

Data-Dependent Geometries and Structures : Analyses and Algorithms for Machine Learning

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29th March 2012

What is a “*data-dependent geometry*”?

Standard paradigm

- A dataset is sampled from a space with a **given** geometry
- the “distances” between particular points is **independent** of the sample

Data-dependent paradigm

- A dataset is sampled from a space with an **unknown** geometry
- Hence the “distances” between particular points is **dependent** on the sample
- **Implication:** We need to learn the “geometry” (Assumptions Needed!)

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Consider the following dataset of a new stories

News stories (Source, Headline)

- 1 (*Financial Times*, Research and Development in Fusion increased by 60% Last Quarter)
- 2 (*St. Petersburg Gazetteer*, Major layoffs expected in tourism sector)
- 3 (*The Times*, Super-Tanker founders on Florida coast. Largest spill of the millennium.)

Observation

Knowing “3” suggests the distance from “1” and “2” be reduced

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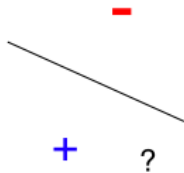
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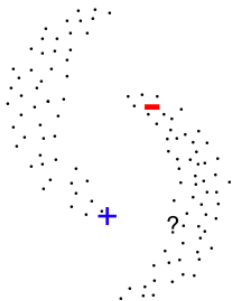
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Illustration



Illustration



Topics

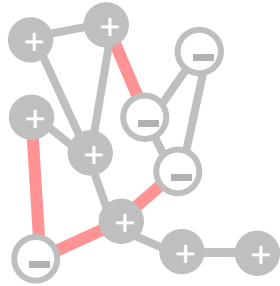
- Graph-based semi-supervised learning
 - Laplacian-based methods (Data dependent kernels)
 - Tree approximations (online mistake bounds)
 - Link classification (Active learning)
 - Fast algorithms (Bayesian Marginalisation)
- Exploiting the structure of an unknown data-generating distribution
 - Localized Pac-Bayes analysis

Resources Allocated

Resources

Activity	duration	cost
Guy Lever RA (UCL)	5 months	€23K
Fabio Vitale RA (Insubria)	9 months	€19K
Travel and subsistence	—	€3K
Total:	—	€45K

- 1 N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. A correlation clustering approach to link classification in signed networks., *Submitted*, 2012.
- 2 N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. See the tree through the lines: the shazoo algorithm., *NIPS*, 2012.
- 3 M. Herbster. A triangle inequality for p -resistance., *NIPS Workshop: Networks Across Disciplines: Theory and Applications*, 2010.
- 4 M. Herbster, S. Pasteris, and F. Vitale. Efficient prediction for tree markov random fields in a streaming model., *NIPS Workshop on Discrete Optimization in Machine Learning*, 2011.
- 5 G. Lever, T. Diethe, and J. Shawe-Taylor. Data dependent kernels in nearly-linear time., *AISTATS*, 2012.
- 6 G. Lever, F. Laviolette, and J. Shawe-Taylor. Tighter pac-bayes bounds through distribution-dependent priors., *Theoretical Computer Science (To appear)*, 2012.



Main Insubria activities

- **Vertex classification on weighted graphs**

N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. See the tree through the lines: the shazoo algorithm. In Proc. of 25th NIPS, 2012.

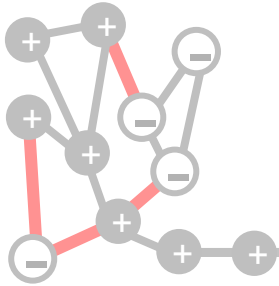
- **Link classification on unweighted graphs**

N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. A correlation clustering approach to link classification in signed networks. Submitted, 2012.

- **Main issues:**

- Construction of meaningful and natural **complexity measures**
- Accuracy guarantees / **optimality**
- **Scalability**
- **Practical utility**

- **Performance measure (analysis):** number of prediction mistakes



Vertex Classification

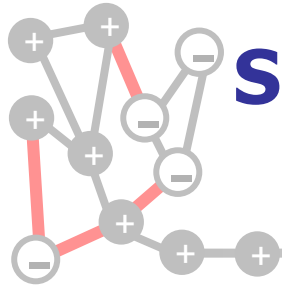
The Shazoo algorithm

- **Learning on graphs/trees domains:** hyperlinked webpages, social networks, co-author networks, biological networks, ...
- **Our learning problem: Vertex classification** of weighted, connected and undirected **trees (and graphs)** based only on **graph topology**
- We focus on **binary labeling**
- **Bias: strongly connected nodes \longrightarrow same label**
Weight cut-edges **small**

The Shazoo algorithm [Cesa-Bianchi et al. NIPS 2012]: **input = weighted trees T**
(if the input is a graph G we can run Shazoo on a **spanning tree** T of G)

- **Shazoo (1) partitions** T into components (satisfying some properties), **(2)** uses **mincut** for estimating the labels of the component **border** vertices, **(3)** uses a **NN method** for predicting the required label

N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. See the tree through the lines: the shazoo algorithm. In Proc. of 25th NIPS, 2012.



Shazoo Algorithm: Analysis, implementation and computational complexity

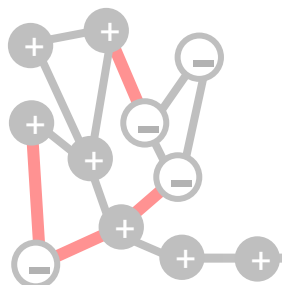
Accuracy: **#mistakes** of Shazoo is **optimal** (up to log factors)

Implementation: **simple and fast recursive method** (based on sum-product algorithm) for using the mincut strategy

Time complexity: 

- **On line protocol:** Worst case time per prediction: **$O(\#vertices)$** (rarely encountered in practice)
- **Batch protocol** (vertices are split into training and test sets) :
Worst case time for predicting **all** labels of the test set: **$O(\#vertices)$**

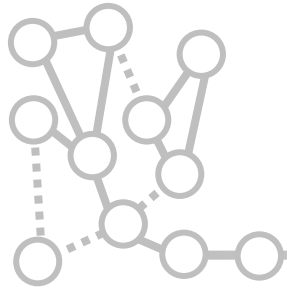
Space complexity: **Linear in #vertices**



Shazoo algorithm Experiments

- **Real-world weighted graphs:** web spam detection, character recognition, text categorization and bioinformatics
- **Competitors:** **LABPROP** (label propagation algorithm), **OMV** (label majority vote of adjacent nodes) and **WTA** (Weighted Tree Algorithm)
- **We used **spanning trees**** generated in different ways **for running Shazoo (and WTA)**
- **Experiment protocol:** **batch** (training set size = **5%**, **10%** and **25%**)
- **Main results:**
 - **Shazoo outperforms WTA and OMV on all datasets**
(unlike **WTA** it **explicitly exploits the tree structure**)
 - Aggregating prediction of committees of random spanning trees via majority vote, **Shazoo outperforms LABPROP** when the training set size is small

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Link classification

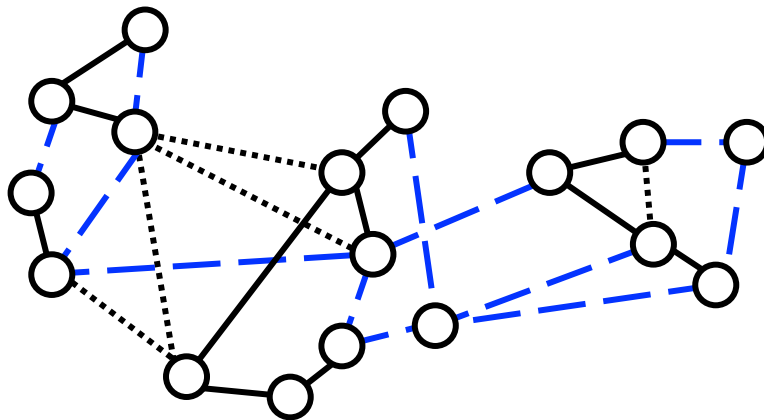
Protocol: Active Learning (focus)

Negative edges in real world networks:

Disapproval or distrust in social networks, negative endorsements on the Web, inhibitory interactions in biological networks, sentiment between two individuals for recommender systems

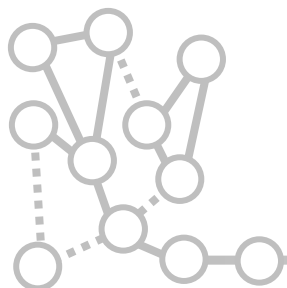
Active learning protocol

- Learner selects a set $TrSet$ of edges (training set)
- All labels of the edges of $TrSet$ are revealed
- Learner predicts the labels of all remaining edges



- Edge label +1 → similarity
- Edge label -1 → dissimilarity
- - - - Hidden label

N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. A correlation clustering approach to link classification in signed networks. Submitted, 2012.



Active link classification

Main results

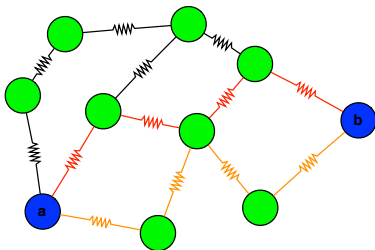
- For this problem we studied a meaningful and natural **complexity measure** related to a notion of cutsize induced by Correlation Clustering
- **Accuracy guarantees:** We devised an algorithm **optimal** up to a $O(\rho^{3/2} \sqrt{|V|})$ factor on any labeled graph $\mathbf{G}(\mathbf{V}, \mathbf{E})$, while the test set size is not smaller than $\frac{1}{\rho}$ times the training test size
- **Scalability:** Our algorithm requires an amortized time per prediction equal to $O\left(\sqrt{\frac{|V|}{\rho}} \log |V|\right)$
- Research directions:
 - Use **randomization** against adversarial label assignment
 - Test our algorithm on real-world graphs drawn from different domains: social networks (Epinions, Slashdot), movie rating datasets (Movielens) and other web datasets (political election datasets, ...)

N. Cesa-Bianchi, C. Gentile, F. Vitale, and G. Zappella. A correlation clustering approach to link classification in signed networks. Submitted, 2012.

- Exploiting the structure of a graph (resistance metric)
- Fast online algorithms for labeling a graph
- ① A triangle inequality for p -resistance.
 - p -resistance generalises the effective resistance of a network
 - Laplacian and Mincut methods popular, p -resistance for SSL generalises both
 - Fundamental inequality for p -resistance
 - Geometric insight given for k -center clustering
- ② Efficient prediction for tree markov random fields in a streaming model
 - **Exponential** speedup for online tree MRF vertex marginalization
 - Computational complexity – characterised by a particular hierarchal covering of a tree

A triangle inequality for p -resistance (1)

- 1 Identify a graph with a network of resistors



- 2 **Definition:** The (effective) p -resistance from a and b is

$$r_p(a, b) = \left[\min_{\mathbf{u} \in \mathbb{R}^n} \left\{ \sum_{(i,j) \in E(\mathbf{G})} \frac{|u_i - u_j|^p}{\pi_{ij}} : u_a = 1, u_b = 0 \right\} \right]^{-1}$$

- 3 p -Resistance trades off geodesic distance and connectivity

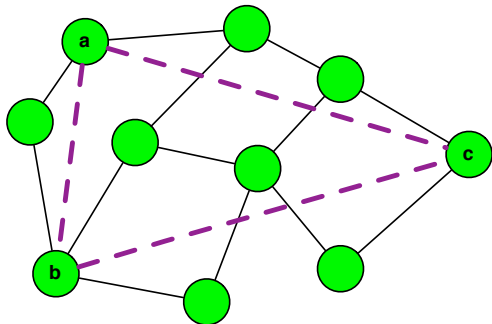
- 4 Resistors in parallel

- 4 Resistors in series

$$r_p^{\text{par}}(a, b) = \left(\sum_{i=1}^n \frac{1}{\pi_i} \right)^{-1}$$

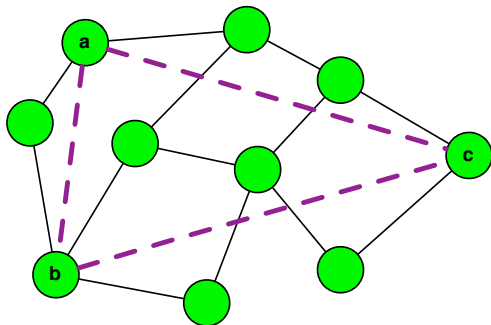
$$r_p^{\text{ser}}(a, b) = \left(\sum_{i=1}^n \pi_i^{\frac{1}{p-1}} \right)^{p-1}$$

A triangle inequality for p-resistance (2)



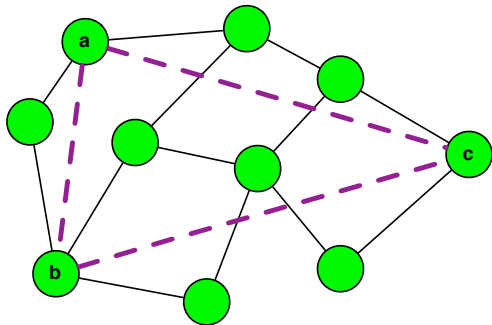
- 1 Electric Network ($p = 2$): $r_2(a, c) \leq r_2(a, b) + r_2(b, c)$
- 2 Pipe Network ($p = 1$): $r_1(a, c) \leq \max(r_1(a, b), r_1(b, c))$
- 3 Generic $p \in (1, \infty)$: $r_p(a, c) \leq \left(r_p(a, b)^{\frac{1}{p-1}} + r_p(b, c)^{\frac{1}{p-1}} \right)^{p-1}$

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A triangle inequality for p -resistance (3)

Application: k -center clustering

Objective:

$$\min_{v_1^*, \dots, v_k^* \in V} \max_{v \in V} \min_{i \in \mathbb{N}_k} d(v, v_i^*).$$

Farthest first algorithm

Input: A set $V = v_1, \dots, v_n$, a $k \in \mathbb{N}$, and a metric $d(V, V) \rightarrow \mathbb{R}$

Initialization: $\tilde{v}_1 = v_1$

for $t = 2, \dots, k$ **do**

$$\tilde{v}_t = \operatorname{argmax}_{v \in V} \min_{i \in \mathbb{N}_{t-1}} d(v, \tilde{v}_i)$$

end for

return $\{\tilde{v}_1, \dots, \tilde{v}_k\}$

Theorem

Given a graph \mathcal{G} the farthest first algorithm gives a 2^{p-1} -opt k -center clustering with respect to the p -resistance for $p > 1$.

Efficient prediction for tree markov random fields (1)

Model

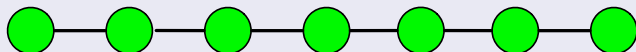
Given a tree-structured MRF at time $t = 1, 2, \dots$

Actions:

- i) predict a label at a vertex on the tree*
- ii) update by associating a label with a vertex*
- iii) delete the label at a vertex.*

Problem

Problem: Online belief propagation is *slow* — **linear** on a tree.

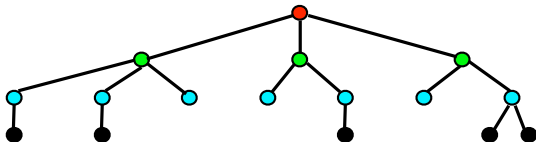
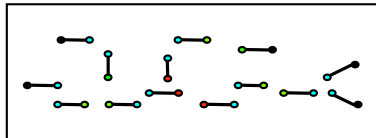
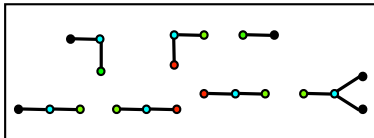
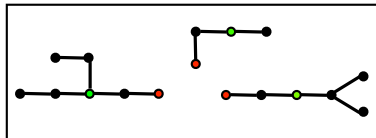
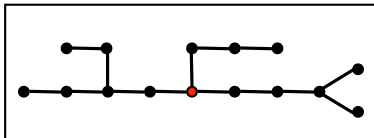


Solution: We construct a (*decomposition*) tree on the original

Result: D-propagation is **fast** on a tree.

Efficient prediction for tree markov random fields (2)

Decompose the tree...



D-propagation

We construct tree D from T of height χ s.t.

$$\log(\text{height}(T)) \leq \chi \leq \min(\log(|T|), \text{height}(T)).$$

For update and prediction we then “ D -propagate” on D .

	Online belief propagation	Online D -propagation
Prediction	$O(1)$	$O(\chi)$
Update	$O(T)$	$O(\chi)$
Initialisation	$O(T)$	$O(T ^3)$ now $O(T)$

- Learning with data-dependent hypothesis classes
- Theoretical and practical advances
- 2 papers:
 - 1 Data dependent kernels in nearly-linear time
 - kernels on general (continuous) spaces capture data-defined structure
 - current methods scale poorly
 - exploit huge amounts of data
 - practical, **fast**
 - 2 Tighter PAC-Bayes bounds through distribution dependent priors
 - bounds for exponential weights and SVMs
 - Localized PAC-Bayes analysis
 - encode assumptions about interaction of classifiers with data
 - tight bounds, new distribution-dependent complexity measure

Data dependent kernels in nearly-linear time (1)

- kernels on general (continuous) domains capture structure in data
 - manifold structure, cluster structure etc.
- we want:
 - Fast (**need to exploit lots of data to be robust**)
 - automatic (no tuning or domain knowledge)
- Problem: Given space \mathcal{X} and subsample $\mathcal{V} \subset \mathcal{X}$, $|\mathcal{V}| = n$ and “intrinsic regularizer”:

$$\text{reg}(h) = \mathbf{h}^\top \mathbf{Q} \mathbf{h} \quad (1)$$

where $h : \mathcal{X} \rightarrow \mathbb{R}$ and $h_i = h(v_i)$, define kernel

$\tilde{K} : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ such that:

- functions $h \in \mathcal{H}_{\tilde{K}}$ smooth w.r.t. (1)
- \tilde{K} extends kernel \mathbf{Q}^+ from \mathcal{V} to \mathcal{X}

Data dependent kernels in nearly-linear time (2)

- One solution (Sindhwani et. al. 2005): pick basic $K : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ then define

$$\langle h, g \rangle_{\tilde{K}} := \beta \langle h, g \rangle_K + (1 - \beta) \mathbf{h}^\top \mathbf{Q} \mathbf{g}, \quad h, g \in \mathcal{H}_K, \quad (2)$$

- kernel \tilde{K} has closed form, but cubic complexity
- solution: disconnect \mathcal{V} from *landmark points* $\mathcal{L} \subset \mathcal{V}$ at which functions in \mathcal{H}_K are measured
- Proposed RKHS has inner product:

$$\langle h, g \rangle_{\check{K}} := \beta \langle h, g \rangle_K + (1 - \beta) (\mathbf{h}^*)^\top \mathbf{Q} \mathbf{g}^*, \quad h, g \in \mathcal{H}_K, \quad (3)$$

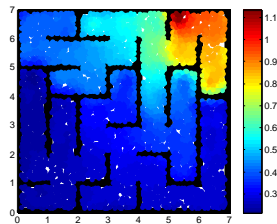
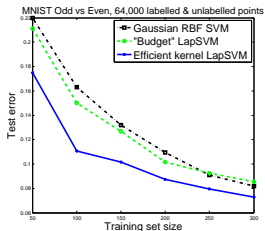
where $\mathbf{h}|_{\mathcal{L}}$ is restriction of $\mathbf{h} \in \mathbb{R}^{\mathcal{V}}$ to \mathcal{L} ,

$\mathbf{h}^* \in \operatorname{argmin}_{\mathbf{h} \in \mathbb{R}^{\mathcal{V}}} \{ \mathbf{h}^\top \mathbf{Q} \mathbf{h} : \mathbf{h}(\ell) = h(\ell), \ell \in \mathcal{L} \}$.

- Theorem: $\check{K}(x, x')$ nearly-linear complexity in n

Data dependent kernels in nearly-linear time (3)

- Benefit: robustness of using a huge graph (avoid short circuiting), but *efficiently computable*
- state of the art performance on large data-sets in SSL



- also follow ups:
 - efficient CV of many parameters
 - journal version in prep.
 - applying to RL to learn kernels on state space

Tighter PAC-Bayes bounds through distribution dependent priors (1)

- Bounds for stochastic classifiers G_Q drawn from distribution Q on \mathcal{H}
- trick is to define PAC-Bayes prior **in terms of unknown distribution**
- No relative entropy term in bounds
- Exponential weights: density on \mathcal{H} is

$$q(h) = \frac{1}{Z} e^{-\gamma \widehat{\text{risk}}_S(h)} \quad (4)$$

- bound: with probability at least $1 - \delta$,

$$\text{kl}(\widehat{\text{risk}}_S(G_Q), \text{risk}(G_Q)) \leq \frac{1}{m} \left(\gamma \sqrt{\frac{2}{m} \ln \frac{2\sqrt{m}}{\delta}} + \frac{\gamma^2}{2m} + \ln \frac{2\sqrt{m}}{\delta} \right)$$

$$\text{kl}(q, p) := q \ln \frac{q}{p} + (1 - q) \ln \frac{1 - q}{1 - p}$$

- no complexity term – only parameter γ

Tighter PAC-Bayes bounds through distribution dependent priors (2)

- RKHS regularization algorithms:

$$h_S^* := \operatorname{argmin}_{h \in \mathcal{H}_K} \{ \widehat{\operatorname{risk}}_S^\ell(h) + \eta \|h\|_K^2 \} \quad (5)$$

\mathcal{H}_K is RKHS with norm $\|\cdot\|_K$. G_Q is GP with mean and covariance

$$\mathbb{E}[G(x)] = h_S^*(x), \quad \operatorname{Cov}(G(x), G(x')) = \frac{1}{\gamma} K(x, x') \quad (6)$$

- bound:

$$\mathbb{P}_S \left(\operatorname{kl}(\widehat{\operatorname{risk}}_S(G), \operatorname{risk}(G)) \leq \frac{1}{m} \left(\frac{2\gamma}{\eta^2 m} \ln \frac{8}{\delta} + \ln \frac{4\sqrt{m}}{\delta} \right) \right) \geq 1 - \delta$$

- KL term removed – only parameters η and γ
– interpreted as complexity terms

- We would like to extend the completion to September 2012
- Until September 2012
 - 1 Extend results on fast online prediction for tree MRFs
 - 2 Experiments with Bristol data set
- Post September 2012 : Extend p -resistance research
 - UCL and Tuebingen : 2 papers each p -resistance an open research area
 - Visit between UCL and Tuebingen (possibly also Insubria)
 - Some directions:
 - 1 Computational issues (efficiency + representer theorem)
 - 2 Loss bounds over the full spectrum of $p \in \infty$
 - 3 Reinforcement learning application