

A Shapley value Approach for Influence Attribution

Panagiotis Papapetrou

Aalto University, Finland

Joint work with:

Aris Gionis, Yahoo! Research, Spain

Heikki Mannila, Aalto University, Finland

Influential individuals

- People always intrigued by characterizing influential ideas, books, scientists, politicians, etc.
- Main question: who or what is influential?
- Examples
 - Who initiates the most influential “tweets”?
 - Who are the most influential scientists?
 - Which actors influence a movie rating the most?

Goal

- **We address a novel problem in the context of characterizing who is influential.**
- **Our setting:**
 - Individuals accomplish tasks in a collaborative manner.
 - **Influence attribution:** each individual is assigned a score based on his/her performance.

Outline

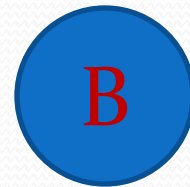
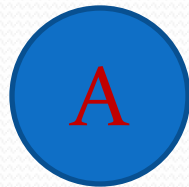
- **Problem Formulation**
- Proposed Solution
- Experimental Evaluation
- Conclusions

Example: author-publication

- Individual => author.
- Task => publication.
- Impact score =>
 - CC: Citation count of the publication.
 - PR: PageRank score of the publication.

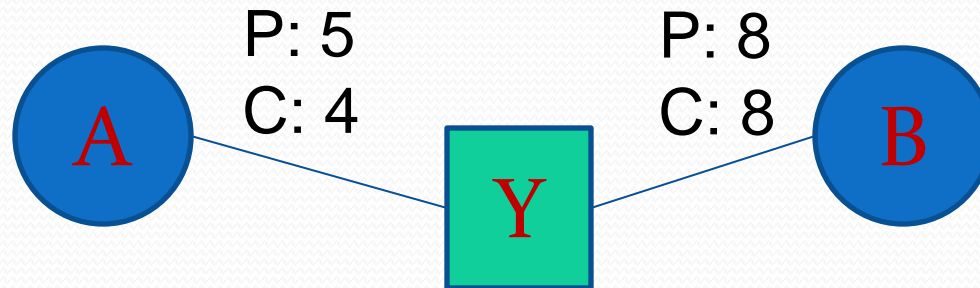
Example: author-publication

- Two researchers A and B.
- Question: who is more influential?



Example: author-publication

- One common collaborator: Y.

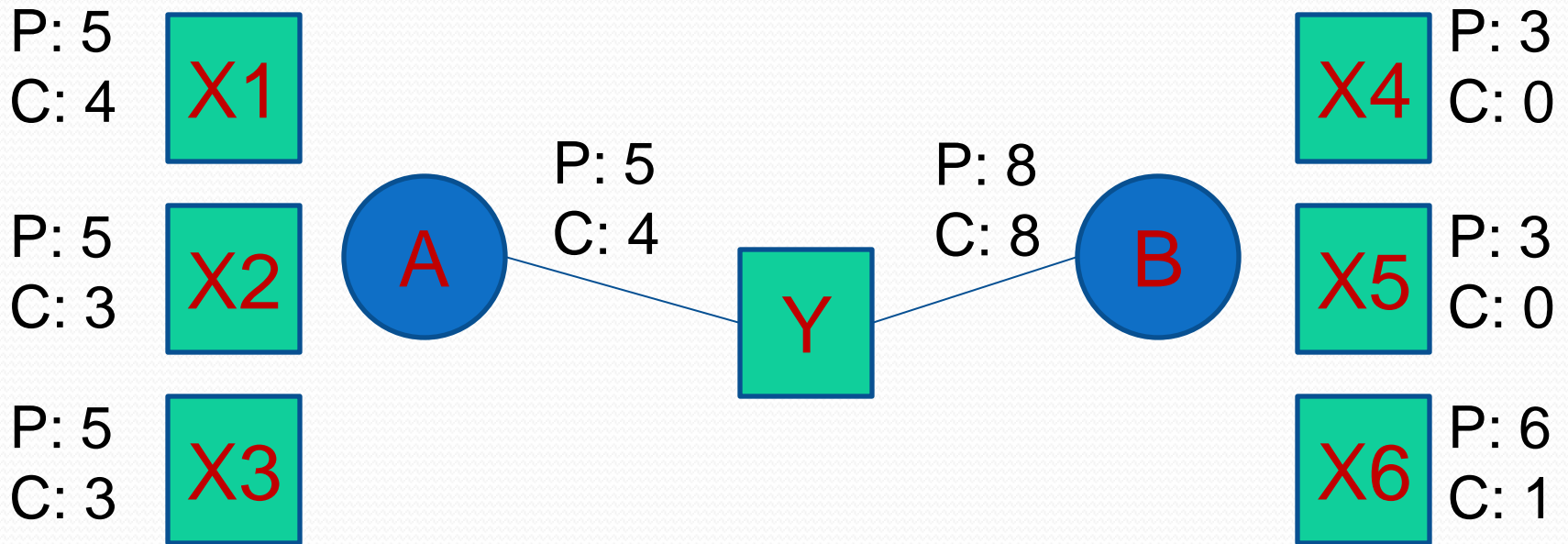


P: number of papers

C: number of citations per paper

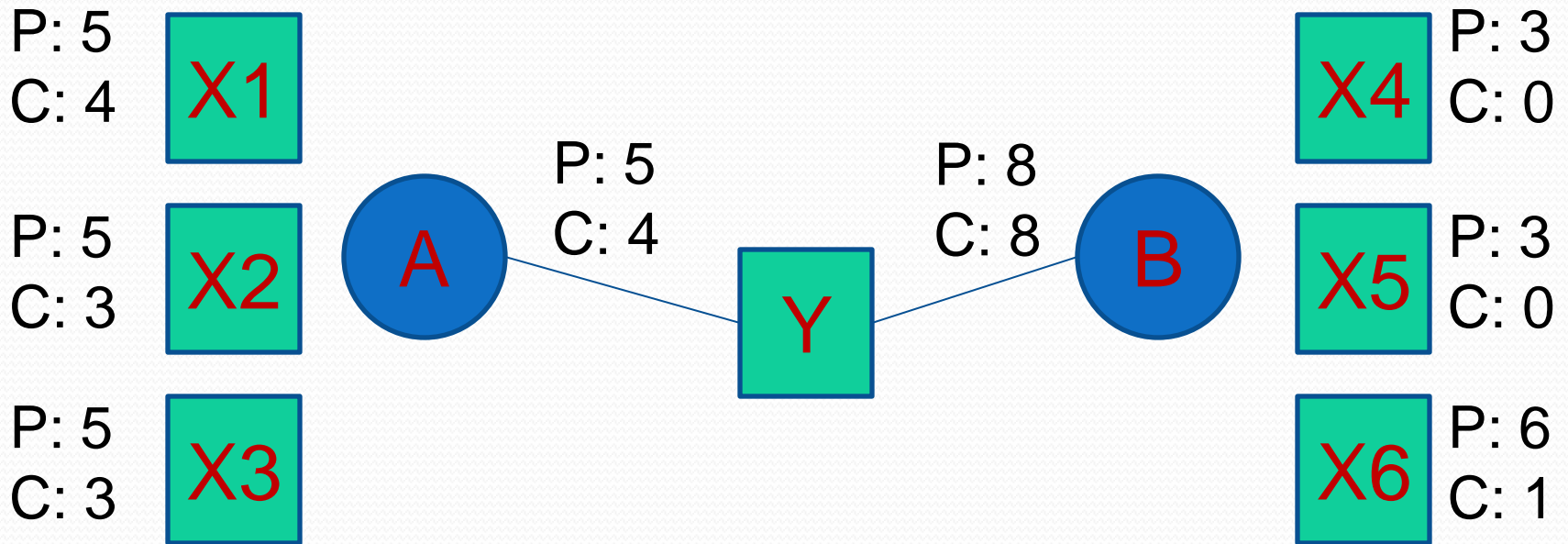
Example: author-publication

- Three additional collaborators for A and B.



Example: author-publication

- Three additional collaborators for A and B.



Researcher	Papers	Citations	H-index
A	20	70	4
B	20	70	8

Example: author-publication

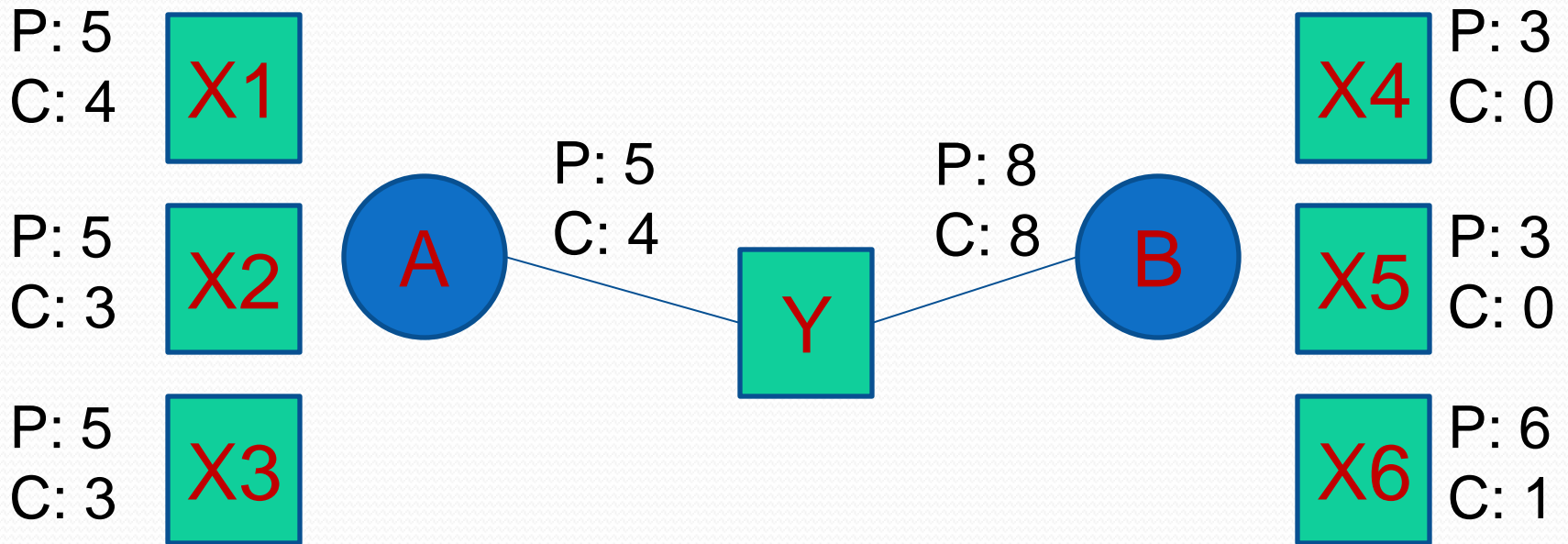
- Three additional collaborators for A and B.

H-Index: a scientist's H-index is h , if h of his/her publications have at least h citations and the rest of his/her publications have at most h citations each.

Researcher	Papers	Citations	H-index
A	20	70	4
B	20	70	8

Example: author-publication

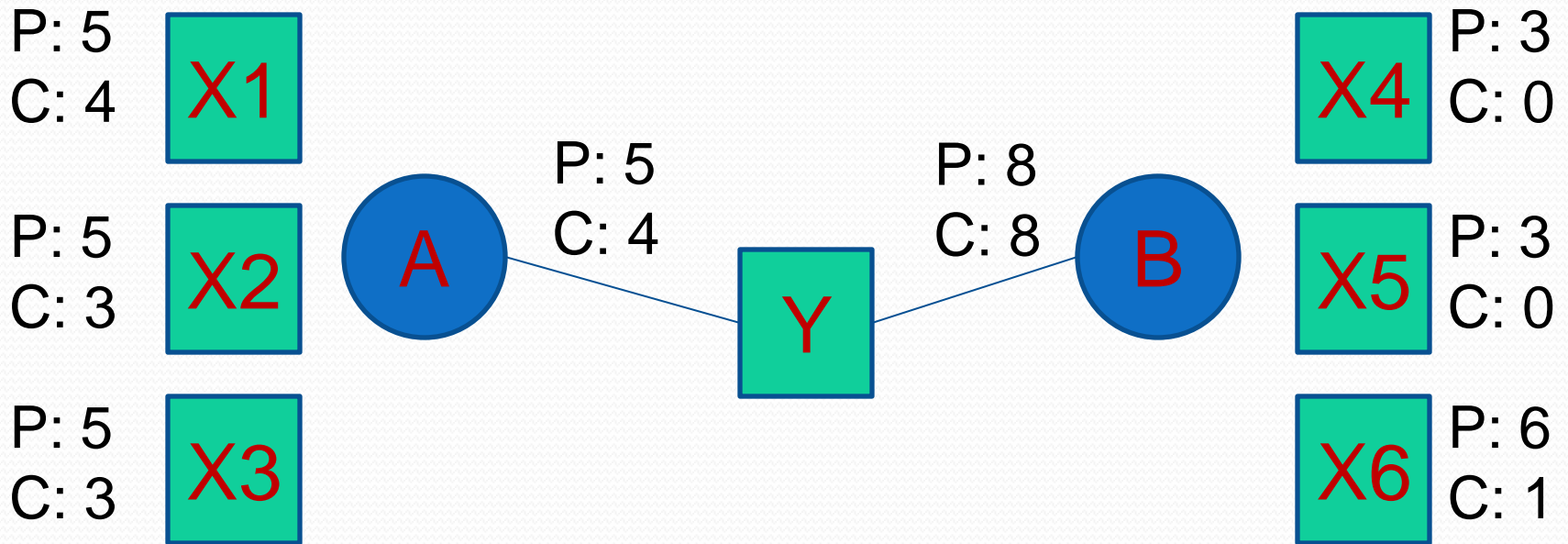
- Three additional collaborators for A and B.



Researcher	Papers	Citations	H-index
A	20	70	4
B	20	70	8

Example: author-publication

- Three additional collaborators for A and B.



- But is B indeed that influential?
- Or is B just being favored due to the fame of Y?

Example: author-publication

- Drop Y out of the picture.



- The performance of A remains quite high.
- The performance of B is weakened a lot.

Example: author-publication

- Drop Y out of the picture.



Researcher	Papers	Citations	H-index
A	15	50	4
B	12	6	1

Background

- Existing measures in bibliometrics can be enriched.
- Social network analysis methods focus on finding *important* individuals based on in-degree or refinements.
- Information diffusion finds individuals who act as *good* initiators.
- Coalitional games: Shapley value.

Problem Definition

- Given
 - a set of individuals $V = \{V_1, \dots, V_n\}$,
 - a set of tasks $T = \{T_1, \dots, T_m\}$,
 - a set of impact scores $I = \{I_1, \dots, I_m\}$.
- Goal:
 - Compute the set of influence scores $\phi = \{\phi_1, \dots, \phi_n\}$.
- Φ_i is the influence score of individual V_i .

Outline

- Problem Formulation
- **Proposed Solution**
- Experimental Evaluation
- Conclusions

Shapley Value

- Consider an underlying set V .
- Assume for all possible subsets S of V we know $v(S)$.
- $v(S)$: gain function
 - expresses the gain achieved by the cooperation of the individuals in S .
- Shapley value: the share allocation to individual V_i .

$$\phi_i(v) = \sum_{S \subseteq V} \frac{|S|!(|V| - |S| - 1)!}{|V|!} (v(S \cup \{V_i\}) - v(S)).$$

Shapley Value

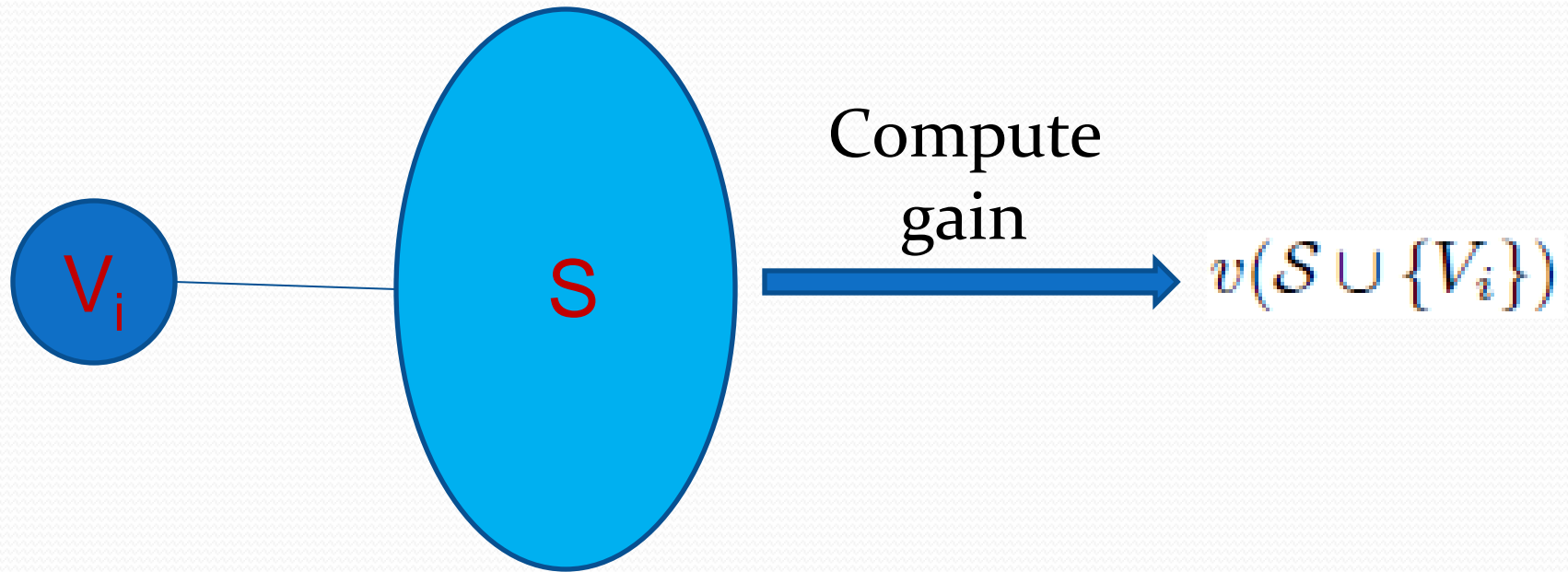
- Can be shown theoretically that the resulting attribution satisfies natural fairness properties [Winter 2002].
- However, a direct application of the Shapley value definition in our setting is not possible:
 - it assumes an averaging over exponentially many sets,
 - it is not possible to probe arbitrary sets S and obtain $v(S)$,
 - we may not have available the impact score of papers for every possible subset of authors!

Our Approach

- We compute the marginal gains by averaging only over **coalitions for which we have available impact scores.**
- In order to average in a marginal contribution we need to have available both values $v(\mathcal{S} \cup \{V_i\})$ and $v(\mathcal{S})$.
- In many cases we have available only one of the two.
- How shall we deal with such cases?
 - Ignore them? → very sparse data.

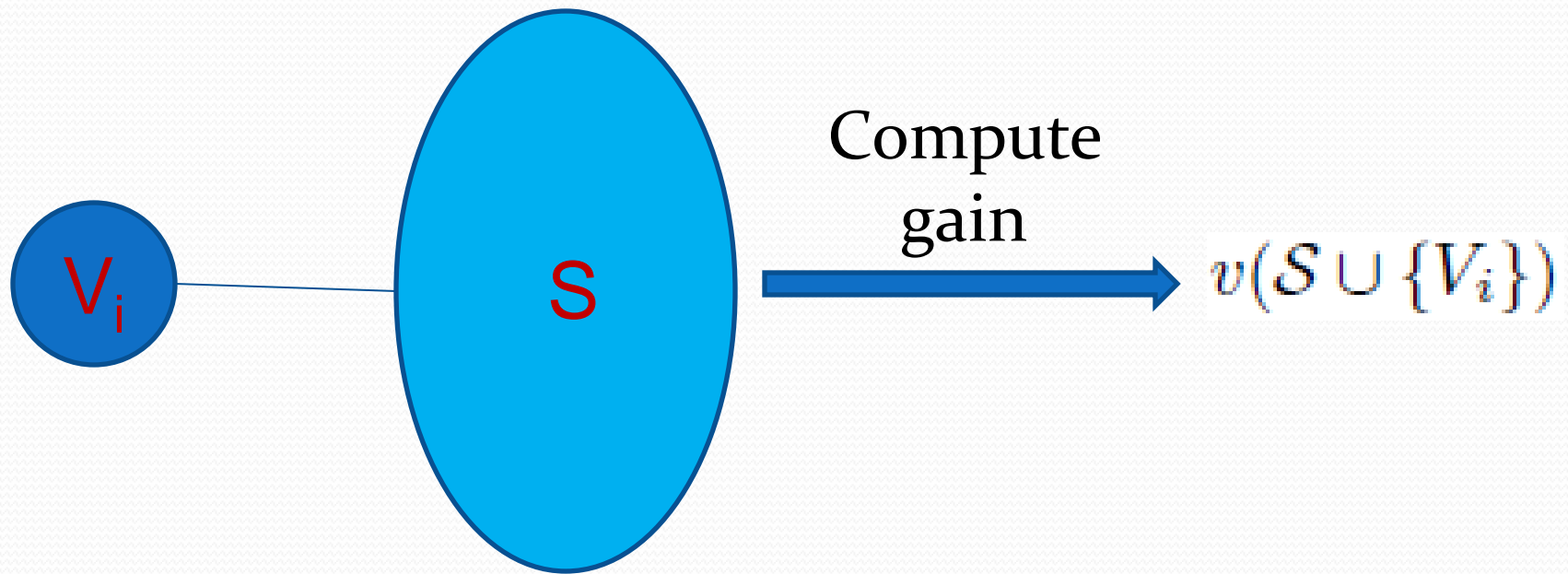
Our Approach

- We choose to take into account all cases for which $S \cup \{V_i\}$ is available.



Our Approach

- We choose to take into account all cases for which $S \cup \{V_i\}$ is available.



- **What about $v(S)$?**

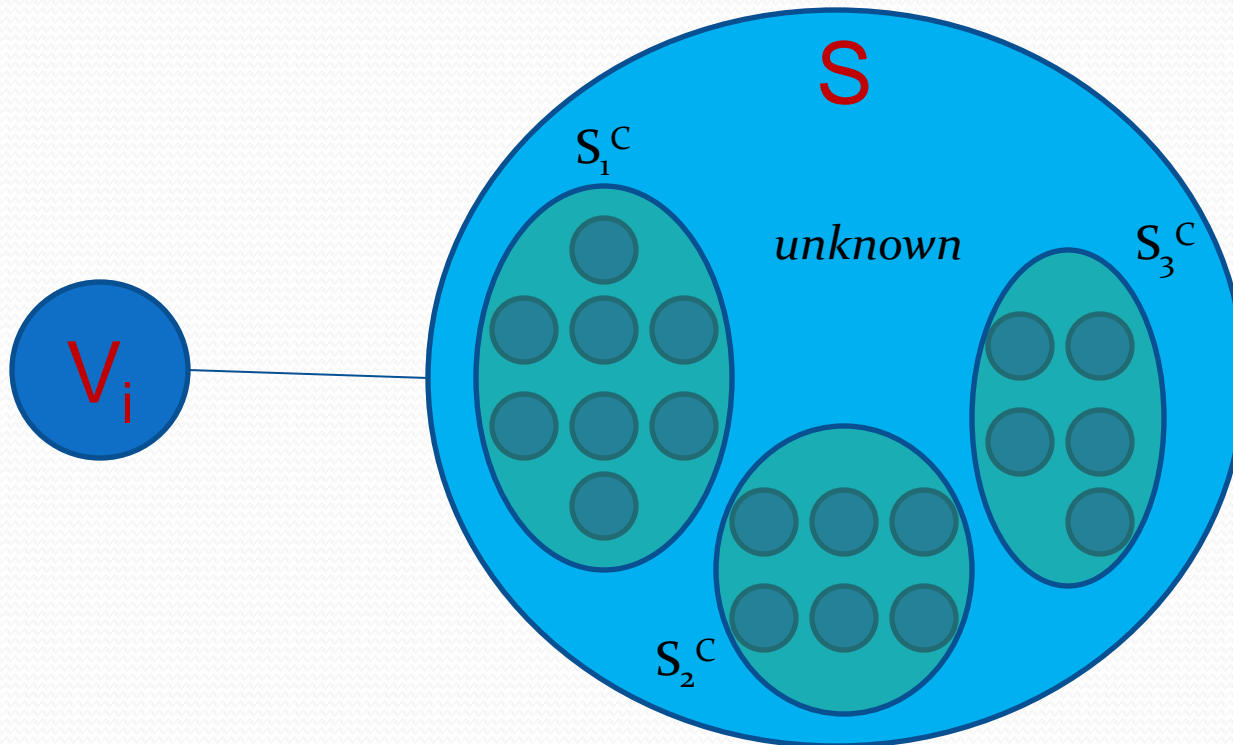
Shared impact factor

- Let I_j be the impact factor of each common task T_j between a group of individuals S .
- Then the shared impact factor is the *average impact factor* among all their common tasks T_S .

$$v(S) = \frac{1}{|T_S|} \sum_{j=1}^{|T_S|} I_j.$$

Approximated Shared impact factor

- What if for some set S we have no complete information about the coalitions?



Approximated Shared impact factor

- What if for some set S we have no complete information about the coalitions?
- Take only the subsets S_i^c of S for which there is such information:

$$v'(\mathcal{S}) = \frac{1}{|\mathcal{S}^c| + 1} \left(\sum_{i=1}^{|\mathcal{S}^c|} v(\mathcal{S}_i^c) + \bar{v}(\mathcal{S} \setminus \mathcal{S}_i^c) \right)$$

Approximated Gain Function

- What about $\bar{v}(\mathcal{S})$?
- Assuming a monotonic behavior, i.e., teams are at least as good as the best individual in the team, we define:

$$\bar{v}(\mathcal{S}) = \max_{V_i \in \mathcal{S}} \phi_i(v).$$

The Iterative Algorithm

- Goal: compute the influence score ϕ_i of each individual.
- At each iteration t the Shapley value is computed using the original definition:

$$\phi_i(v) = \sum_{\mathcal{S} \subseteq \mathcal{V}} \frac{|\mathcal{S}|!(|\mathcal{V}| - |\mathcal{S}| - 1)!}{|\mathcal{V}|!} (v(\mathcal{S} \cup \{V_i\}) - v(\mathcal{S})).$$

The Iterative Algorithm

- Goal: compute the influence score ϕ_i of each individual.
- At each iteration t the Shapley value is computed using the original definition:
- Whenever we need to probe a coalition for which the impact factor is not available, use the approx. shared impact factor:

$$v'(\mathcal{S}) = \frac{1}{|\mathcal{S}^c| + 1} \left(\sum_{i=1}^{|\mathcal{S}^c|} v(\mathcal{S}_i^c) + \bar{v}(\mathcal{S} \setminus \mathcal{S}_i^c) \right)$$

The Iterative Algorithm

- Goal: compute the influence score ϕ_i of each individual.
- At each iteration t the Shapley value is computed using the original definition:
- Whenever we need to probe a coalition for which the impact factor is not available, use the approx. shared impact factor.
- Influence score is updated:

$$\phi_i^{t+1}(v') = \sum_{\mathcal{V}_{T_j} | V_i \in T_j} \frac{|\mathcal{V}_{T_j}|!(|\mathcal{V}| - |\mathcal{V}_{T_j}| - 1)!}{|\mathcal{V}|!} (v'(\mathcal{V}_{T_j}) - v'(\mathcal{V}_{T_j} \setminus V_i)).$$

Outline

- Problem Formulation
- Proposed Solution
- **Experimental Evaluation**
- Conclusions

Experimental Setup

- Datasets:
 - ISI Web of Science.
 - Internet Movie Database (IMDB).
- ISI Web of Science:
 - Part of the Thomson Reuters ISI Web of Science data.
 - ISI covers mainly journal publications.
 - We sampled data related to our institutions published within years 2003 and 2009.
 - Our dataset contains information about 1212 authors.

Experimental Setup

- Internet Movie DataBase:
 - We sampled a total of 2 000 male actors.
 - We restricted the movie genre type to comedy or action.
 - For each actor we considered only the movies where his credit position was among the top 3.

Experimental Evaluation

- We used two very common bibliometric indicators as the baseline:
 - H-Index, G-index.
- Impact score for a publication:
 - CC: Citation count of the publication.
 - PR: PageRank score of the publication.

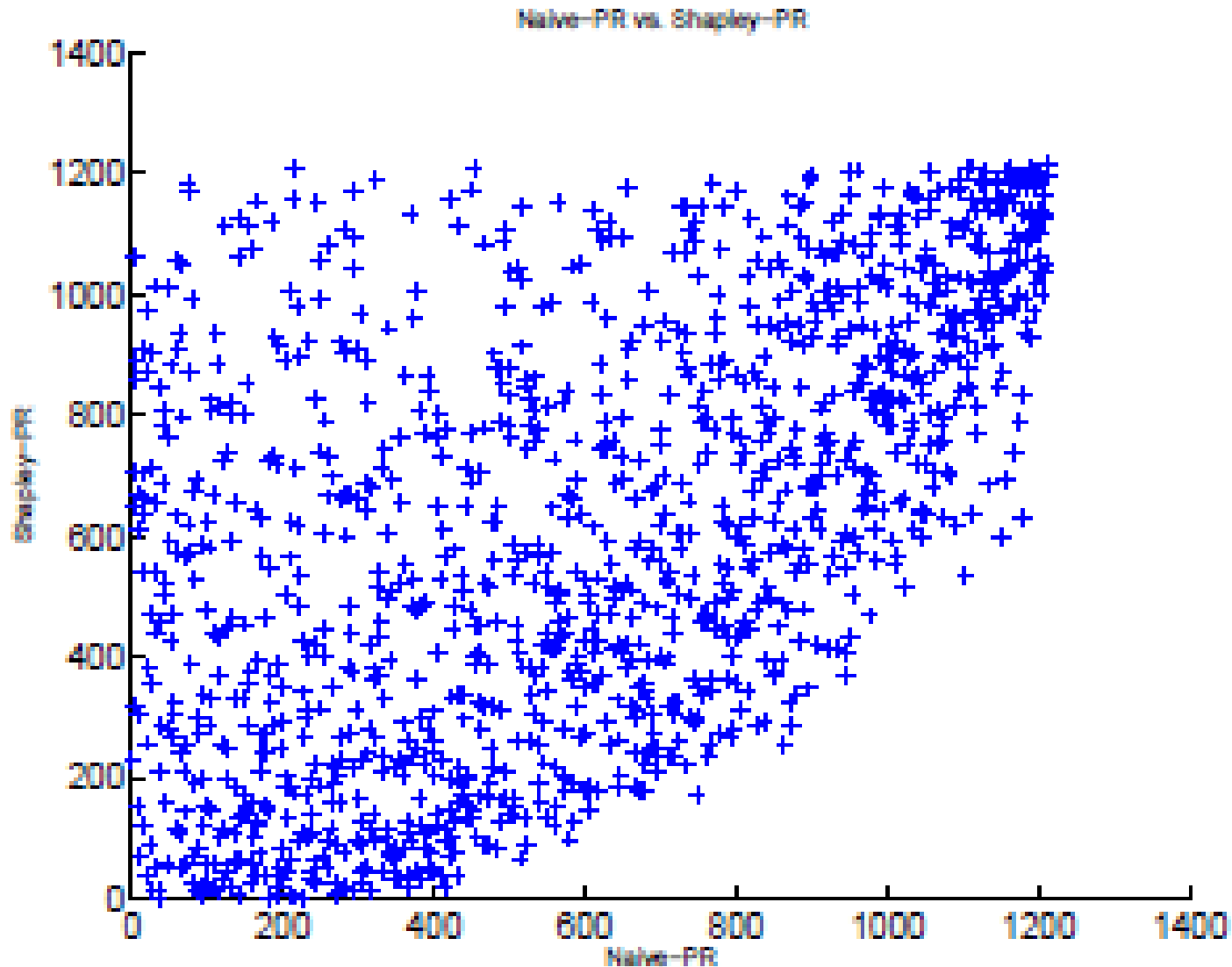
Experimental Evaluation

- Each movie is assigned with an impact score defined as follows:

$$\textit{average rating} \quad \times \quad \textit{number of people}$$

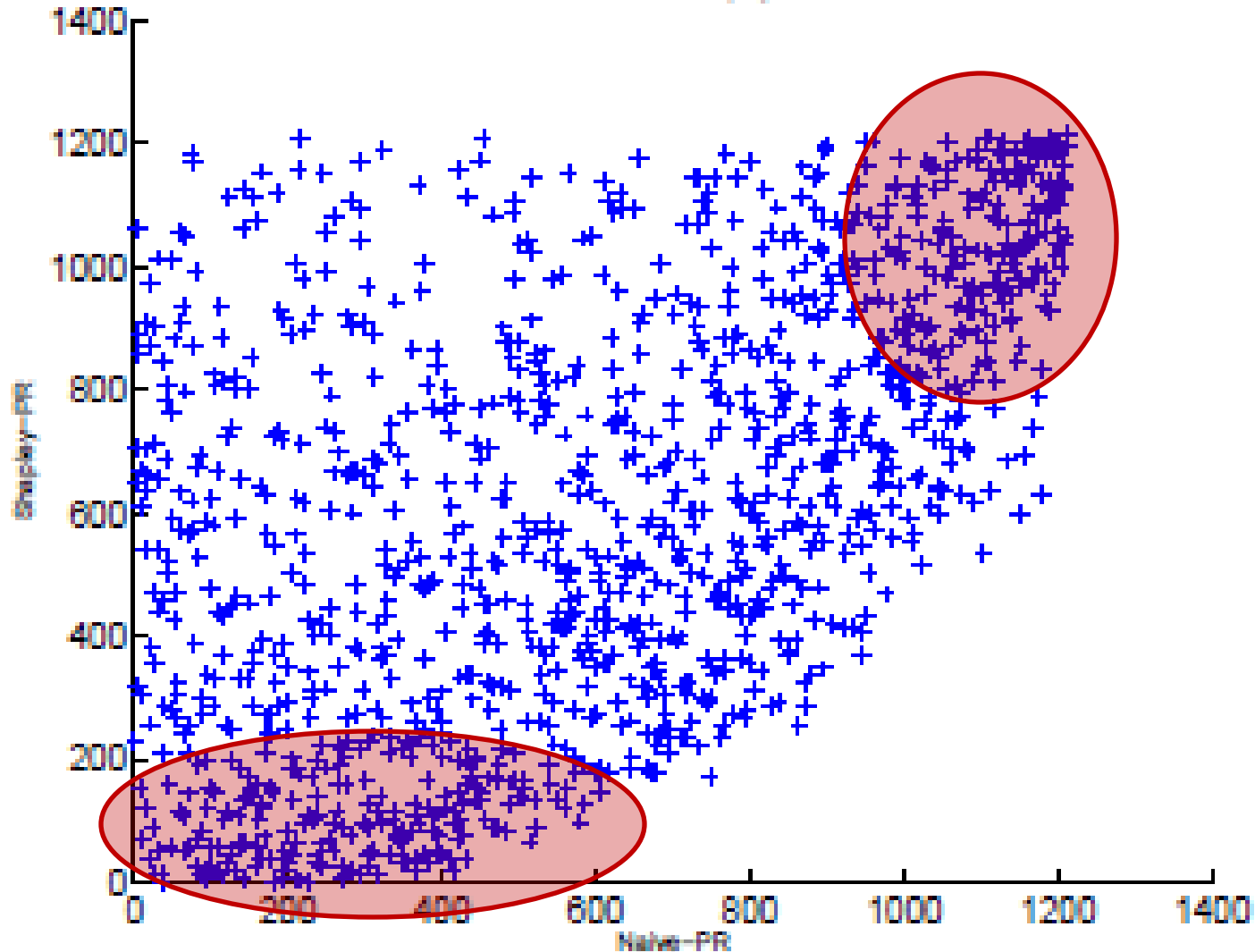
- Performance measure:
 - **Rank of an individual:** *number of individuals who are at least as influential.*

Naïve PR vs. Shapley PR



Naïve PR vs. Shapley PR

Naïve-PR vs. Shapley-PR



Experimental Evaluation

- Top-10 actors given by the Shapley method.

Actor Name	Shapley Naïve		Actor Name	Naïve Shapley	
Robert De Niro	1	3	Peter Sellers	1	14
Al Pacino	2	8	Jack Nicholson	2	11
Brad Pitt	3	15	Robert De Niro	3	1
Bruce Willis	4	7	Adam Sandler	4	59
Arnold Schwarzenegger	5	24	Daniel Day-Lewis	5	36
Will Smith	6	13	Chris Farley	6	20
Eddie Murphy	7	10	Bruce Willis	7	4
Robin Williams	8	9	Al Pacino	8	2
Morgan Freeman	9	17	Robin Williams	9	8
Ben Stiller	10	29	Eddie Murphy	10	7

Experimental Evaluation

- Examples of actors with high ranking differences between Shapley and Naïve.

Actor Name	Shapley	Naïve	# of Movies in IMDB
Jim Carrey	11	79	34
Sylvester Stallone	12	41	46
Daniel Day-Lewis	36	5	27
Adam Sandler	59	4	39

Outline

- Problem Formulation
- Proposed Solution
- Experimental Evaluation
- **Conclusions**

Conclusions

- Addressed the problem of influence attribution
- Proposed a method that employs the game theoretic concept of Shapley value.
- Methodology can be applied to real scenarios:
 - Author-publication data.
 - Movie data.
- Experiments on two domains showed that the rankings produced by the proposed method and the naïve approach of equal division of influence differ highly.

Future Work

- Investigation of other domains such as:
 - user-blogs,
 - social media sites.
- How additional information about the individuals can affect/be taken into account.
- Further evaluate the quality of the obtained rankings by performing user studies.



Appendix

The Iterative Algorithm

Algorithm 1 The Shapley Algorithm

- 1: **Input:** a set of individuals \mathcal{V} , a set of tasks \mathcal{T} , and the corresponding set of impact scores \mathcal{I} .
 - 2: **Output:** the influence score ϕ_i of each individual $V_i \in \mathcal{V}$
 - 3: // Initialization: $\forall T_i, i = 1, \dots, m$ assigned to individual V_i :
 - 4: **for** $j = 1 : |\mathcal{V}|$ **do**
 - 5: $\phi_i^0 = \sum_{i=j}^m I_j$
 - 6: **end for**
 - 7: **while** convergence **do**
 - 8: Initialize $\phi_i^{t+1}(v') = 0$
 - 9: **for** $T_j \in \mathcal{T}$ **do**
 - 10: **for** $V_i \in \mathcal{V}_{T_j}$ such that V_i is assigned with task T_j **do**
 - 11: $\phi_i^{t+1}(v') = \phi_i^{t+1}(v') + \frac{|\mathcal{V}_{T_j}|!(|\mathcal{V}|-|\mathcal{V}_{T_j}|-1)!}{|\mathcal{V}|!} (v'(\mathcal{V}_{T_j}) - v'(\mathcal{V}_{T_j} \setminus V_i))$
 - 12: **end for**
 - 13: **end for**
 - 14: **end while**
-

The Iterative Algorithm

Algorithm 1 The Shapley Algorithm

- 1: **Input:** a set of individuals \mathcal{V} , a set of tasks \mathcal{T} , and the corresponding set of impact scores \mathcal{I} .
- 2: **Output:** the influence score ϕ_i of each individual $V_i \in \mathcal{V}$
- 3: // Initialization: $\forall T_i, i = 1, \dots, m$ assigned to individual V_i :
- 4: **for** $j = 1 : |\mathcal{V}|$ **do**
- 5: $\phi_i^0 = \sum_{i=j}^m I_j$
- 6: **end for**
- 7: **while** convergence **do**
- 8: Initialize $\phi_i^{t+1}(v') = 0$
- 9: **for** $T_j \in \mathcal{T}$ **do**
- 10: **for** $V_i \in \mathcal{V}_{T_j}$ such that V_i is assigned with task T_j **do**
- 11: $\phi_i^{t+1}(v') = \phi_i^{t+1}(v') + \frac{|\mathcal{V}_{T_j}|!(|\mathcal{V}|-|\mathcal{V}_{T_j}|-1)!}{|\mathcal{V}|!} (v'(\mathcal{V}_{T_j}) - v'(\mathcal{V}_{T_j} \setminus V_i))$
- 12: **end for**
- 13: **end for**
- 14: **end while**

The Iterative Algorithm

Algorithm 1 The Shapley Algorithm

- 1: **Input:** a set of individuals \mathcal{V} , a set of tasks \mathcal{T} , and the corresponding set of impact scores \mathcal{I} .
 - 2: **Output:** the influence score ϕ_i of each individual $V_i \in \mathcal{V}$
 - 3: // Initialization: $\forall T_i, i = 1, \dots, m$ assigned to individual V_i :
 - 4: for $j = 1 : |\mathcal{V}|$ do
 - 5: $\phi_i^0 = \sum_{i=j}^m I_j$
 - 6: end for
 - 7: **while** convergence **do**
 - 8: Initialize $\phi_i^{t+1}(v') = 0$
 - 9: for $T_j \in \mathcal{T}$ do
 - 10: for $V_i \in \mathcal{V}_{T_j}$ such that V_i is assigned with task T_j do
 - 11: $\phi_i^{t+1}(v') = \phi_i^{t+1}(v') + \frac{|\mathcal{V}_{T_j}|!(|\mathcal{V}|-|\mathcal{V}_{T_j}|-1)!}{|\mathcal{V}|!} (v'(\mathcal{V}_{T_j}) - v'(\mathcal{V}_{T_j} \setminus V_i))$
 - 12: end for
 - 13: end for
 - 14: end while
-

The Iterative Algorithm

Algorithm 1 The Shapley Algorithm

```
1: Input: a set of individuals  $\mathcal{V}$ , a set of tasks  $\mathcal{T}$ , and the corresponding set of impact scores  $\mathcal{I}$ .
2: Output: the influence score  $\phi_i$  of each individual  $V_i \in \mathcal{V}$ 
3: // Initialization:  $\forall T_i, i = 1, \dots, m$  assigned to individual  $V_i$ :
4: for  $j = 1 : |\mathcal{V}|$  do
5:    $\phi_i^0 = \sum_{i=j}^m I_j$ 
6: end for
7: while convergence do
8:   Initialize  $\phi_i^{t+1}(v') = 0$ 
9:   for  $T_j \in \mathcal{T}$  do
10:    for  $V_i \in \mathcal{V}_{T_j}$  such that  $V_i$  is assigned with task  $T_j$  do
11:       $\phi_i^{t+1}(v') = \phi_i^{t+1}(v') + \frac{|\mathcal{V}_{T_j}|!(|\mathcal{V}|-|\mathcal{V}_{T_j}|-1)!}{|\mathcal{V}|!} (v'(\mathcal{V}_{T_j}) - v'(\mathcal{V}_{T_j} \setminus V_i))$ 
12:    end for
13:  end for
14: end while
```

Termination Criterion

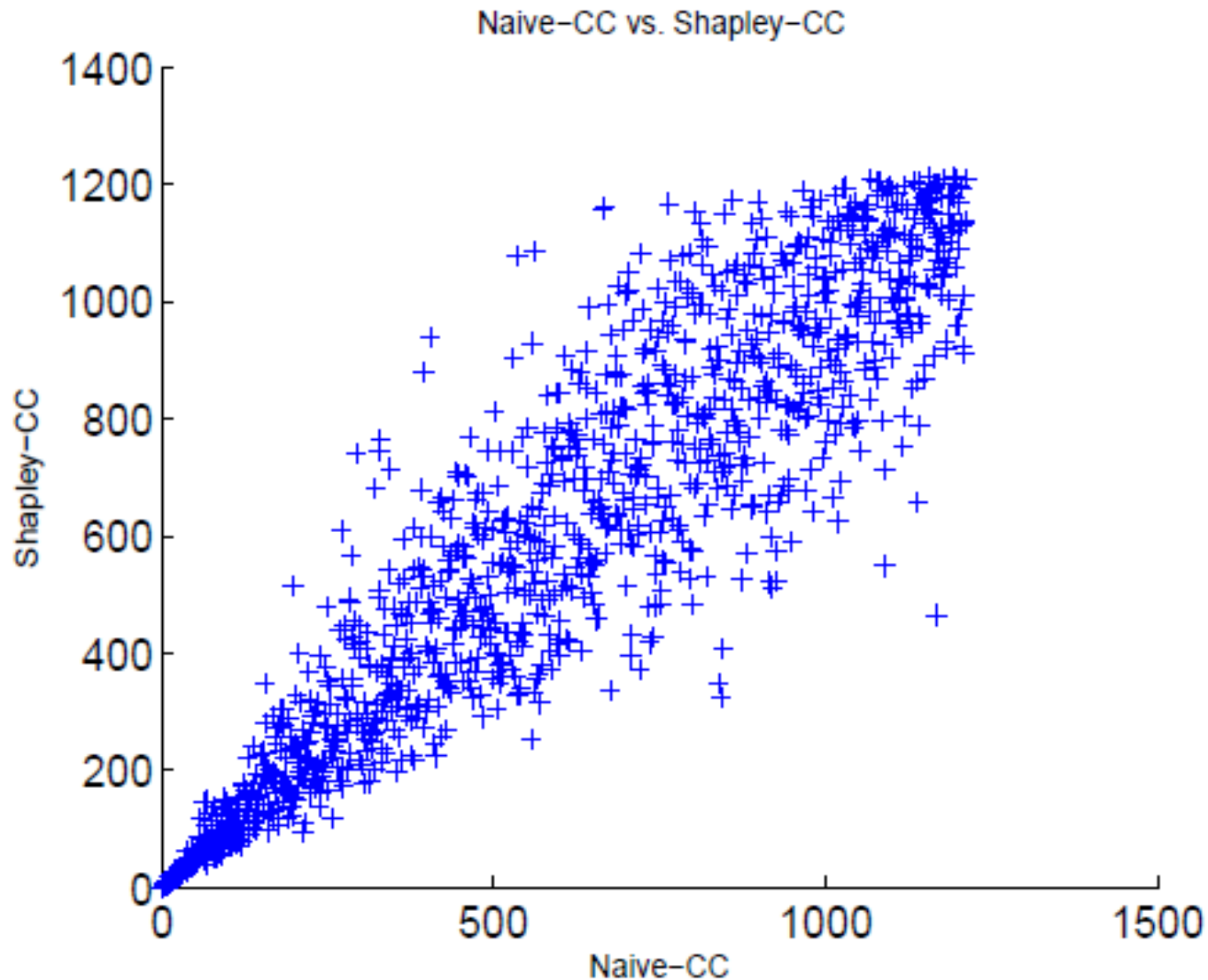
- The iterative algorithm terminates when influence scores at two consecutive iterations converge:

$$\frac{\sum_{i=1}^{|\mathcal{V}|} |\phi_i^t - \phi_i^{t-1}|}{\sum_{i=1}^{|\mathcal{V}|} \phi_i^{t-1}} \leq \epsilon \in (0, 1).$$

Enforcing Monotonicity

- Gain function should be
 - monotone, i.e., if $\mathcal{S}_1 \subseteq \mathcal{S}_2$ then $v(\mathcal{S}_1) \leq v(\mathcal{S}_2)$.
 - non-negative.
- Compute all pay-offs.
- Identify all pairs of pay-offs such that
$$\mathcal{S}_1 \subseteq \mathcal{S}_2 \text{ and } v(\mathcal{S}_1) > v(\mathcal{S}_2).$$
- Set $v(\mathcal{S}_1) = v(\mathcal{S}_2)$.
- Repeat until all violations are eliminated.

Naïve CC vs. Shapley CC



Naïve CC vs. Shapley CC

