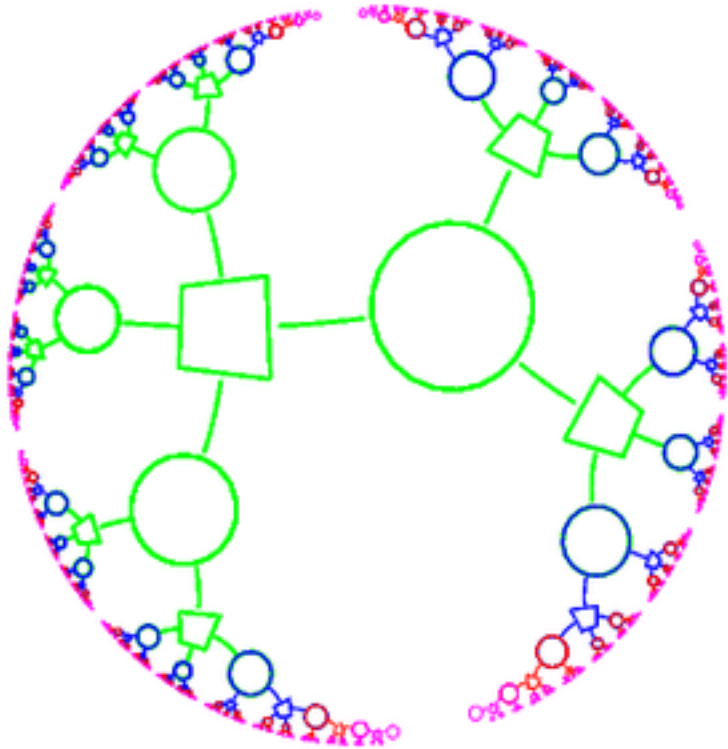


Advanced
Monte
Carlo
Methods

Information theory, pattern recognition, and neural networks



- Source coding (Data compression)
- Noisy-channel coding
- Inference + probabilistic methods
 - 9-10 Inference
 - 11 Clustering
 - 12 Monte Carlo methods
 - 13 Advanced Monte Carlo methods
 - 14 Variational methods

www.inference.phy.cam.ac.uk/itprnn/

www.inference.phy.cam.ac.uk/itila/

Overview

- Data compression
- Noisy-channel coding
 - ▶ Chs 1-6, 8-10, 14
- Inference, data modelling
 - clustering, pattern recognition
 - ▶ Chs 20, 22
- Probability toolbox
 - Monte Carlo methods
 - ▶ Ch 29, 30, 32
 - Variational methods
 - ▶ Ch 33
- Neural networks
 - ▶ Chs 38, 39, (& perhaps 41, 44), 42
- State-of-the-art error-correcting codes

Recommended exercises

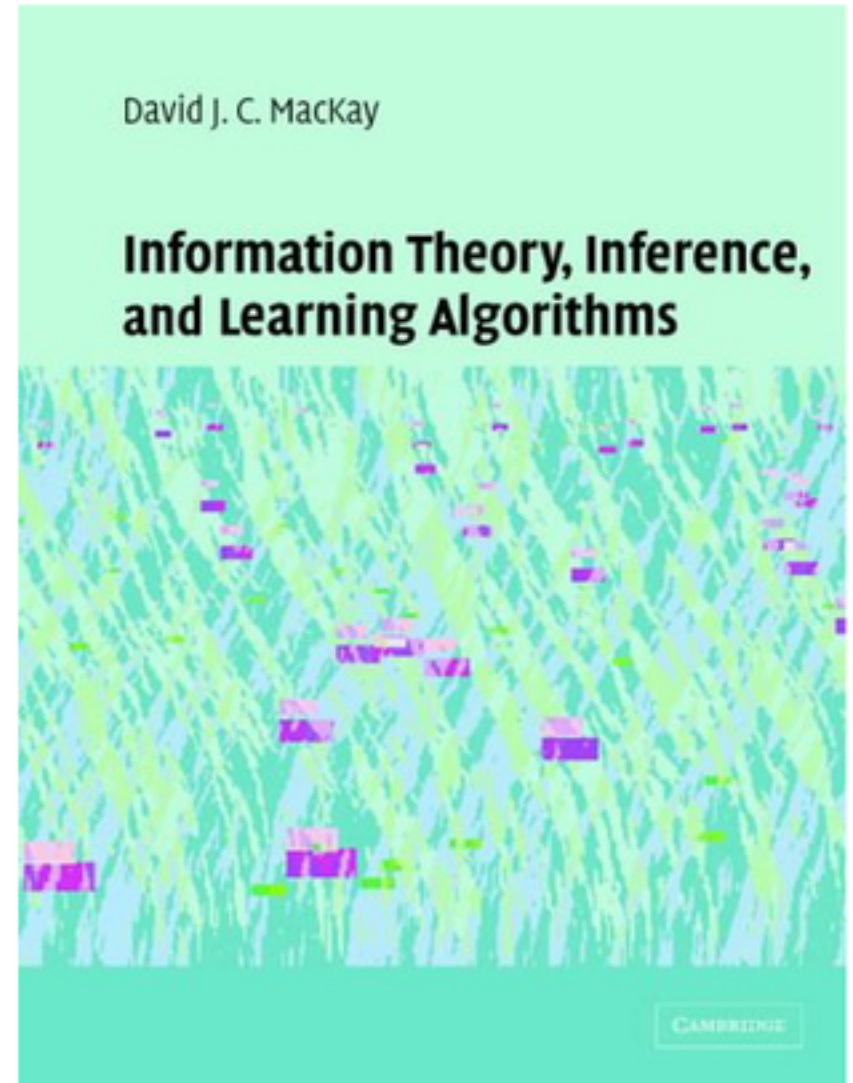
- 29.14, 33.5, 33.7, 27.1, 22.11, 39.4, 39.5
- Handouts 2, 3 (on website)
- The 5 cards magic trick (15.6)
 - 8♦, 2♥, 10♣, 9♦

Additional reading

- Laplace's method (Ch 27)
- Ising models (Ch 31)

The course

www.inference.phy.cam.ac.uk/itprnn/



The book

www.inference.phy.cam.ac.uk/itila/

Monte Carlo methods

Simple Monte Carlo methods

- Importance sampling
- Rejection sampling

Markov-chain Monte Carlo methods

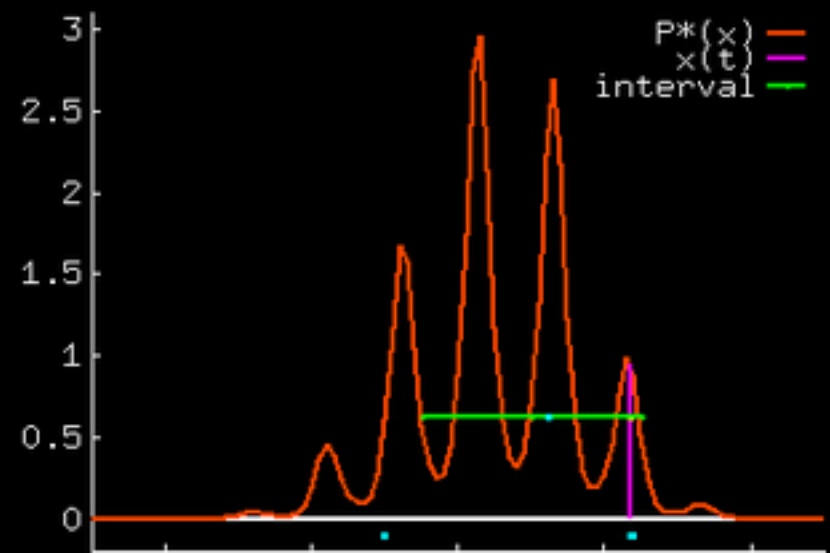
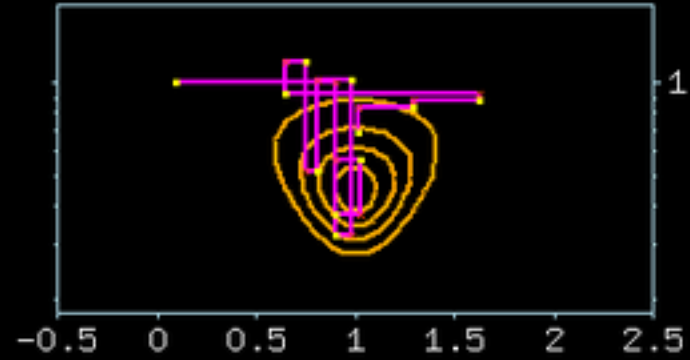
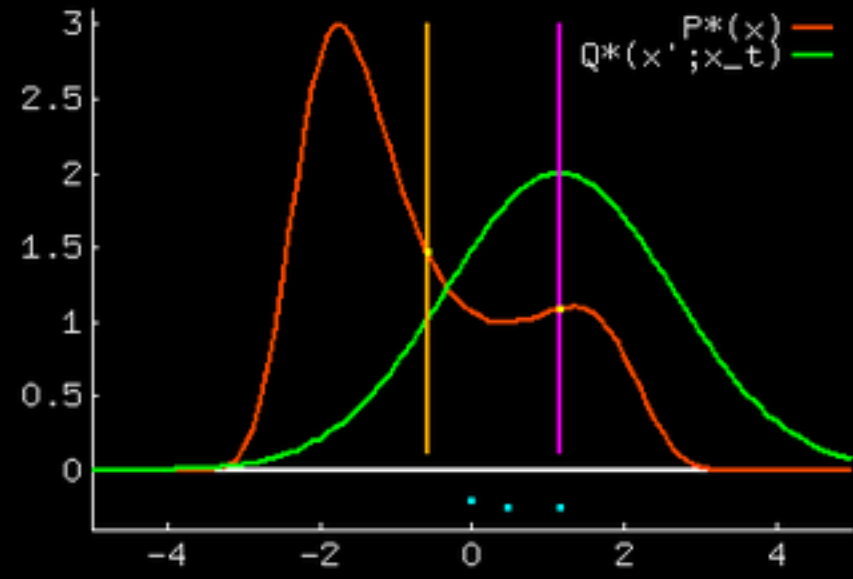
- Metropolis method
- Gibbs sampling
- Slice sampling

Reducing random-walk behaviour

- Hamiltonian Monte Carlo
- Overrelaxation

Exact sampling

[itp/exact/rc](#) RUNME



$$P(x) = \frac{P^*(x)}{Z} = \frac{e^{-E(x)}}{Z}$$

Can evaluate E
not Z

Problem 1

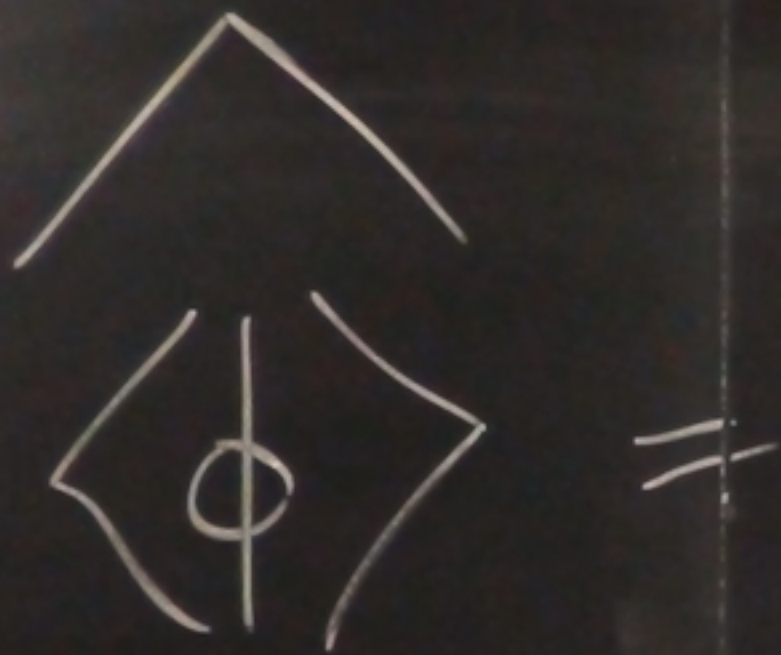
samples $x^{(r)} \sim P$

Problem 2

$$\langle \phi \rangle_P = \sum_x \underbrace{P(x)} \phi(x)$$

Samples $X^{(r)} \sim P$

$$\langle \phi \rangle_P = \sum_x P(x) \phi(x)$$



$$\sum \phi(x^{(r)})$$

R

$$P(x) = \frac{e^{-E(x; \underline{J})}}{Z(\underline{J})}$$

$$E(\underline{x}) = -\frac{1}{2} \sum_{m \neq n} \dots$$

$$E(x; \underline{J})$$

$$\overline{Z(\underline{J})}$$

$$Z(\underline{x}) = -\frac{1}{2} \sum_{m \neq n} J_{mn} x_m x_n - \sum_n h_n x_n$$

$$x \in \{-1, 1\}^N$$

$$\sum_n h_n x_n$$

$$\frac{e^{-\beta E(\underline{x}; \underline{J})}}{Z(\beta, \underline{J})}$$

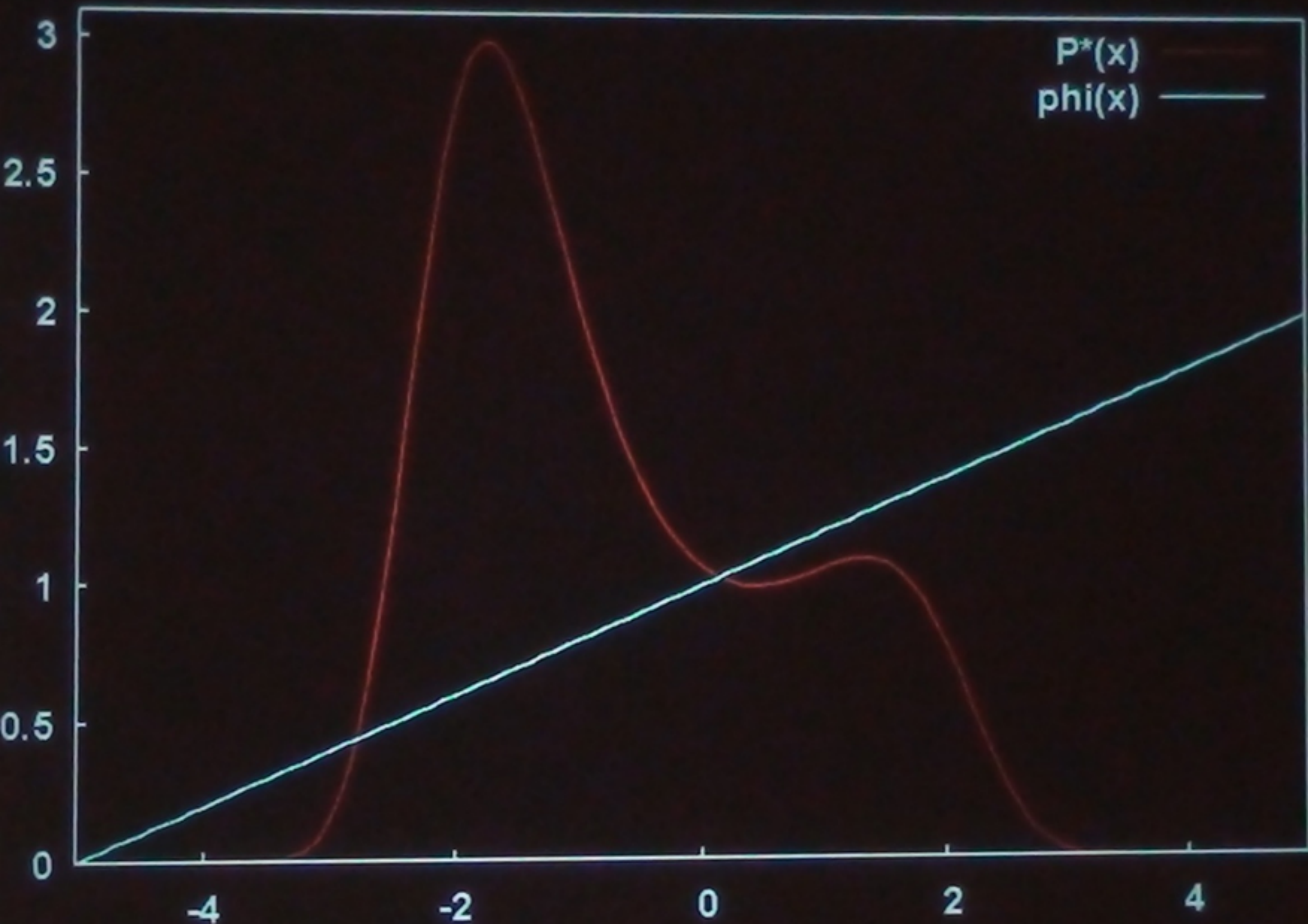
$$\beta \equiv \frac{1}{T}$$

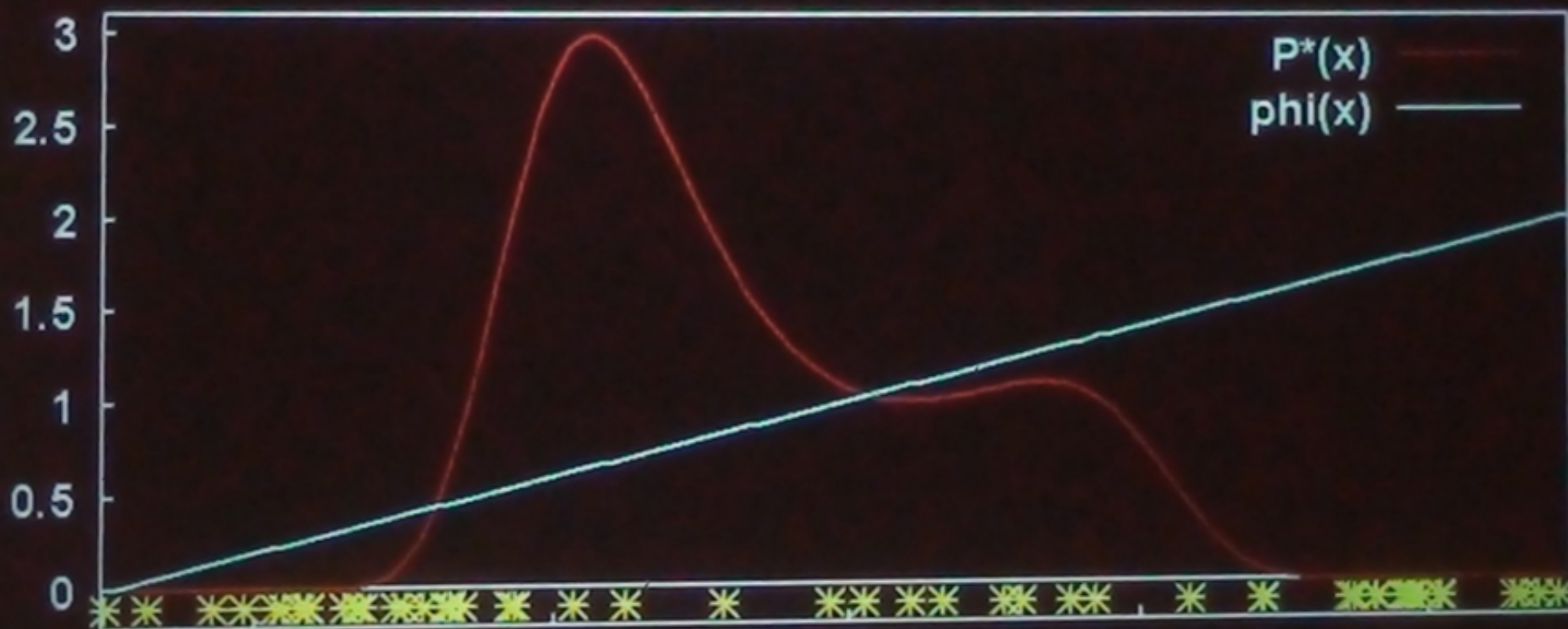
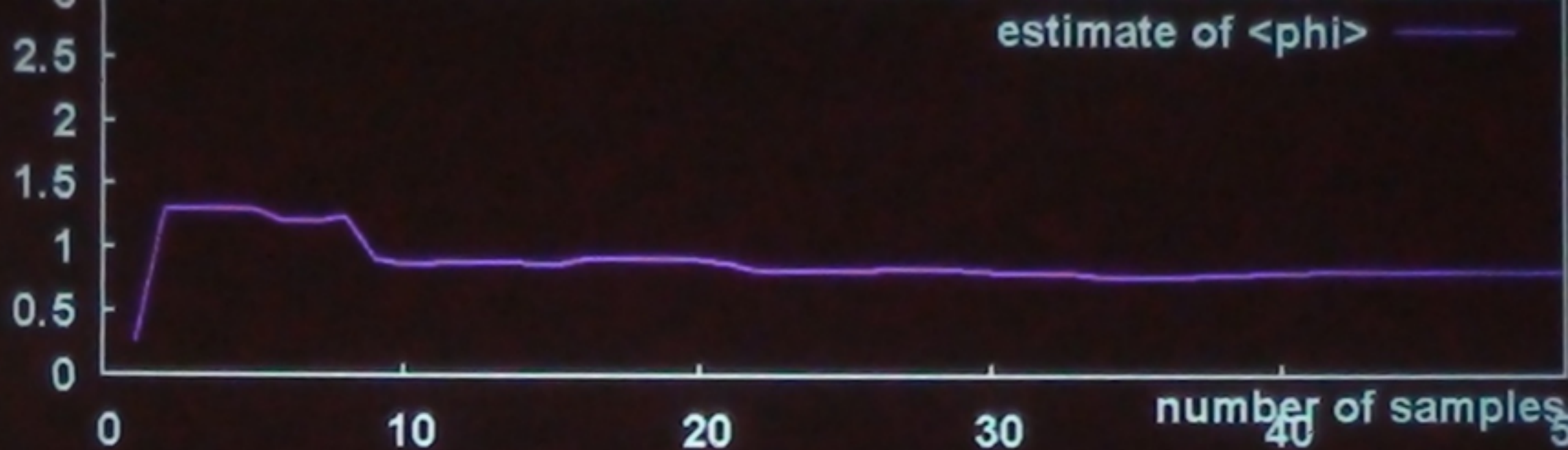
$$\underline{x} \in \{-1, 1\}^N$$

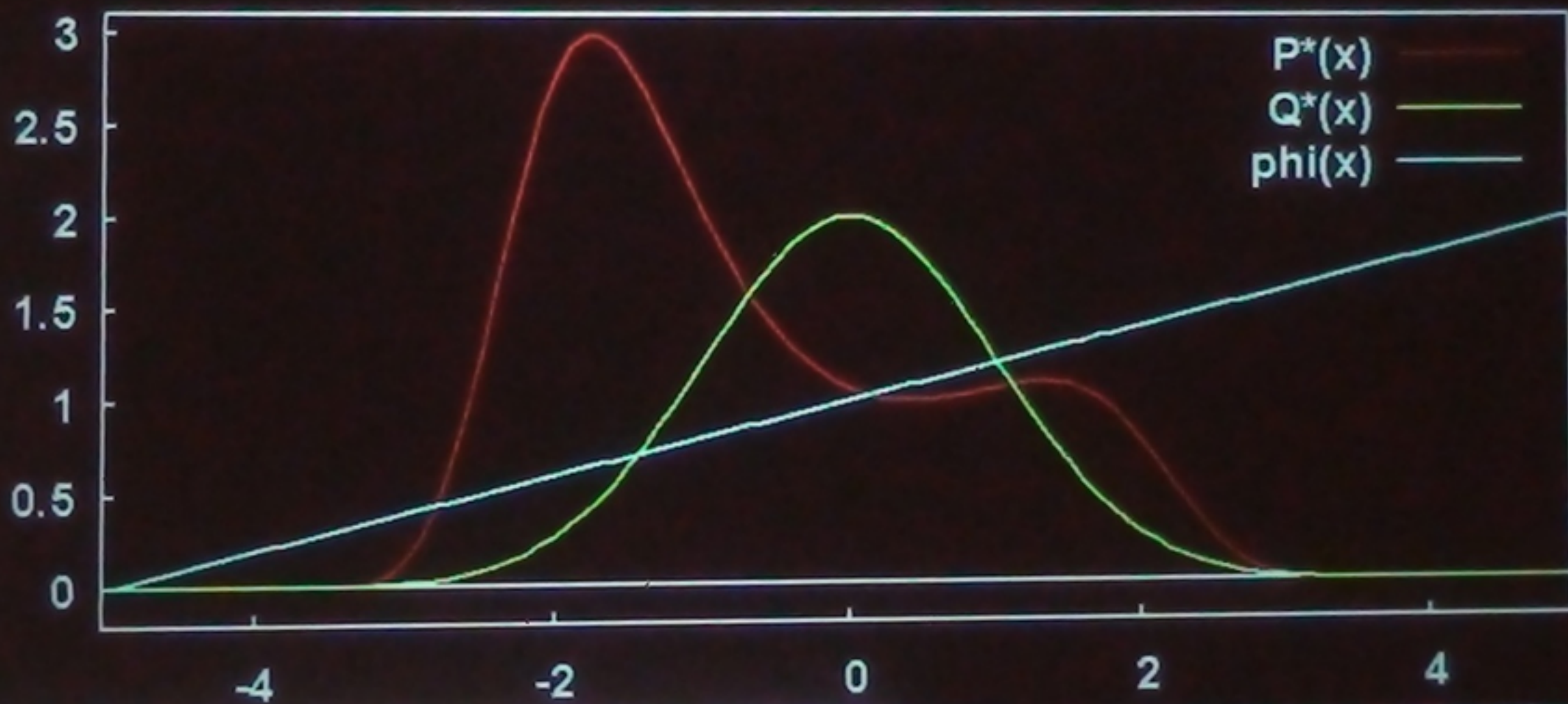
$$E(\underline{x}) = -\frac{1}{2} \sum_{m \neq n} J_{mn} x_m x_n - \sum_n h_n x_n$$

$\langle E \rangle$ $\langle E^2 \rangle$ $\langle m \rangle$ $\langle m^2 \rangle$

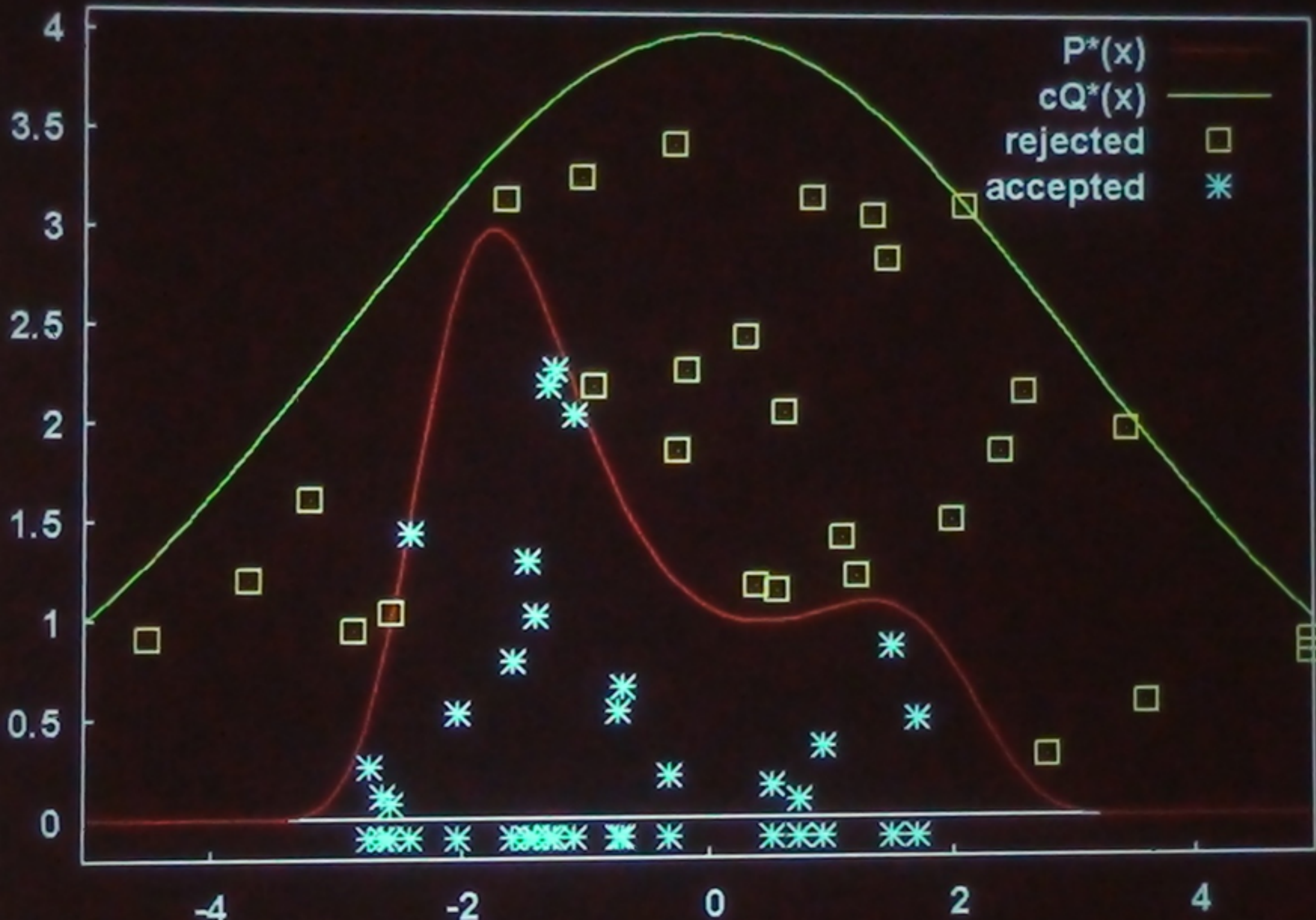
$$S = \left\langle \log \frac{1}{P(\underline{x})} \right\rangle_P$$



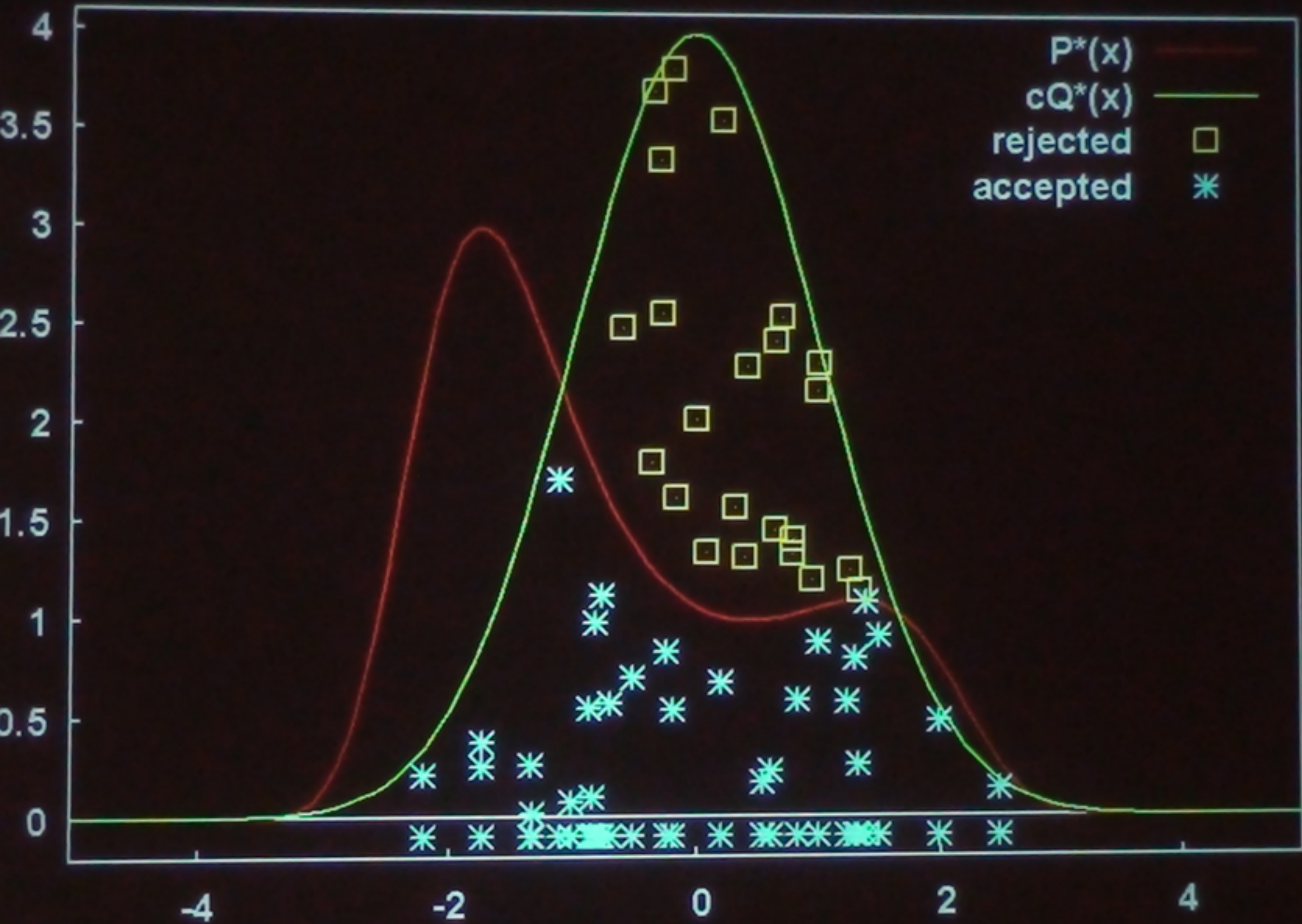


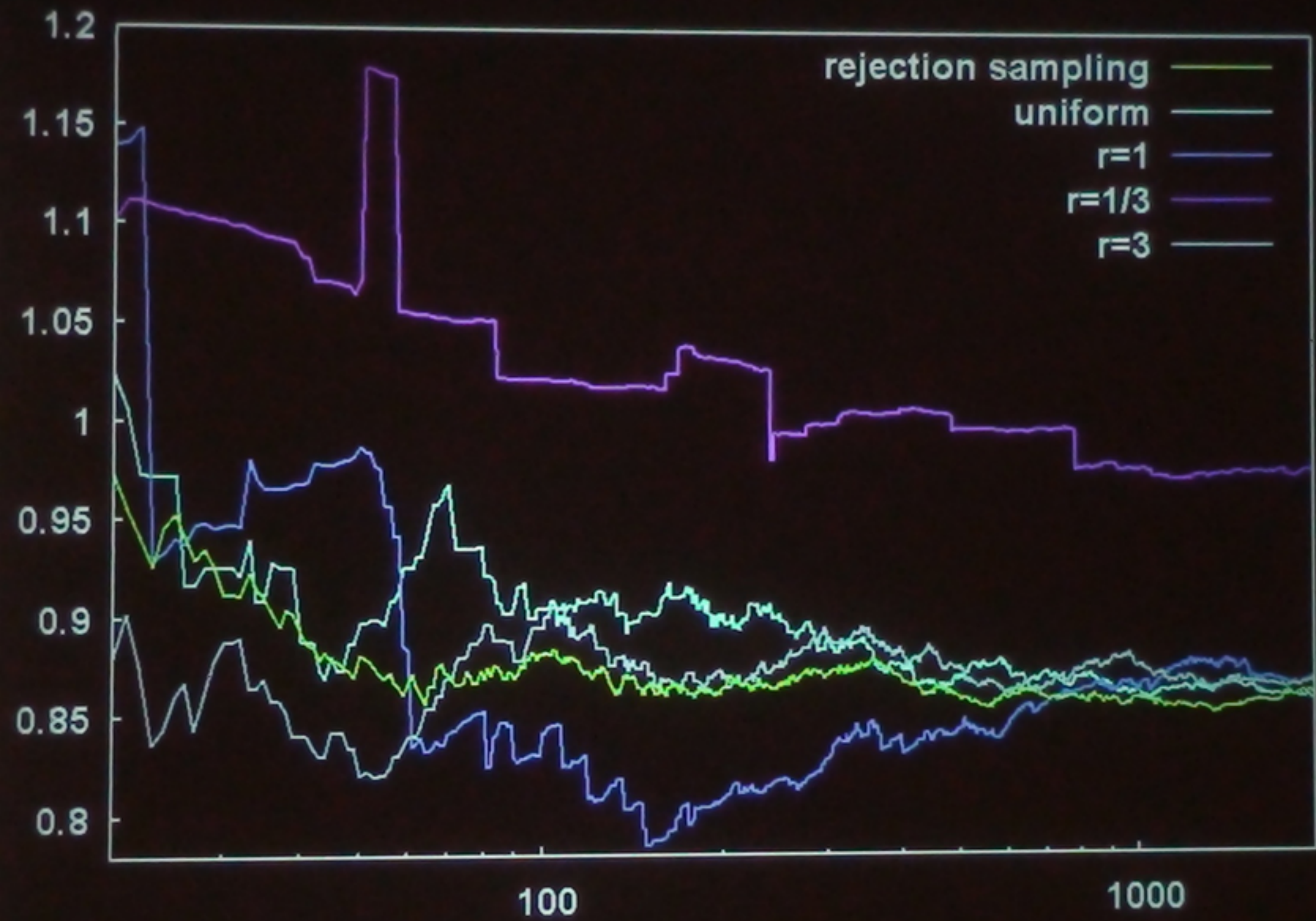


50 samples, 19 accepted

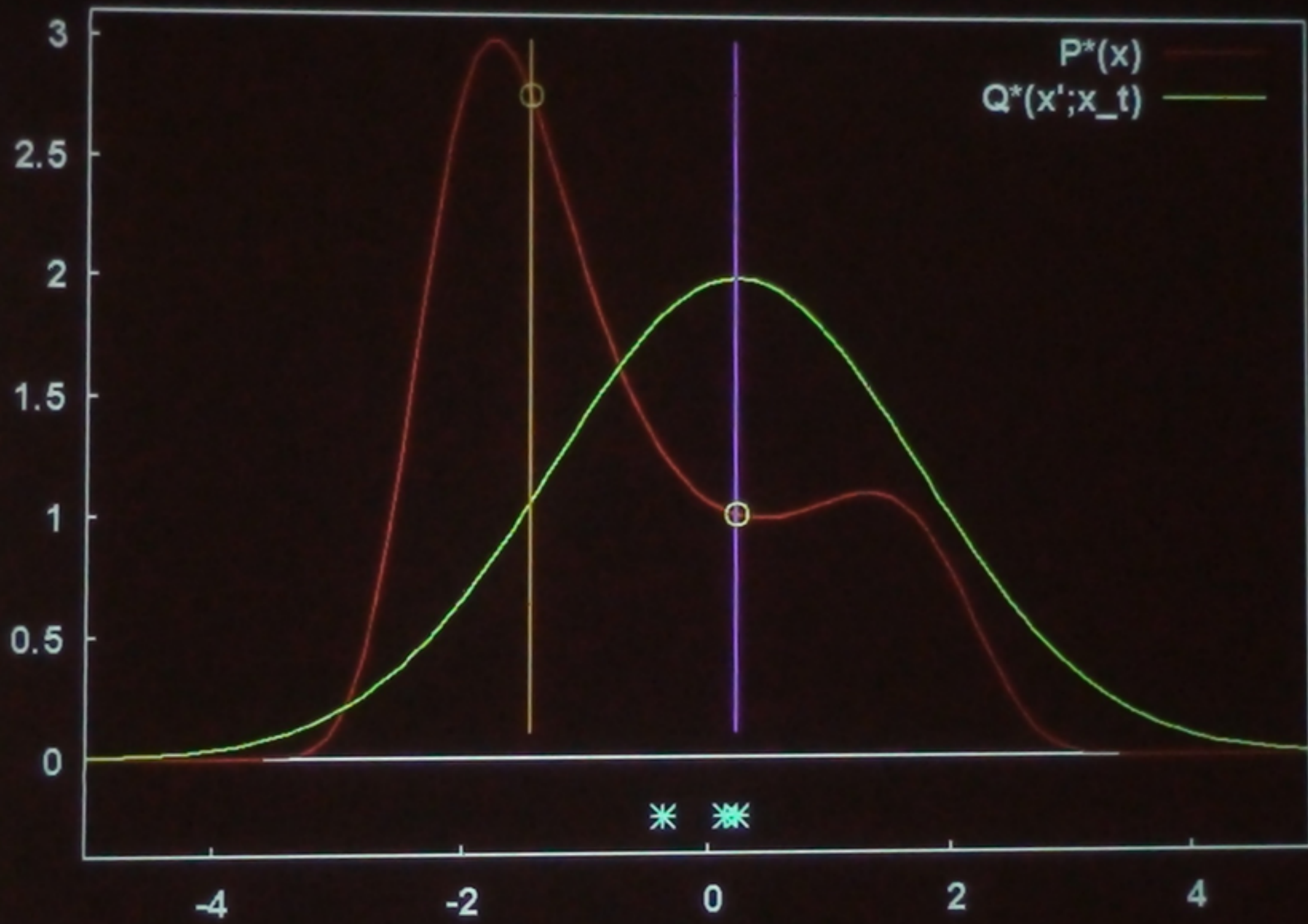


50 samples, 27 accepted





3 samples



Monte Carlo methods

Simple Monte Carlo methods

- Importance sampling
- Rejection sampling

Markov-chain Monte Carlo methods

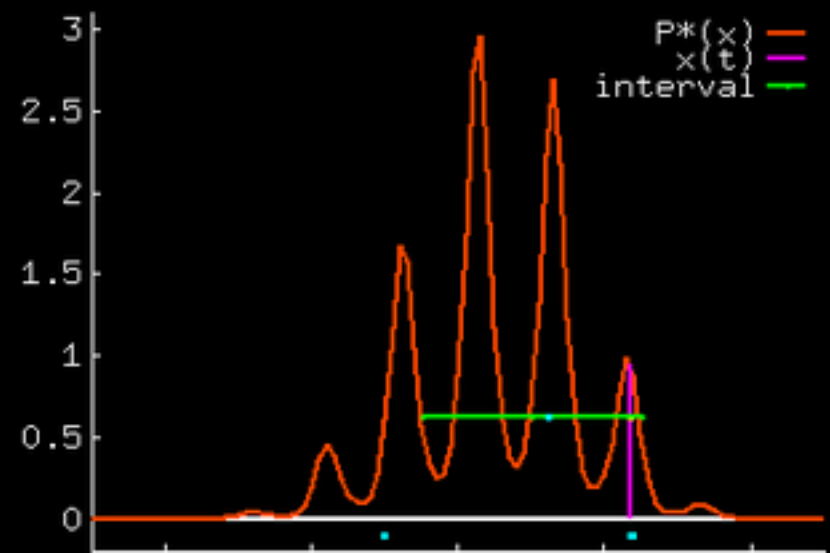
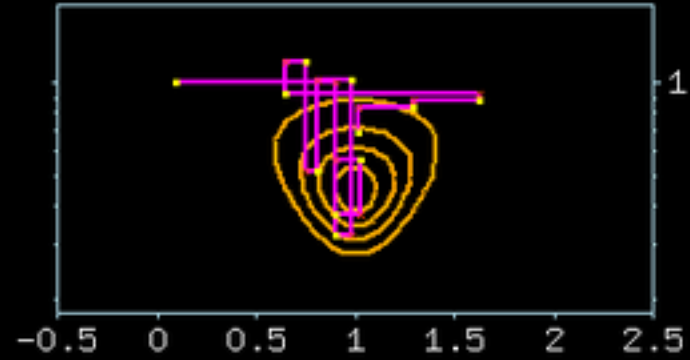
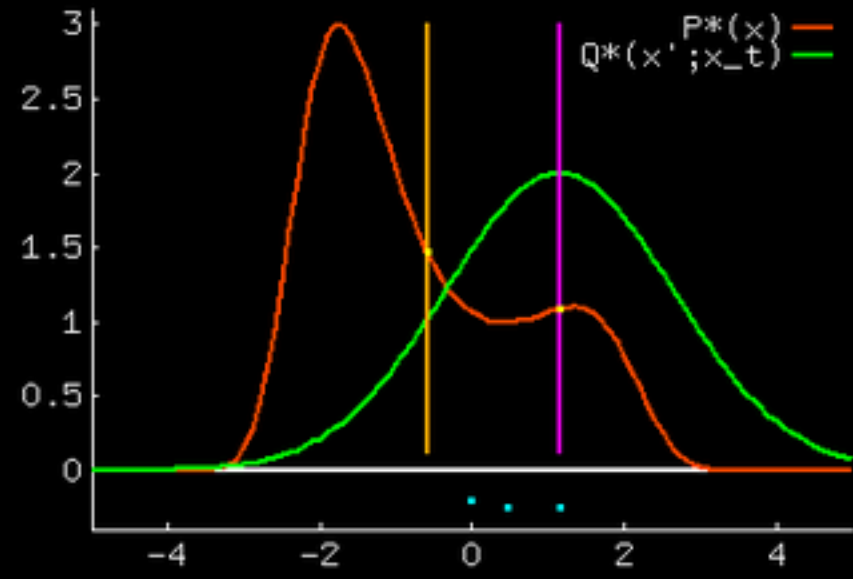
- Metropolis method
- Gibbs sampling
- Slice sampling

Reducing random-walk behaviour

- Hamiltonian Monte Carlo
- Overrelaxation

Exact sampling

[itp/exact/rc](#) RUNME



Problems with standard Monte Carlo methods

● Random walk behaviour

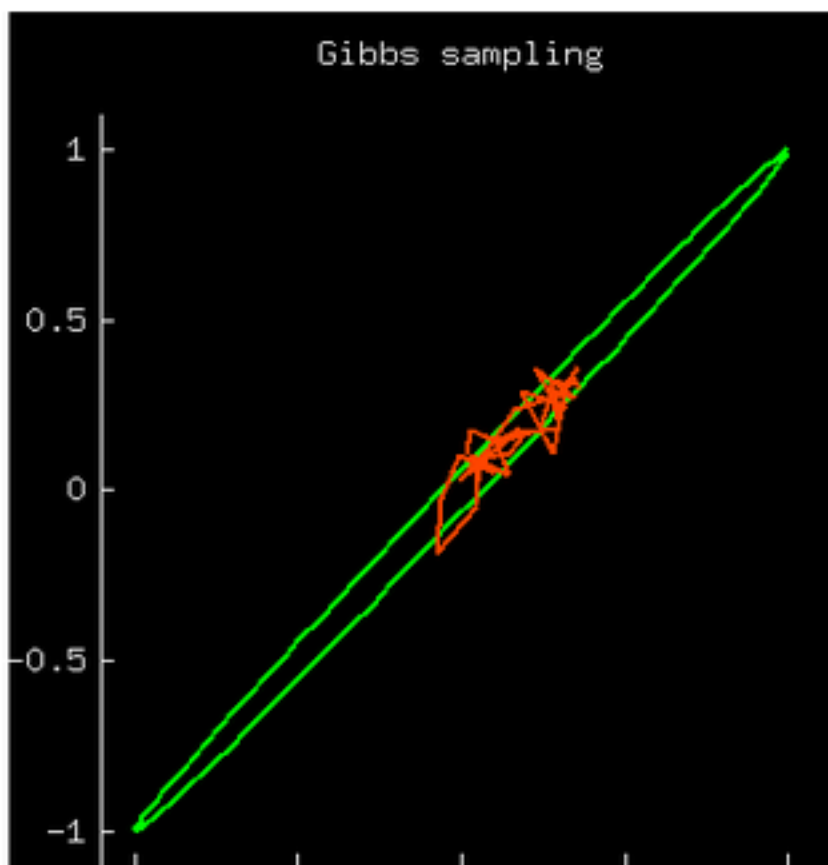
● Sensitivity to step size

● When to stop

Efficient methods

Slice sampling

Exact sampling



Problems with standard Monte Carlo methods

● Random walk behaviour

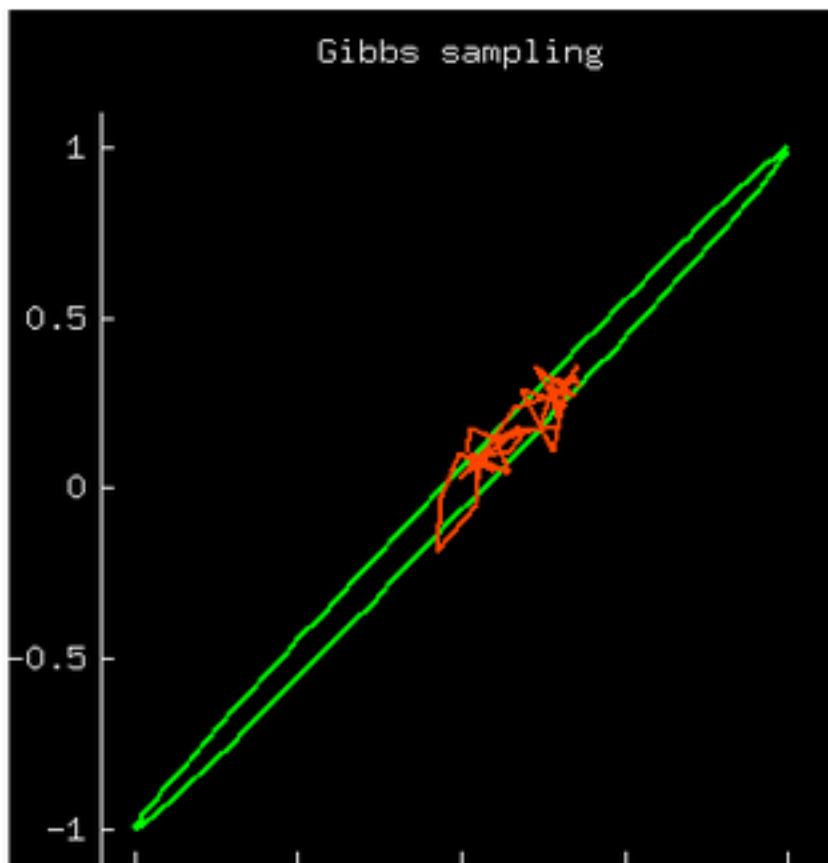
● Sensitivity to step size

● When to stop

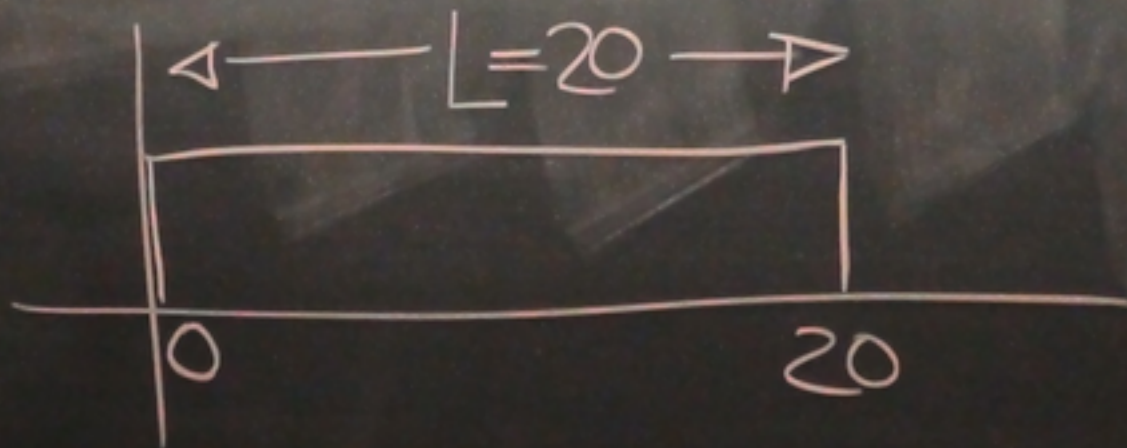
Efficient methods

Slice sampling

Exact sampling

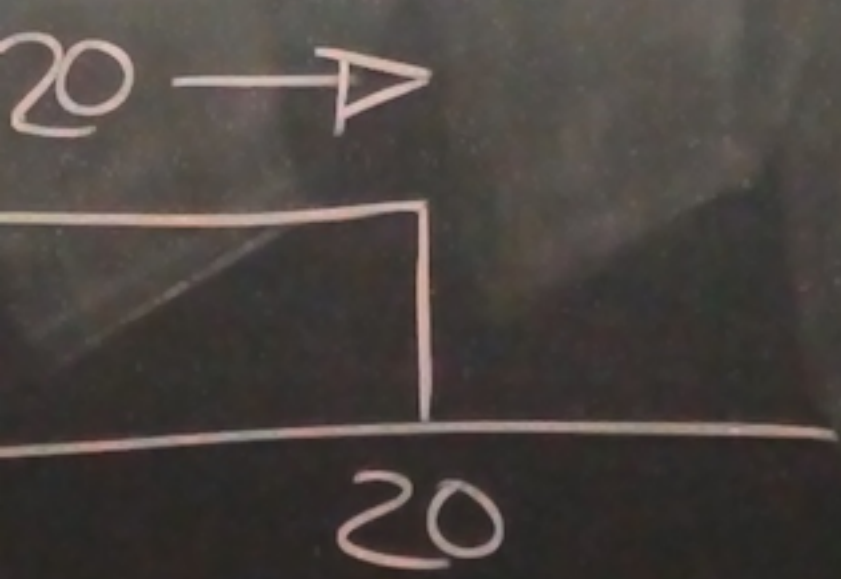


$$P^*(x) = \begin{cases} 1 & x \in \{0, 1, 2, 3, \dots, 20\} \\ 0 & \text{otherwise} \end{cases} \quad x \in \{\text{integers}\}$$



$$Q(x', x) = \begin{cases} \frac{1}{2} & x' = x - 1 \\ \frac{1}{2} & x' = x + 1 \end{cases}$$

otherwise



step size

$$\epsilon = 1$$

$$= \left\{ \begin{array}{l} 1/2 \\ 1/2 \end{array} \right.$$

$$x' = x \ominus 1$$

$$x' = x \oplus 1$$

25:lewis:/home/mackay/itp/metrop> ./demo.p

```
      *  
     *  
    *  
   *  
  *  
 *  
*  
 *  
  *  
   *  
    *  
     *  
      *  
     *  
    *  
   *  
  *  
 *  
*  
 *  
  *  
   *  
    *  
     *
```

20 iterations

Q1: roughly
how long
until this chain
generates a
"good" sample from
 P ?

Q2: how long
until we hit a wall

Q3: how long until we've hit both walls?

Minimum # of steps to reach a wall = $\left(\approx \frac{L}{\varepsilon} \right) = 10$

min # of steps to visit both walls = 31 $\left(\approx \frac{L}{\varepsilon} \right)$

distance after time T

$$S_t = \pm 1$$

$$\Delta x = \sum_{t=1}^T S_t$$

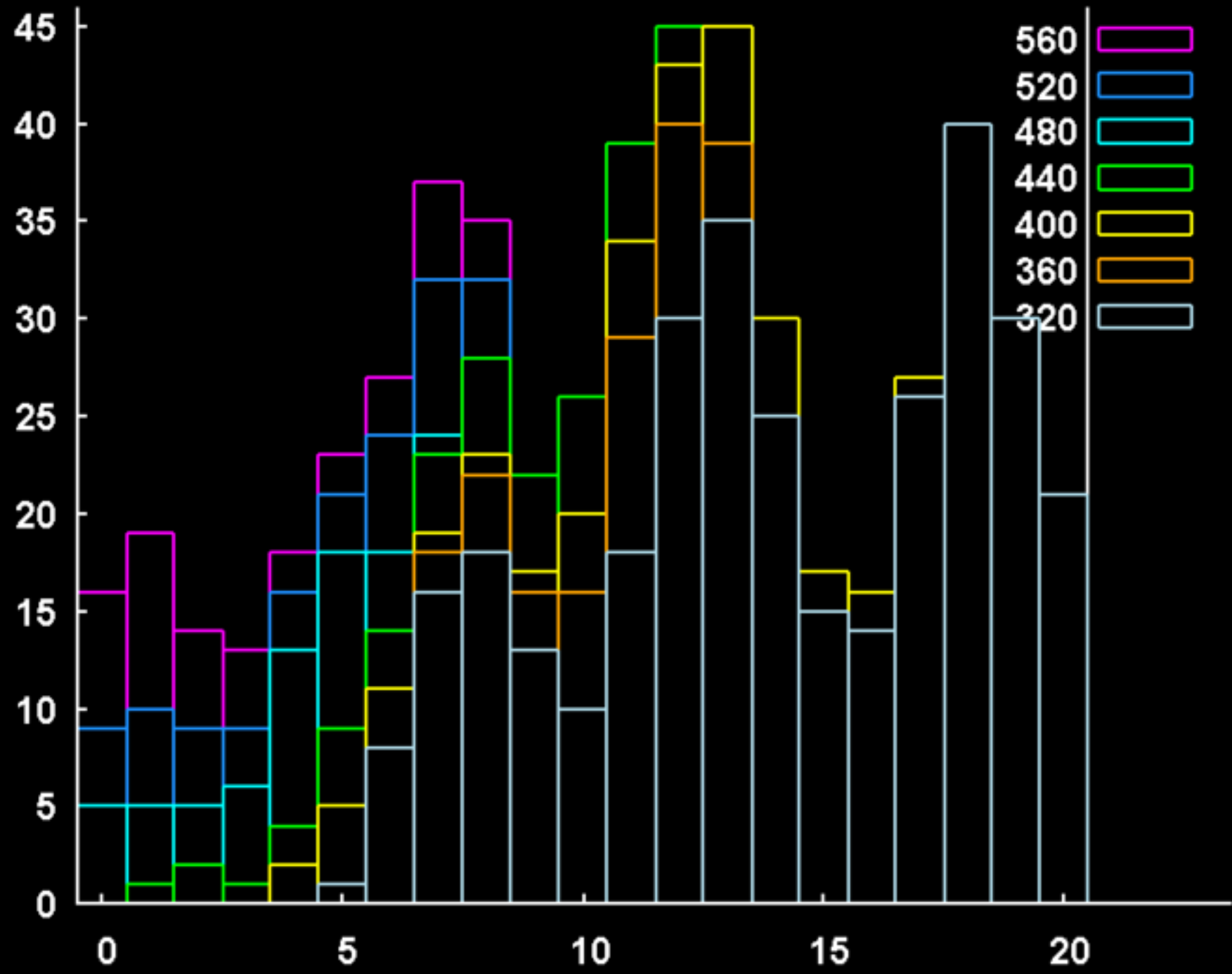
neglect walls

$\text{Var}(\Delta x)$

$$\langle \Delta x^2 \rangle = \sum_{t=1}^T \langle S_t^2 \rangle = T$$

So $\langle \Delta x^2 \rangle = L^2$ need $T = \left(\frac{L}{\epsilon}\right)^2$

560 iterations



1200 iterations

Terminal

File Edit View Terminal Help

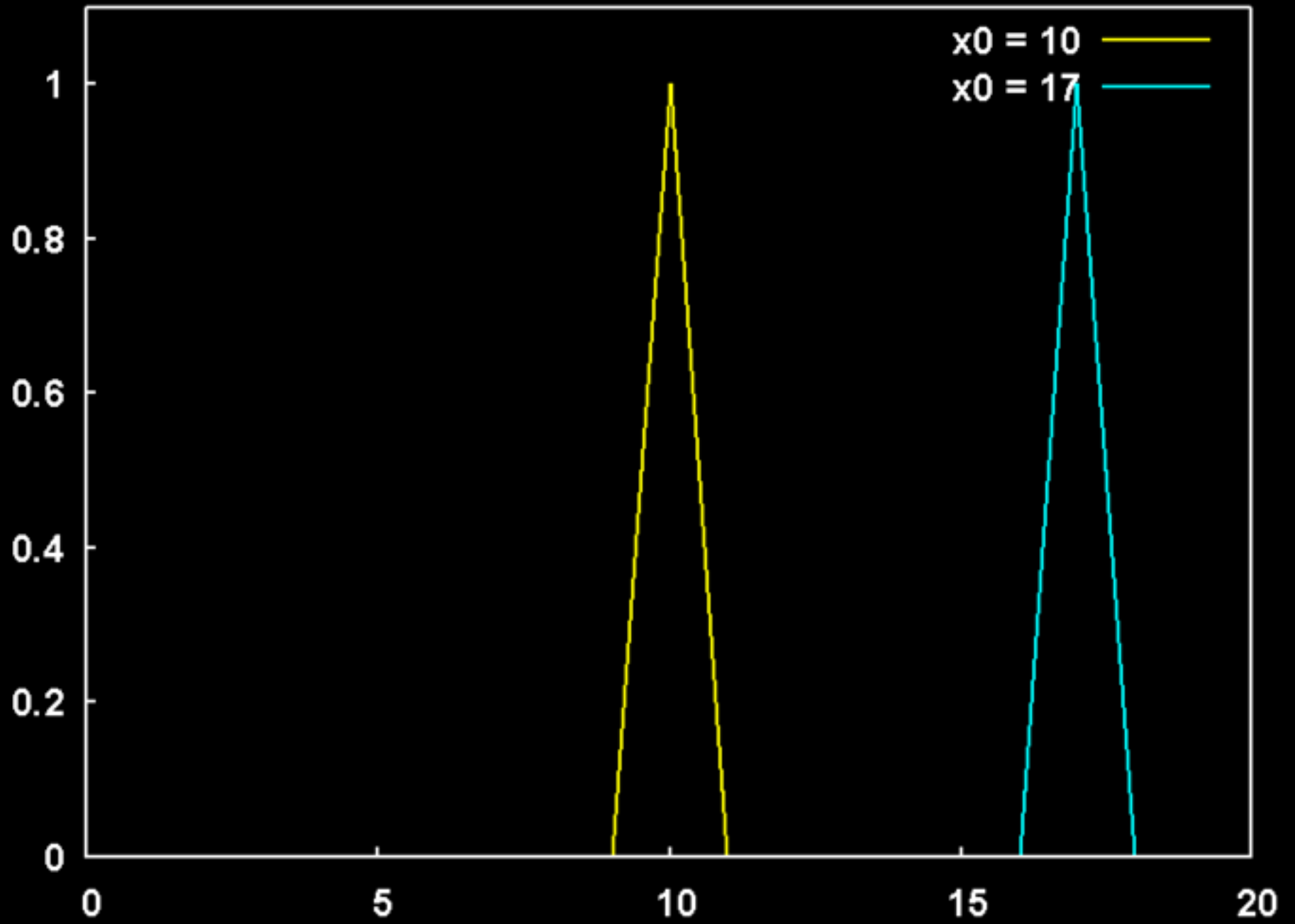
```

50 50 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
50 0 50 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 50 0 50 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 50 0 50 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 50 0 50 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 50 0 50 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 50 0 50 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 50 0 50 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 50 0 50 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 50 0 50 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 50 0 50 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 50 0 50 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 50 0 50 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 50 0 50 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 50 0 50 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 50 0 50 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 50 0 50 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 50 0 50 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 50 0 50
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 50 50

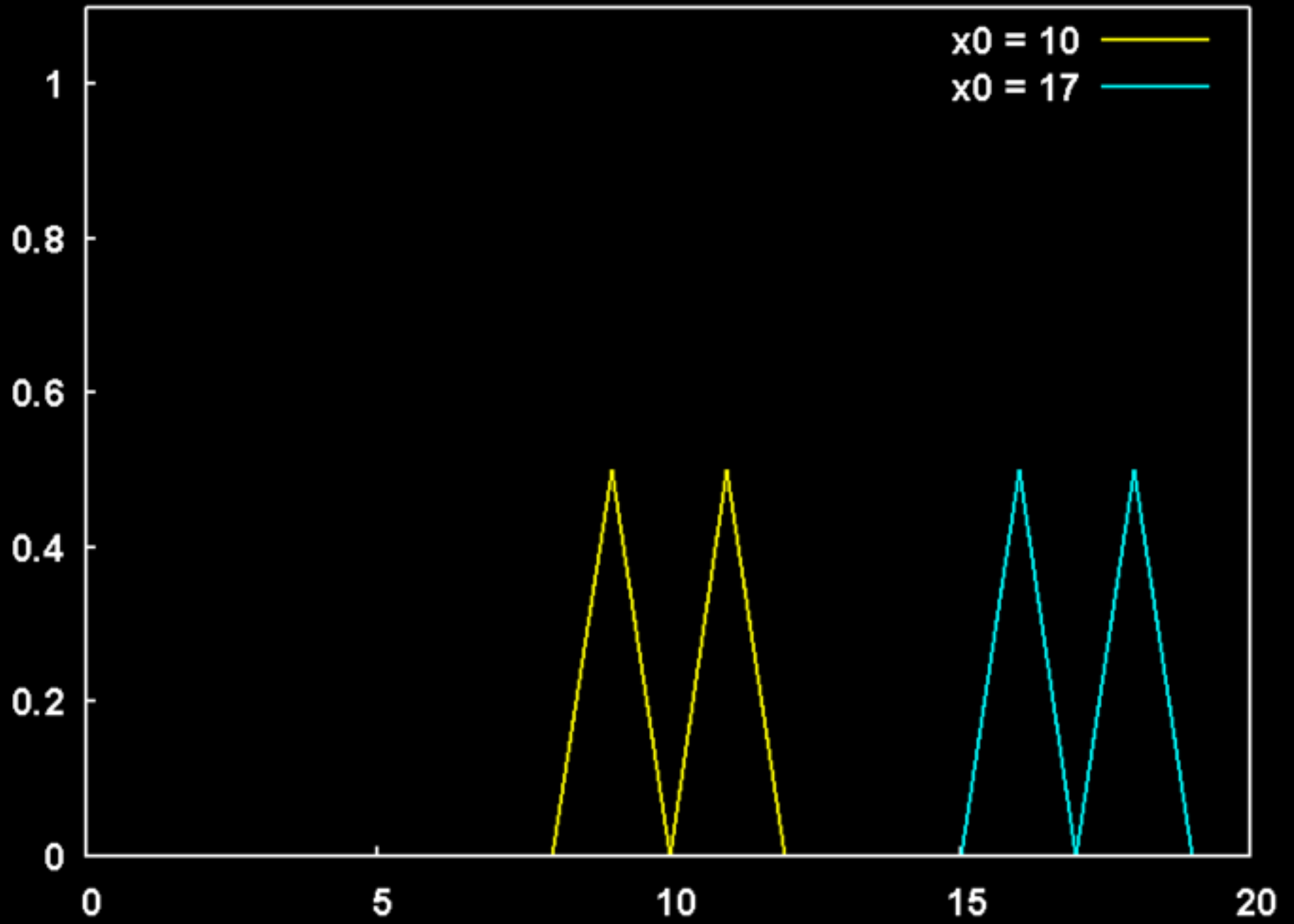
```

Ready?

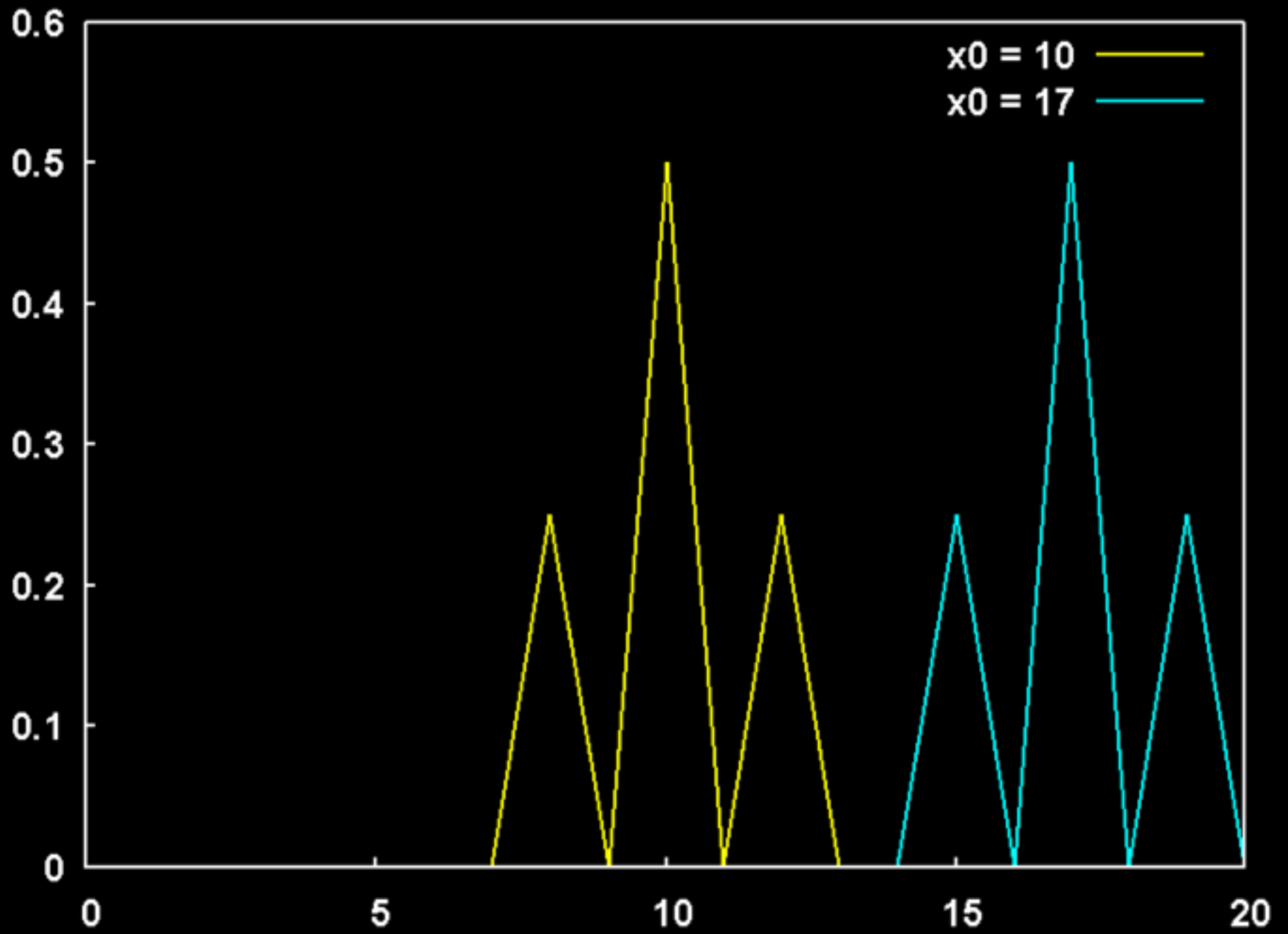
t=0



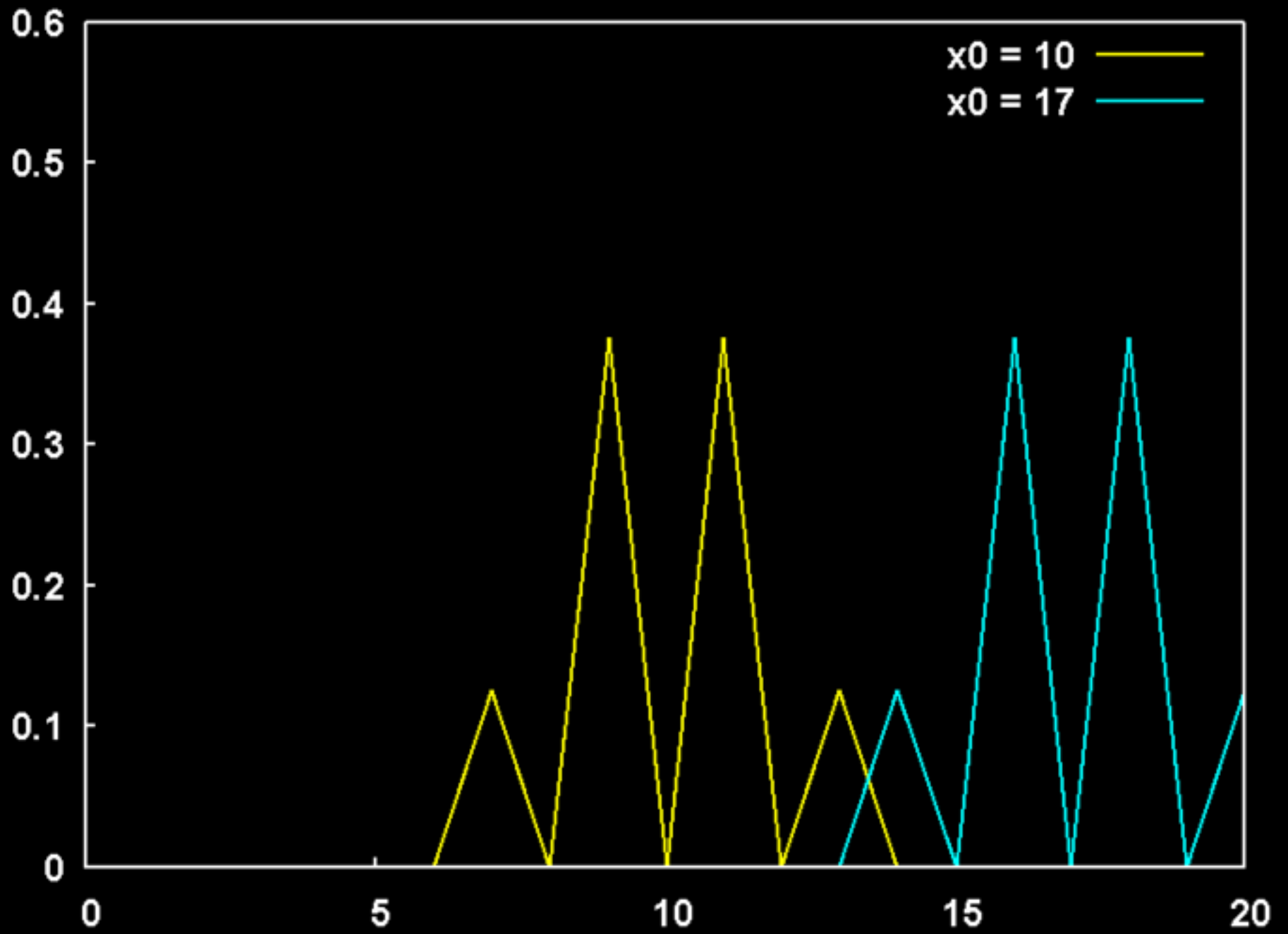
t=1



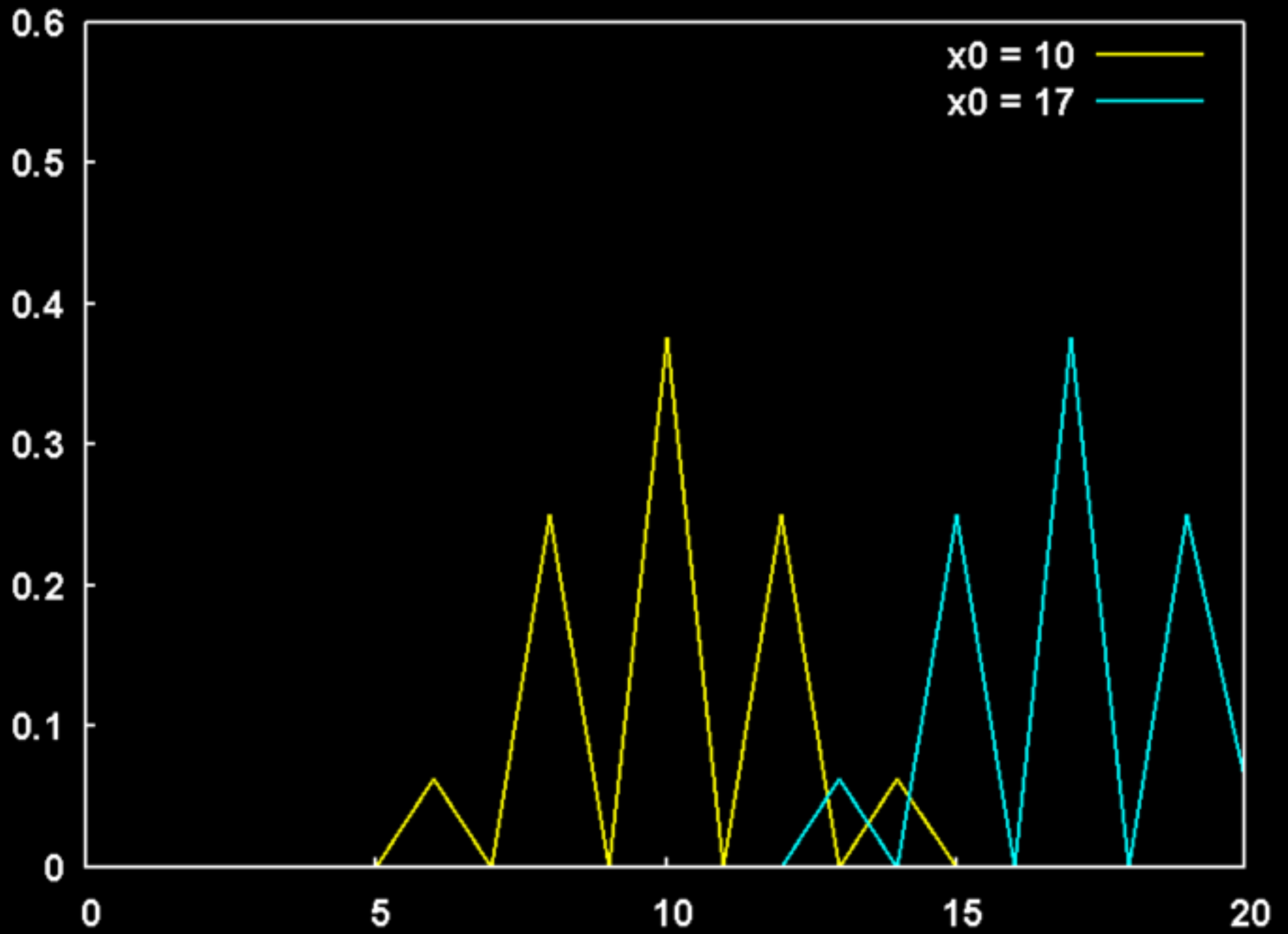
t=2



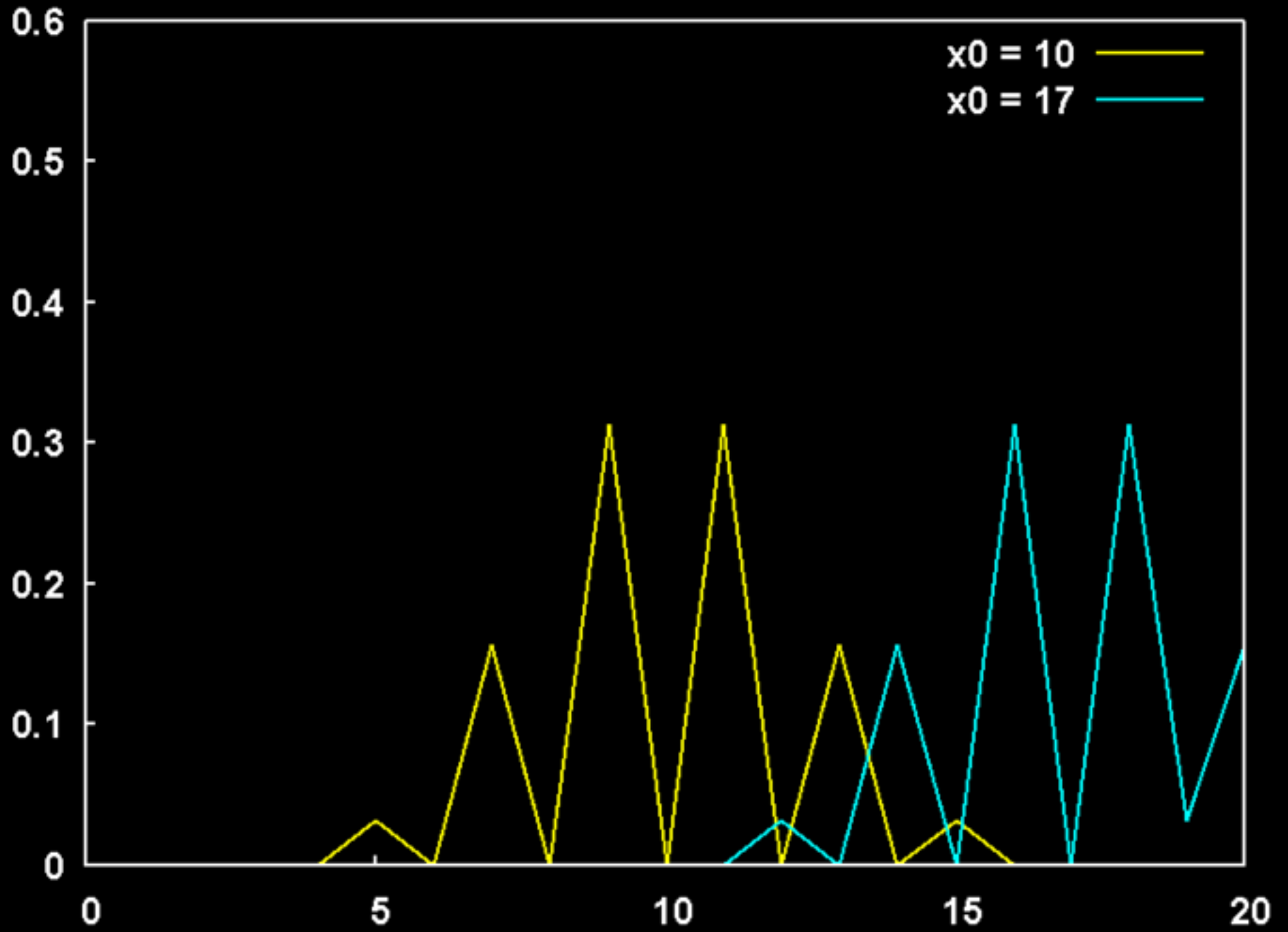
t=3



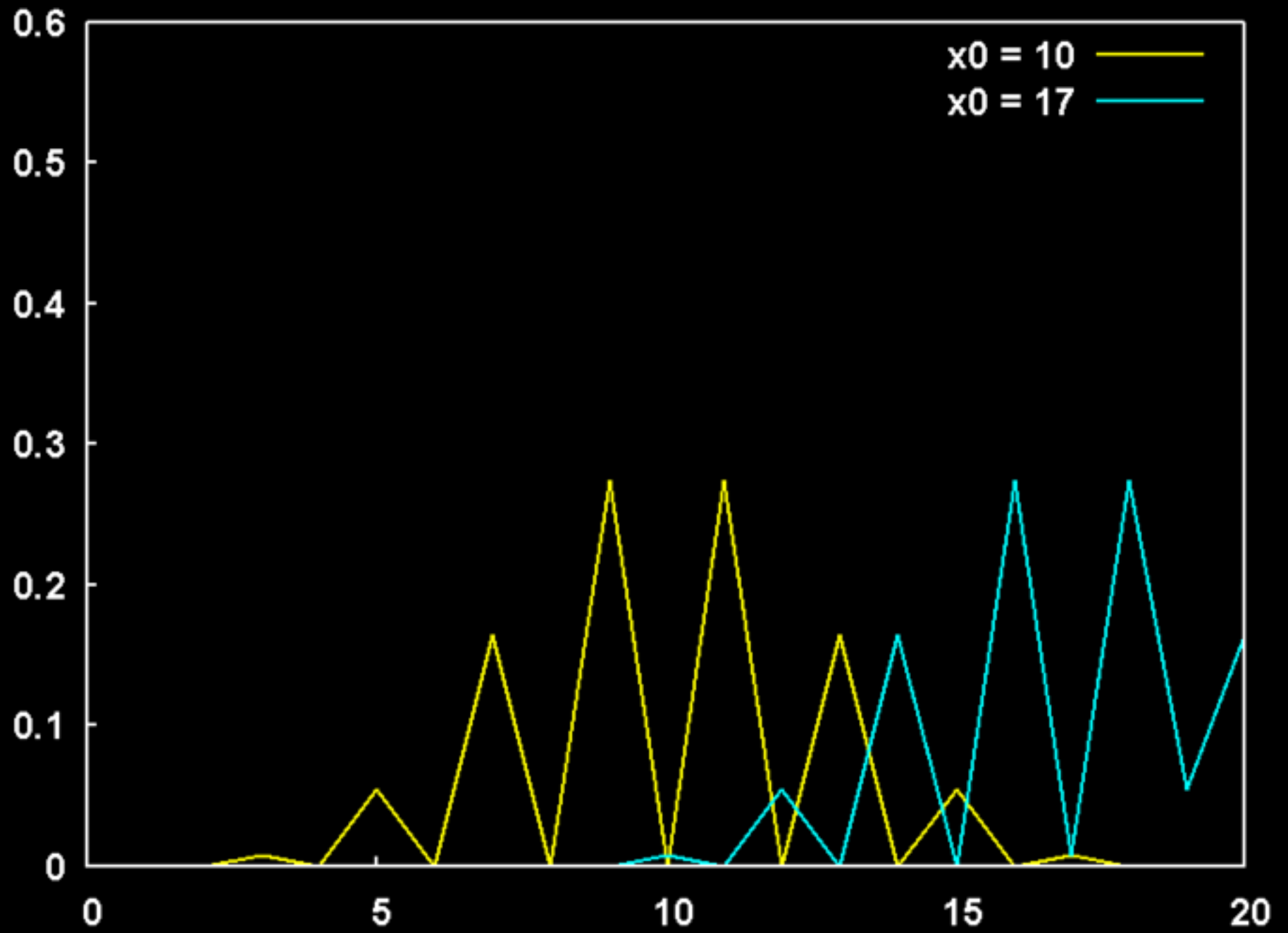
t=4



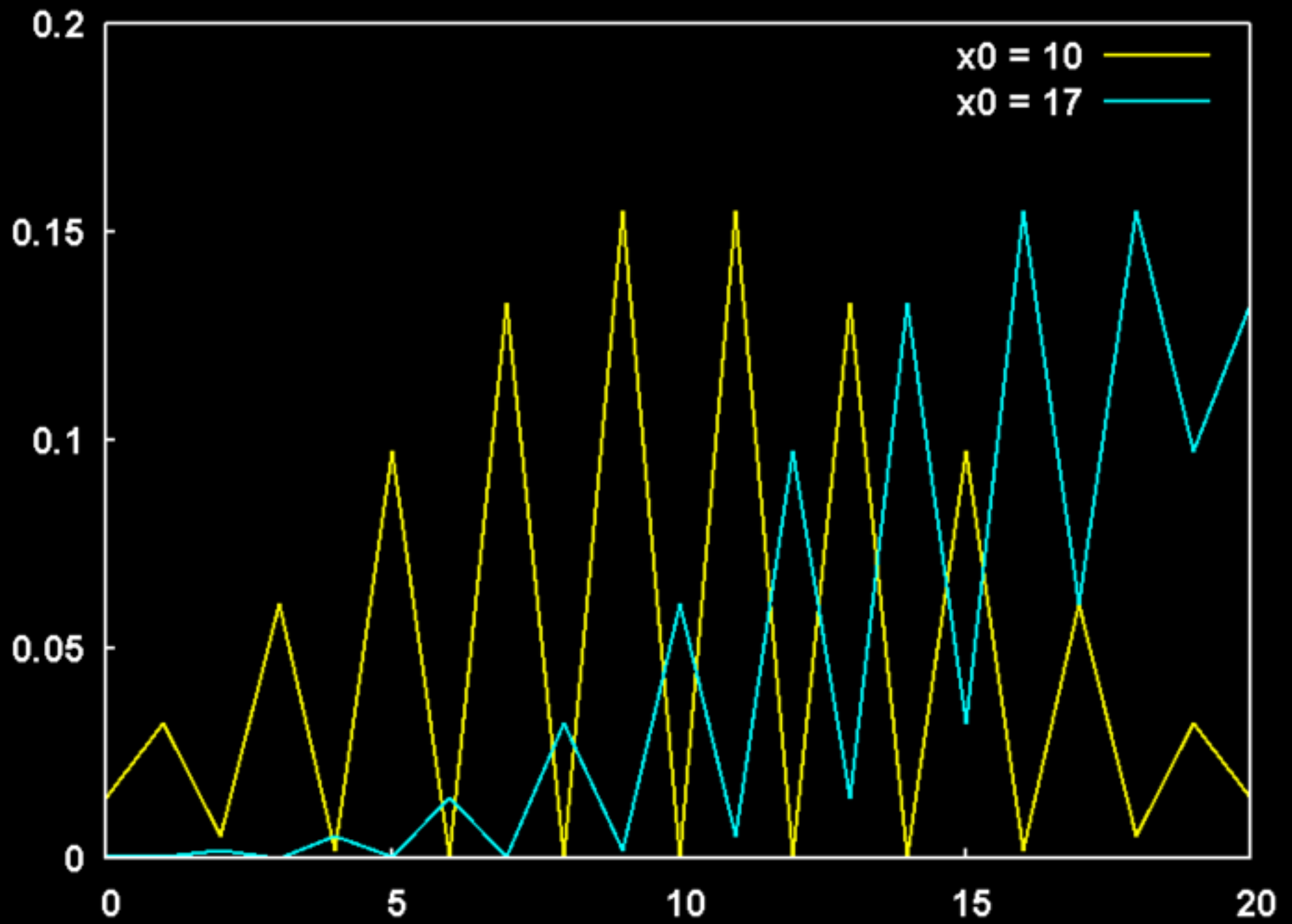
t=5



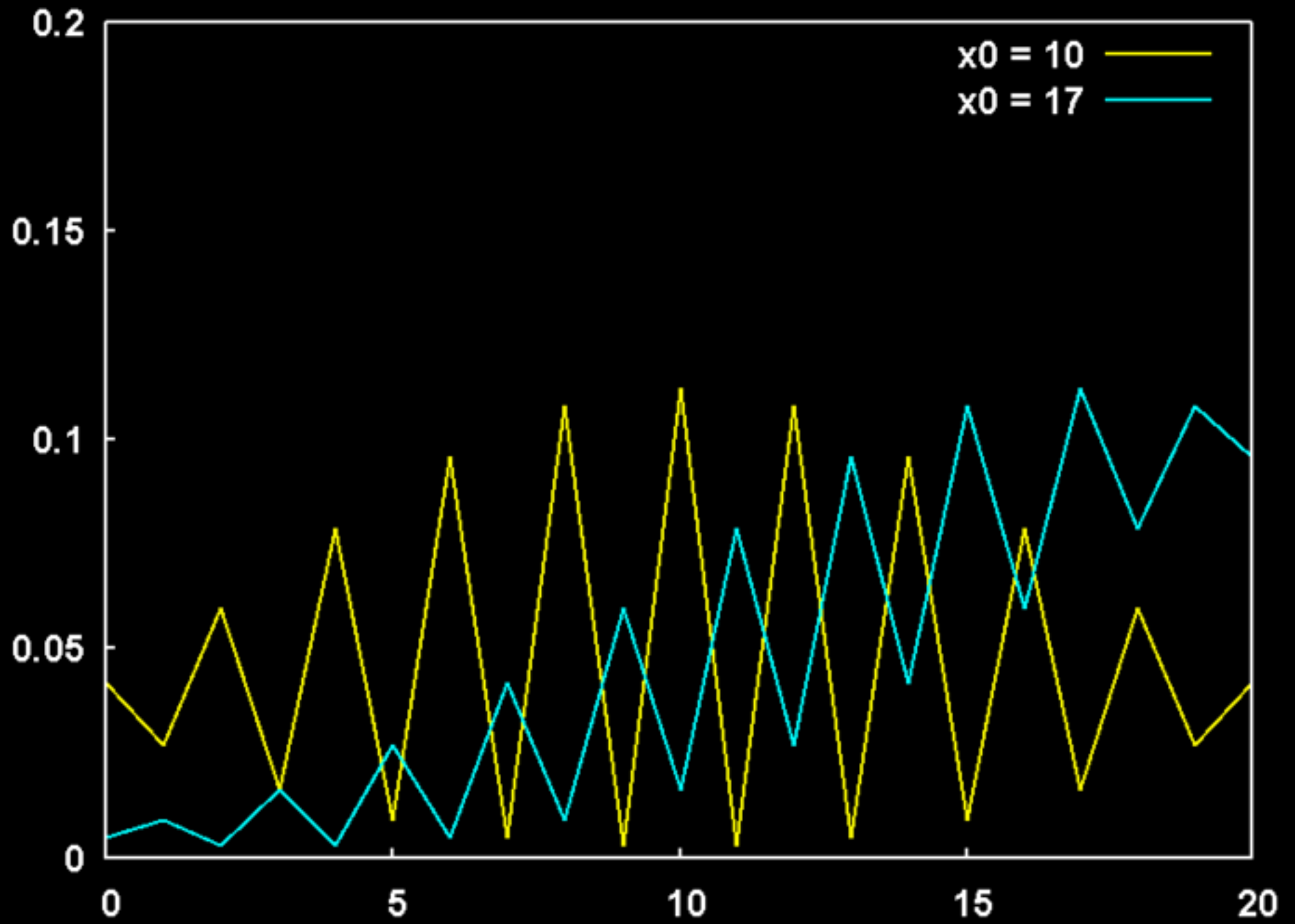
t=7



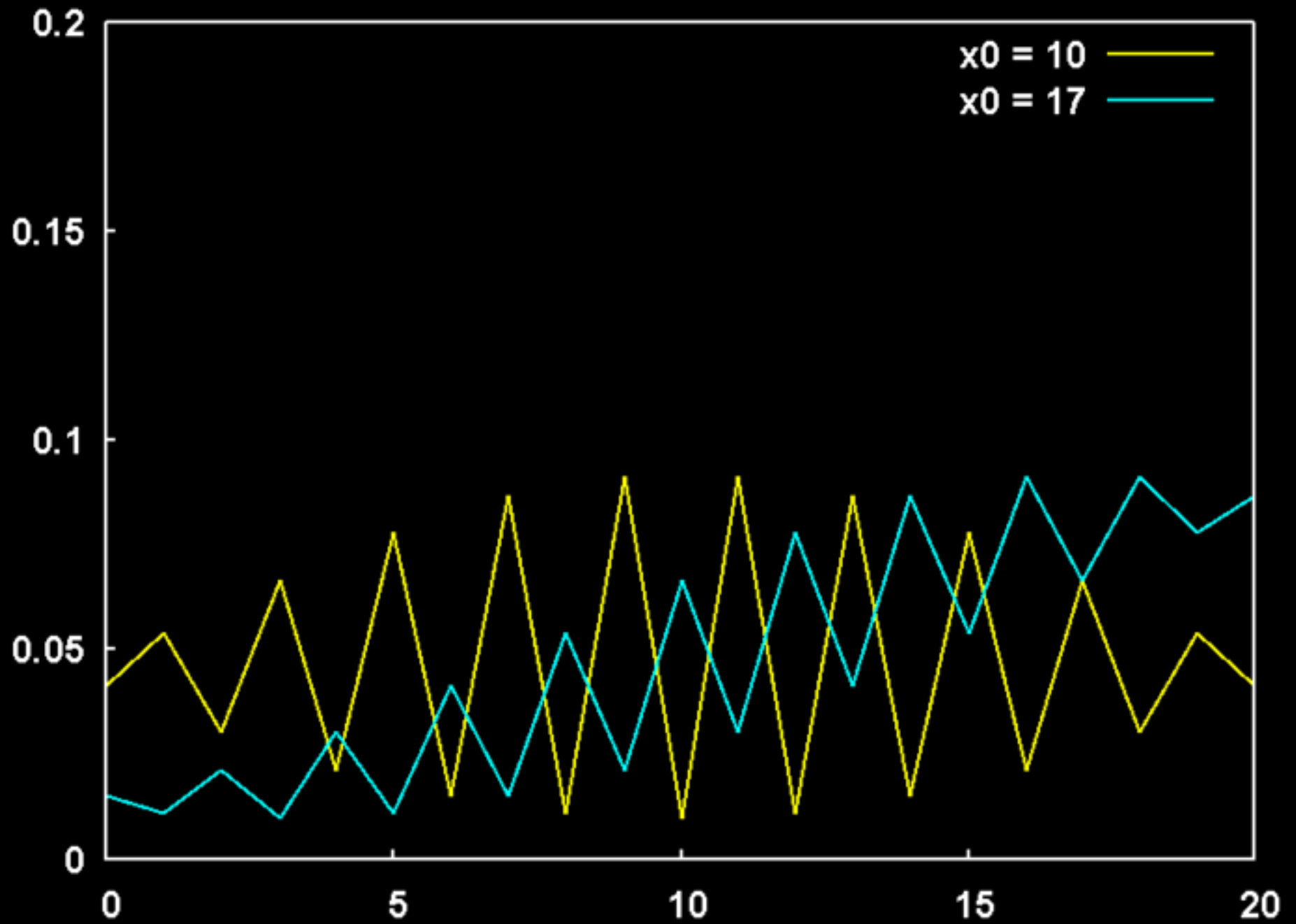
t=25



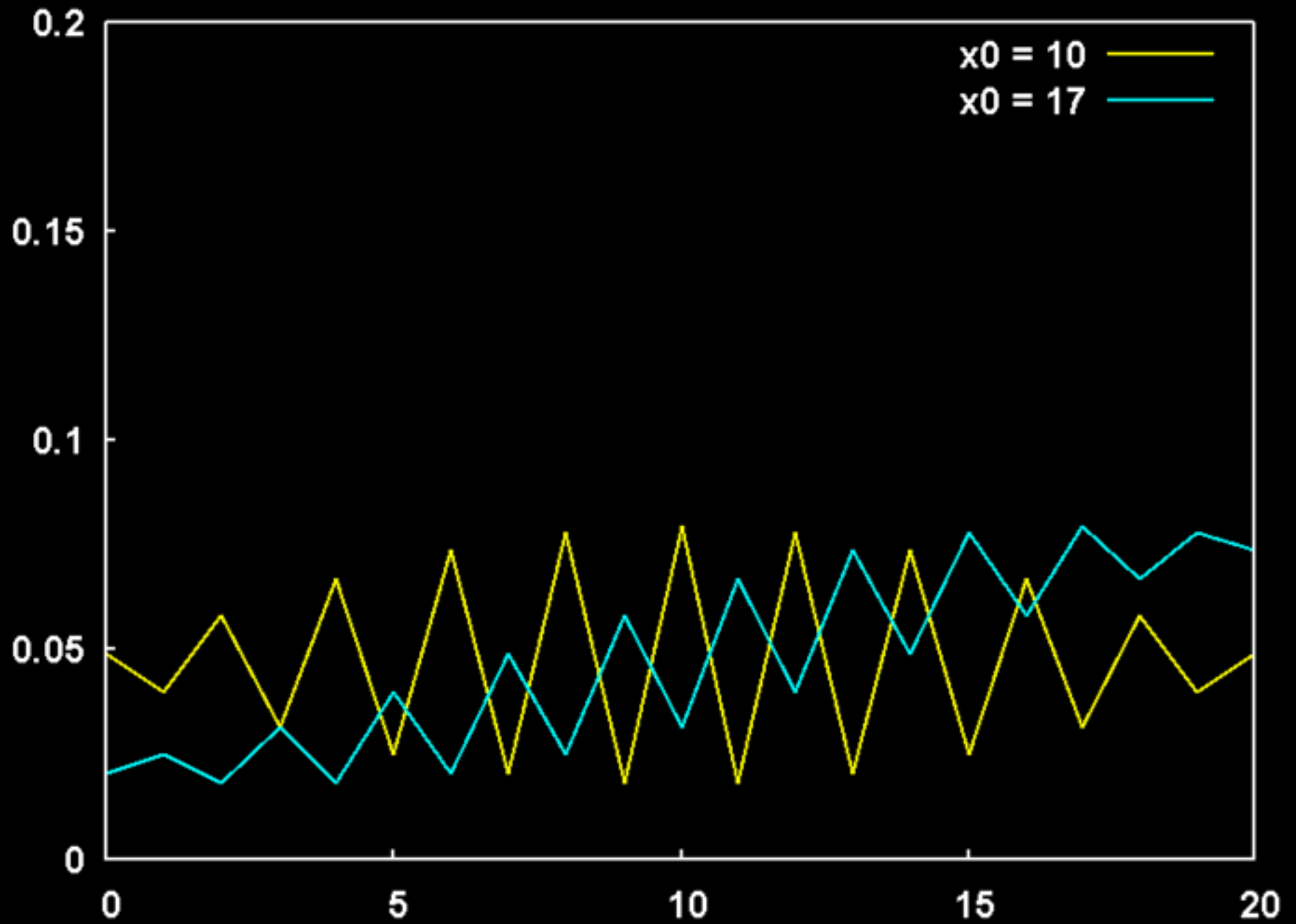
t=50



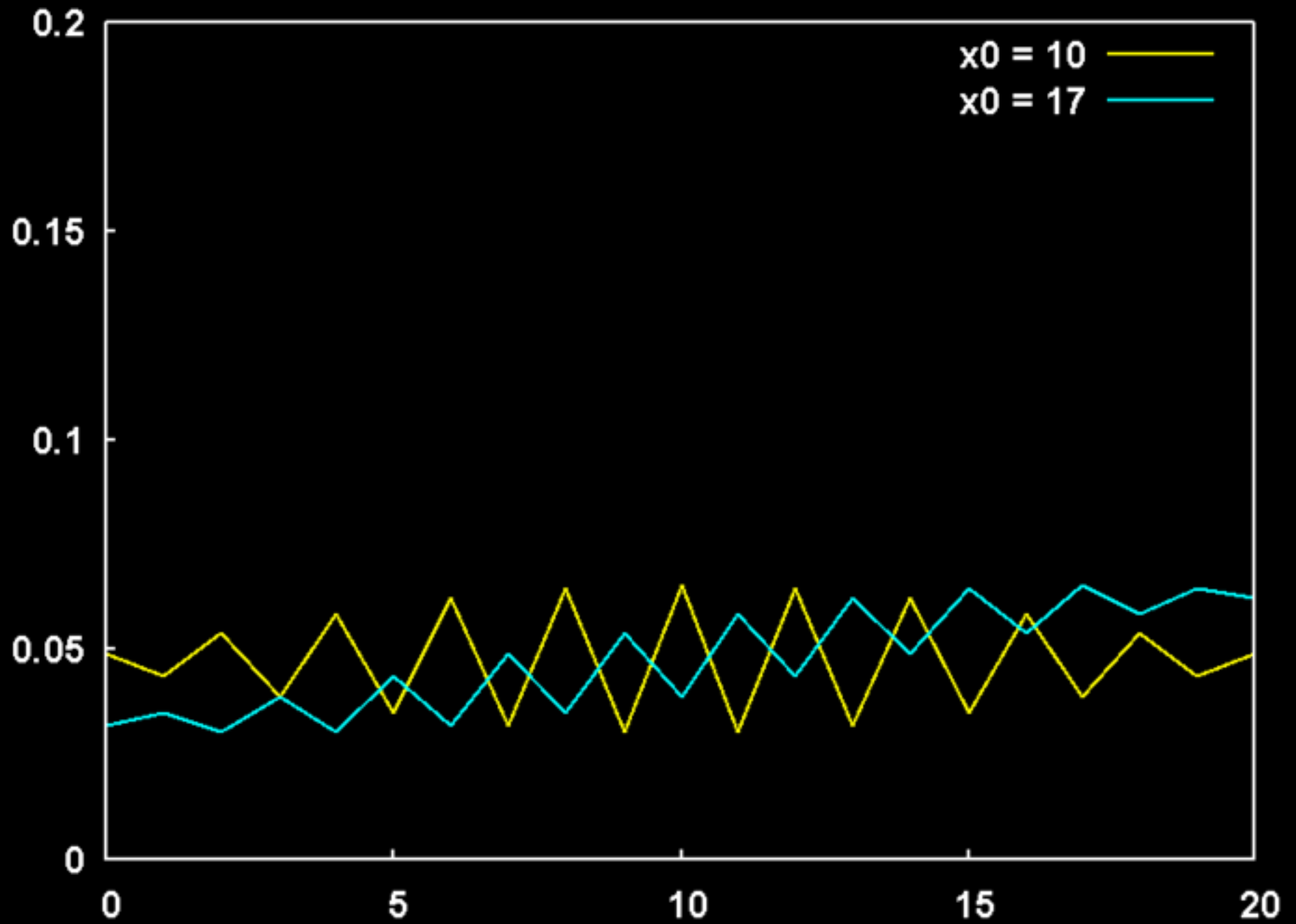
t=75



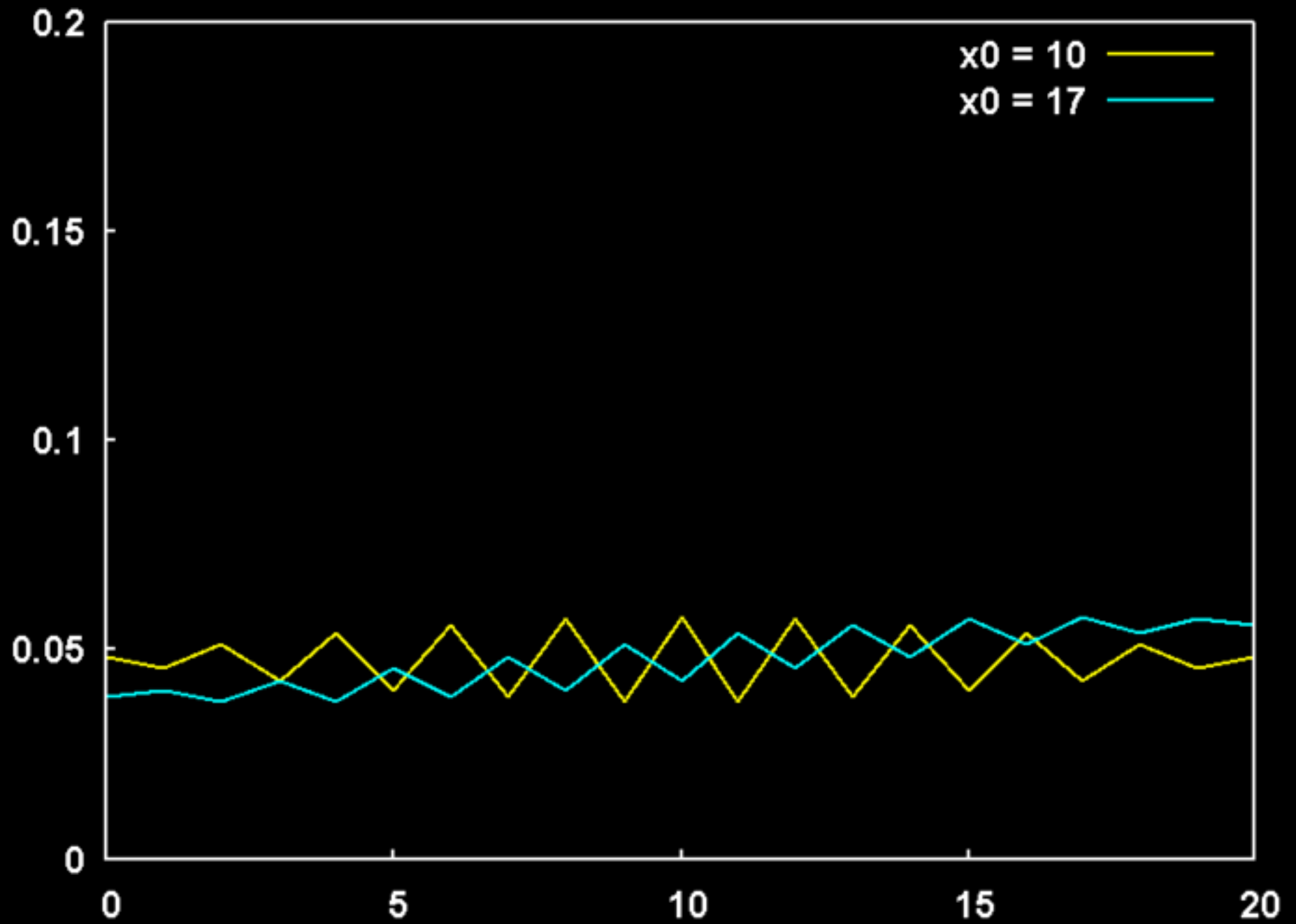
t=100



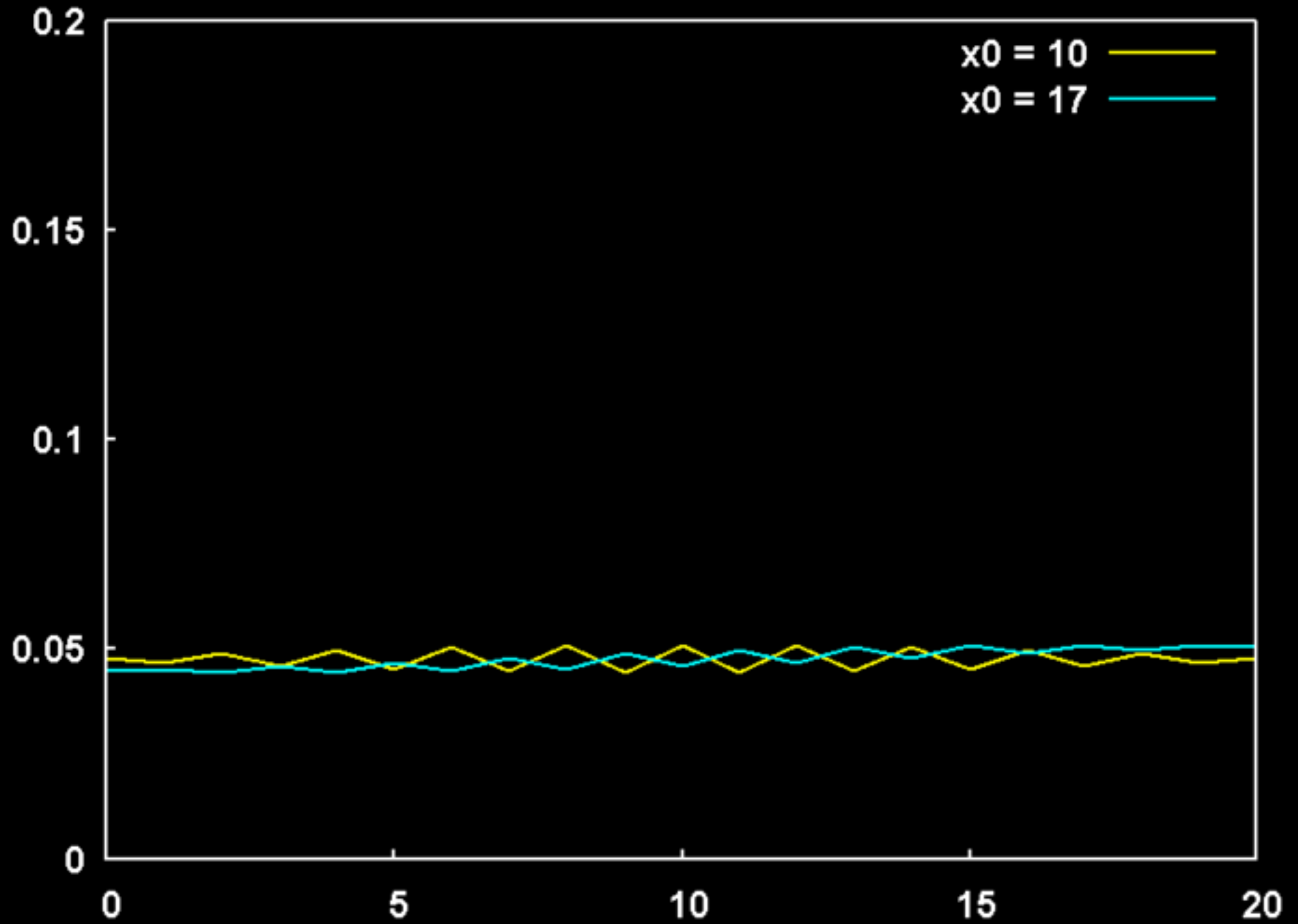
t=150



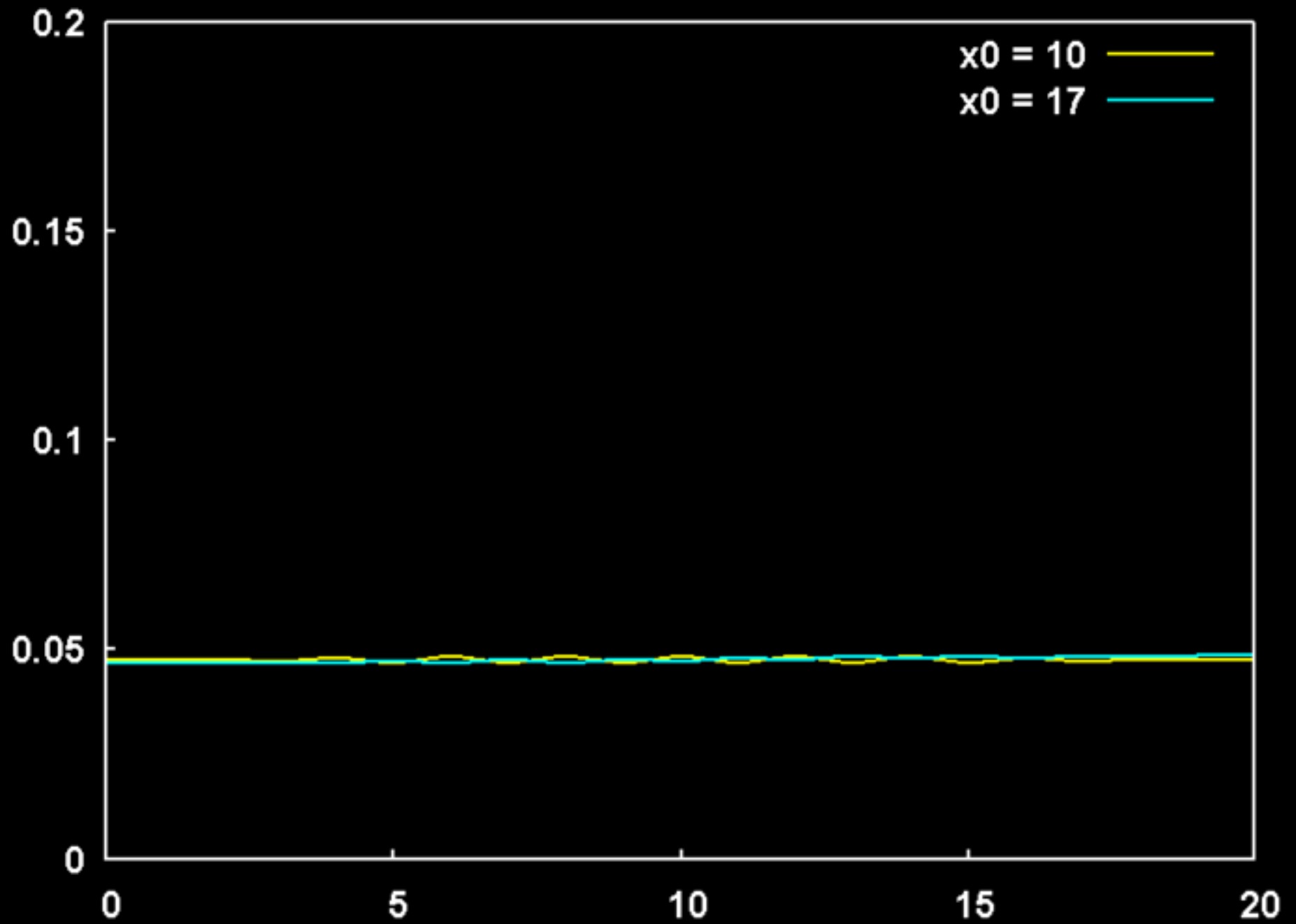
t=200



t=300

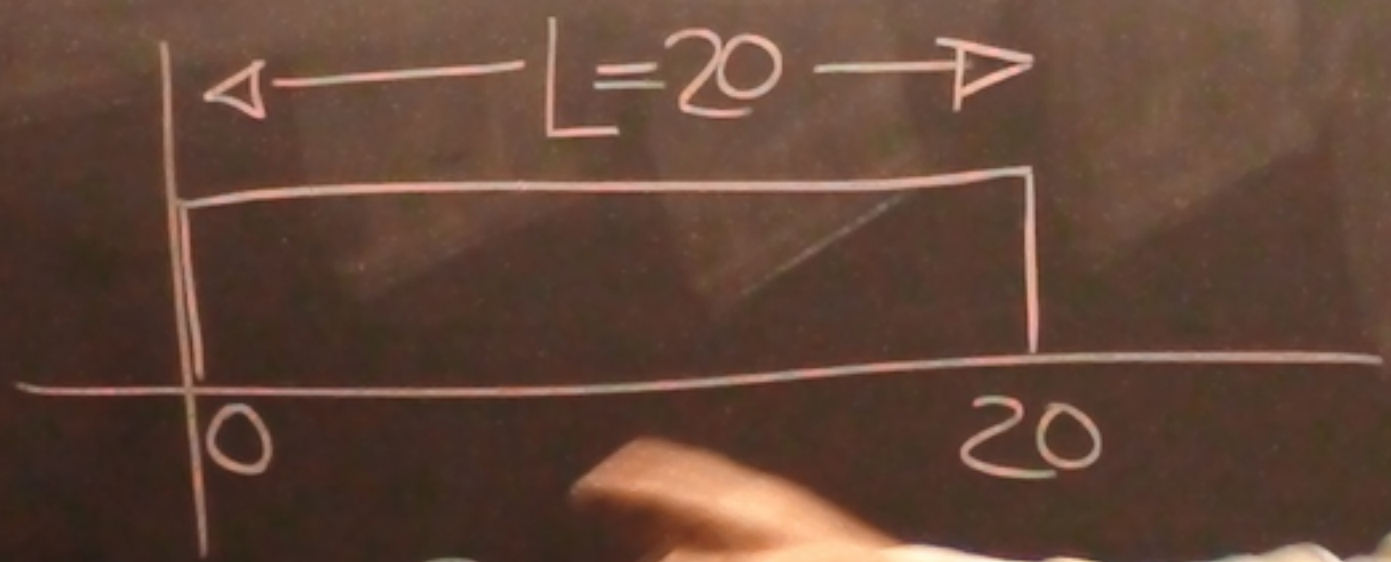


t=400



$$x \in \{ \text{integers} \}$$

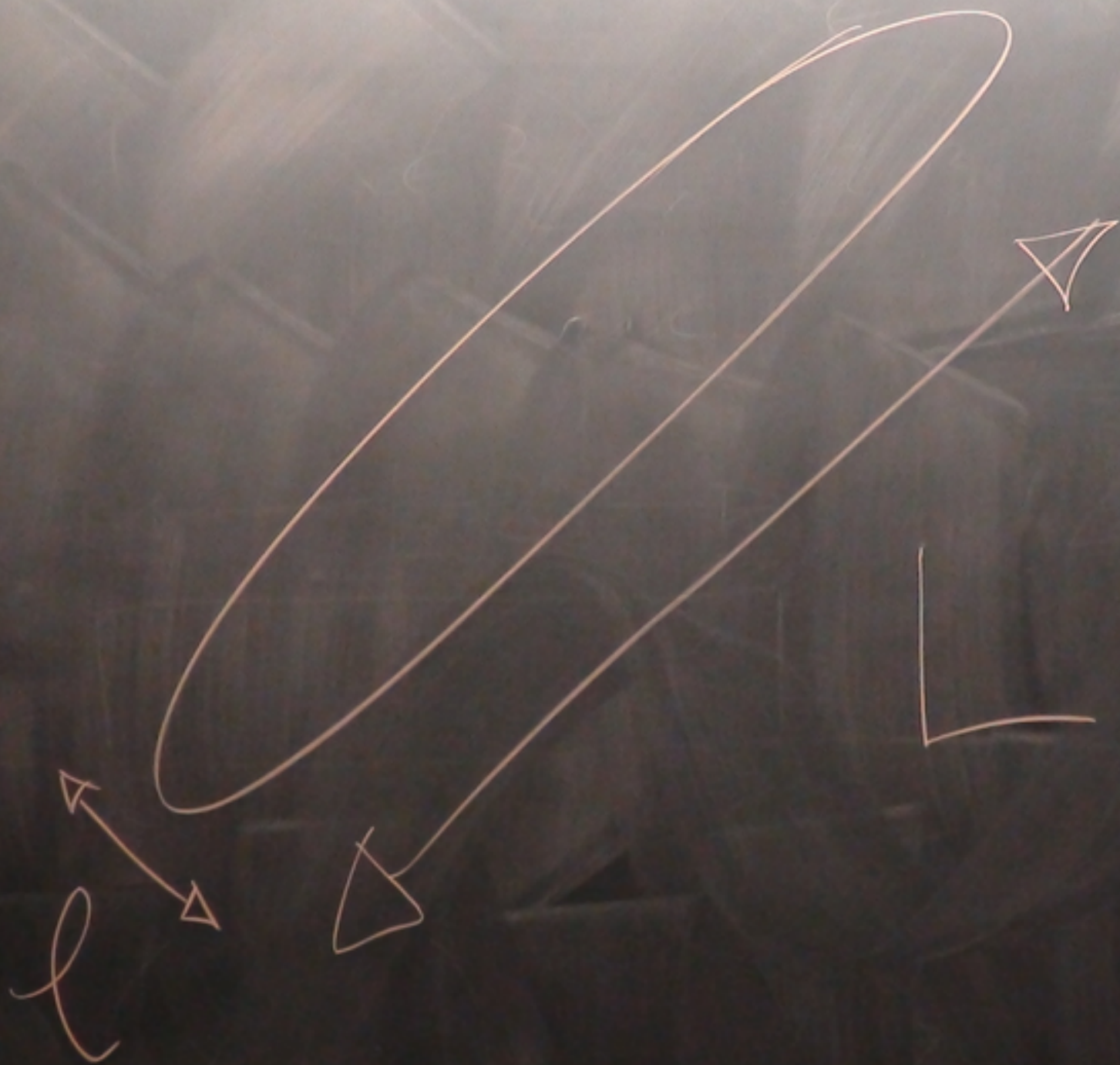
$$\left\{ \begin{array}{l} 1 \\ 0 \end{array} \right. \left\{ \begin{array}{l} x \in \{0, 1, 2, 3, \dots, 20\} \\ \text{otherwise} \end{array} \right.$$



$$Q(x', x) = \int_{x'}^x$$

$$x' = x$$







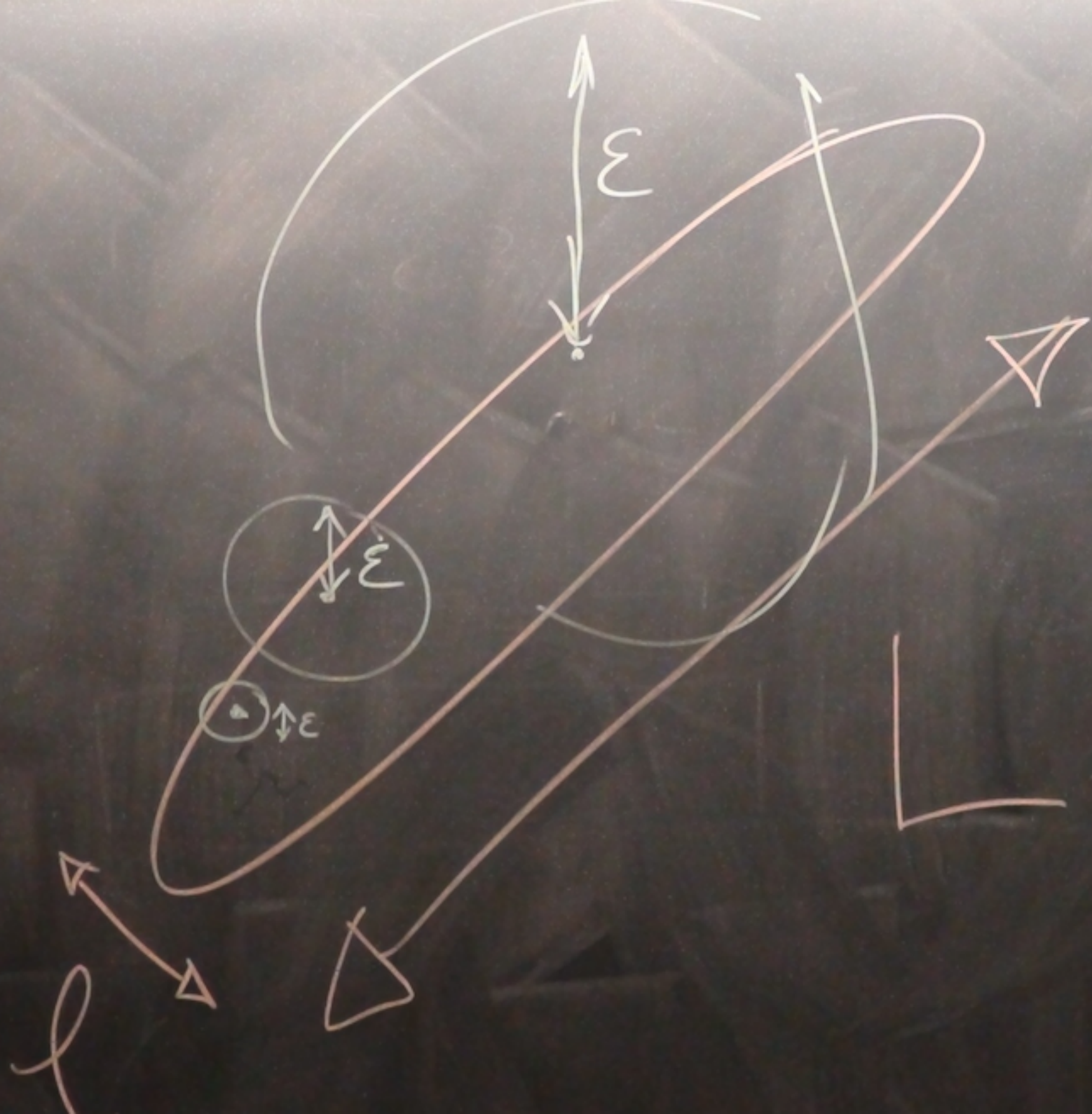
γ dimensions

l

$k-\gamma$ dimensions

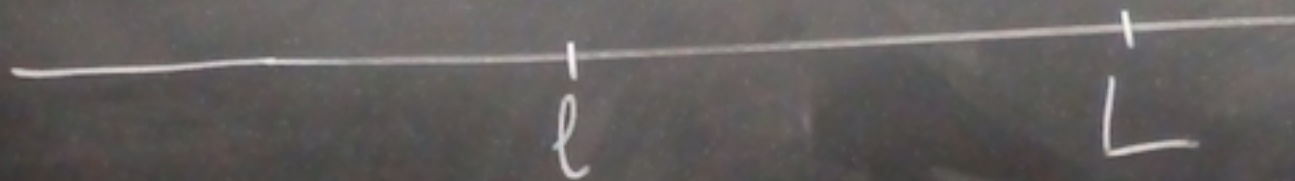
L





dimensions

l



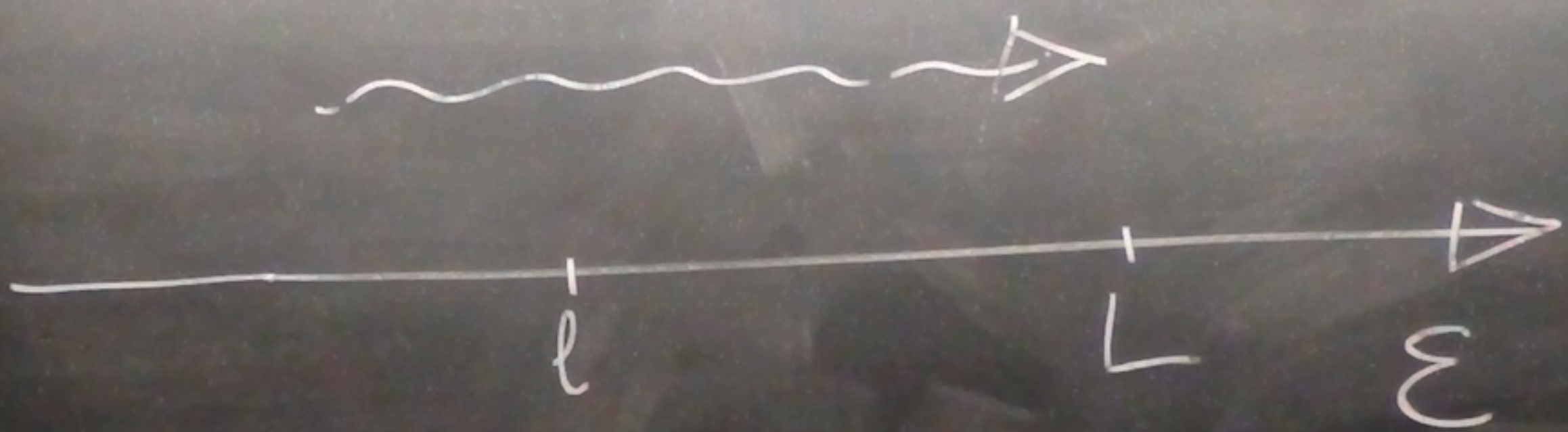
dimensions

L

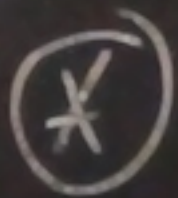
need
at least

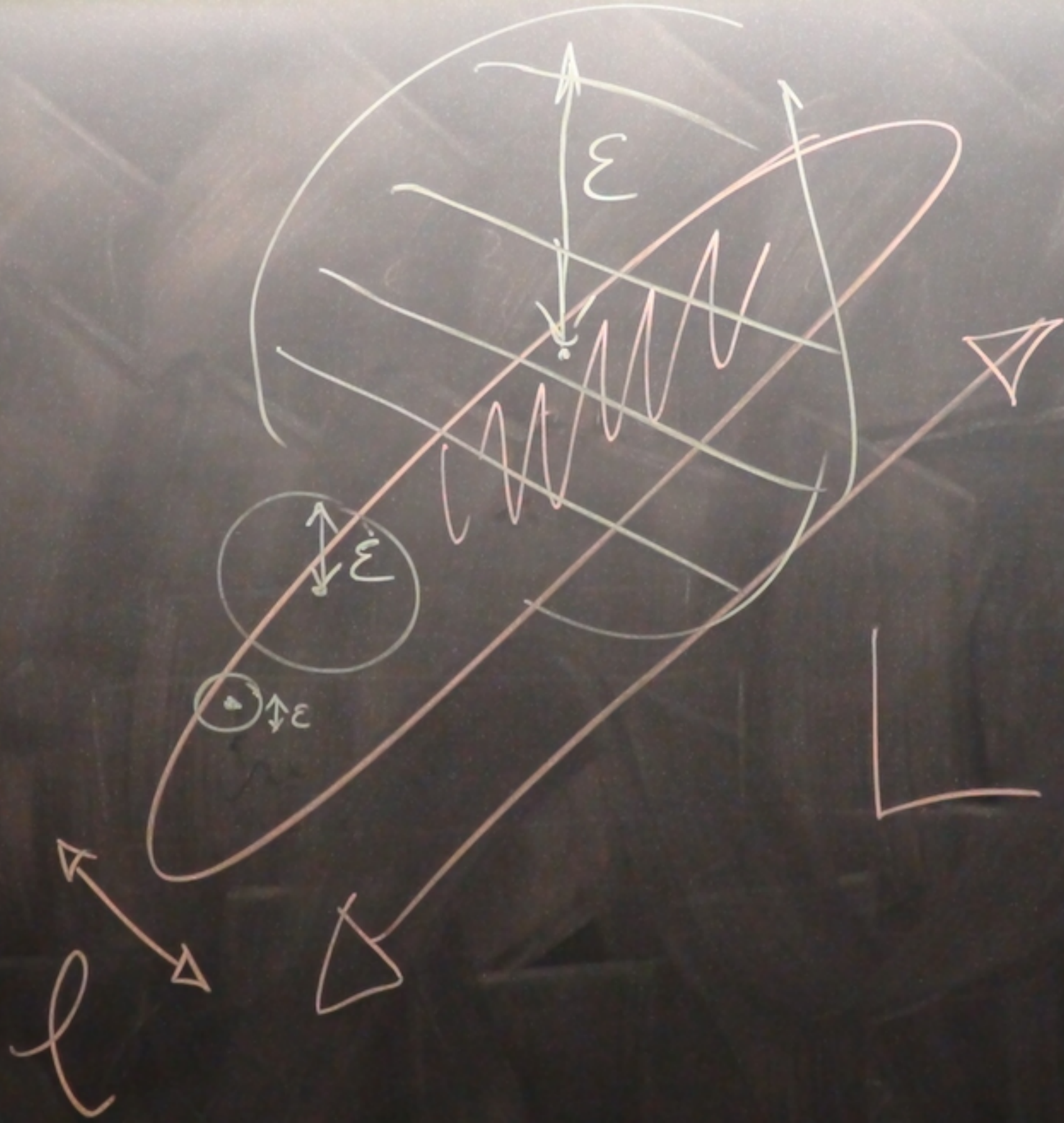
$$T \approx \left(\frac{L}{\epsilon}\right)^2$$

steps to get a
fresh independent sample



Steps to get a
fresh independent sample.



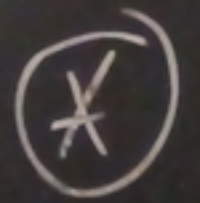
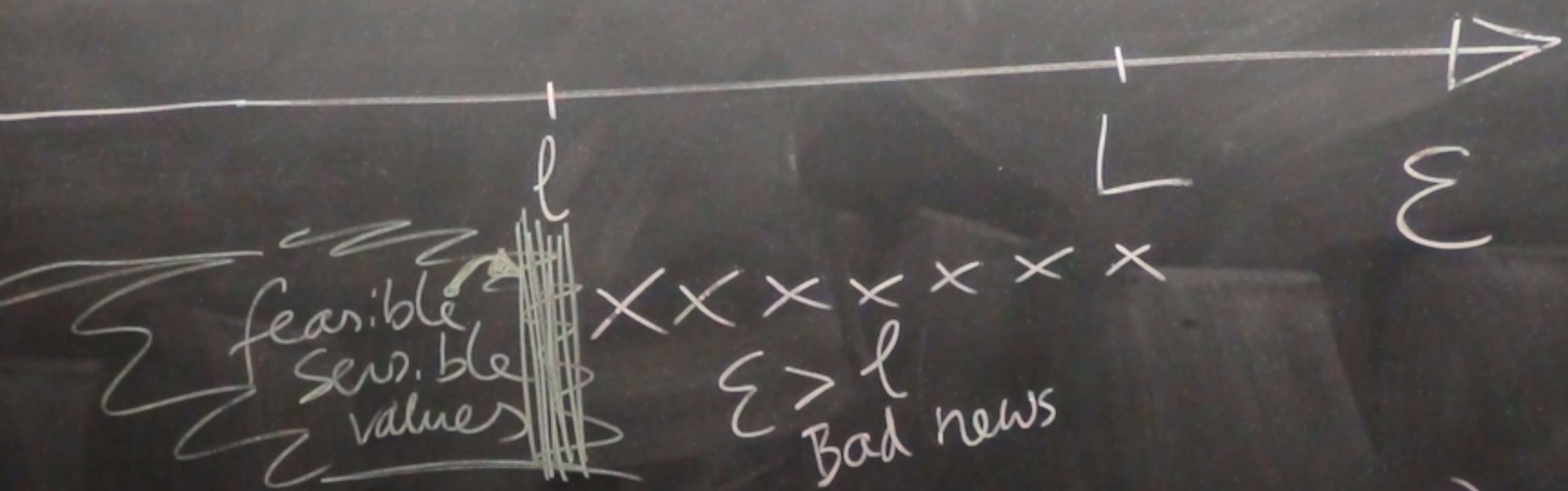


if $\epsilon \gg l$

Prob of accepted move =

$$\frac{l \delta}{\epsilon \delta}$$

$$= \left(\frac{l}{\epsilon} \right)$$



Steps to get a
fresh independent sample.

optimal

$$\varepsilon \approx l$$

& resulting

optimal

acceptance

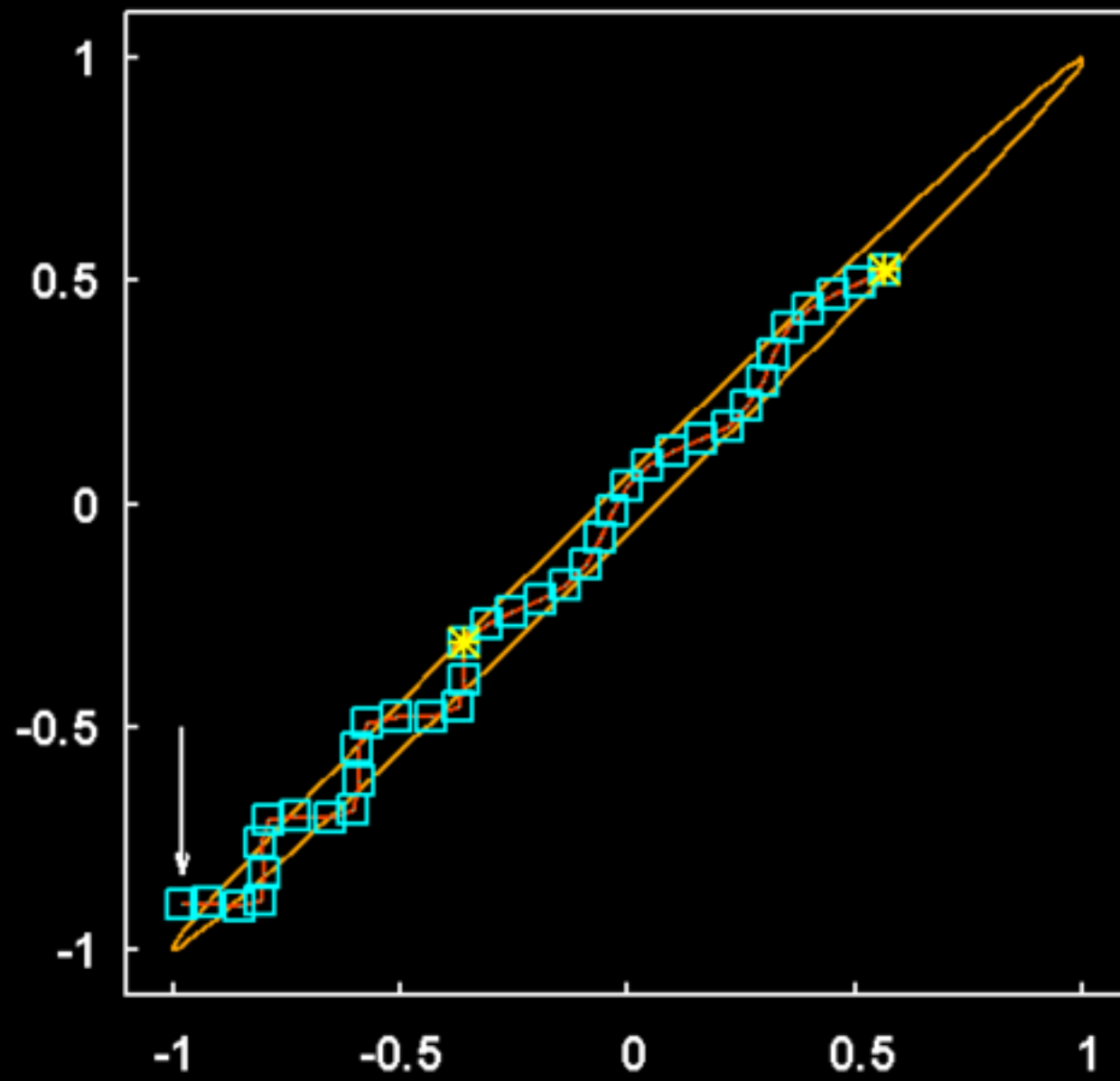
probability

$$\approx 1/2$$

Efficient Monte Carlo methods

Hamiltonian Monte Carlo

Overrelaxation



HMC

(or Hybrid)

Hamiltonian MC

momentum

$$-\frac{1}{2} \frac{p^2}{m}$$

$$P(x, p) = P(x) \times \frac{e^{-\beta \left(E(x) + \frac{1}{2} \frac{p^2}{m} \right)}}{Z}$$

X^0

\sim

Φ



Φ^0

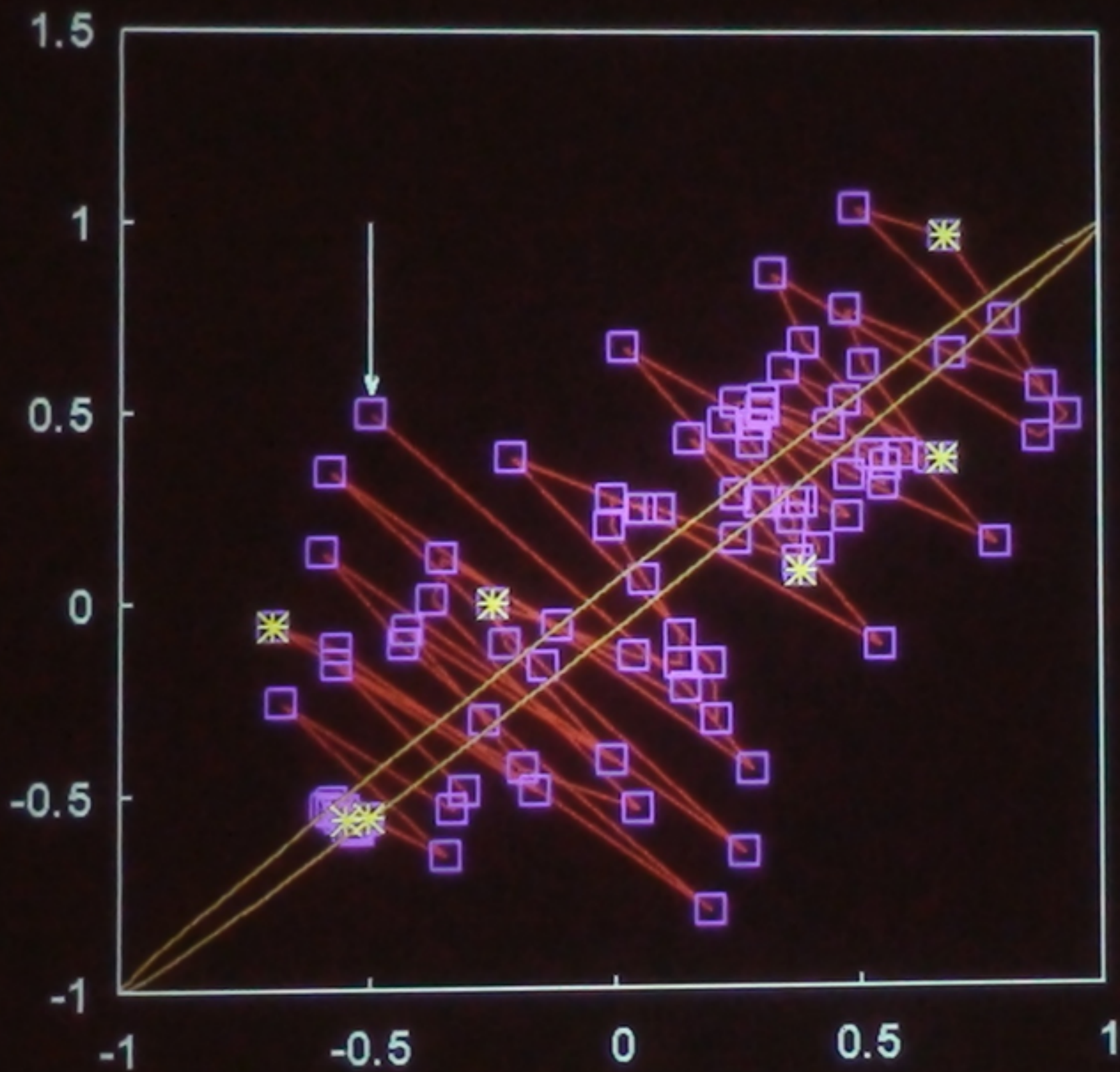
\sim

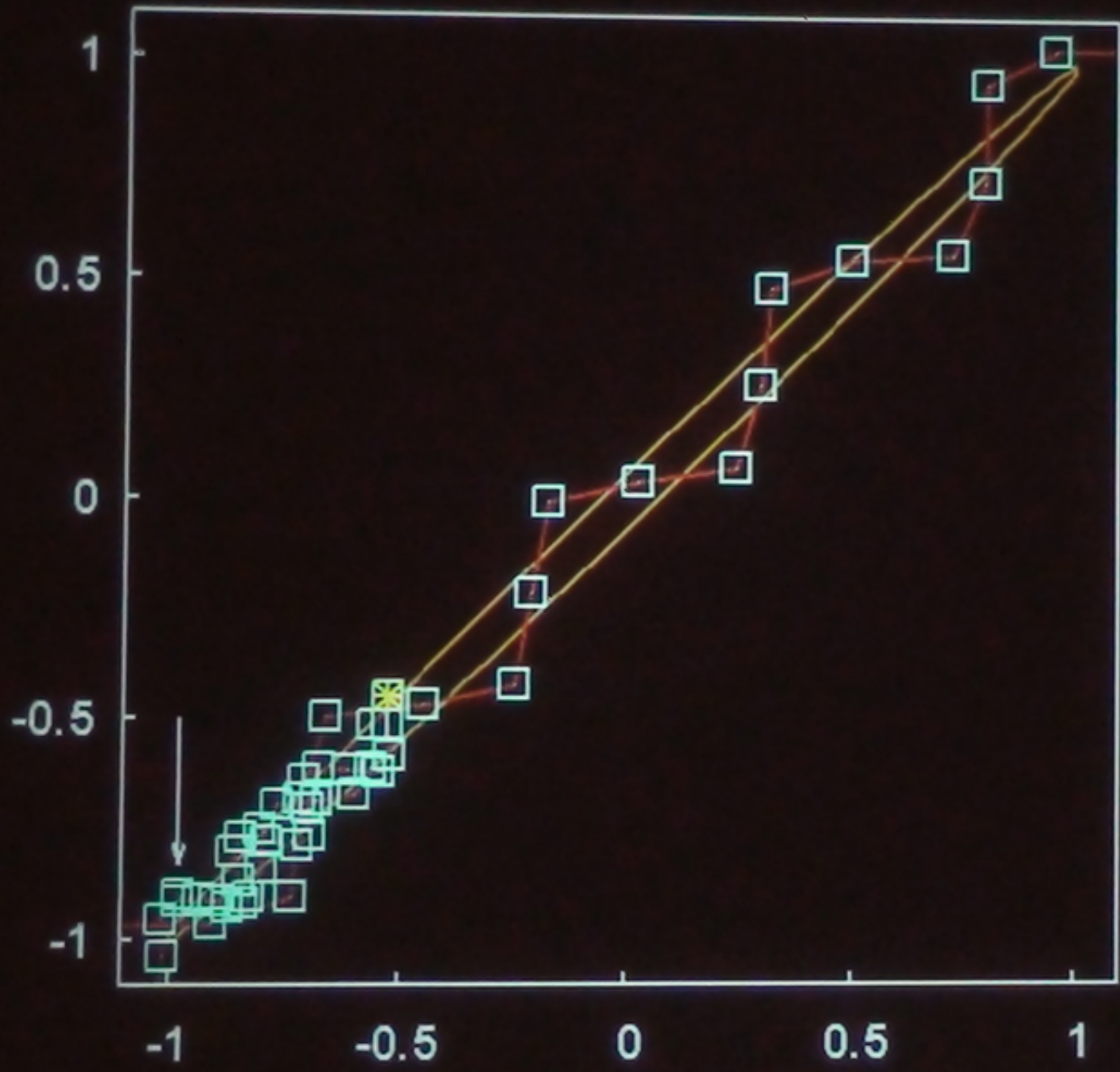
X^1
 Φ^1

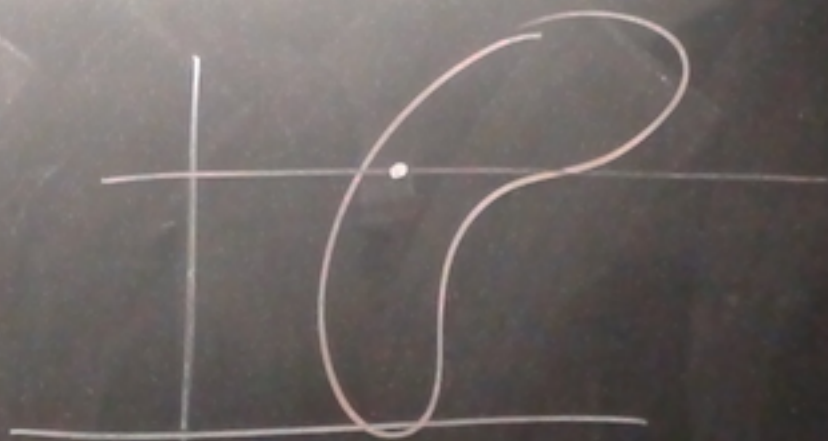
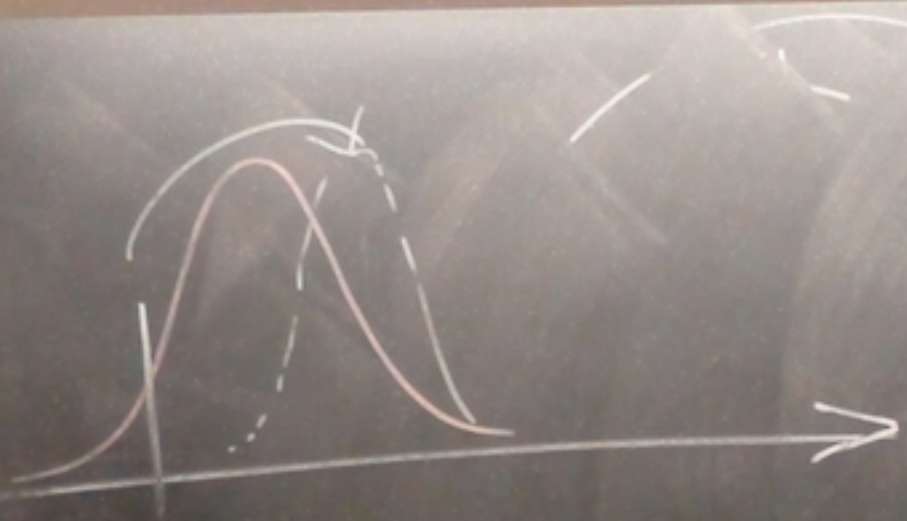
1. Simulate Newton's law (approximately) (for a time)

2. accept/reject based on change in total energy
 $-\frac{1}{2}p^2/m$

3. randomize the momentum $p \sim l$

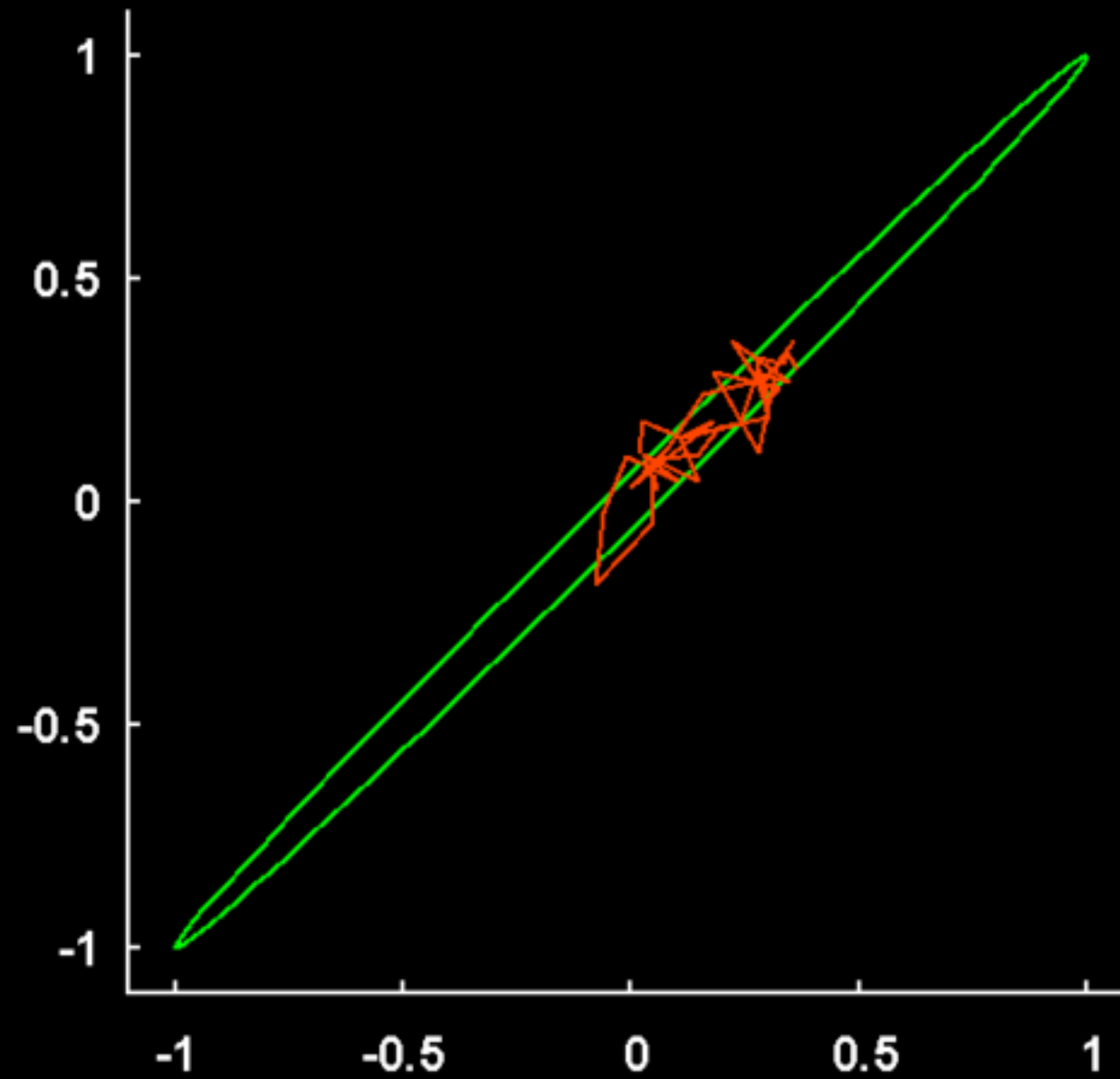




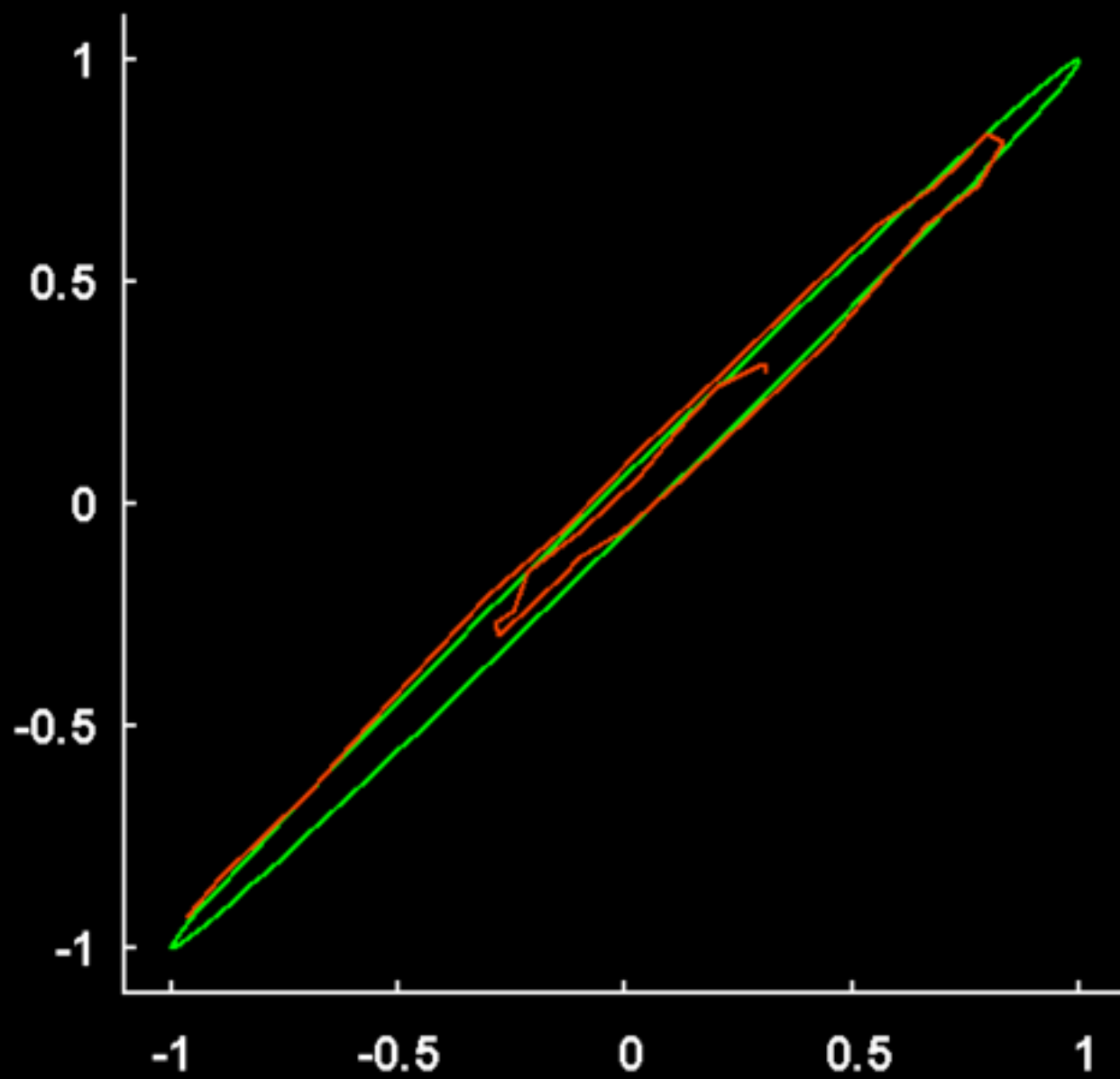


Adler's overrelaxation
for conditional distributions that are Gaussians.

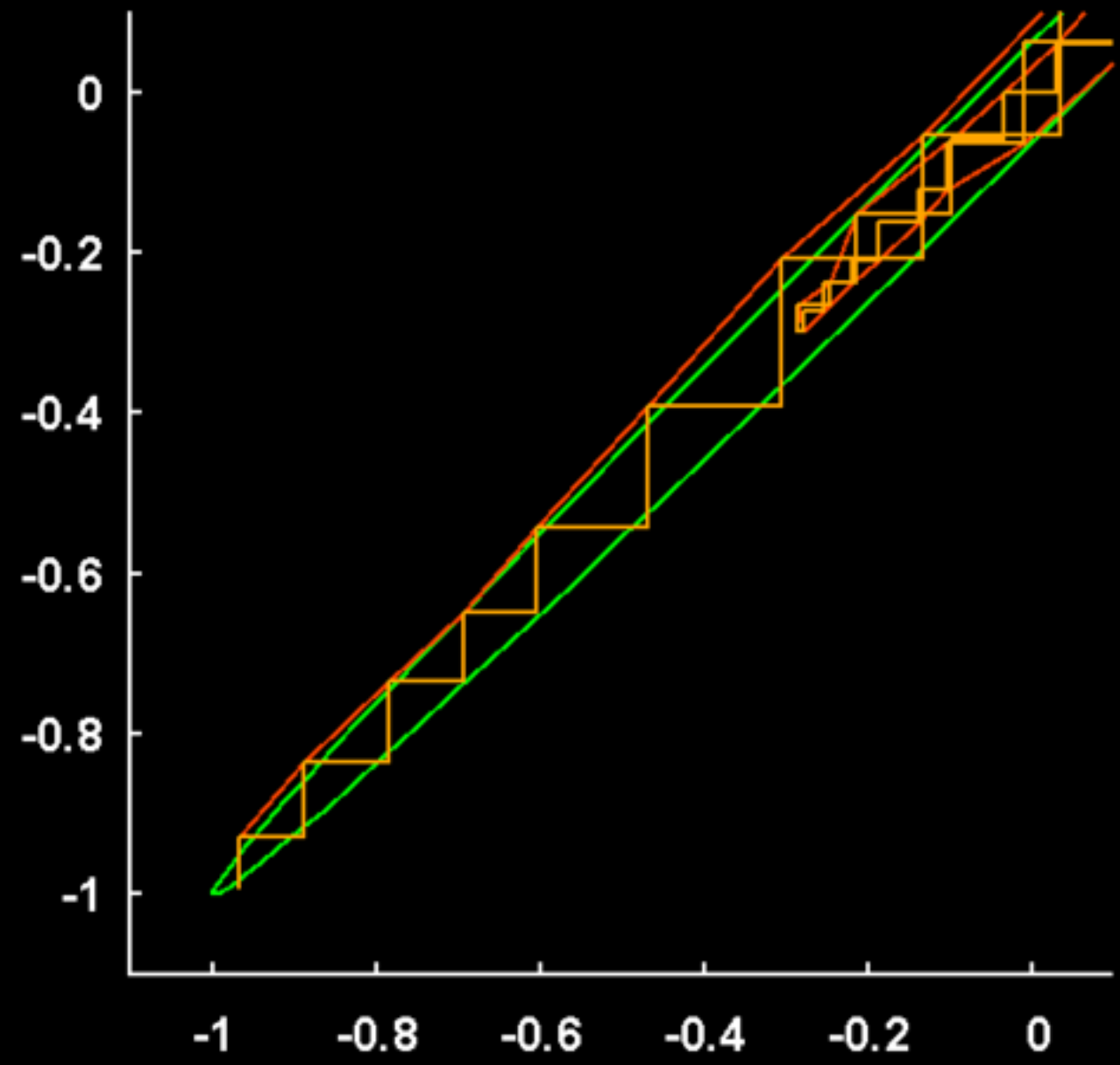
Gibbs sampling



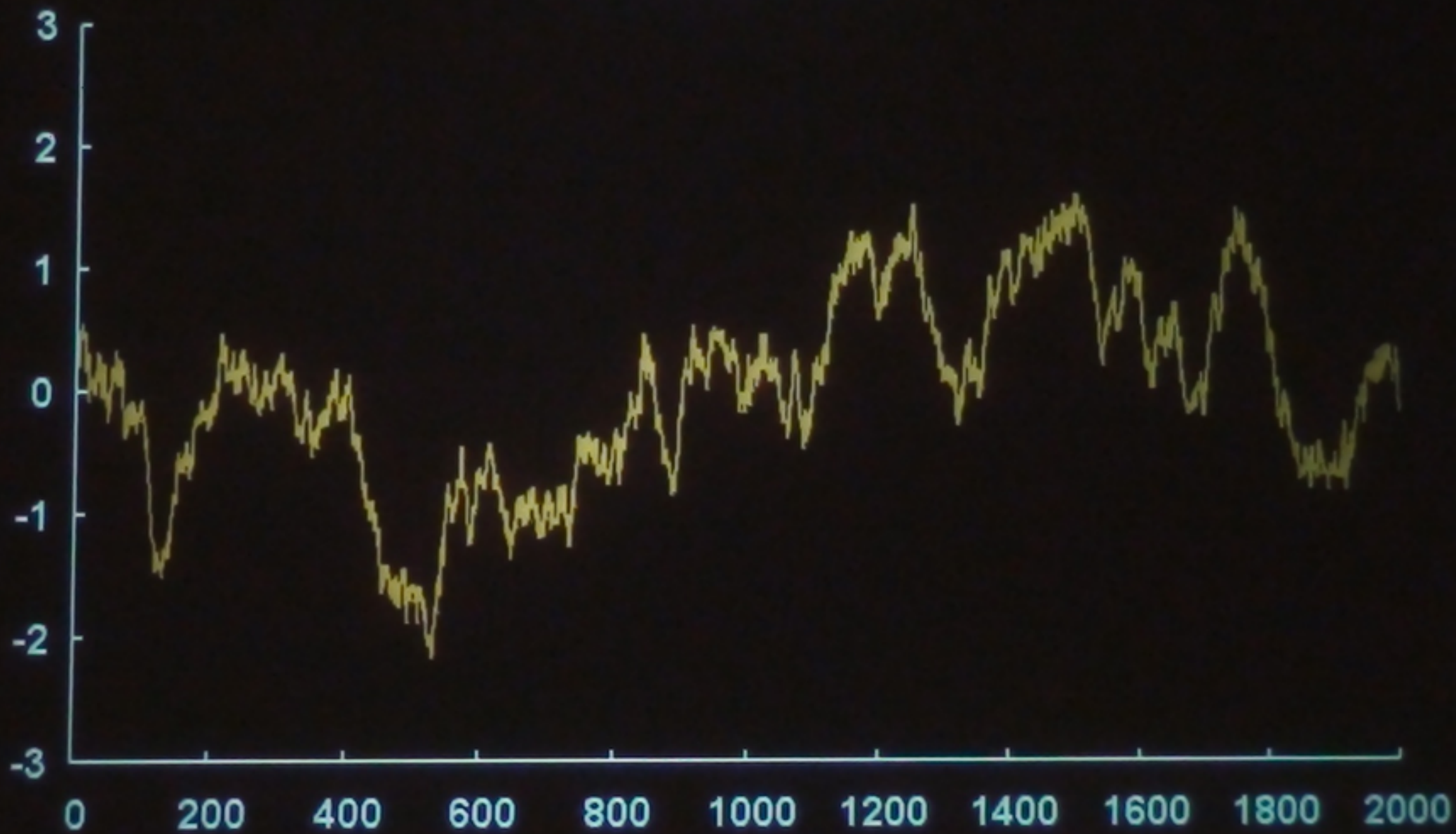
Adler's Overrelaxation



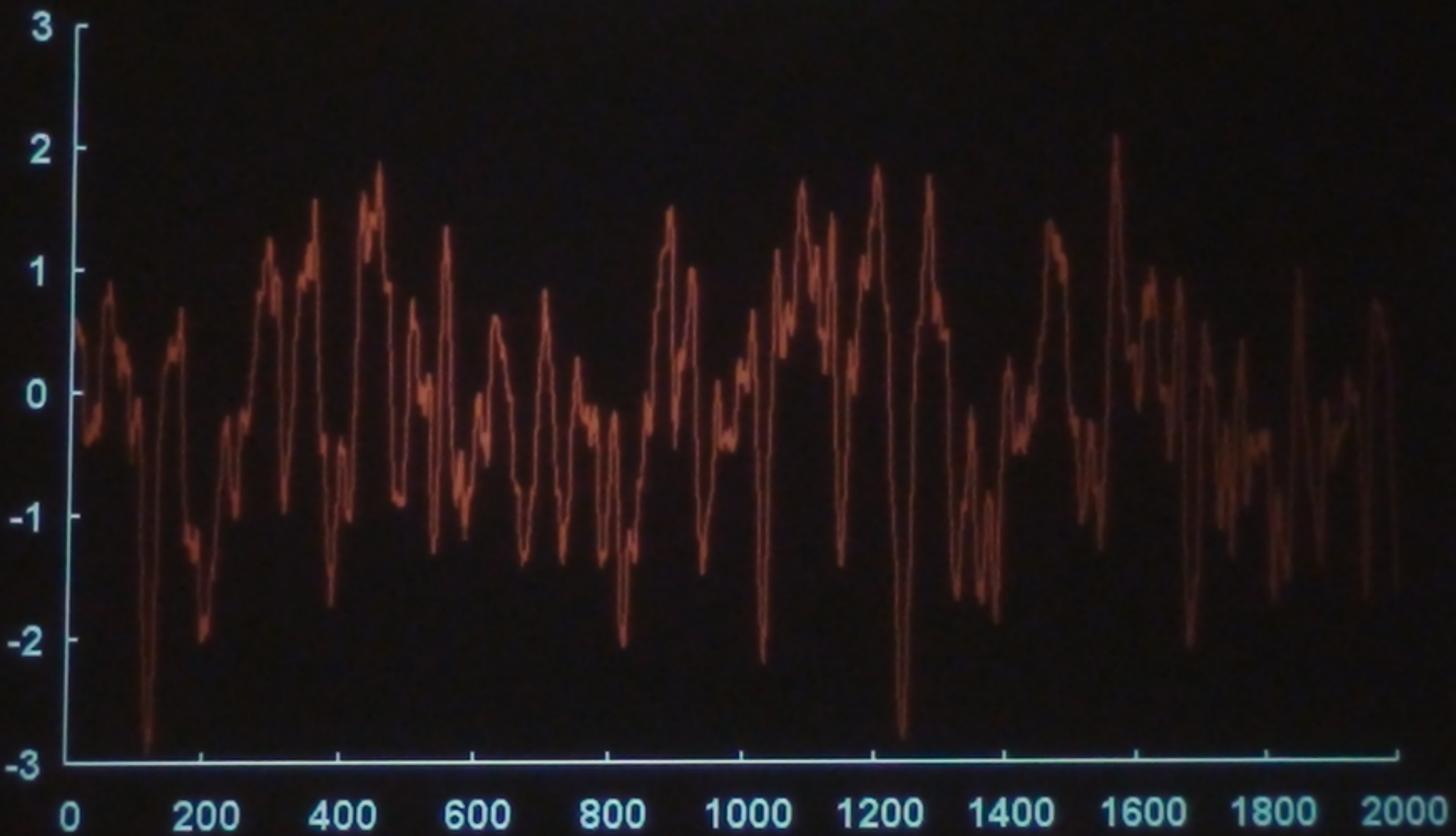
Adler's Overrelaxation



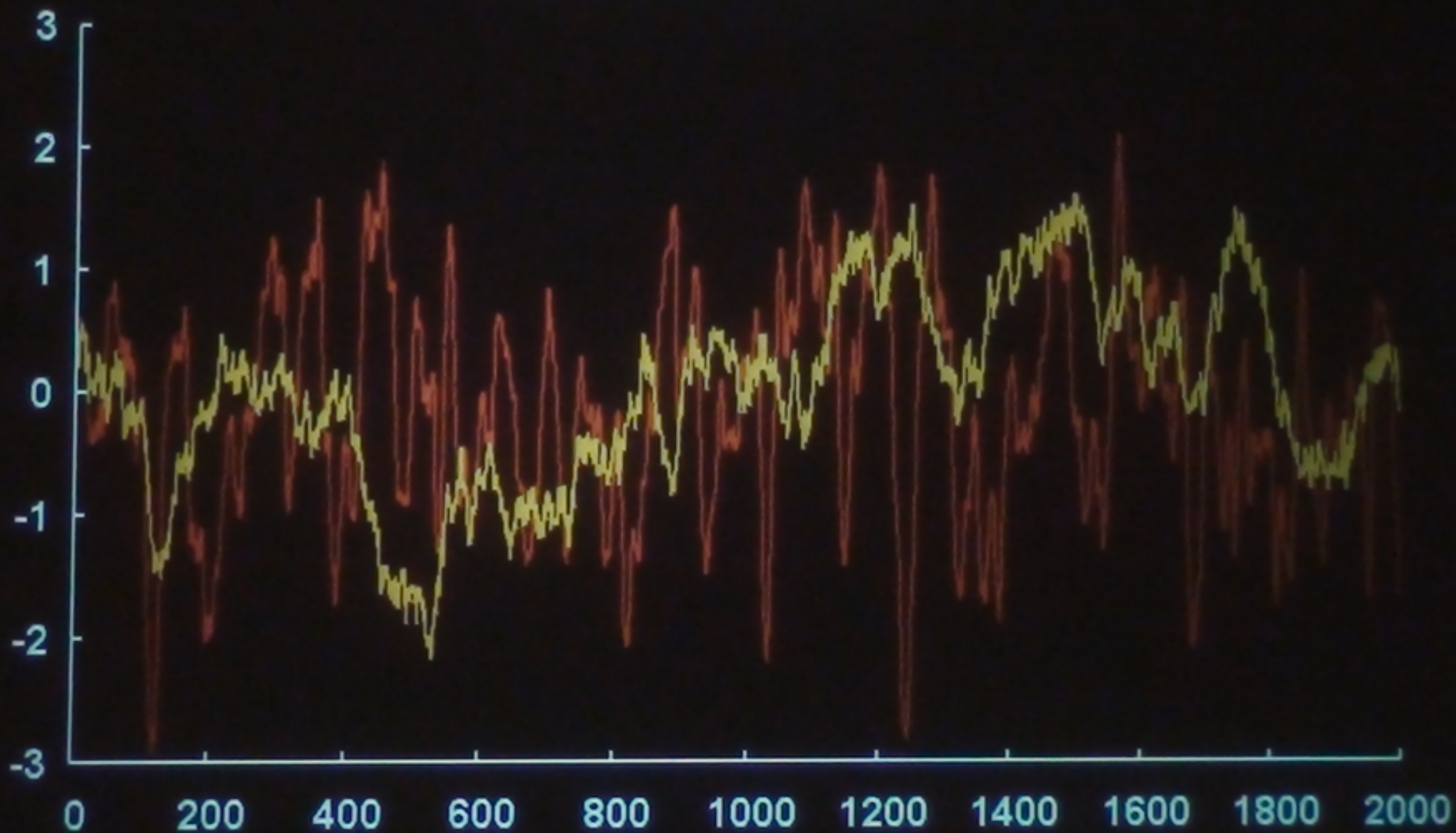
Gibbs sampling - x1



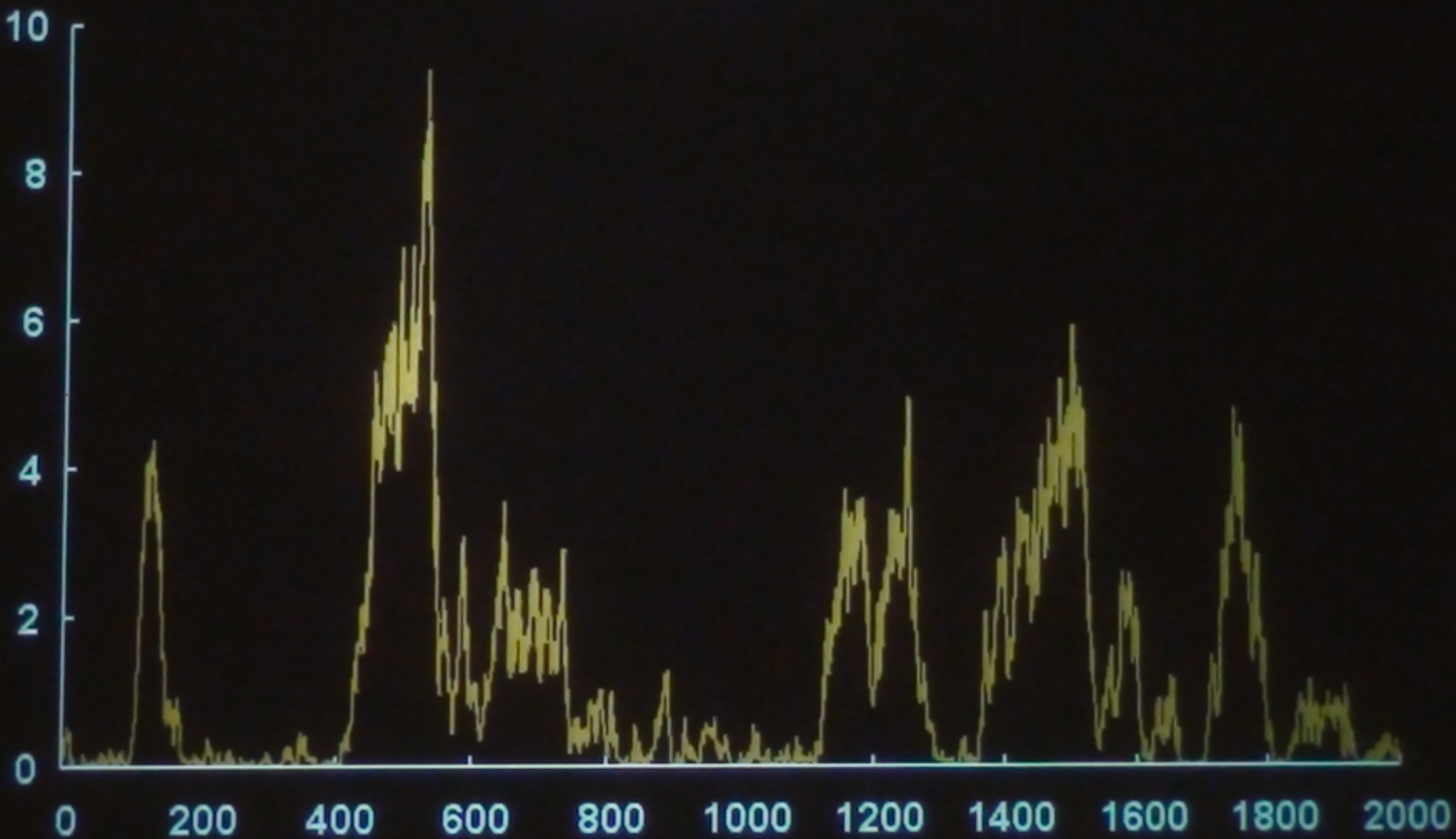
Adler's Overrelaxation - x1



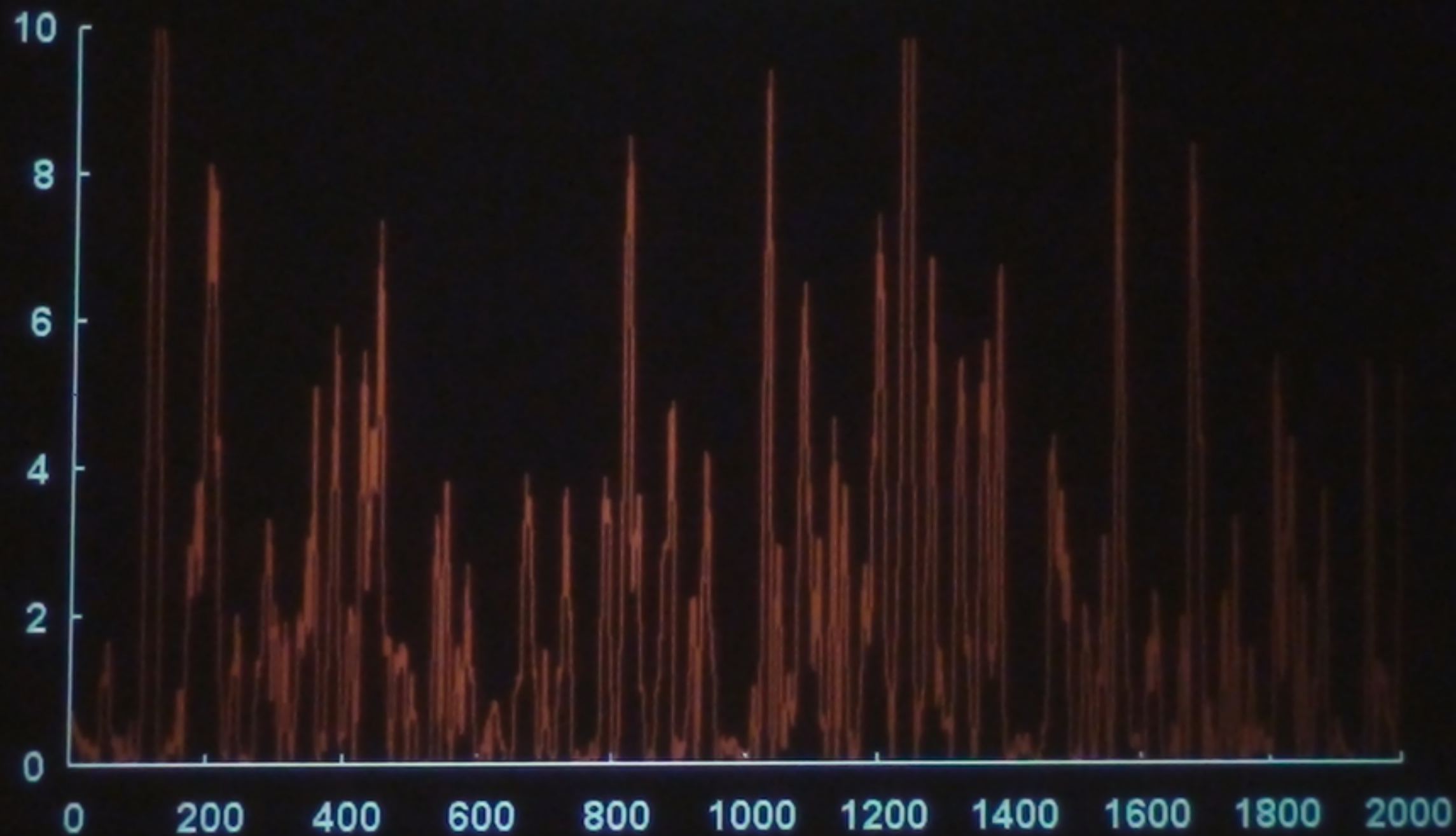
Adler's Overrelaxation - x1



Gibbs sampling - x_1^2

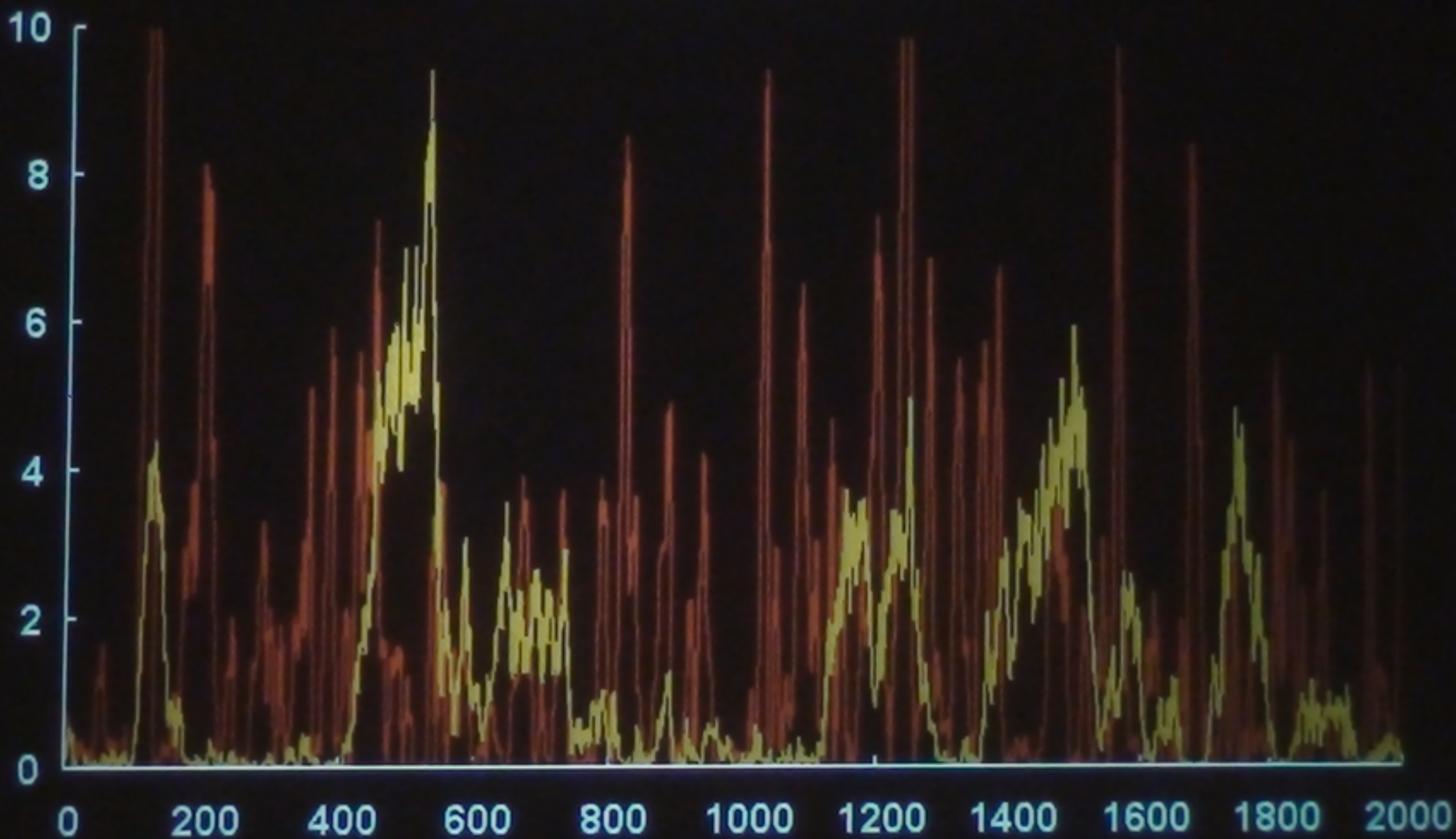


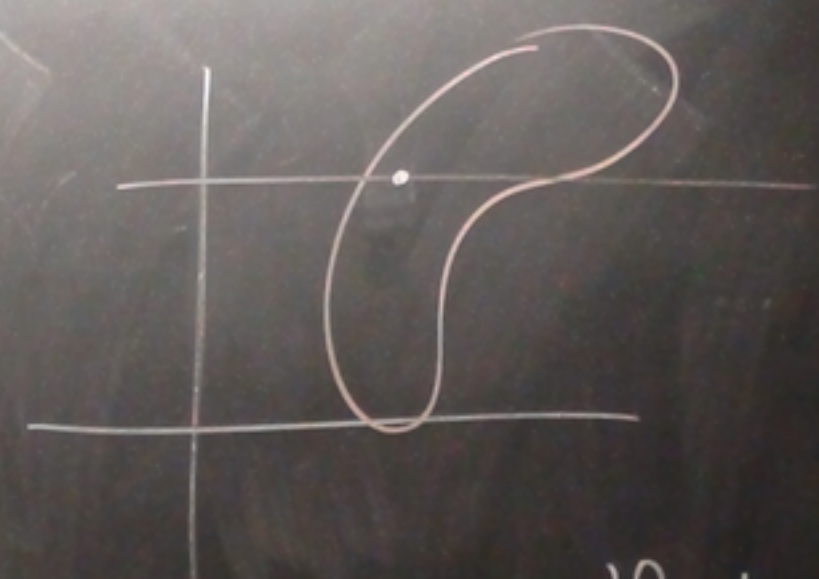
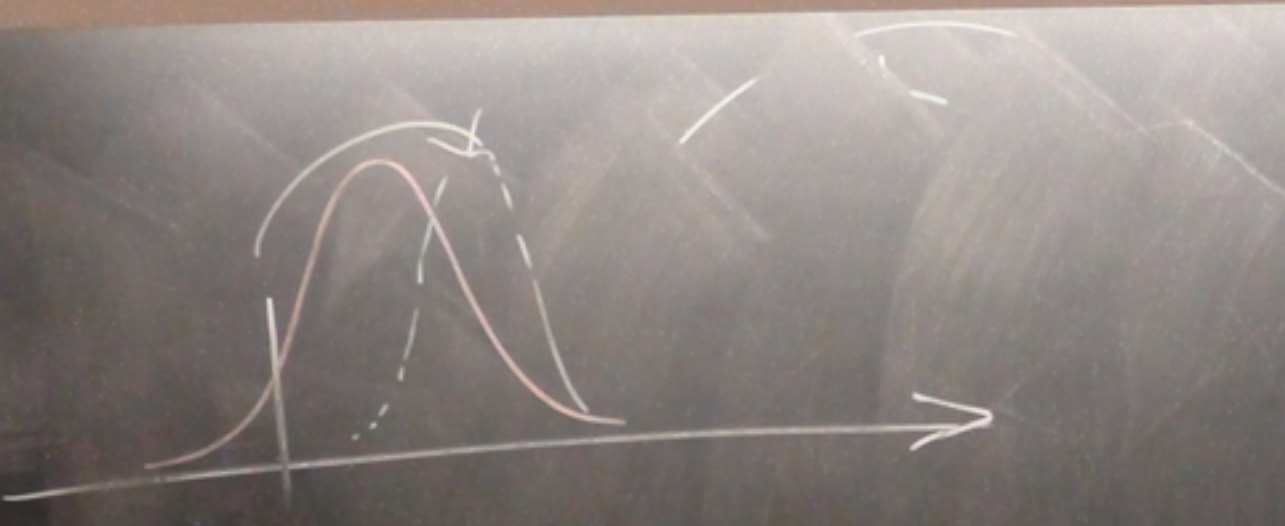
Adler's Overrelaxation - $x1^2$



gibbs x1^2
adler x1^2

Adler's Overrelaxation - x_1^2

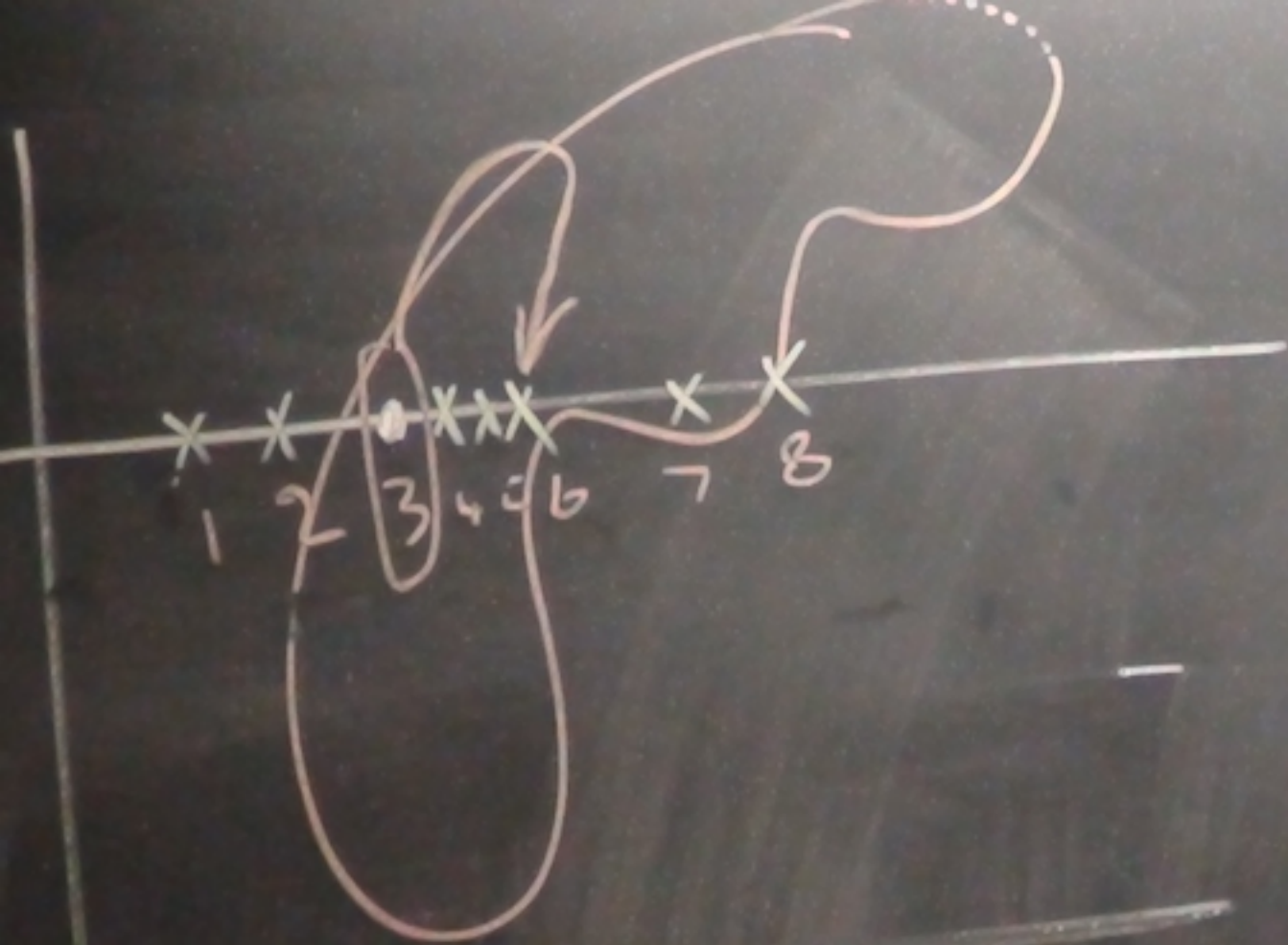




Adler's overrelaxation
for conditional distributions that are Gaussians.

Ordered overrelaxation

Radford Neal



draw
K
times

$K \approx 20$

BUGS

Robust Monte Carlo methods

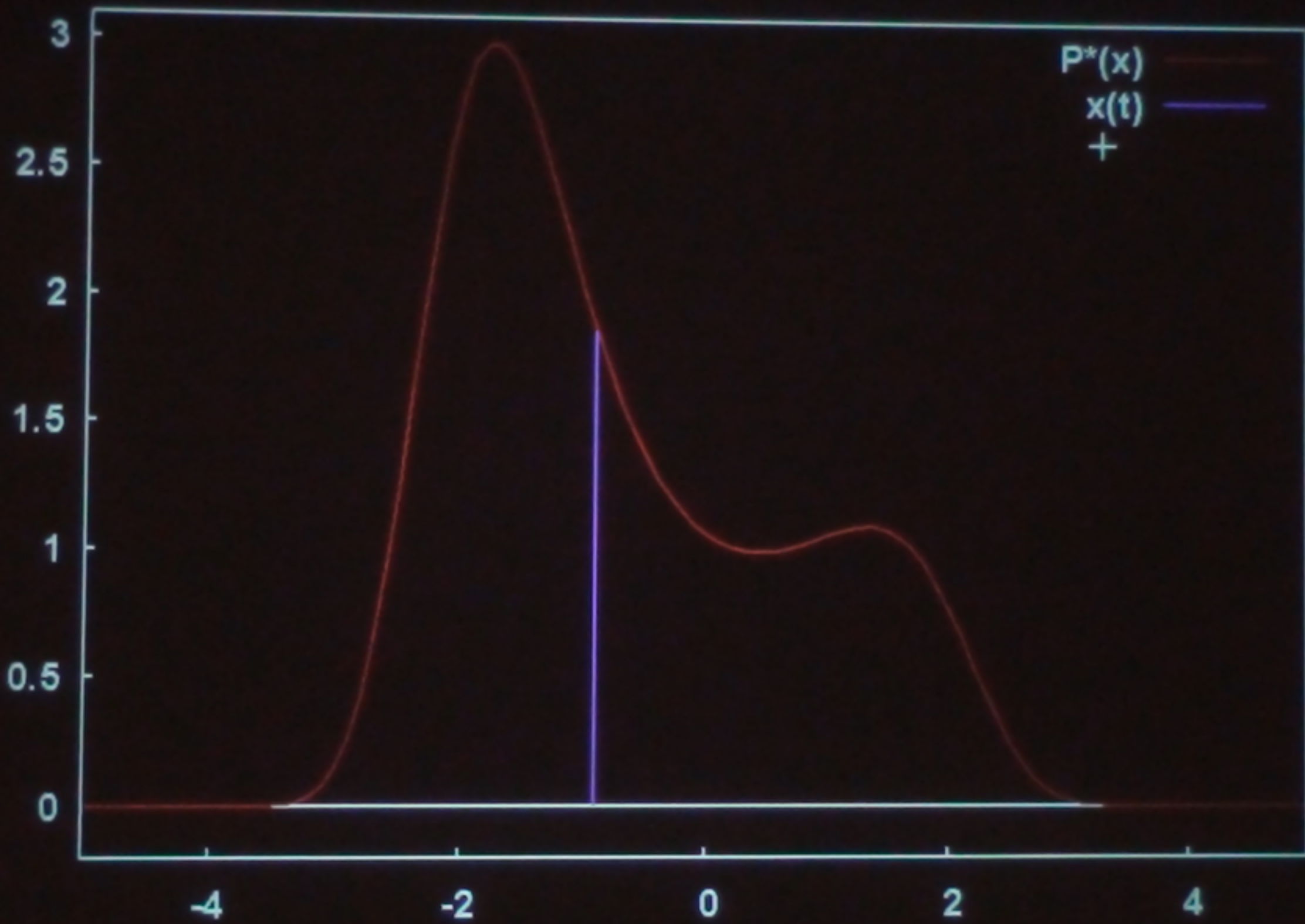
Slice sampling

Slice sampling

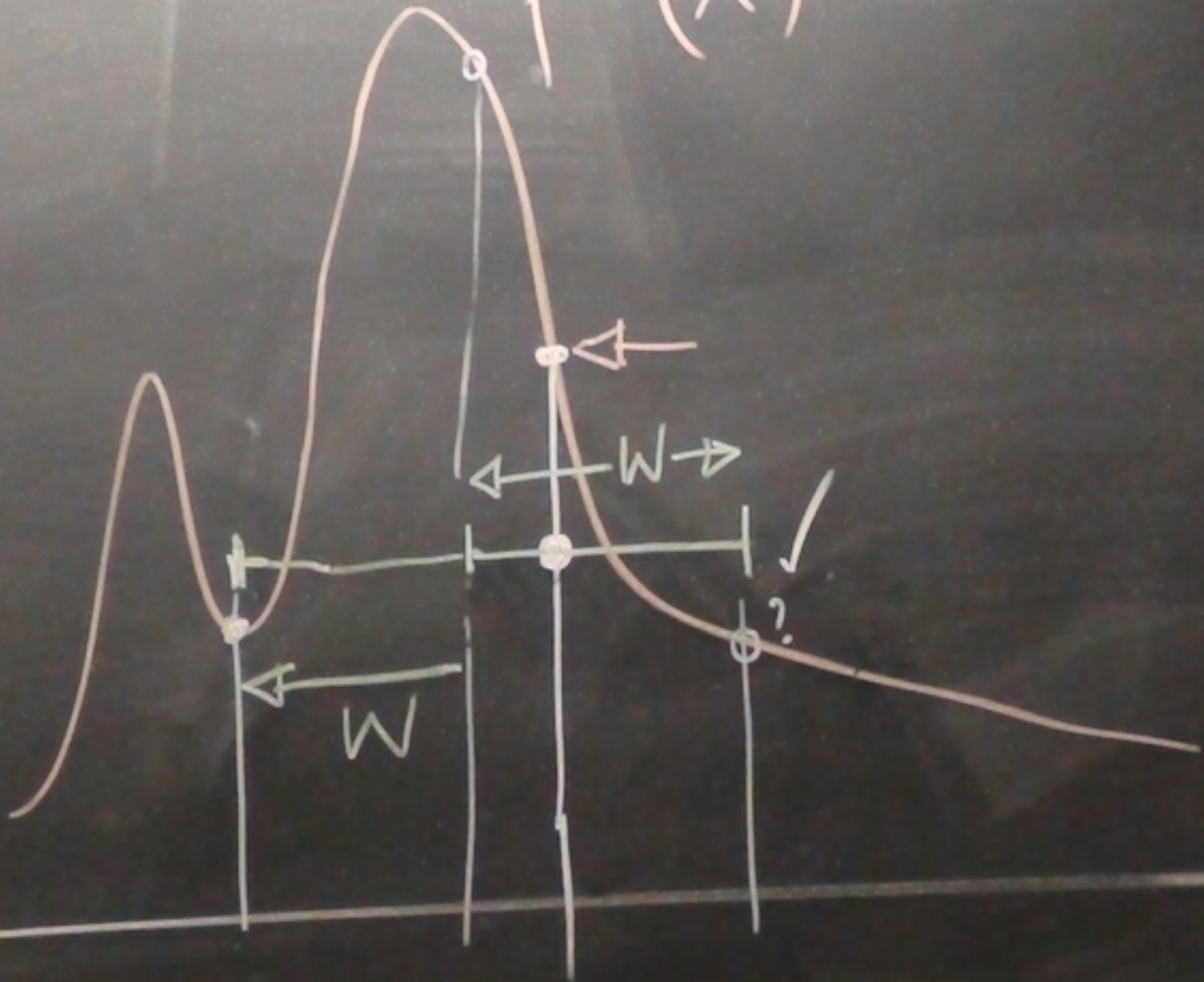
Radford Neal

John Skilling

1 samples

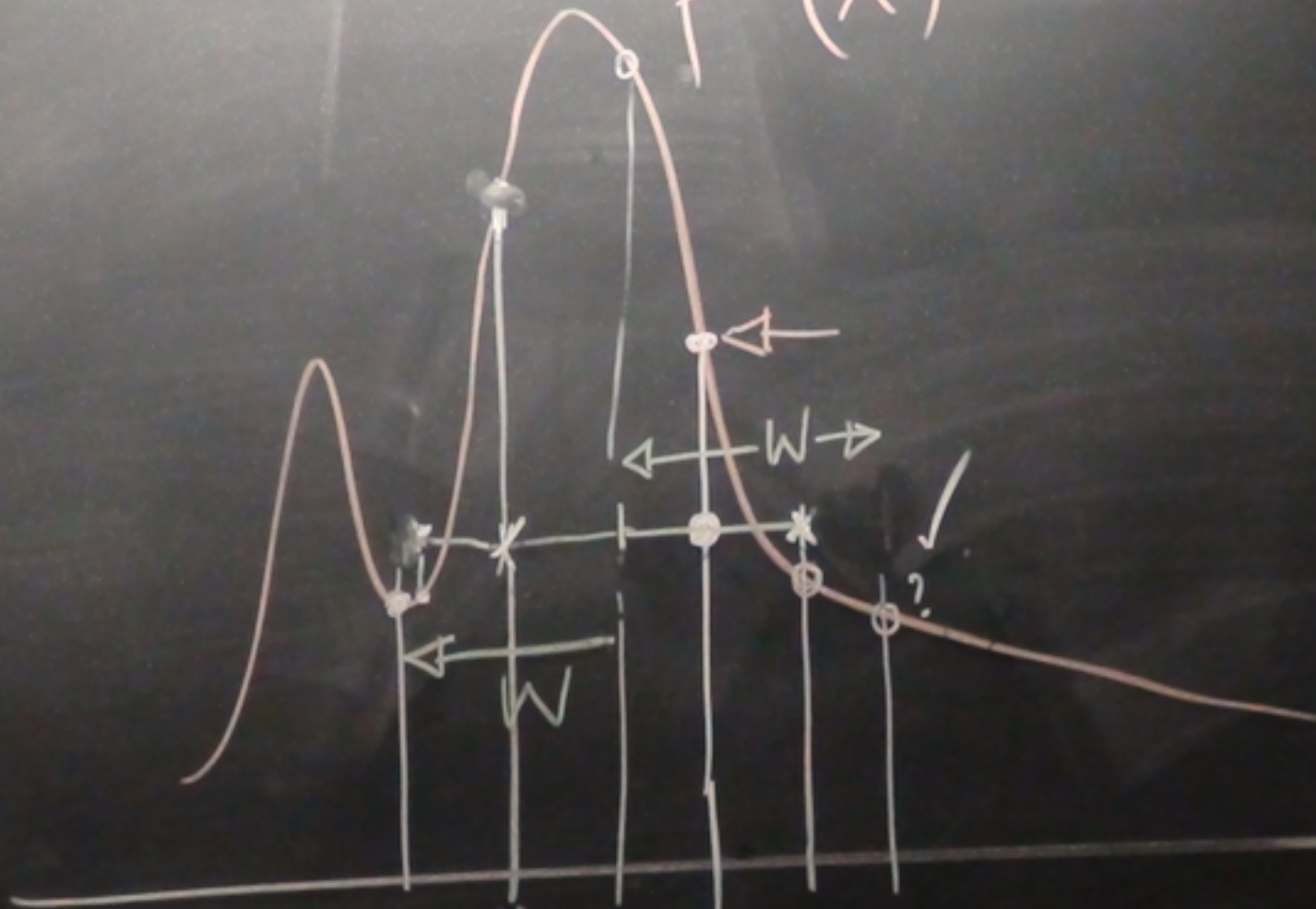


$P^*(x)$



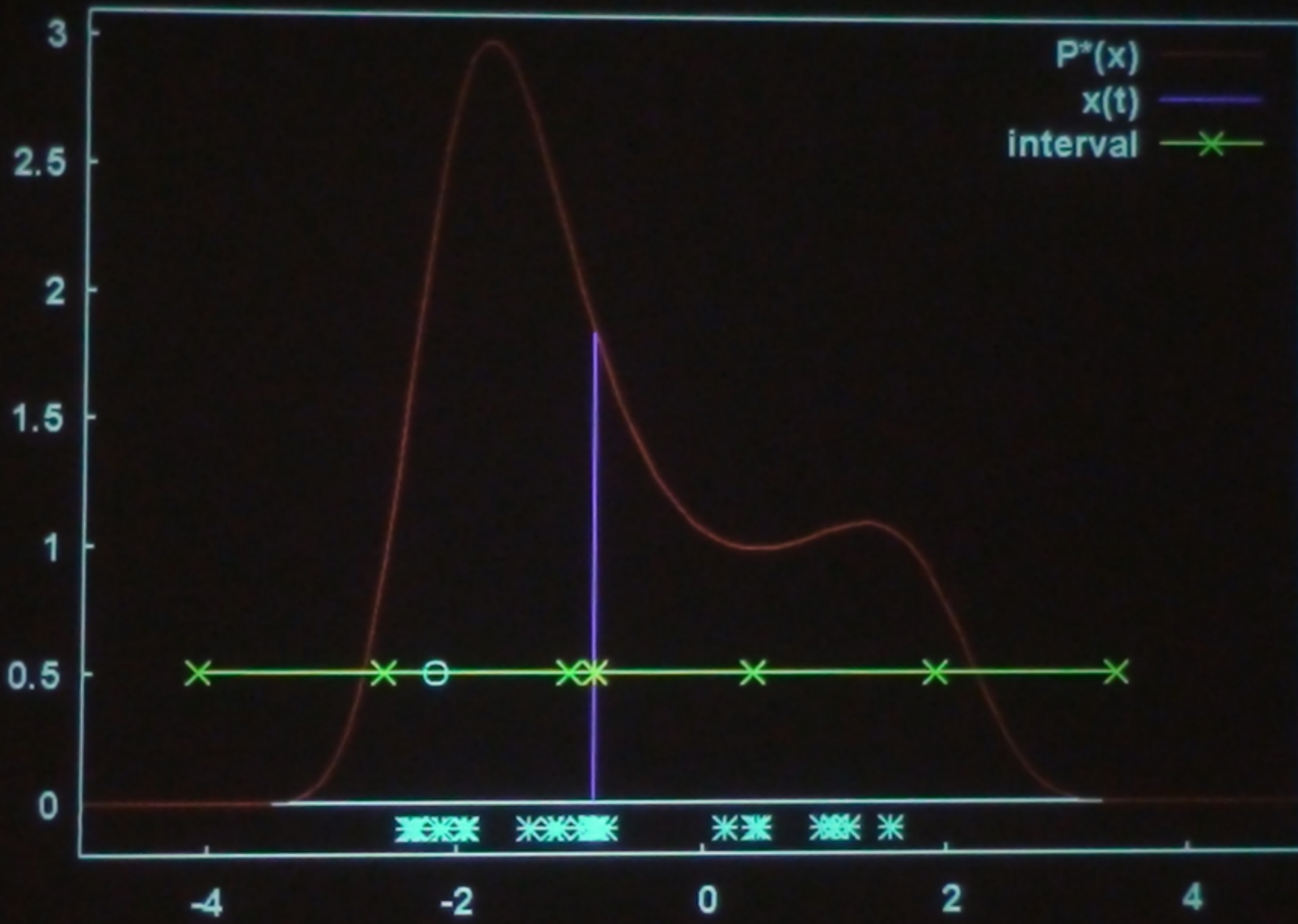
X_T

$$P^*(x)$$

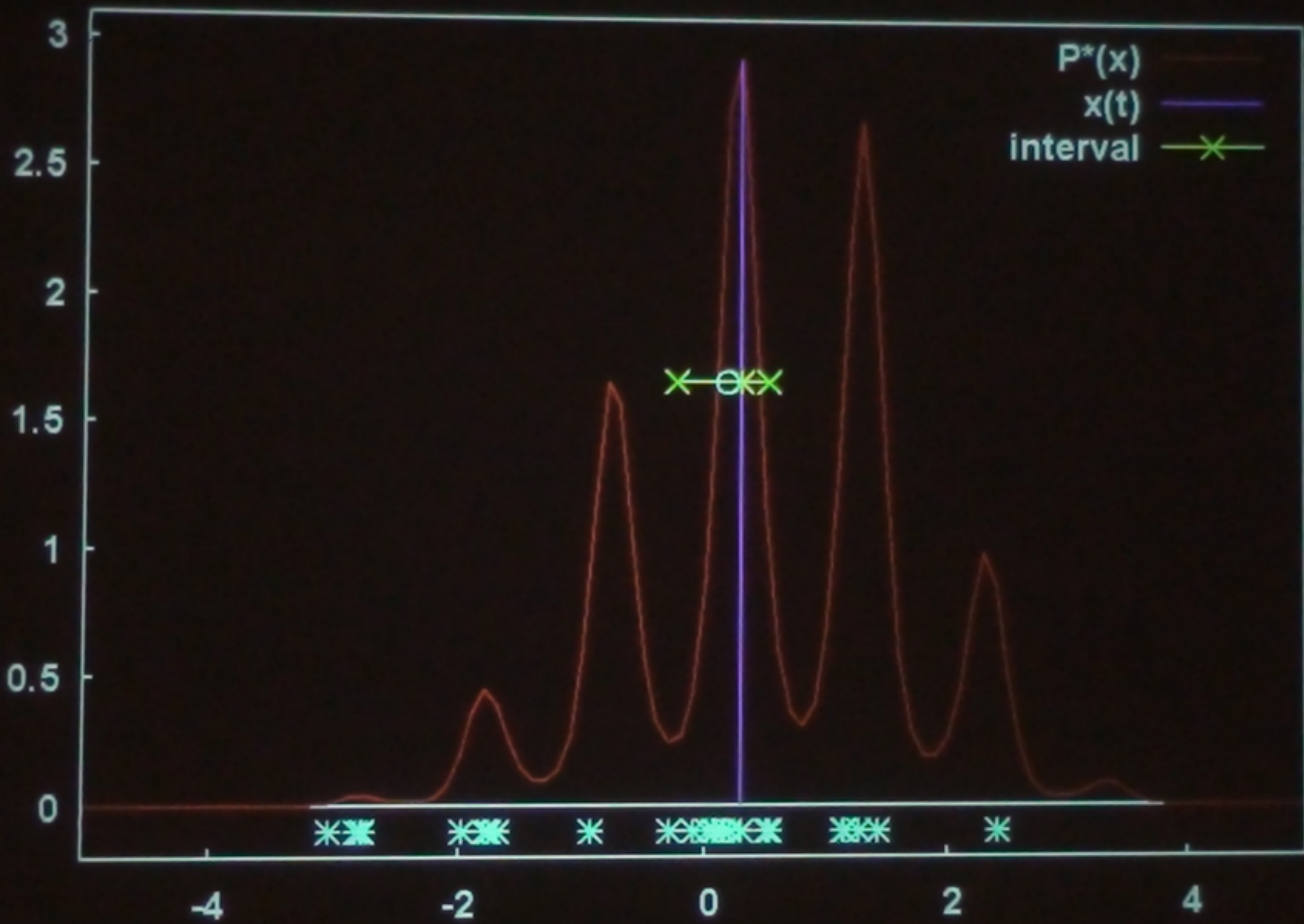


x_{t+1}
 x_t

25 samples



25 samples

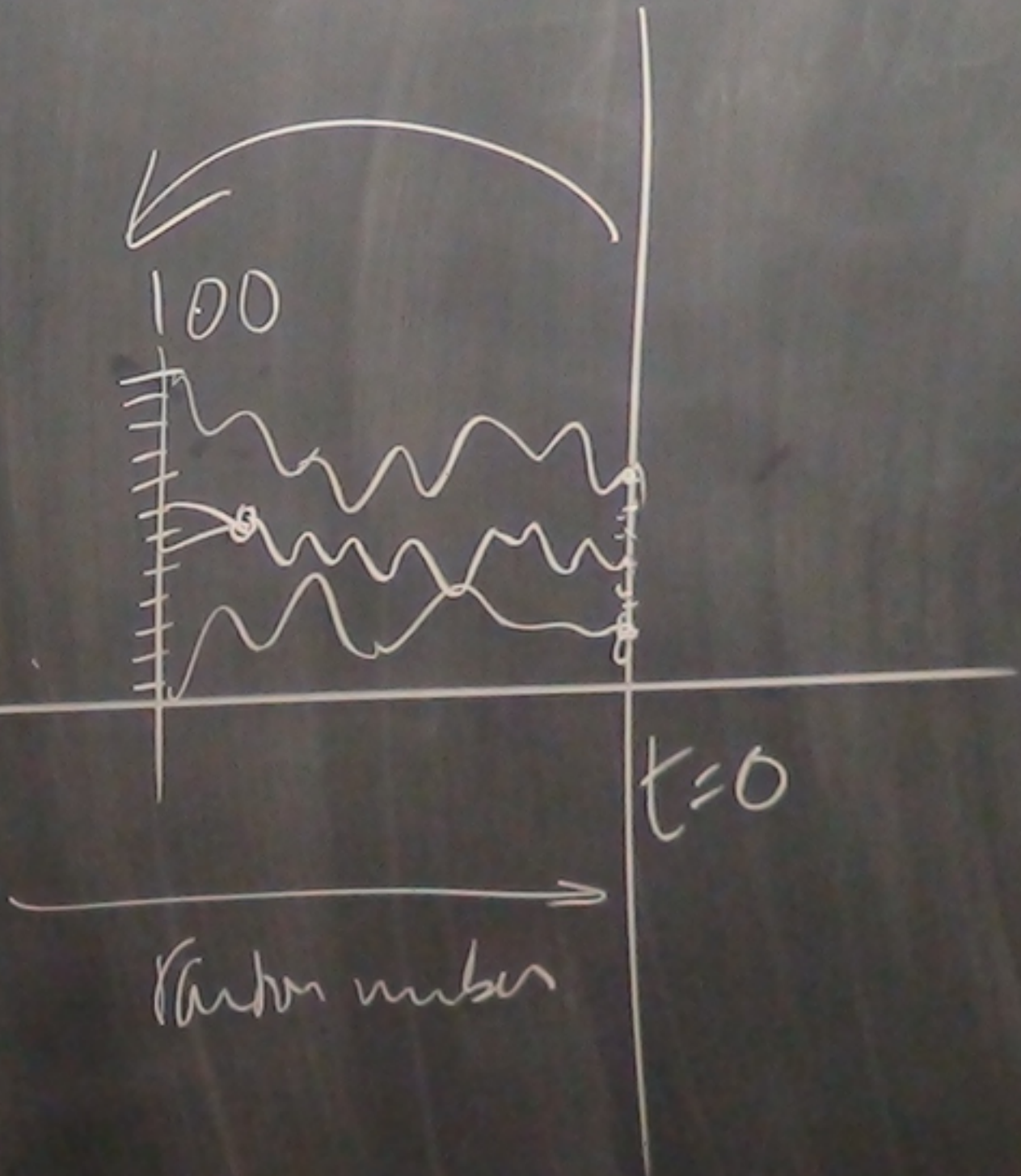


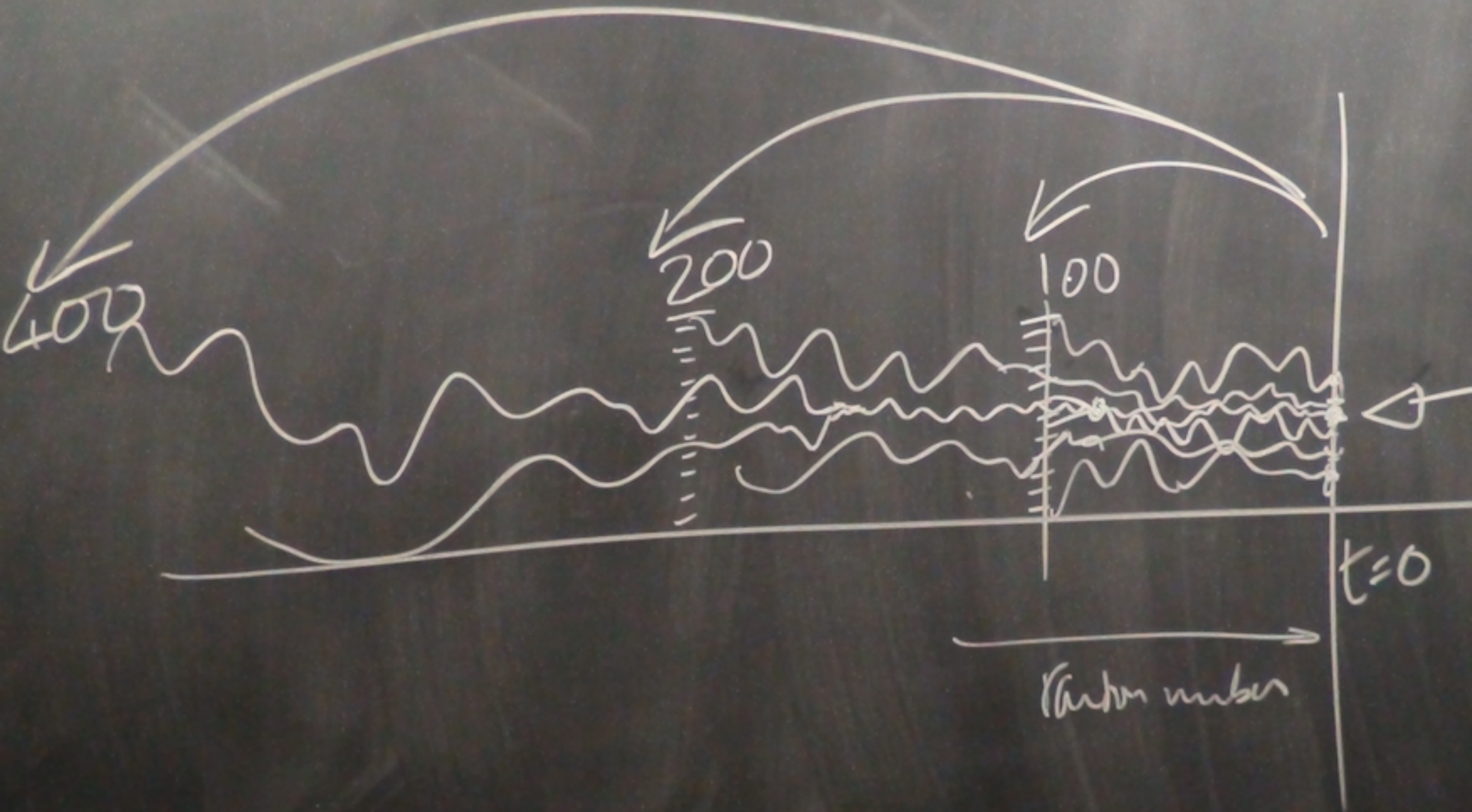
Self-terminating Monte Carlo methods

Exact sampling

How long?

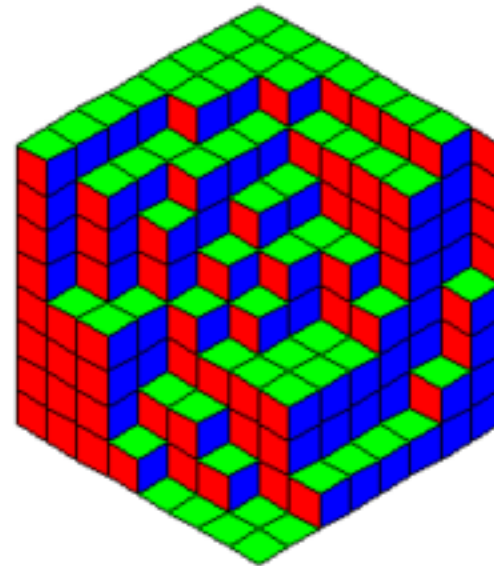
∞ by long.



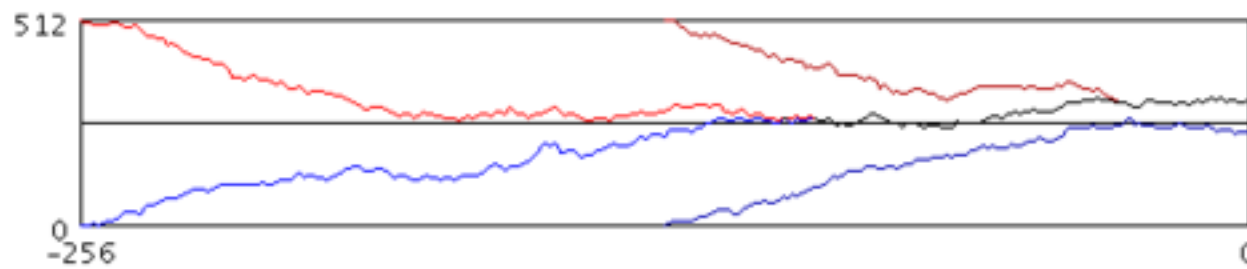


Exact sampling

Hexagon

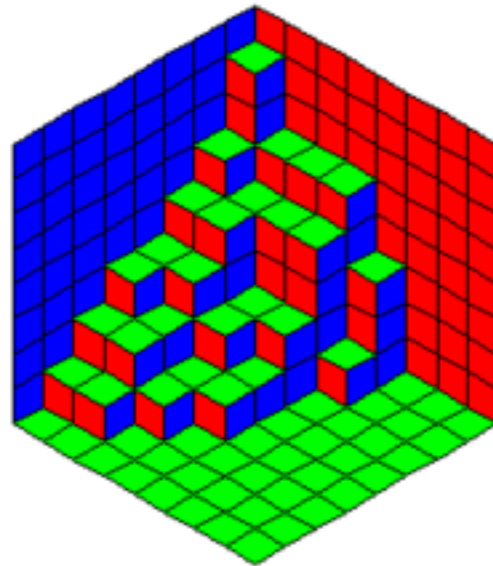


Height: 313

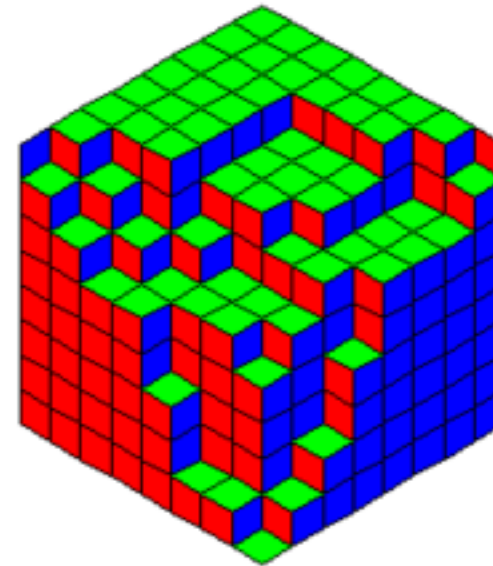


Exact sampling

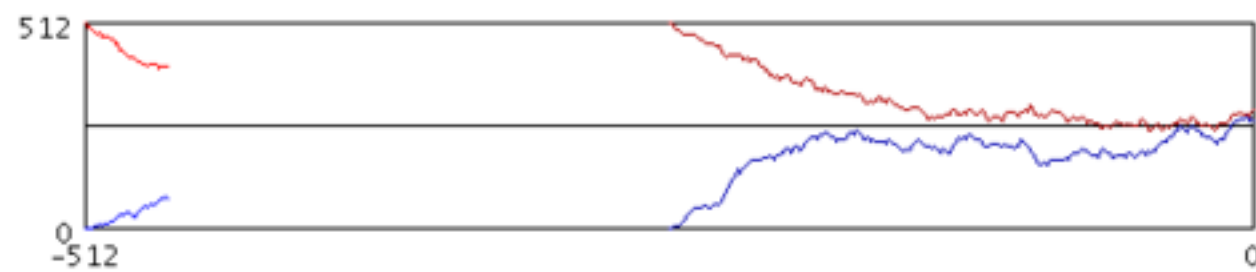
Hexagon



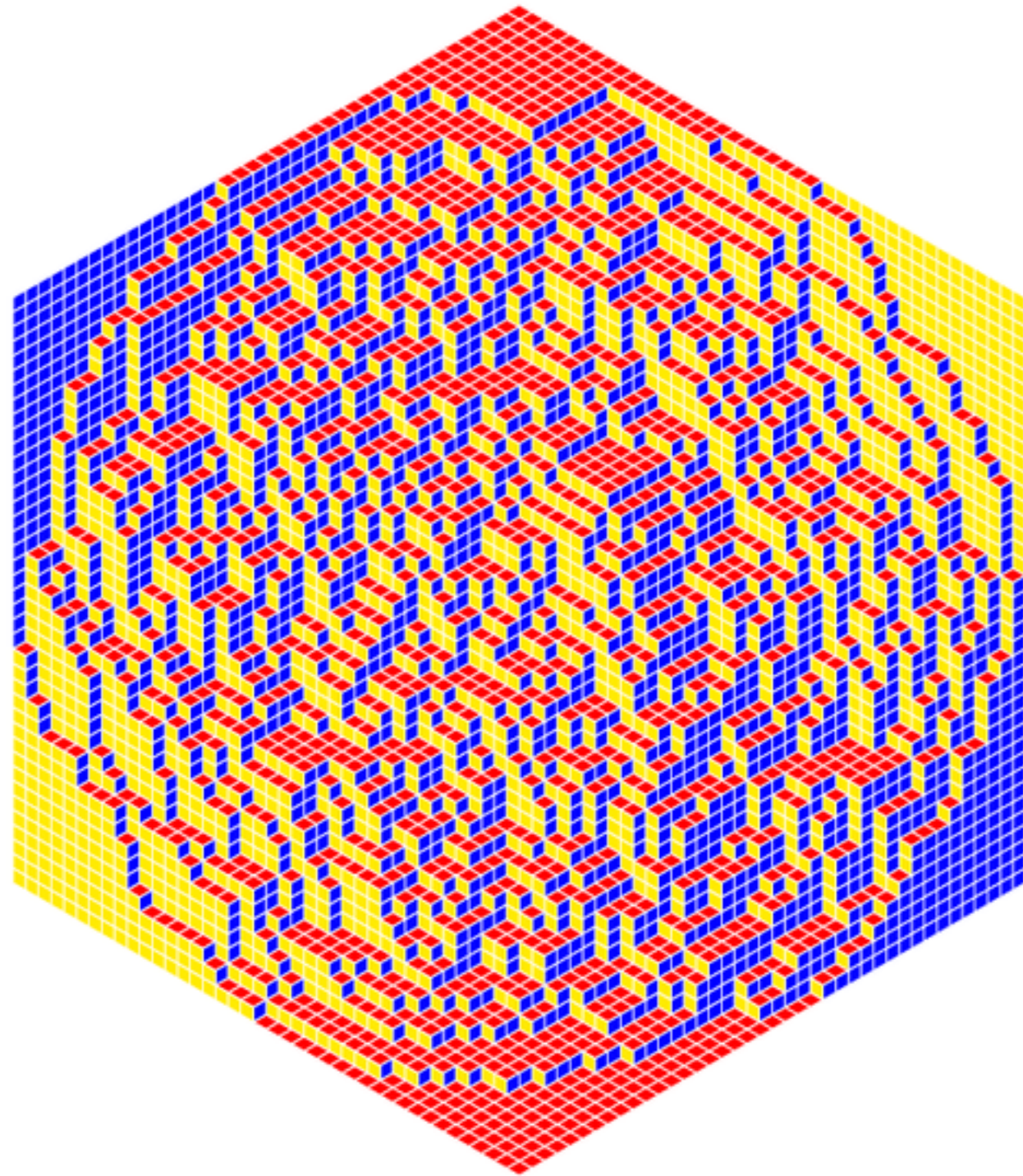
Height: 78

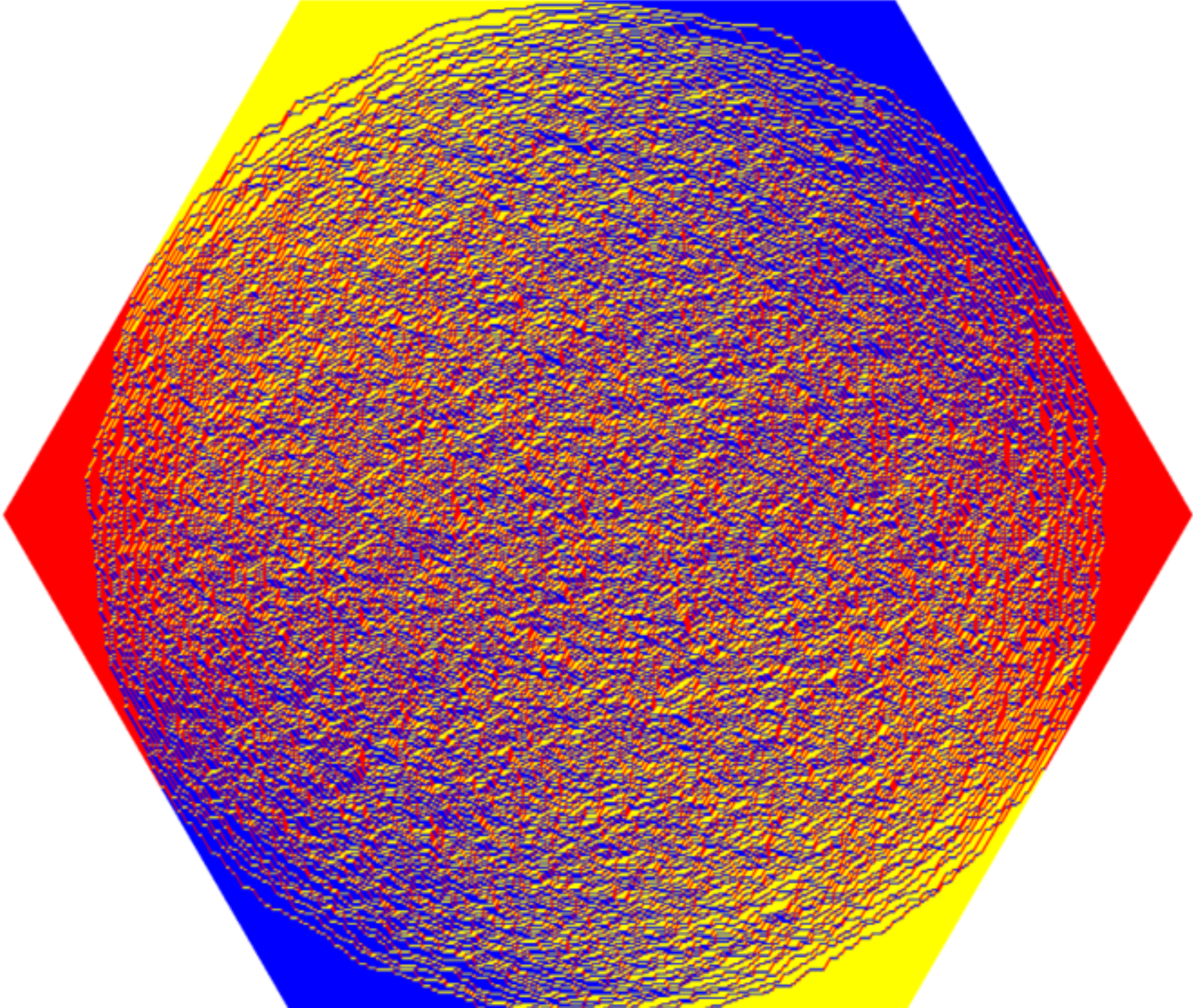
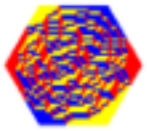


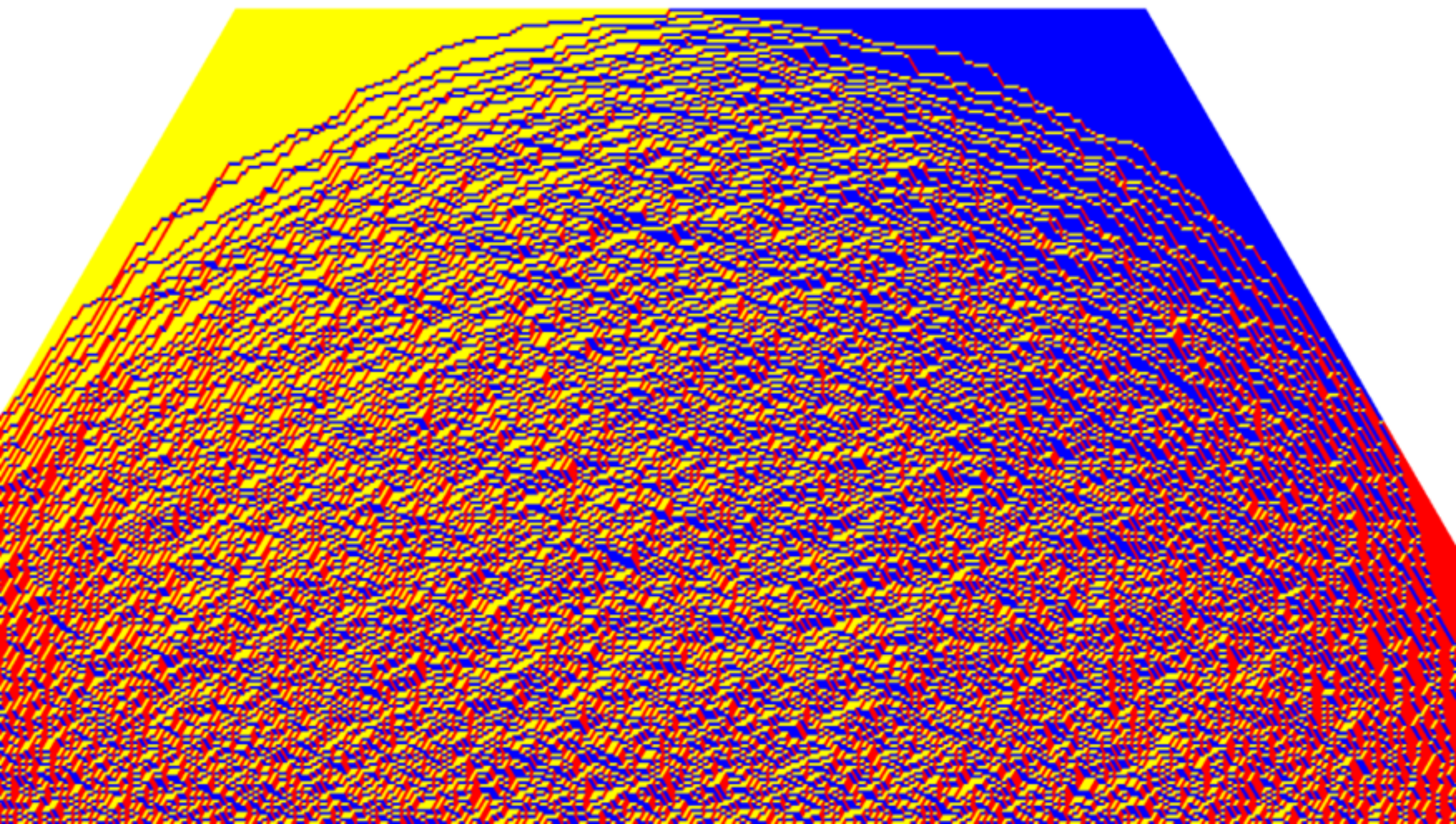
Height: 407



Exact sampling

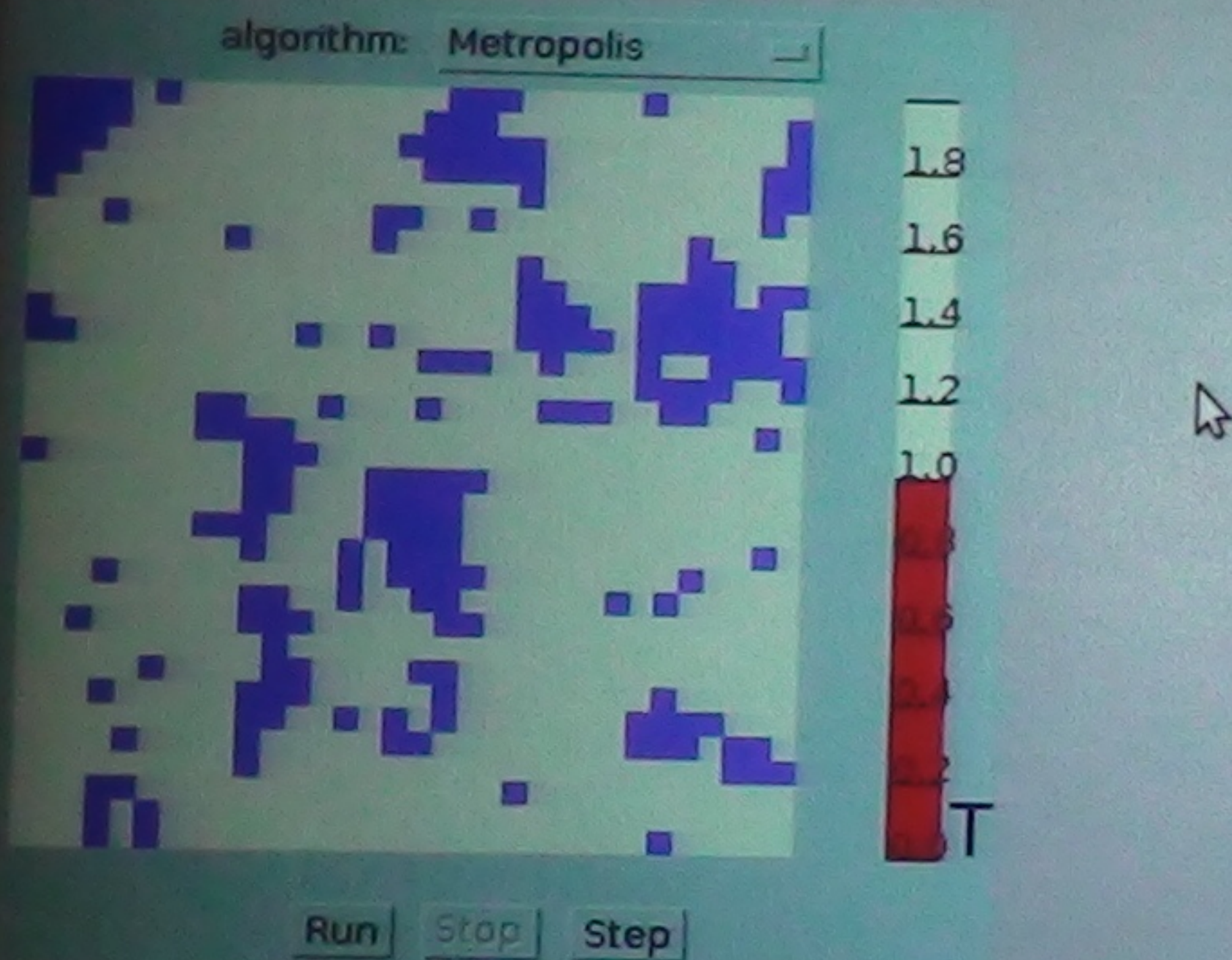






Exact sampling for the Ising model

controlled by the red bar, the spins prefer to be parallel.



In the Delft computational physics group, Ising simulations

controlled by the red bar, the spins prefer to be para

algorithm: Metropolis



Run Stop Step

Introduction to the Ising model

$N = 4096$

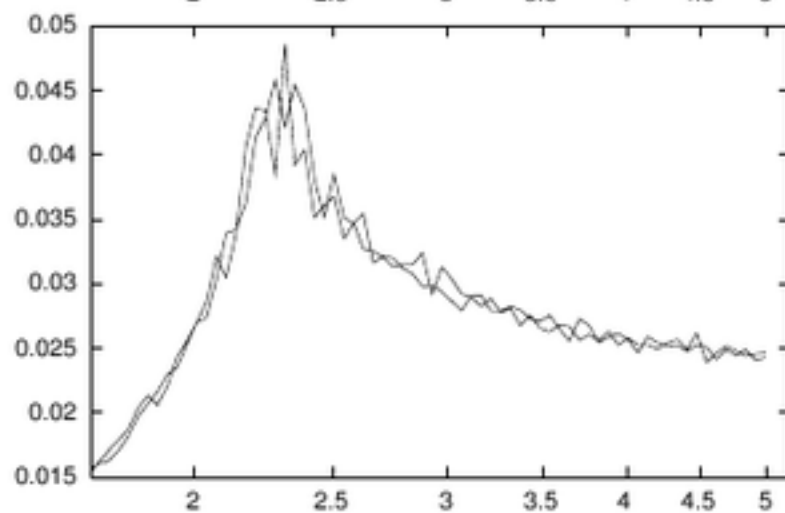
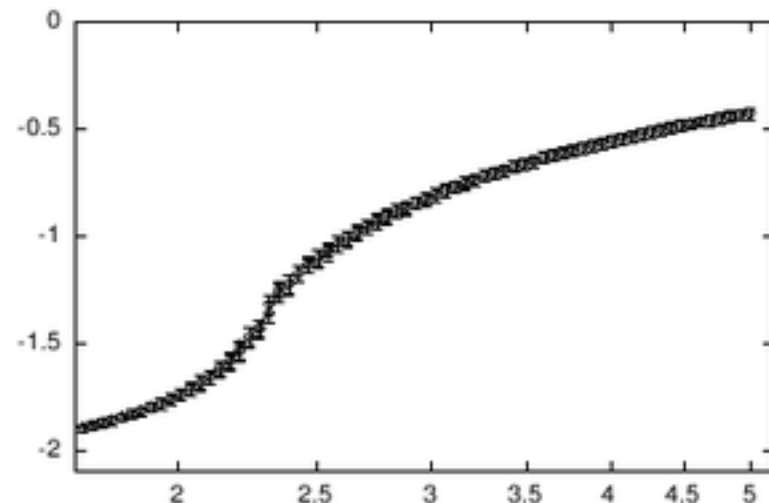
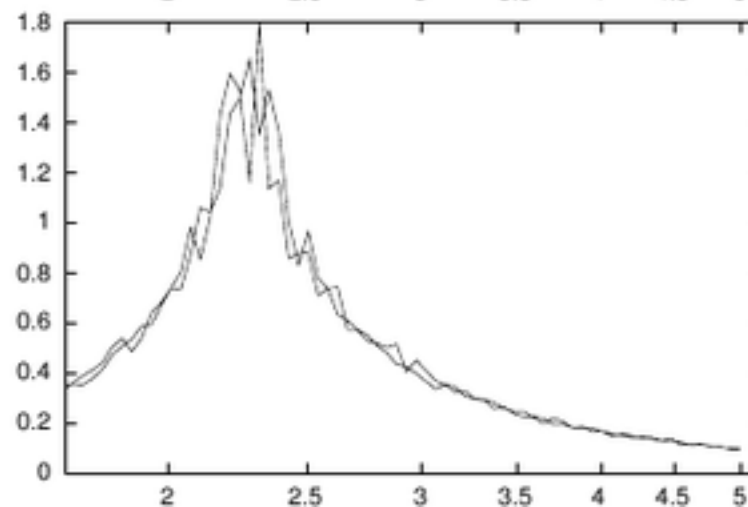
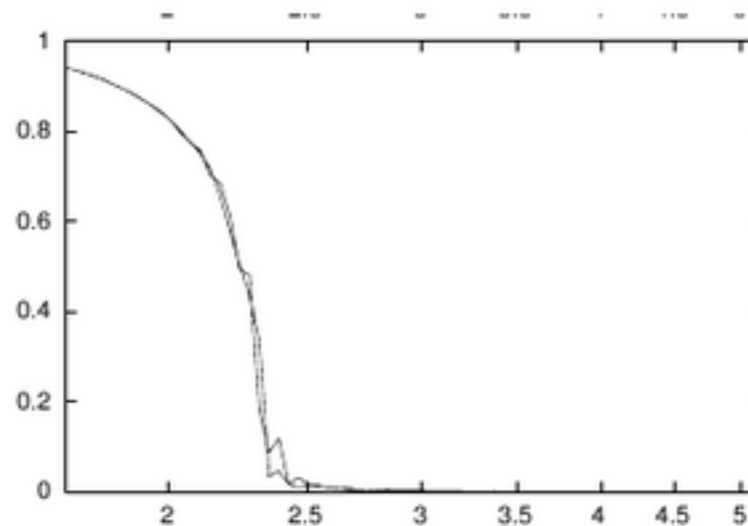
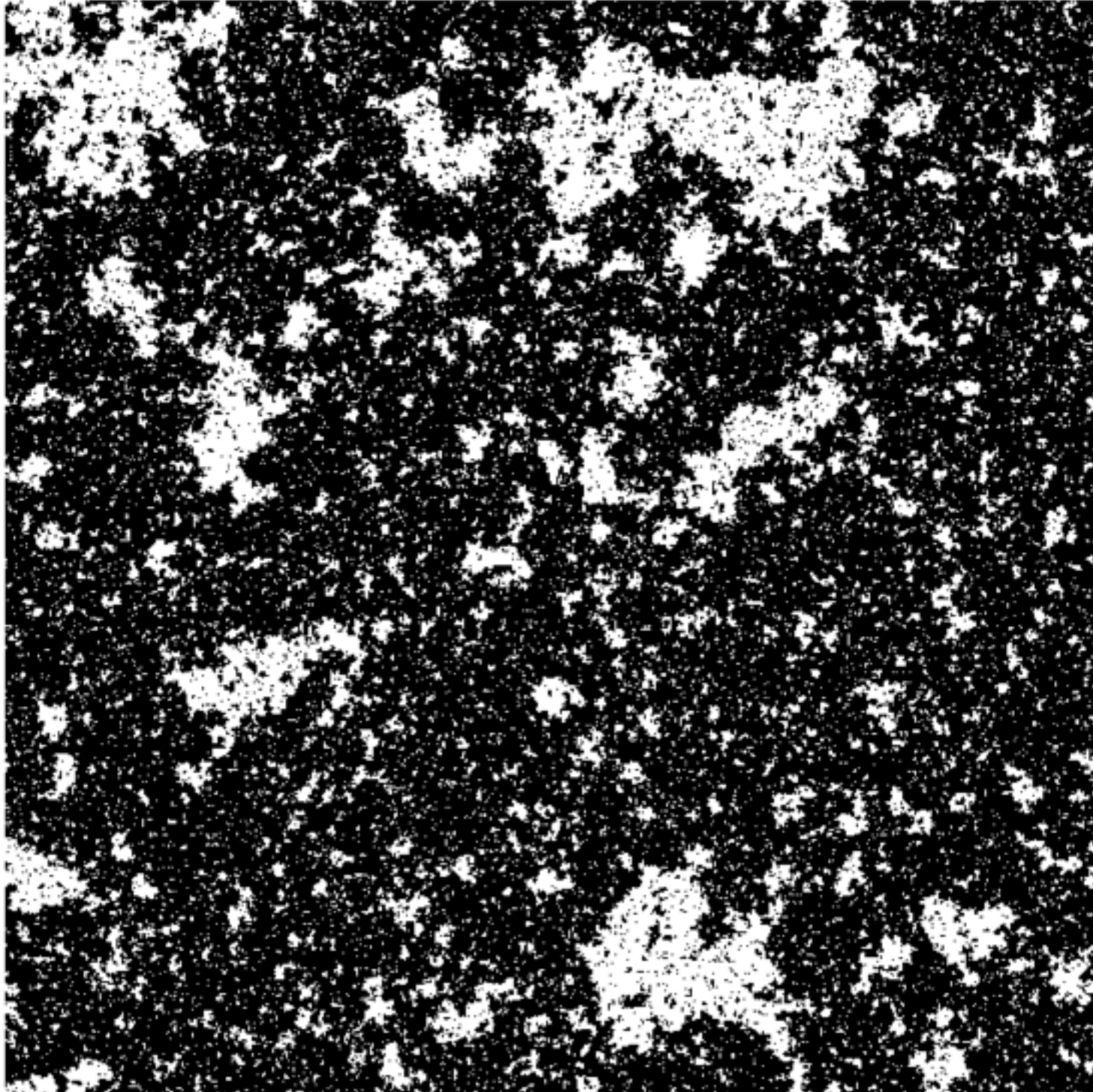


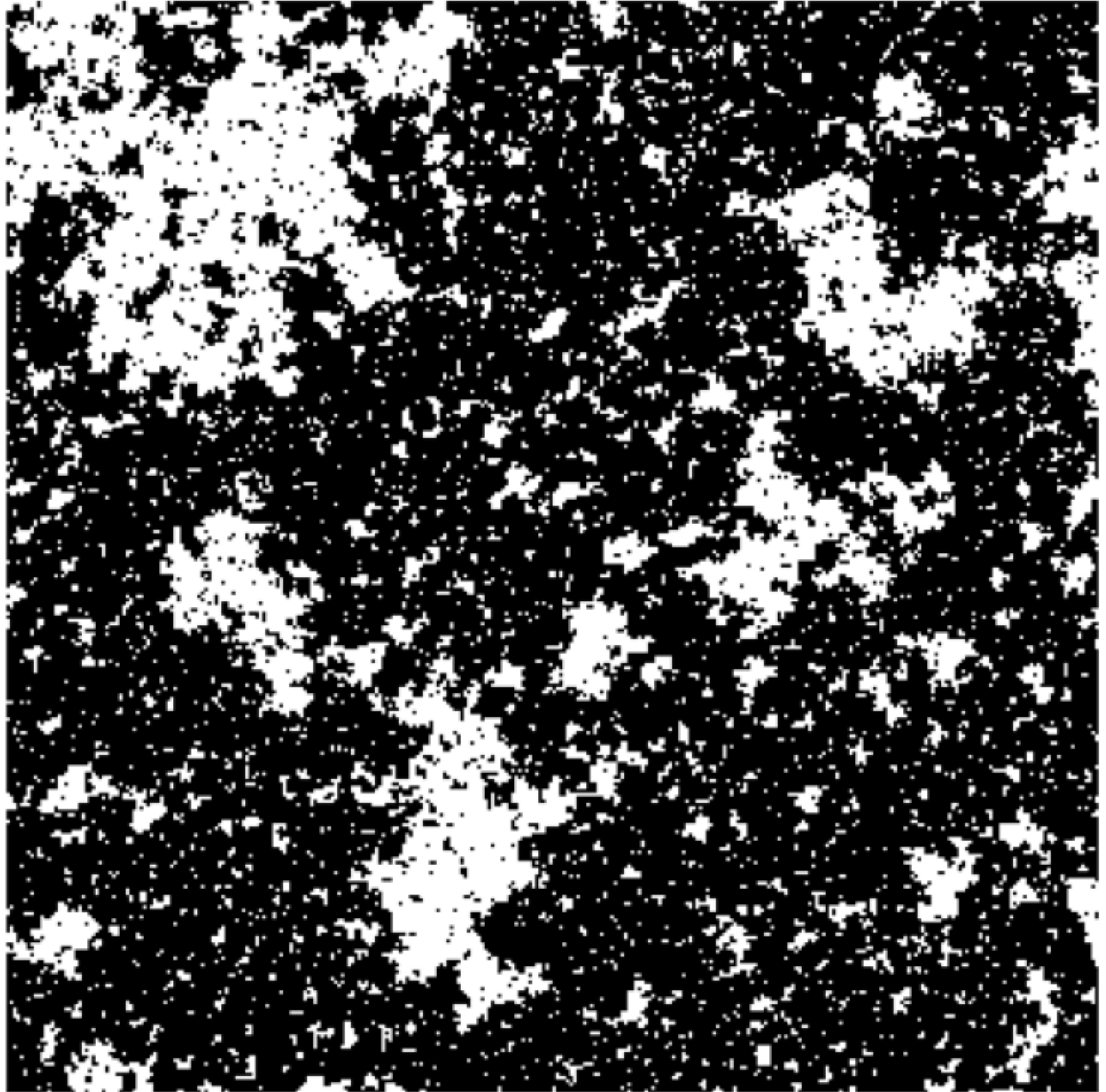
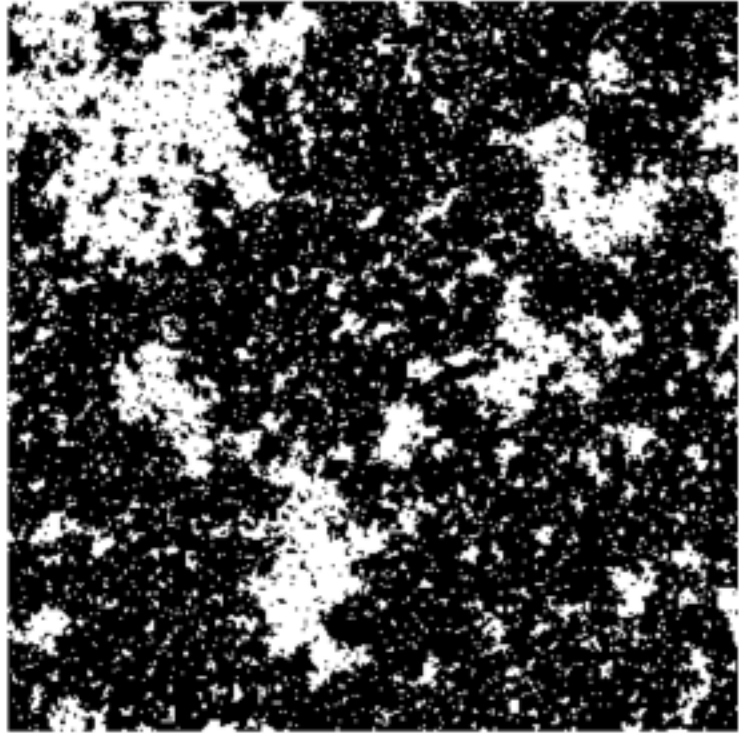
Figure 31.4. Detail of Monte Carlo simulations of rectangular Ising models with $J = 1$. (a) Mean energy and fluctuations in energy as a function of temperature. (b) Fluctuations in energy (standard deviation). (c) Mean square magnetization. (d) Heat capacity.



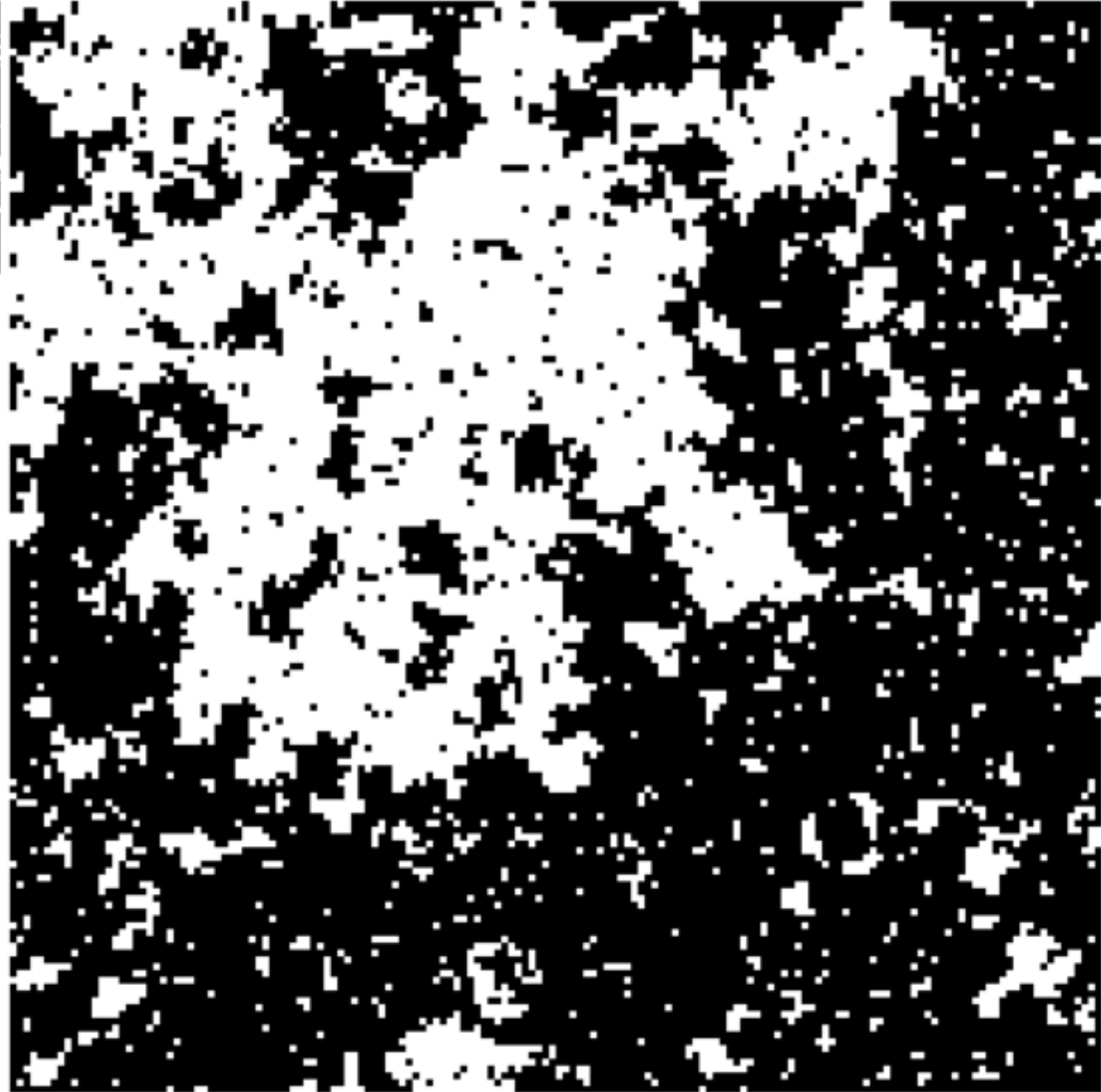
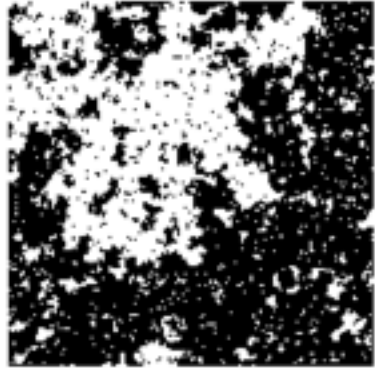
Exact sampling - Ising model at T_c



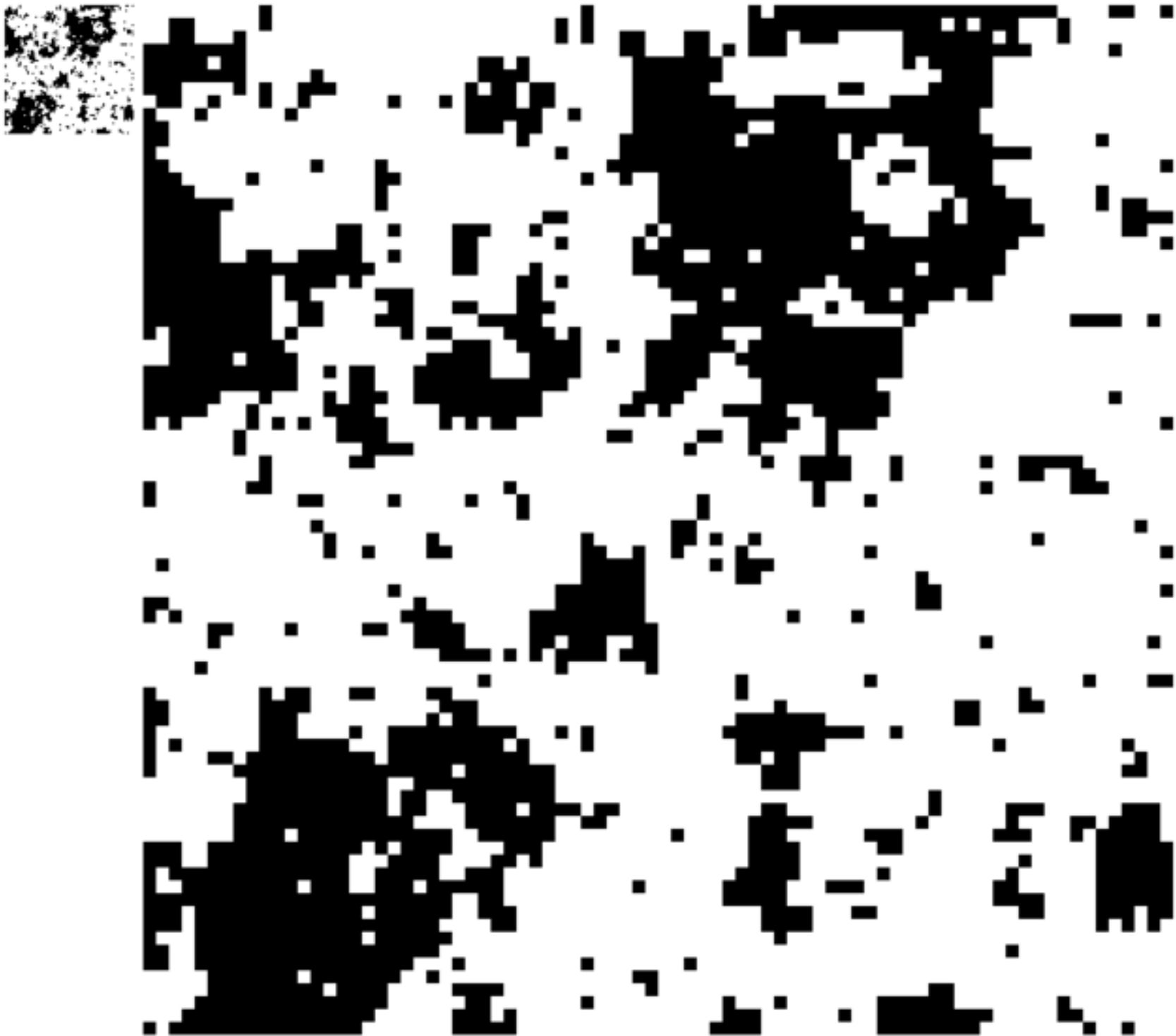
Exact sampling - Ising model at T_c



Exact sampling - Ising model at T_c



Exact sampling - Ising model at T_c



Problems with standard Monte Carlo methods

- Random walk behaviour

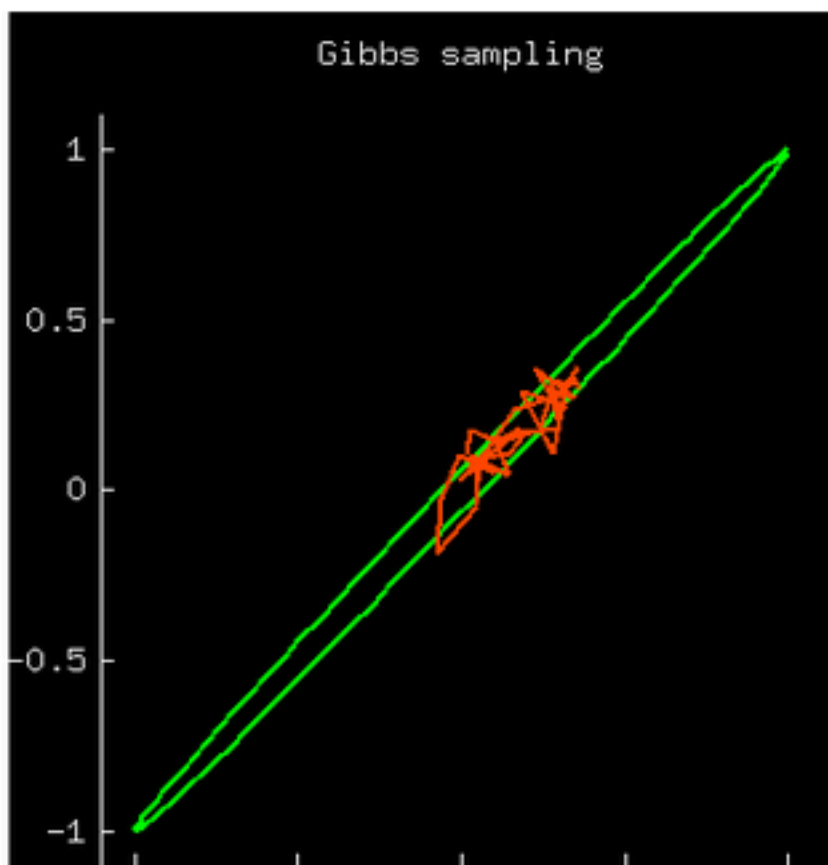
- Sensitivity to step size

- When to stop

Efficient methods

Slice sampling

Exact sampling



- Not revealing the normalizing constant

 - Thermodynamic integration

 - Reversible-jump Markov chain Monte Carlo

 - The acceptance ratio method

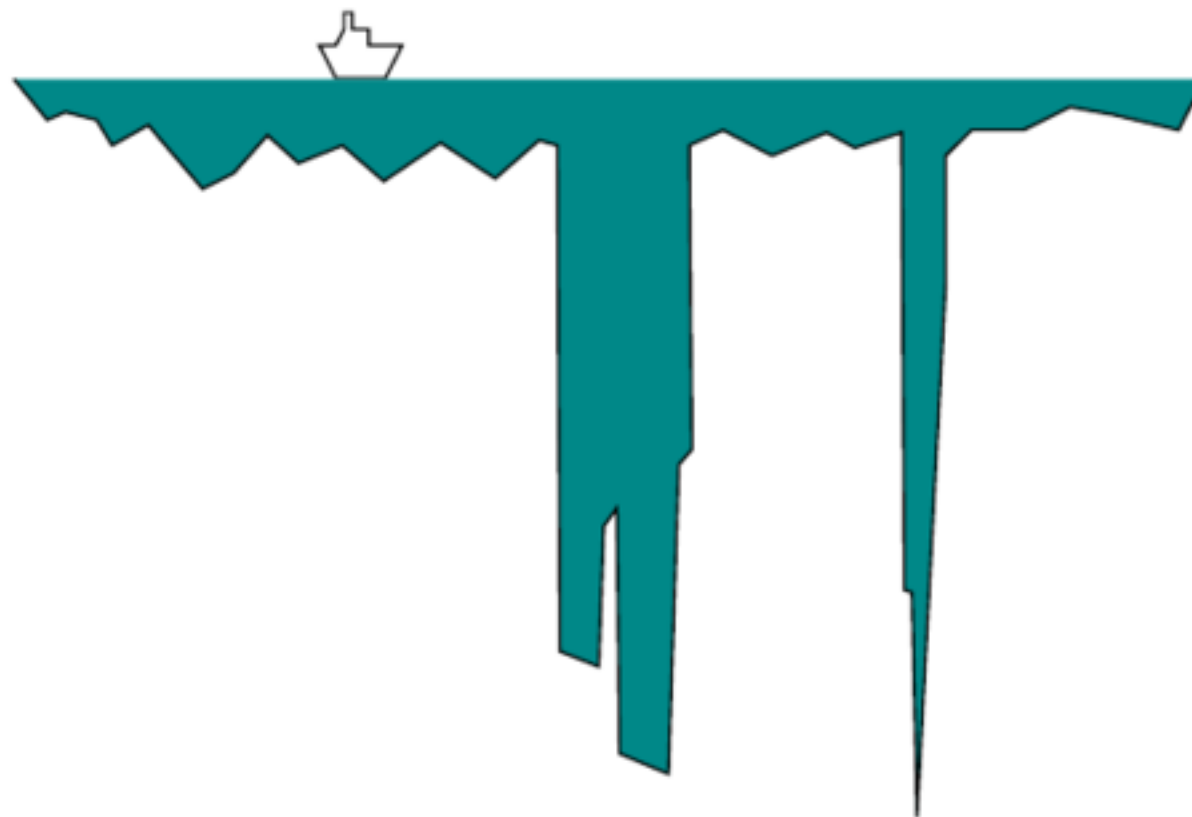
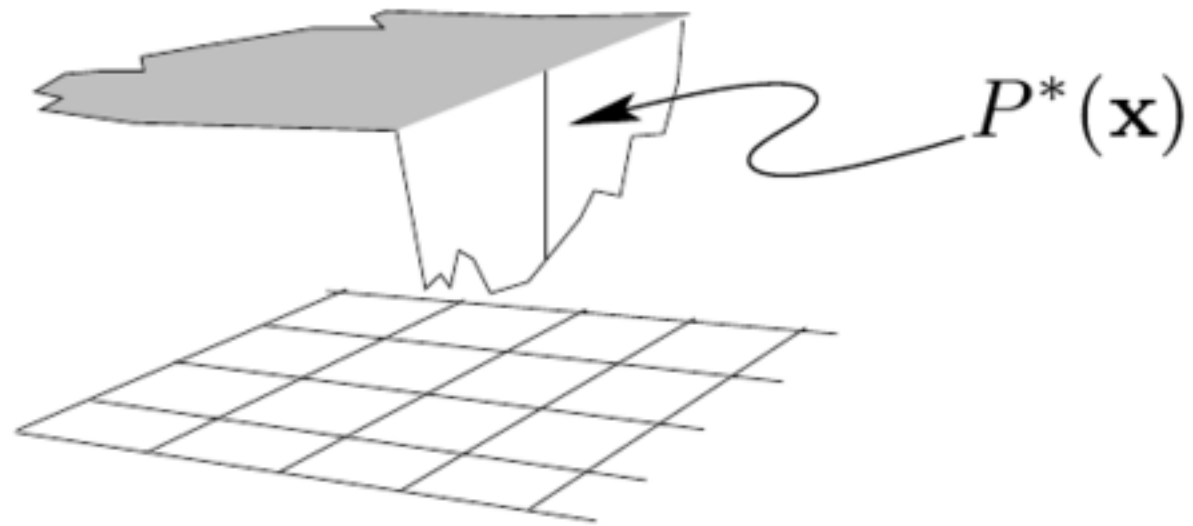
 - Umbrella sampling

 - Simulated tempering

 - Tempered transitions (Radford Neal)

 - Annealed importance sampling (Radford Neal)

 - Linked importance sampling (Radford Neal)



8

and Neal

Skilling

