

DogOnt - Ontology Modeling for Intelligent Domotic Environments

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Outline

- 1 Introduction
- 2 Objectives
- 3 Intelligent Domotic Environments
- 4 DogOnt
- 5 DogOnt - applications
- 6 Conclusions



DOMus infoOrmaTICS: Information technology in the home (domus is Latin for home).

- Remote lighting and appliance control have been used for years (see X10),
- Nowadays domotics is another term for the digital home, including: the networks and devices that add comfort and convenience as well as security;
- Controlling heating, air conditioning, food preparation, TVs, stereos, lights, appliances, entrance gates and security system all fall under the domotics umbrella.



Domotic Systems - drawbacks (1/2)

Many vendors on the market, each with separate, not compatible, solutions

- Different technologies (bus, powerline, wireless)
- Different protocols (KNX, MyOpen, X10, LonWorks)
- Different device features
- Different sophistication of device firmware (from simple relay to full software-based operation)



Domotic Systems - drawbacks (2/2)

Nowadays Domotic Systems are rooted on simple electric automation

- Only simple automation is supported
 - Simple scenarios
 - Fixed, programmed behaviors
 - Simple comfort, security and energy saving policies
- No support for more complex interactions
 - Adaptation to user preferences
 - Context detection
 - Structural verification
 - Static and dynamic reasoning on the house state



Starting considerations

- The sparseness of domotics solutions, the differences in languages, communication means and protocols is very similar to the “old web”
- Semantic Web technologies can help solving
 - Interoperation issues
 - Integration of different technologies
- and can support home intelligence through
 - Reasoning
 - Context Modeling
 - ...



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Objectives

Evolving Domotic Systems into Intelligent Domotic Environments (IDEs) supporting Interoperation, Integration and Intelligence.

- By
 - Adding a single (cheap) device for
 - interoperating different domotic plants
 - implementing complex behaviors
 - **Modeling environments in a semantic-rich, technology independent way**
 - Providing suitable querying and reasoning mechanism over the environment model

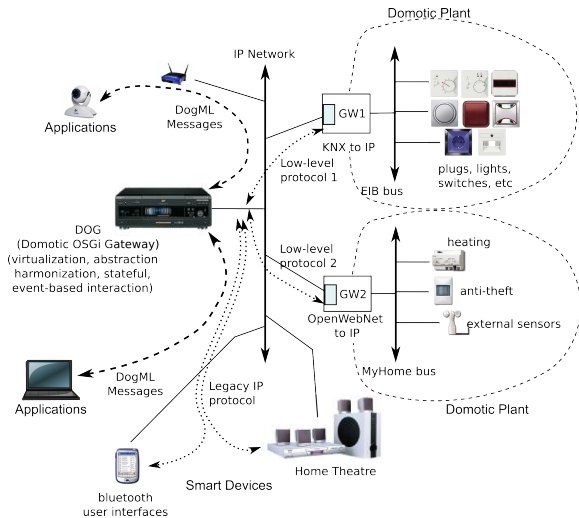


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Anatomy of an IDE



- DOG is a Domotic House Gateway [ICTAI2008] designed for transforming commercial Domotic Systems into Intelligent Domotic Environments.
- It provides
 - Interoperation between different domotic networks through proper drivers;
 - technology independent, ontology-based, house and device modeling
 - advanced, inter-network, rule-based scenario definition and operation
 - reasoning on the house model
- **DogOnt** is the ontology model lying at the bases of DOG



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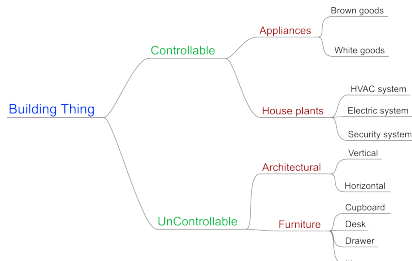
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Environment Modeling (1/2)

BuildingThing

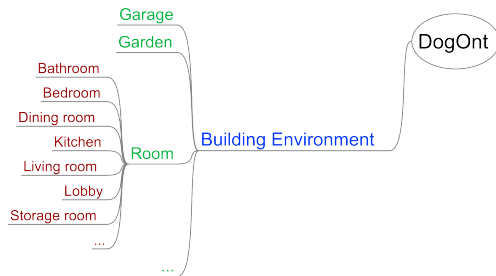
- Models all the elements of a Building Environment divided into
 - Controllable
 - UnControllable
- The UnControllable sub-tree allows to model
 - Furniture elements
 - Walls, floors, ceilings and other architectural elements (Architectural sub-tree)



Environment Modeling (2/2)

BuildingEnvironment

- Models rooms and architectural spaces composing a house
 - Rooms
 - External spaces such as garages, garden, etc.



Device Modeling

- Devices are modeled independently from specific technologies
- 3 Modeling axes:
 - **Typology** - describes the type of device, separating appliances and devices belonging to house plants
 - **Functionality** - describes the tasks that a device can accomplish, by defining the available commands
 - **State** - describes the conditions in which a device can be (e.g. a Lamp can be ON or OFF)
- Technology specific aspects are modeled through separate classes
 - **NetworkComponent** - the root concept for modeling every network specific information, its sub-classes reflect the different networks supported by DOG.



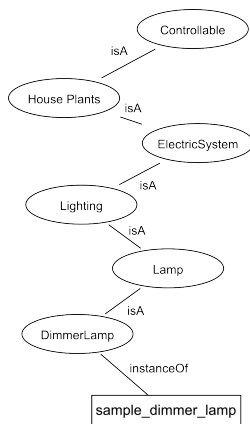
Controllable devices taxonomy

■ Appliances

- Brown Goods (TV, HiFi,...)
- White Goods (Fridge, Dishwasher,...)

■ HousePlants

- Electric
- HVAC (Heating Ventilation & Air Conditioning)
- Security



Functionalities (1/3)

- Control Functionalities
 - Model the ability of a device to be controlled
 - Define the possible commands and their range (needed for continuous functionalities)
 - Almost every Controllable has a control functionality
- Notification Functionalities
 - Model the ability of a device to issue a notification about state/configuration changes
 - Define the possible notifications
 - Typical of Sensors and Buttons/Switches
- Query Functionalities
 - Model the ability of a device to be queried about its state/configuration
 - It's defined **for all** Controllables



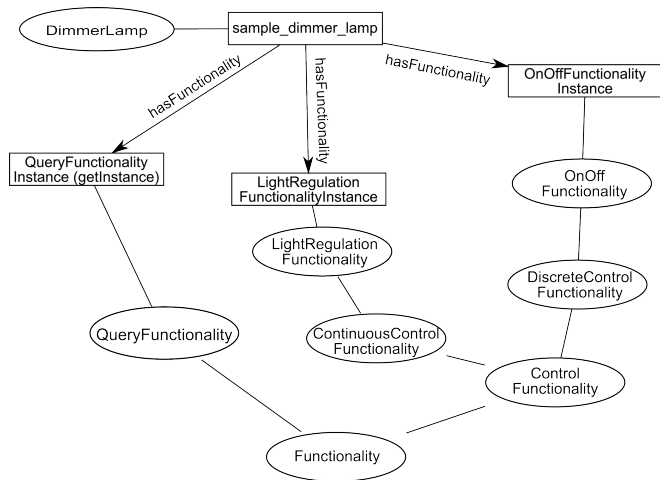
Functionalities (2/3)

Every Functionality class is subdivided into

- Continuous Functionalities
 - Model the ability to change device properties in a continuous manner (e.g. dimming the light emitted by a lamp)
- Discrete Functionalities
 - Model the ability to abruptly change device properties (e.g. switching a lamp On)



Functionalities (3/3)



States (1/2)

States are classified according to the kind of values they can assume

- Continuous states

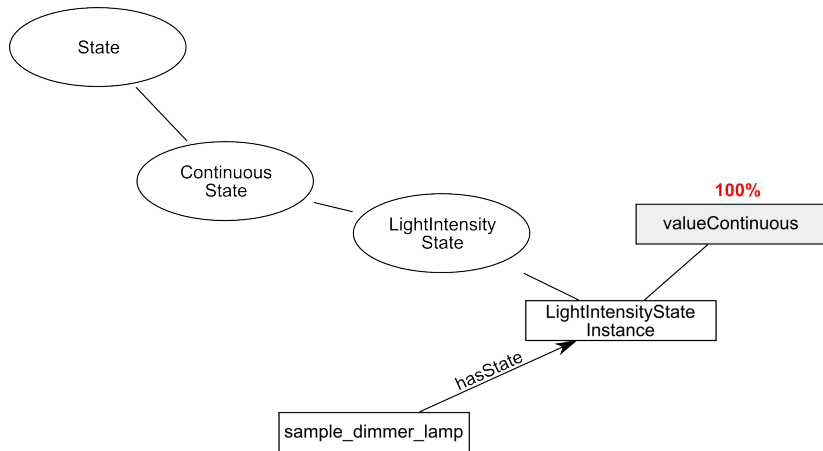
- Model continuously changing qualities (e.g. the current dimming level of a lamp)
- The current state value is stored in the *continuousValue* property.

- Discrete states

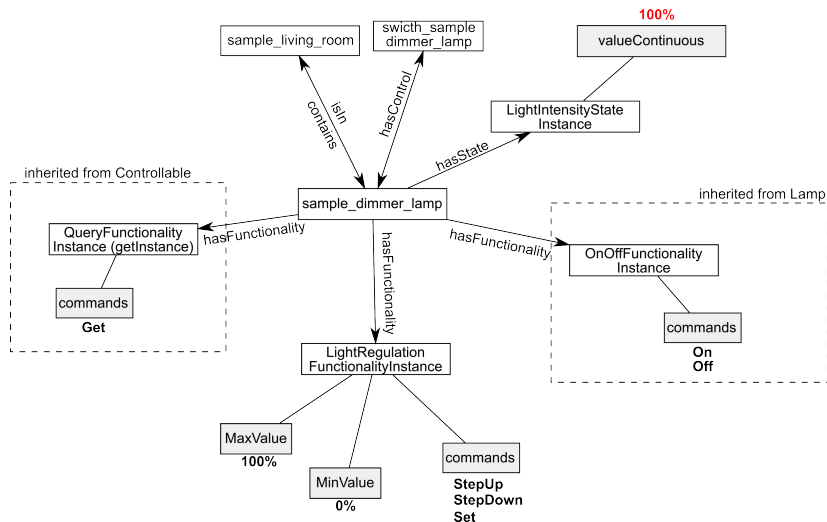
- Model discretely changing qualities (e.g. the lamp being On or Off)
- The current state value is stored in the *discreteValue* property.
- Possible states are listed in the *possibleStates* property.



States (2/2)



DimmerLamp modeling example



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DogOnt applications in IDEs (1/2)

DogOnt supports several critical features of IDEs

- Device Modeling

- Allows to define a **central point of configuration** for real devices
- Abstracts from network-specific issues, exposing systems and objects as a **uniform set of devices, states and functionalities**
- Enables **syntactic and semantic check of commands** received from external applications/devices



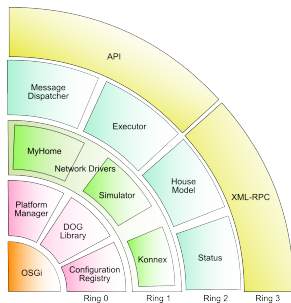
DogOnt applications in IDEs (2/2)

- Device Modeling (continued...)
 - Transitive closure and Classification Reasoning allow to **decouple evolution of the model and domotic systems developments**
 - Supports the definition of top-down **inter-plant** scenarios (e.g. scenarios activated by external applications which involve devices in more than one plant)
 - Provides the basis for interoperation between plants (e.g. allowing a BTicino button to control a KNX light)
 - Frequent issue in Hospitals, Universities, Factories
 - **On-going work on automatic generation of interoperation rules from DogOnt (DogOnt v2.0)**



Example application - DOG

<http://domoticdog.sourceforge.net>



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Conclusions

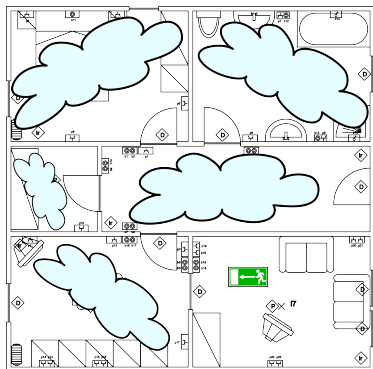
- We defined DogOnt: an ontology for describing domotic environments with a particular focus on objects, states and functionalities
- DogOnt is currently used by the DOG home gateway, allowing to control several, different, domotic plants, at the same time
- Standard reasoning methods allow to decouple the evolution of DogOnt and of the modeled environments
- DogOnt can be used as a basis on which building more complex/intelligent behaviors for commercial domotic systems



On-going work

We are currently working on:

- Structural verification of domotic environments through the evaluation of SWRL constraints on DogOnt model instances
- Dynamic detection/prediction of safety critical situations (smoke propagation, safe exit detection in case of fire) using rule-based reasoning and DogOnt



Questions?

Thank you!
Any Question?



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