

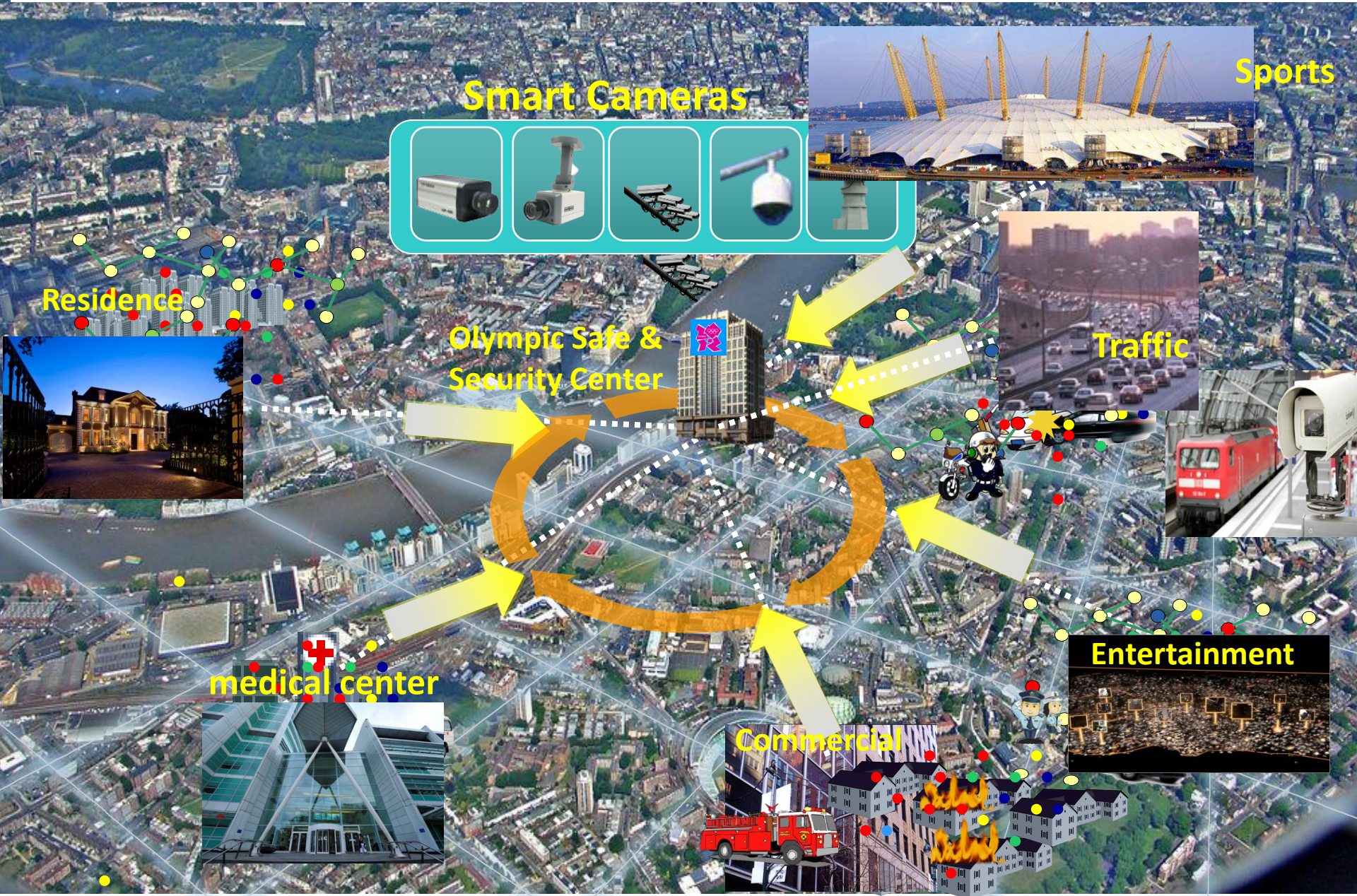


A Fast and Performance-Maintained Transcoding Method based on Background Modeling for Surveillance Video

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From Sydney, to Beijing and then London, safety and security is always one of main concerns for each Olympics



Smart Cameras



Sports



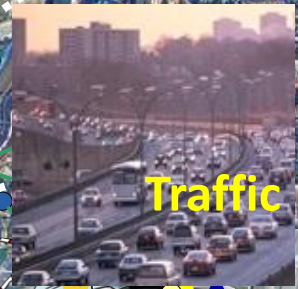
Residence



Olympic Safe & Security Center



Traffic



medical center



Commercial



Entertainment



Huge amount of surveillance video data

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1.5T/day for one HD Camera

30days~6months storage time

More than 4M cameras
in UK for Olympics

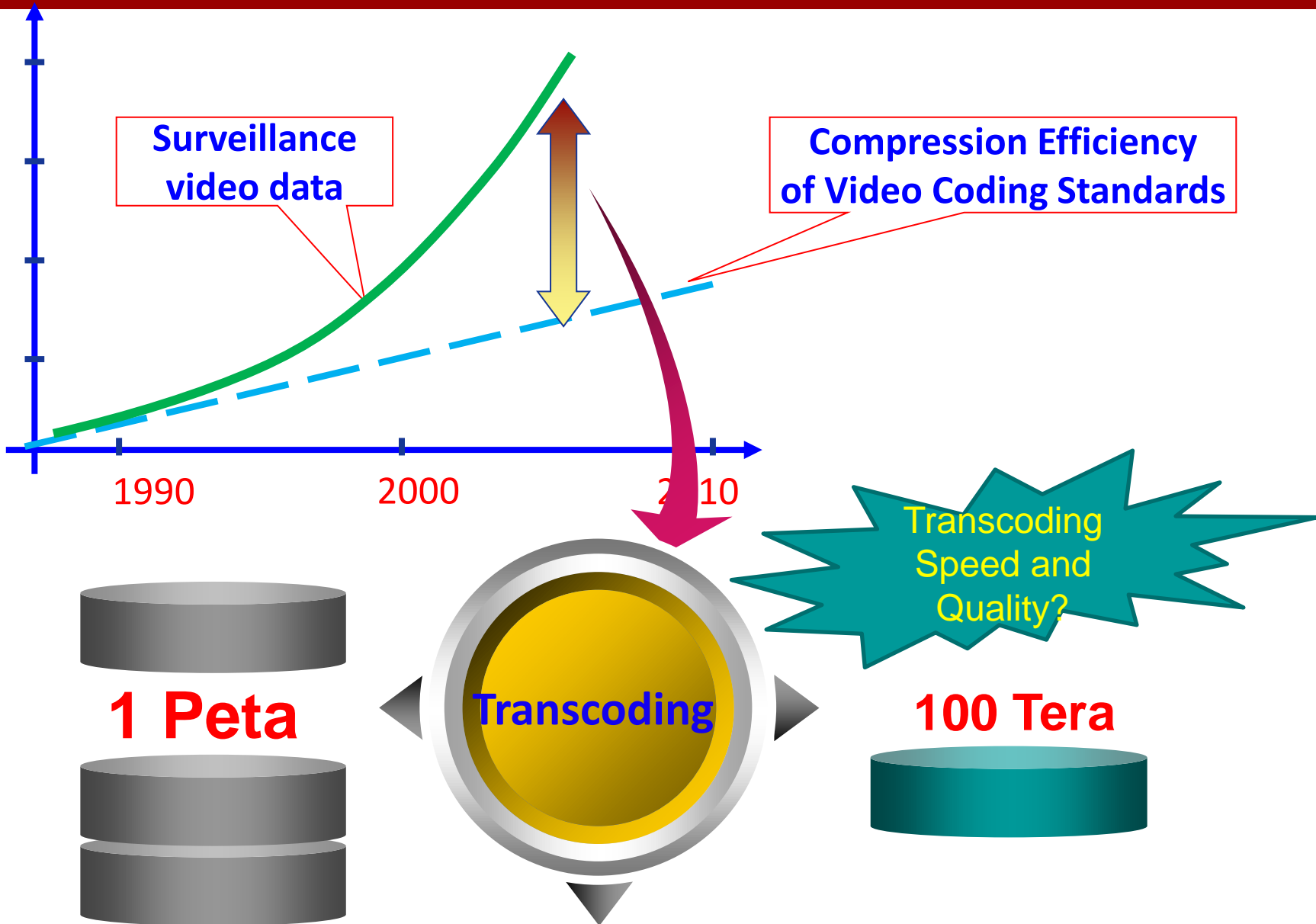


18,000~108,000 Peta

Huge data poses a grand challenge for transmission and long-term storage!

Surveillance video data increases extremely faster than the compression efficiency

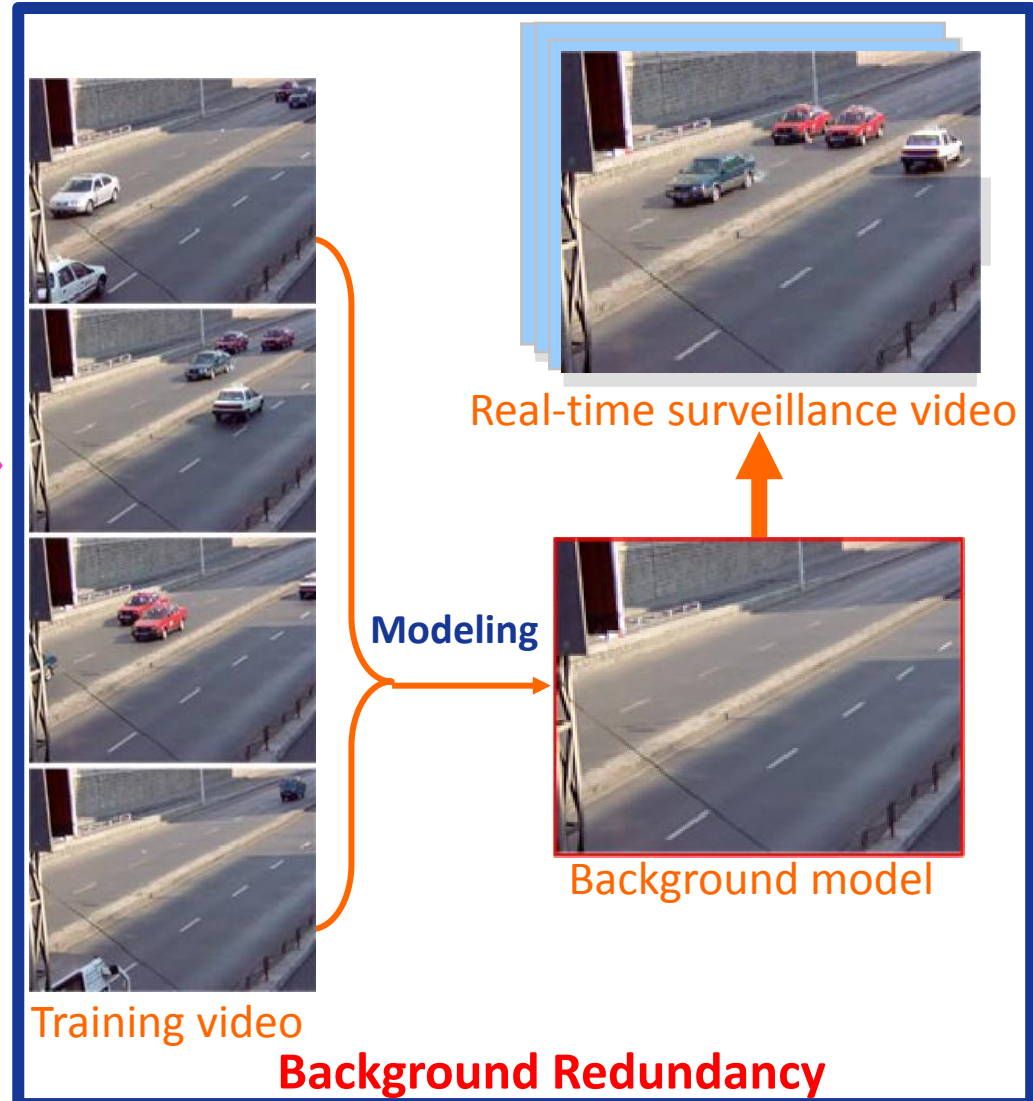
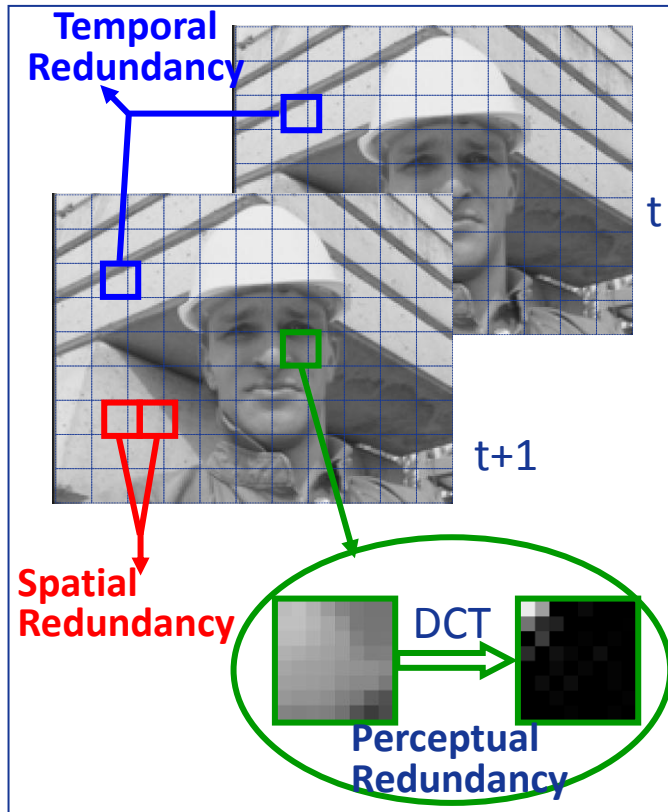
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How to guarantee the transcoding quality and speed?

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- ✓ Beyond the traditional redundancy...For surveillance video, we can remove ...?
- ✓ Background is a special kind of visual redundancy for surveillance video



How to guarantee the transcoding quality and speed?

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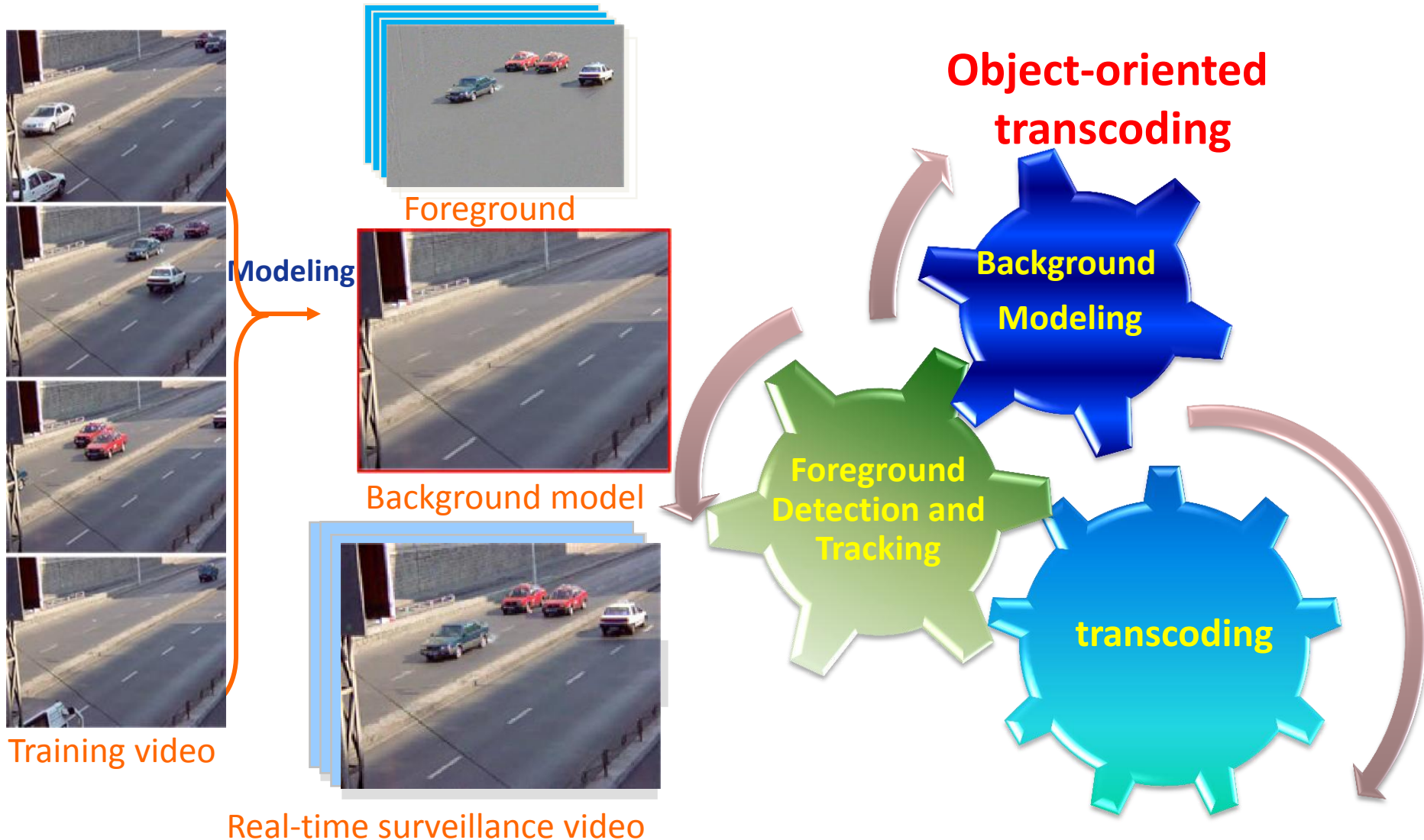
Whenever cloudy or fog, rainy or snow, in the morning or afternoon, most surveillance cameras are always deployed at a fixed position and cover a specific range of the scene for a long time even forever



How to guarantee the transcoding quality and speed?

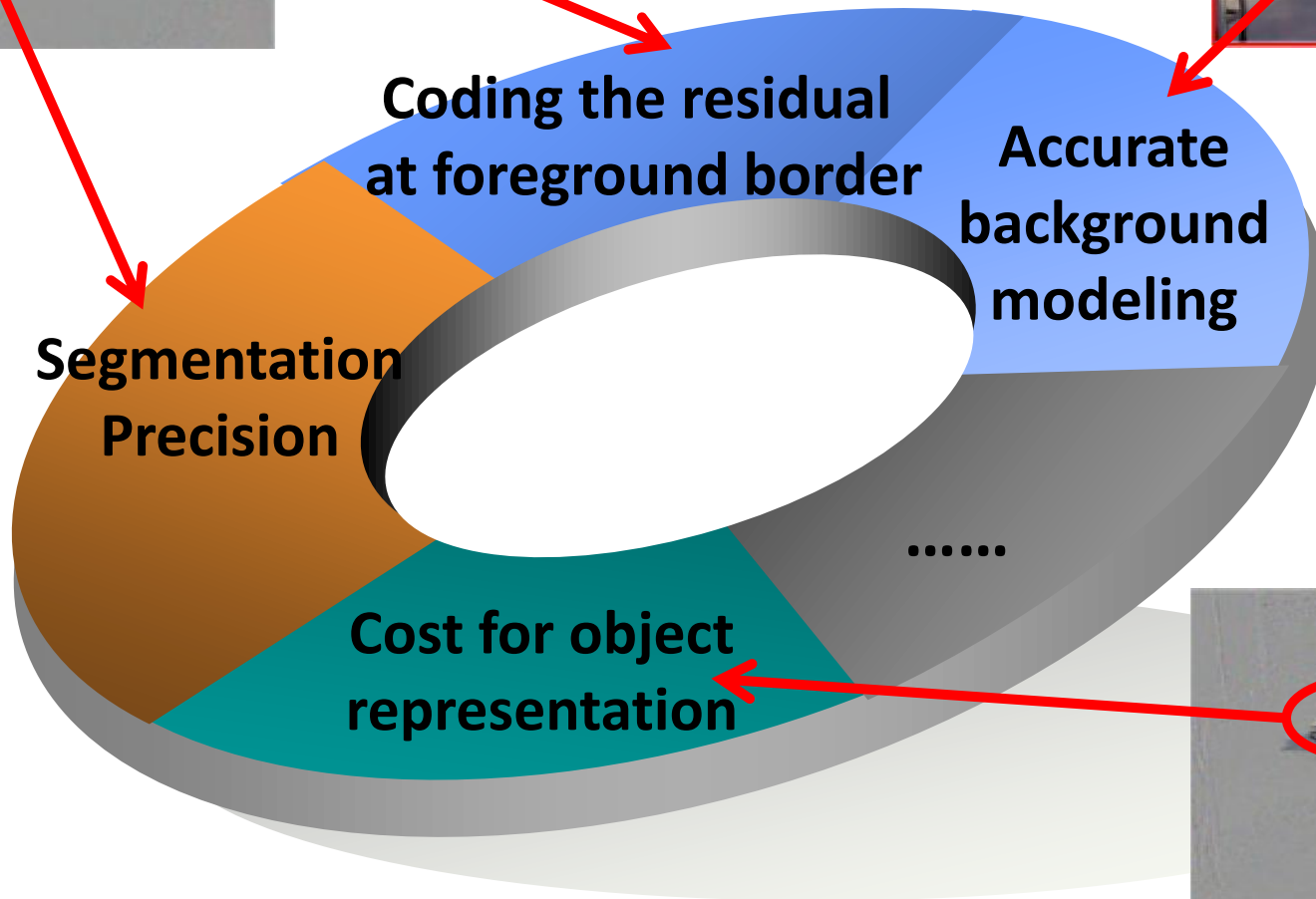
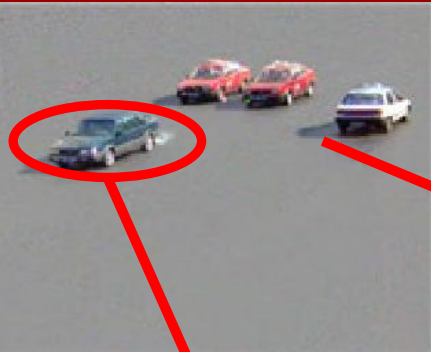
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✓ **Key idea:** Separately transcoding the foreground and background!



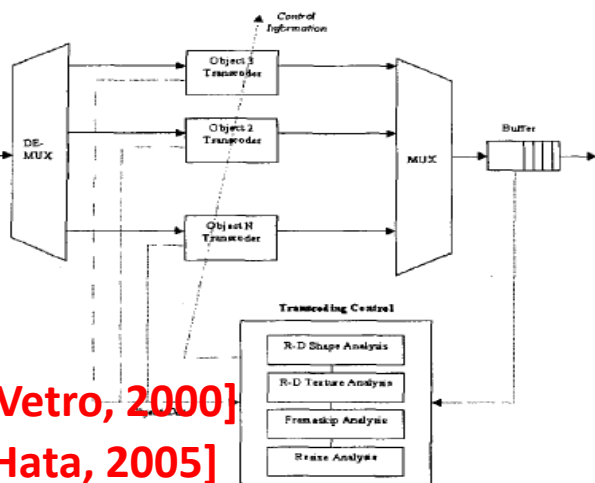
Challenges in separately transcoding the background and foreground

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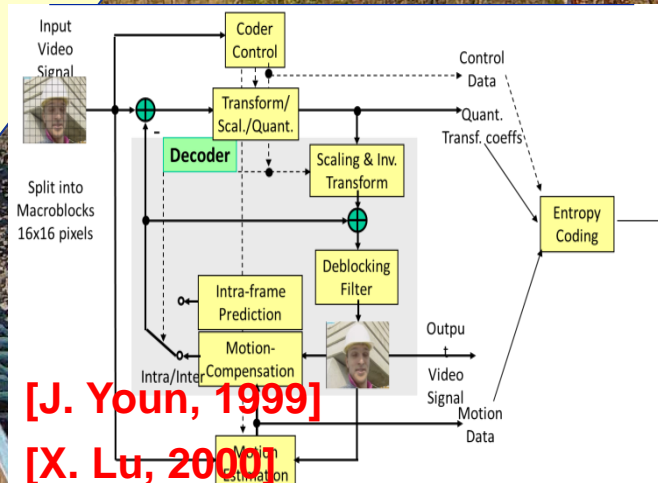
How to handle these challenges in object-oriented coding?

Object-oriented Transcoding



China's high-speed train

Hybrid Block-based Transcoding

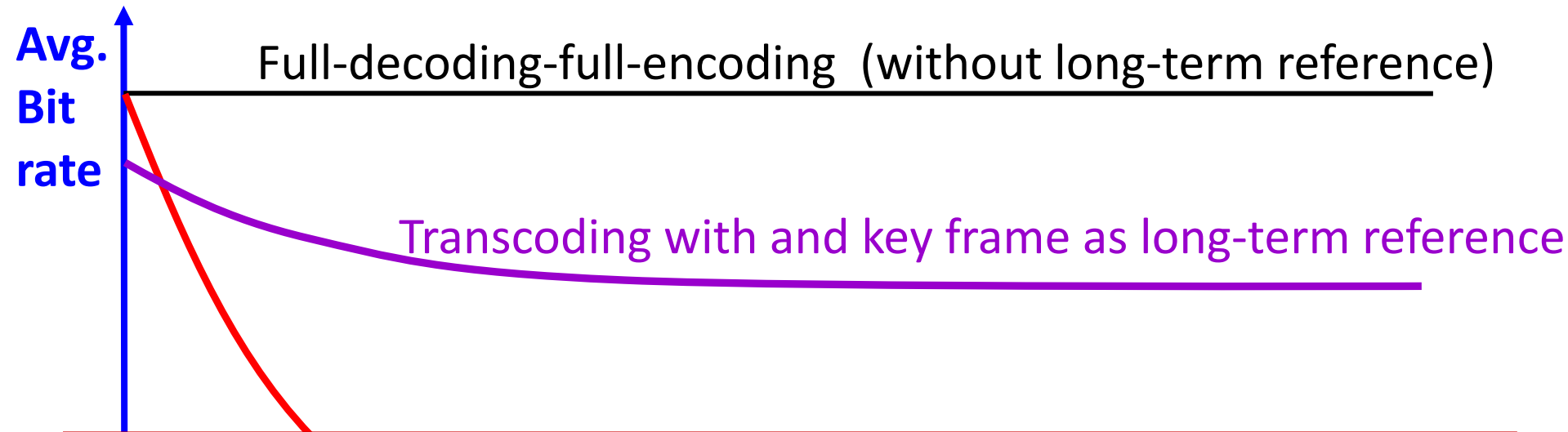


Can we integrate object-oriented transcoding with hybrid block-based methods for a best performance?

Hybrid block-based transcoding with background model

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The expected bitrate curve



Two key problems:

- ✓ How to model and utilize the background for high-efficient transcoding?
- ✓ How to exploit the characteristics of surveillance video for fast transcoding?

t

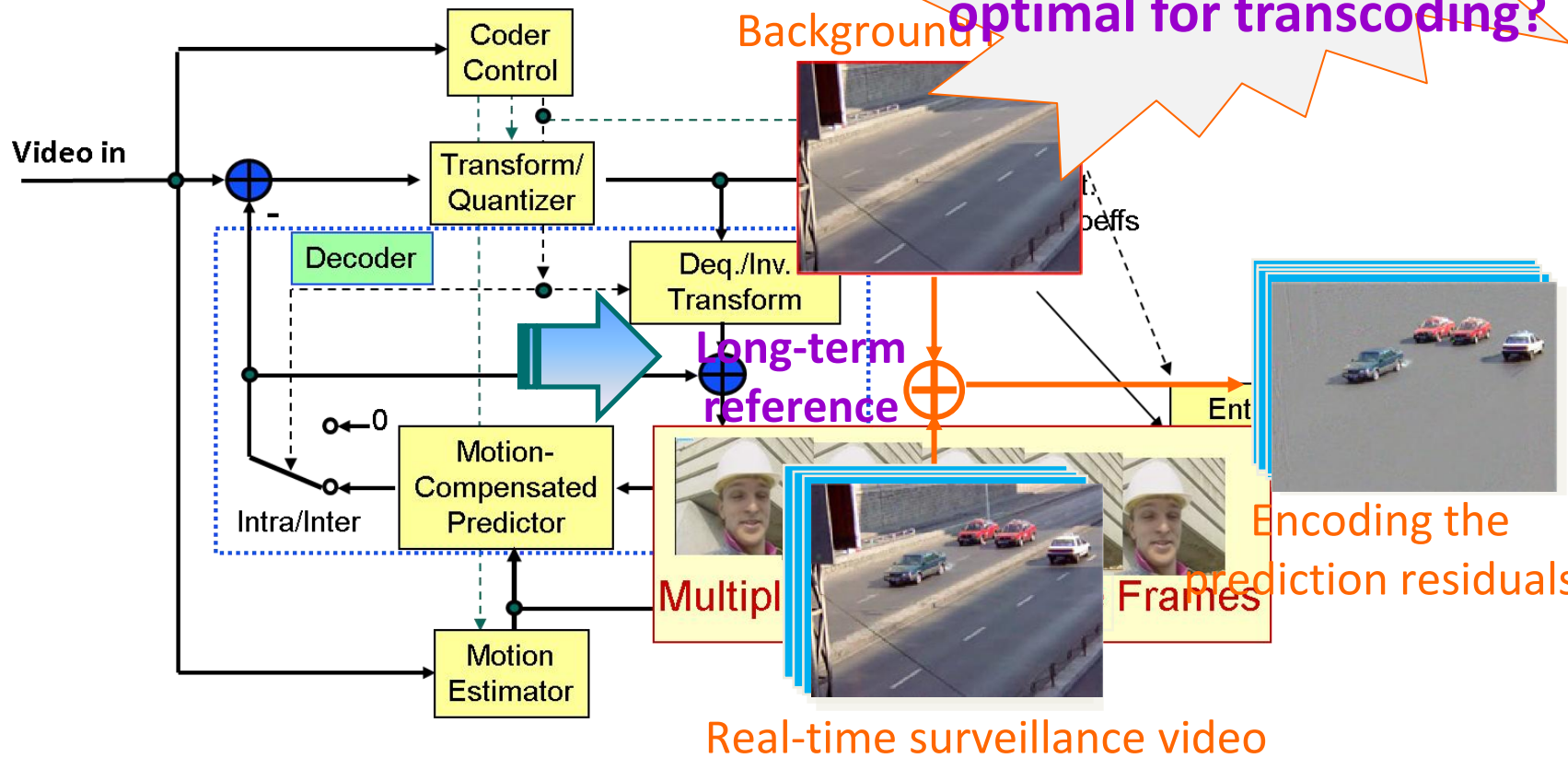
High-Efficient Transcoding:

Background Model as the Reference

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From: multiple past reference frames
To: background model as the reference

What kind of background model is optimal for transcoding?

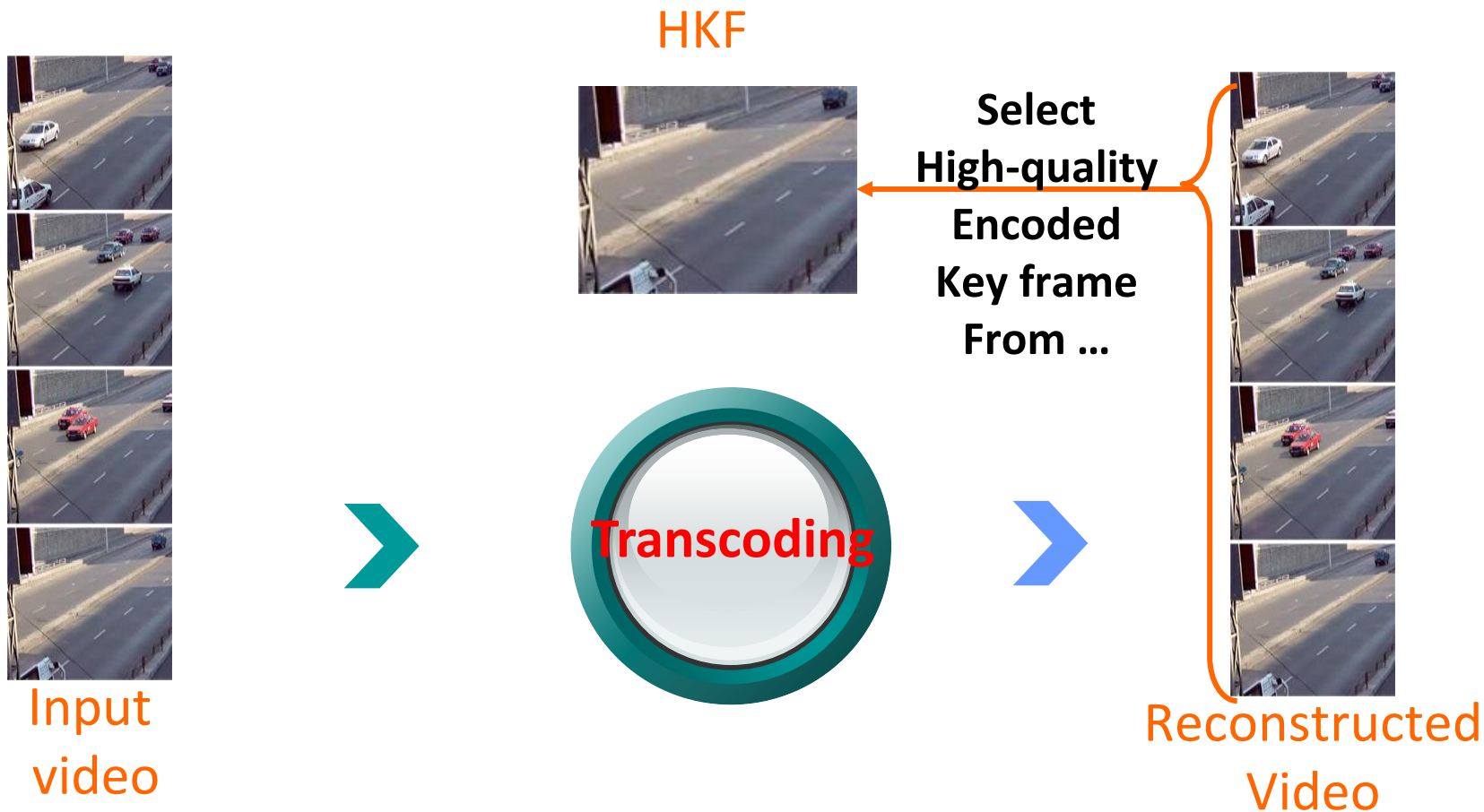


High-Efficient Transcoding:

Optimal Background Model

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(1) Using the high-quality-transcoded key frame (HKF) as long-term reference

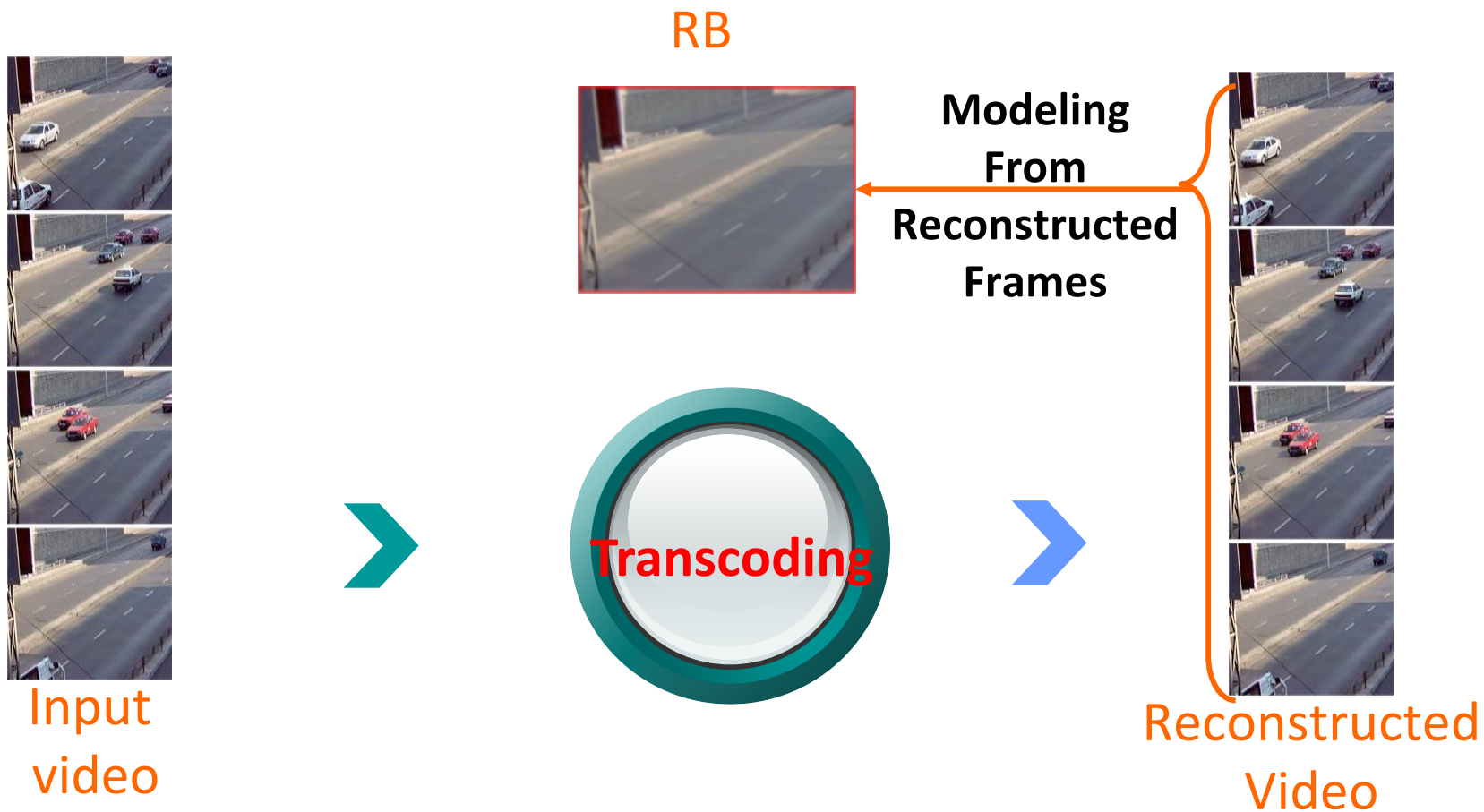


High-Efficient Transcoding:

Optimal Background Model

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(2) Using the background modeled from the reconstructed frames (RB) as long-term reference

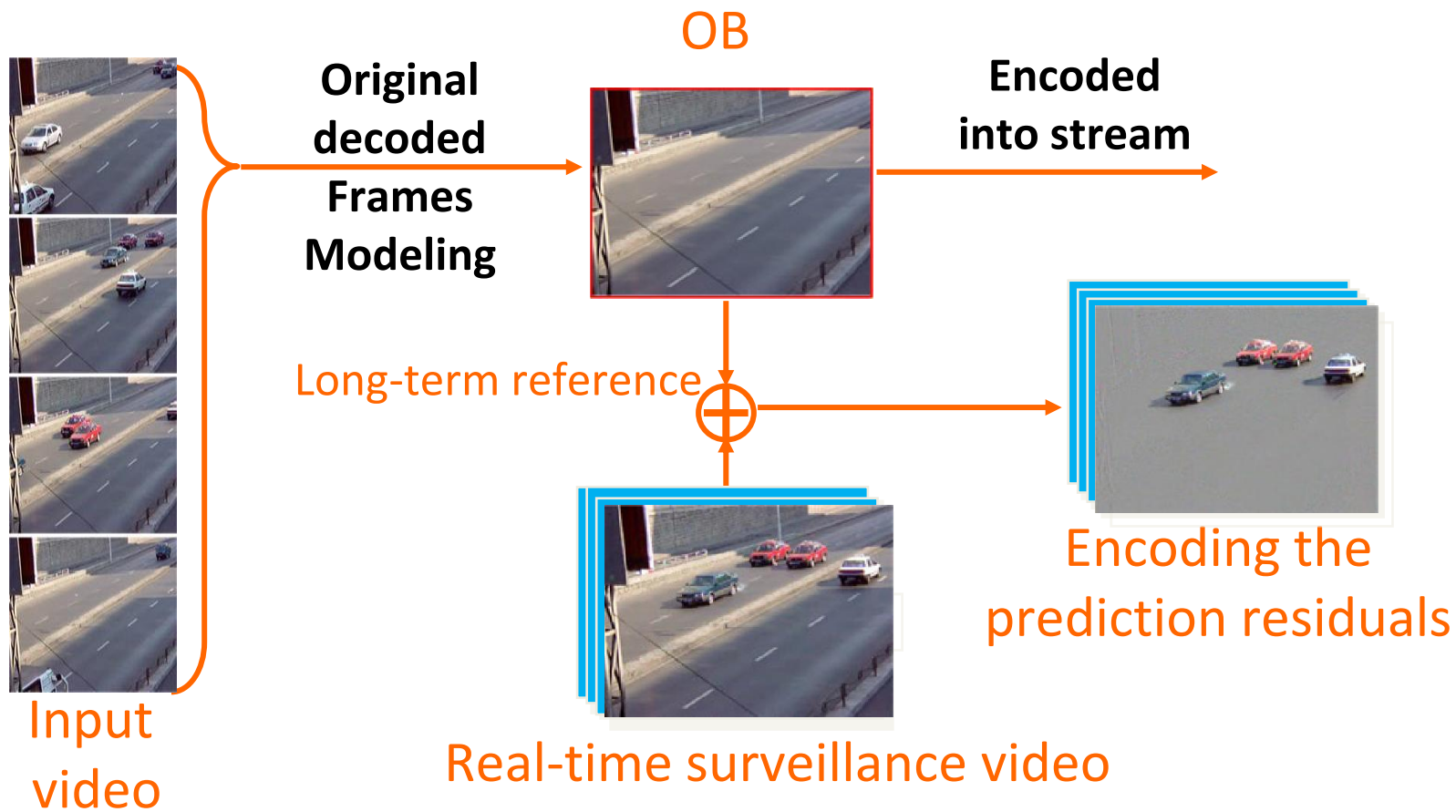


High-Efficient Transcoding:

Optimal Background Model

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(3) Using the background modeled from the original-decoded frames (OB) as long-term reference



High-Efficient Transcoding: *Theoretical Analysis: Why the OB is best?*

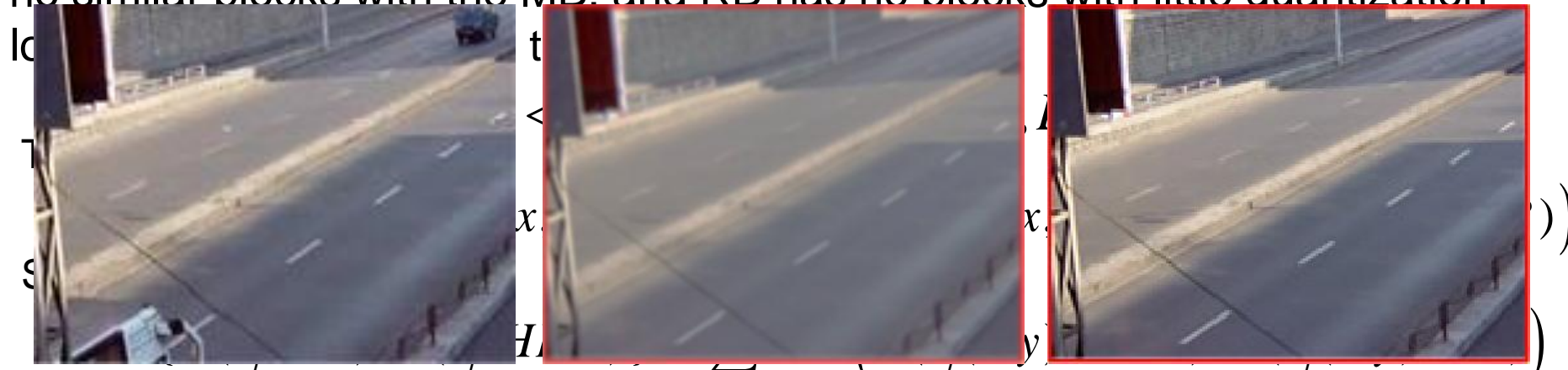
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Exploiting the original-decoded-frame to train the background (OB) can achieve the best transcoding gains!

Lemma 1: *The distortion of OB is minimal*

$$D(OB, \Lambda) < \min \{ D(HKF, \Lambda), D(RB, \Lambda) \}$$

Proof: For any MB with the position (x, y) in an input frame $I_i \in \Lambda$, HKF has no similar blocks with the MB, and RB has no blocks with little quantization



We get **High quality** **But Not clean** $D(I_i, OB) = \sum_{x,y} D(I_i(x,y), OB)$ **Clean** **But Not high quality** $< \min \{ D(I_i, RB), D(I_i, HKF) \}$ **Clean and High quality**

By integrating results for all frames in Λ , we can obtain the lemma.

High-Efficient Transcoding:

Theoretical Analysis: Why the OB is best?

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Lemma 2: *The power spectral density of OB is minimal*

$$\Phi_{OB}(\Lambda) < \min \left\{ \Phi_{RB}(\Lambda), \Phi_{HKF}(\Lambda) \right\}$$

Proof of Lemma 2 can be derived from [Leontaris & Cosman, 2007] and [Girod, 1987]

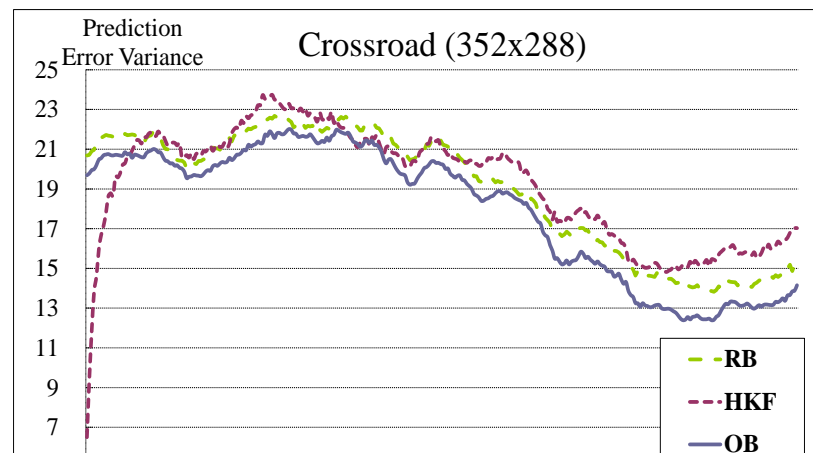
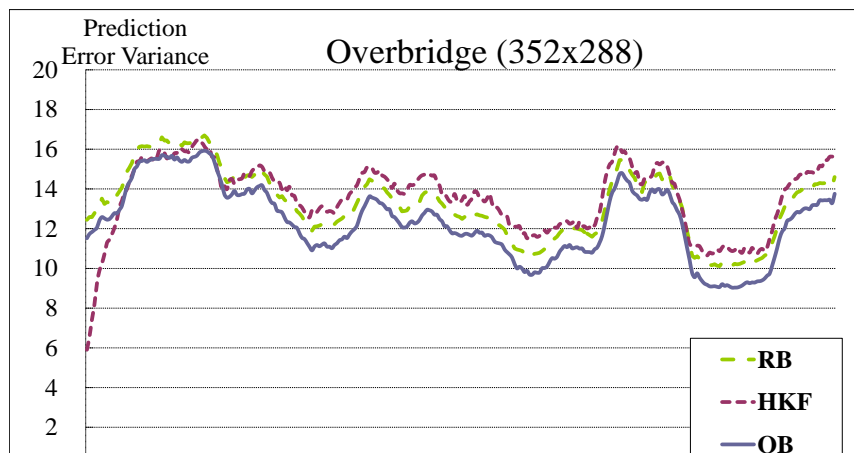
$$\Delta\Phi_{OB,HKF}(\Lambda) = \Phi_{OB}(\Lambda) - \Phi_{HKF}(\Lambda)$$

$$\approx \frac{1}{4} \times \sum_{k=1}^n \left(\Psi(\Gamma(I_k(x, y), OB)) - \Psi(\sum_{x,y}(\Gamma(I_k(x, y), HKF))) \right) < 0$$

$$\Delta\Phi_{OB,RB}(\Lambda) = \Phi_{OB}(\Lambda) - \Phi_{RB}(\Lambda)$$

$$\approx \sum_{k=1}^n \left(\Psi(\Gamma(I_k(x, y), OB)) - \Psi(\sum_{x,y}(\Gamma(I_k(x, y), RB))) \right) < 0$$

$$\Delta\Phi_{i,j}(\Lambda) \approx \frac{\Phi_{nn_l_i}(\Lambda) - \Phi_{nn_l_j}(\Lambda)}{4}$$



After the initial several frames, the PEV of the OB becomes less than that of the HKF and RB.

High-Efficient Transcoding:

Theoretical Analysis: Why the OB is best?

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Theorem 1: *Let $RD(OB, \Lambda)/RD(RB, \Lambda)/RD(HKF, \Lambda)$ denote the rate-distortion performance between an input long surveillance sequence and OB/RB/HKF; Using the same motion search method,*

$$RD(OB, \Lambda) < \min \{RD(OB, \Lambda), RD(RB, \Lambda)\}$$

Proof:

As stated in [Liu et al. 2010], when given two prediction reference frames, **the one with smaller prediction distortion and smaller $\Phi(\Lambda)$** leads to a better compression efficiency.

Thus by integrating Lemma 1 and 2, we can derive Theorem 1.

**So the remaining problem becomes
*how to model OB from the decoded sequence?***

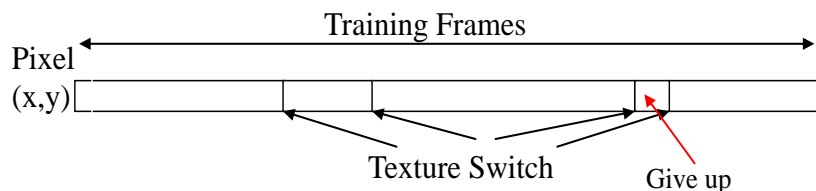
High-Efficient Transcoding:

Low-Complexity Background Modeling

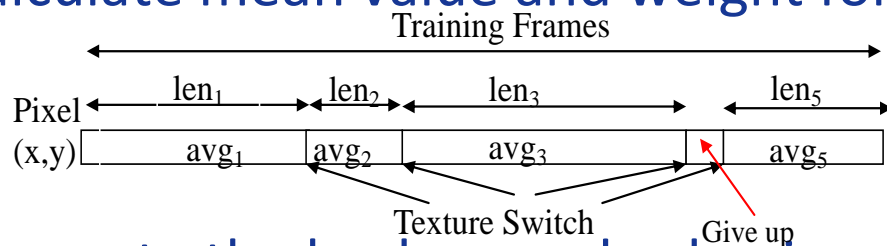
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❖ Segment-and-Weight based Running Averaging (SWRA)

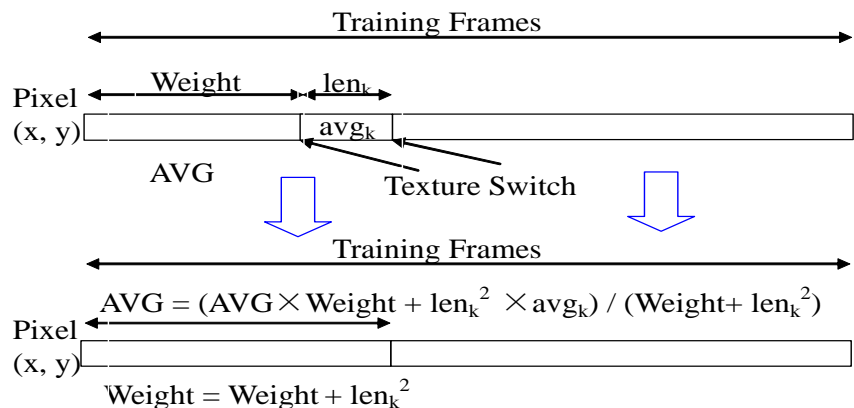
- Step 1: Divide training frames into segments



- Step 2: Calculate mean value and weight for each segment



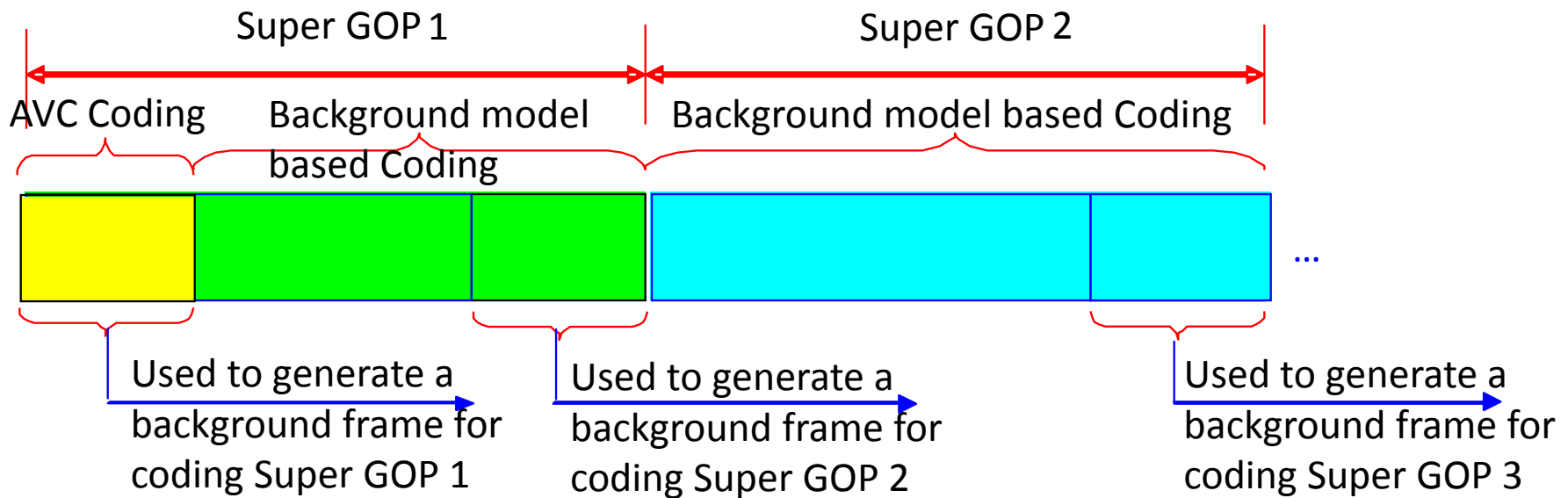
- Step 3: Generate the background value in a running way



High-Efficient Transcoding: Background Model Update

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❖ The no-delay sequence structure background updating



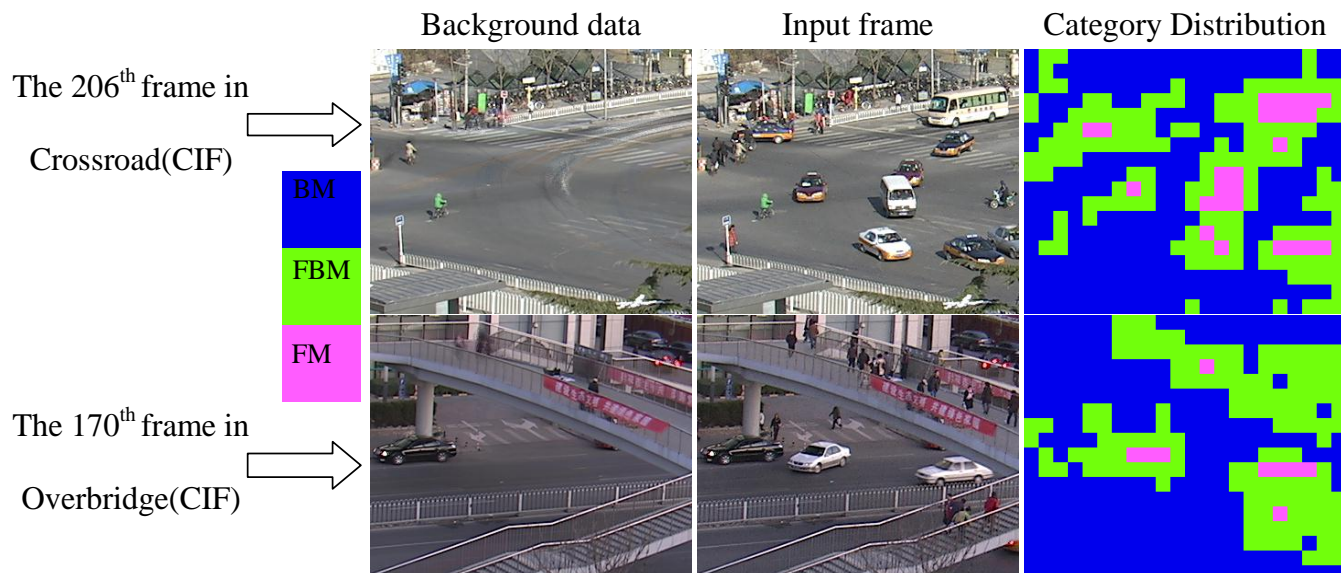
Fast Transcoding:

MB Classification Based Algorithms

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- ❖ Key idea: *To classify MBs into three categories, and then separately design suitable fast transcoding methods for each MB category.*

$$\sum_{i=1}^{N_B} \left((C_i - BG_i) - \beta \right) > 0$$



FM: With few background pixels

BM: With few foreground pixels

FBM: foreground border MBs

Fast Transcoding Algorithm 1: Reference Frame Selection

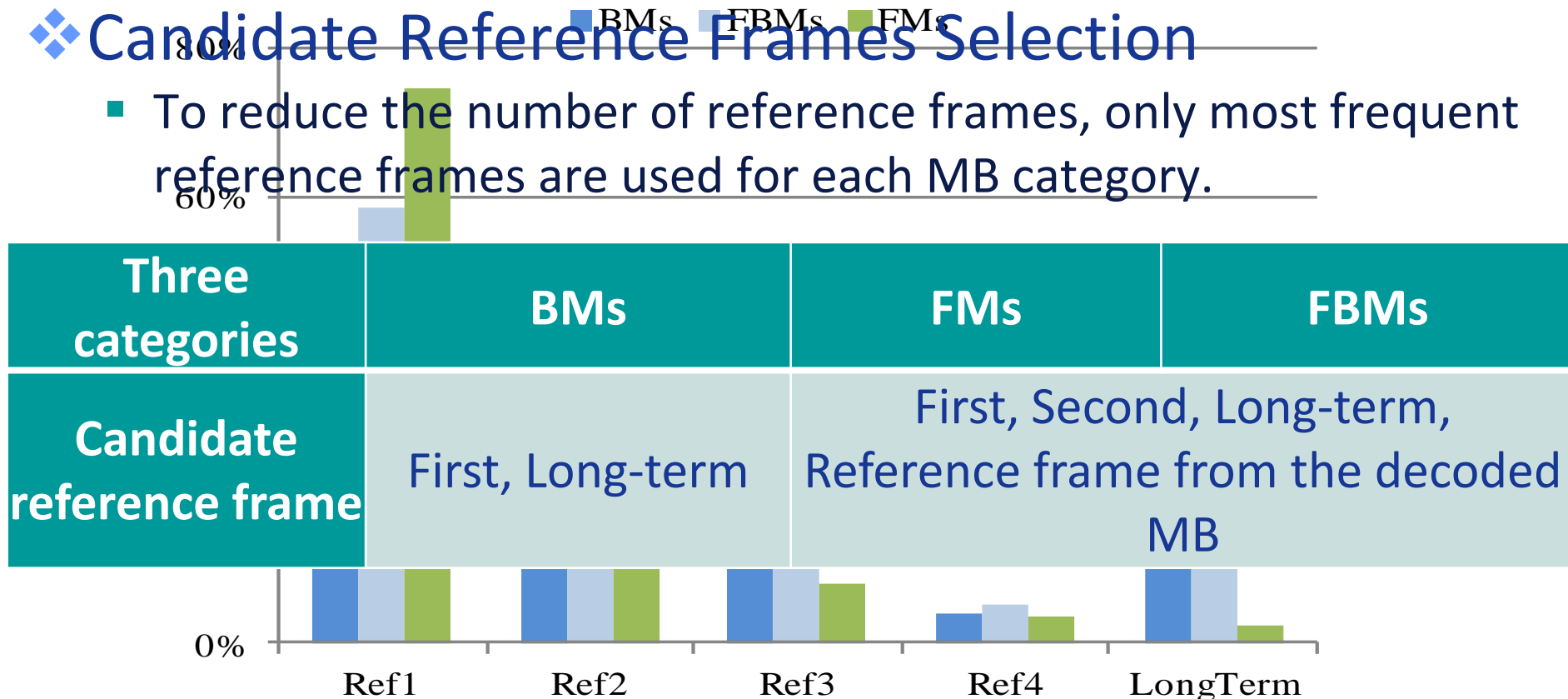
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❖ MB Category based Analysis for reference frames

- The 1st reference frame is necessary for all the MBs
- The long-term reference frame also takes up a large percent for BMs and FBMs

❖ Candidate Reference Frames Selection

- To reduce the number of reference frames, only most frequent reference frames are used for each MB category.



Fast Transcoding Algorithm 2: Adaptive Motion Search Range Calculation

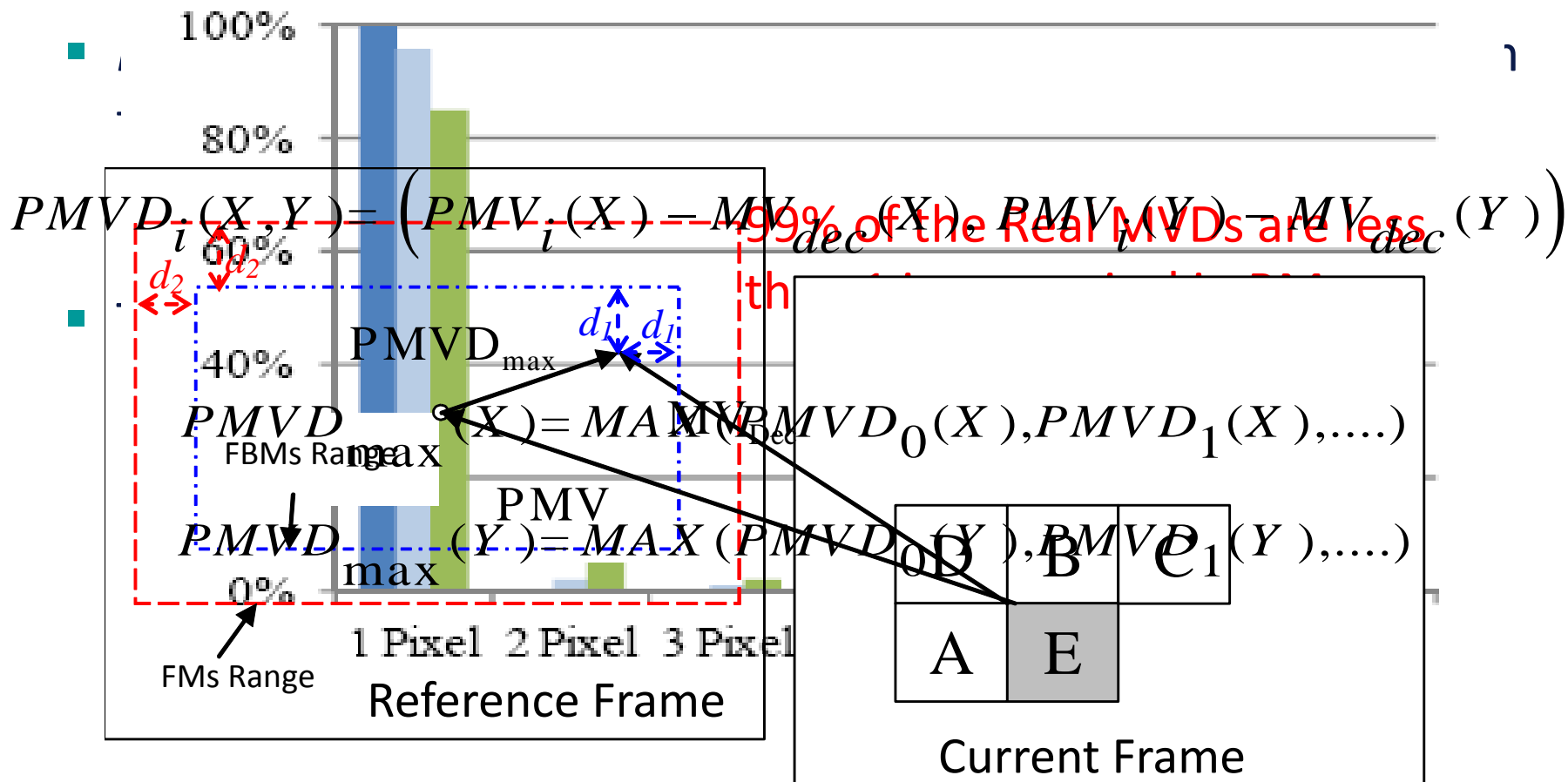
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❖ Analysis for the distribution of Real MVDs

Real MVDs: difference between decoded MV and predicted MV

❖ Metrics

■ BMs ■ FBMs ■ FMs



Fast Transcoding Algorithm 2: *Adaptive Motion Search Range Calculation*

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Input:

R_{org} : the original input motion search range

$PMVD_{max}(i)$: the maximum value of $PMVD(X)$ or $PMVD(Y)$

d_1 : the extra search range for FBMs

d_2 : the extra search range for FMs

Initialization:

The output value R_{mod} is initialized to R_{org} .

Calculation:

Classify each MB into different categories, then

A. For BM, R_{mod} is set to 1.

B. For FMs and FBMs:

If the MB is an FBM, set *Flag* to 0; else set *Flag* to 1.

if ($PMVD_{max}(i) == 0$)

$$R_{mod} = 1 + 1 \times Flag,$$

else if ($PMVD_{max}(i) == 1$)

$$R_{mod} = d_1 + d_2 \times Flag,$$

else if ($PMVD_{max}(i) \leq R_{org} - d_1 - d_2$)

$$R_{mod} = PMVD_{max}(i) + d_1 + d_2 \times Flag,$$

else

$$R_{mod} = R_{org};$$

Output: R_{mod}

Fast Transcoding Algorithm 3: Mode Decision Refinement

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Analysis for the distribution of candidate modes

- SKIP and 16x16 prediction forbidden in this step in almost 99% of FMs. E and MD complexity
- 16x16 intra prediction is seldom used in FBMs

Decode Mode	FMs	FBMs	BMs
S	level1, I16MB		16x16, SKIP
8x4	level2, I16MB	level2	
4x8			
4x4	level3, I16MB	level3	
I4MB			

*S: Decode Mode Size={ SKIP,16x16,16x8,8x16,8x8, I16MB},

*level1={SKIP,16x16,16x8,8x16,8x8,I4MB},

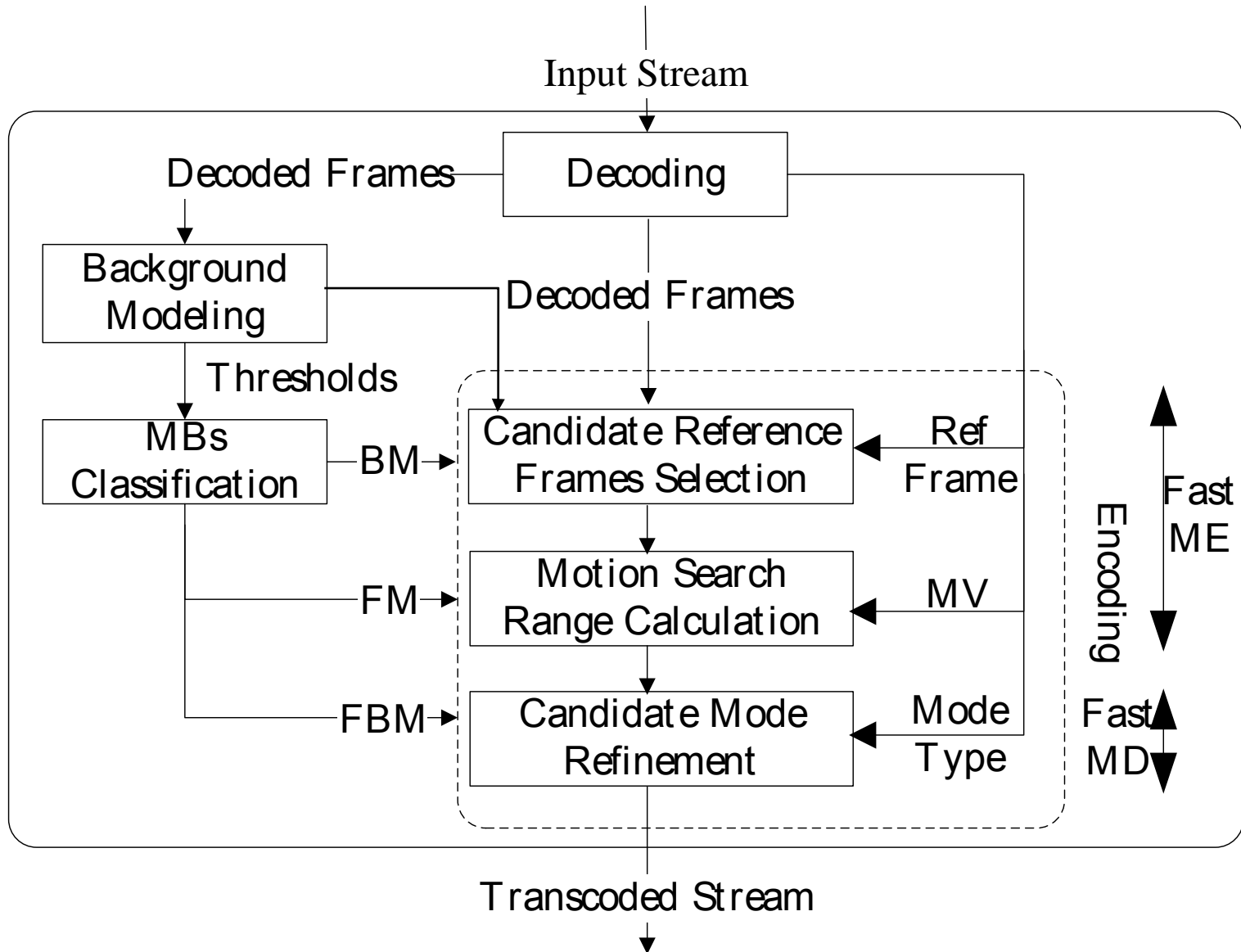
*level2={SKIP,16x16,16x8,8x16,8x8,I4MB,8x4,4x8},

*level3={SKIP,16x16,16x8,8x16,8x8,I4MB,8x4,4x8,4x4}

SKIP 16x16 16x8 8x16 8x8 8x4 4x8 4x4 I4MB I16MB

System Framework

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Experiments

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Extensive Datasets

2 Mbps



Crossroad (CIF)

Overbridge (CIF)

Snowroad (CIF)

Snowway (CIF)

4 Mbps



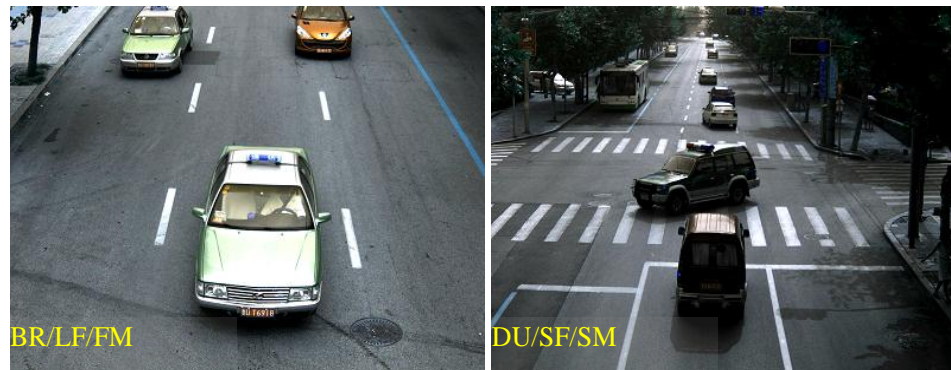
Crossroad (SD)

Overbridge (SD)

Office (SD)

Bank (SD)

32 Mbps



CarRoad (HD)

Crossroad (HD)

Experimental Setup

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❖ Transcoding Anchors

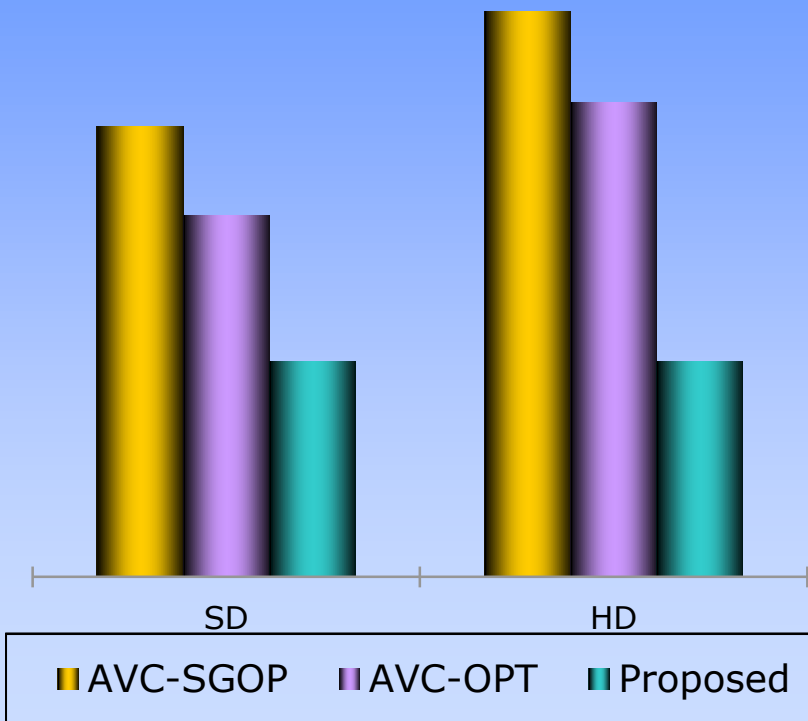
- **FDFE+AVC-SGOP**: H.264 with IntraPeriod=Length of S-GOP
- **FDFE+AVC-OPT**: H.264 using Key Frame as long-term reference

Parameter	Value	Parameter	Value
Porfile	Baseline	Used MODE	ALL
Rate Control	Disable	Framerate	25
Entropy Coding	UVLC	Frame Structure	IPPP
Search Range	32	IntraPeriod	0
RD Optimization	High	SAD Method	Hadamard
Motion Search	Fast Full	Reference Num	5

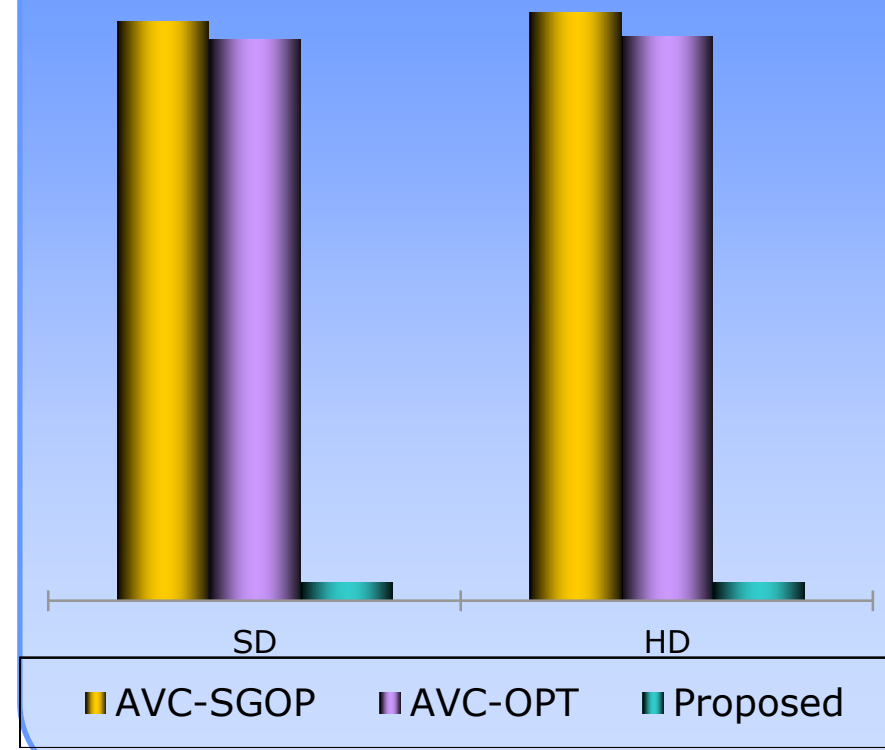
Experimental Results (1)

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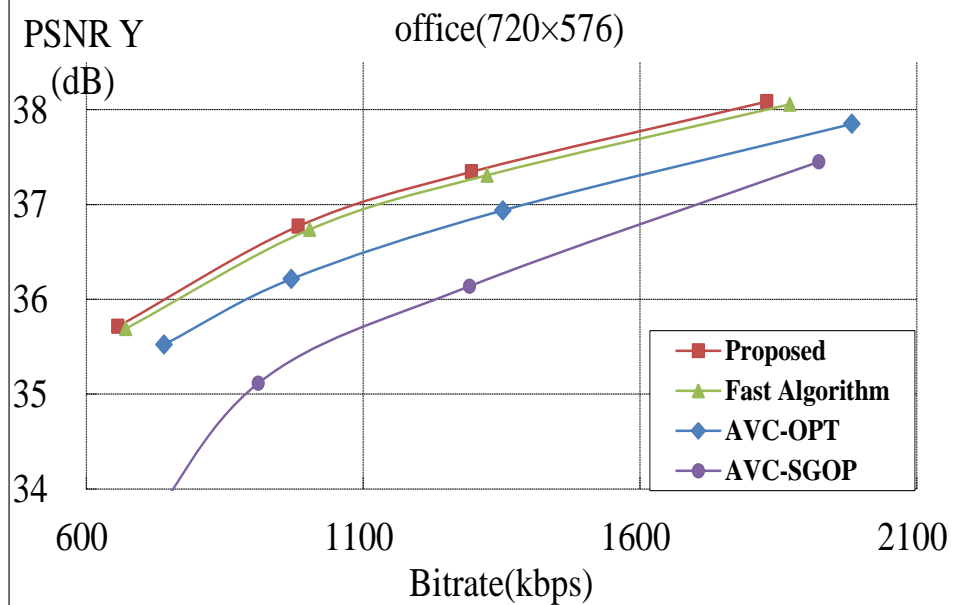
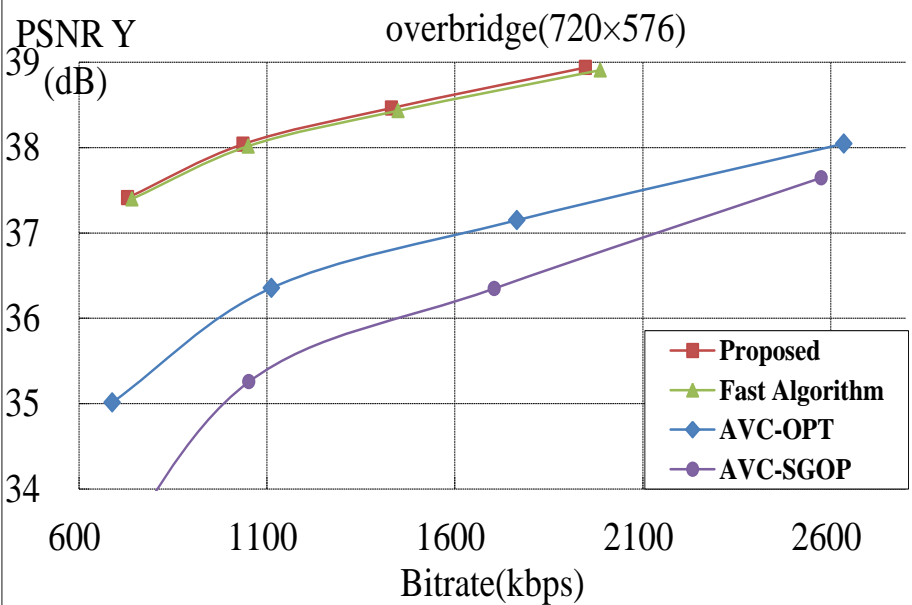
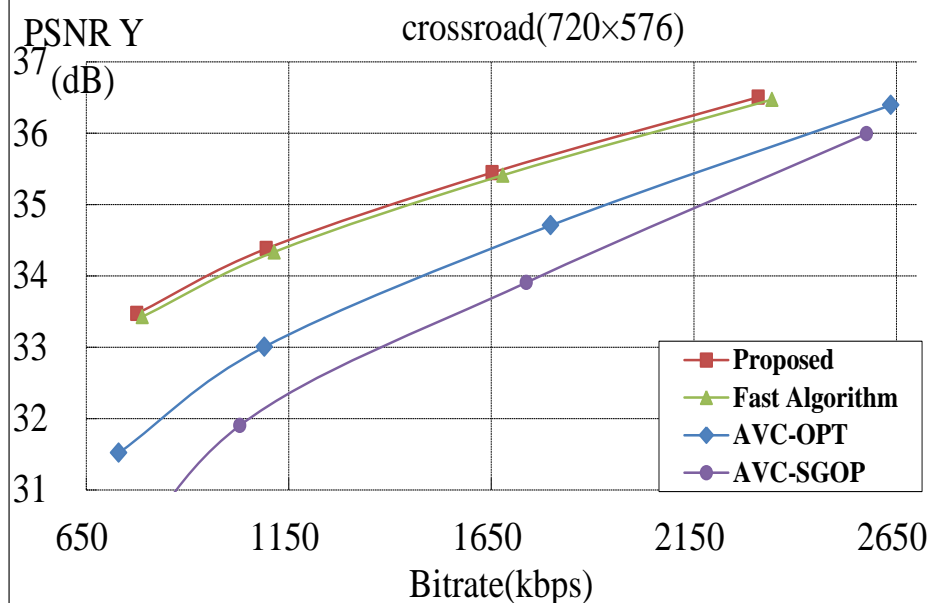
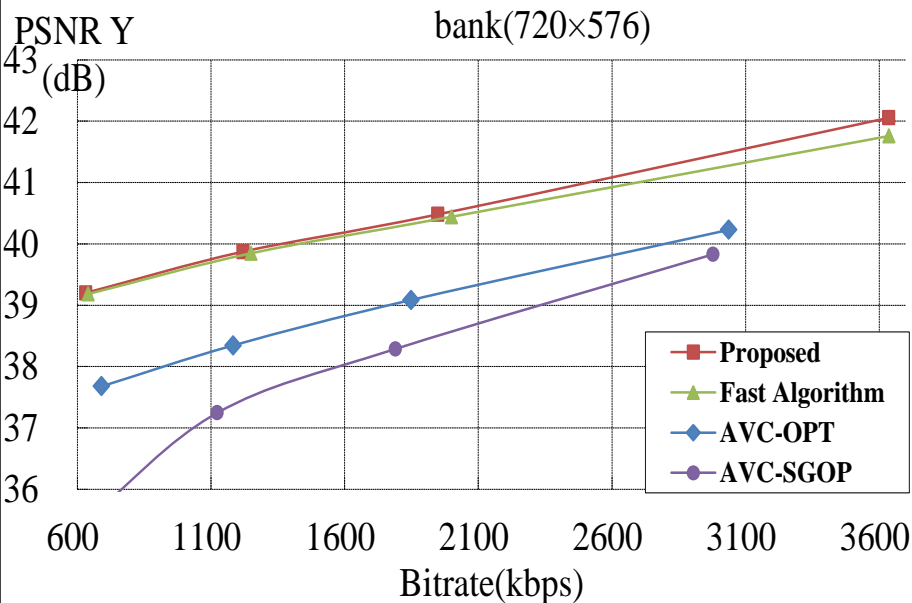
Bitrate



Complexity



Experimental Results (2)



Experimental Results (3)

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❖ Contribution Distribution of Different Components

- Motion search range results in significant total-time saving

Table 5. Separate contribution for each algorithm (%)

	Crossroad	Overbridge	Snowroad	Snowate.	average
Search Range Calculation	93.91	93.02	94.77	94.90	94.15
Mode Refinement	12.29	10.69	16.73	14.00	13.43
Reference Frame Selection	34.05	31.17	47.89	42.08	38.80

Table 6. Search Points Reduction(%)

Crossroad	Overbridge	Snowroad	Snowate.	average
87.42	80.00	93.48	95.35	89.06

DEMO

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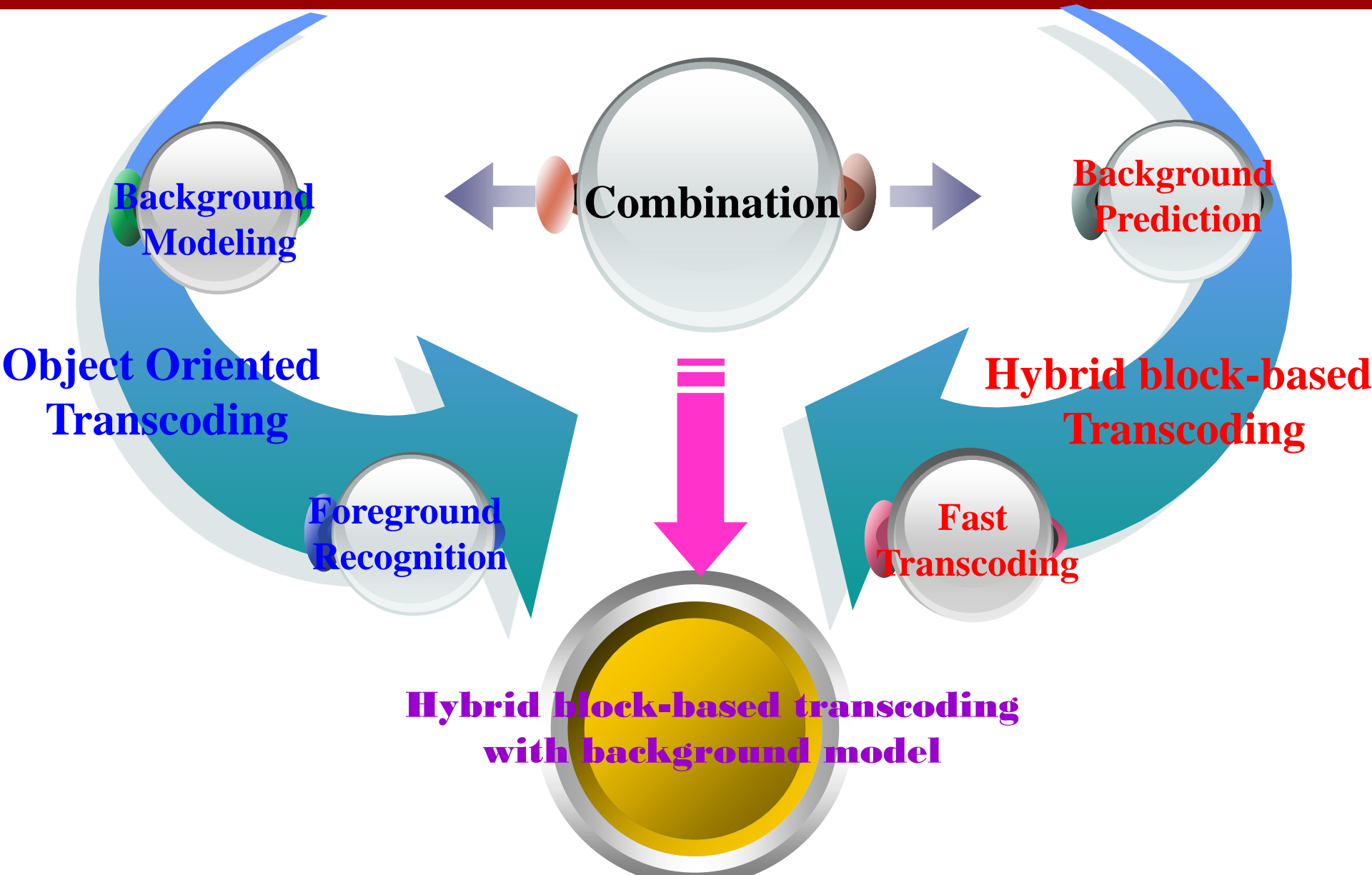
SD Sequence: From 2.3M to 440k

Super-Compressor for Surveillance Video

- High-efficiency: 2~10 times of H.264 HP
- Low transcoding complexity: About 5% of the state-of-the-art encoder

Conclusion

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Conclusion

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Contribution

Theoretically prove OB is an optimal reference, transcoding
With this background model saves half the bit-rate

MB-classification based Analysis and design
three methods to speed-up the transcoding

Extensive Experiments On CIF/SD/HD Videos

Practically co-operating with Hisense Co. LTD. for
Surveillance Video transcoding



Thank You !