

Learning Recommendations in Social Media Systems By Weighting Multiple Relations

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Outline



Introduction

Social media sharing

Tag recommendation

Relational Graphs

Random walks on relational

Relation weight learning

Evaluation



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Social media sharing

Social image/video sharing sites

- **Flickr**: 6B images (Aug 2011)
- **Youtube**: 48 hours uploaded each minute (Dec 2010)

Each site is a environment with

- **Multiple entities** and **actors**
- **Multiple activities**
 - Navigation, search, tagging, commenting



The screenshot shows a Flickr page for a photo titled "A Spring In My Step". The photo is a vibrant field of multi-colored flowers (yellow, red, white, pink) in bloom. The page layout includes the Flickr logo and navigation links at the top, a search bar, and a "Sign In" link. Below the photo, there is a caption "A Spring In My Step", a "Comments and faves" section with three user comments, and a "Tags" section with various location and subject tags. A map on the right side of the page shows the photo's location in Union Square, New York, NY.

Image tagging and tag recommendation



Flickr tags are both **predefined** and **tree text**

- Common topics emerge when people agree on the semantic description of objects

Image understanding by content analysis is hard

Tags are **great help** in image sharing and search

Reliable tag recommendation

- Tag bootstrap** for a new image
- Tag expansion** for an existing image

05 alba amsterdam austria artistic architecture art ayahu australia autumn baby barcelona barcelona beach berlin birthday black blackandwhite blue boon boon bw california cameraphone camping canada canon car cat cats chicago china christmas church city clouds color concert day of december dog dogs england europe fal family festival florida flower flowers food france friends fun garden geotagged germany girl graffiti green halloween hawaii hazy holiday home honeymoon hongkong house india inland italy japan july kids lake landscape light london losangeles macro me mexico mobile moon mountains museum music nature new newyork newyorkcity newzealand night nyc ocean soccer paris park party people plus portrait red river roadtrip rock rock sea sanfrancisco scotland seo seattle sep sky snow spain street summer sunset sweden taiwan toads thailand thailand thailand tokyo toronto travel tree trees trip uk urban usa vacation vancouver washington water wedding white winter wisla yeshu yeshu 200

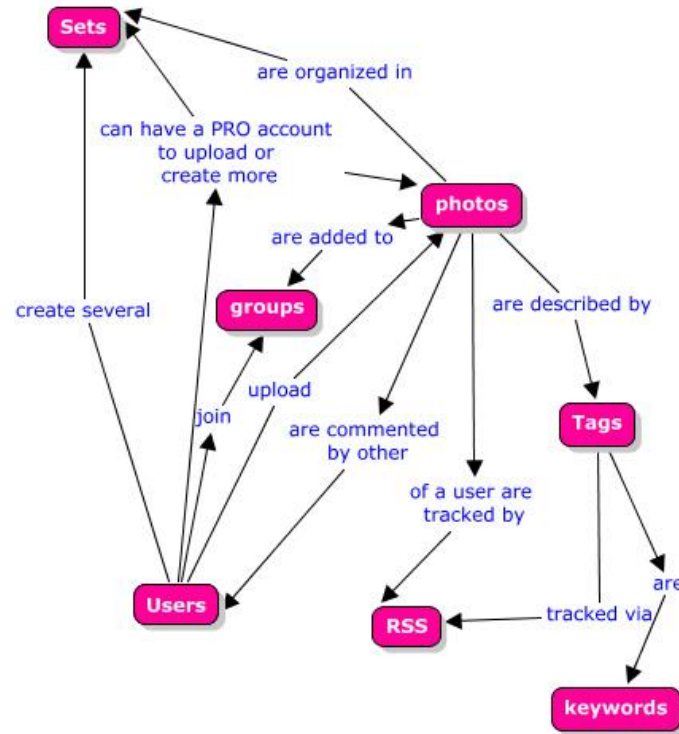


Entity types

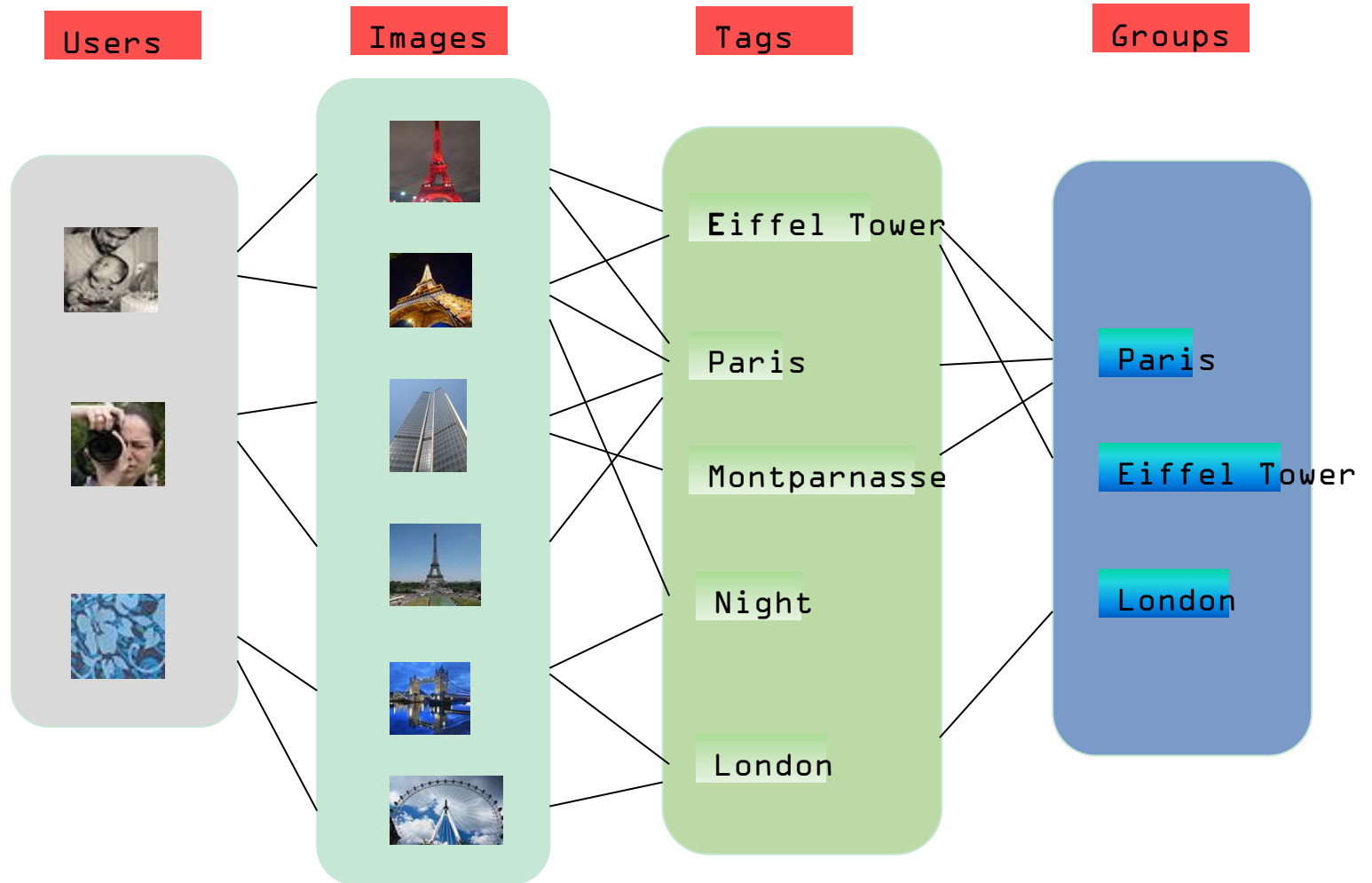
users, photos, tags, keywords, sets, groups, Rss

Multitude of relations

- Users oriented services around entities of different types



Flickr example



Tag recommendation

Challenge

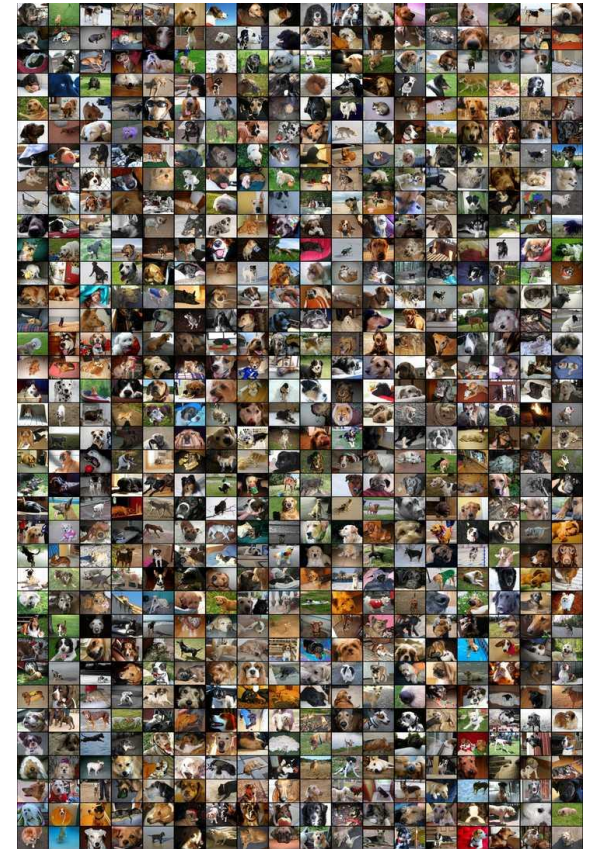
- How to benefit from all available relations

Task

- given a recommendation task, determine the optimal combination of relations

Our approach

- We model it as a **weighted random walk** on the unfolded relational graph
- We minimize **a loss function over the weights** of relations contributing to the weighted random walk
- **Scalability** concern



“Dog” tag images

Prior Art



- **Recommender systems** based on collective social knowledge [Garg08, Overell09, Sigurbj10]
- **Random walks** on weighted graphs [Toutanova04]
- Recommendation algorithms for the **MovieLens** collection and **Netflix** competition
- **Label propagation** [Zhou06] on the relational graph
- **Supervised** random walk [Backstrom11]

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Relational graph



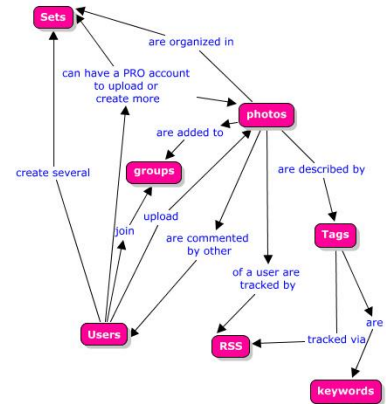
Represents entity types and relations between them

Graph $G = (E, R)$, where

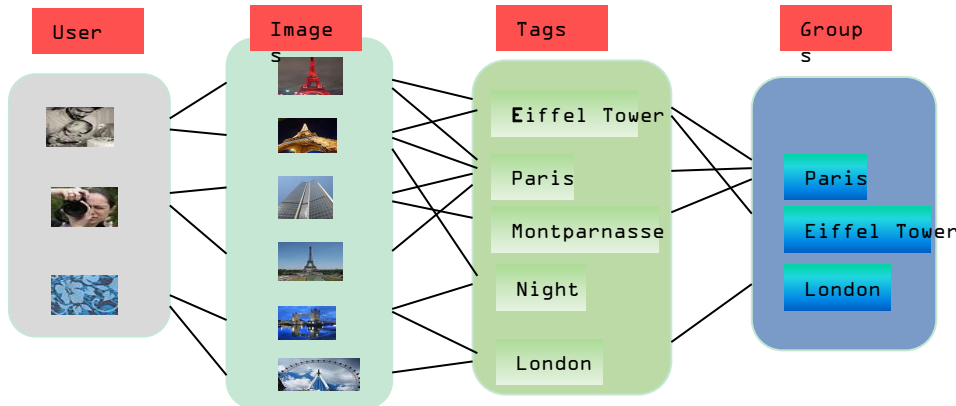
- Entity type $e_k \in E$ is represented as a node
- Relation $r_{kl} \in R$ between entities of types e_k and e_l

Flickr relational graph for 7 entity types:

- {photos, users, tags, groups, keywords, sets, rss}



Unfolded relational graph = instantiation of G



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Random walk model

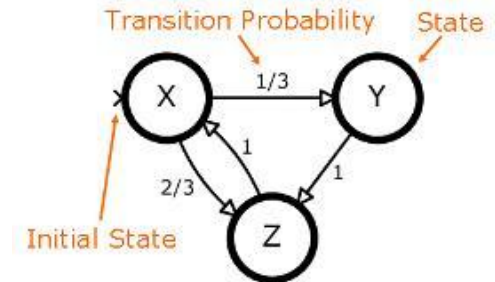


A **Markov chain** is defined by

- a set of **states** S
- an **initial distribution** P_0 over S
- a set of state **transition probabilities** $A = P(S_t | S_{t-1})$
 - the Web graph example
- **Reset** probability α

Stationary distribution of the Markov chain

$$\pi = \alpha \sum_{t=0}^{\infty} (1 - \alpha)^t P_0 A^t$$



Relational random walk model



A Relational Markov chain

- Node set S of the unfolded relational graph
- Initial distribution P_0 and resetting α
- Walk through the relation $r_{kl} \in R$ contributes with the weight $w_{kl}, 0 \leq w_{kl} \leq 1$

Random walk over the weighted sum of relation probability matrices A_{kl} :

$$A = \sum_{kl} w_{kl} A_{kl}$$

Transition probabilities $P_i = P(S_t | S_{t-1})$

w_{kl}

are a function of $\sum_k w_{kl} = 1$

Normalization constraint

Projection on tag nodes

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Relational weight learning



Approximation of the stationary distribution

- the truncated version, k steps of the random walk
- look for weights minimizing the prediction error on a training set T

Probability estimation loss

- **square loss** for true y and prediction p

$$l_{sq}(y, p) = (y - p)^2$$

- **Multi-label square loss** for true Y and prediction P vectors

$$L_{sq}(Y, P) = (l_{sq}(y_i, p_i)), i = 1, \dots, L$$

Gradient

$$\nabla L_{sq}(Y, P) = \left(\frac{\partial}{\partial p_i} l_{sq}(y_i, p_i) \right)_{i=1, \dots, L} = 2(Y - P)$$

Loss function



- We dispose the **training set** T
 - the image tags are true vectors Y
- Define a **scoring function** to be the empirical loss over the set T :

$$Loss(H) = \frac{1}{|T|} \sum_{j \in T} L_{sq}(Y_j, P_j)$$

- **Tag prediction** vector for image j

$$P_j = \alpha \sum_{t=1}^k (1 - \alpha)^t P_0^j A^t$$

- **Loss gradient**

$$\frac{\partial Loss(H)}{\partial w_{kl}} = \frac{1}{|T|} \sum_{j \in T} \nabla L_{sq}(Y_j, P_j) \frac{\partial P_j}{\partial w_{kl}}$$

- **Chain rule** for matrix derivatives

$$\frac{\partial A^t}{\partial w_{kl}} = \frac{\partial (A^{t-1} A)}{\partial w_{kl}} = \frac{\partial A^{t-1}}{\partial w_{kl}} A + A^{t-1} A_{kl}$$

Optimization problem



- The **constrained optimization problem**

$$\begin{aligned} & \min_{w_{kl}} \text{Loss}(H) \\ & \text{s.t.} \\ & 0 \leq w_{kl} \leq 1 \\ & \sum_l w_{kl} = 1, k = 1, \dots, b. \end{aligned}$$

- Converted into unconstrained one
- **Quazi-Newton** L-BFGS algorithm for gradient-based optimization
- Feed the derivatives of the loss function with respect to variables w_{kl}

Hessian matrix



- The **Hessian matrix** for the loss function may help the quasi-Newton method
- **Faster convergence** to a (generally local) optimum point

$$\frac{\partial \text{Loss}(H)}{\partial w_{kl} \partial w_{k'l'}} = \frac{1}{|T|} \sum_{j \in T} \frac{\partial}{\partial P_j} \nabla L_{sq}(Y_j, P_j) \frac{\partial^2 P_j}{\partial w_{kl} \partial w_{k'l'}}$$

- **Recursive formula** for the second derivatives of matrix series

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Evaluation



Python/SciPy/SpaMax implementation

Flickr API to download entities and relations

$E = \{\text{images, tags, users}\}$

Core relations between them

- **described_by** (image, tag)
- **upload** (user, image)
- **commented_by** (user, image)

Inferred relations

- **similarity** (user, user)

Flickr dataset

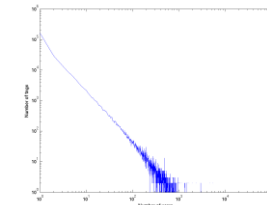
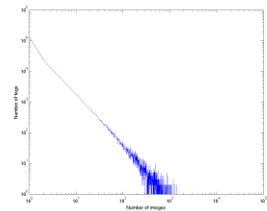


- 100,000 images by 1,951 users
- 127,182 different tags (113,426 after normalization)

Relation	Min	Max	Mean
Image2tag	1	132	5.65
User2image	1	384	27.32
User2user	0	43	1.24

Matrices are sparse and follow the **power law** distribution

- Preferential attachment in social networks
 - Number of tags per image
 - Number of tags used by a user



Experiment setting



Bootstrap mode

- predict tags for a newly uploaded image

Query mode

- Extend existing tags for an image

Cross-validation for the top 5 tag prediction

Evaluation metrics:

- precision, recall for the multi-label case

Baseline method

- the best un-weighted combination of relations

Alternative loss functions



All satisfy the symmetry condition in y and p

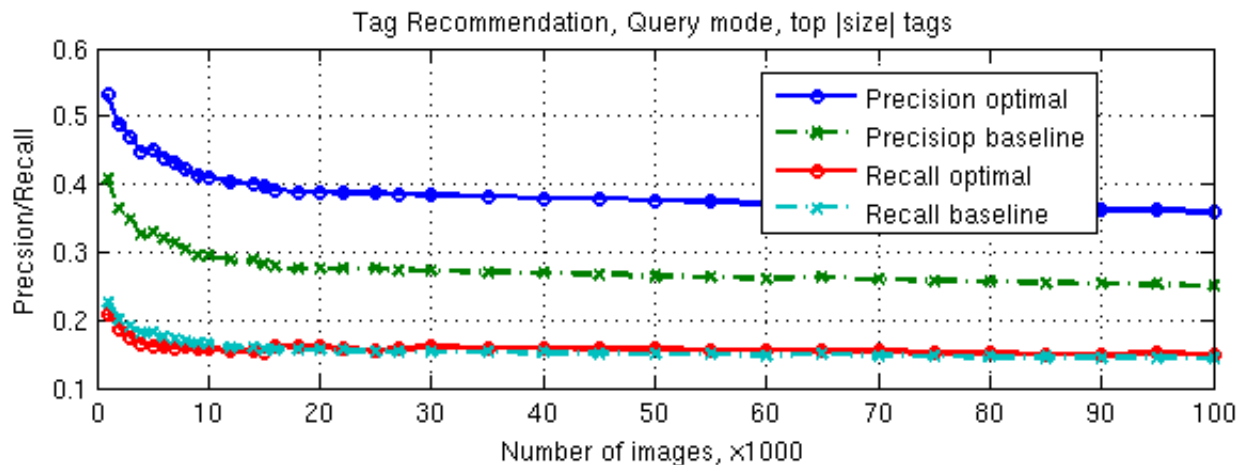
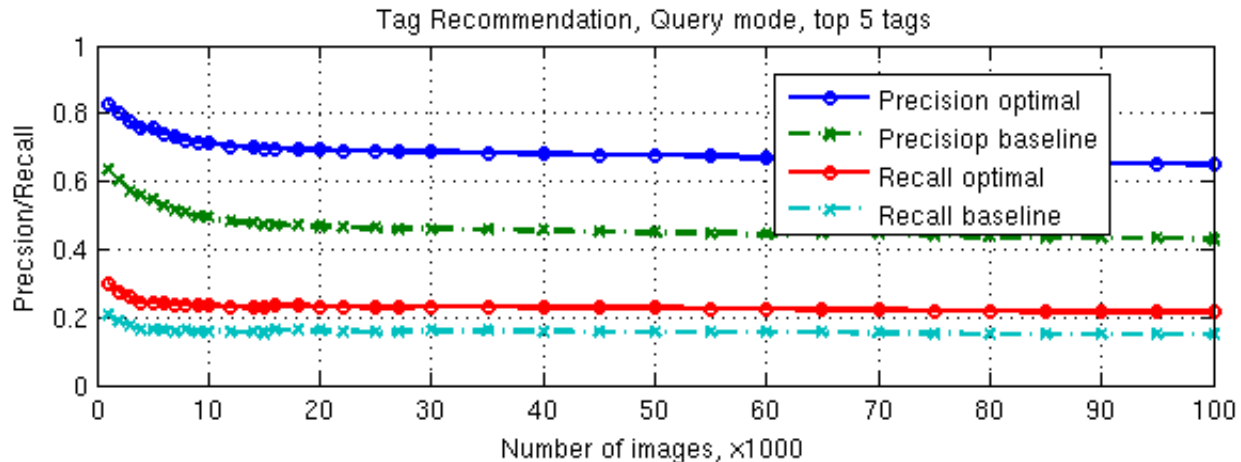
- **Absolute loss** $l_{abs}(y, p) = |y - p|$
- **Exponential loss** $l_{exp}(y, p) = \exp^{|y-p|} - 1$
- **Huber loss** $huber(y, p) = \begin{cases} \frac{|y-p|^2}{2}, & \text{if } |y-p| \leq 0.5 \\ |y-p| - \frac{1}{2}, & \text{otherwise,} \end{cases}$

All are differentiable but derivatives are not continuous

Tag recommendation



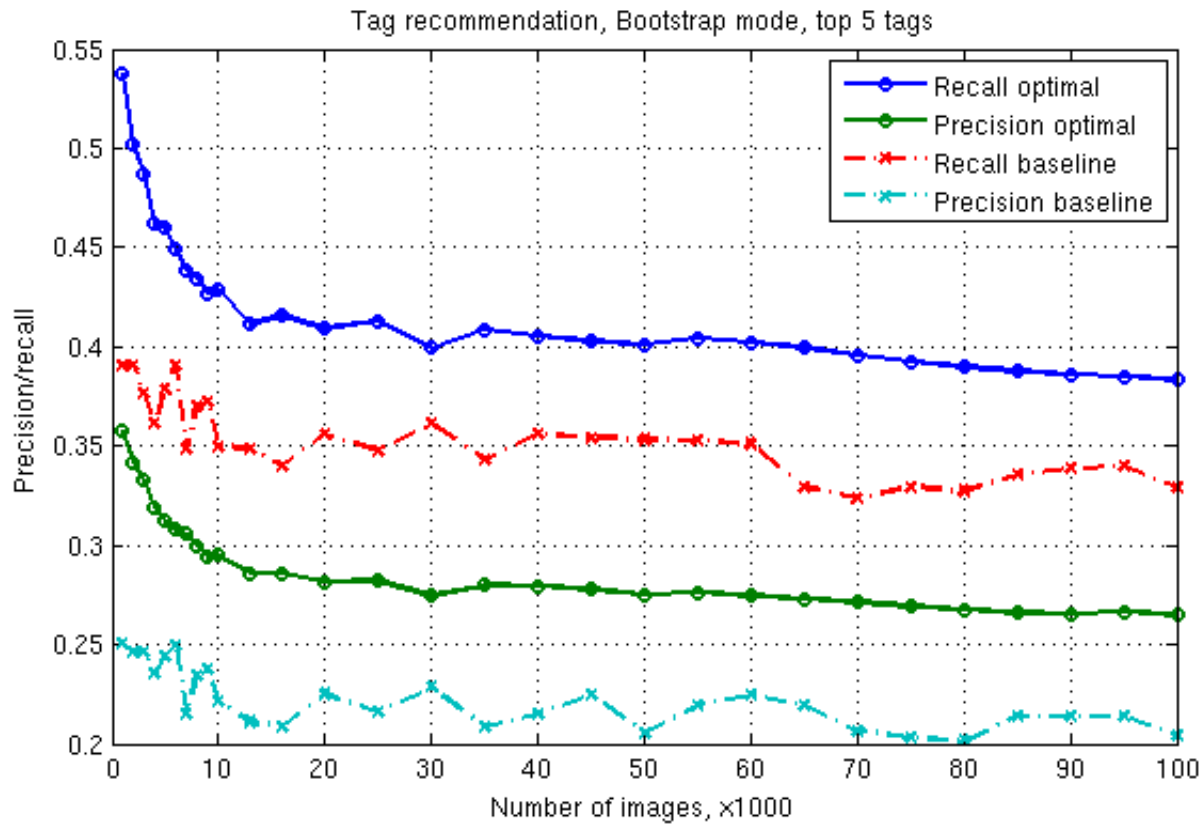
Querying mode



Tag recommendation



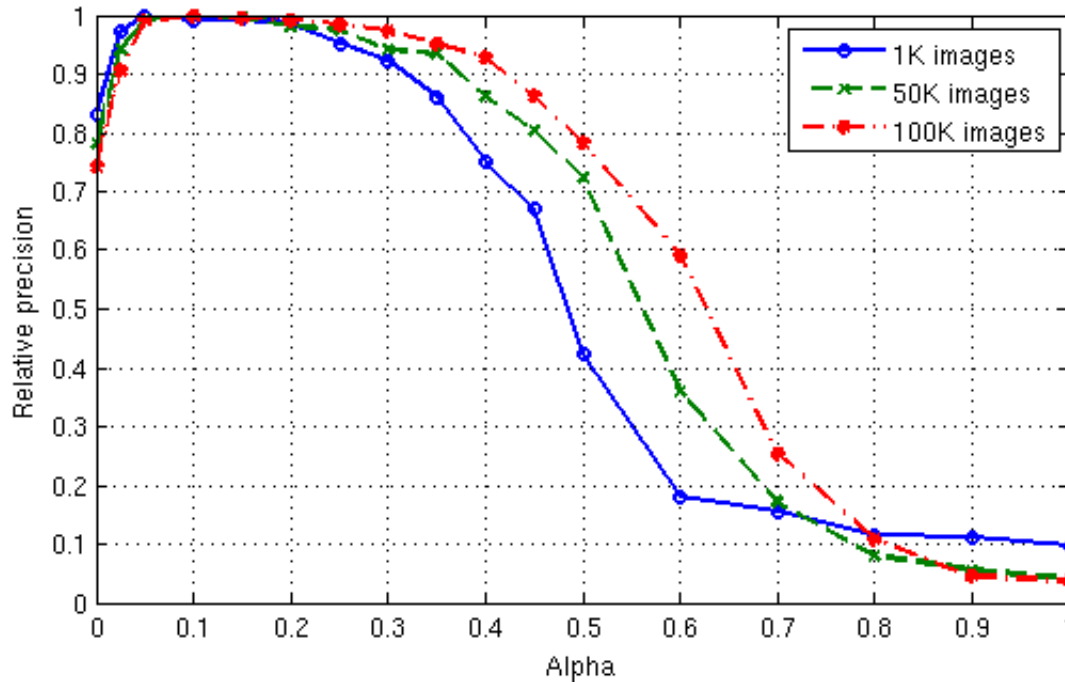
Bootstrap mode



Resetting coefficient effect



Tag recommendation for 1K/50K/100K images
Querying mode

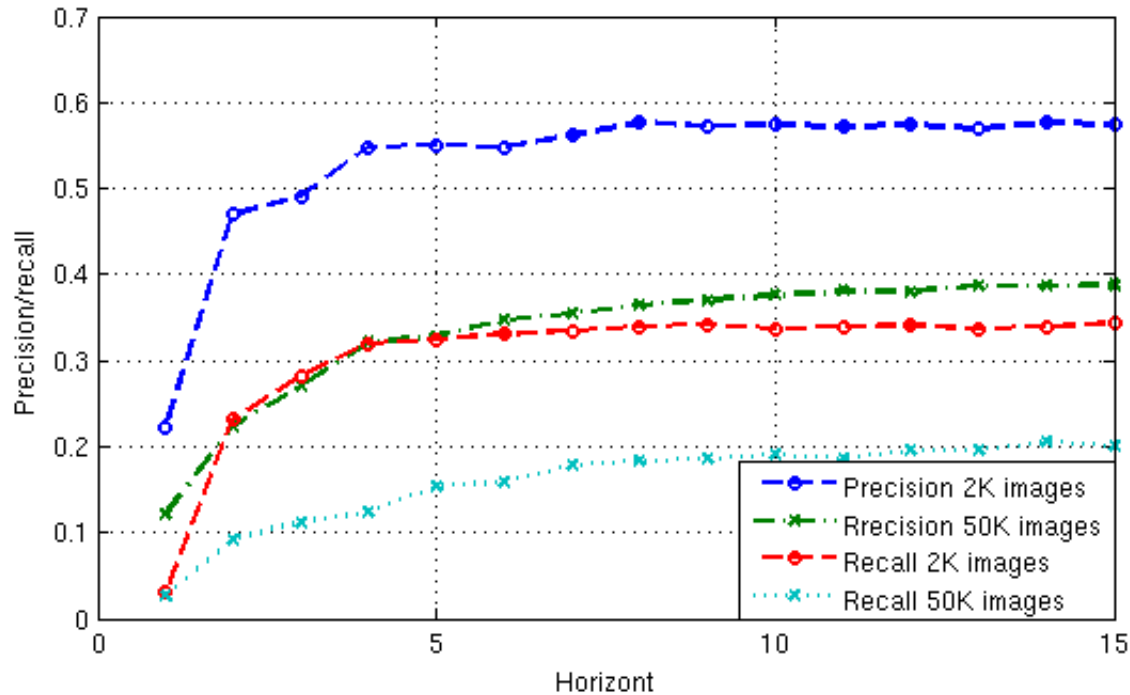


Impact of iteration number



Tag recommendation for 2K/50K images

- Querying mode



Lessons learned (Conclusion)



Relational random walk in the loss minimization form

Scalability is good (thank to the sparse matrices)

MapReduce version (64-cores parallel cluster) is for 12M images

- Flickr relations enriched with image features
- Local context

Hessian is of limited help (< 10K images)

Positioning w.r.t. matrix co-factorization

Interest in relation (in)dependence criteria

• Relations on groups and sets are of little





Thank you !

Questions ?

Algorithm 1



Algorithm 1 Loss function and its gradient

Require: Training dataset T , the restarting probability α

Require: Relation matrices A_{kl} , weights $(w_{kl}), k, l = 1, \dots, b$

Ensure: Loss function value $Loss(H)$ and the gradient $\nabla Loss(H)$

- 1: $A = \sum_{kl} w_{kl} A_{kl}$
- 2: **for** $j = 1$ to $|T|$ **do**
- 3: Set the initial distribution P_0 for object j
- 4: **for** $t = 1$ until convergence **do**
- 5: $P_j^t = \alpha P_0 + (1 - \alpha) P_j^{t-1} A$
- 6: **for all** w_{kl} **do**
- 7: Update $\frac{\partial P_j^t}{\partial w_{kl}}$ using (7)
- 8: **end for**
- 9: **end for**
- 10: Set $L(Y_j, P_j)$ using (4)
- 11: $Loss(H) = Loss(H) + L(Y_j, P_j)$
- 12: **for all** w_{kl} **do**
- 13: Set $\frac{\partial L(Y_j, P_j)}{\partial w_{kl}}$ using (6)
- 14: $\frac{\partial Loss(H)}{\partial w_{kl}} = \frac{\partial Loss(H)}{\partial w_{kl}} + \frac{\partial L(Y_j, P_j)}{\partial w_{kl}}$
- 15: **end for**
- 16: **end for**
- 17: Return $Loss(H)$ and the gradient $\nabla Loss(H)$ at $(w_{kl}), k, l = 1, \dots, b$.

Random Walk



The Markov chain model for walking on the relational graph

Defined as the supervised learning problem

- Define the loss function over a training set of examples
- Loss is a function of the weights of relations contributing to the weighted random walk
- Measure metric between estimated and true probability distributions on tags