

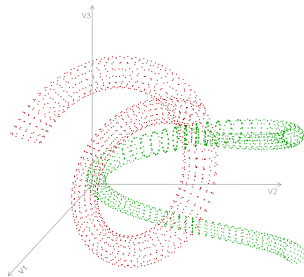
PERTURBO: a new classification algorithm based
on the spectrum perturbations of the
Laplace-Beltrami operator

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Université de Bretagne Sud

Problem and motivations

- 1 Supervised classification problem
- 2 A geometric point of view on the manifold processing
- 3 In 3 dimension problems, strong parallel with computer graphics



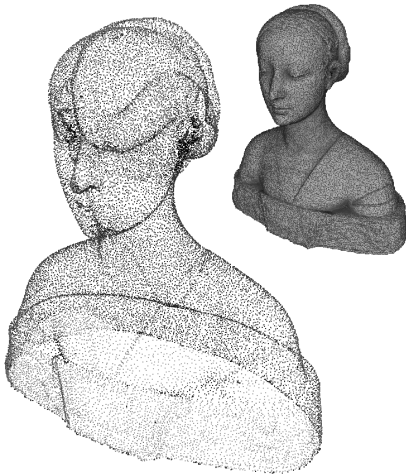
Outline

- 1 Sampling problems in computer graphics
- 2 Application to machine learning and classification
- 3 Experimental results
- 4 Future works
- 5 Conclusion

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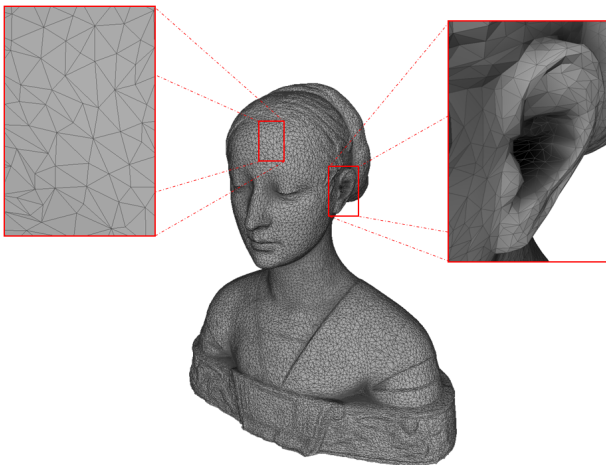
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Sampling point clouds in computer graphics



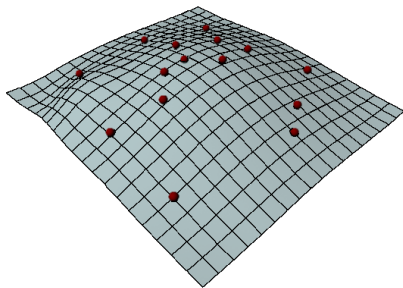
- 1 Too many points required to sample real life objects
- 2 The reduction of the number of samples leads to compact storing
- 3 Only the informative enough samples are kept

Spectral sampling



Need for metric to quantify the modification of the definition of the object surface induced by a new sample [Öztireli, Alexa & Gross, 2010].

Riemanian manifolds and the Laplace-Beltrami Operator



- 1 The surface is assumed to be a Riemannian manifold \mathcal{M} (i.e. differentiable everywhere).
- 2 The Laplace-Beltrami operator $\Delta(\cdot)$ is a generalization of the Laplace operator for Riemannian manifolds.
- 3 The spectrum of $\Delta(\mathcal{M})$ completely defines \mathcal{M} up to an isometry.

Approximating the Laplace-Beltrami operator

- 1 The surface being unknown, the computation of $\Delta(\mathcal{M})$ is impossible.
- 2 It can be approximated with the Gram matrix \mathbf{K} of the samples $\{x_1, \dots, x_i, \dots, x_N\}$, fitted with a Gaussian dissimilarity measure:

$$\mathbf{K}_{ij} = k(x_i, x_j) = \exp\left(-\frac{\|x_i - x_j\|^2}{2\sigma^2}\right) \quad (1)$$

- 3 The spectrum of \mathbf{K} is used to characterize the real object surface [Coifman & Lafon, 2006] and its perturbation is used to evaluate the interest of a sample [Öztireli, Alexa & Gross, 2010].

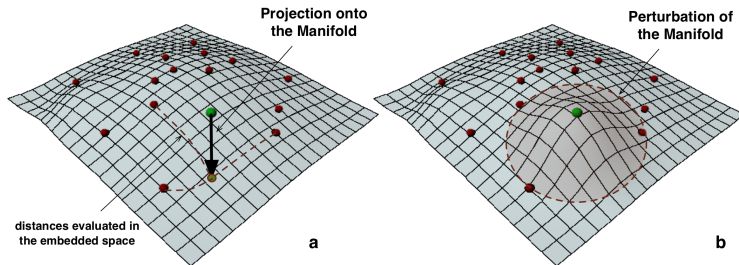
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Idea #1 : Comparing a class to a surface

The perturbation of \mathbf{K} :

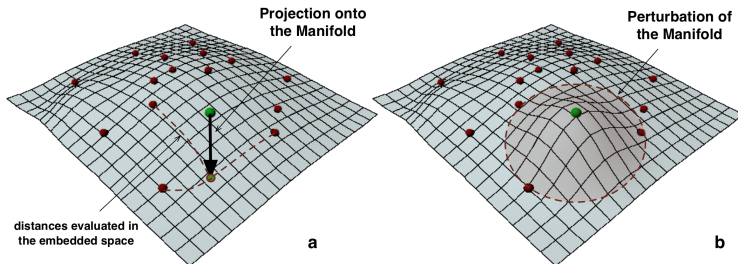
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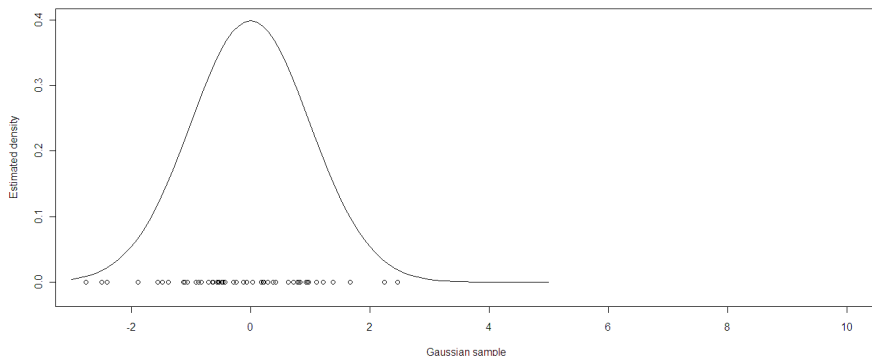
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- 2 In statistics ?



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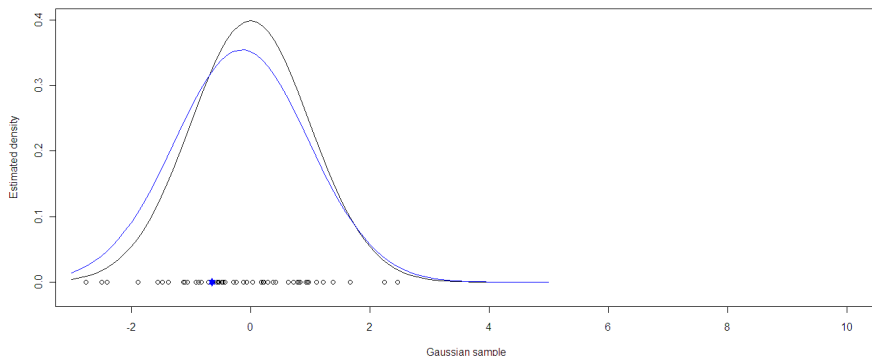
- ① In computer graphics, it quantifies the interest of a sample.
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 - ① Only an outlier modifies the distribution of its class



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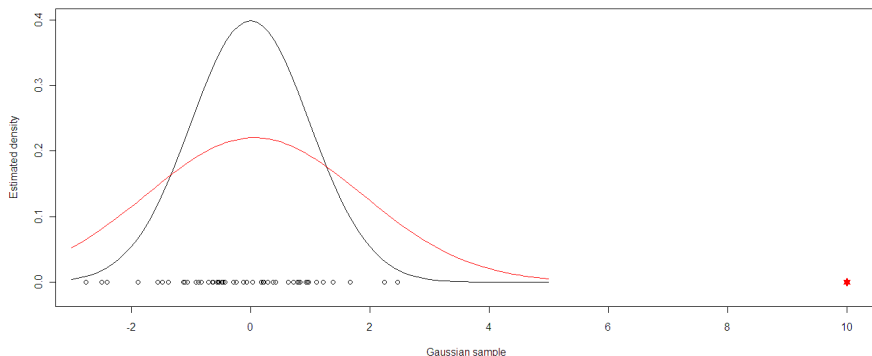
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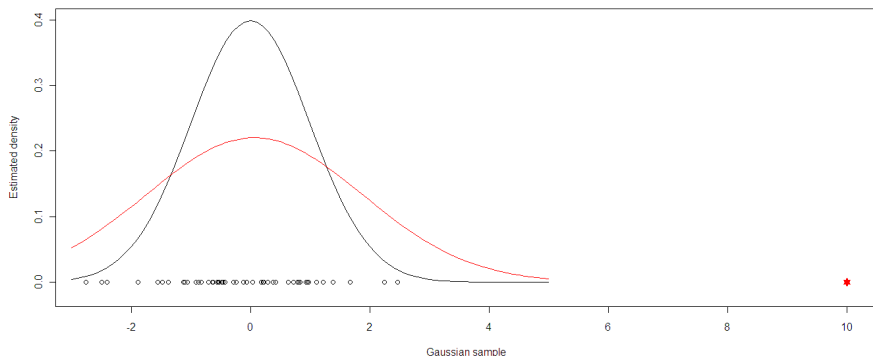
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Idea #1 : Comparing a class to a surface

The pertubation of \mathbf{K} :

- ① In computer graphics, it quantifies the interest of a sample.
- ② In statistics ?
 - ① Only an outlier modifies the distribution of its class
 - ② An interesting clue of the membership of a sample to a class !



Idea #2: Class-wise manifold learning

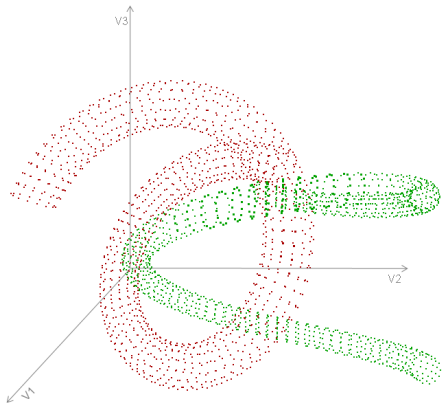


Figure: Fictive example of a 2-class problem where each class is embed in a dedicated manifold.

- 1 For each class ℓ , a dedicated manifold \mathcal{M}_ℓ is considered
- 2 All the manifold are learned independently
- 3 Each class ℓ is represented by a particular matrix \mathbf{K}_ℓ

Remarks and notations

Remarks:

- 1 \mathbf{K}_ℓ is also the classical Gram matrix in the Gaussian RKHS
- 2 The proxy for Laplace-Beltrami operator \equiv a kernel trick

Notations:

- \mathcal{X} The input space (generated by the problem variables)
- \mathcal{Z} The feature space associated to the Gaussian kernel
- $\phi()$ the mapping from \mathcal{X} onto \mathcal{Z}
- \mathcal{T}_ℓ The set of training examples for \mathcal{M}_ℓ
- \mathbf{K}_ℓ The Gram matrix of $\phi(\mathcal{T}_\ell)$ in \mathcal{Z}
- \tilde{x} A test sample in \mathcal{X}

The perturbation measure in the Gaussian RKHS (1)

Let us project $\phi(\tilde{x})$ on the manifold \mathcal{M}_ℓ in \mathcal{Z} , i.e. $\langle \phi(\mathcal{T}_\ell) \rangle$:

$$\phi(\tilde{x}) = \underbrace{r_\ell(\tilde{x})}_{\text{coplanar to } \langle \phi(\mathcal{T}_\ell) \rangle} + \underbrace{o_\ell(\tilde{x})}_{\text{orthogonal to } \langle \phi(\mathcal{T}_\ell) \rangle} \quad (2)$$

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From [Öztireli, Alexa & Gross, 2010], the perturbation of \mathbf{K}_ℓ by \tilde{x} comes from $o_\ell(\tilde{x})$. Thus, the perturbation measure reads:

$$\tau(\tilde{\mathbf{x}}, \mathcal{M}_\ell) = \frac{\|o_\ell(\tilde{x})\|^2}{\|\phi(\tilde{x})\|^2} = 1 - \frac{\|r_\ell(\tilde{x})\|^2}{\|\phi(\tilde{x})\|^2} = 1 - \|r_\ell(\tilde{x})\|^2 \quad (3)$$

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If Φ_ℓ is the matrix whose columns are the elements of $\phi(\mathcal{T}_\ell)$, then, the projector over $\langle \phi(\mathcal{T}_\ell) \rangle$ can be written as: $\Phi_\ell(\Phi_\ell^T \Phi_\ell)^{-1} \Phi_\ell^T$

The perturbation measure in the Gaussian RKHS (2)

$$\|r_\ell(\tilde{\mathbf{x}})\|^2 = \|\Phi_\ell(\Phi_\ell^T \Phi_\ell)^{-1} \Phi_\ell^T \phi(\tilde{\mathbf{x}})\|^2 \quad (4)$$

The perturbation measure in the Gaussian RKHS (2)

$$\begin{aligned} \|r_\ell(\tilde{\mathbf{x}})\|^2 &= \|\Phi_\ell(\Phi_\ell^T \Phi_\ell)^{-1} \Phi_\ell^T \phi(\tilde{\mathbf{x}})\|^2 \\ &\vdots \\ &= (\phi(\tilde{\mathbf{x}})^T \Phi_\ell) ((\Phi_\ell^T \Phi_\ell)^T)^{-1} (\Phi_\ell^T \phi(\tilde{\mathbf{x}})) \end{aligned} \quad (4)$$

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$$\begin{aligned} ||r_\ell(\tilde{\mathbf{x}})||^2 &= ||\Phi_\ell(\Phi_\ell^T \Phi_\ell)^{-1} \Phi_\ell^T \phi(\tilde{\mathbf{x}})||^2 \\ &\quad \vdots \\ &= (\phi(\tilde{\mathbf{x}})^T \Phi_\ell) \underbrace{((\Phi_\ell^T \Phi_\ell)^T)^{-1}}_{\mathbf{K}_\ell^{-1}} (\Phi_\ell^T \phi(\tilde{\mathbf{x}})) \end{aligned} \quad (4)$$

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Finally:

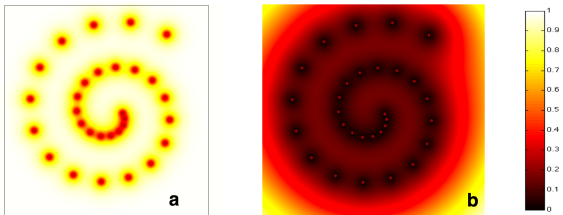
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PerTurbo: A new classification algorithm

Training step:

\forall class ℓ , \mathbf{K}_ℓ^{-1} is computed.

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- 2 The sample $\tilde{\mathbf{x}}$ is associated to the class with the least induced perturbation, which reads as:

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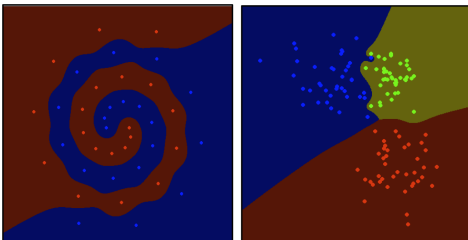
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Experimental setting and analysis of the results

Experimental setting:

- ① Several tests conducted on simulated and real datasets
[[UCI Machine Learning Repository](#)]
- ② Comparison to several algorithms (among which SVMs)
- ③ SVMs are fully optimized with cross validation
- ④ Several versions of PerTurbo are tested (see article)

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Qualitative results of PerTurbo:

- ① Performances similar to SVMs
- ② Less efficient with missing values or binary variables
- ③ Depending on the problem, the best version is not the same

Datasets

Table: Description of simulated/UCI datasets

Datasets	#Training	#Tests	#Classes	#Variables	Comments
SimData-1	200	800	10	19	64 components
SimData-2	200	800	10	26	64 components
SimData-3	200	800	10	31	75 components
Ionosphere	71	280	2	34	
diabets	154	614	2	8	missing values
Blood-transfusion	150	598	2	4	
Ecoli	67	269	8	7	too small for CV
Glasses	43	171	6	9	
Wines	36	142	3	13	
Parkinsons	39	156	2	22	
Letter-reco	4000	16000	26	16	
Hill-valley1	606	606	2	100	50% unlabeled
Hill-valley2	606	606	2	100	50% unlabeled

Accuracy rates

Table: Comparison of the accuracy rates (mean and standard deviation, in percentages) with SVM (with optimized parameters and hyper-parameters)

Datasets	PerTurbo	SVM	Comparison
SimData-1	79.0 (1.8)	76.7 (1.3)	●
SimData-2	54.7 (2.5)	45.0 (1.8)	●
SimData-3	19.7 (1.2)	16.2 (1.3)	●
Ionosphere	92.1 (1.6)	92.5 (1.8)	●
diabets	72.6 (2.2)	74.0 (1.7)	●
Blood-transfusion	76.9 (1.0)	77.6 (1.5)	●
Ecoli	83.7 (2.5)	83.2 (2.2)	●
Glass	65.4 (2.9)	60.6 (4.4)	●
Wines	72.60 (1.3)	96.1 (1.7)	●
Parkinsons	83.8 (1.3)	85.0 (3.3)	●
Letter-reco	92.7 (0.2)	91.9 (0.3)	●
Hill-valley1	60.7	56.4	●
Hill-valley2	59.9	55.3	●

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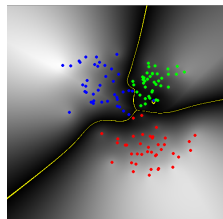
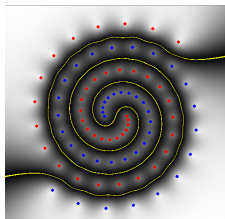
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Active Learning (1)

It is rather simple to find the borders of the classes:

$$B = \{\mathbf{x} \in \mathcal{X} \text{ s.t. } |\tau_{r(1)}(\mathbf{x}) - \tau_{r(2)}(\mathbf{x})| = 0\}$$

where $r(i)$ is the i th least perturbed class by \mathbf{x} .



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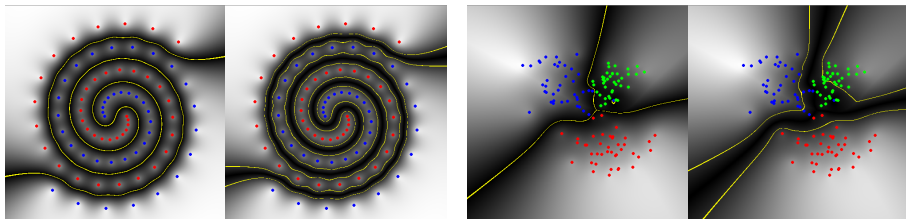
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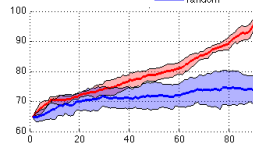
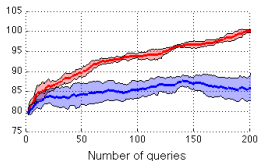
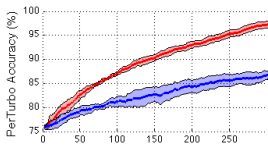
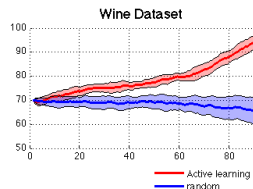
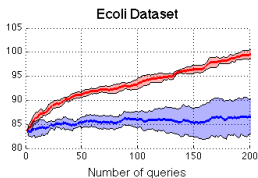
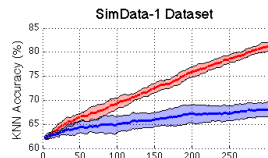
where $r(i)$ is the i th least perturbed class by \mathbf{x} . Then,

$$B' = \{\mathbf{x} \in \mathcal{X} \text{ s.t. } |\tau_{r(1)}(\mathbf{x}) - \tau_{r(2)}(\mathbf{x})| < \gamma\}$$

with $\gamma < 1$, corresponds to the region to query with an active learning policy.



Active Learning (2)



Others

Regularization:

- ① What if \mathbf{K}_ℓ is not invertible ? \Rightarrow pseudo inverse
- ② Matrix regularization

Graph Laplacian Eigenmaps, dimensionality reduction:

- ① \mathbf{K}_ℓ has the same spectrum as Graph Laplacian
- ② We provide a new “projection method” for GLE [Belkin, 2003]

Kernel Mahalanobis distance:

- ① Mahalanobis in Kernel space [Haasdonk & Pekalska, 2008]
- ② The perturbation measure is similar to some of their distances

Exhaustive study for parameter tuning:

- ① The standard deviation σ associated to the Gaussian kernel
- ② Additional parameters: Regularization, spectrum truncation...

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PerTurbo: Main results

- ① Classification algorithm inspired by computer graphics results
- ② With very few parameters to tune
- ③ Performances similar to SVM
- ④ Perspectives:
 - ① Active learning
 - ② Matrix regularization
 - ③ Manifold learning and dimensionality reduction
 - ④ Kernel Mahalanobis distance

Questions

Thank you !