

Factored 3-Way Restricted Boltzmann Machines for Modeling Natural Images

Marc'Aurelio Ranzato, Alex Krizhevsky and Geoff Hinton

Dept. of Computer Science – University of Toronto

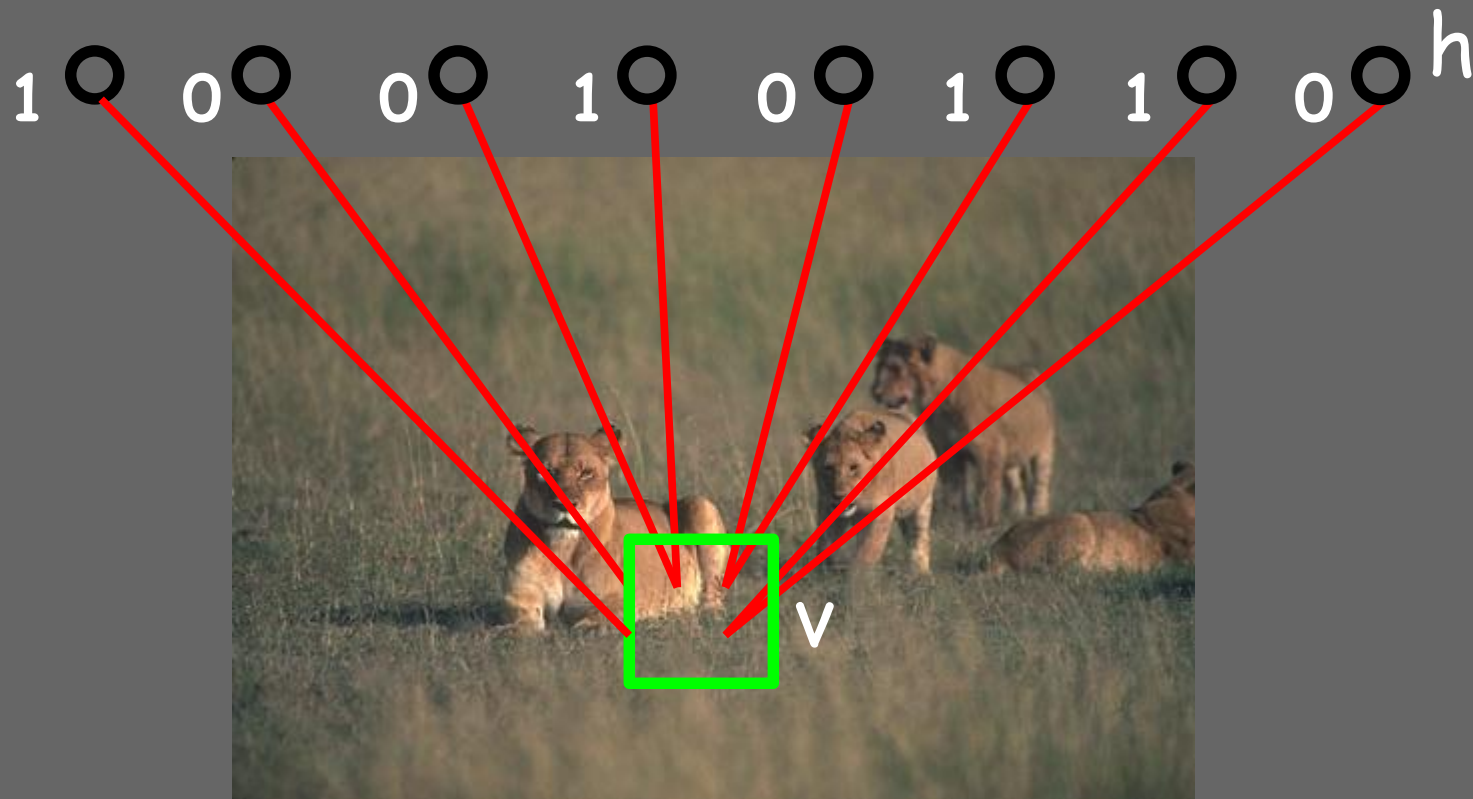
Marc'Aurelio Ranzato

www.cs.toronto.edu/~ranzato

AISTATS - 14 May 2010

- Want to model natural images by using a generative model $p(\text{image } v; W)$

- Want to use the model to produce representations $p(\text{image } v, \text{hidden units } h; W)$



Goal: define $p(v, h)$

Q.: What is the key property of natural images?

Goal: define $p(v, h)$

Q.: What is the key property of natural images?

A.: smoothness

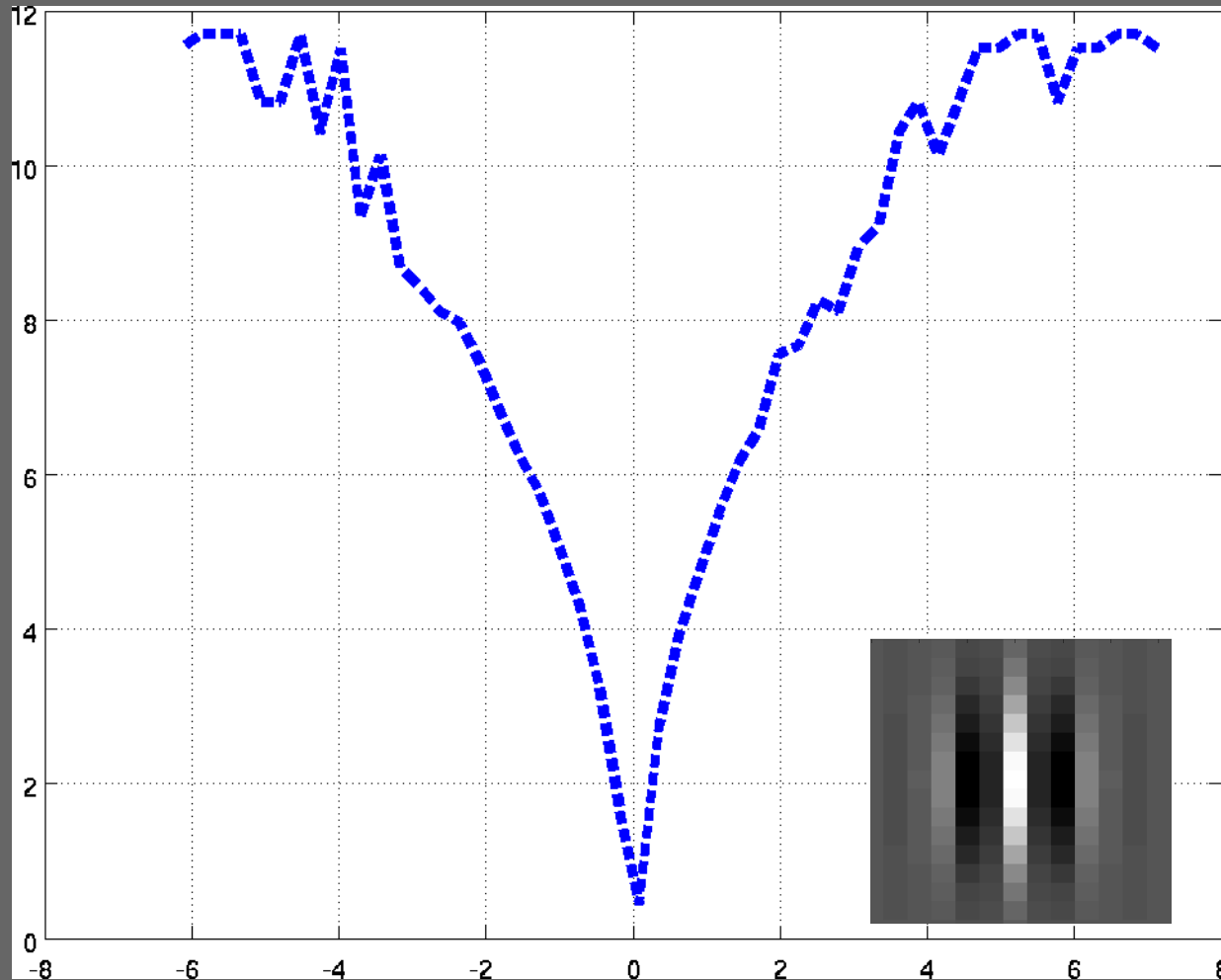


Most of the times, the value of one pixel can be well predicted from its neighbors



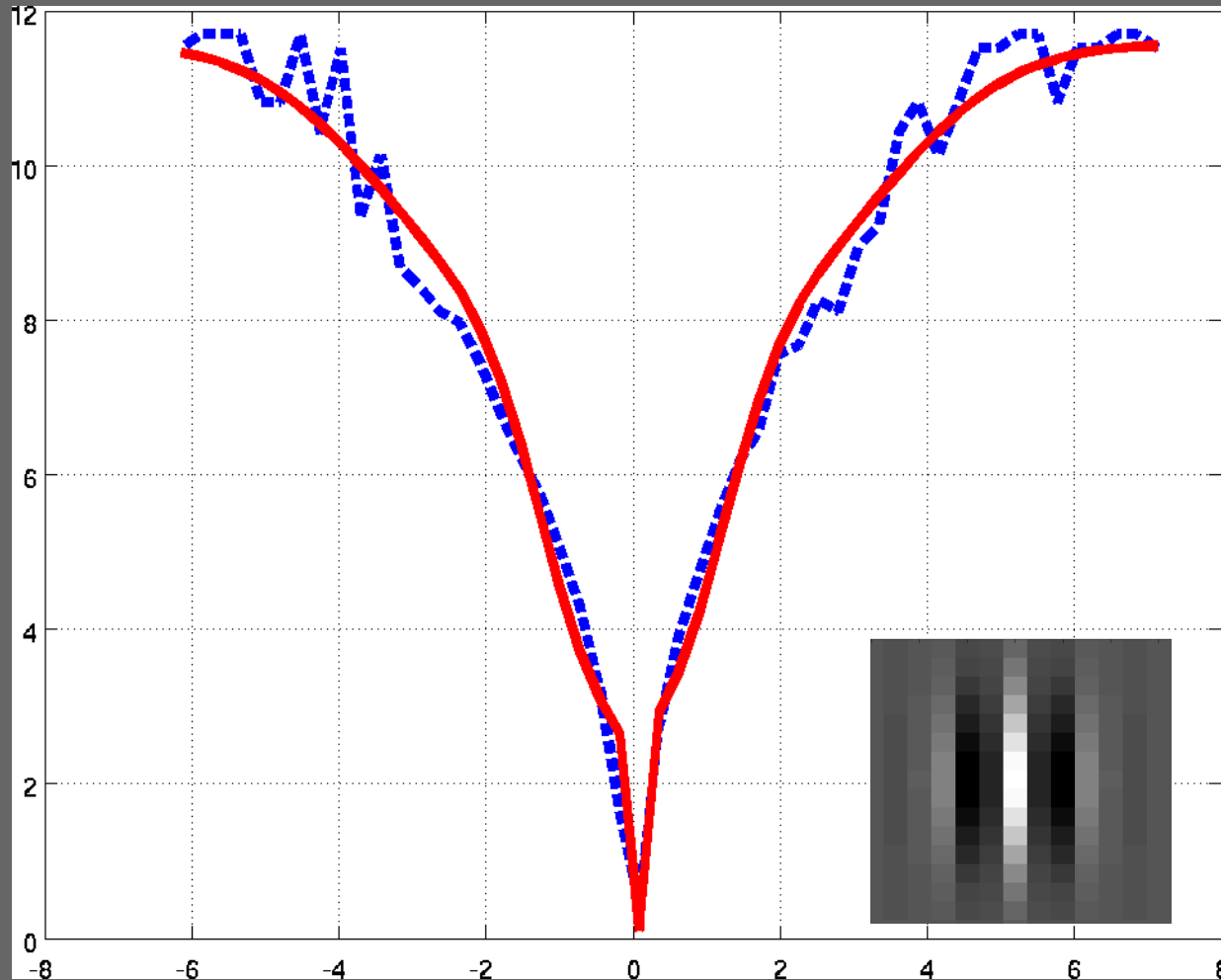
Most local neighborhoods
are smooth

- $\log(\text{empirical p.d.f. of filter response})$)



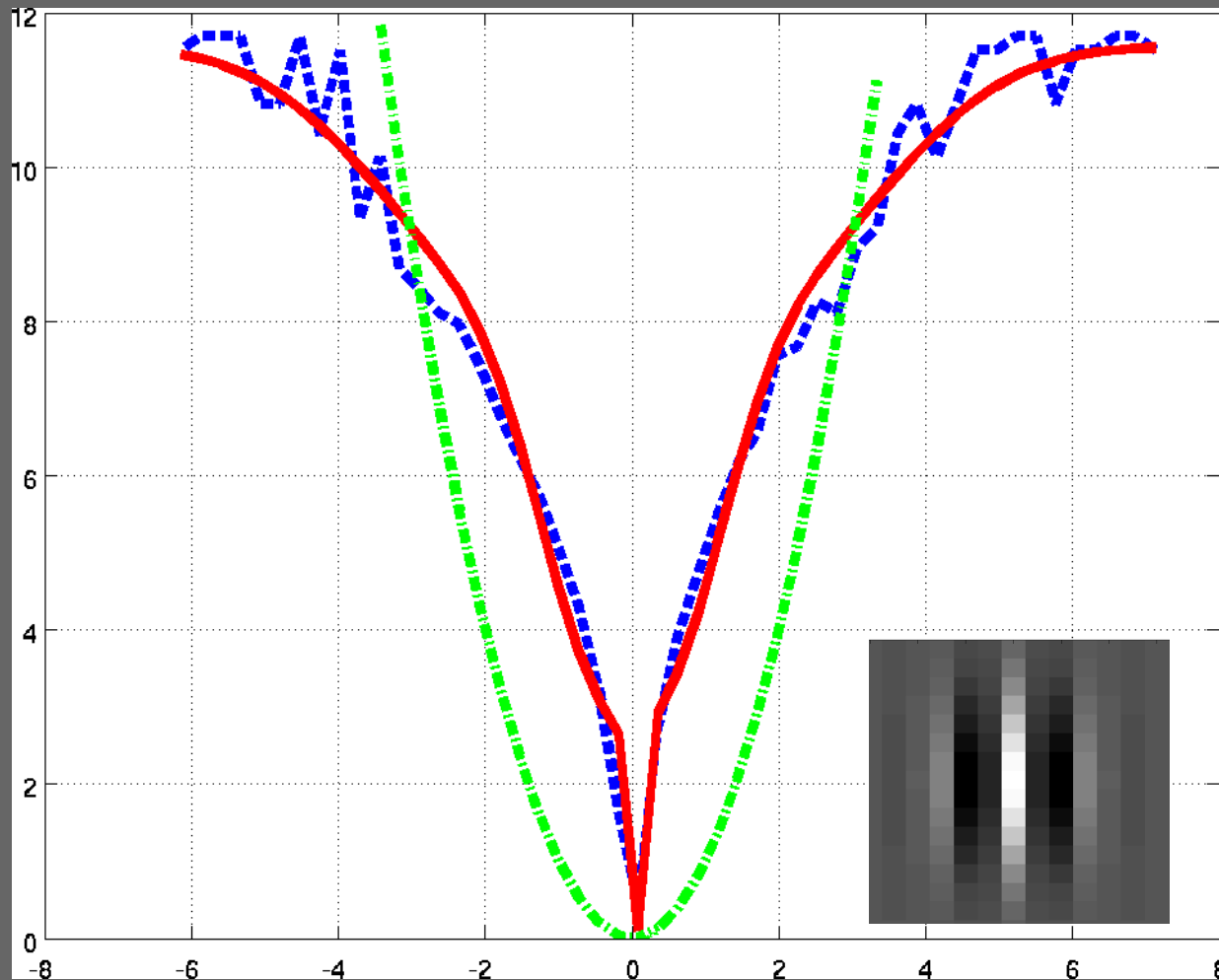
Finding an edge at this location and orientation is rare

- $\log(\text{empirical p.d.f. of filter response})$
- $\log(\text{fit of model p.d.f. to filter response})$



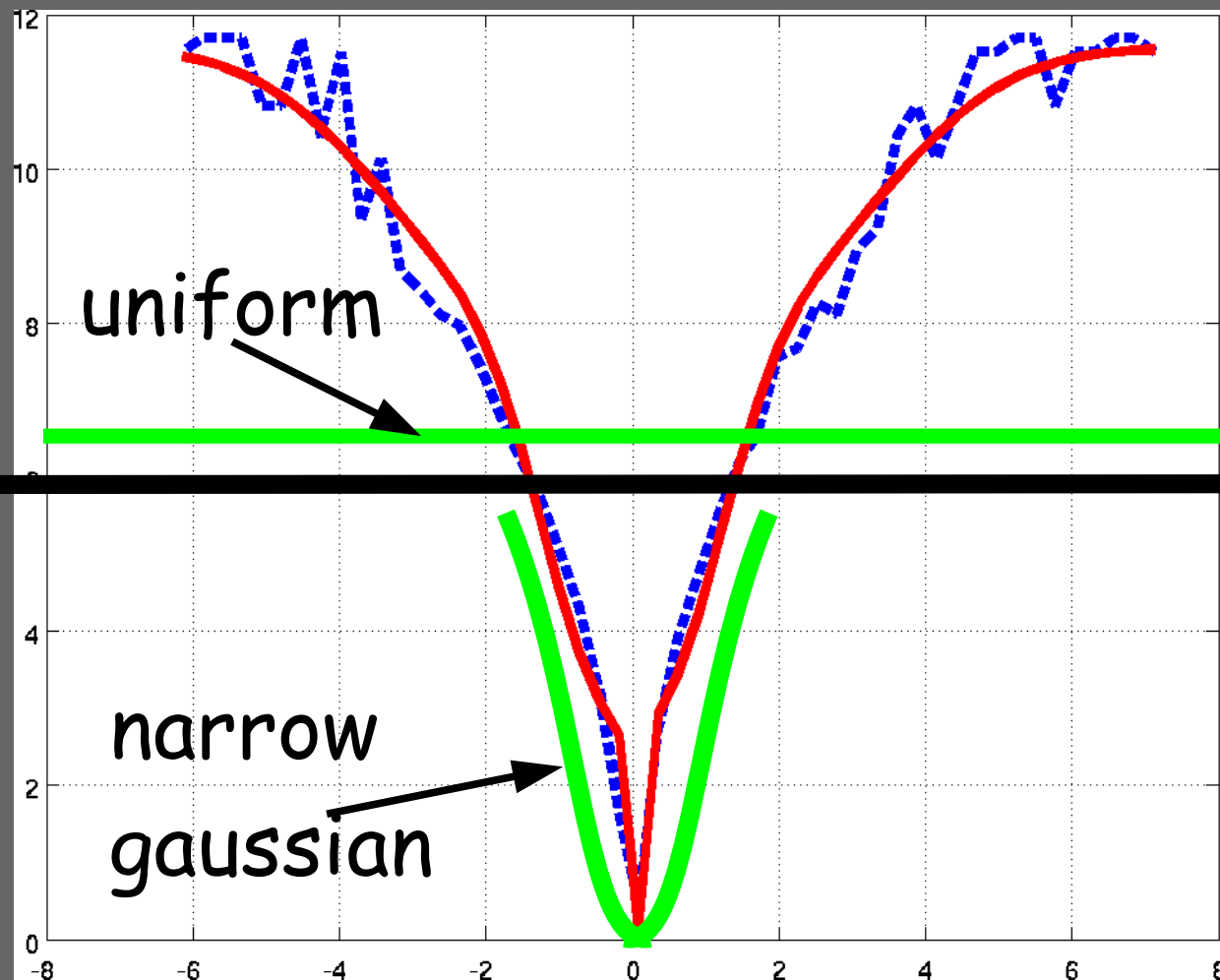
Finding an edge at this location and orientation is rare

- $\log(\text{empirical p.d.f. of filter response})$
- $\log(\text{fit of model p.d.f. to filter response})$
- $\log(\text{fit of Gaussian p.d.f. to filter response})$

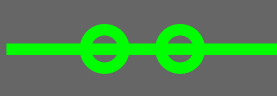


Finding an edge at this location and orientation is rare

KEY IDEA: use "switch" hidden variable



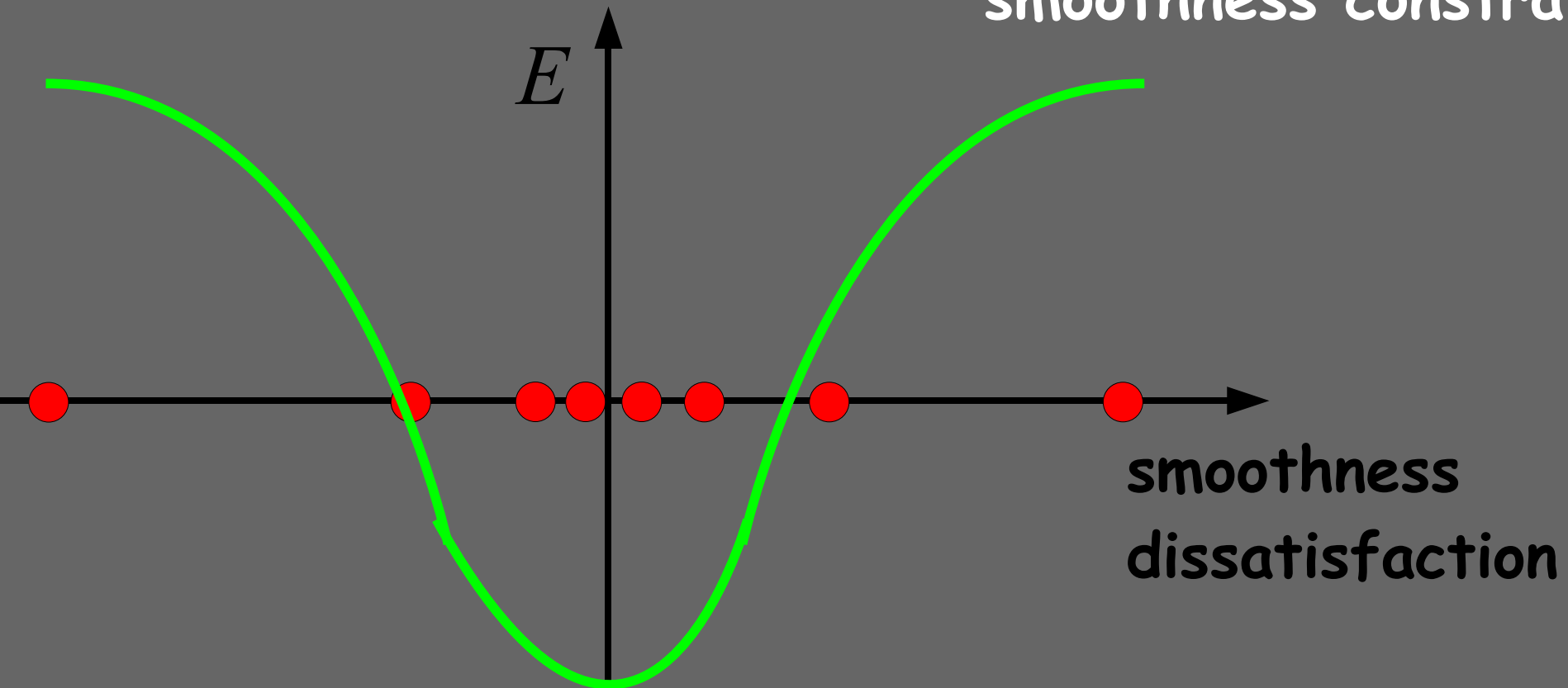
 $h = 0$
structured
images

 $h = 1$
smooth
images

Goal: define $p(v, h)$

$$p(v, h) \propto \exp[-E(v, h)]$$

Energy measures
dissatisfaction of
smoothness constraints



- Smooth images are more likely
- (Rare) structured images are unlikely but possible

- What is a good measure of smoothness dissatisfaction?
- Edges are not smooth.
E.g. what is a vertical edge?



- What is a good measure of smoothness dissatisfaction?

- Edges are not smooth.

E.g. **what is a vertical edge?**



polarity



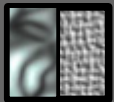
contrast



color



texture



...

- What is a good measure of smoothness dissatisfaction?

- Edges are not smooth.

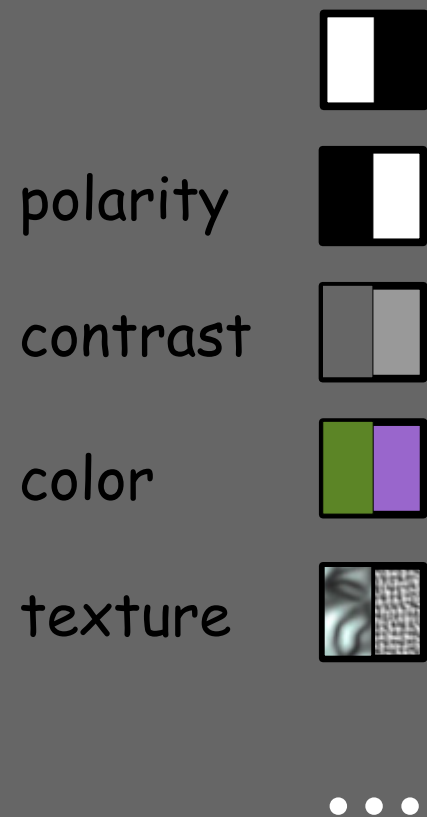
E.g. what is a vertical edge?



■ What is a good measure of smoothness dissatisfaction?

■ Edges are not smooth.

E.g. what is a vertical edge?



Geoff: lack of horizontal
"interpolation"



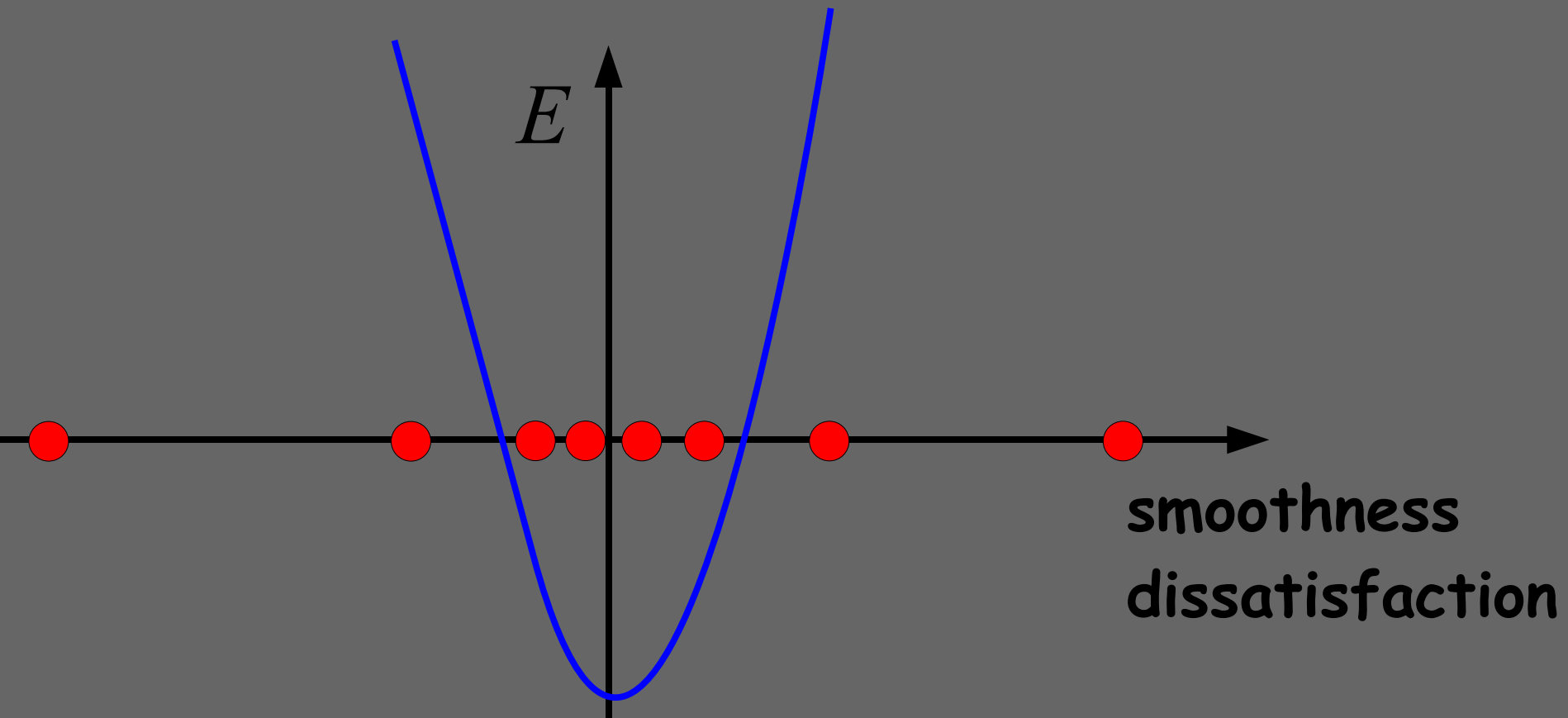
smoothness dissatisfaction
=
learned by set of linear filters
(patterns of "broken" interpolation)

$$E = \sum_i \text{smoothness_dissatisfaction}_i - b_i$$

$$\text{smoothness_dissatisfaction}_i = W_i v$$

$$E = \sum_i \text{smoothness_dissatisfaction}_i^2 - b_i$$

$$\text{smoothness_dissatisfaction}_i = W_i v$$



$$E = \sum_i h_i \text{smoothness_dissatisfaction}_i^2 - h_i b_i$$

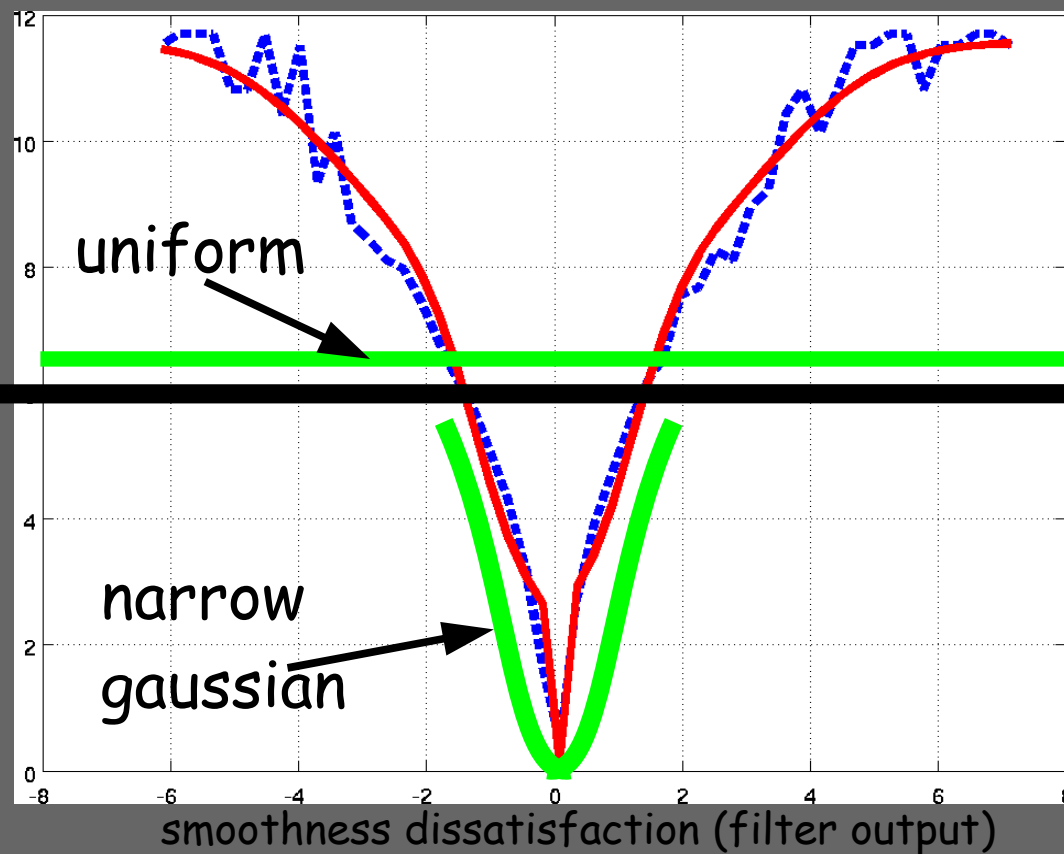
$$\text{smoothness_dissatisfaction}_i = W_i v$$

$h_i \in \{0, 1\}$ introduce hiddens to allow violations

$$E = \sum_i h_i \text{smoothness_dissatisfaction}_i^2 - h_i b_i$$

$$\text{smoothness_dissatisfaction}_i = W_i v$$

$h_i \in \{0, 1\}$ introduce hiddens to allow violations

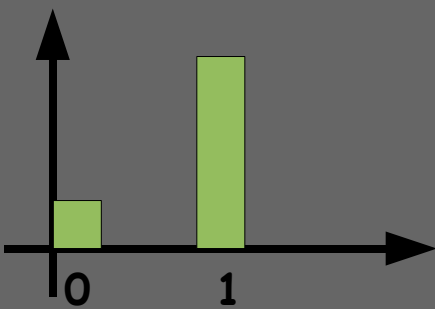


$h = 0$
structured
images

$h = 1$
smooth
images

$$E = h_1 (W_1 v)^2 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

$$W_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad W_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad b_1 = 10 \quad b_2 = 10$$

$$p(h_i = 1 | v) = \sigma(-(W_i v)^2 + b_i)$$


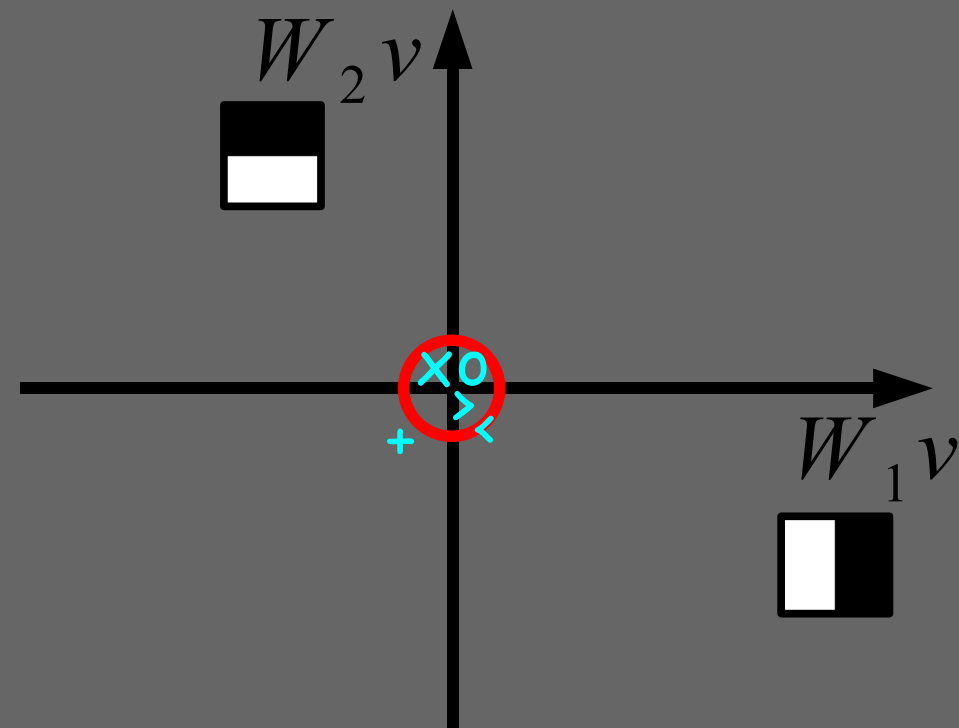
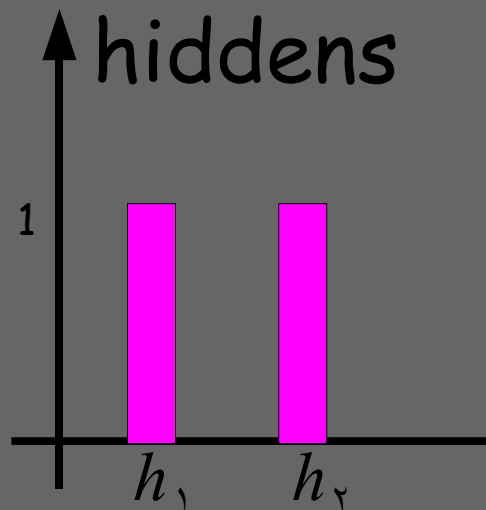
The bar chart illustrates the probability distribution $p(h_i = 1 | v)$ for $i=0$ and $i=1$. The x-axis is labeled with 0 and 1. The y-axis is unlabeled. The bar at 0 is short, and the bar at 1 is tall.

$$p(v|h) = N\left(0, \frac{1}{2} (h_1 W_1' W_1 + h_2 W_2' W_2)^{-1}\right)$$

$$E = h_1 (W_1 v)^2 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

$$W_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad W_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad b_1 = 10 \quad b_2 = 10$$

image



$$E(v, h) \approx -b_1 - b_2 = -20$$

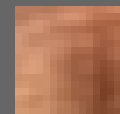
low energy



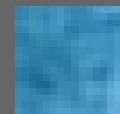
x



+



o



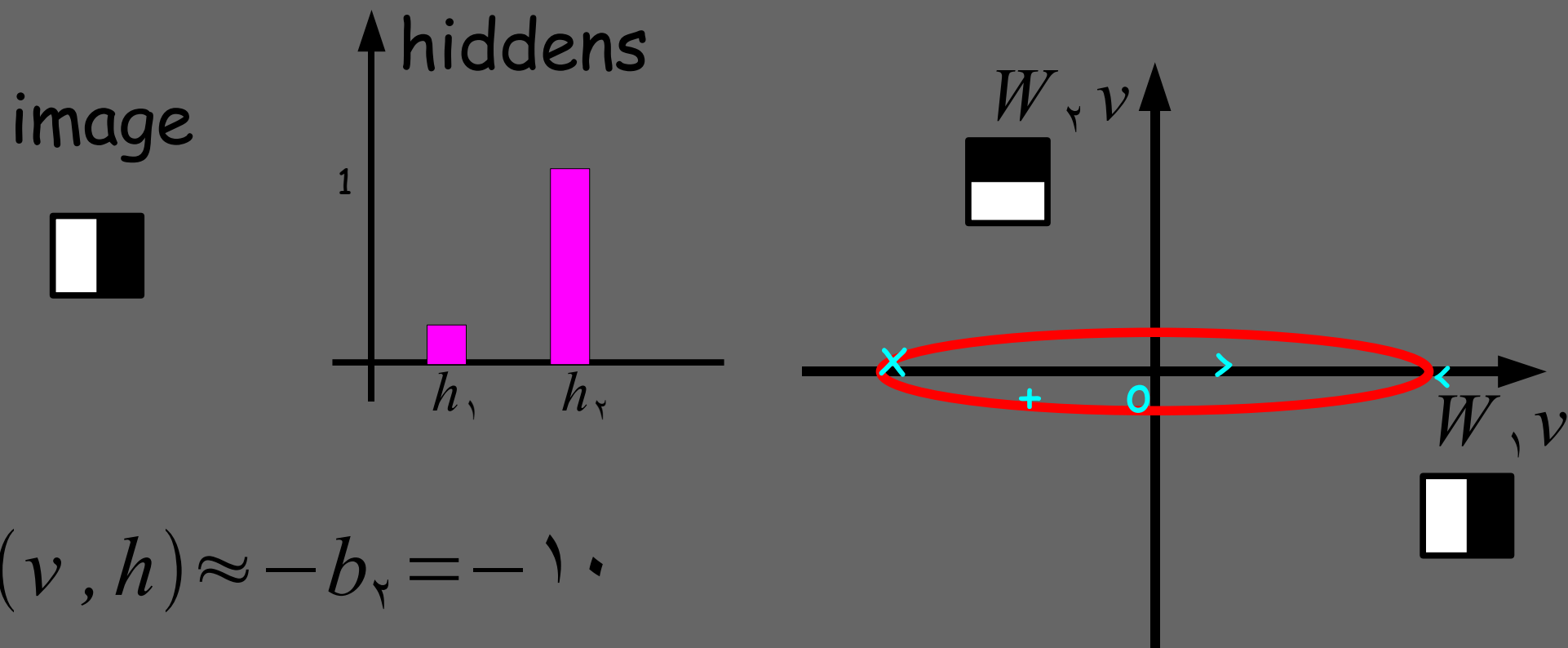
>



<

$$E = h_1 (W_1 v)^1 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

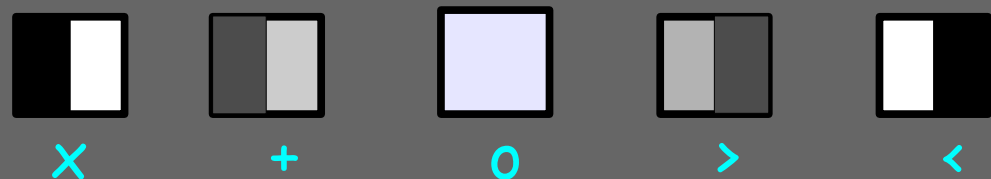
$$W_1 = \begin{bmatrix} 1 & 0 \end{bmatrix} \quad W_2 = \begin{bmatrix} 0 & 1 \end{bmatrix} \quad b_1 = 1 \quad b_2 = 1$$



$$E(v, h) \approx -b_2 = -1$$

higher energy

(h_1 gave discount!)



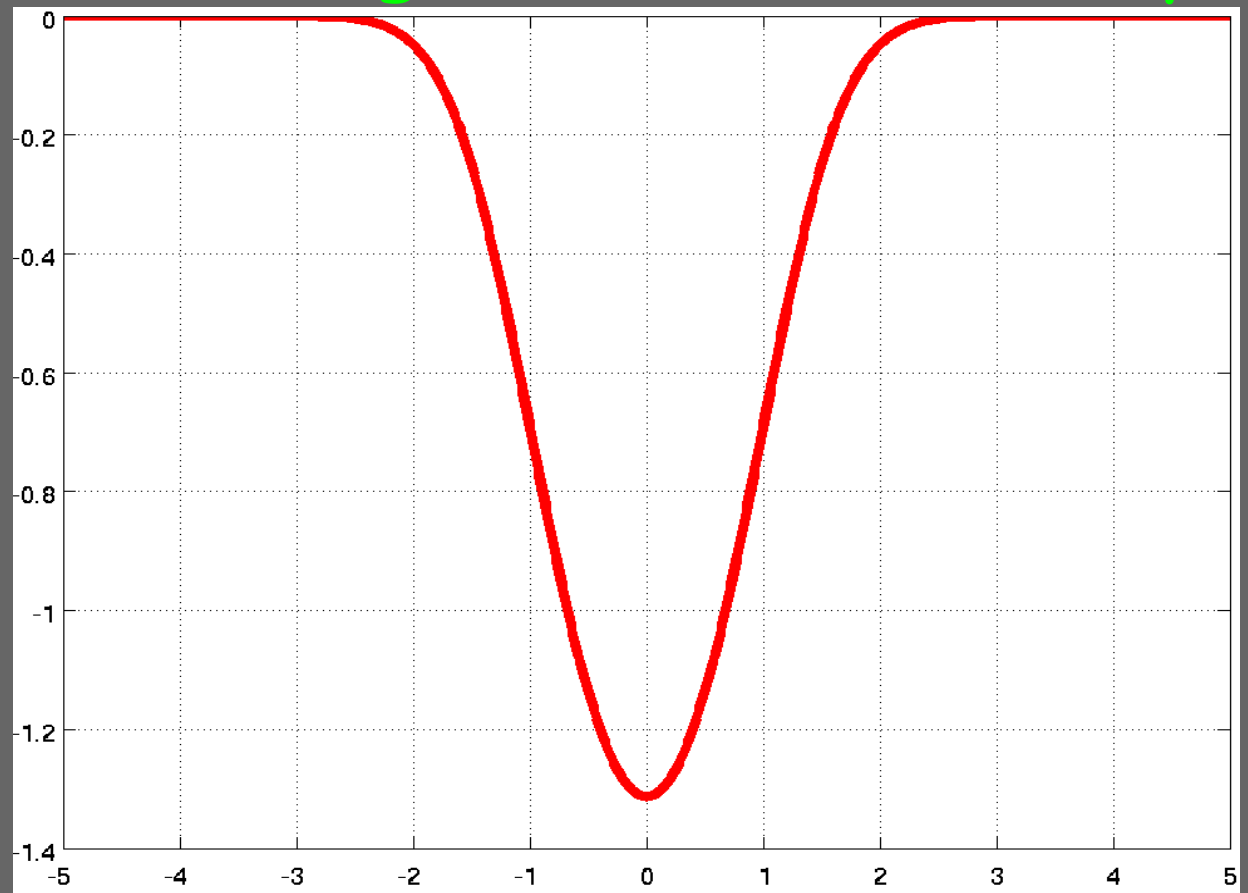
$$E = h_1 (W_1 v)^2 + h_2 (W_2 v)^2 - b_1 h_1 - b_2 h_2$$

$$W_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \quad W_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \quad b_1 = 10 \quad b_2 = 10$$

Binary hiddens can be marginalized out exactly

$$-\log(p(v)) + k$$

We allow (rare)
smoothness
violations



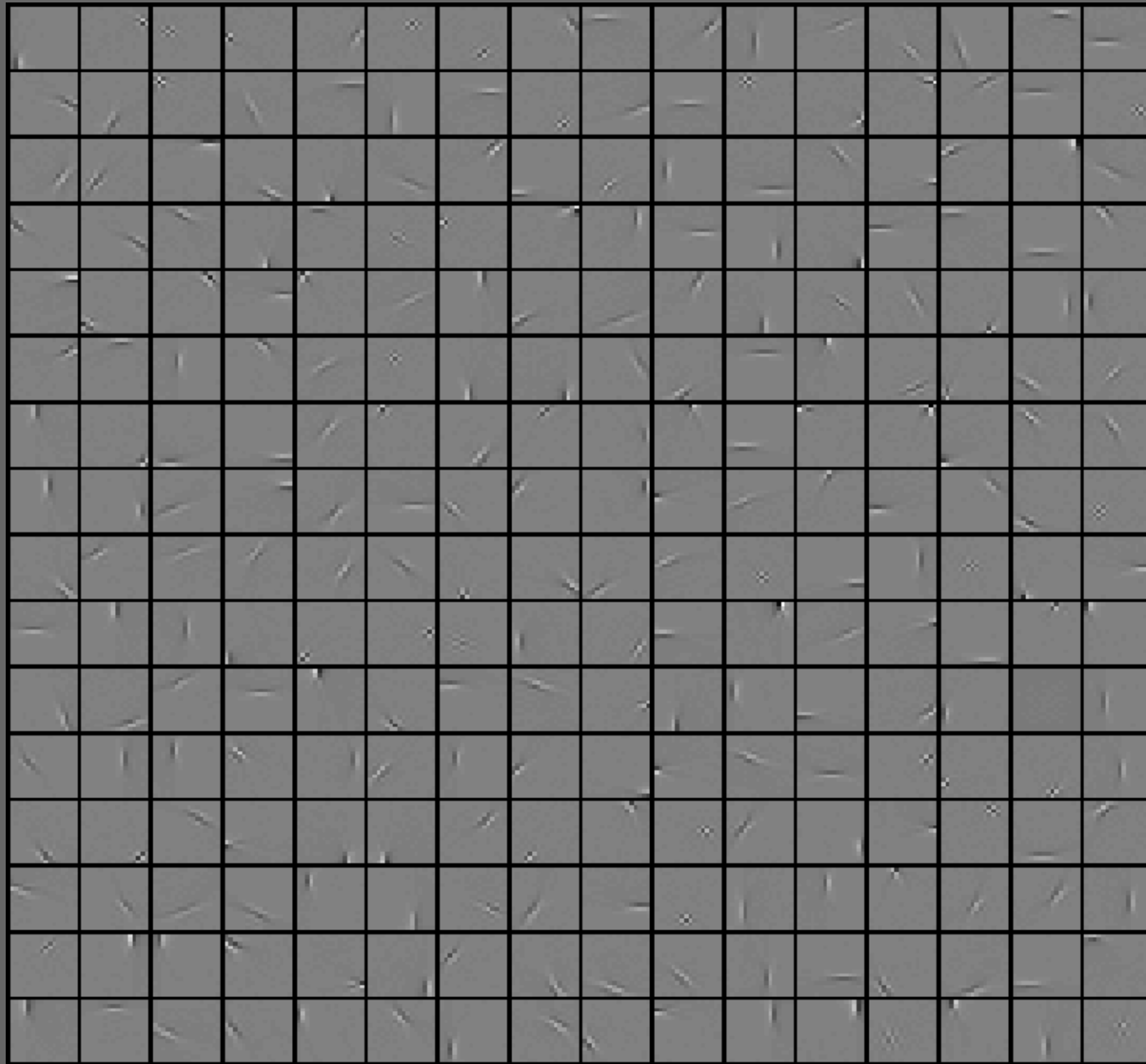
filter output

$$E = \frac{1}{2} \sum_k \sum_f h_k P_{fk} (W_f v)^2 - b_k h_k$$

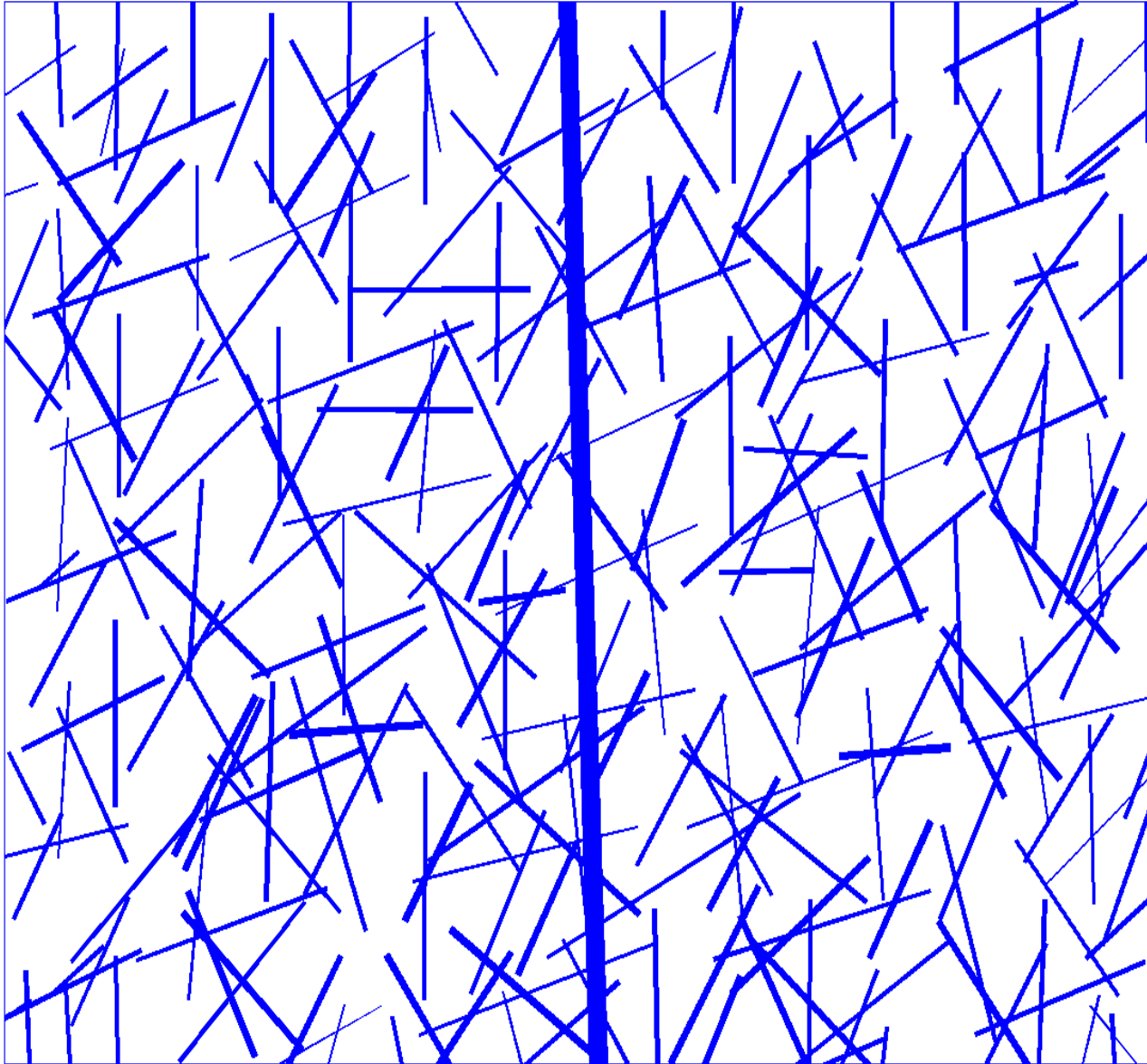
Learning: $\{W, P, b\}$

- approximate maximum likelihood
- Contrastive Divergence
- Hybrid Monte Carlo

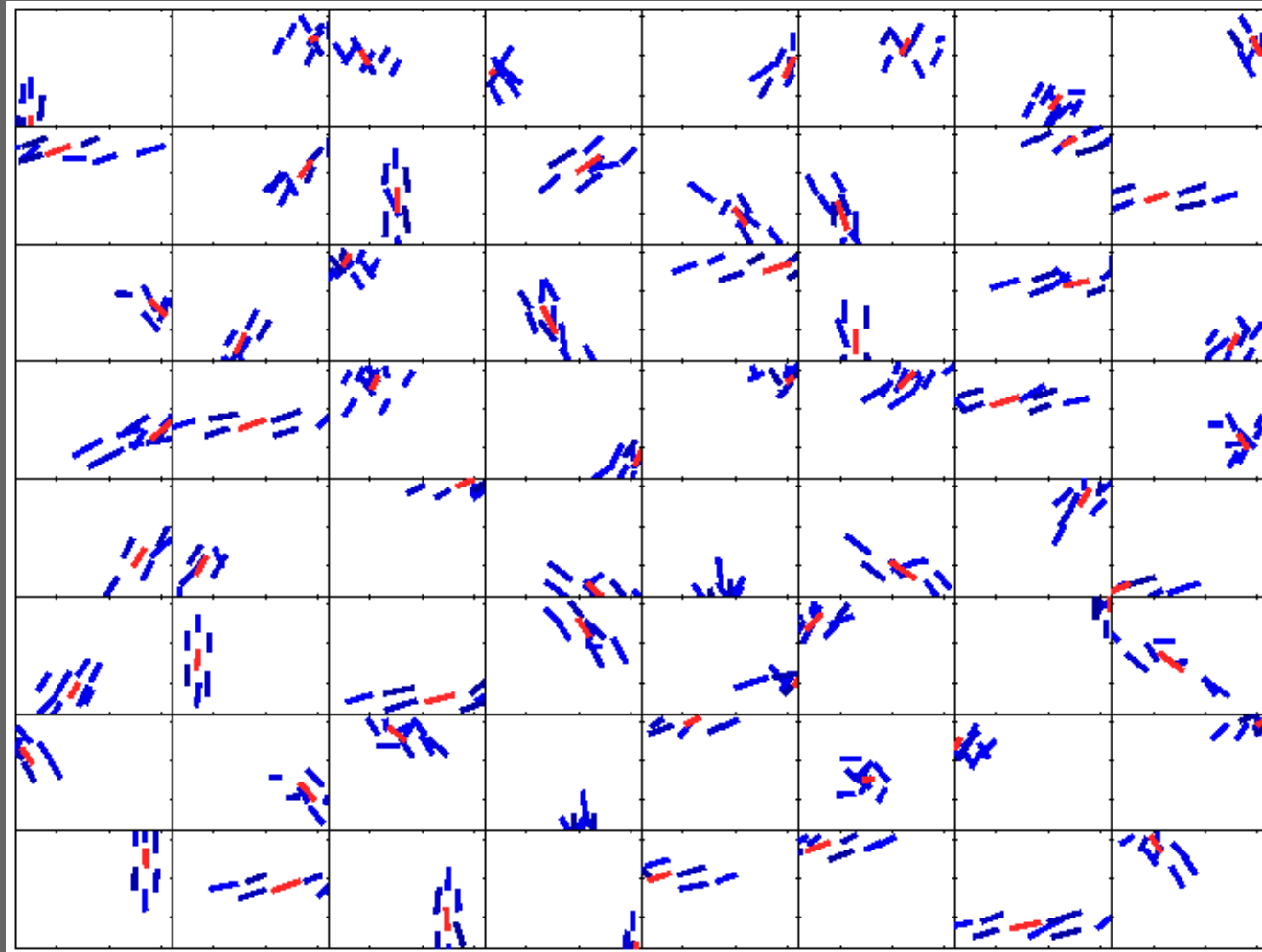
Learned filters (directions of smoothness dissatisfaction) on natural images



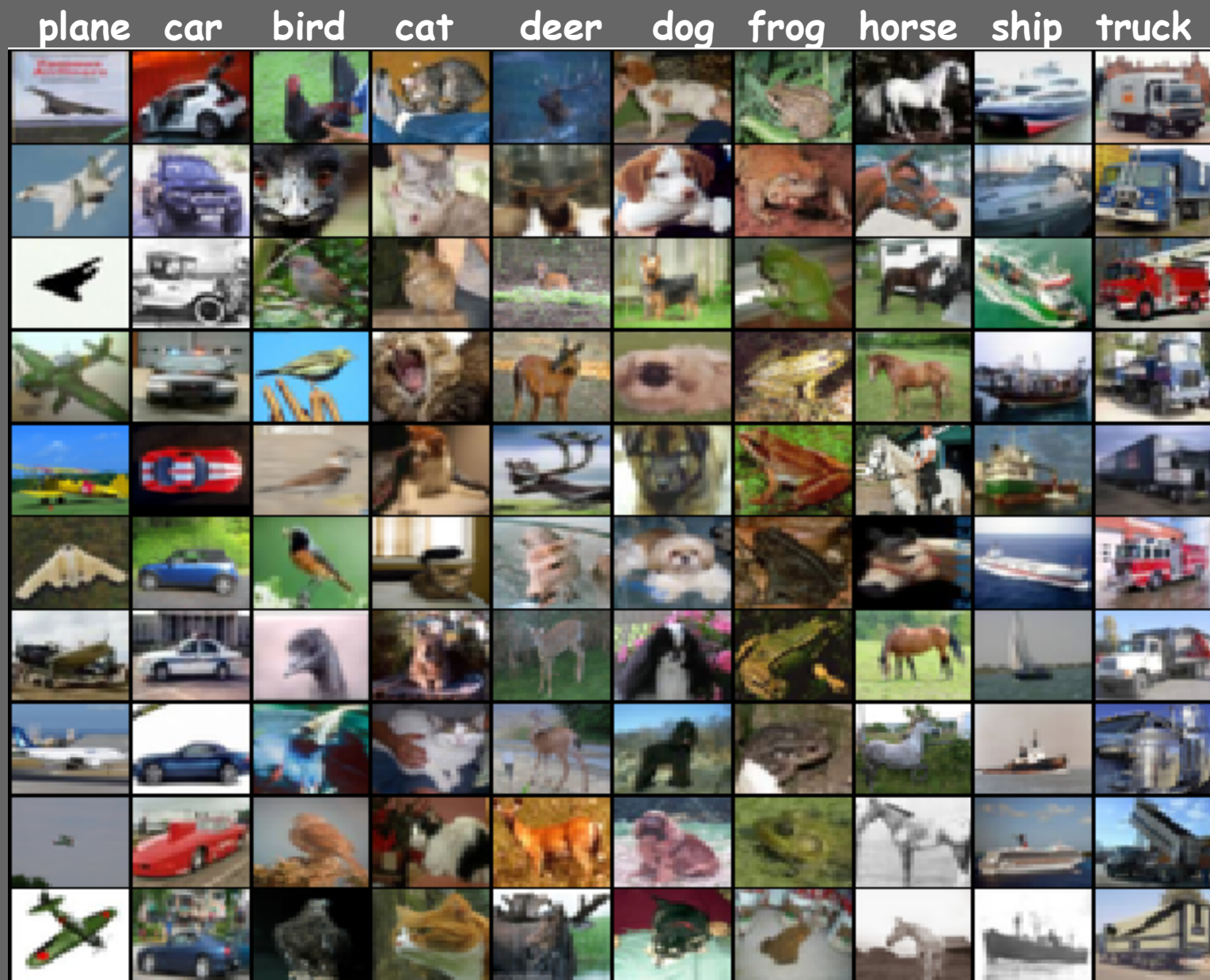
Learned filters: Gabor fit



Learned filters: grouping



RECOGNITION: CIFAR 10 dataset



RECOGNITION: CIFAR 10 dataset

Accuracy

3way RBM - DBN

input -> 9800 - 4096

64.7%

GRBM - DBN*

input - 10000 - 10000

56.6%

3way RBM - DBN

input -> 9800 - 4096 - 384

58.7%

GIST

input - 384

54.7%

* from Krizhevsky 2009

Conclusions

- Model of natural images producing binary features
 - Invariance or robustness to distortions
 - Good for recognition
 - Probabilistic model of simple-complex cell model
 - Easy to integrate with DBN's

Conclusions

- Model of natural images producing binary features
 - Invariance or robustness to distortions
 - Good for recognition
 - Probabilistic model of simple-complex cell model
 - Easy to integrate with DBN's
- Code and more recent developments available at:
<http://www.cs.toronto.edu/~ranzato>

THANK YOU!