

Polynomial Time Probabilistic Learning of a Subclass of Linear Languages with Queries

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This talk...

- Probabilistic learning algorithm of a subclass of **linear languages** with membership queries
- learning via queries + special examples → Probabilistic learning

Use translation algorithms

representative sample → random examples

equivalence query → random examples

Motivations

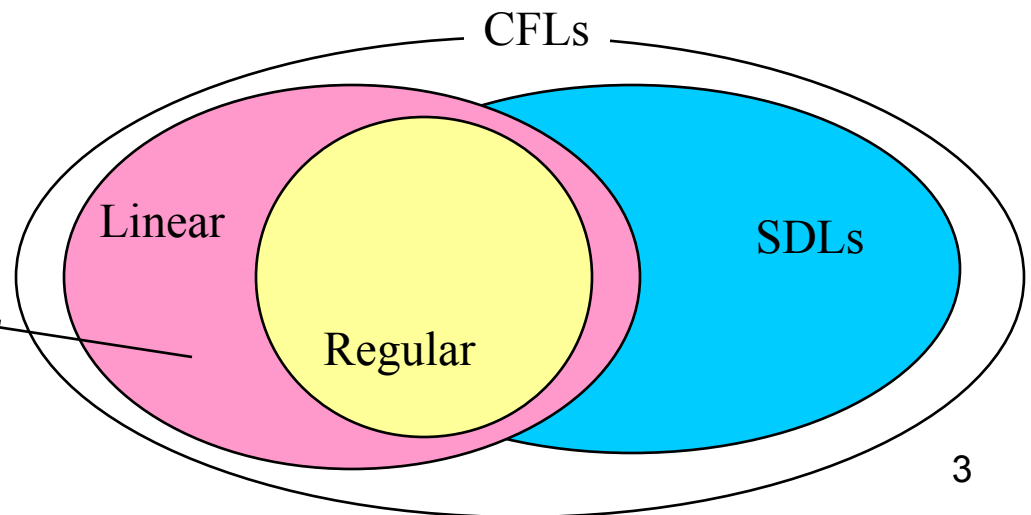
A simple deterministic grammar (**SDG**) has at most one rule $A \rightarrow a\beta$ for every pair of $\left(\begin{array}{l} A \in N \\ a \in \Sigma \end{array} \right)$

\Rightarrow learning algorithm for **SDG** from

(Tajima et al. 2004)

- membership queries
- representative sample

\Rightarrow for **linear languages**



Linear grammar

A context-free grammar is a linear grammar if every rule is of the form

$$A \rightarrow aBc$$

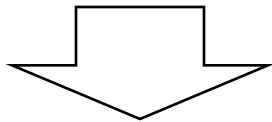
$$A \rightarrow aB$$

A, B : nonterminal

$$A \rightarrow a$$

$$A \rightarrow Bc$$

a, c : terminal



Any linear grammar can be written in **RL-linear** s.t. if every rule is of the form

$$A \rightarrow aB$$

$$A \rightarrow Bc$$

$$A \rightarrow a$$

and $\left\{ \begin{array}{l} A \rightarrow aB, \quad A \rightarrow aC \Rightarrow B = C \\ A \rightarrow Ba, \quad A \rightarrow Ca \Rightarrow B = C \end{array} \right.$

Strict-deterministic linear grammar

An RL-linear is a **Strict-det linear**

if, for any pair of rules $A \rightarrow u, A \rightarrow v$ ($|u|, |v| \geq 2$)

$u = aB, v = cD$ or $u = Ba, v = Dc$ for some a, B, c, D

\Rightarrow A has only left linear rules (or right linear rules)

Ex) $L = \{a^i b^i \cup a^i c^i\}$

$S \rightarrow aA,$

$A \rightarrow Bb, A \rightarrow Cc, A \rightarrow b, A \rightarrow c,$

$B \rightarrow aD, D \rightarrow Bb, D \rightarrow b,$

$C \rightarrow aE, E \rightarrow Cc, E \rightarrow c$

Deterministic linear grammar

A linear grammar is deterministic linear (DL) if every rule is of the form

$$A \rightarrow aBu \quad \text{or} \quad A \rightarrow \varepsilon$$

and

$$A \rightarrow aBu, \quad A \rightarrow aCv \quad \Rightarrow \quad B = C, u = v$$

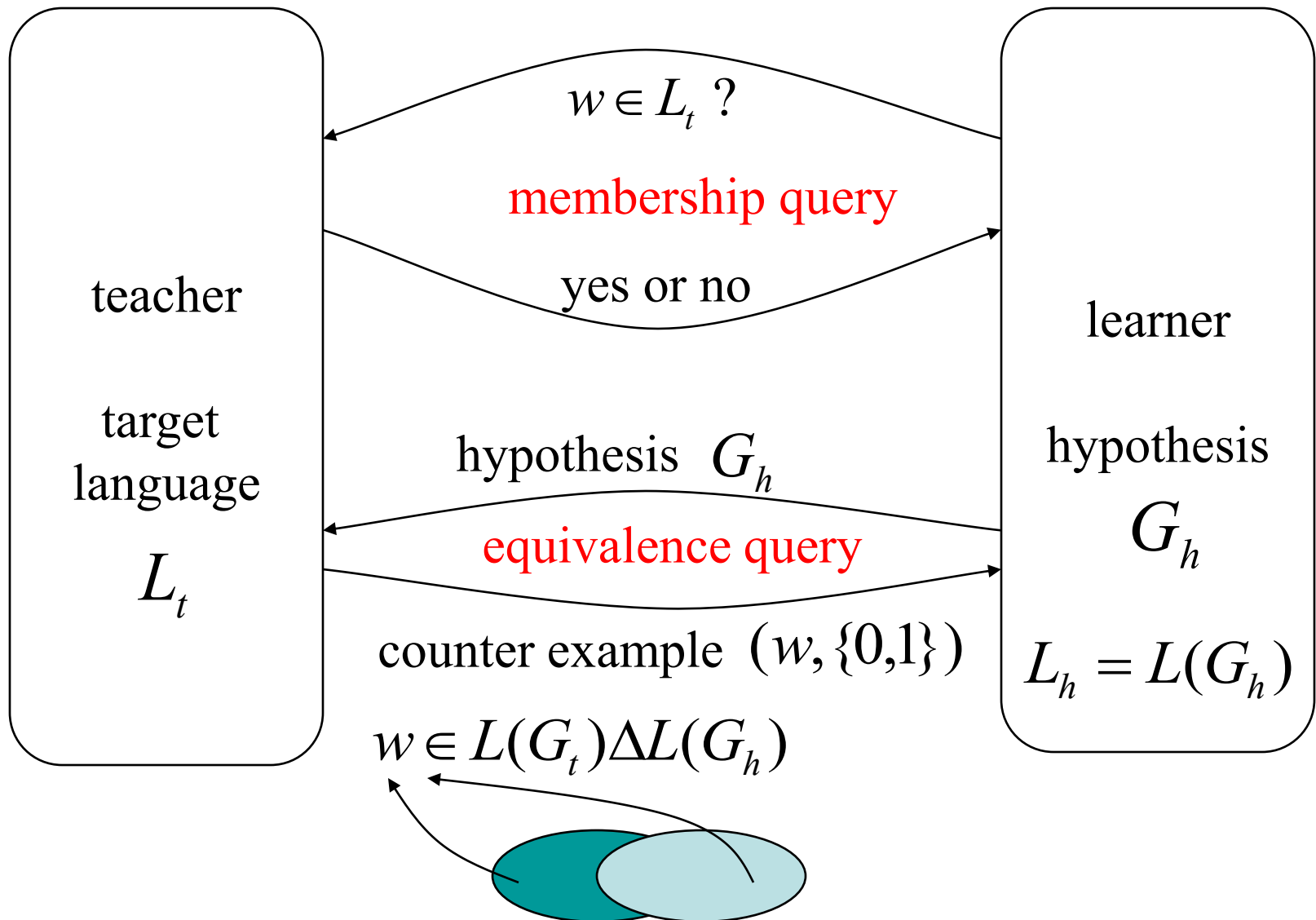
$(u, v \in \Sigma^*, A, B \in N, a \in \Sigma)$

Theorem (de la Higuera, Oncina 2002) :

DL : identifiable in the limit from polynomial time and data

Theorem : $DL \subset \text{strict-det}$

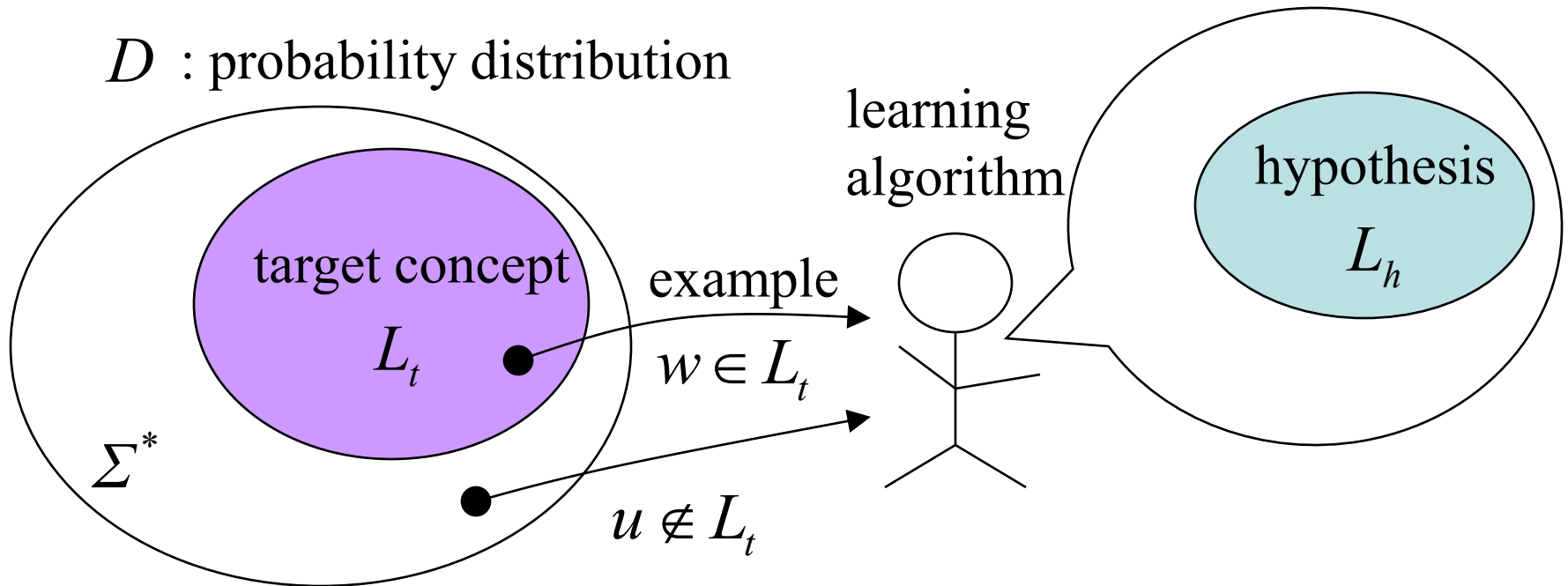
MAT learning (Angluin1987)



PAC learning (Valiant 1984)

PAC : Probabilistic Approximate Correct

D : probability distribution

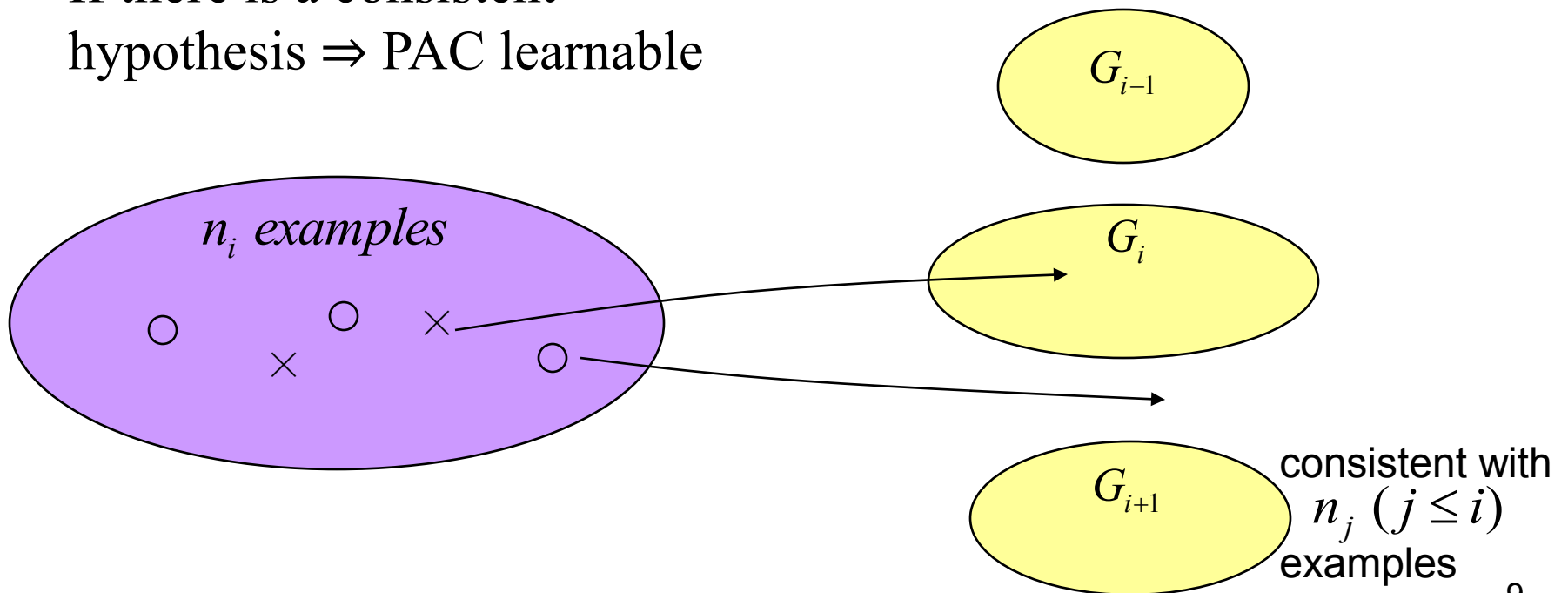


$\Pr(P(L_t \Delta L_h) \leq \varepsilon) \geq 1 - \delta \implies L_h \text{ is PAC}$

Equivalence query \Rightarrow PAC learning algorithm (Angluin[1987])

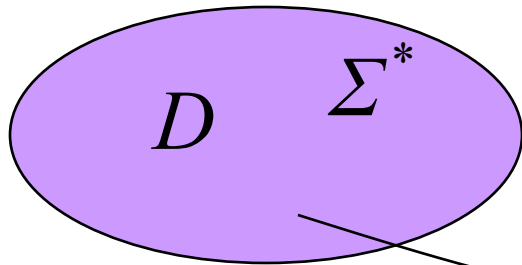
If a hypothesis is consistent with $n_i \geq \frac{1}{\epsilon} \left(\ln \left(\frac{1}{\delta} \right) + (\ln 2)(i+1) \right)$ then PAC examples

If there is a consistent hypothesis \Rightarrow PAC learnable



Probabilistic learning with queries

Example oracle



$\Pr(w)$

Learning algorithm

$(w, \{0,1\})$

hypothesis

G_h

Yes or No

Membership query

target language
 L_t

$w \in \Sigma^*$

$$\Pr(P(L_t \Delta L(G_h)) \leq \varepsilon) \geq 1 - \delta$$

Representative sample for a Strict-det

$G = (N, \Sigma, P, S)$: Strict-det

$Q \subseteq L(G)$: representative sample (RS) \Leftrightarrow

$\forall (A \rightarrow \beta) \in P, \exists w \in Q \text{ s.t.}$

$$S \xRightarrow{*} xA\gamma \xRightarrow{*} x\beta\gamma \xRightarrow{*} w$$

for some $x \in \Sigma^*, \gamma \in N^*$

All rules are used to generate Q

Example :

$$G = (N = \{S, A, B, C, D, E\}, \Sigma = \{a, b, c\}, P, S)$$

$$P = \{ \overset{\circlearrowleft}{\star} S \rightarrow aA, \$$

$$\star A \rightarrow Bb, \ \overset{\blacktriangle}{A} \rightarrow Cc, \ \overset{\bullet}{A} \rightarrow b, \ \overset{\circlearrowleft}{A} \rightarrow c, \$$

$$\star B \rightarrow aD, \ \star D \rightarrow Bb, \ \star D \rightarrow b, \$$

$$\overset{\blacktriangle}{C} \rightarrow aE, \ \overset{\blacktriangle}{E} \rightarrow Cc, \ \overset{\blacktriangle}{E} \rightarrow c$$

then

$$Q = \{ \overset{\bullet\bullet}{ab}, \ \overset{\circlearrowleft\circlearrowleft}{ac}, \ \overset{\star\star\star\star\star\star}{aaabbbb}, \ \overset{\blacktriangle\blacktriangle\blacktriangle\blacktriangle\blacktriangle\blacktriangle}{aaacccc} \}$$

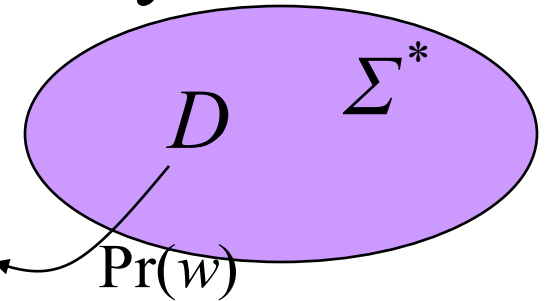
is a representative sample (RS)

Rule occurring probability

G_t : a target grammar

D : a probability distribution on Σ^*

for an example $(w, \{0,1\})$



ε : error parameter

δ : confidential parameter

$|P_t|$: the size of target grammar's rules

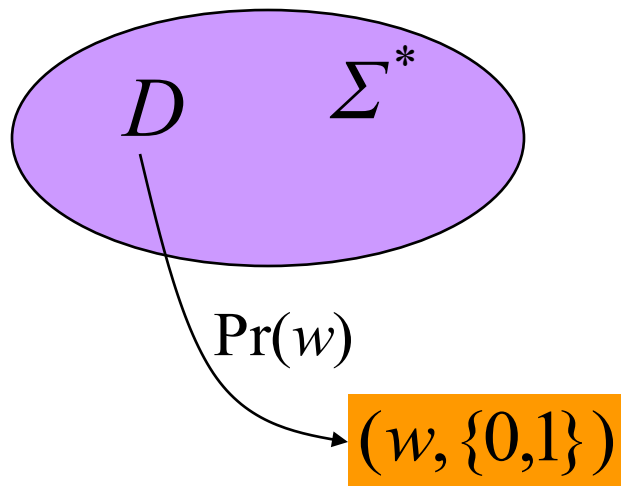
For every rule $A \rightarrow \beta$, define

$$Z(A \rightarrow \beta) = \{w \in \Sigma^* \mid S \xRightarrow[G_t]{*} \alpha_1 A \alpha_2 \Rightarrow \alpha_1 \beta \alpha_2 \xRightarrow[G_t]{*} w,$$

for some $\alpha_1, \alpha_2 \in (N \cup \Sigma)^*\}$

$$\Pr(A \rightarrow \beta) = \sum_{w \in Z(A \rightarrow \beta)} \Pr(w)$$

is a rule occurring probability s.t. $A \rightarrow \beta$ appears in the derivation of an example



$$\Pr(A \rightarrow \beta)$$

is an probability that

- $w \in L(G_t)$
- and $A \rightarrow \beta$

is used in the derivation

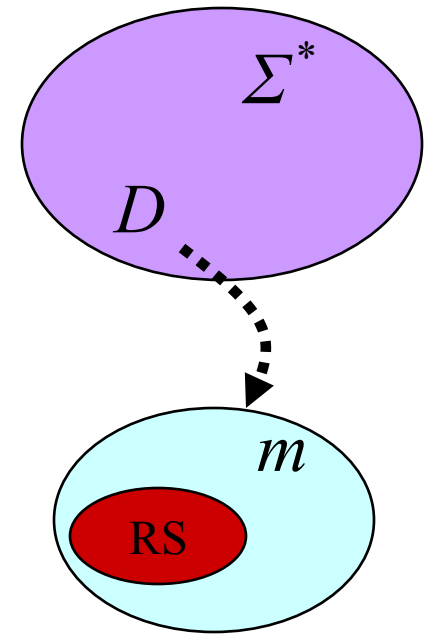
$$S \xRightarrow[G_t]{*} w$$

Let $d = \min \{ \Pr(A \rightarrow \beta) \mid A \rightarrow \beta \in P_t \}$

Suppose

$$m > \frac{1}{d} \log \left(\frac{|P_t|}{\delta} \right)$$

The set of m -examples contains
a set of **RS** with the probability $1 - \delta$



Proof:

“Any rule doesn’t appear in derivations of m -examples”
occurs

$$|P_t|(1-d)^m \leq |P_t|e^{-dm} < \delta$$

We can conclude that

1. Equivalence query can be replaced by

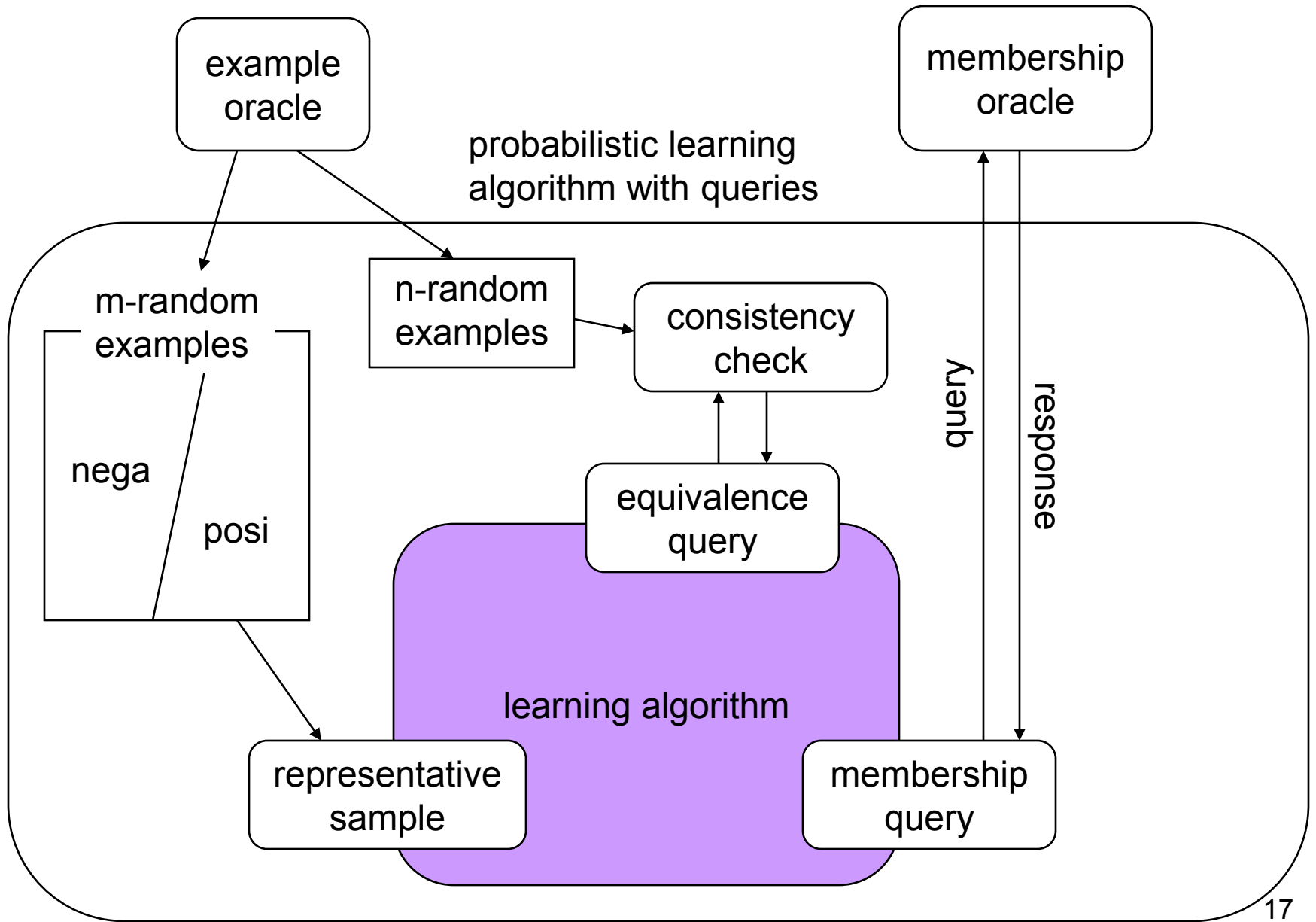
$$n_i \geq \frac{1}{\varepsilon} \left(\ln \left(\frac{1}{\delta} \right) + (\ln 2)(i + 1) \right)$$

random examples

2. Representative sample can be replaced by

$$m > \frac{1}{d} \log \left(\frac{|P_t|}{\delta} \right)$$

random examples



Learning algorithm via queries and RS

$$M_h = \{(u, v, w) \mid uvw \in RS\}$$

$$T = \Sigma$$

while (finish == 0) begin

 make nonterminals N_h from T, M_h

 make rules P_h and hypothesis G_h

 if (equivalence query for G_h responds “yes”)

 output G_h , finish = 1

 else

 update T by the counterexample w

end

Making nonterminals

$$(u, v, w) \stackrel{T}{=} (x, y, z) \Leftrightarrow MEM(uvw) = MEM(xyz)$$

$$M_h = \{(u, v, w) \mid uvw \in RS\}$$

then

$$N_h = (M_h / \stackrel{T}{=})$$

$A(u, v, w, \stackrel{T}{=})$: a nonterminal
= an equivalence class contains (u, v, w)

Making rules

Make all rules as follows except for not consistent with query results

$$P_{CFG} = \{ A(u, avb, w, \overset{T}{=}) \rightarrow aA(u, vb, w, \overset{T}{=}), \\ A(u, avb, w, \overset{T}{=}) \rightarrow A(u, av, w, \overset{T}{=})b, \\ A(u, a, w, \overset{T}{=}) \rightarrow a \}$$

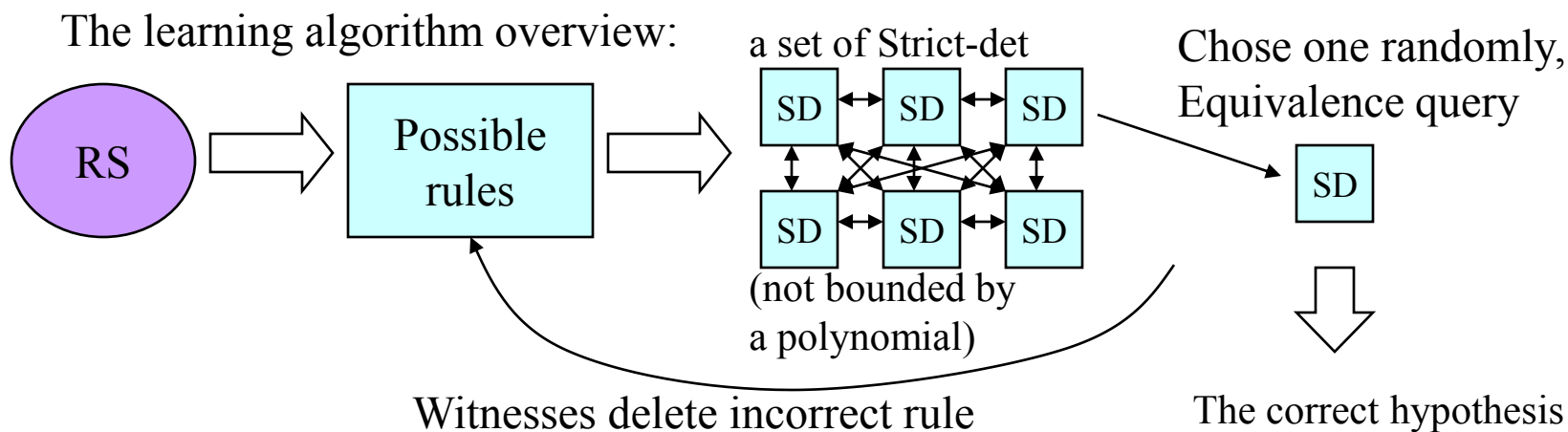
Select a hypothesis randomly $P_h \subseteq P_{CFG}$

$$G_h = (N_h, \Sigma, P_h, A(\varepsilon, w, \varepsilon, \overset{T}{=}))$$

Exact learning of strict-det

- Strict-det is polynomial time exact learnable via
 - membership queries, and
 - a **representative samples (RS)**

c.f. [Angluin(1980)] for regular sets



Conclusions

- Strict-det linear language can be probabilistic learnable with queries in polynomial time

Future works

- Identification from polynomial time and data (teachability)
- RS \rightarrow Correction queries

Theorem

Strict-det linear languages are
polynomial time probabilistic learnable with
membership queries

Simple Deterministic Languages

- Context-free grammar (CFG) $G = (N, \Sigma, P, S)$ in 2-standard *Greibach normal form* is Simple Deterministic Grammar (SDG) iff
$$A \rightarrow a\beta \quad (\beta \in N^*, |\beta| \leq 2)$$
is unique for every $A \in N$ and $a \in \Sigma$
- Simple Deterministic Language (SDL) is the generated language by a SDG

Representative sample for an SDG

$G = (N, \Sigma, P, S) : \text{SDG}$

$Q \subseteq L(G) : \text{representative sample (RS)} \iff$

$\forall (A \rightarrow a\beta) \in P, \exists w \in Q \text{ s.t.}$

$S \xRightarrow{*} xA\gamma \xRightarrow{*} xa\beta\gamma \xRightarrow{*} w$

for some $x \in \Sigma^*, \gamma \in N^*$

All rules are used to generate Q

Example :

$$G = (N = \{S, A, B, C\}, \Sigma = \{a, b, c\}, P, S)$$

$$P = \{ \overset{\bullet}{\star} S \rightarrow aA, \blacktriangle S \rightarrow cC,$$

$$\star A \rightarrow aAB, \overset{\bullet}{\star} A \rightarrow b,$$

$$\begin{matrix} \star \\ \blacktriangle \end{matrix} B \rightarrow b, \blacktriangle C \rightarrow cCB, \blacktriangle C \rightarrow b \quad \}$$

then

$$Q = \{ \overset{\bullet}{\bullet} ab, \overset{\star}{\star}{\star}{\star}{\star} aabb, \overset{\blacktriangle}{\blacktriangle}{\blacktriangle}{\blacktriangle} ccbb \}$$

is a representative sample (RS)

PAC learning

(Valiant1984)

Target language : L_t

Hypothesis language : $L(G_h)$

Probability distribution : P on Σ^*

A PAC learning algorithm outputs G_h such that

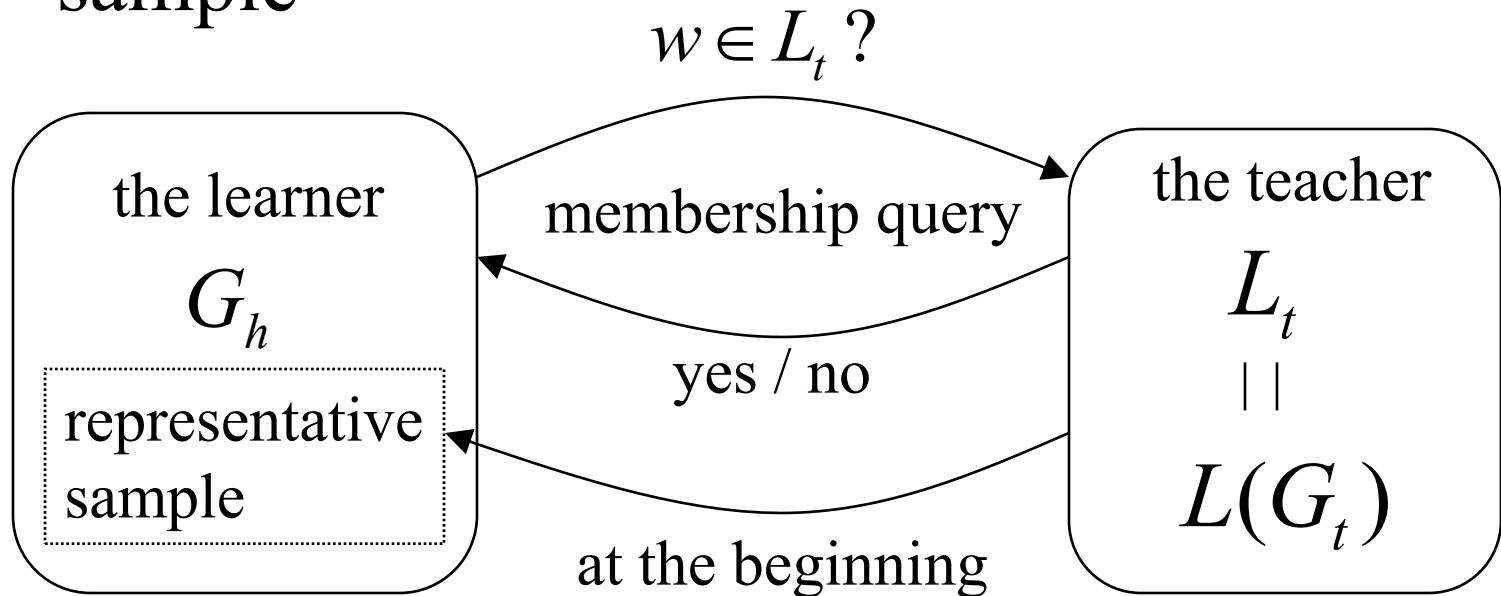
$$\Pr(P(L_t \Delta L(G_h)) \leq \varepsilon) \geq 1 - \delta$$

where
$$P(L_t \Delta L(G_h)) = \sum_{w \in L_t \Delta L(G_h)} P(w)$$

Query learning of SDLs

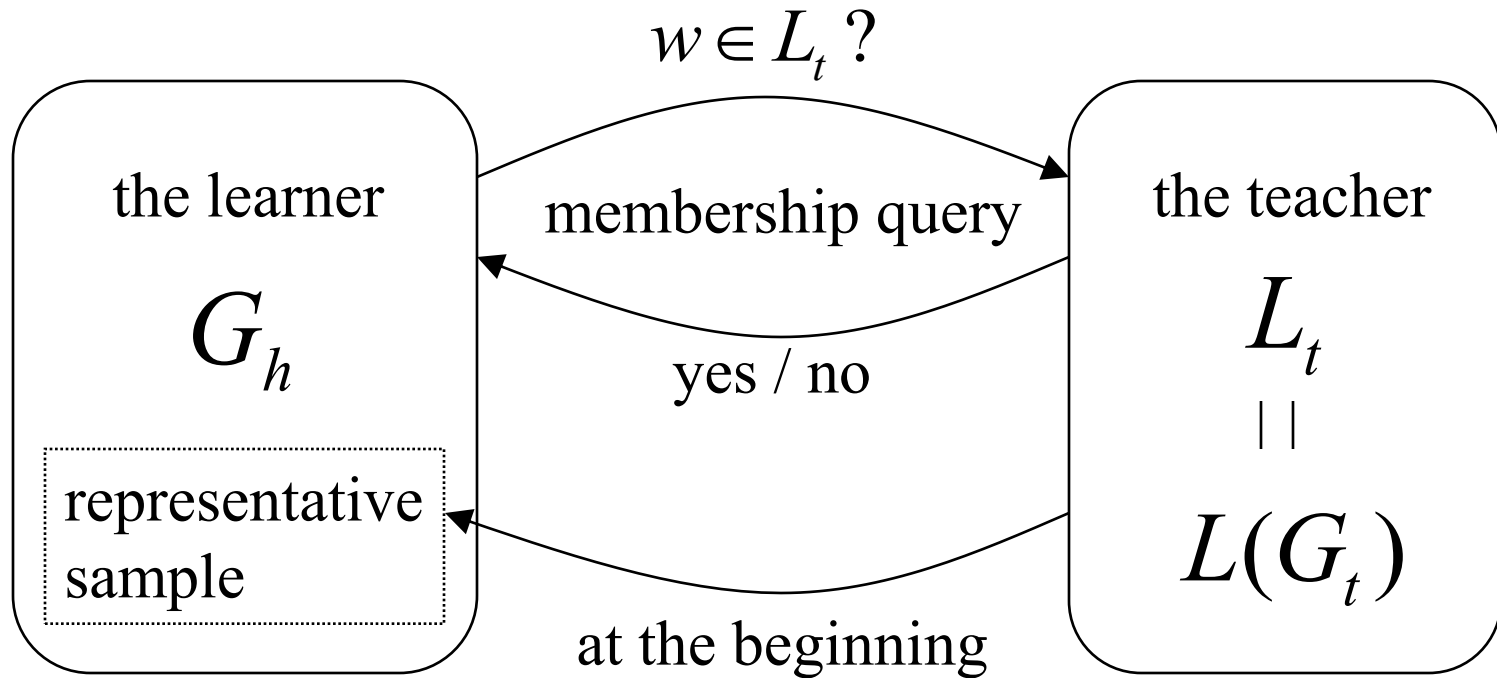
(Tajima2000)

- SDLs are polynomial time learnable via membership queries and a representative sample



representative sample : a special finite subset of L_t

Learning model



representative sample : a special finite subset of L_t