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ICML, Montréal, Québec, June 17th, 2009

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#### Structured prediction: models interdependence among outputs

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- Exact inference only tractable w/ strong locality assumptions
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- This paper: LP-relaxed inference and max-margin learning
  - Guarantees for algorithmic separability
  - New interpretation: balancing accuracy and computational cost
  - Learning bounds via polyhedral characterizations
- Application: dependency parsing with rich features

• Let x be a sentence in  $\mathcal{X} \triangleq \Sigma^*$ 



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 This is a structured classification problem involving non-local interactions among output variables





2 Learning with LP-Relaxed Inference

3 Experiments





Structured Classification and LP

### Outline



2 Learning with LP-Relaxed Inference

3 Experiments





Structured Classification and LP

### Notation

 $\blacksquare \text{ Input set } \mathcal{X}$ 



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Structured Classification and LP

### Notation

- $\blacksquare \ \text{Input set} \ \mathcal{X}$
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Structured Classification and LP

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- Input set X
- Output set  $\mathcal{Y}$
- Labeled dataset  $\mathcal{L} \triangleq \{(x_1, y_1), \dots, (x_m, y_m)\} \subseteq \mathcal{X} \times \mathcal{Y}$

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• drawn i.i.d. from P(X, Y)

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• Loss function  $\ell : \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}_+$ 

Structured Classification and LP

### Notation

- $\blacksquare \text{ Input set } \mathcal{X}$
- Output set *Y*
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- Here: linear classifiers

$$h_{\mathbf{w}}(x) = \arg \max_{y \in \mathcal{Y}} \mathbf{w}^{\top} \mathbf{f}(x, y)$$

• Hypothesis space  $\mathcal{H} \triangleq \{h_{\mathbf{w}} \mid \mathbf{w} \in \mathcal{W}\}$ ,  $\mathcal{W} \subseteq \mathbb{R}^d$  convex

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- Assumption: features decompose over the parts

$$\mathbf{f}(x,y) \triangleq \sum_{r \in y} \mathbf{f}_r(x) = \sum_{r \in \mathcal{R}} z_r \mathbf{f}_r(x) = \mathbf{F}(x) \mathbf{z},$$

•  $\mathbf{F}(x) \triangleq (\mathbf{f}_r(x))_{r \in \mathcal{R}}$  is a feature matrix (d-by- $|\mathcal{R}|)$ 

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Structured Classification and LP

#### From the Output Set to a Polytope



Structured Classification and LP

#### From the Output Set to a Polytope



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Structured Classification and LP

### From the Output Set to a Polytope



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# Inference

Minkowski-Weyl theorem: there is a representation

$$\mathcal{Z} = \{ \mathsf{z} \in \mathbb{R}^n \mid \mathsf{A}\mathsf{z} \le \mathsf{b} \}$$

where **A** is a *p*-by-*n* matrix and **b** is a vector in  $\mathbb{R}^p$   $(p, n \in \mathbb{N})$ 

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Are we done? No: Finding **A** and **b** is problem dependent.

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Are we done? No: Finding A and b is problem dependent.
In general p = O(exp(n)) (exponentially many constraints)
Structured Classification and LP

#### LP-Relaxed Inference and Outer Polytope

• Often: a concise representation of an outer polytope  $\overline{Z} \supseteq Z$ such that  $\overline{Z} \cap \mathbb{Z}^n = V(Z)$ 

$$\max_{\mathbf{z}\in\mathcal{Z}}\mathbf{s}^{\top}\mathbf{z} = \max_{\mathbf{z}\in\bar{\mathcal{Z}},\mathbf{z}\in\mathbb{Z}^n}\mathbf{s}^{\top}\mathbf{z}$$



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Structured Classification and LP

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Structured Classification and LP

## Learning

What about learning?



Structured Classification and LP

#### Learning

- What about learning?
- Assumption: The loss function also decomposes over the parts

Structured Classification and LP

### Learning

- What about learning?
- Assumption: The loss function also decomposes over the parts
- Example: Hamming loss

$$\begin{split} \ell(y';y) &\triangleq \sum_{r \in \mathcal{R}} \left( \mathbb{I}(r \in y') \mathbb{I}(r \notin y) + \mathbb{I}(r \notin y') \mathbb{I}(r \in y) \right) \\ &= \|\mathbf{z}' - \mathbf{z}\|_1 \\ &= \mathbf{p}^\top \mathbf{z}' + q \quad \text{where } \mathbf{p} \triangleq \mathbf{1} - 2\mathbf{z} \text{ and } q \triangleq \mathbf{1}^\top \mathbf{z} \end{split}$$

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Hamming loss is an affine function of z

Structured Classification and LP

#### Learning

Structured SVM:

$$\min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{t=1}^m r_t(\mathbf{w})$$

where the slack  $r_t(\mathbf{w})$  is the solution of the loss-augmented inference (LAI) problem

$$r_t(\mathbf{w}) = \max_{y'_t \in \mathcal{Y}} \mathbf{w}^\top \underbrace{\mathbf{f}(x_t, y'_t)}_{\mathbf{F}_t \mathbf{z}'_t} - \mathbf{w}^\top \underbrace{\mathbf{f}(x_t, y_t)}_{\mathbf{F}_t \mathbf{z}_t} + \underbrace{\ell(y'_t; y_t)}_{\mathbf{p}_t \mathbf{z}'_t + q_t}$$

Structured Classification and LP

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$$= \left( \max_{\mathbf{z}'_t \in \mathcal{Z}} (\mathbf{F}_t^\top \mathbf{w} + \mathbf{p}_t)^\top \mathbf{z}'_t \right) - (\mathbf{F}_t^\top \mathbf{w})^\top \mathbf{z}_t + q_t$$

Also an LP.

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Learning with LP-Relaxed Inference

## Outline



#### 2 Learning with LP-Relaxed Inference

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3 Experiments



## Exact and Relaxed Structured SVMs

Structured SVM (exact):

$$\min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{t=1}^m r_t(\mathbf{w})$$

where the slack  $r_t(\mathbf{w})$  is the solution of the exact LAI problem

$$r_t(\mathbf{w}) = \left(\max_{\mathbf{z}'_t \in \mathcal{Z}} (\mathbf{F}_t^\top \mathbf{w} + \mathbf{p}_t)^\top \mathbf{z}'_t \right) - (\mathbf{F}_t^\top \mathbf{w})^\top \mathbf{z}_t + q_t$$

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Relax.

### Exact and Relaxed Structured SVMs

Structured SVM (relaxed):

$$\min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{t=1}^{m} \overline{r}_t(\mathbf{w})$$

where the slack  $\bar{r}_t(\mathbf{w})$  is the solution of the relaxed LAI problem

$$\bar{\mathbf{r}}_t(\mathbf{w}) = \left( \max_{\mathbf{z}'_t \in \tilde{\mathbf{z}}} (\mathbf{F}_t^\top \mathbf{w} + \mathbf{p}_t)^\top \mathbf{z}'_t \right) - (\mathbf{F}_t^\top \mathbf{w})^\top \mathbf{z}_t + q_t$$

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$$\begin{aligned} \overline{r}_t(\mathbf{w}) &= \left( \max_{\mathbf{z}'_t \in \overline{\mathcal{Z}}} (\mathbf{F}_t^\top \mathbf{w} + \mathbf{p}_t)^\top \mathbf{z}'_t \right) - (\mathbf{F}_t^\top \mathbf{w})^\top \mathbf{z}_t + q_t \\ &\geq r_t(\mathbf{w}) \quad \text{upper bounds the exact slack} \end{aligned}$$

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## Algorithmic Separability

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• Remark:  $\mathcal{L}$  algorithmically separable  $\implies \mathcal{L}$  separable

## Algorithmic Separability

- LP relaxed inference augments the output space: makes up artificial negative examples
- Equivalently: an approximate algorithm A<sub>w</sub> which sometimes returns fractional solutions
- Some definitions [Kulesza and Pereira, 2007]
  - $\mathcal{L}$  is separable if  $\exists w$  s.t.  $h_w$  classifies all data correctly
  - $\mathcal{L}$  is alg. separable if  $\exists w \text{ s.t. } \mathcal{A}_w$  classifies all data correctly
- Remark:  $\mathcal{L}$  algorithmically separable  $\implies \mathcal{L}$  separable
- Margin of separation: Minimal  $\gamma$  s.t.  $\forall (x_t, y_t) \in \mathcal{L}, y'_t \in \mathcal{Y}(x_t)$ :

$$\mathbf{w}^{\top}\mathbf{f}(x_t, y_t) \geq \mathbf{w}^{\top}\mathbf{f}(x_t, y_t') + \gamma \ell(y_t, y_t') \text{ with } \|\mathbf{w}\| = 1.$$

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# A Sufficient Condition for Algorithmic Separability

Zooming around a fractional vertex of the outer polytope:



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# A Sufficient Condition for Algorithmic Separability

Let L be the radius of the largest loss ball centered at a fractional vertex which does not contain any integer vertex



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- Assume binary-valued features
- Let  $N_f$  be the maximum number of active features per part

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#### Proposition

If  $\mathcal{L}$  is separable with  $\gamma \geq L'\sqrt{N_f}$  then it is algorithmically separable.

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#### Proposition

If  $\mathcal{L}$  is separable with  $\gamma \geq L'\sqrt{N_f}$  then it is algorithmically separable.

- In the paper: bounds for the nonseparable case
- Also: bounds for  $\epsilon$ -approximate algorithms

Learning with LP-Relaxed Inference

## Balancing Accuracy and Runtime

**Typical goal**: minimize expected loss  $\mathbb{E}\ell(h(X), Y)$ 



Learning with LP-Relaxed Inference

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- **Typical goal:** minimize expected loss  $\mathbb{E}\ell(h(X), Y)$
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• Let  $\ell_c(h, x)$  be the cost of computing h(x)

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- Let  $\ell_c(h, x)$  be the cost of computing h(x)
- Let  $\mathbb{E}\ell_c(h, X)$  be the average computational cost of h

## Balancing Accuracy and Runtime

- **Typical goal:** minimize expected loss  $\mathbb{E}\ell(h(X), Y)$
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- Let  $\ell_c(h, x)$  be the cost of computing h(x)
- Let  $\mathbb{E}\ell_c(h, X)$  be the average computational cost of h
- Alternative goal: minimize  $\underbrace{\mathbb{E}\ell(h(X), Y)}_{\ell(h(X), Y)} + \eta \cdot \underbrace{\mathbb{E}\ell_c(h, X)}_{\ell(h(X), Y)}$

expected loss of h average cost of h

Learning with LP-Relaxed Inference

#### Balancing Accuracy and Runtime

Recall that exact inference in our setting is cast as an ILP:

$$\max_{\mathbf{z}\in\bar{\mathcal{Z}}\cap\mathbb{Z}^n}\mathbf{s}^\top\mathbf{z} \quad \text{with } \mathbf{s}=\mathbf{F}(x)^\top\mathbf{w},$$



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Learning with LP-Relaxed Inference

## Nice Score Vectors and Low-Cost Hypotheses

A "nice" score vector s is one which hits an integer vertex



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# Nice Score Vectors and Low-Cost Hypotheses

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- At test time: s ~ P(F(X)<sup>⊤</sup>w) is a r.v. that depends on X (filtered by the parameters w)



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■ Idea: Approximate computational cost by relaxation gap:  $\mathbb{E}\ell_c(h_{\mathbf{w}}, X) \approx \mathbb{E}\ell(h_{\mathbf{w}}(X), \overline{h}_{\mathbf{w}}(X))$ 

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- Idea: Approximate computational cost by relaxation gap:  $\mathbb{E}\ell_c(h_{\mathbf{w}}, X) \approx \mathbb{E}\ell(h_{\mathbf{w}}(X), \bar{h}_{\mathbf{w}}(X))$ 
  - Most ILP solvers (branch-and-bound, Gomory's cuts) converge faster as this gap is smaller

Learning with LP-Relaxed Inference

## Balancing Accuracy and Runtime

■ Add a empirical relaxation gap term to our learning objective:  $\frac{1}{m} \sum_{t=1}^{m} (\bar{r}_t(\mathbf{w}) - r_t(\mathbf{w}))$ 

Learning with LP-Relaxed Inference

## Balancing Accuracy and Runtime

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- The learning problem becomes

$$\min_{\mathbf{w}} \frac{\lambda}{2} \|\mathbf{w}\|^2 + \underbrace{\frac{1-\eta}{m} \sum_{t=1}^m r_t(\mathbf{w})}_{\text{Exact LAI}} + \underbrace{\frac{\eta}{m} \sum_{t=1}^m \bar{r}_t(\mathbf{w})}_{\text{Relaxed LAI}}.$$

Learning with LP-Relaxed Inference

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In the paper: a stochastic adaptation of the online subgradient algorithm [Ratliff et al., 2006]

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- In the paper: a stochastic adaptation of the online subgradient algorithm [Ratliff et al., 2006]
- A PAC bound with respect to the best exact learner
  - It measures the impact of the approximation in learning
  - Previous bounds were in terms of the approximate learner [Kulesza and Pereira, 2007]

- Experiments

## Outline



2 Learning with LP-Relaxed Inference

3 Experiments





## Experiments

Dependency parsing for seven languages

Danish, Dutch, Portuguese, Slovene, Swedish, Turkish, English



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## Experiments

Dependency parsing for seven languages

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Exact inference is efficient with a arc-factored model
 Find a maximal spanning tree [McDonald et al., 2005]

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 Find a maximal spanning tree [McDonald et al., 2005]
 Beyond that: NP-hard [McDonald and Satta, 2007]

## Experiments

Dependency parsing for seven languages

Danish, Dutch, Portuguese, Slovene, Swedish, Turkish, English



Exact inference is efficient with a arc-factored model

Find a maximal spanning tree [McDonald et al., 2005]

- Beyond that: NP-hard [McDonald and Satta, 2007]
- Our model: a ILP formulation with non-arc-factored features

- Models grandparents/siblings interactions
- Models valency and nonprojective arcs
- Only  $O(n^3)$  variables and constraints
- More details: [Martins et al., 2009]



**Experiment** #1: Training with LP-relaxed LAI ( $\eta = 1$ )





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- Two different decoders at test time:
  - Exact decoder (solve an ILP)
  - Approximate decoder (solve the relaxed LP; if the solution is fractional, round it in polynomial time by finding a maximal spanning tree on the reweighted graph)



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- Two different decoders at test time:
  - Exact decoder (solve an ILP)
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- Strong baselines:
  - [MP06] approximate second-order parser
    [McDonald and Pereira, 2006]
  - [MDSX08] stacked parser [Martins et al., 2008]

Experiments

## Experiments

- Our models:
  - Arc-factored



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- Experiments

### Experiments

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  - Full model (with exact decoding) much better



- Experiments

## Experiments

- Our models:
  - Arc-factored
  - Full model (with exact decoding) much better
  - Approximate decoding did not considerably affect accuracy



## Experiments

Where are the baselines?



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## Experiments

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## Experiments

**Experiment** #2: does  $\eta$  really penalize computational cost?

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Slovene dataset (with a reduced set of features)

## Experiments

Experiment #2: does η really penalize computational cost?
 Slovene dataset (with a reduced set of features)



 As η increases, the model learns to avoid fractional solutions

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# Experiments

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Experiment #2: does η really penalize computational cost?
 Slovene dataset (with a reduced set of features)



- As η increases, the model learns to avoid fractional solutions
- Runtime does correlate with the relaxation gap
- Yet the approximate decoder is significantly faster
- Our full model: Same order of magnitude as the baselines (≈ 0.632 sec.)

- Conclusion

# Outline



2 Learning with LP-Relaxed Inference

3 Experiments





- Conclusion

# Conclusions and Future Work

 We studied the impact of LP relaxed inference in max-margin learning

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### Conclusions and Future Work

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# Conclusions and Future Work

- We studied the impact of LP relaxed inference in max-margin learning
- We established sufficient conditions for algorithmic separability
- As a by-product: a new learning algorithm that penalizes computational cost
- We demonstrated the effectiveness of these techniques in dependency parsing with non-arc-factored features
- Future work: polyhedral characterizations that guarantee tighter bounds

# Conclusions and Future Work

- We studied the impact of LP relaxed inference in max-margin learning
- We established sufficient conditions for algorithmic separability
- As a by-product: a new learning algorithm that penalizes computational cost
- We demonstrated the effectiveness of these techniques in dependency parsing with non-arc-factored features
- Future work: polyhedral characterizations that guarantee tighter bounds
- Conditions for vanishing relaxation gap in online learning

# Conclusions and Future Work

- We studied the impact of LP relaxed inference in max-margin learning
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- Future work: polyhedral characterizations that guarantee tighter bounds
- Conditions for vanishing relaxation gap in online learning
- Connections with regularization

#### Polyhedral Outer Approximations with Application to Natural Language Parsing

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# Balancing Accuracy and Runtime

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if \sigma_t = 1 then
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end for
Return the averaged model \hat{\mathbf{w}} \leftarrow \frac{1}{m} \sum_{t=1}^{m} \mathbf{w}_t.
```

#### Generalization Bound

#### Proposition

Setting 
$$\alpha_t = 1/(\lambda t)$$
,  $\lambda = \Theta\left(\sqrt{\frac{1+\log m}{m}}\right)$  and  $\eta_t = \Theta(t^{-1/2})$ :

$$\mathbb{E}\ell(h_{\hat{\mathbf{w}}}(X),Y) \leq \frac{1}{m}\sum_{t=1}^{m}r_t(\mathbf{w}^*) + \frac{L \cdot o(m)}{m} + O\left(\sqrt{\frac{1}{m}\ln\frac{1}{\delta}}\right)$$

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Previous bounds were in terms of the approximate learner [Kulesza and Pereira, 2007]