

Lightweight Implementations of Probabilistic Programming Languages via Transformational Compilation

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Implementing Probabilistic Programming Languages Without the Agonizing Pain

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Summary

Goal: Create **probabilistic programming languages** which help express complex probabilistic models

Observation: We would like to leverage **existing language infrastructure** (compilers, parallelization, profilers, debuggers, etc.)

Contribution: A method to help **transform any language** into a probabilistic programming language

Outline

- **Introduction to Probabilistic Programming**
- **Lightweight Implementations of PPLs**
- **New Inference Options**

Probabilistic Programming

The Big Idea

Use a **programming language** to express your model

- 1) Write down a function which makes random choices
- 2) Fix the output of the function (ie, condition the model)
- 3) Reason about the random choices needed to produce the output
(run the program backwards!)

Write a **probability compiler / interpreter** to perform inference

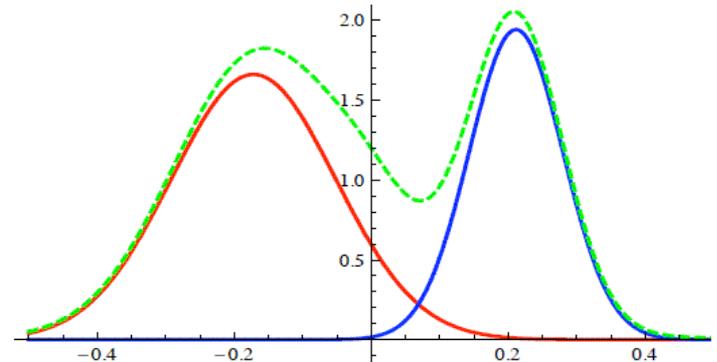
Distributions over Traces

Probabilistic programs define distributions by defining a **distribution over possible execution traces**

The distribution is fully specified by a generative procedure

```
function X = gmm()  
    if ( rand > 0.5 )  
        X = -0.2 + randn  
    else  
        X = 0.2 + 0.5*randn  
    end;  
return;
```

```
>> gmm  
-0.21  
>> gmm  
0.3  
...
```



Complex distributions are crafted **compositionally**

Example: LDA

```
function X = lda()

    K = 10;
    for k=1:K
        topics(k,:) = dirichlet( 1, vocab_size );
    end;

    for d=1:num_docs
        topic_dist = dirichlet( 1, K );
        for w=1:num_words(d)
            topic = multinomial( topic_dist );
            X{d}(w) = multinomial( topics(topic,:) );
        end;
    end;

return;
```

Nonparametrics

Nonparametric distributions are implemented with **stochastic memoization**

Idea:

Given a stochastic function

g

a stochastic memoizer returns a new function

f

which treats **g** as a base measure

Calls to **f** return

a previous or a new value from **g**

according to

the **Dirichlet Process**

```
>> g = @randn;
```

```
>> f = dpmem( g, 1.0 );
```

```
>> f()
```

```
-1.2
```

```
>> f()
```

```
-0.8
```

```
>> f()
```

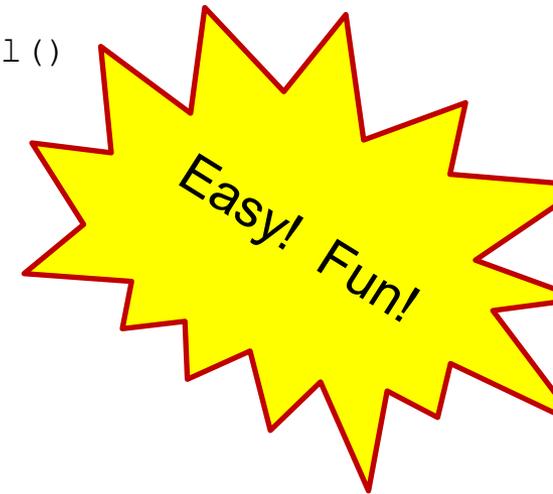
```
-1.2
```

```
>> f()
```

```
-1.2
```

Example: ((H)DP)MM

```
function X = gaussian_mixture_model()  
    K = 3;  
    mu = randn( 1, K );  
  
    for i=1:100  
        ind = randi( k );  
        X(i) = mu( ind ) + randn;  
    end;  
  
    return;
```



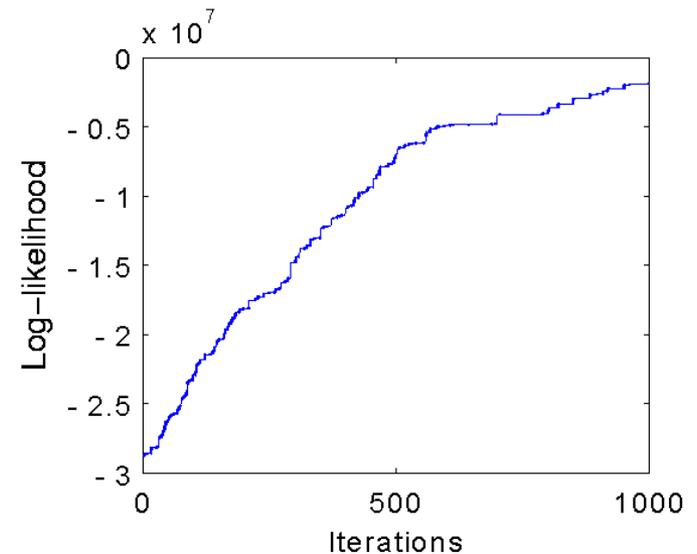
```
function X = dp_mixture_model()  
  
    b = dpmem( 1.0, @randn );  
  
    for i=1:100  
        X(i) = b() + randn;  
    end;  
  
    return;
```

```
function X = hdp_mixture_model()  
  
    a = dpmem( 1.0, @randn );  
    b = dpmem( 1.0, @a );  
  
    for i=1:100  
        X(i) = b() + randn;  
    end;  
  
    return;
```

Meta-Modeling

If your language has **eval()** in it, you can reason about **the structure of the model itself**

```
function Y = induce_program( X )  
  
    text_of_code = sample_pcfg();  
  
    f = eval( text_of_code );  
  
    for i=1:100  
        Y(i) = f( X(i) ) + randn;  
    end;  
  
    return;
```



Lightweight PPL Implementations

Inference

Goal: Perform inference in an **arbitrary program**

Approach: **MCMC**

Need: **Proposals, scoring mechanisms**

Therefore need: The ability to **control program execution**
...without the agonizing pain.

Observation: Execution Trace

```
function X = simple_model()
```

```
    m = poissrnd();
```

```
    for i=1:m  
        X(i) = gammarnd();  
    end;
```

```
    for i=m+1:2*m  
        X(i) = randn();  
    end;
```

```
return;
```

Random Choices Encountered



Observation: Execution Trace

```
function X = simple_model()
```

```
  m = poissrnd();
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```
  for i=1:m  
    X(i) = gammarnd();  
  end;
```

```
  for i=m+1:2*m  
    X(i) = randn();  
  end;
```

```
  return;
```

Random Choices Encountered



Note: if two traces make all of the same choices,
their execution paths will be the same!

Transformational Compilation

This suggests the following approach:

- 1) Give every random choice **a name**
- 2) Rewrite code to **make it deterministic**
- 3) When a random choice is encountered, use its name to look up its value in a **database of random values**

We can control execution traces
by manipulating values in the database!

MCMC over Execution Traces

With the database in hand, we can implement inference:

- 1) Given an execution trace
- 2) Propose changes to some variables
- 3) Update the trace, **reusing as much randomness as possible**
- 4) Score; accept/reject

Initialize: $[ll, \mathbb{D}] = \text{trace_update}(\emptyset)$

Repeat forever:

Select a random f_k via its name n

Look up its current value $(t, x, l, \theta_{db}) = \mathbb{D}(n)$.

Propose a new value $x' \sim \mathcal{K}_t(\cdot|x, \theta_{db})$

Compute $F = \log \mathcal{K}_t(x'|x, \theta_{db})$

Compute $R = \log \mathcal{K}_t(x|x', \theta_{db})$

Compute $l' = \log p_t(x'|\theta_{db})$

Let $\mathbb{D}' = \mathbb{D}$

Set $\mathbb{D}'(n) = (t, x', l', \theta_{db})$

$[ll', \mathbb{D}'] = \text{trace_update}(\mathbb{D}')$;

if $(\log(\text{rand}) < ll' - ll + R - F)$

 // accept

$\mathbb{D} = \mathbb{D}'$

$ll = ll'$

 // clean out unused values from \mathbb{D}

else

 // reject; discard \mathbb{D}'

endif;

end repeat;

But What Name?

How should we name random variables?

Idea: according to their
structural position in the trace

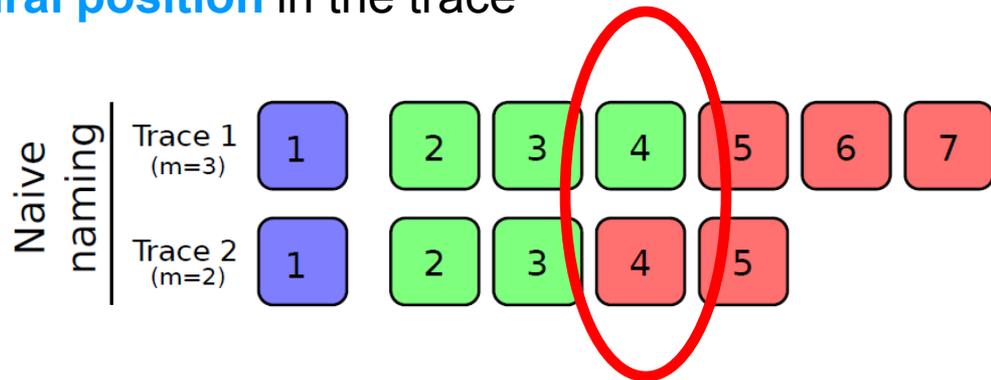
```
function X = simple_model()  
  
    m = poissrnd();  
  
    for i=1:m  
        X(i) = gammarrnd();  
    end;  
  
    for i=m+1:2*m  
        X(i) = randn();  
    end;  
  
    return;
```

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    end;  
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```



 poisson

 gamma

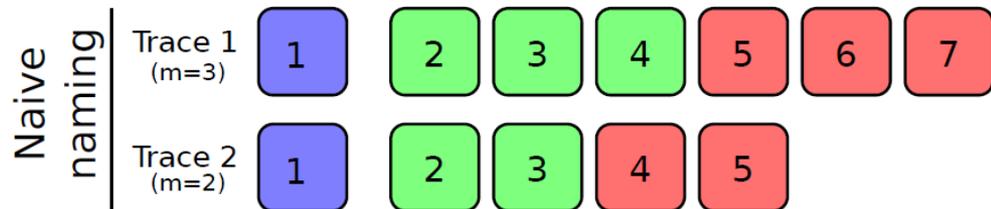
 gaussian

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```
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        X(i) = gammarnd();  
    end;  
  
    for i=m+1:2*m  
        X(i) = randn();  
    end;  
  
    return;
```



 poisson

 gamma

 gaussian

Generating Names

Augment the transformed source with
additional name-generating code

Imperative Naming Specification

- Begin executing f with empty function, line, and loop stacks.
- When entering a new function,
 - push a unique function id on the function stack.
 - push a 0 on the line stack.
- When moving to a new line
 - increment the last value on the line stack.
- When starting a loop
 - push a 0 on the loop stack.
- When iterating through a loop
 - increment the last value on the loop stack.
- When exiting a loop
 - pop the loop stack.
- When exiting a function
 - pop the function stack and the line stack.

Functional Naming Specification

```
 $\mathcal{A}^{top}[E] = ((\text{lambda (addr) } \mathcal{A}[E]) \text{'(top)})$   
 $\mathcal{A}[(\text{lambda } (I_{i=1}^n) \text{ } E_{body})] = (\text{lambda (addr . } I_{i=1}^n) \mathcal{A}[E_{body}])$   
where  $S$  is a globally unique symbol.  
 $\mathcal{A}[(\text{mem } E)] = ((\text{lambda (maddr f) (lambda (addr . args)$   
    (apply f (cons args maddr) args))) addr  $\mathcal{A}[E])$   
 $\mathcal{A}[(\text{begin } E_{i=1}^n)] = (\text{begin } \mathcal{A}[E_i]_{i=1}^n)$   
 $\mathcal{A}[(\text{letrec } ((I_i \ E_i)_{i=1}^n) \text{ } E_{body})] = (\text{letrec } ((I_i \ \mathcal{A}[E_i]_{i=1}^n) \mathcal{A}[E_{body}])$   
 $\mathcal{A}[(\text{if } E_t \ E_c \ E_a)] = (\text{if } \mathcal{A}[E_t] \ \mathcal{A}[E_c] \ \mathcal{A}[E_a])$   
 $\mathcal{A}[(\text{define } I \ E)] = (\text{define } I \ \mathcal{A}[E])$   
 $\mathcal{A}[(\text{quote } E)] = (\text{quote } E)$   
 $\mathcal{A}[(\text{Eop } E_{i=1}^n)] = (\mathcal{A}[E_{op}] (\text{cons 'S addr}) \mathcal{A}[E_i]_{i=1}^n)$   
 $\mathcal{A}[E] = E$ , otherwise.
```

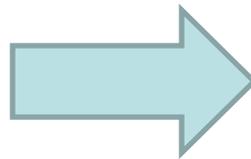
Stochastic Matlab

Bher

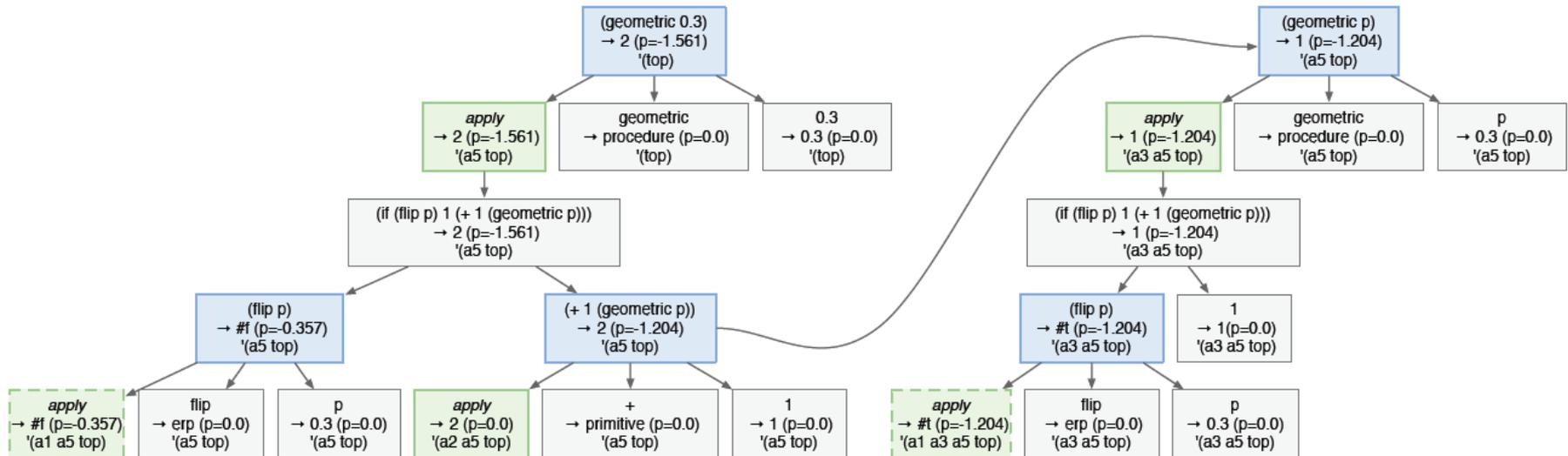


Example: Geometric

```
(begin
  (define geometric
    (lambda (p)
      (if (flip p)
          1
          (+ 1 (geometric p))))))
(geometric .7))
```

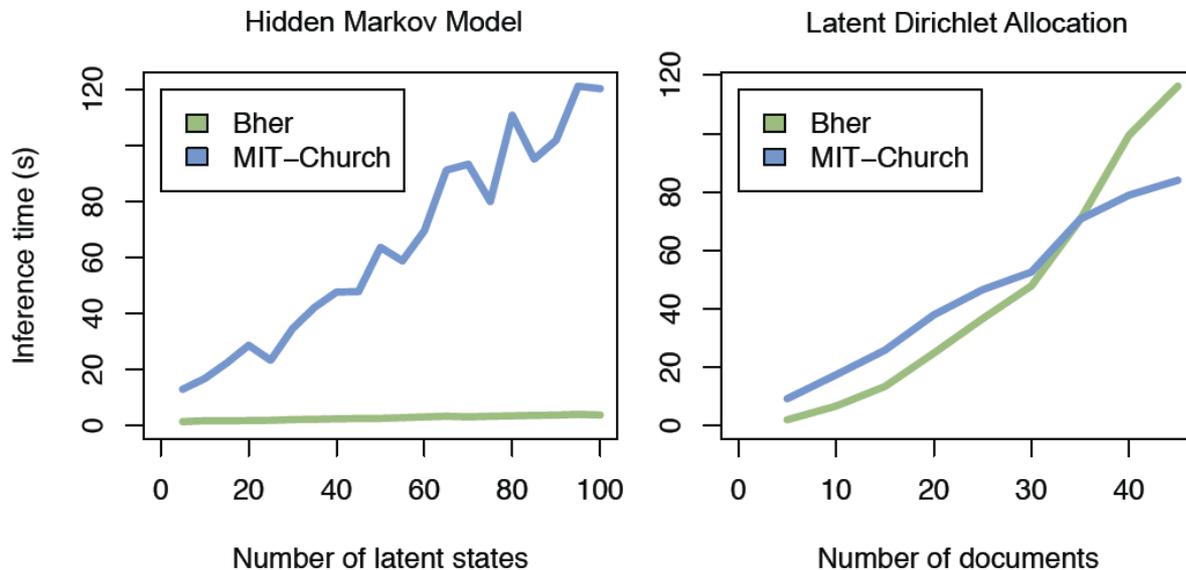


```
((lambda (addr)
  (begin
    (define geometric
      (lambda (addr p)
        (if (flip (cons 'a1 addr) p)
            1
            (+ (cons 'a2 addr)
                1
                (geometric (cons 'a3 addr) p))))))
    (geometric (cons 'a4 addr) 0.7)))
  ' (top))
```



Minimal Interpretative Overhead

Can **improve performance** by leveraging native ecosystem



Note: can also simplify implementations
(Bher codebase is **1/10 the size** of MIT-Church)

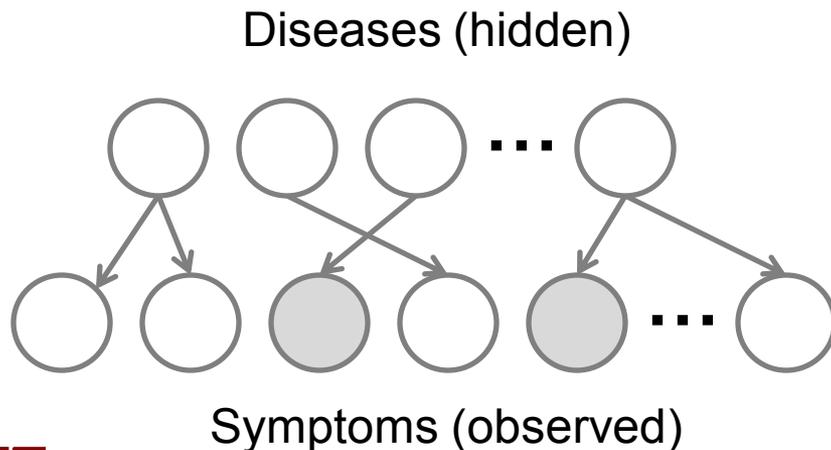
New Inference Options

Different Inference Options

The model is in **readable/executable format**
Can give the code a **non-standard interpretation**

For example:

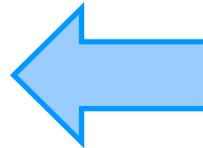
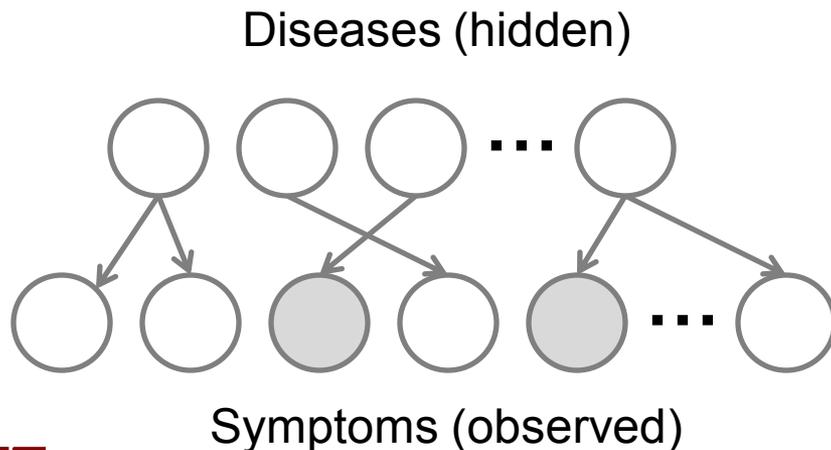
automatic differentiation
program analysis to identify known efficient sub-structures
operator overloading



Dynamic Dependency Analysis

Use **operator overloading**
to **dynamically track** fine-grained dependencies

Construct a **good proposal**
by **getting rid of the bad parts** of a big proposal

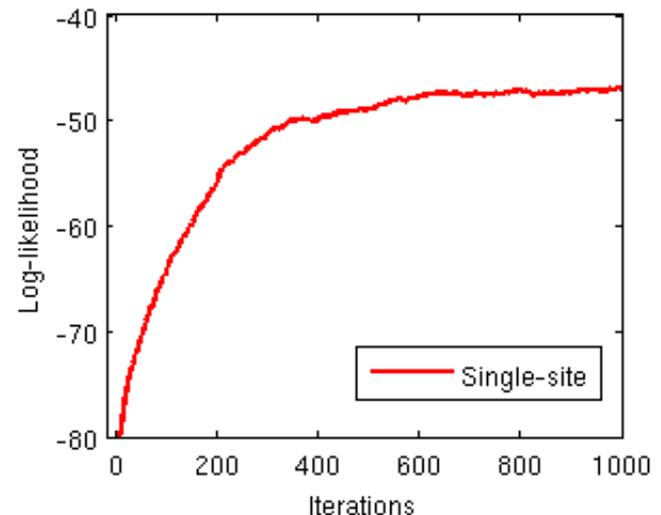
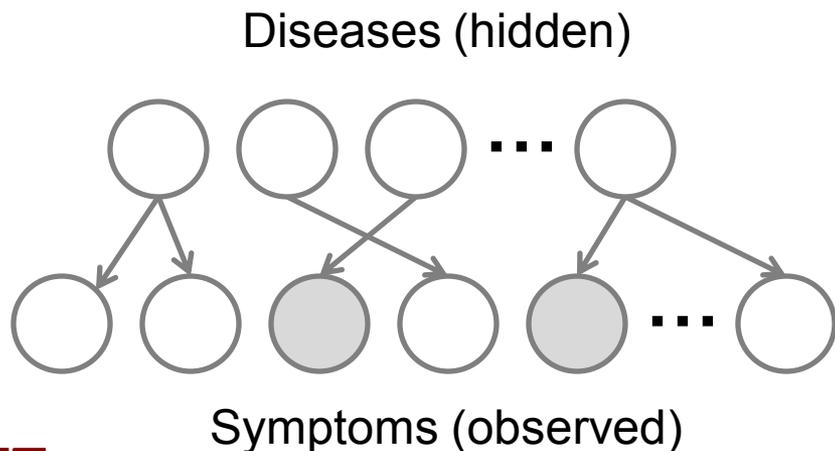


- 1) Propose lots of changes
- 2) Track dependency structure
- 3) Whittle away bad parts!

Dynamic Dependency Analysis

Use **operator overloading**
to **dynamically track** fine-grained dependencies

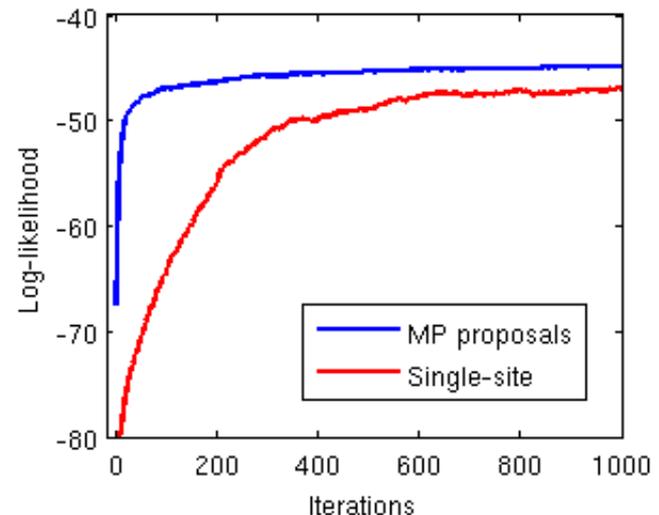
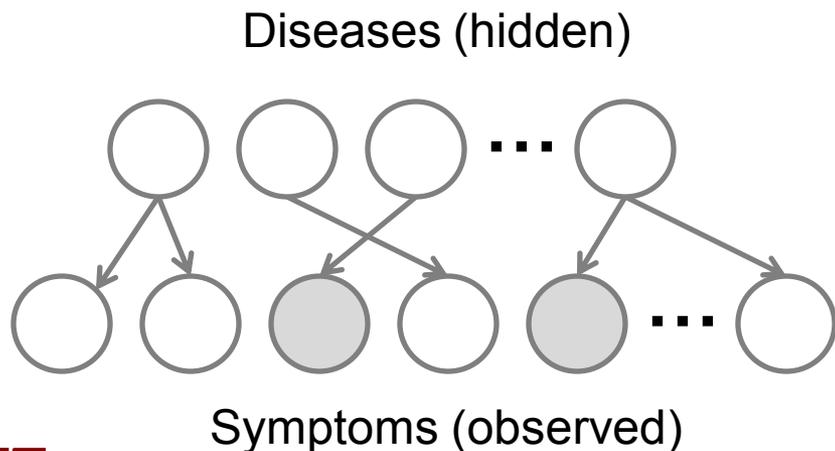
Construct a **good proposal**
by **getting rid of the bad parts** of a big proposal



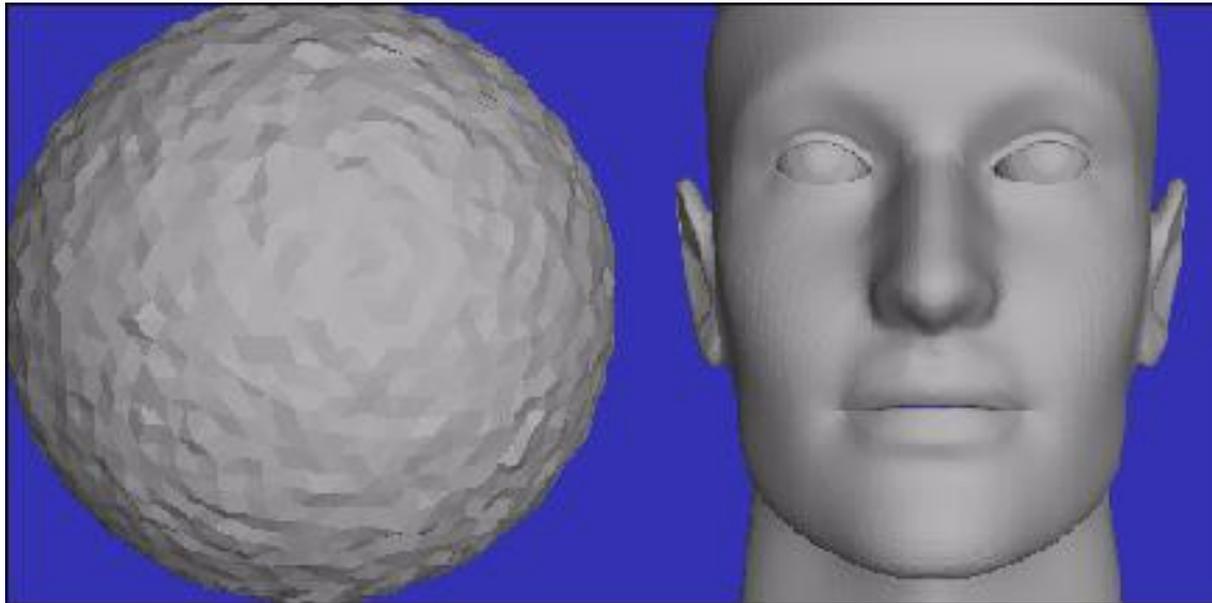
Dynamic Dependency Analysis

Use **operator overloading**
to **dynamically track** fine-grained dependencies

Construct a **good proposal**
by **getting rid of the bad parts** of a big proposal



Example: mesh inference



```
function X = mesh_inference( base_mesh )  
    mesh = base_mesh + randn( size(base_mesh) );  
    img = render( mesh );  
    X = img + randn(size(img));  
    return;
```

Summary

- **A generic technique for implementing PPLs**
 - Name random choices
 - Manipulate execution traces via a database of randomness
 - Structural naming conventions
 - Transformational compilation
- **Basis for several language implementations**
 - Functional: Bher
 - Imperative: Stochastic Matlab
 - New: pystoch
- **Machine-readable models**
 - suggests new options for analysis, inference

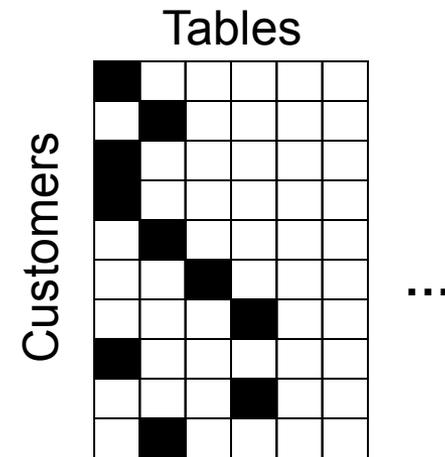
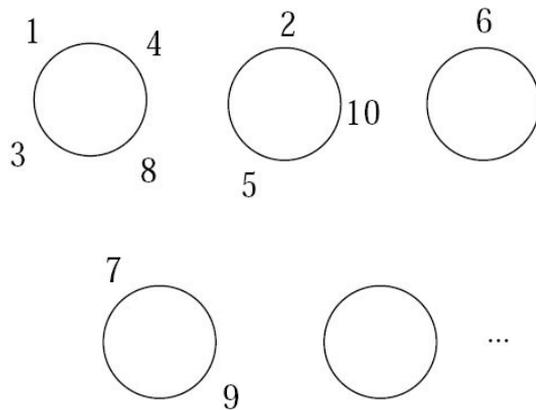
Thank you!

Stochastic Matlab

- An open-source project
- Sample-based inference
- Freely mix deterministic and stochastic functions
- Can use MEX files
- Some integration with GPU
- Integrated profiling / debugging / visualizations

The Chinese Restaurant Process

A stochastic, generative process which induces a **distribution over partitions**



Properties:

An exchangeable, nonparametric distribution

Can **identify dimensionality of data**

Allows dimensionality to grow with new data (unbounded seating!)

Allows for **parameter sharing**

Classic Model Specification

How do we
specify a probabilistic model?

Currently: a combination of
The English text in the paper
Statistician's notation
Graphical notation

But how do you clearly specify **complex models**?

Typical Design Cycle

Do math

Construct a model

Come up with equations
Limited by what you think is tractable

**Code up
inference**

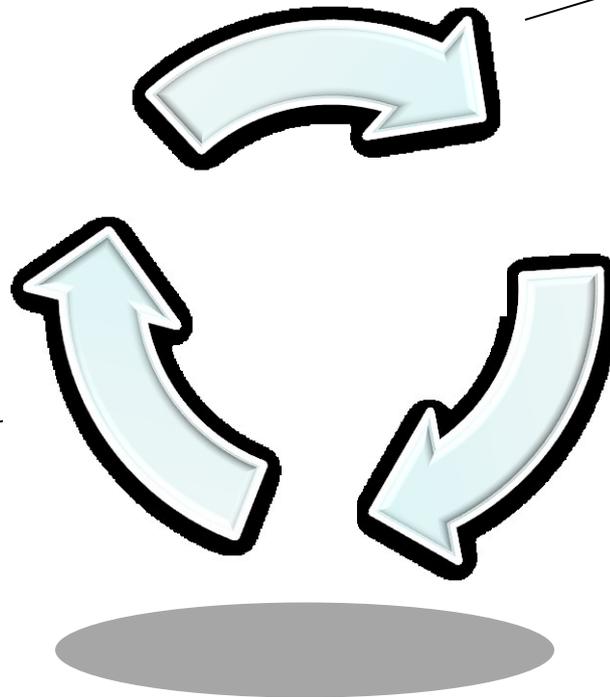
It's different every time

Does it match your math?
Want to try 100 different algorithms?
Hopefully, it's right...

**Experiment
and analyze**

Run Experiments

Is your model right?
Is your code right?
Is your data good?

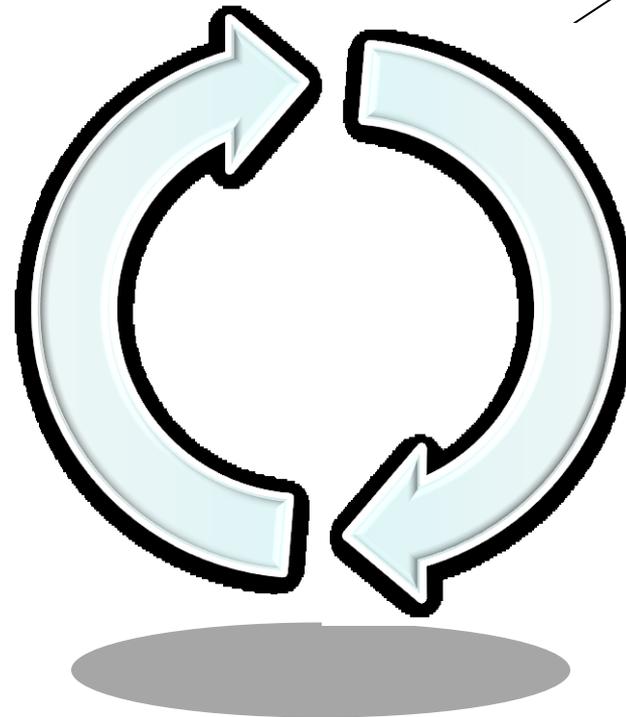


New Design Cycle

Code up your model

A precise specification

The compiler does the heavy lifting
Can try multiple inference algorithms
(coded by experts!)



Experiment and analyze

Run Experiments

Is your model right?
Is your code right?
Is your data good?

PCFGs

```
function X = sample_sentences()  
    for i=1:10  
        X{i} = [ NP() VP() ];  
    end;  
return;
```

```
function X = NP()  
    if ( rand > 0.5 )  
        X = [ DET() N() ];  
    else  
        X = [ DET() ADJ() N() ];  
    end;  
return;
```

```
function X = N()  
    nouns = { 'dog', 'cat', 'klein bottle' };  
    i = randi( length(nouns) );  
    X = nouns{ i };  
return;
```

Adaptor Grammars

```
function X = sample_sentences()  
    dp_NP = dpmem( 1.0, @NP() );  
    for i=1:10  
        X{i} = [ dp_NP() VP() ];  
    end;  
return;
```

```
function X = NP()  
    if ( rand > 0.5 )  
        X = [ DET() N() ];  
    else  
        X = [ DET() ADJ() N() ];  
    end;  
return;
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```
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