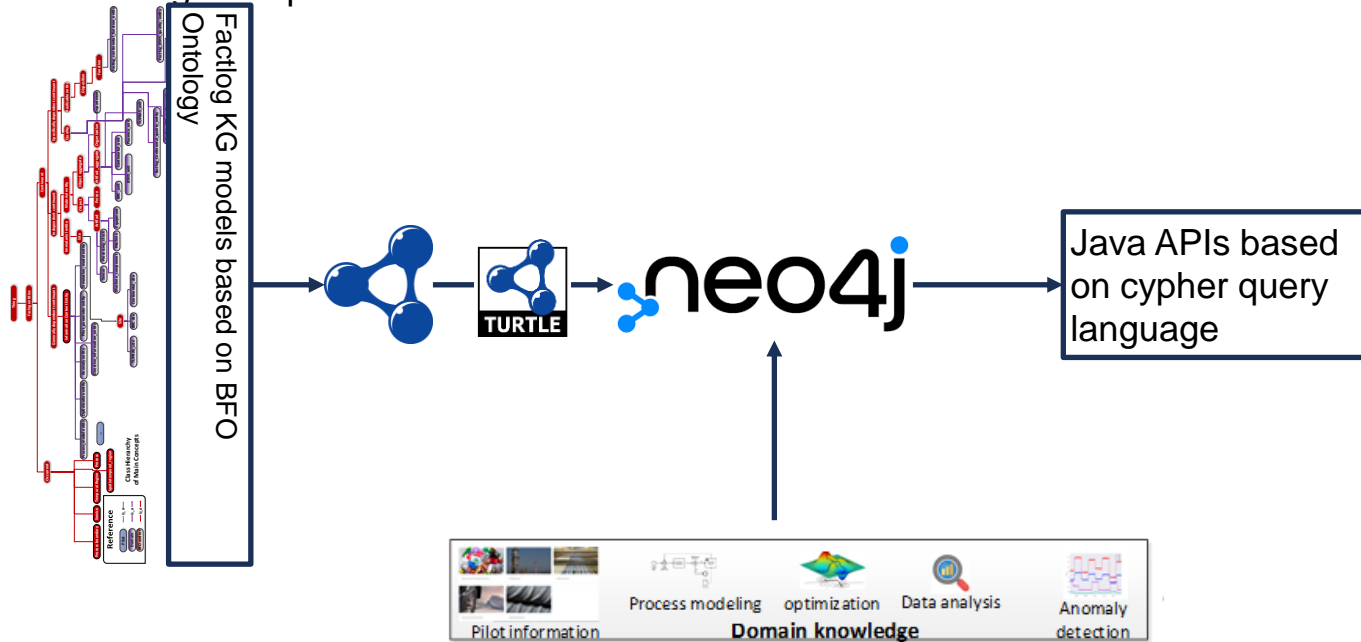
TUPRAS

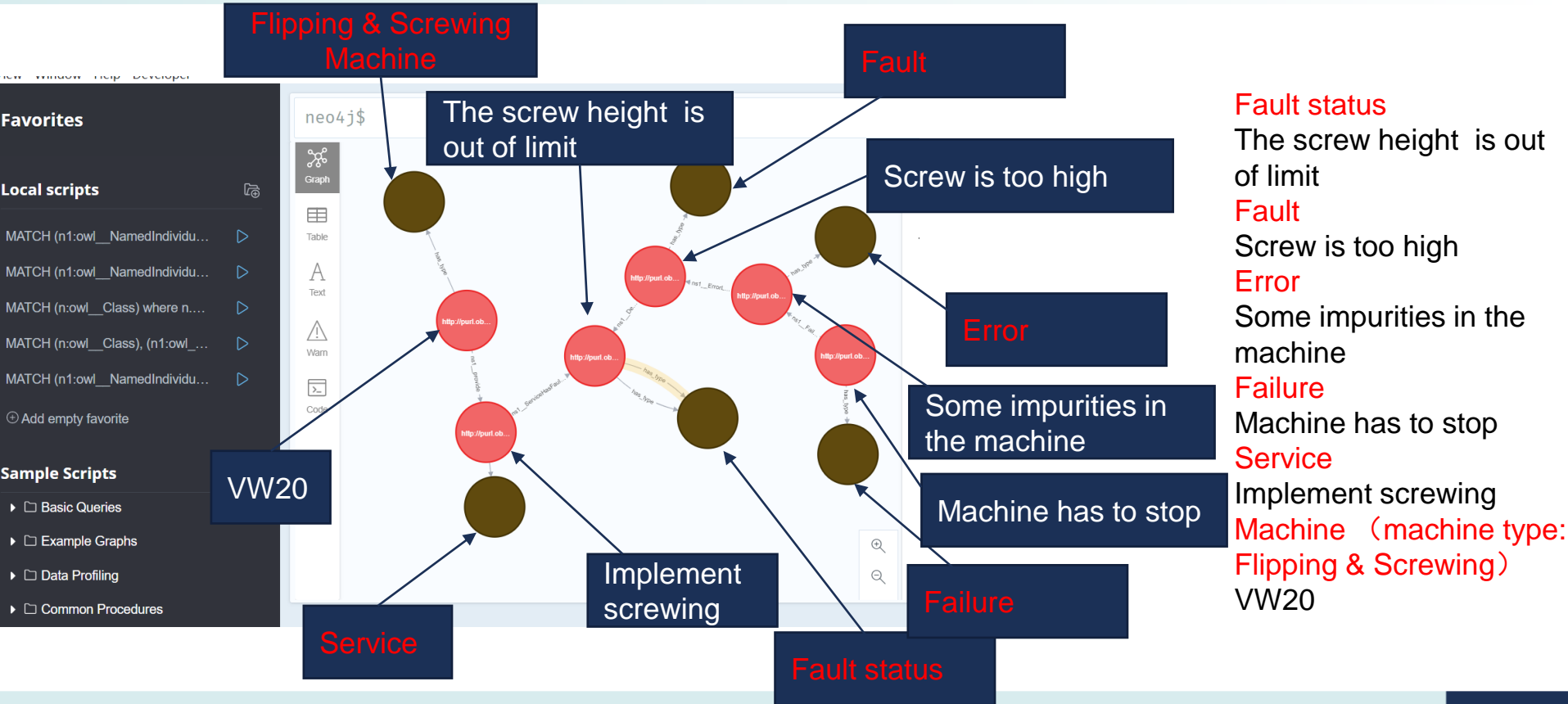
Knowledge graph model



JEMS

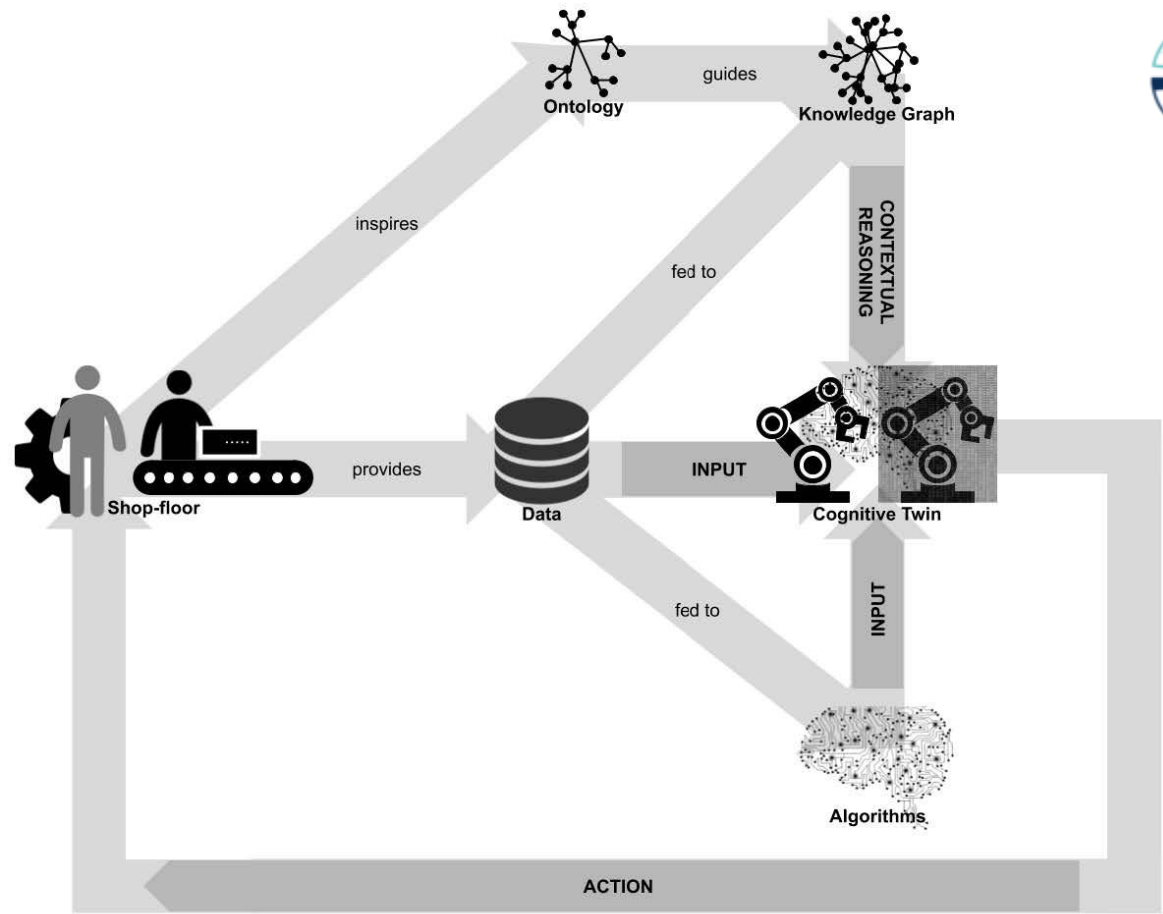
Task 3.3 Factory knowledge 4.0 Interpreting factory knowledge base from the cognition point of view EPFL







<https://www.factlog.eu/>



Thank you for your attention!



www.ict4sm.epfl.ch/



<https://www.linkedin.com/in/dimitris-kiritsis-07124/>



dimitris.kiritsis@epfl.ch