

An Alternating Direction Method for Dual MAP LP Relaxation

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The MAP Problem

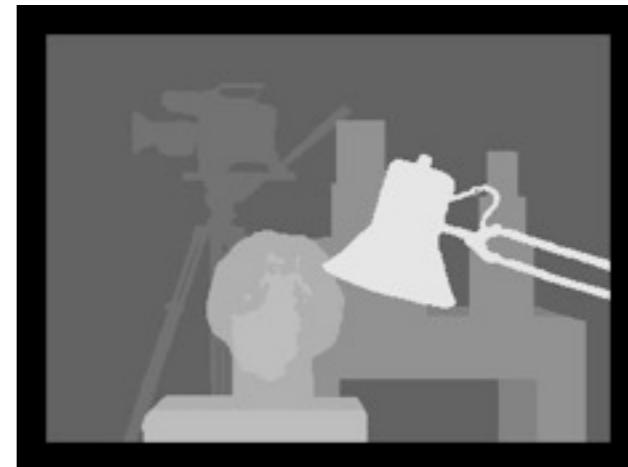
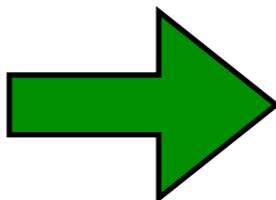
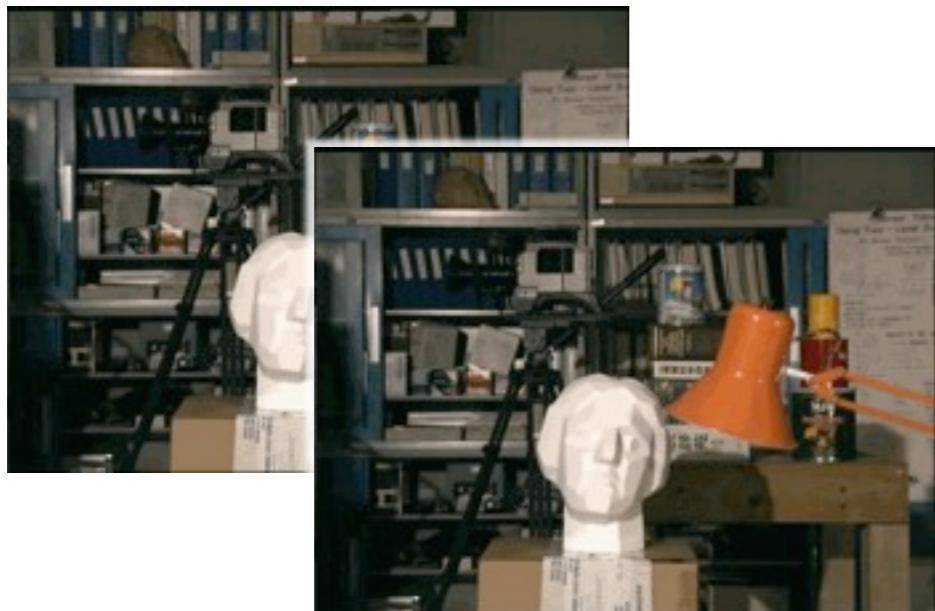
- Many machine learning tasks can be cast as finding the most probable configuration in a probabilistic graphical model.
- Applications
 - Language processing
 - Computer vision
 - Computational biology
 - Many others

The MAP Problem

- **POS tagging:** given a sentence find the part-of-speech for each word

John	hit	the	ball
Noun	Verb	Det	Noun

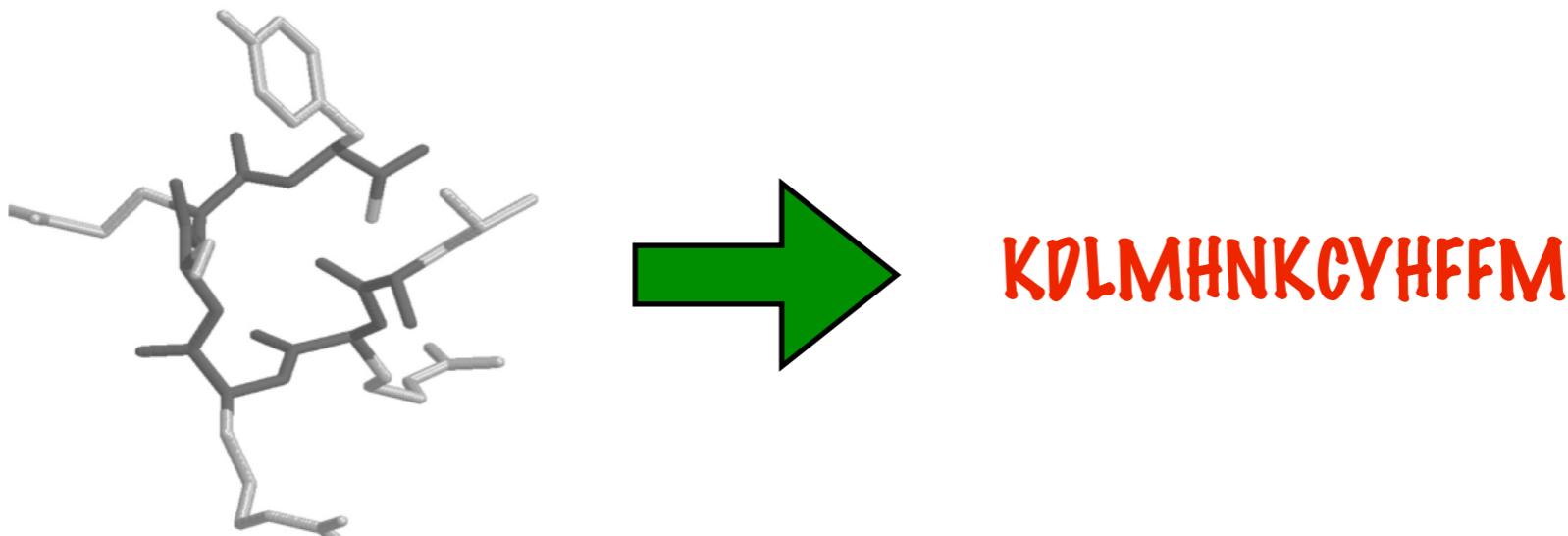
- **Stereo vision:** given left and right images, find the disparity of each pixel



[Tappen & Freeman 2003]

MAP for Protein Design

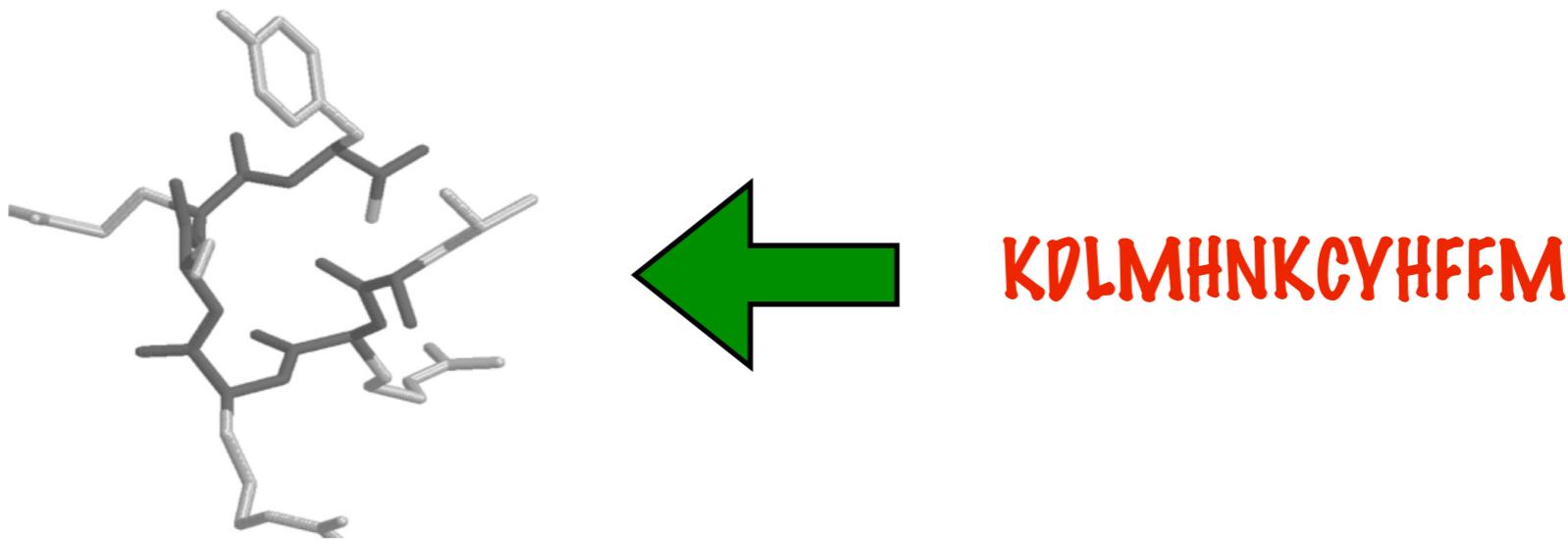
- Given 3D shape, find amino-acids with most stable structure



[Yanover et al. 2006]

MAP for Protein Design

- Given 3D shape, find amino-acids with most stable structure



- Side-chain prediction (the inverse problem): given a sequence of amino-acids find most stable 3D configuration

[Yanover et al. 2006]

The MAP Problem

- NP hard for general models
- LP relaxations often provide good approximations
- Off-the-shelf LP solvers are slow in practice due to problem size [Yanover et al. 2006]
- Several algorithms suggested, but many are either slow or not globally convergent

Our Work

- A novel algorithm for MAP with LP relaxation
- Guaranteed to globally converge
- Scalable - efficient closed-form iterative local updates
- Based on the dual linear programming relaxation
- Uses the alternating direction method of multipliers (ADMM)

The MAP Problem

- Formally:

- Discrete variables

$$X_1, \dots, X_n$$

- Markov random field (MRF)

$$p(x) \propto \exp \left(\sum_i \theta_i(x_i) + \sum_c \theta_c(x_c) \right)$$

Singleton factors **High-order factors** **pairwise factor**
 $\theta_{ij}(x_i, x_j)$

Example:

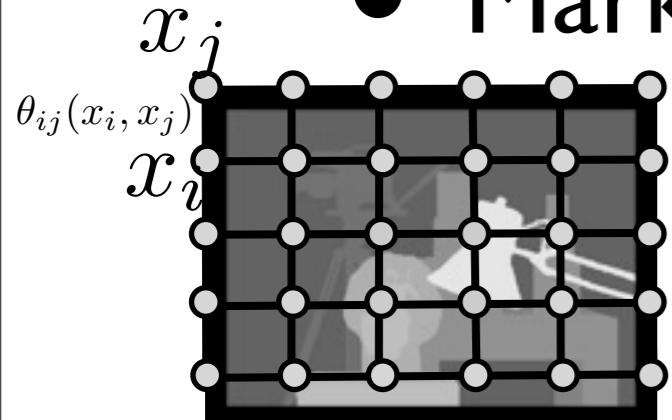
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- Markov random field (MRF)



$$p(x) \propto \exp \left(\sum_i \theta_i(x_i) + \sum_c \theta_c(x_c) \right)$$

- Find the most probable configuration
(maximum a-posteriori):

$$\arg \max_x \sum_i \theta_i(x_i) + \sum_c \theta_c(x_c)$$

MAP and LP Relaxation

- General MAP is NP-hard!
- LP relaxation

$$\begin{aligned} & \max_x \sum_i \theta_i(x_i) + \sum_c \theta_c(x_c) \\ &= \max_{\mu \in M(G)} \sum_i \sum_{x_i} \mu_i(x_i) \theta_i(x_i) + \sum_c \sum_{x_c} \mu_c(x_c) \theta_c(x_c) \\ &= \max_{\mu \in M(G)} \mu \cdot \theta \end{aligned}$$

↑
Realizable
marginal
distributions

$$\begin{aligned} \mu_i(x_i) &= p(x_i) \\ \mu_c(x_c) &= p(x_c) \end{aligned}$$

for some p

[Wainwright & Jordan 2010]

MAP and LP Relaxation

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[Wainwright & Jordan 2010]

MAP and LP Relaxation

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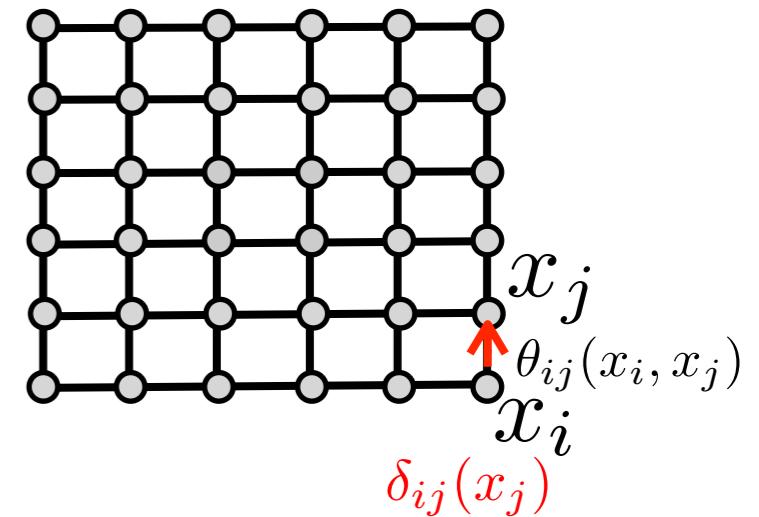
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- Tractable, BUT off-the-shelf LP solvers do poorly
[Yanover et al. 2006]

[Wainwright & Jordan 2010]

The Dual LP

- Focus on the pairwise case.
- Dual variables $\delta_{ij}(x_j)$ for each directed edge
- Define: $\bar{\theta}_{ij}(x_i, x_j) = \theta_{ij}(x_i, x_j) - \delta_{ij}(x_j) - \delta_{ji}(x_i)$
$$\bar{\theta}_i(x_i) = \theta_i(x_i) + \sum_{k \in N(i)} \delta_{ki}(x_i)$$
- Dual Objective:
$$\min_{\delta} \sum_i \max_{x_i} \bar{\theta}_i(x_i) + \sum_{ij} \max_{x_i, x_j} \bar{\theta}_{ij}(x_i, x_j)$$
- Maximum is over small elements



Dual MAP-LP

- The Lagrangian dual problem

$$\min_{\delta} \sum_i \max_{x_i} \left(\theta_i(x_i) + \sum_{c:i \in c} \delta_{ci}(x_i) \right) + \sum_c \max_{x_c} \left(\theta_c(x_c) - \sum_{i:i \in c} \delta_{ci}(x_i) \right)$$

$\bar{\theta}_i(x_i)$ $\bar{\theta}_c(x_c)$

- Two common algorithms:

[Werner 2007; Sontag et al. 2010]

Dual MAP-LP

- The Lagrangian dual problem

$$\min_{\delta} \sum_i \max_{x_i} \left(\theta_i(x_i) + \sum_{c:i \in c} \delta_{ci}(x_i) \right) + \sum_c \max_{x_c} \left(\theta_c(x_c) - \sum_{i:i \in c} \delta_{ci}(x_i) \right)$$

$\bar{\theta}_i(x_i)$ $\bar{\theta}_c(x_c)$

- Two common algorithms:

- Coordinate descent - fast but might get stuck

- [Schlesinger 1976; Werner 2007; Globerson & Jaakkola 2007]

- Subgradient - slow convergence

- [Komodakis et al. 2007]

Globally Optimal Methods

- Subgradient descent [Komodakis et al. 2007]
- Alternative solution: smooth the objective by adding local entropy terms
 - Can then apply gradient descent [Johnson 2008; Hazan & Shashua 2010]
 - Or accelerated gradient-based method [Jojic et al. 2010]. Temperature parameter might affect accuracy of the solution or cause numerical issues
- Our approach: Augmented Lagrangians

Augmented Lagrangians

- Optimization problem:

$$\begin{array}{ll}\text{minimize} & f(x) \\ \text{s.t.} & Ax = b\end{array}$$

- Equivalent (augmented) problem:

$$\begin{array}{ll}\text{minimize} & f(x) + \frac{\rho}{2} \|Ax - b\|^2 \\ \text{s.t.} & Ax = b\end{array}$$

Quadratic
smoothing

- Augmented Lagrangian:

$$\mathcal{L}_\rho(x, \nu) = f(x) + \nu^\top (Ax - b) + \frac{\rho}{2} \|Ax - b\|^2$$

[Gabay & Mercier 1976; Glowinski & Marroco 1975; Boyd et al. 2011]

Augmented Lagrangians

- Augmented Lagrangian:

$$\mathcal{L}_\rho(x, \nu) = f(x) + \nu^\top (Ax - b) + \frac{\rho}{2} \|Ax - b\|^2$$

- Dual problem:

$$\max_{\nu} \min_x \mathcal{L}_\rho(x, \nu)$$

- Dual Subgradient ascent:

$$\nu_{t+1} = \nu_t + \epsilon(Ax_{t+1} - b)$$

$$x_{t+1} = \arg \max_x \mathcal{L}_\rho(x, \nu_t)$$

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Natural step size

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Natural step size

$$x_{t+1} = \arg \max_x \mathcal{L}_\rho(x, \nu_t)$$

↑
Costly

Decomposable Objectives

- Optimization problem

$$\text{minimize } f(x) + g(z) \text{ s.t. } Ax = z$$

$$+ \underbrace{\frac{\rho}{2}}_{\text{Quadratic smoothing}} \|Ax - z\|^2$$

- Augmented Lagrangian

$$\mathcal{L}_\rho(x, z, \nu) = f(x) + g(z) + \nu^\top(Ax - z) + \frac{\rho}{2} \|Ax - z\|^2$$

- ADMM updates

$$\nu^{t+1} = \nu^t + \rho(Ax^{t+1} - z^{t+1})$$

$$x^{t+1}, z^{t+1} = \arg \min_{x, z} \mathcal{L}_\rho(x, z, \nu^t)$$

[Gabay & Mercier 1976; Glowinski & Marroco 1975; Boyd et al. 2011]

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*Don't want to
optimize jointly!*

[Gabay & Mercier 1976; Glowinski & Marroco 1975; Boyd et al. 2011]

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$$z^{t+1} = \arg \min_z \mathcal{L}_\rho(x^{t+1}, z, \nu^t)$$

[Gabay & Mercier 1976; Glowinski & Marroco 1975; Boyd et al. 2011]

ADMM for MAP-LP

- Martins et al. [2011] apply ADMM to the *primal* MAP-LP

$$\max_{\mu \in L(G)} \mu \cdot \theta$$

- Does not handle non-pairwise non-binary models (only through binarization)
- Our approach: apply ADMM to the *dual* MAP-LP
 - Handles non-pairwise non-binary models directly

The Augmented Dual LP Algorithm

$$\min_{\delta} \sum_i \max_{x_i} \left(\theta_i(x_i) + \sum_{c:i \in c} \delta_{ci}(x_i) \right) + \sum_c \max_{x_c} \left(\theta_c(x_c) - \sum_{i:i \in c} \delta_{ci}(x_i) \right)$$

- Can now apply ADMM!
- Properties:
 - Efficient updates
 - Convergence guarantee
 - $O(1/\varepsilon^2)$ time in worst case, but fast in practice

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$$\text{s.t. } \lambda_c(x_c) = \sum_{i:i \in c} \delta_{ci}(x_i) \quad \forall c, x_c$$

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$$\text{s.t. } \lambda_c(x_c) = \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \quad \forall c, x_c$$

$$\text{s.t. } \delta_{ci}(x_i) = \bar{\delta}_{ci}(x_i) \quad \forall c, i, x_i$$

- Can now apply ADMM!

- Properties:

- Efficient updates

- Convergence guarantee

- $O(1/\epsilon^2)$ time in worst case, but fast in practice

$$A\bar{\delta} = \begin{pmatrix} \delta \\ \lambda \end{pmatrix}$$

0 + g(\delta, \lambda)

$$\min f(x) + g(z) \quad \text{s.t.} \quad Ax = z$$

$$x = \bar{\delta} \quad , \quad z = \begin{bmatrix} \delta \\ \lambda \end{bmatrix}$$

Updates

Updates

- Example: the λ update

$$\min_{\lambda_c} \max_{x_c} (\theta_c(x_c) - \lambda_c(x_c)) + \sum_{x_c} \mu_c(x_c) \lambda_c(x_c) + \frac{\rho}{2} \sum_{x_c} \left(\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \right)^2$$

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- Requires solving a QP

$$\min_x \frac{1}{2} \|x\|^2 - v^\top x + \frac{1}{\rho} \max_i(x_i)$$

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- Can be done efficiently via partitioning ($O(n)$ in expectation)

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ADLP Algorithm

Algorithm 1 The Augmented Dual LP Algorithm (ADLP)

for $t = 1$ to T **do**

Update δ : for all $i = 1, \dots, n$

$$\text{Set } \bar{\theta}_i = \theta_i + \sum_{c:i \in c} (\bar{\delta}_{ci} - \frac{1}{\rho} \gamma_{ci})$$

$$\bar{\theta}'_i = \text{TRIM}(\bar{\theta}_i, \frac{|N(i)|}{\rho})$$

$$q = (\bar{\theta}_i - \bar{\theta}'_i) / |N(i)|$$

$$\text{Update } \delta_{ci} = \bar{\delta}_{ci} - \frac{1}{\rho} \gamma_{ci} - q \quad \forall c : i \in c$$

Update λ : for all $c \in C$

$$\text{Set } \bar{\theta}_c = \theta_c - \sum_{i:i \in c} \bar{\delta}_{ci} + \frac{1}{\rho} \mu_c$$

$$\bar{\theta}'_c = \text{TRIM}(\bar{\theta}_c, \frac{1}{\rho})$$

$$\text{Update } \lambda_c = \theta_c - \bar{\theta}'_c$$

Update $\bar{\delta}$: for all $c \in C, i : i \in c, x_i$

$$\text{Set } v_{ci}(x_i) = \delta_{ci}(x_i) + \frac{1}{\rho} \gamma_{ci}(x_i) + \sum_{x_{c \setminus i}} \lambda_c(x_{c \setminus i}, x_i) + \frac{1}{\rho} \sum_{x_{c \setminus i}} \mu_c(x_{c \setminus i}, x_i)$$

$$\bar{v}_c = \frac{1}{1 + \sum_{k:k \in c} |X_{c \setminus k}|} \sum_{k:k \in c} |X_{c \setminus k}| \sum_{x_k} v_{ck}(x_k)$$

$$\text{Update } \bar{\delta}_{ci}(x_i) = \frac{1}{1 + |X_{c \setminus i}|} \left[v_{ci}(x_i) - \sum_{j:j \in c, j \neq i} |X_{c \setminus \{i,j\}}| \left(\sum_{x_j} v_{cj}(x_j) - \bar{v}_c \right) \right]$$

Update the multipliers:

$$\gamma_{ci}(x_i) \leftarrow \gamma_{ci}(x_i) + \rho (\delta_{ci}(x_i) - \bar{\delta}_{ci}(x_i)) \quad \text{for all } c \in C, i : i \in c, x_i$$

$$\mu_c(x_c) \leftarrow \mu_c(x_c) + \rho (\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i)) \quad \text{for all } c \in C, x_c$$

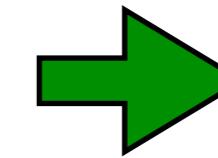
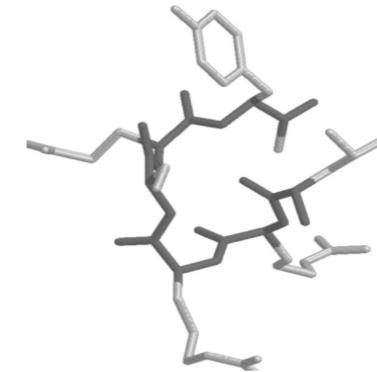
end for

Experiments

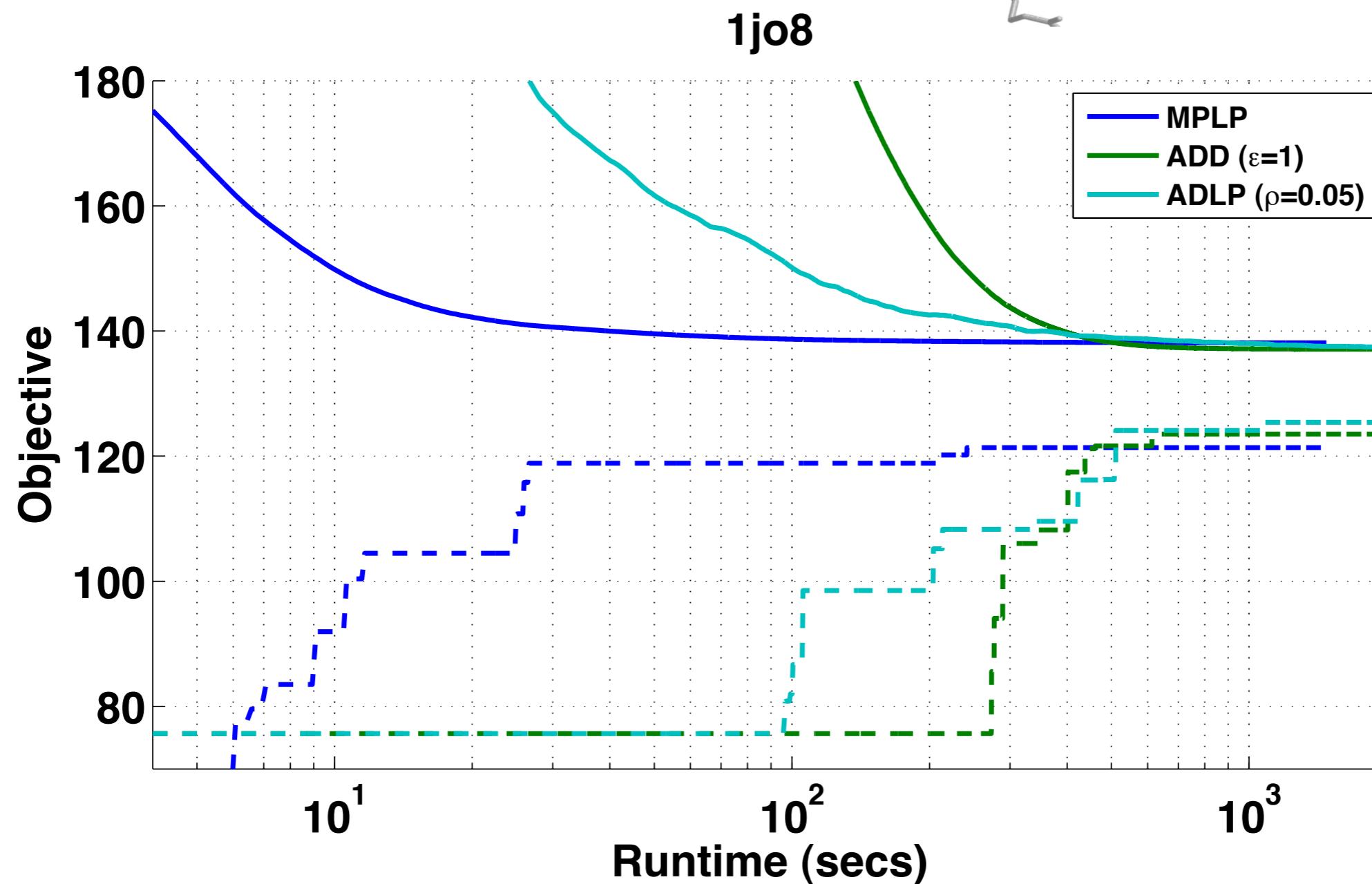
- Compared algorithms
 - Block coordinate descent (**MPLP**)
[Globerson & Jaakkola 2007]
 - Accelerated Dual Decomposition (**ADD**)
[Jojic et al. 2010]
 - Our Augmented Dual LP algorithm (**ADLP**)

Experiments

- Protein design problem

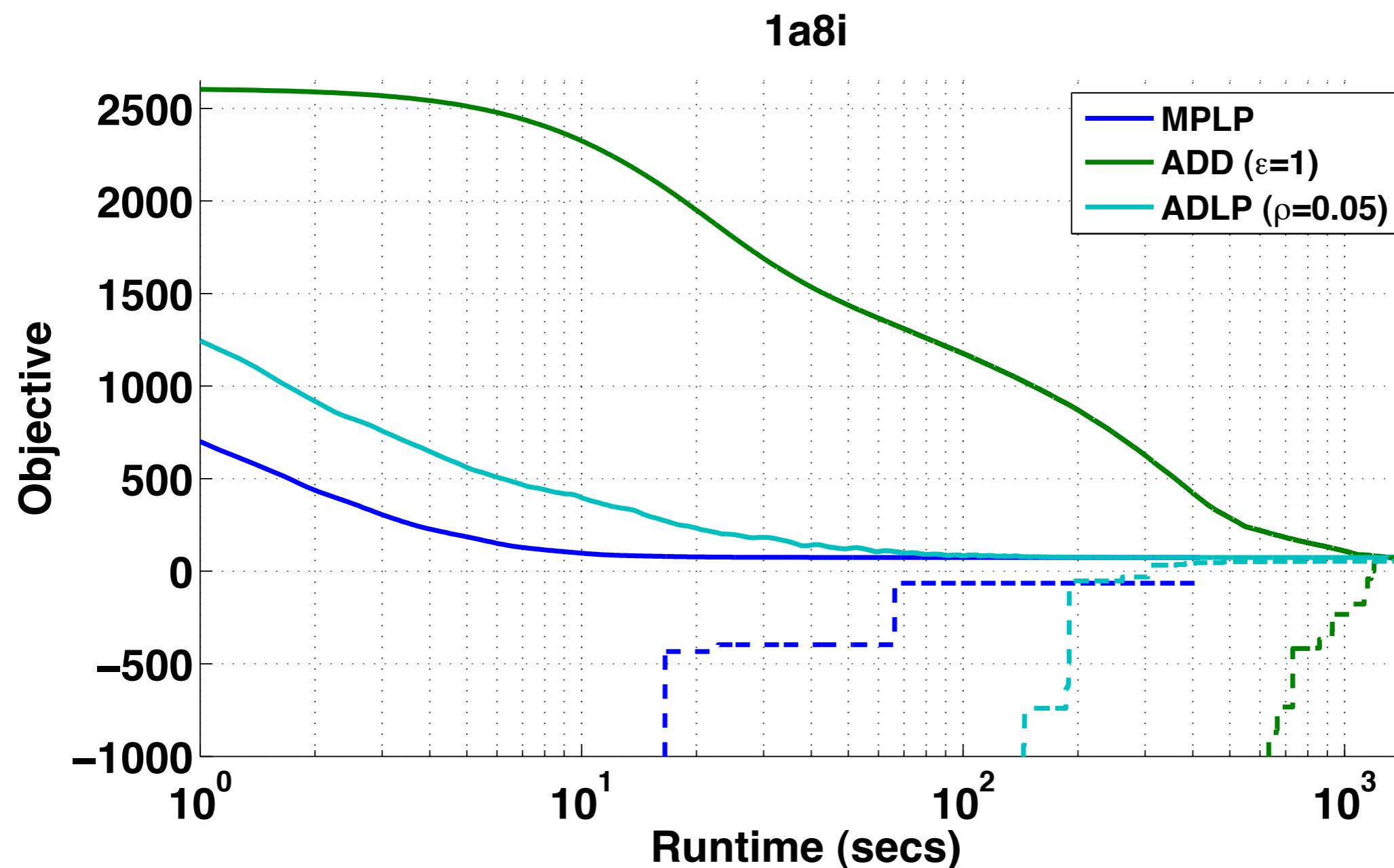


KDLMHNKCYHFFM



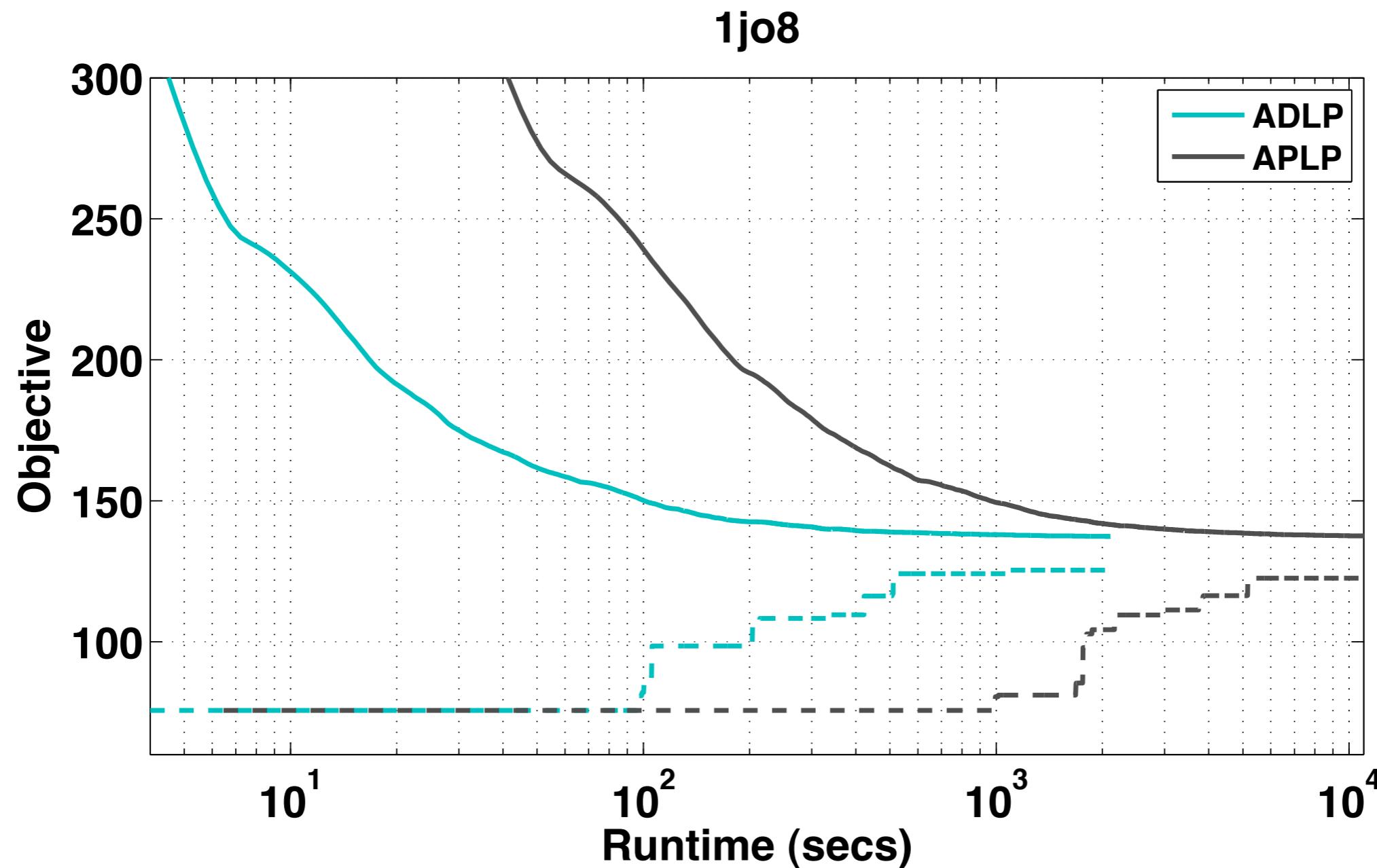
Experiments

- Side chain prediction (inverse problem)



Experiments

- Protein design: primal vs. dual ADMM
(our primal ADMM variant handles high-order non-binary factors directly)



Summary

- A novel algorithm for MAP-LP based on applying ADMM to the dual LP
- Efficient closed-form updates
- Provably converges to the approximate optimum
- Empirically effective

Thank you!

The Augmented Lagrangian

$$\mathcal{L}_\rho(\delta, \lambda, \bar{\delta}, \gamma, \mu) =$$

$$\begin{aligned} & \sum_i \max_{x_i} \left(\theta_i(x_i) + \sum_{c:i \in c} \delta_{ci}(x_i) \right) + \sum_c \max_{x_c} (\theta_c(x_c) - \lambda_c(x_c)) \\ & + \sum_c \sum_{x_c} \mu_c(x_c) \left(\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \right) + \frac{\rho}{2} \sum_c \sum_{x_c} \left(\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \right)^2 \\ & + \sum_c \sum_{i:i \in c} \sum_{x_i} \gamma_{ci}(x_i) (\delta_{ci}(x_i) - \bar{\delta}_{ci}(x_i)) + \frac{\rho}{2} \sum_c \sum_{i:i \in c} \sum_{x_i} (\delta_{ci}(x_i) - \bar{\delta}_{ci}(x_i))^2 \end{aligned}$$

Updates

- The λ update

$$\min_{\lambda_c} \max_{x_c} (\theta_c(x_c) - \lambda_c(x_c)) + \sum_{x_c} \mu_c(x_c) \lambda_c(x_c) + \frac{\rho}{2} \sum_{x_c} \left(\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \right)^2$$

- The δ update

$$\min_{\delta_i} \max_{x_i} \left(\theta_i(x_i) + \sum_{c:i \in c} \delta_{ci}(x_i) \right) + \sum_{c:i \in c} \sum_{x_i} \gamma_{ci}(x_i) \delta_{ci}(x_i) + \frac{\rho}{2} \sum_{c:i \in c} \sum_{x_i} (\delta_{ci}(x_i) - \bar{\delta}_{ci}(x_i))^2$$

- The $\bar{\delta}$ update

$$\begin{aligned} & - \sum_{i:i \in c} \sum_{x_i} \gamma_{ci}(x_i) \bar{\delta}_{ci}(x_i) + \frac{\rho}{2} \sum_{i:i \in c} \sum_{x_i} (\delta_{ci}(x_i) - \bar{\delta}_{ci}(x_i))^2 \\ & - \sum_{x_c} \mu_c(x_c) \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) + \frac{\rho}{2} \sum_{x_c} \left(\lambda_c(x_c) - \sum_{i:i \in c} \bar{\delta}_{ci}(x_i) \right)^2 \end{aligned}$$