

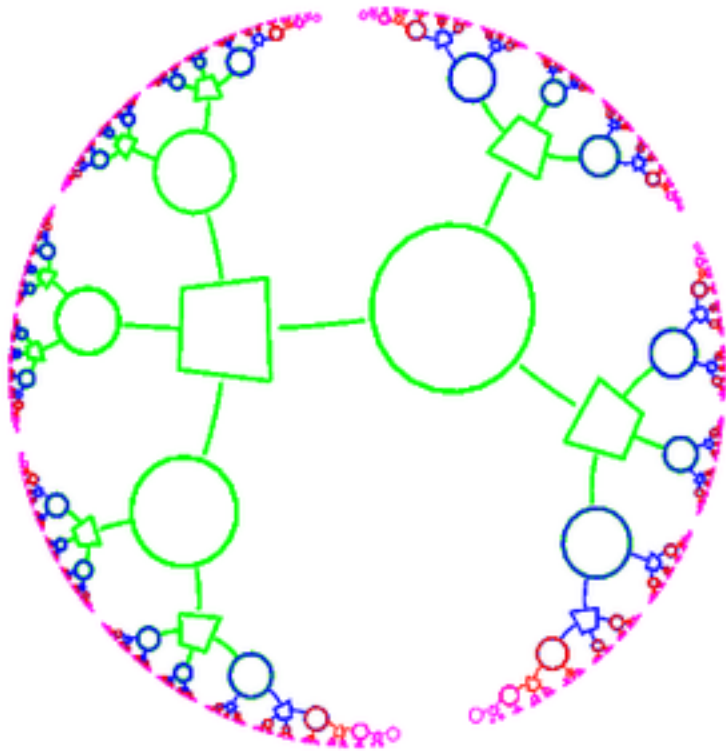
Neural Networks, part II

- Content addressable memories

State-of-the-art

error-correcting codes

Information theory, pattern recognition, and neural networks



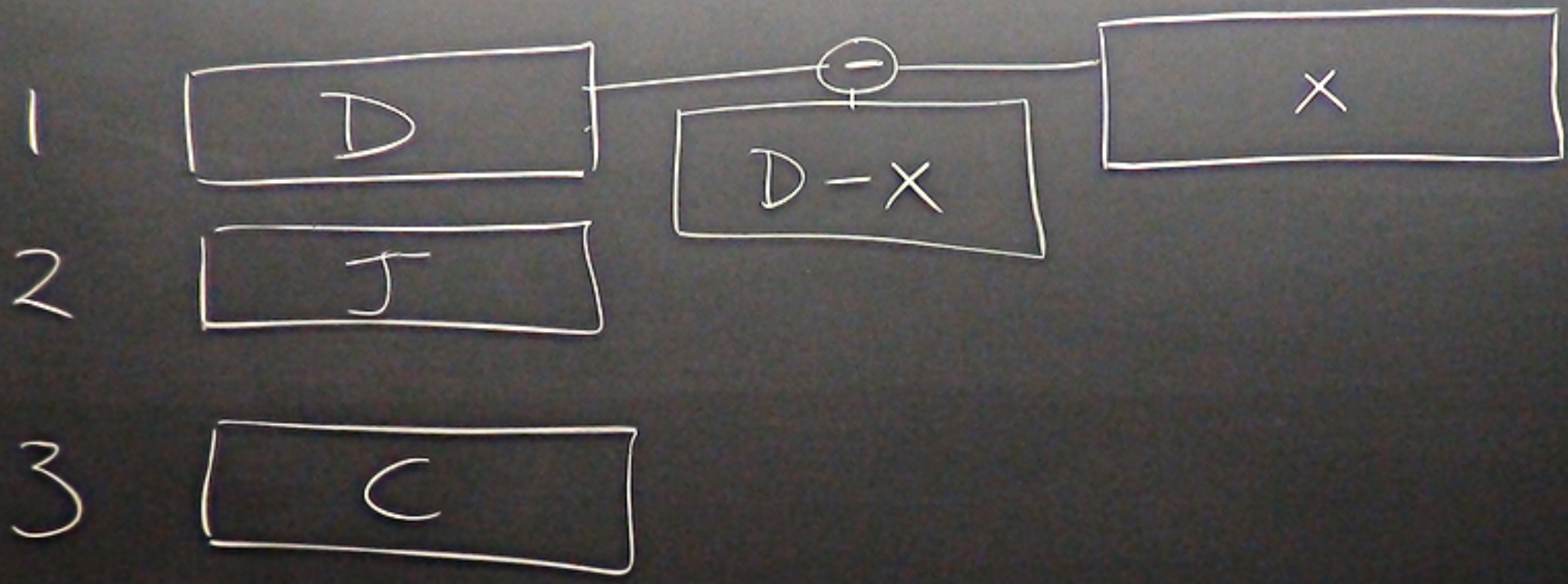
- Source coding (Data compression)
- Noisy-channel coding
- Inference + probabilistic methods
 - 9-10 Inference
 - 11 Clustering
 - 12 Monte Carlo methods
 - 13 Advanced Monte Carlo methods
 - 14 Variational methods
- Neural networks
 - 15 Introduction to feedforward neural networks
 - 16 Content-addressable memories
- State-of-the-art error-correcting codes

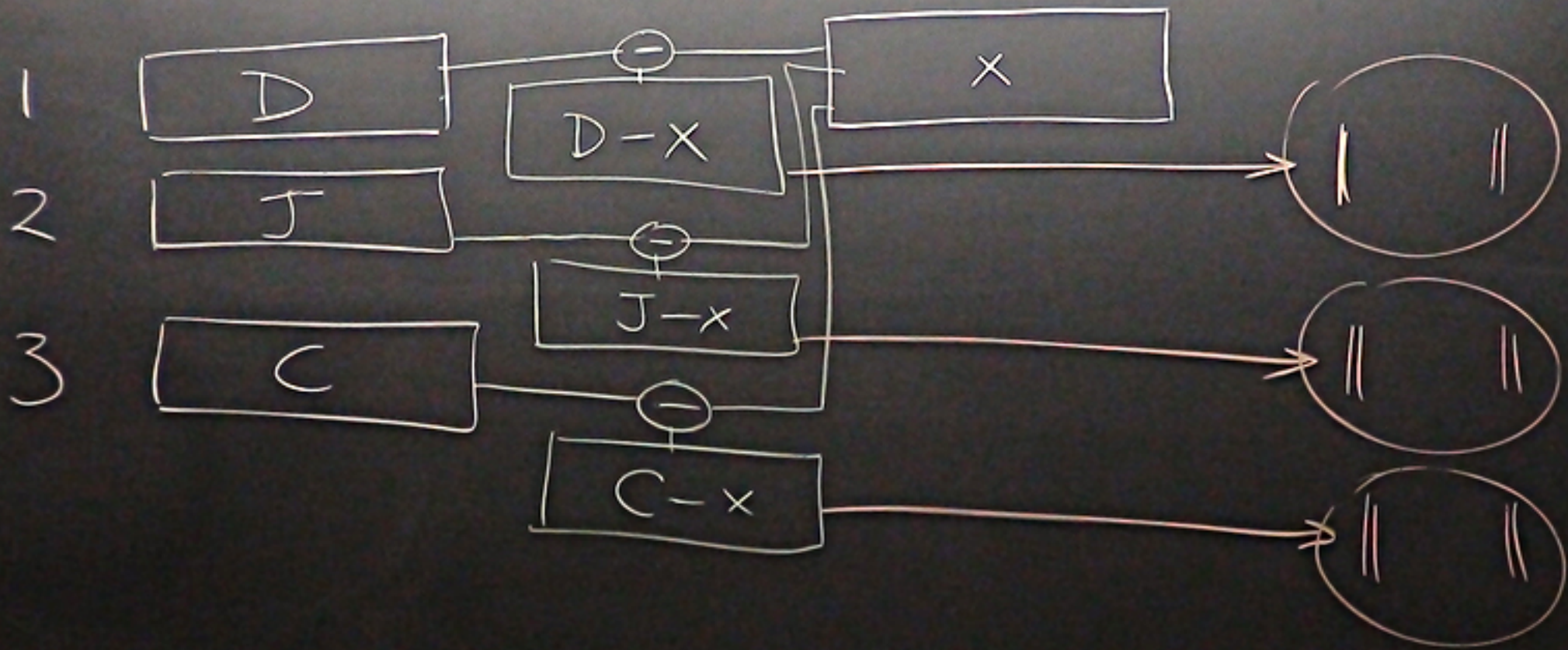
www.inference.phy.cam.ac.uk/itprnn/

www.inference.phy.cam.ac.uk/itila/

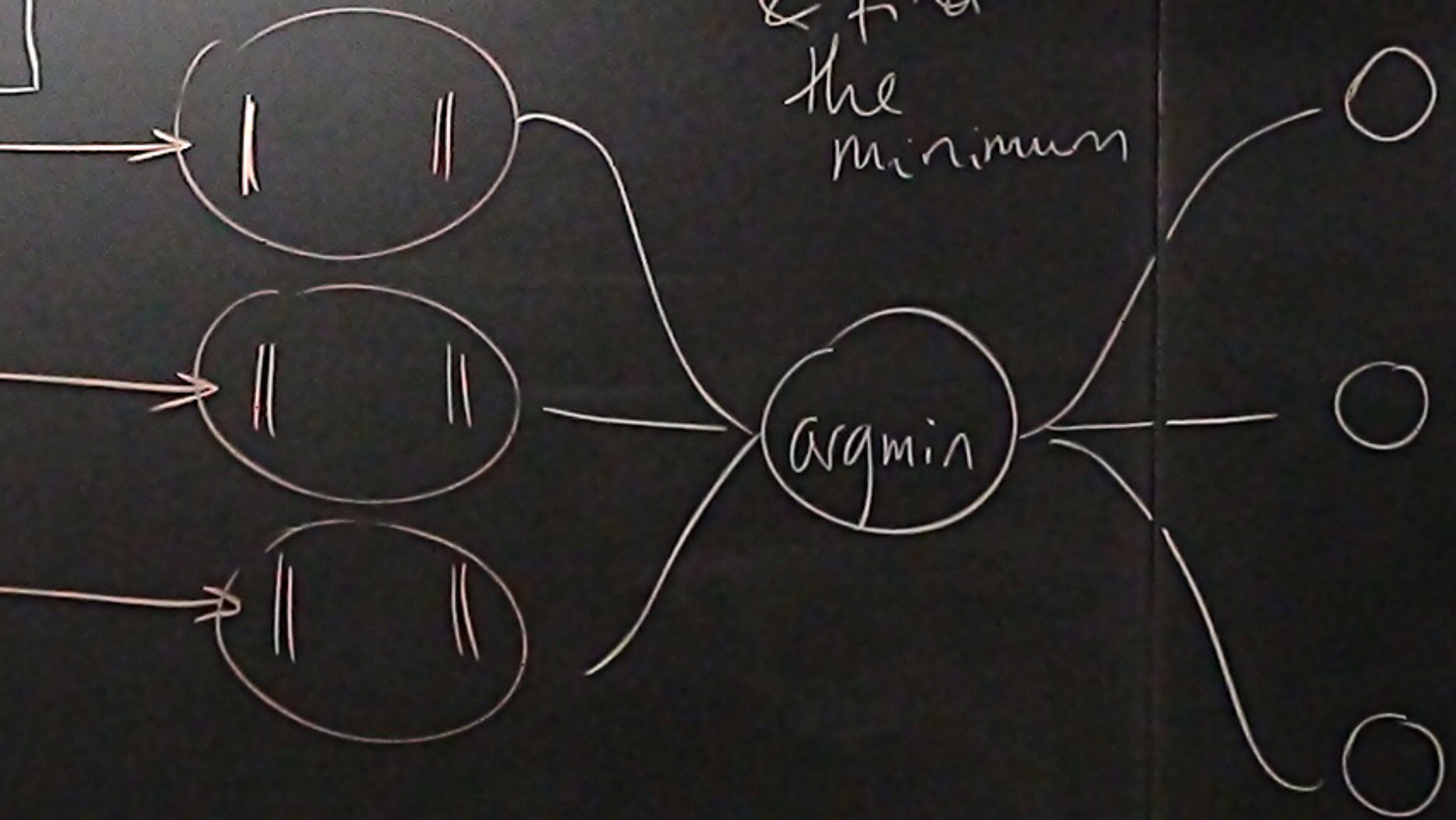
An orthodox approach to content-addressable memory

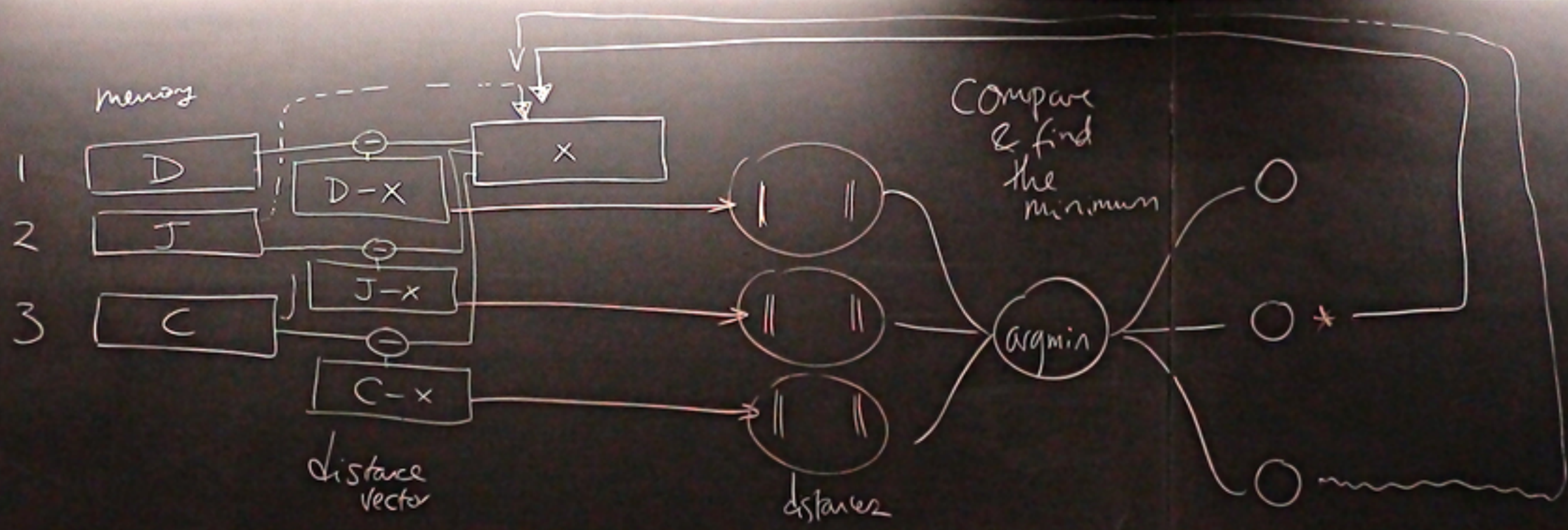
note that this is a brute-force decoder
for the **error-correcting code** whose codewords are the required memories

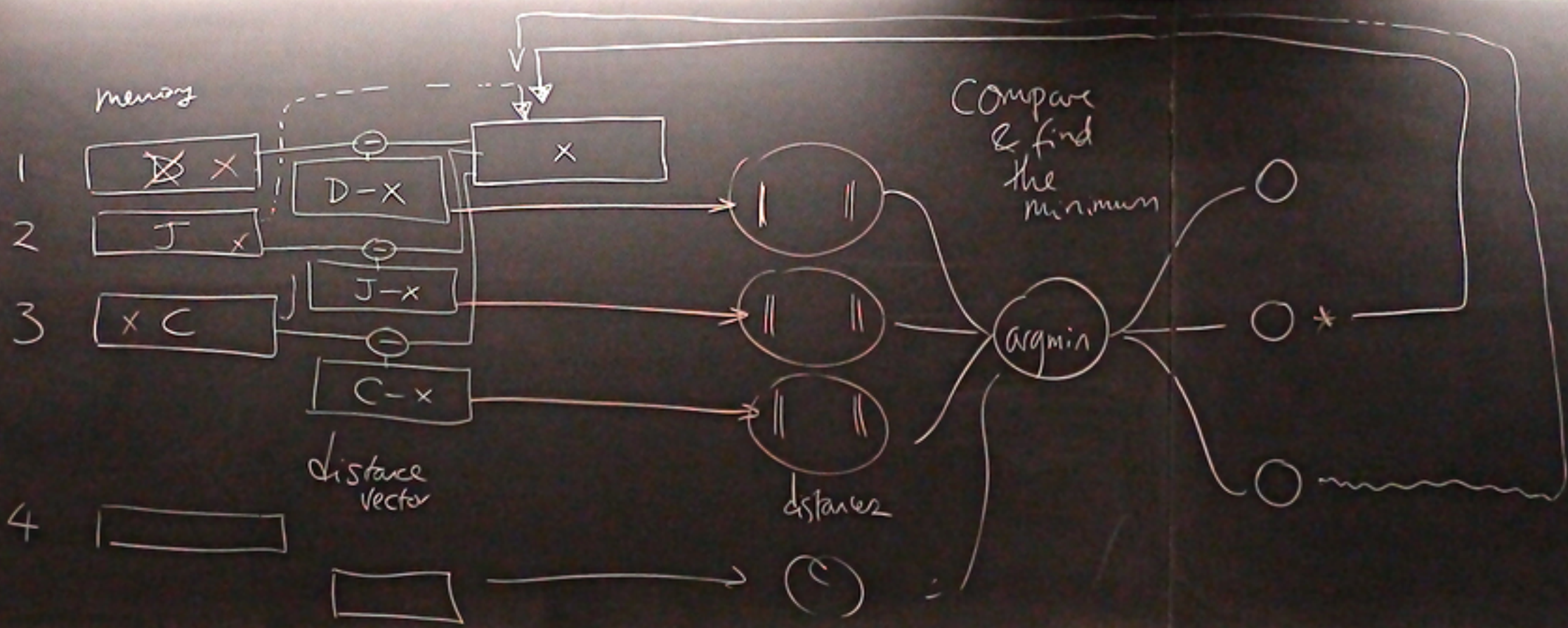




Compare
& find
the
minimum







An orthodox approach to content-addressable memory

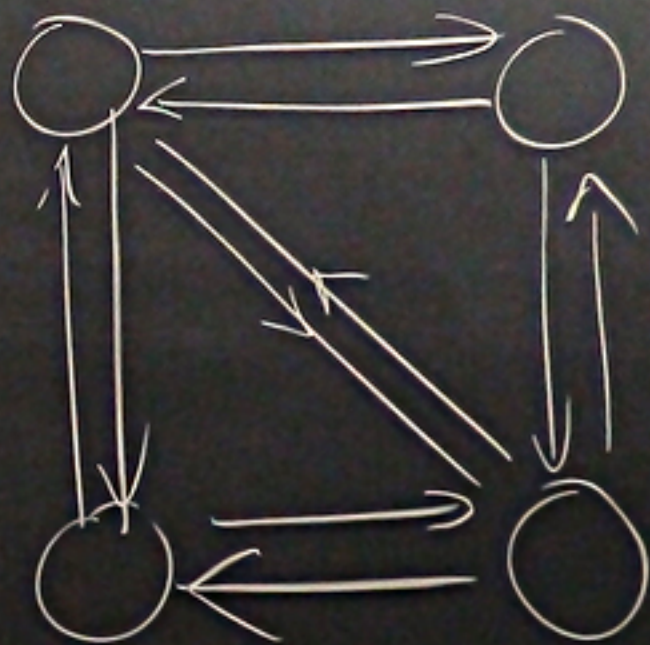
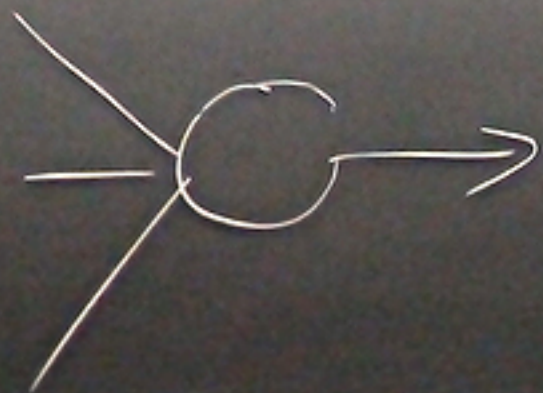
note that this is a brute-force decoder

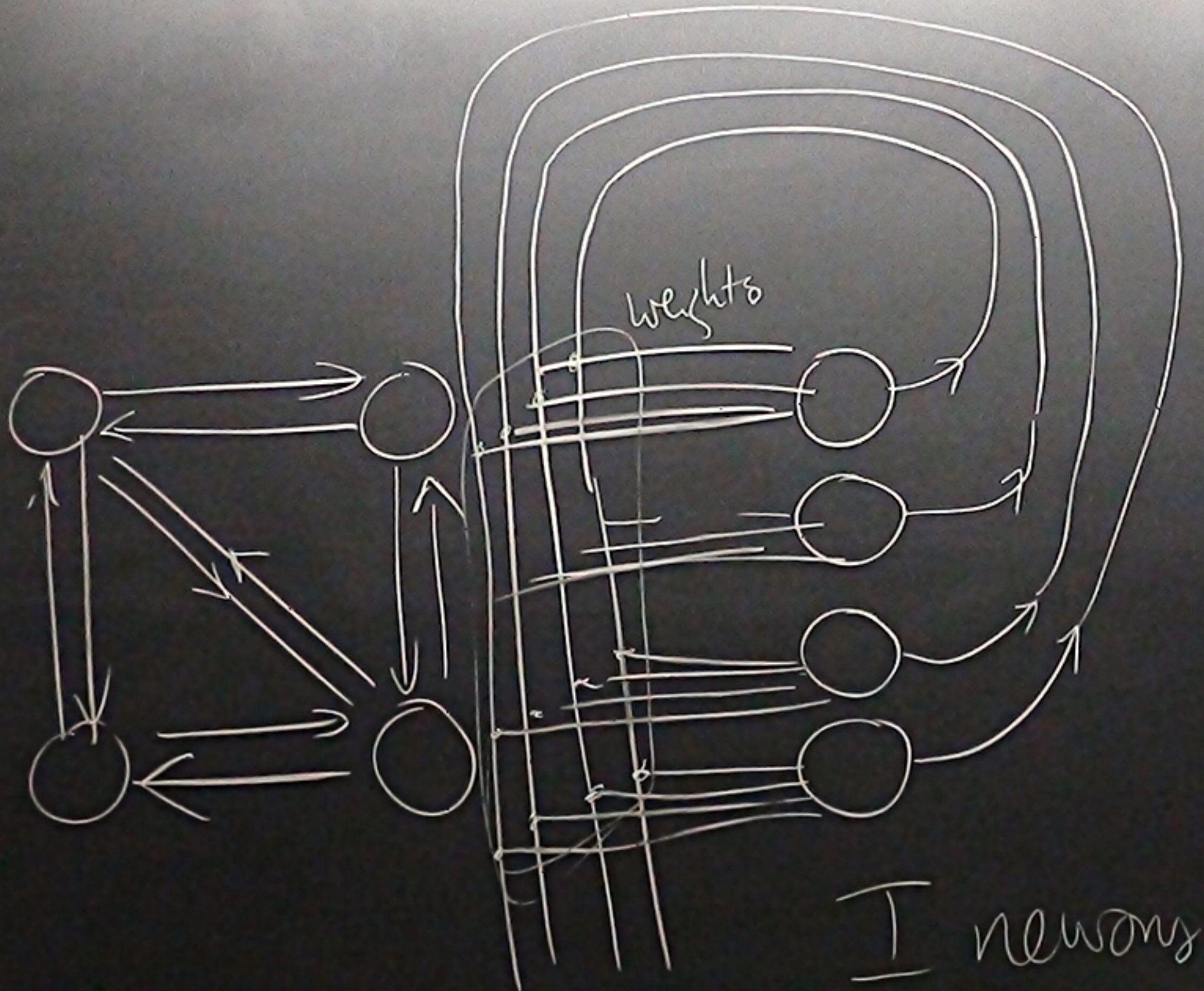
for the **error-correcting code** whose codewords are the required memories

Neural Networks, Part II: Feedback Networks

The Hopfield Network

Chapter 42





The Hopfield network

Architecture

Feedback network

Symmetric weights $w_{ij} = w_{ji}$, $w_{ii} = 0$

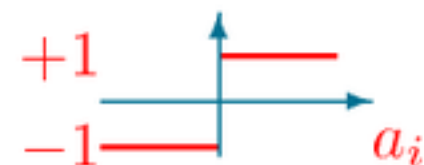
Activity rule

Continuous Hopfield network:

$$a_i = \sum_j w_{ij} x_j + \theta_i$$

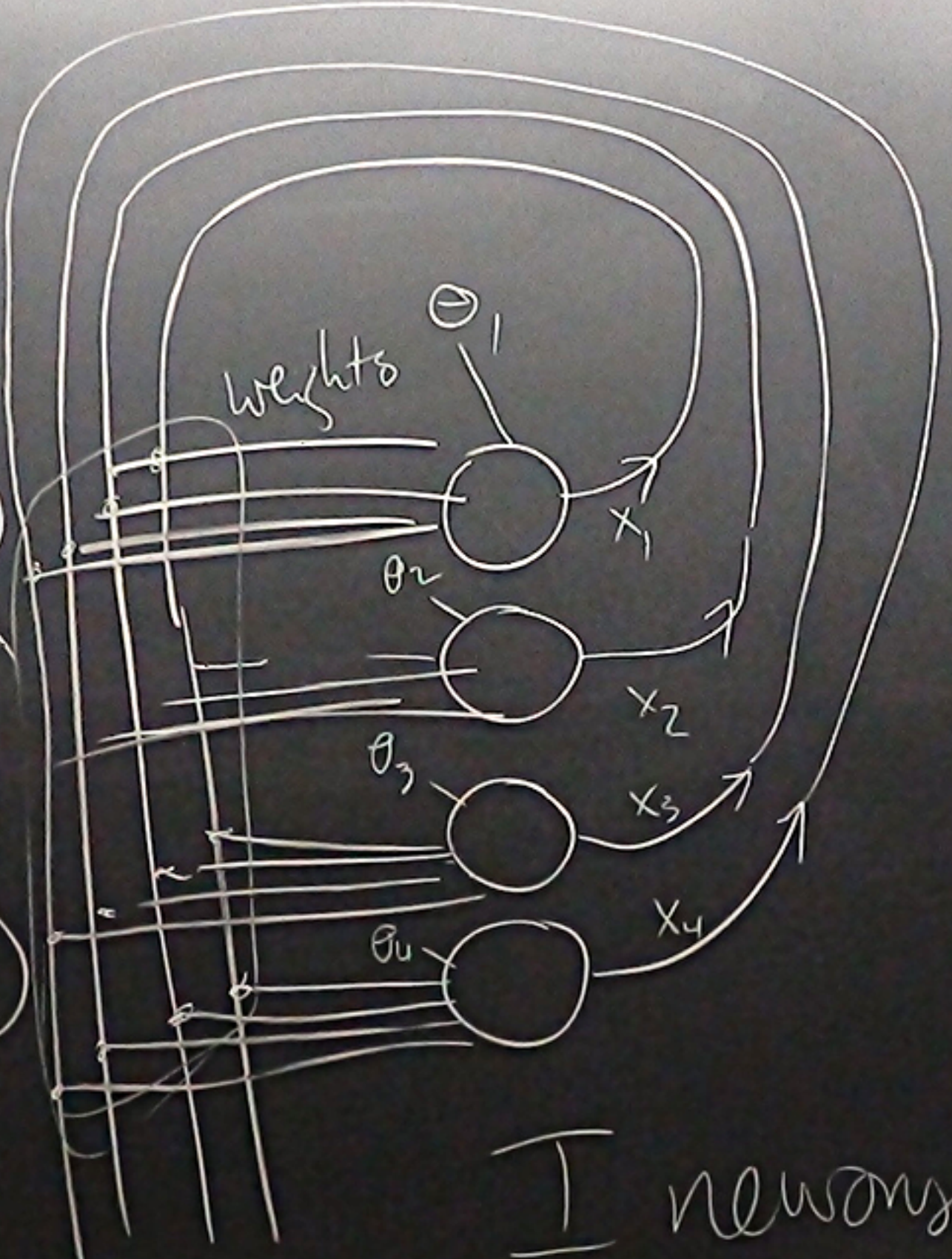
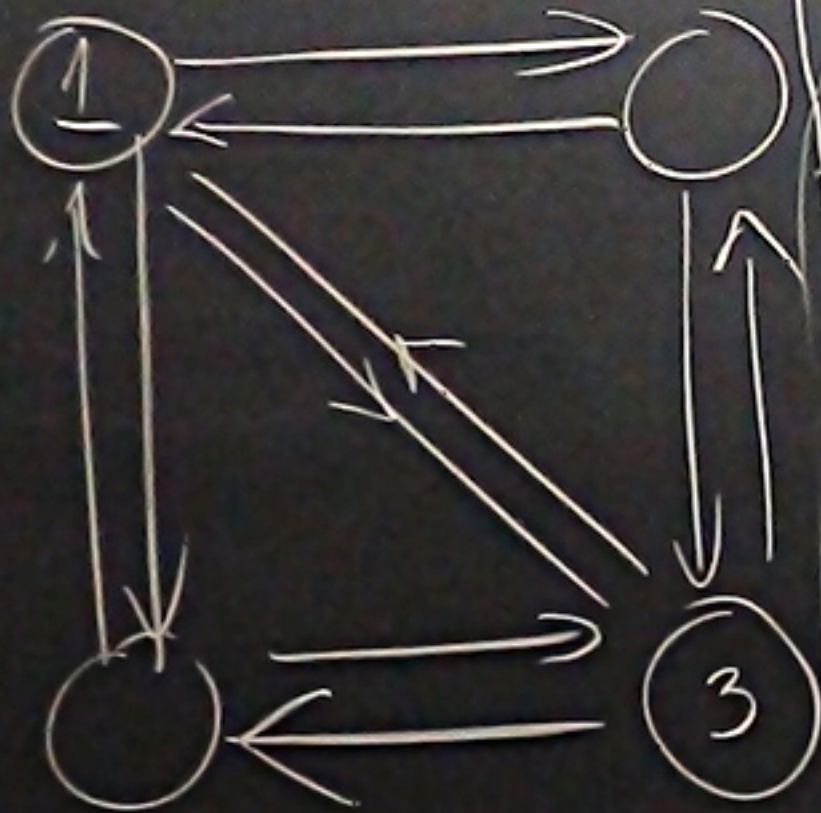
$$x_i = \tanh a_i$$

Binary Hopfield network:

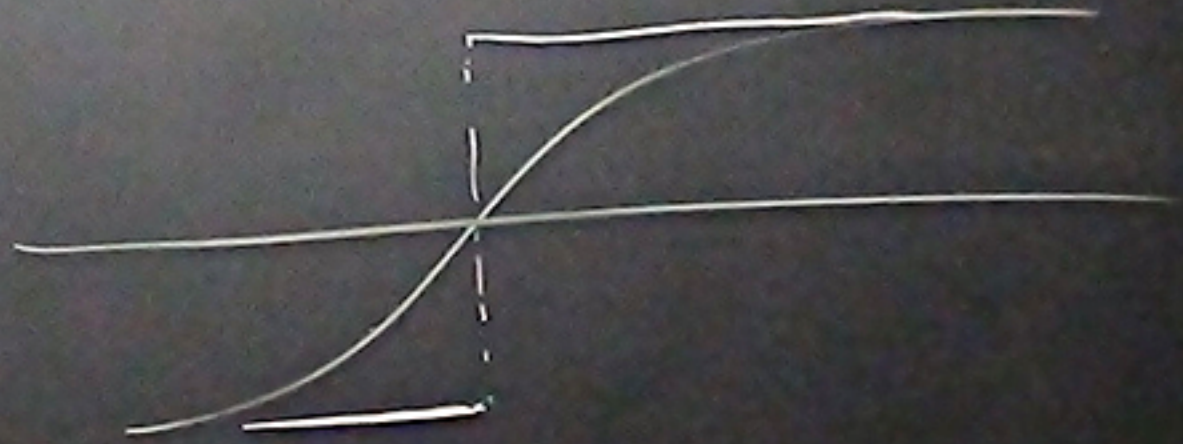
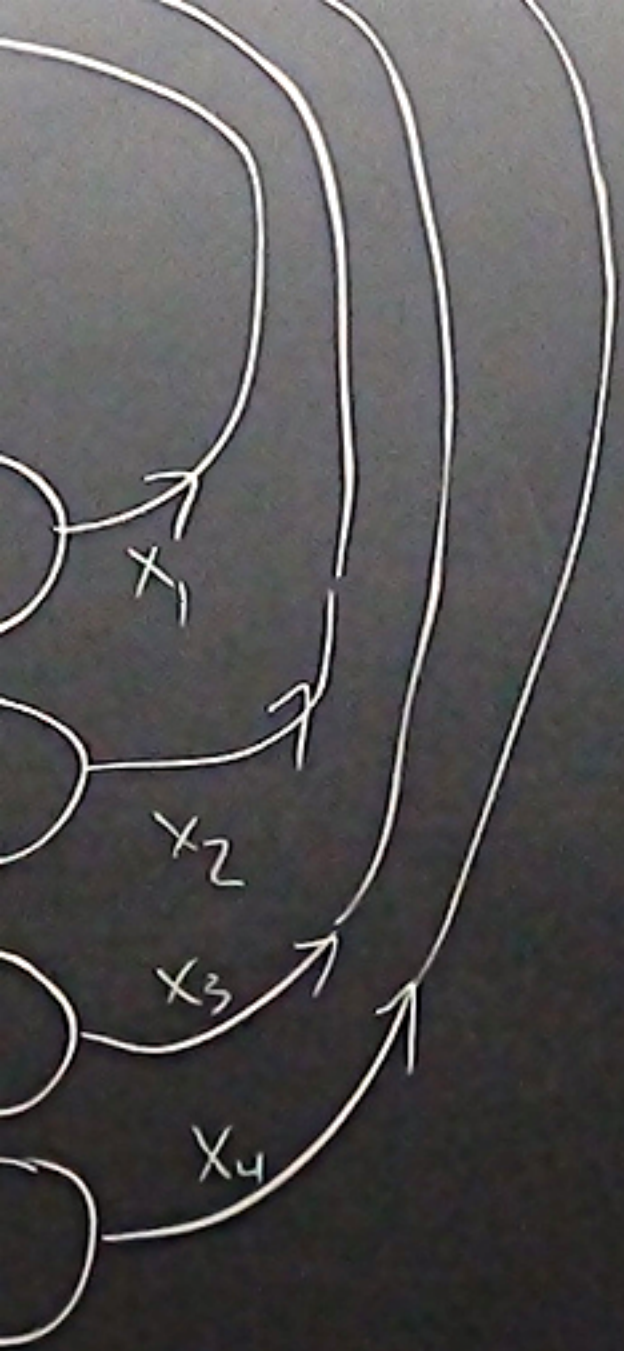
$$x_i = \begin{cases} +1 & \text{if } a_i > 0 \\ -1 & \text{if } a_i < 0 \end{cases}$$


John Hopfield





I neurons



$$I \times I$$

weight matrix

I neurons

weight matrix

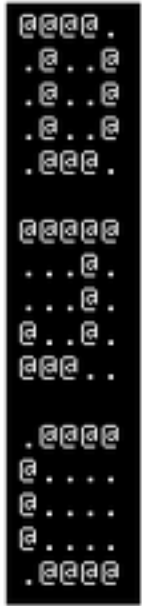
$$\frac{25 \times 24}{2}$$

= # parameters

$$W_{ij} =$$

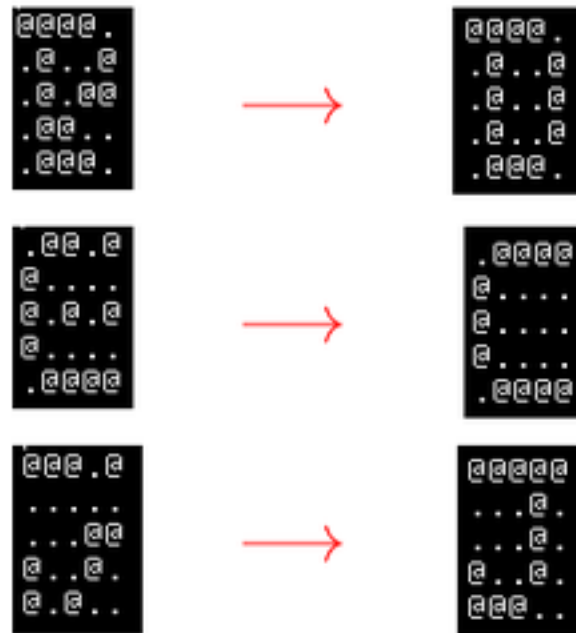
$$I = 25$$

Content-addressable memory challenge



● Make a dynamical system

- 25 dynamical variables, 300 parameters (4-bit precision)
- that has **attracting fixed points** at desired memories
- such that noisy versions are automatically cleaned up



- and such that new memories can be added incrementally
- AND robust to corruption of **more than half the parameters**

Architecture

Feedback network

Symmetric weights $w_{ij} = w_{ji}$, $w_{ii} = 0$

Activity rule

Continuous Hopfield network:

$$a_i = \sum_j w_{ij} x_j + \theta_i$$

$$x_i = \tanh a_i$$

Binary Hopfield network:

$$x_i = \begin{cases} +1 & a_i > 0 \\ -1 & a_i < 0 \end{cases}$$


Learning rule

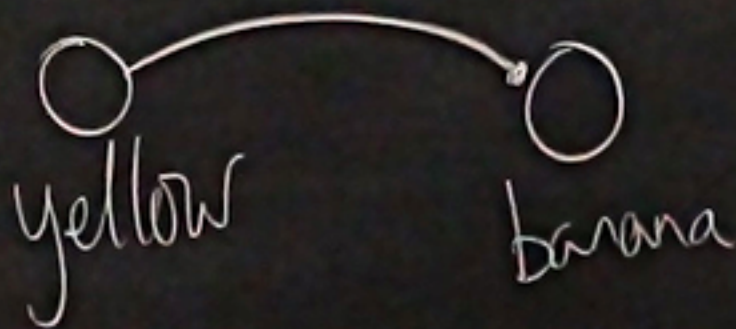
Hebb rule

$$w_{ij} = \sum_{n=1}^N x_i^{(n)} x_j^{(n)}$$

$$W_{ij} = \sum_{n=1}^N x_i^{(n)} x_j^{(n)}$$

patterns to learn $N=3$

$\begin{matrix} \text{d} \\ \text{j} \\ \text{c} \end{matrix}$	
M	$N=4$





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McGurk effect

From Wikipedia, the free encyclopedia

The **McGurk effect** is a perceptual phenomenon that demonstrates an interaction between visual and auditory perception. The illusion occurs when the auditory component of one sound is paired with the visual component of another sound, leading to the perception of a third sound.^[1] The visual information from a speaker changes the way they hear the sound.^[2] People who are used to watching dubbed movies are not susceptible to the McGurk effect because they have, to some extent, learned to ignore the visual information from the mouths of the "speakers".^[3] If a person is getting poor quality auditory information, they may be more likely to experience the McGurk effect.^[4] Integating visual information may also influence whether a person will experience the effect. People with hearing impairment have been shown to be more susceptible to the effect.^[2] Many people are affected due to factors based on many factors, brain damages or disorders.

Contents [hide]
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2 Brain influences
3 Factors
4 Other languages
5 Hearing impairment
6 Infants
7 See also
8 Bibliography

Hebbian learning

Desired memories

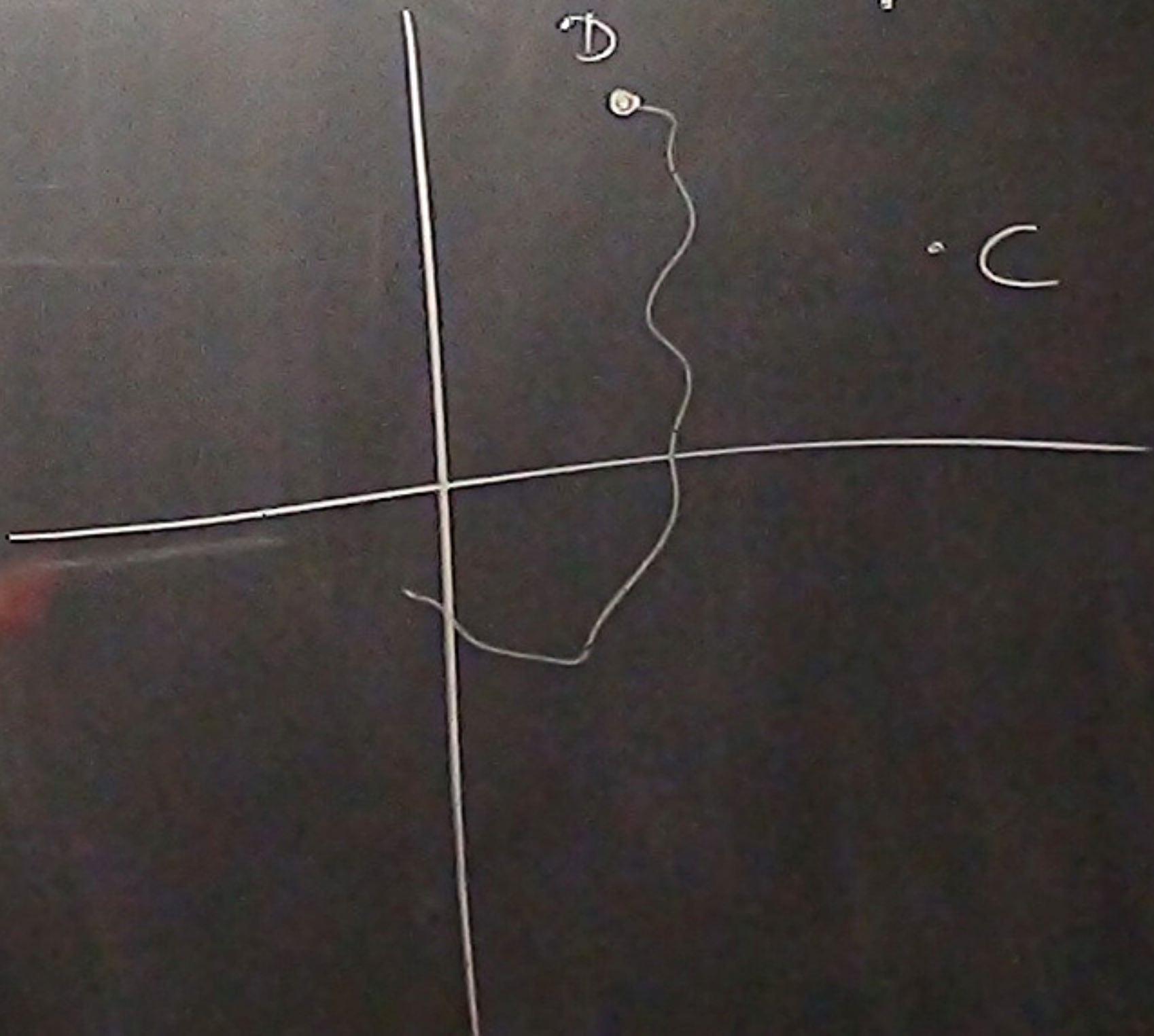
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Weights

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w:  
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-3-1-1-1 1 .-1 1-1-1 3-1 1-1-1 1-1 1-1-1-1-1-1 1 3  
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-3-1-1-1 1 3-1 1-1-1 3-1 1-1-1 1-1 1-1-1-1-1-1 1 .
```

ANU





H.

C.

No noise



AHU

No noise

4%
noise

10%
noise

13%

AMU

✓

✓

✓

✓

✓

✓

✓

✓

AND

No noise

4%
noise

10%
noise

13%

18%

20%

24%

29%

50%

✓
✓
✓

✓
✓
✓

✓

✓

✓
✓
✓

✓

✓
✓
✓
✓

x
x
x

$$Q = \sqrt{\quad}$$

No noise

4%
noise

10%
noise

13%

18%

20%

24%

29%

33%

50%

AMU

✓
✓
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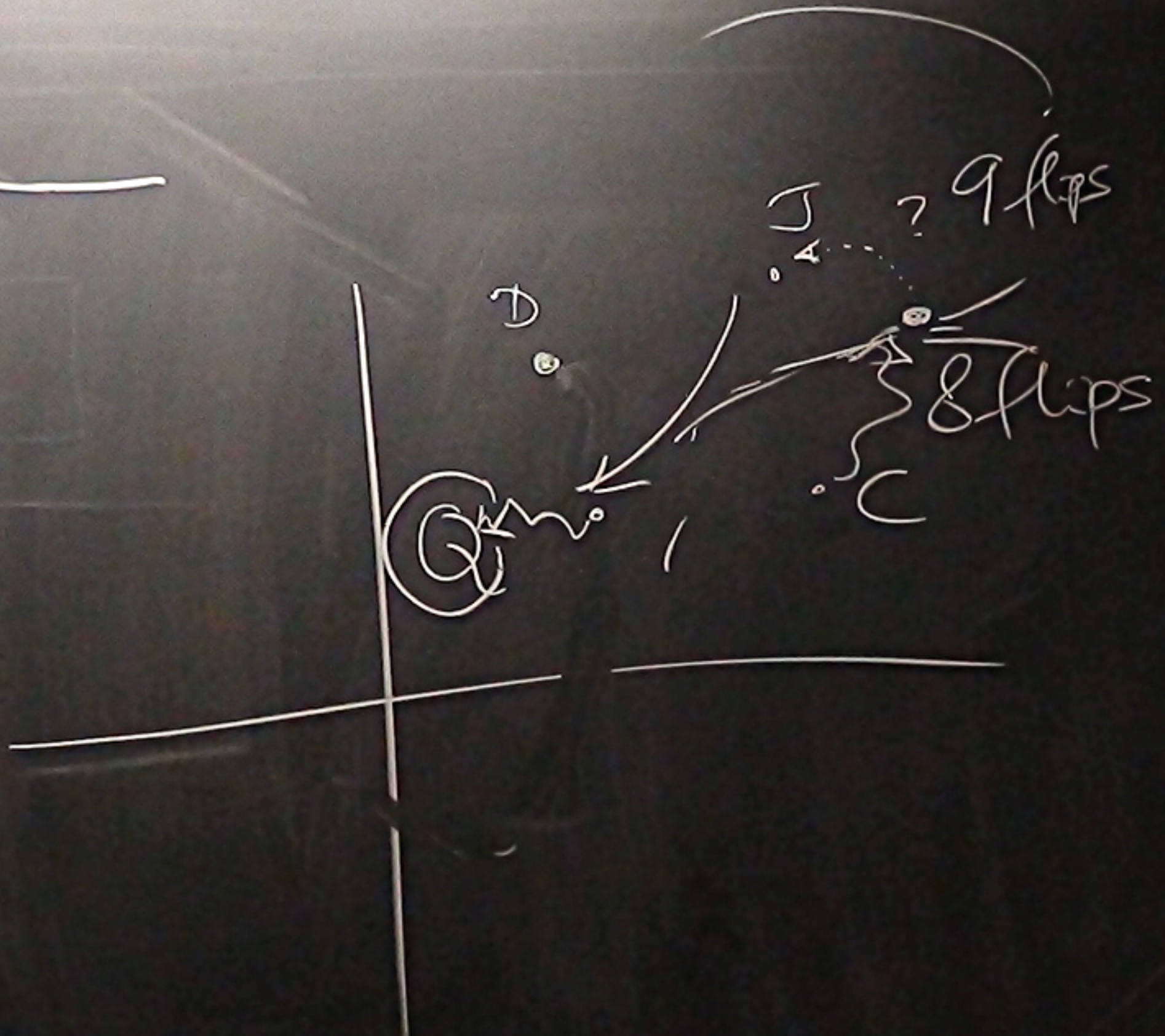
✓
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x

x
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✓

x
x
x

5%

X
X
X



50%

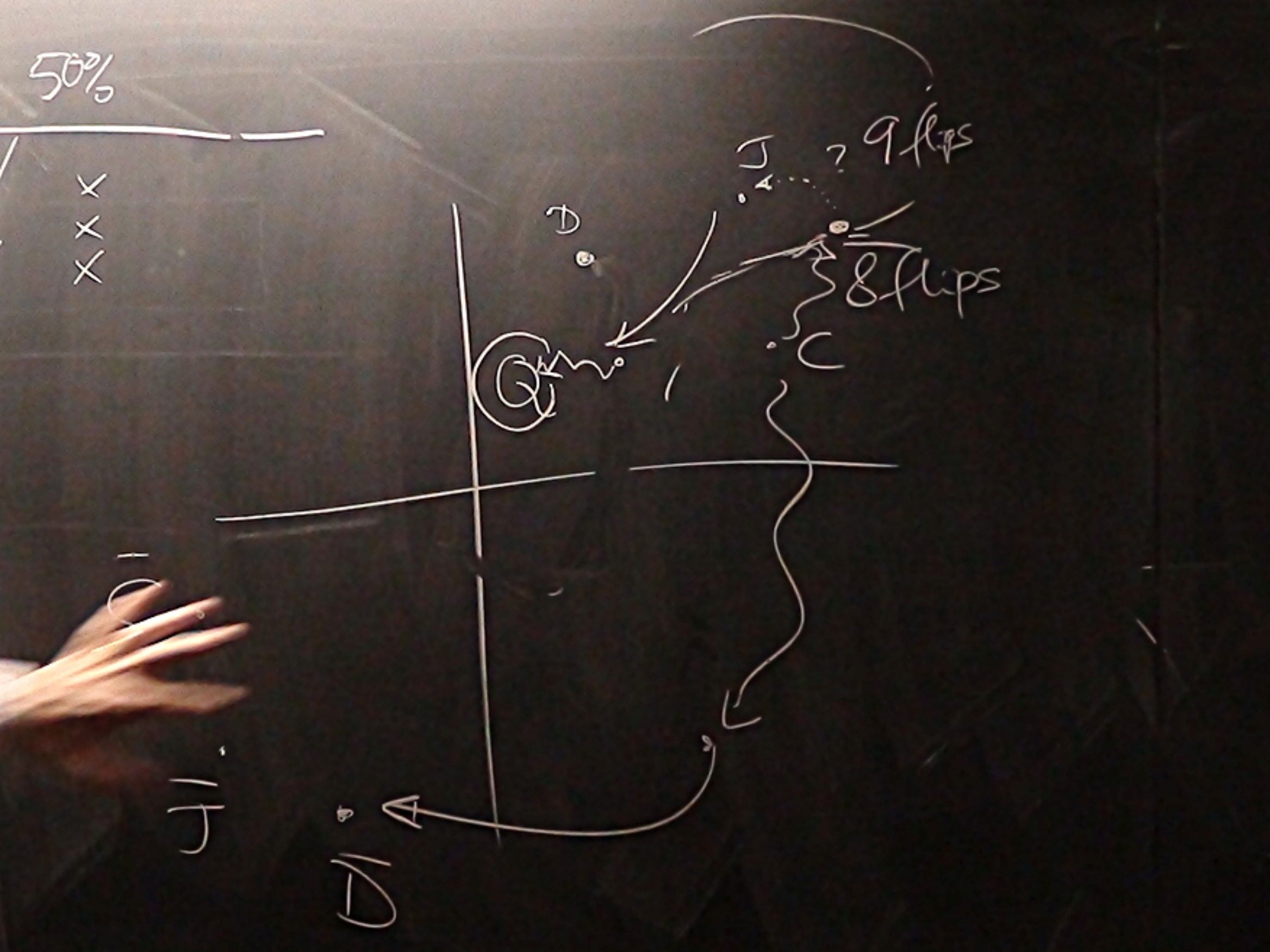
X
X
X

9 flips

8 flips

11

10



$$W_{ij} =$$

N



$X_i^{(n)}$ $X_j^{(n)}$

\swarrow # patterns



27% 24% 29% 33% 50%

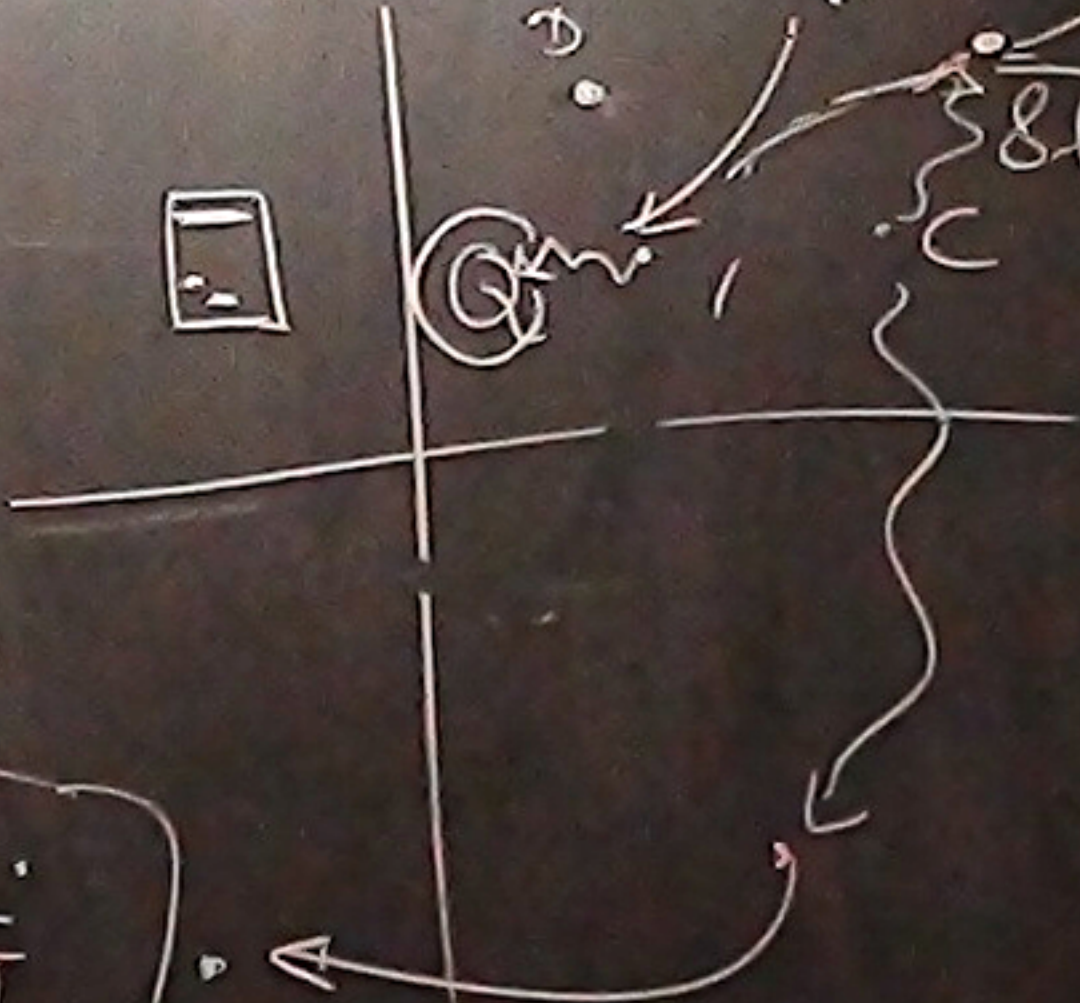
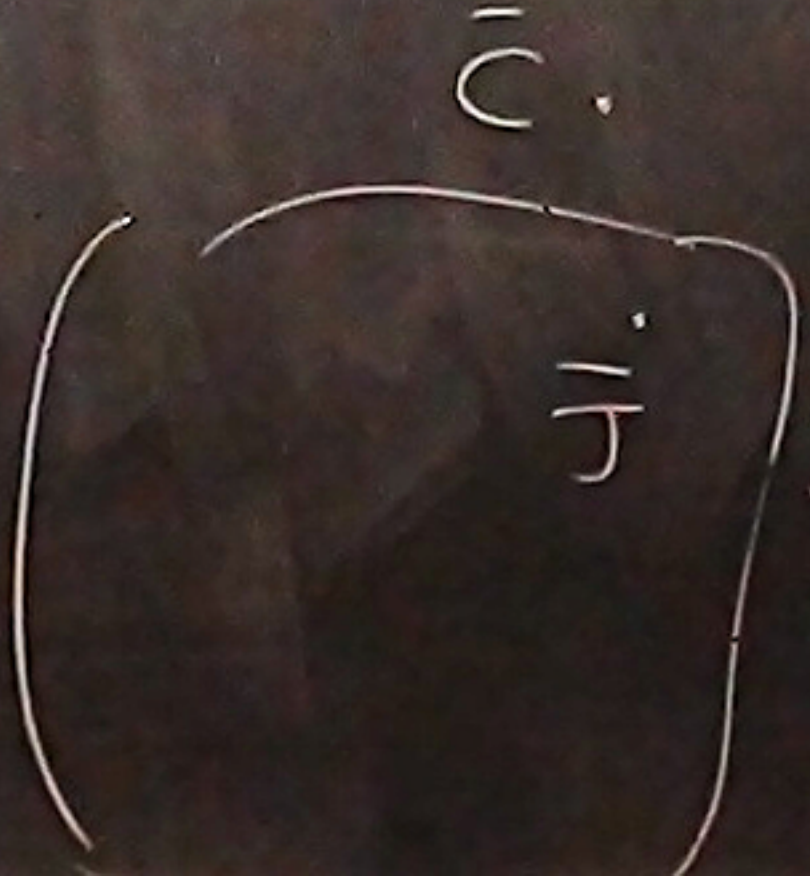
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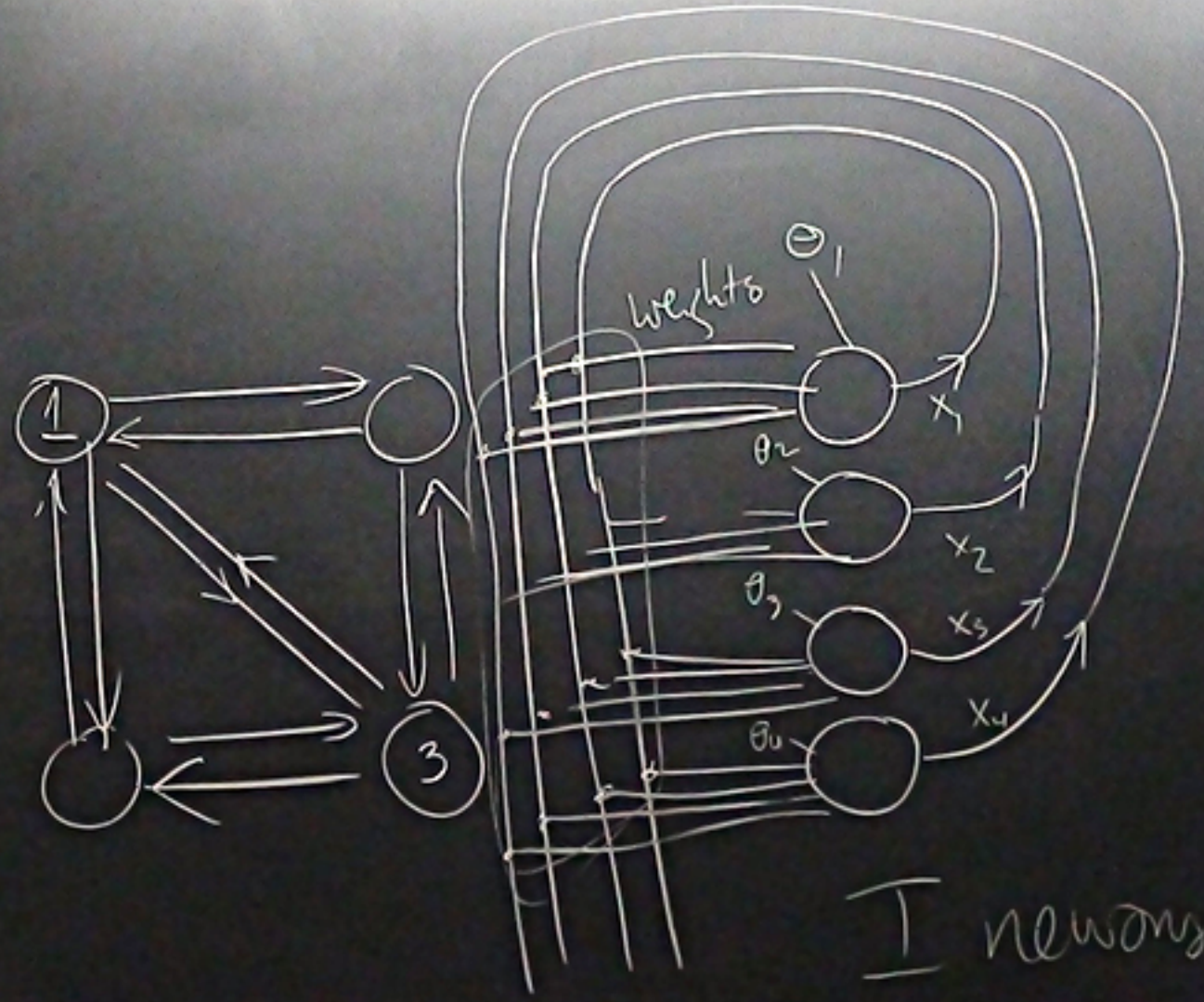
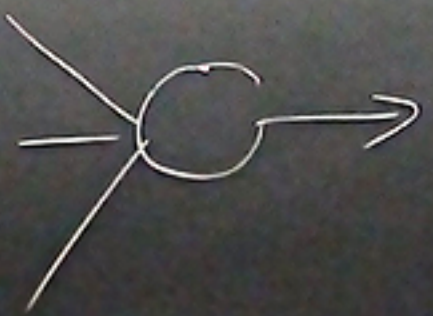
9 flps
8 flps

11.
10.

AND

No noise 4% noise 10% noise 13% 18% 20% 24% 29% 33% 50%

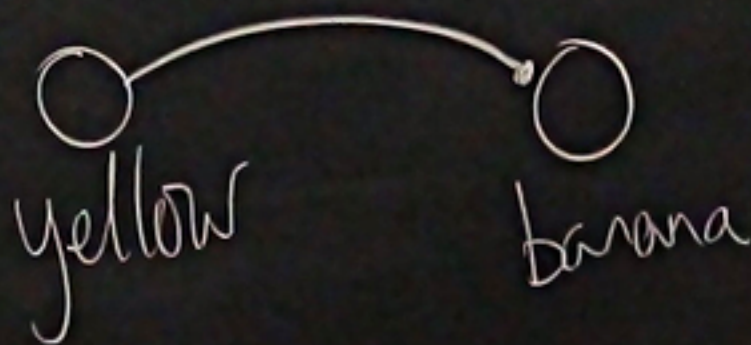
✓	✓	✓		✓		✓		✓	✓	✓
✓	✓		✓	✓	✓	✓		✓	✓	✓
✓	✓			✓		✓	✓	×	✓	×

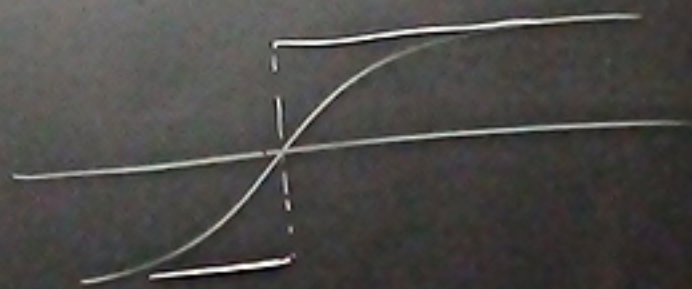


$$W_{ij} = \sum_{n=1}^N x_i^{(n)} x_j^{(n)}$$

patterns to learn $N=3$

d	
j	
c	
M	$N=4$





$I \times I$ weight matrix

$$I = 25$$

$$\frac{25 \times 24}{2}$$

= # parameters

No noise

4%
noise

10%
noise

13%

18%

AND

✓
✓
✓

✓
✓
✓

✓

✓

✓
✓
✓

Corrupt
weights

No noise

4% noise

10% noise

13%

18%

27%

A
S
U

✓
✓
✓

✓
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Corrupt weights 79/300

D
J
C

✓

✓
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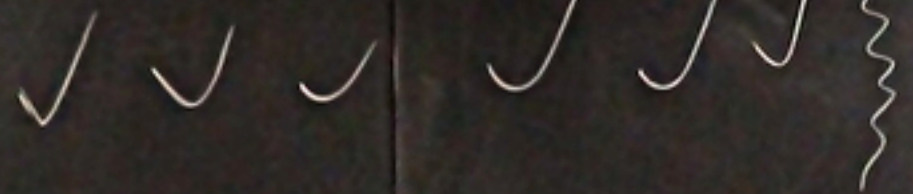
0%

15%

29%

Noise

AHV



AHV
M

N=4

N=5

N=6

No noise

4% noise

10% noise

13%

18%

20%

24%

29%

33%

50%

D
J
C

✓
✓
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x

x
x
x

Corrupt weights
79/300

D
J
C
A
N
U

✓

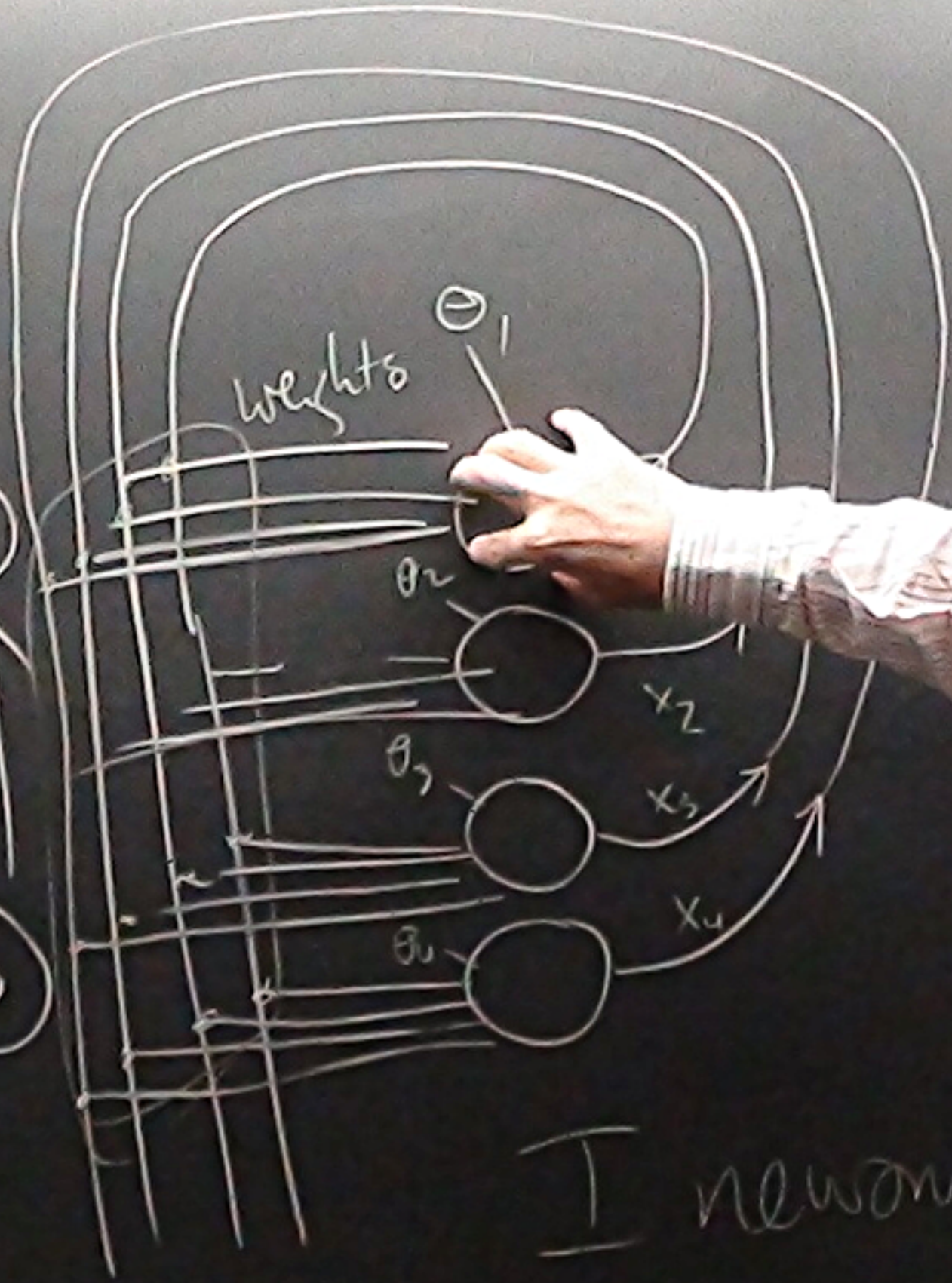
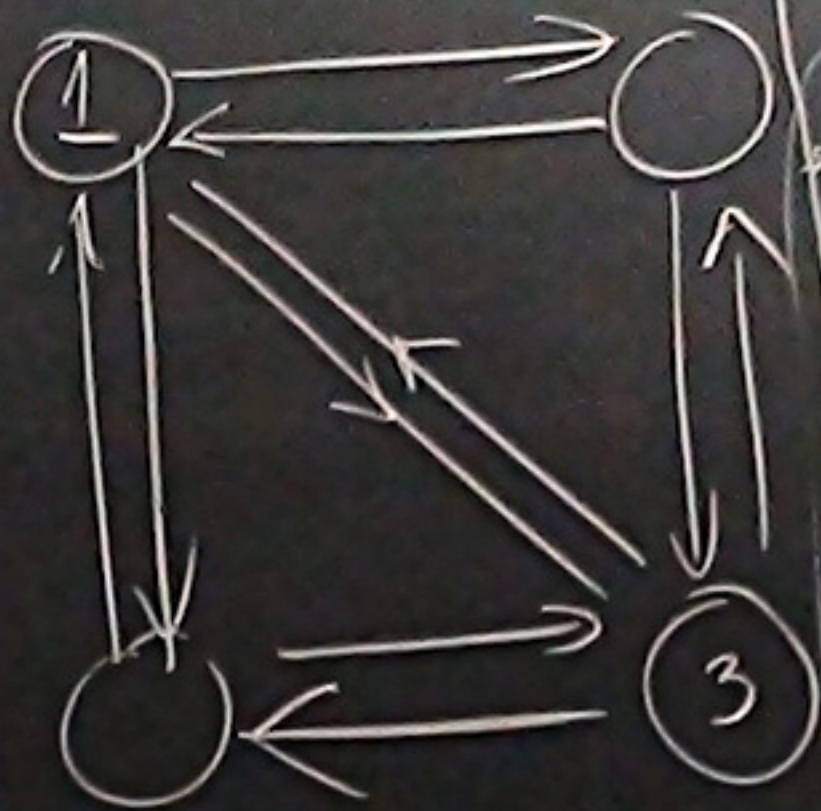
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✓
✓

158/300

237/300

A
B
U

✓
x
x
x



I newtons

0% 5% 8% 15% 17% 27%

Noise

AHV

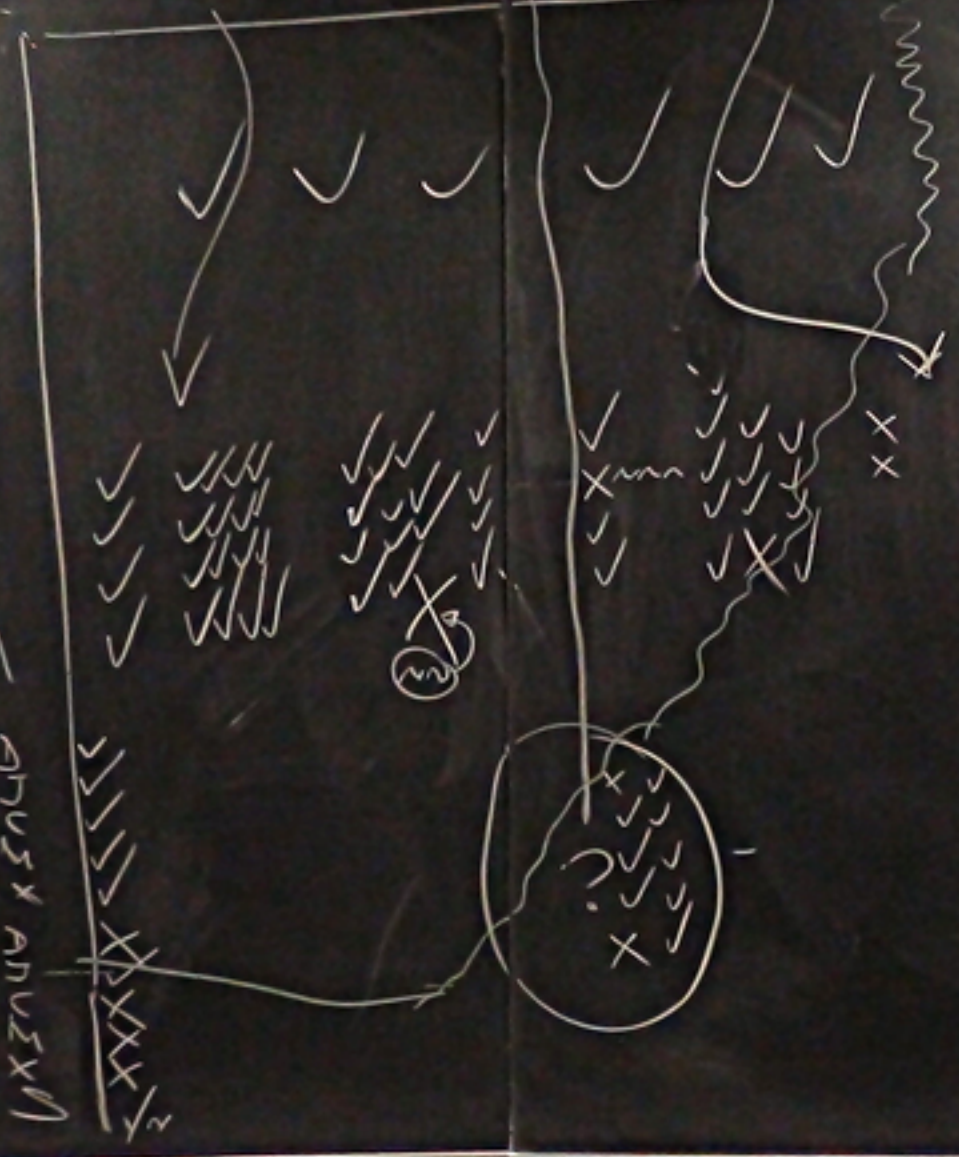
AHVΣ

AHVΣ × AHVΣ(1)

N=4

N=5

N=6



The Hopfield network

- Why does Hopfield net have stable states at all?
- What is the capacity of the Hopfield net?
- What else can we do with them?

Q: Where have we seen the Hopfield net before?

$$w_{ij} = w_{ji}, \quad w_{ii} = 0$$

Dynamics

$$a_i = \sum_j w_{ij} x_j + \theta_i$$
$$x_i = \tanh a_i$$

Hint:

$$a_m = \sum_n J_{mn} \bar{x}_n + h_m$$
$$\bar{x}_n = \tanh a_n$$

Variational methods

When we approximated the spin system whose energy function was

$$E(\mathbf{x}; \mathbf{J}) = -\frac{1}{2} \sum_{m,n} J_{mn} x_m x_n - \sum_n h_n x_n$$

with a separable distribution

$$Q(\mathbf{x}; \mathbf{a}) = \frac{1}{Z_Q} \exp \left(\sum_n a_n x_n \right)$$

and optimized Q so as to minimize the variational free energy

$$\beta \tilde{F}(\mathbf{a}) = \beta \sum_{\mathbf{x}} Q(\mathbf{x}; \mathbf{a}) E(\mathbf{x}; \mathbf{J}) - \sum_{\mathbf{x}} Q(\mathbf{x}; \mathbf{a}) \ln \frac{1}{Q(\mathbf{x}; \mathbf{a})},$$

we found that the iterative equations

$$a_m = \beta \left(\sum_n J_{mn} \bar{x}_n + h_m \right) \quad \text{and} \quad \bar{x}_n = \tanh(a_n)$$

were guaranteed to decrease the variational free energy

$$\beta \tilde{F}(\mathbf{a}) = \beta \left(-\frac{1}{2} \sum_{m,n} J_{mn} \bar{x}_m \bar{x}_n - \sum_n h_n \bar{x}_n \right) - \sum_n H_2^{(e)}(q_n).$$

HN \equiv VFE min approx to
"Q"

$$P(x) = \frac{e^{\sum_i x_i w_{ij} x_j}}{Z}$$

Boltzmann machine

learning algorithm for the BM

→ Hebb rule!

Hopfield net dynamics
minimize

F_2

o
o o

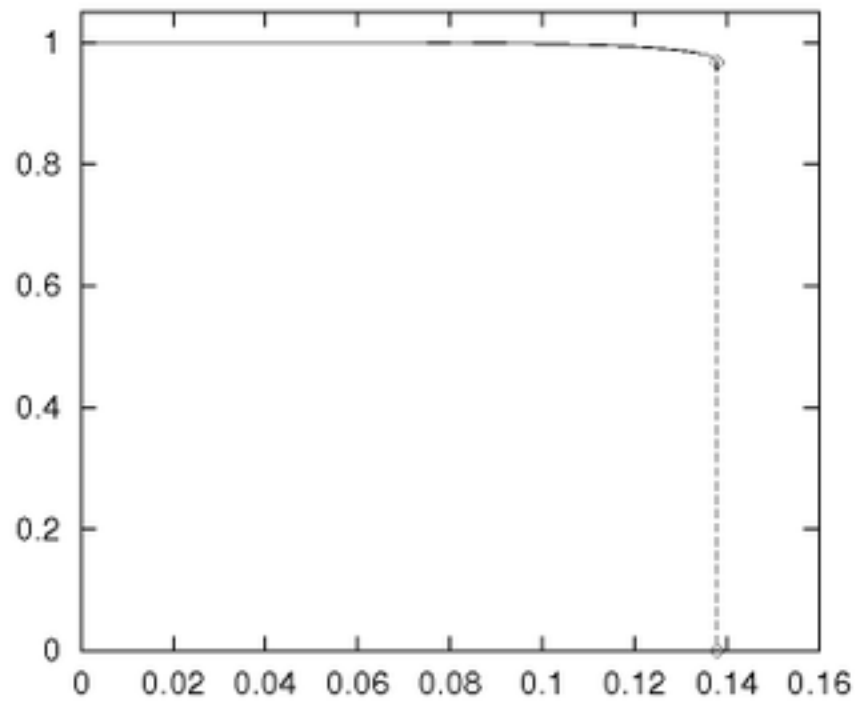
\exists fixed points

$\&$ dynamics

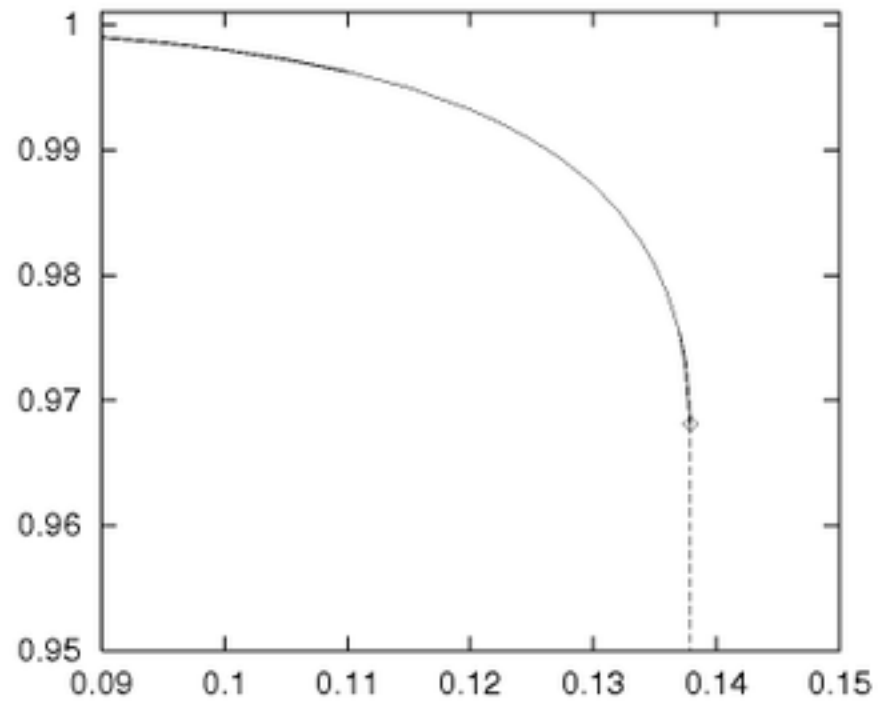


Capacity of Hopfield network

Overlap between a desired memory and the nearest stable state



N/I



N/I

Capacity for random patterns: $N_{\text{crit}} = 0.138 I$

0.24 bits per weight.

I neurons

N patterns

parameters

\sim

$$\frac{I^2}{2}$$

I neurons

N patterns

parameters \sim

$$\frac{I^2}{2}$$

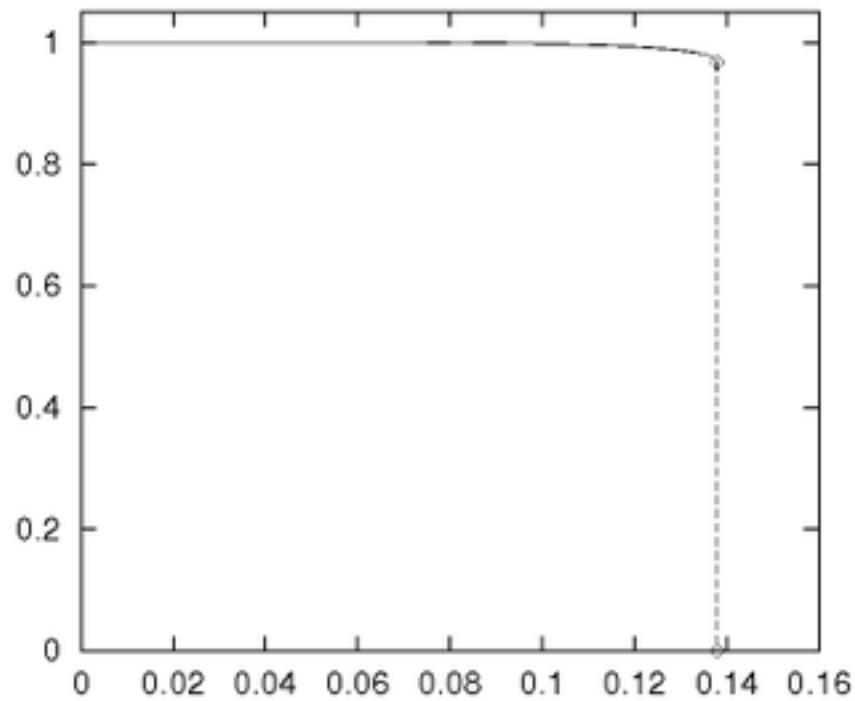
$$N_{\text{crit}} = 0.138 I$$

$$\# \text{bits} \approx N_{\text{crit}} \times I \approx$$

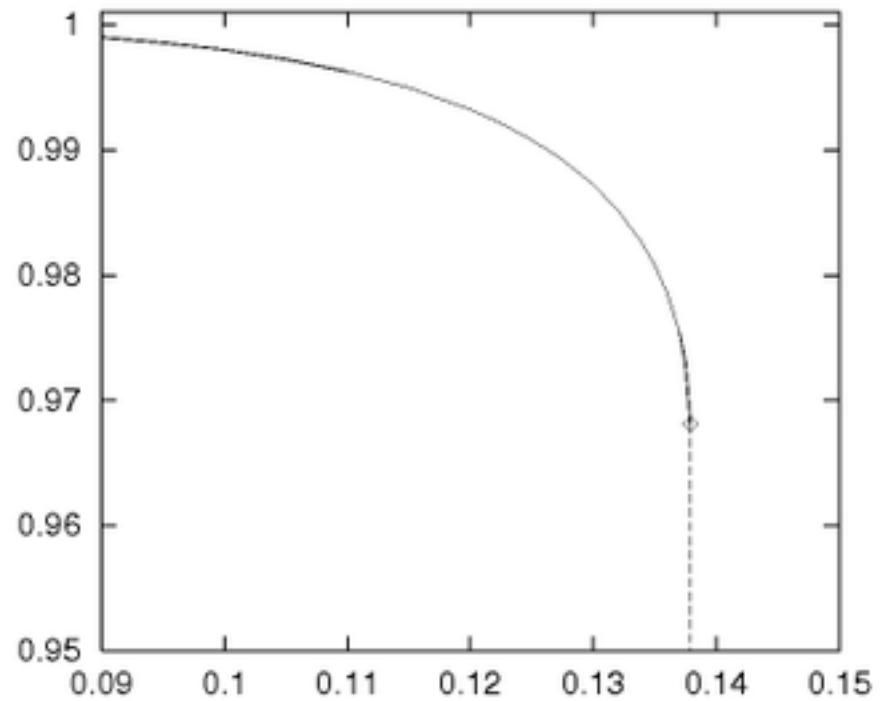
$$0.138 I^2$$

Capacity of Hopfield network

Overlap between a desired memory and the nearest stable state



N/I



N/I

Capacity for random patterns: $N_{\text{crit}} = 0.138 I$

0.24 bits per weight.

The Hopfield network

- Why does Hopfield net have stable states at all?
- What is the capacity of the Hopfield net?
- What else can we do with them?

Energy: 0.0

Actvn: 0.0

Bias: < > -8

penalty1: < > 5

penalty2: < > 7

Negative Weights

	1	2	3	4
A	■	■	■	■
B	■	■	■	■
C	■	■	■	■
D	■	■	■	■

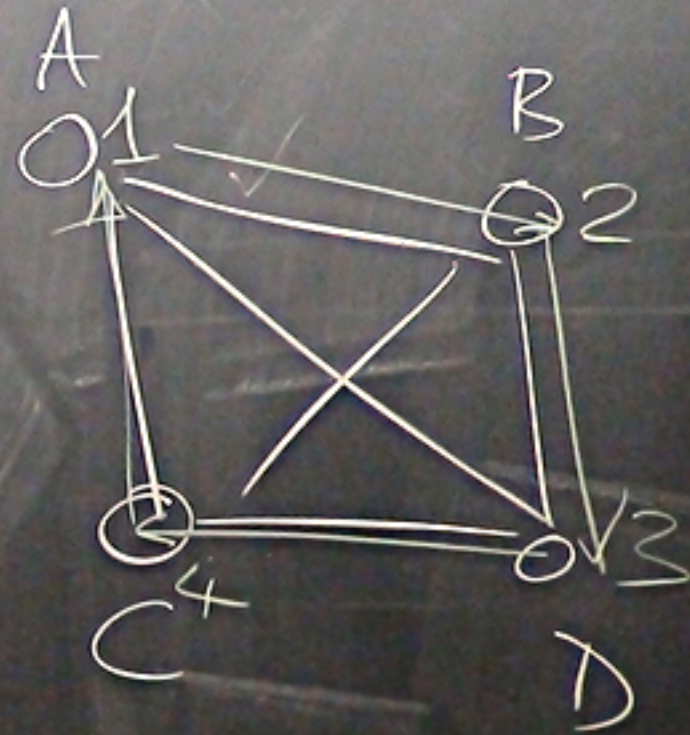
	A	B	C	D
A		1	4	6
B	1		1	4
C	4	1		1
D	6	4	1	

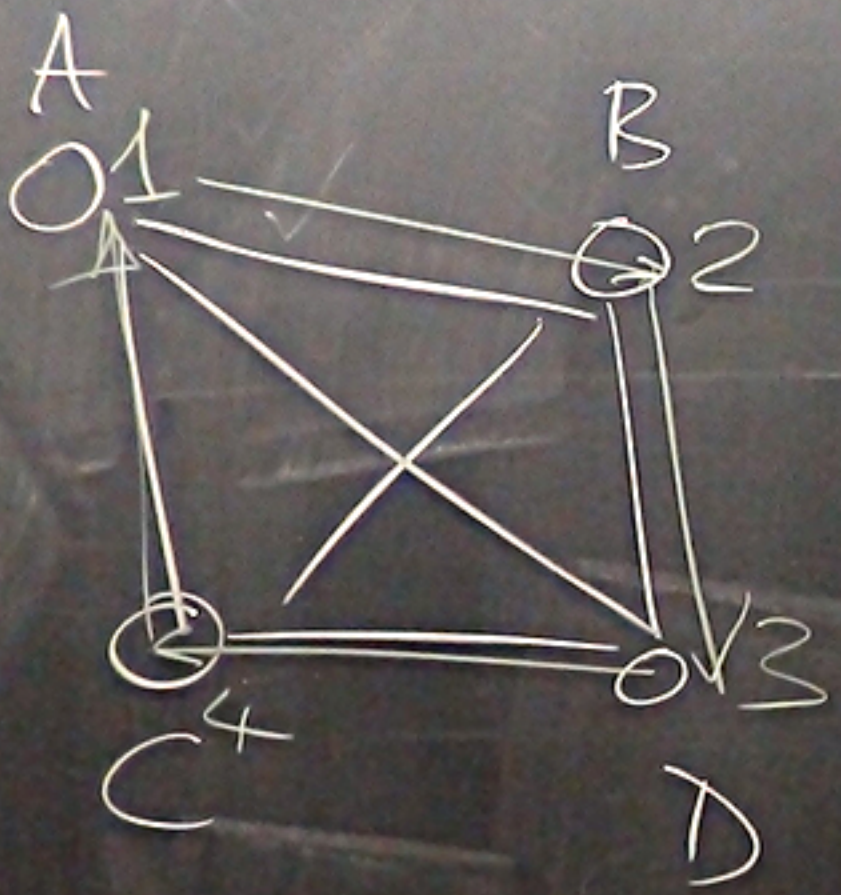
	7	7	7	5	1	0	1	5	4	0	4	5	6	0	6
7		7	7	1	5	1	0	4	5	4	0	6	5	6	0
7	7		7	0	1	5	1	0	4	5	4	0	6	5	6
7	7	7		1	0	1	5	4	0	4	5	6	0	6	5
5	1	0	1		7	7	7	5	1	0	1	5	4	0	4
1	5	1	0	7		7	7	1	5	1	0	4	5	4	0
0	1	5	1	7	7		7	0	1	5	1	0	4	5	4
1	0	1	5	7	7	7		1	0	1	5	4	0	4	5
5	4	0	4	5	1	0	1		7	7	7	5	1	0	1
4	5	4	0	1	5	1	0	7		7	7	1	5	1	0
0	4	5	4	0	1	5	1	7	7		7	0	1	5	1
4	0	4	5	1	0	1	5	7	7	7		1	0	1	5
5	6	0	6	5	4	0	4	5	1	0	1		7	7	7
6	5	6	0	4	5	4	0	1	5	1	0	7		7	7
0	6	5	6	0	4	5	4	0	1	5	1	7	7		7
6	0	6	5	4	0	4	5	1	0	1	5	7	7	7	

Dismiss

TSP

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NP complete problem

NP complete problem.

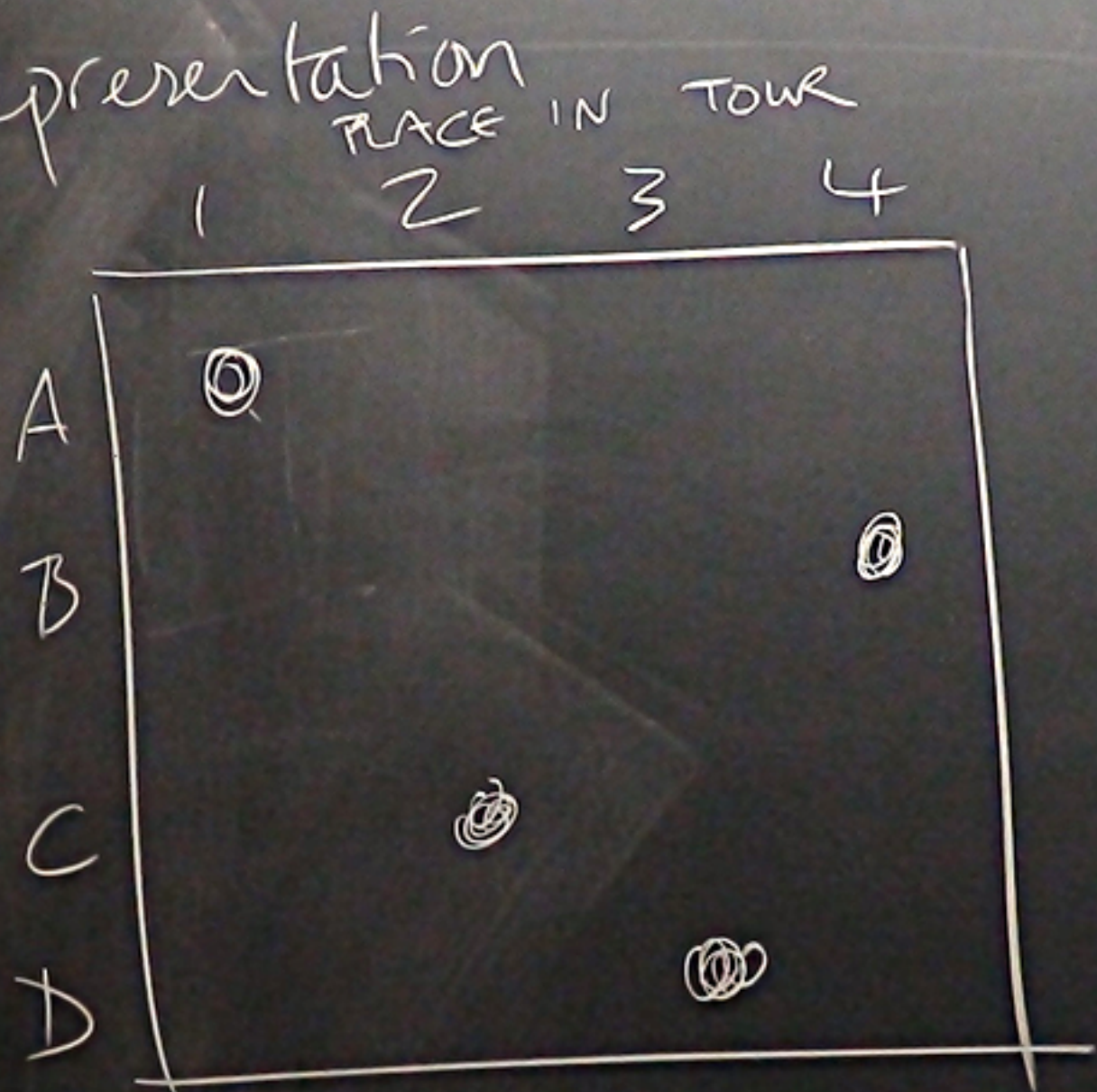
goal:

find a permutation
A, B, C, D

that minimizes total
distance

Network representation

CITY



ACDB

NP complete problem.

goal:

find a

permutation

A, B, C, D

that minimizes total
distance

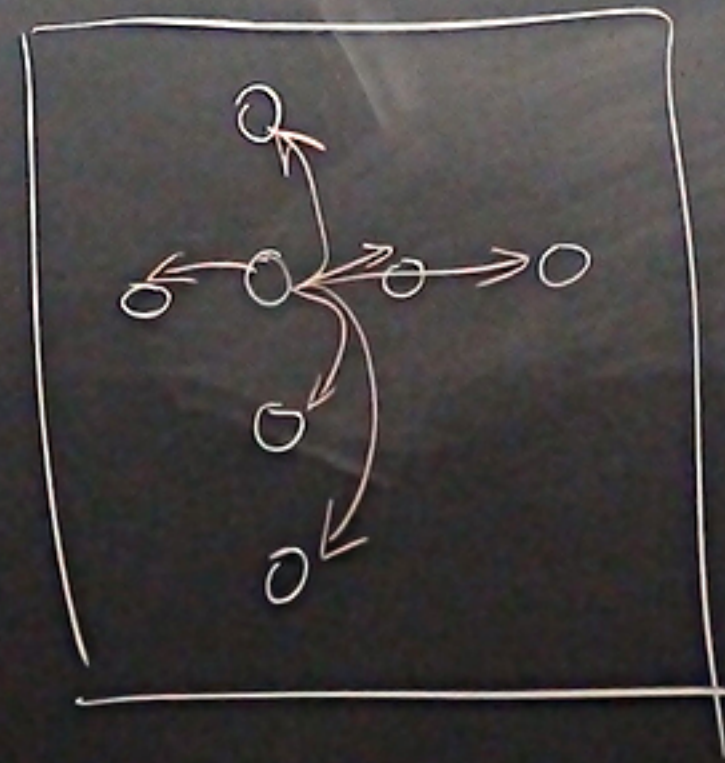
Noise

Network representation
PLACE IN TOUR

CITY

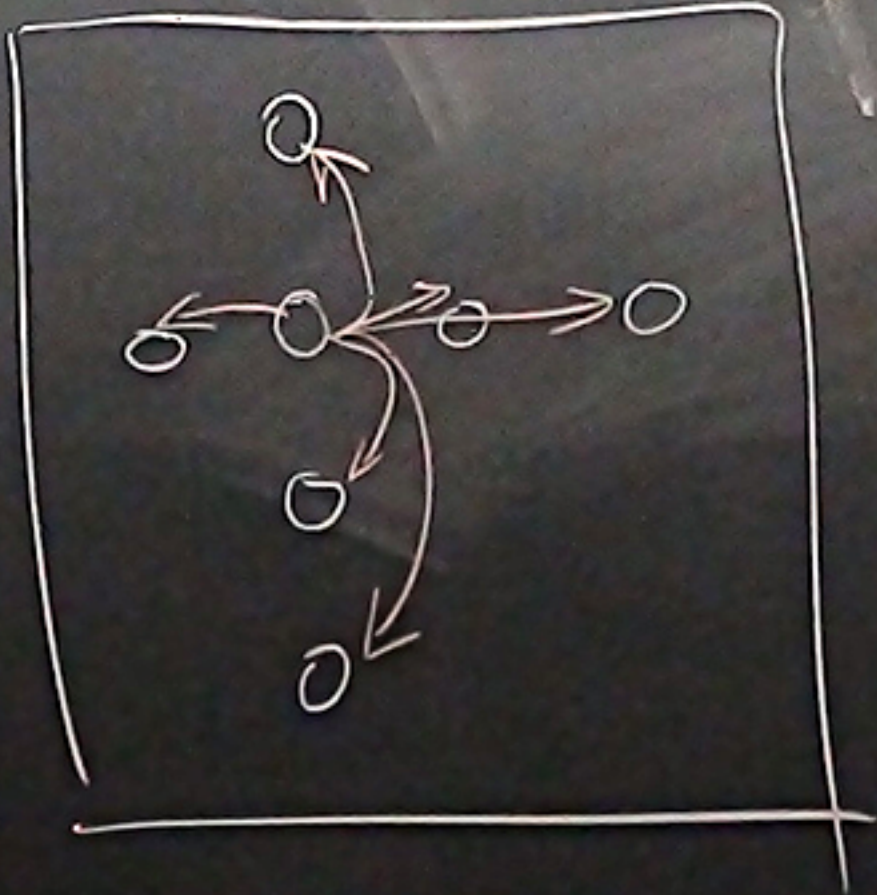


Permutation



ACDB

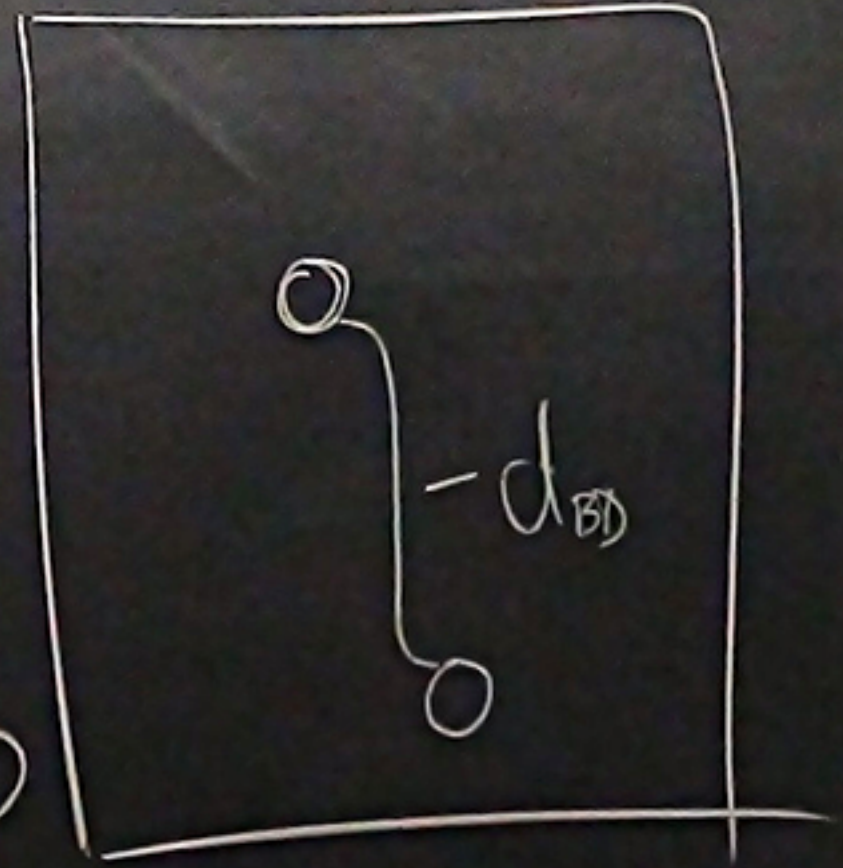
Permutation



2 3

B

D



Energy: 0.0

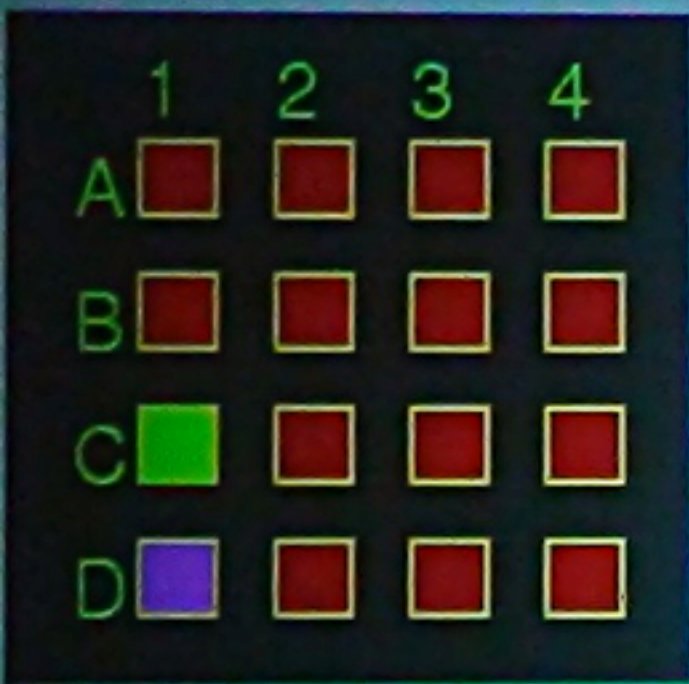
Actvn:

Bias: < > -8

penalty1: < > 5

penalty2: < > 7

Negative Weights



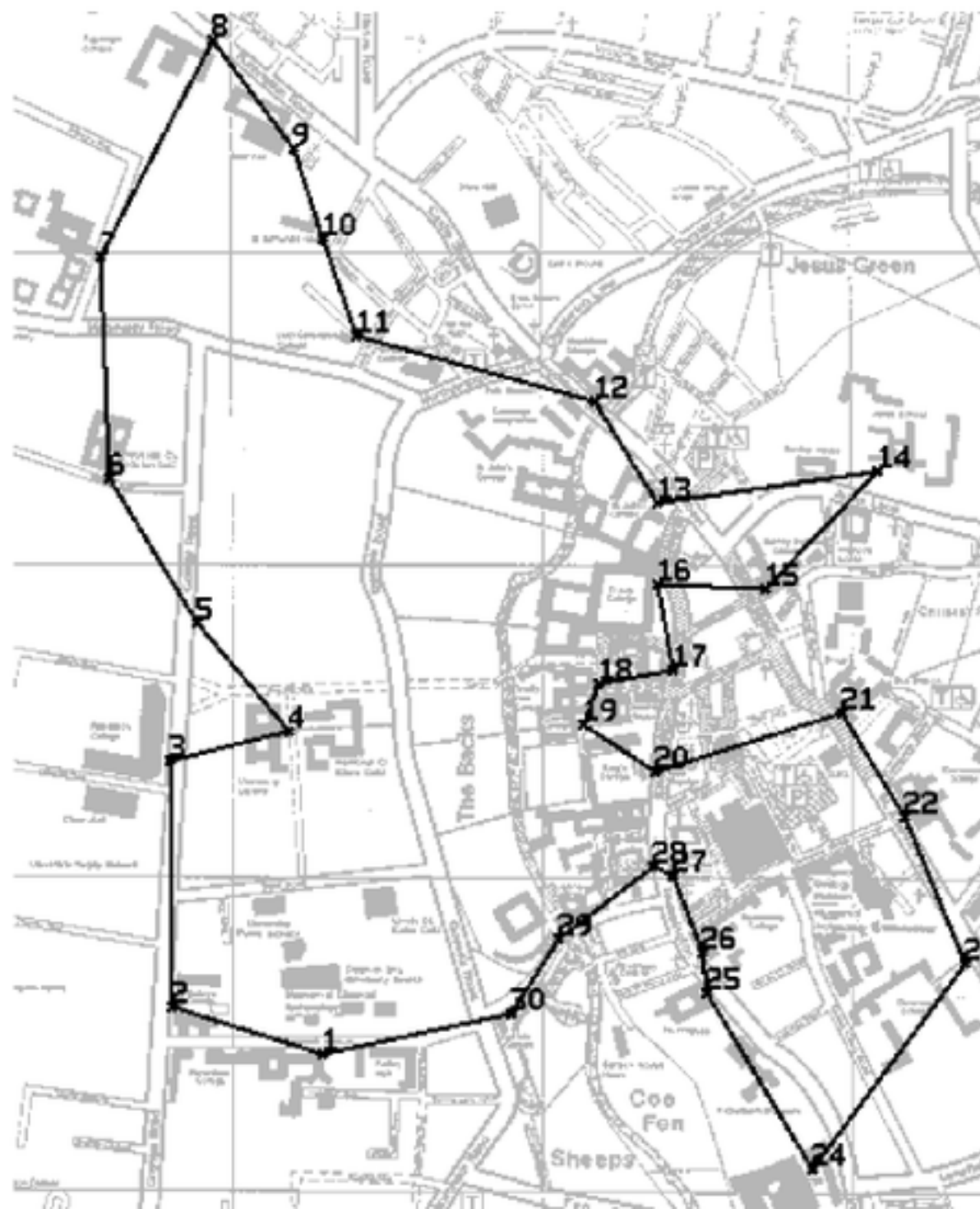
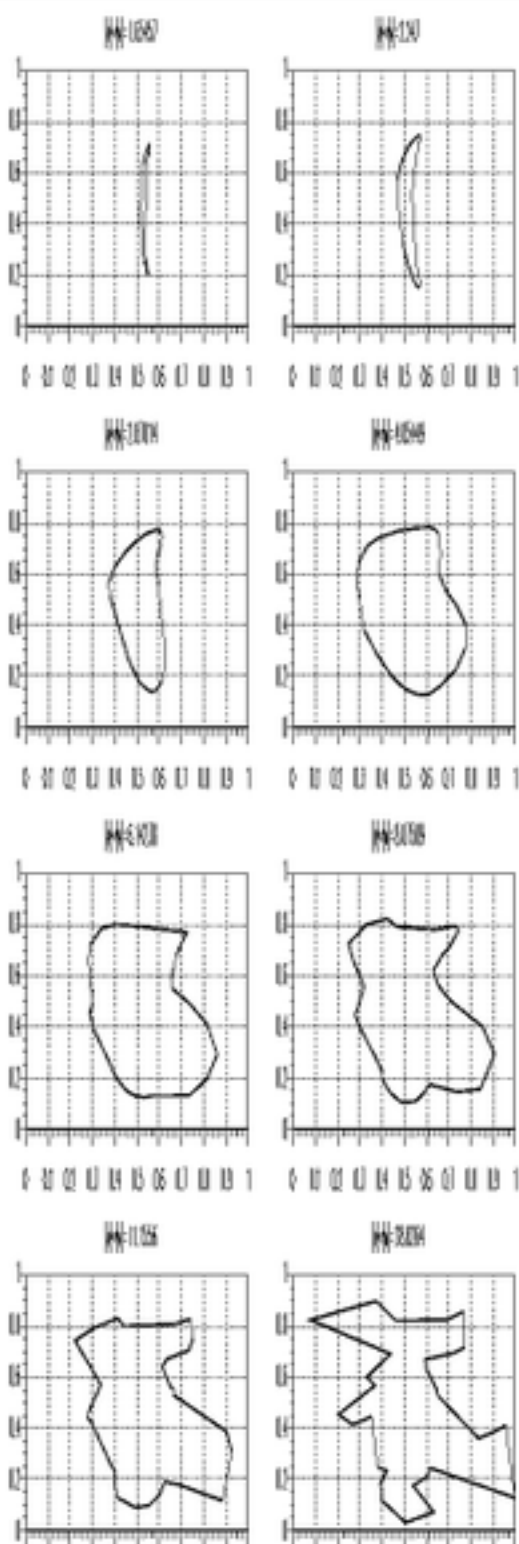
	A	B	C	D
A		1	4	6
B	1		1	4
C	4	1		1
D	6	4	1	

7	7	7	5	1	0	1	5	4	0	4	5	6	0	6	
7		7	7	1	5	1	0	4	5	4	0	6	5	6	0
7	7		7	0	1	5	1	0	4	5	4	0	6	5	6
7	7	7		1	0	1	5	4	0	4	5	6	0	6	5
5	1	0	1		7	7	7	5	1	0	1	5	4	0	4
1	5	1	0	7		7	7	1	5	1	0	4	5	4	0
0	1	5	1	7	7		7	0	1	5	1	0	4	5	4
1	0	1	5	7	7	7		1	0	1	5	4	0	4	5
5	4	0	4	5	1	0	1		7	7	7	1	0	1	1
4	5	4	0	1	5	1	0	7		7	7	1	5	1	0
0	4	5	4	0	1	5	1	7	7		7	0	1	5	1
4	0	4	5	1	0	1	5	7	7	7		1	0	1	5
5	6	0	6	5	4	0	4	5	1	0	1		7	7	7
6	5	6	0	4	5	4	0	1	5	1	0	7		7	7
0	6	5	6	0	4	5	4	0	1	5	1	7	7		7
6	0	6	5	4	0	4	5	1	0	1	5	7	7	7	

Dismiss

Hopfield networks for optimization

"The Travelling Scholar Problem" (Sree Aiyer, 1991)



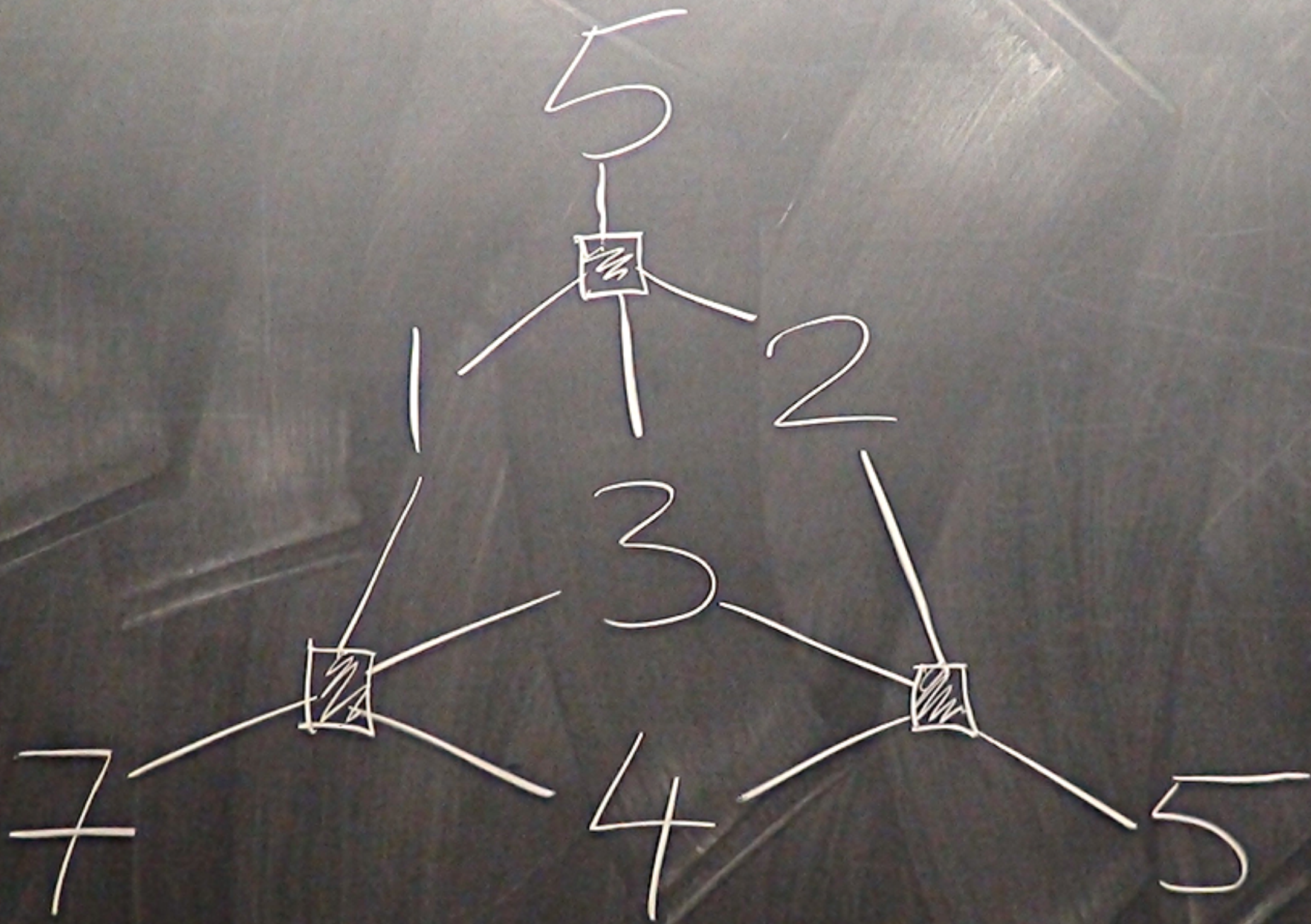
Q: What is this?

$$P_0(\mathbf{x}) = \frac{1}{Z_0} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7]}$$

where $\mathbf{x} = (x_1, x_2, x_3, \dots, x_7)$, $x_n \in \pm 1$
and $\beta = \text{large}$

& What is this?

$$P_1(\mathbf{x}) = \frac{1}{Z_1} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7] + \sum_{n=1}^N b_n x_n}$$



Q: What is this?

$$P_0(\mathbf{x}) = \frac{1}{Z_0} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7]}$$

where $\mathbf{x} = (x_1, x_2, x_3, \dots, x_7)$, $x_n \in \pm 1$
and $\beta = \text{large}$

& What is this?

$$P_1(\mathbf{x}) = \frac{1}{Z_1} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7] + \sum_{n=1}^N b_n x_n}$$

$(7, 4)$ Hamming Code

s $\xrightarrow{\text{Encode}}$ t

$P_0(t)$

BSC

$\xrightarrow{\hspace{10em}}$ r

$$r = t \oplus n$$

$$P(\underline{t} | \underline{r}) = \frac{\prod_{n=1}^N P(r_n | t_n) P_0(\underline{t})}{Z}$$

$$\prod_{n=1}^N P(r_n | t_n) P_0(t)$$

$$P(r | t) P(t)$$

Z

$$e^{b_n t_n}$$

Z

Q: What is this?

$$P_0(\mathbf{x}) = \frac{1}{Z_0} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7]}$$

where $\mathbf{x} = (x_1, x_2, x_3, \dots, x_7)$, $x_n \in \pm 1$
and $\beta = \text{large}$

& What is this?

$$P_1(\mathbf{x}) = \frac{1}{Z_1} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7] + \sum_{n=1}^N b_n x_n}$$

$$P(x) = e^{-\sum_{i,j} w_{ij} x_i x_j + \sum e_i x_i}$$

↑
approx this using a VFE min

$$Q(x)$$

Idea

$$P_1(\mathbf{x}) = \frac{1}{Z_1} e^{\beta [x_1 x_2 x_3 x_5 + x_2 x_3 x_4 x_6 + x_1 x_3 x_4 x_7] + \sum_{n=1}^N b_n x_n}$$

● Solve the decoding problem

$$\max_{\mathbf{x}} P_1(\mathbf{x})$$

using approximate methods?

eg, Approximate $P_1(\mathbf{x})$ by $Q(\mathbf{x})$
using a variational method

Electronics Letters, March 1995

Free energy minimisation algorithm for decoding and cryptanalysis

D.J.C. MacKay

Indexing terms: Decoding, Cryptography

An algorithm is derived for inferring a binary vector \mathbf{s} given noisy observations of \mathbf{As} modulo 2, where \mathbf{A} is a binary matrix. The binary vector is replaced by a vector of probabilities, optimised by free energy minimisation. Experiments on the inference of the state of a linear feedback shift register indicate that this algorithm supersedes the Meier and Staffelbach polynomial algorithm.

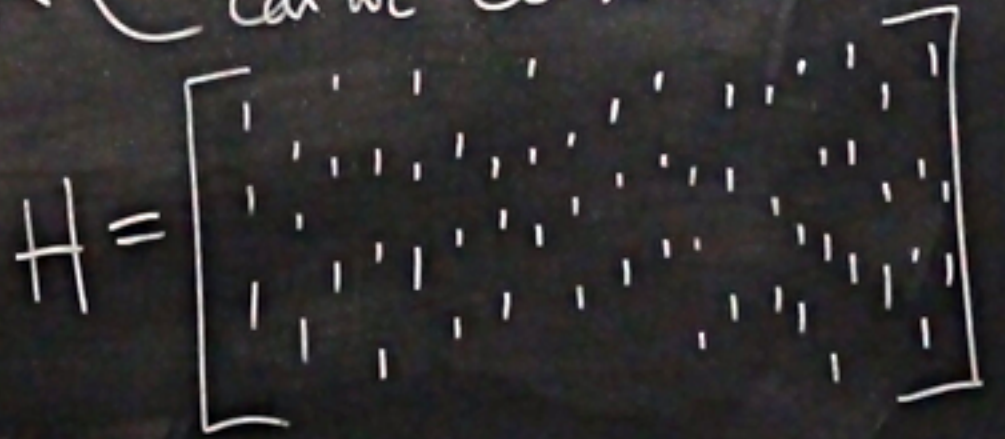
H =





can we do better than this

can we do better than VFE_{min}?



H =



can we do better than VFE_{min}?!

Sum-product algo, thm

Electronics Letters, August 1996

Near Shannon limit performance of low density parity check codes

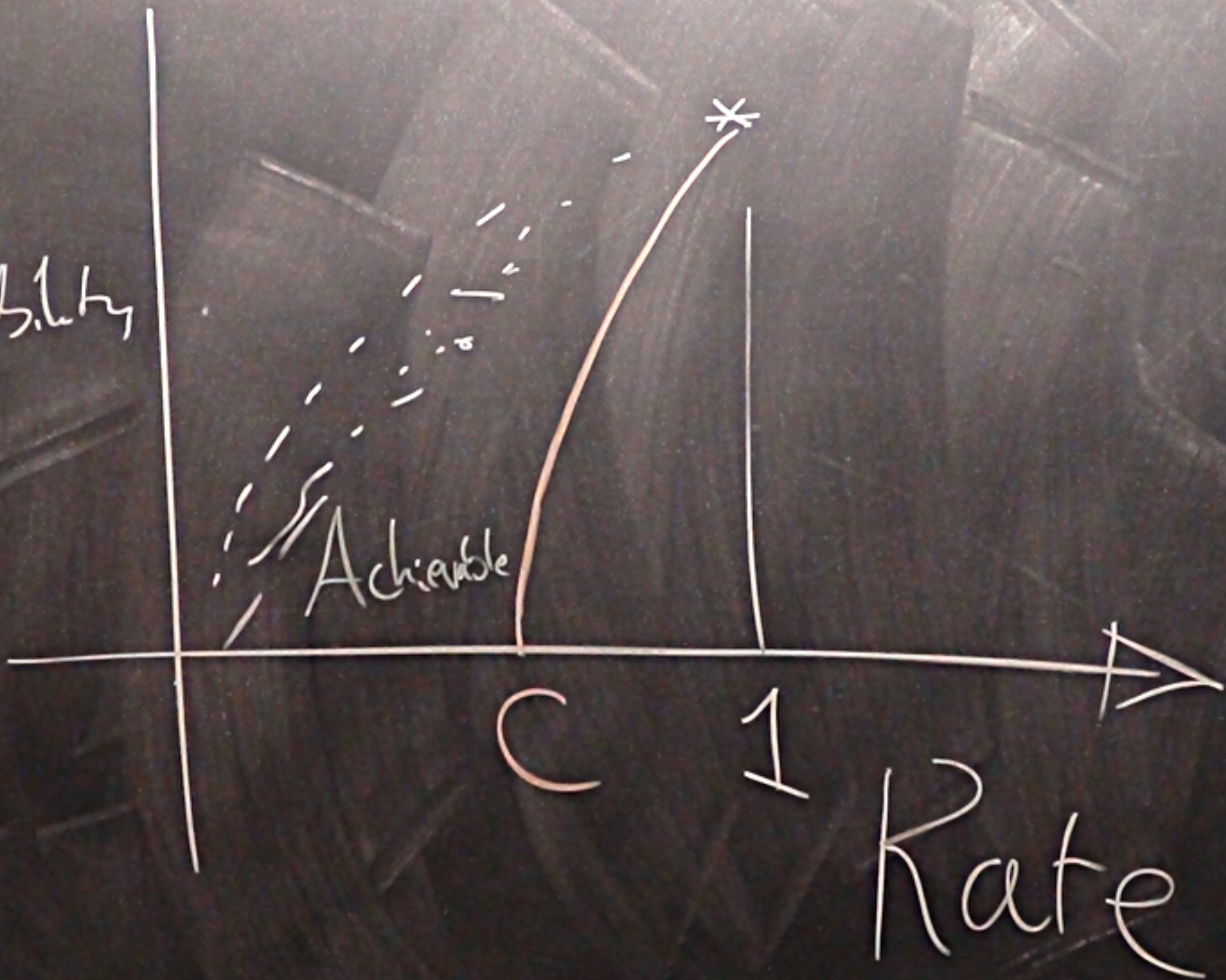
D.J.C. MacKay and R.M. Neal

[Low Density Parity Check Codes: Gallager 1962]

Indexing terms: Probabilistic decoding, Error correction codes

The authors report the empirical performance of Gallager's low density parity check codes on Gaussian channels. They show that performance substantially better than that of standard convolutional and concatenated codes can be achieved; indeed the performance is almost as close to the Shannon limit as that of turbo codes.

Error
probability



Low Density Parity Check Code

We demonstrate a large code that encodes $K = 10000$ source bits into $N = 20000$ transmitted bits.

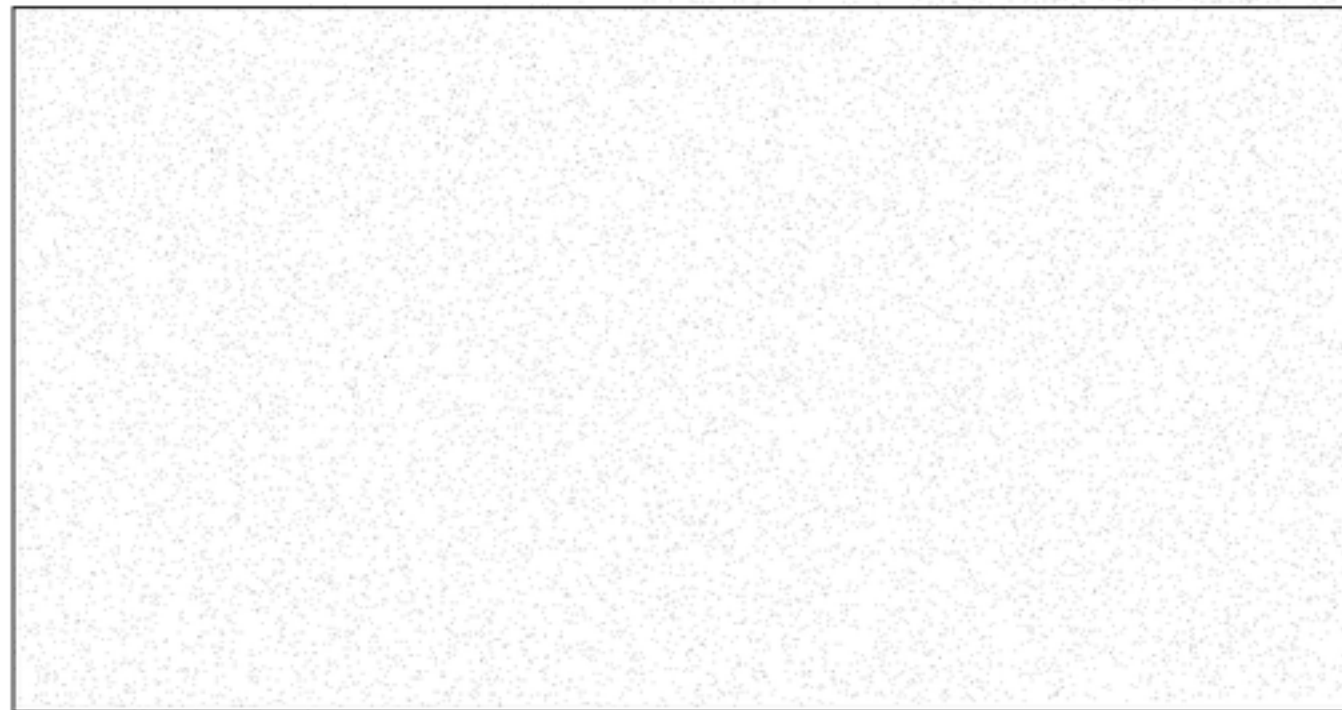
Each parity bit depends on about 5000 source bits.

The encoder is derived from a very sparse 10000×20000 matrix \mathbf{H} with three 1s per column.

TRANSMITTED:

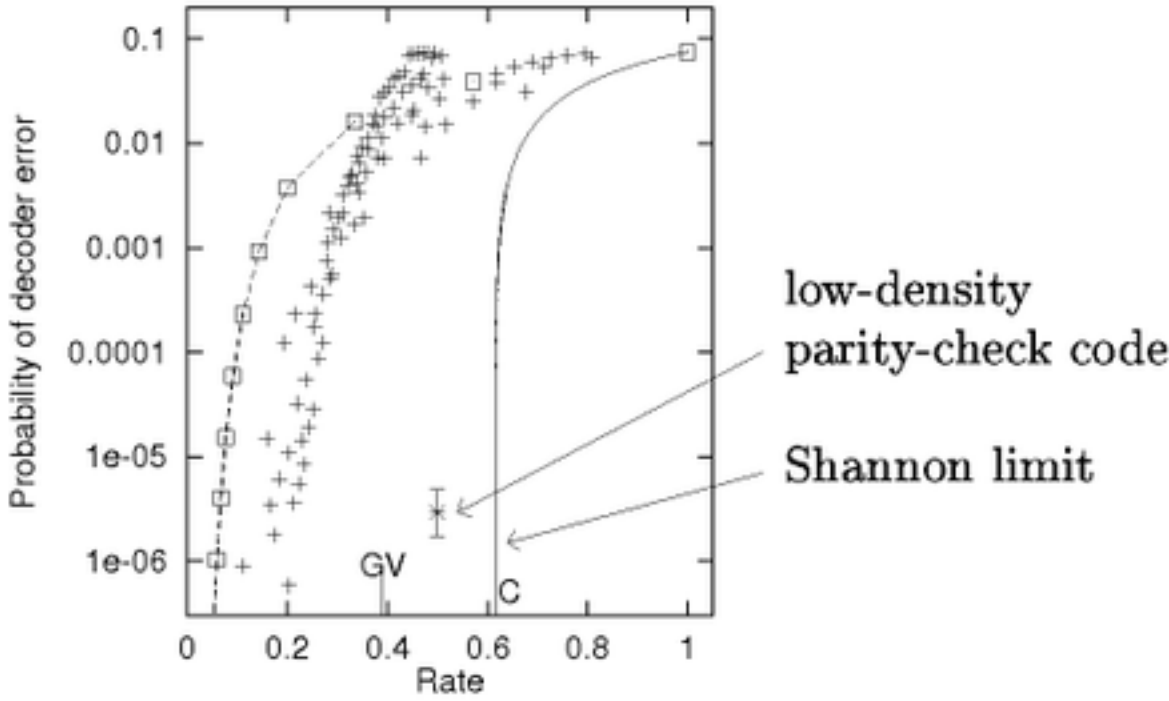


$\mathbf{H} =$



Low Density Parity Check Code (f = 7.5%)

Iterative probabilistic decoding



International Symposium on Information Theory 1997

One paper on low-density parity-check codes



International Symposium on Information Theory 2002

6 sessions on LDPC codes; 10 on sparse-graph codes

Analysis of LDPC Codes I
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R. Michael TANNER

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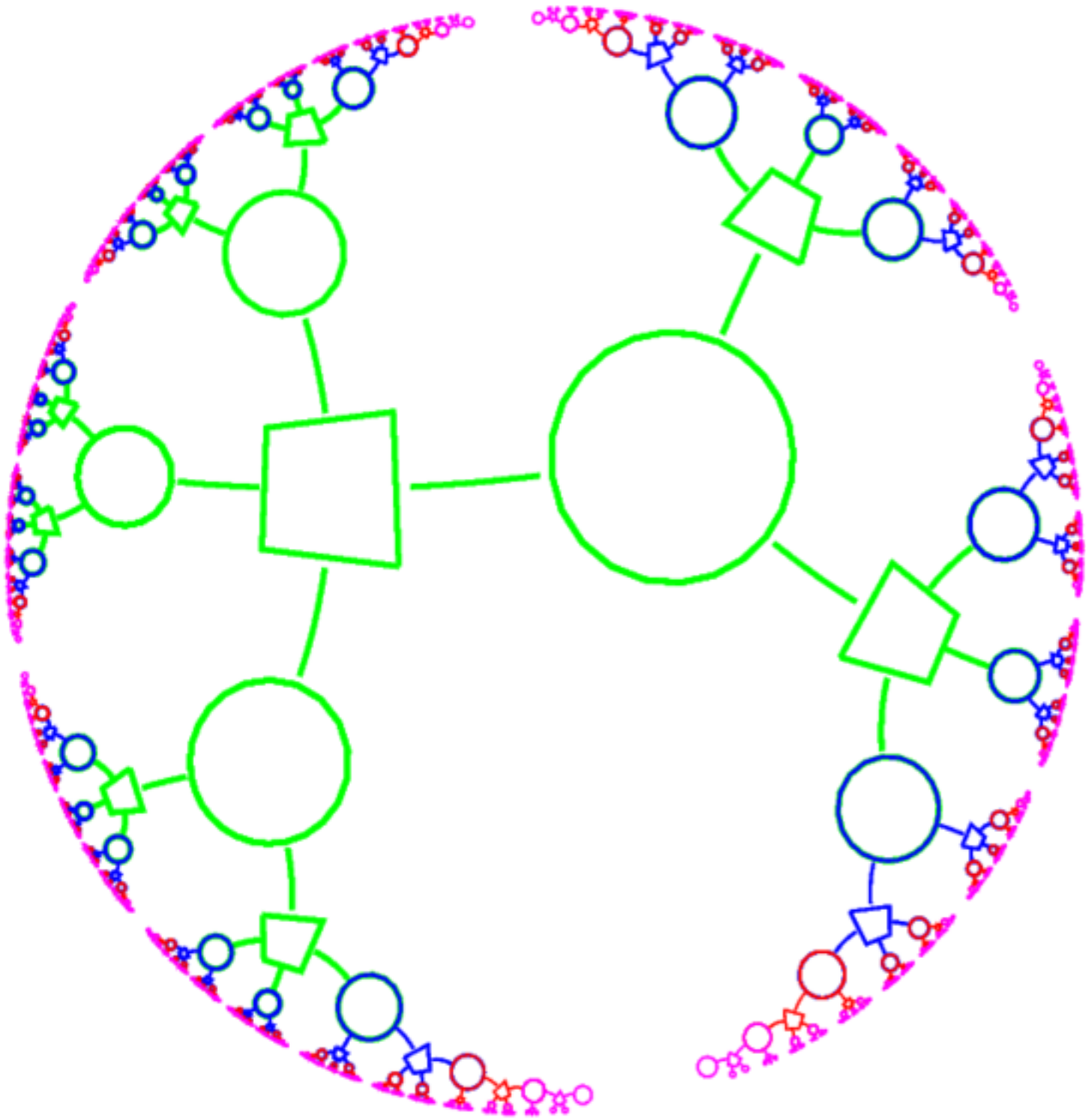
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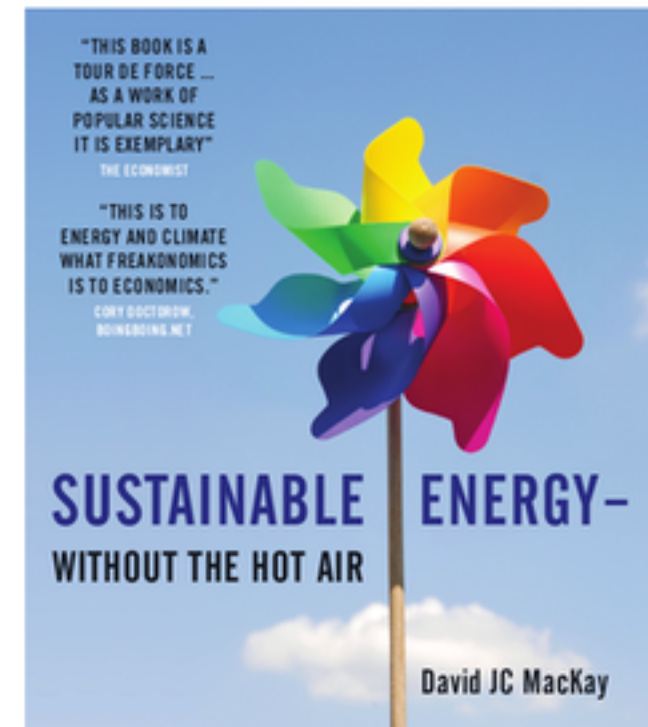
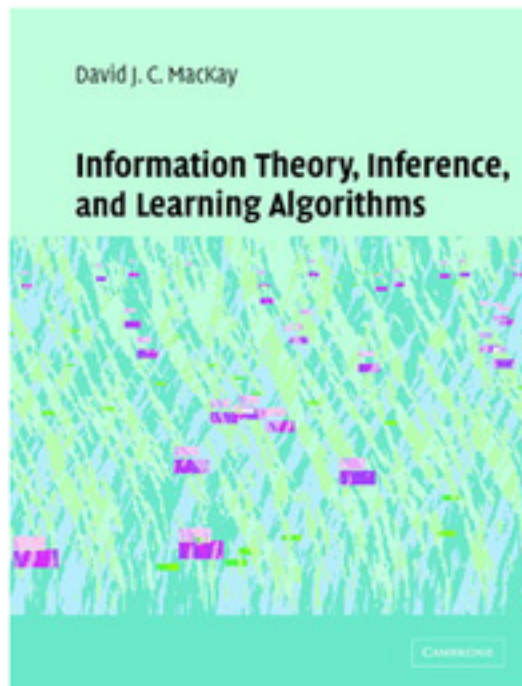
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Construction of LDPC Codes III
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Thomas MITTELHOLZER

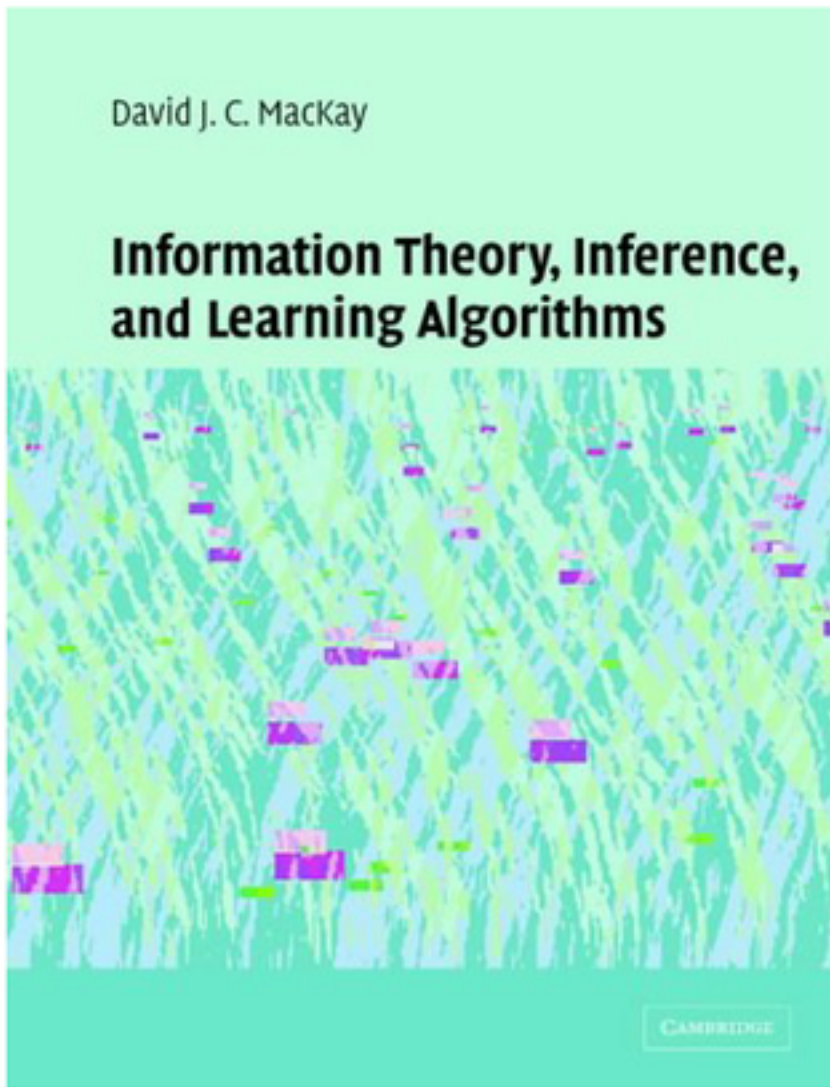


Information Theory

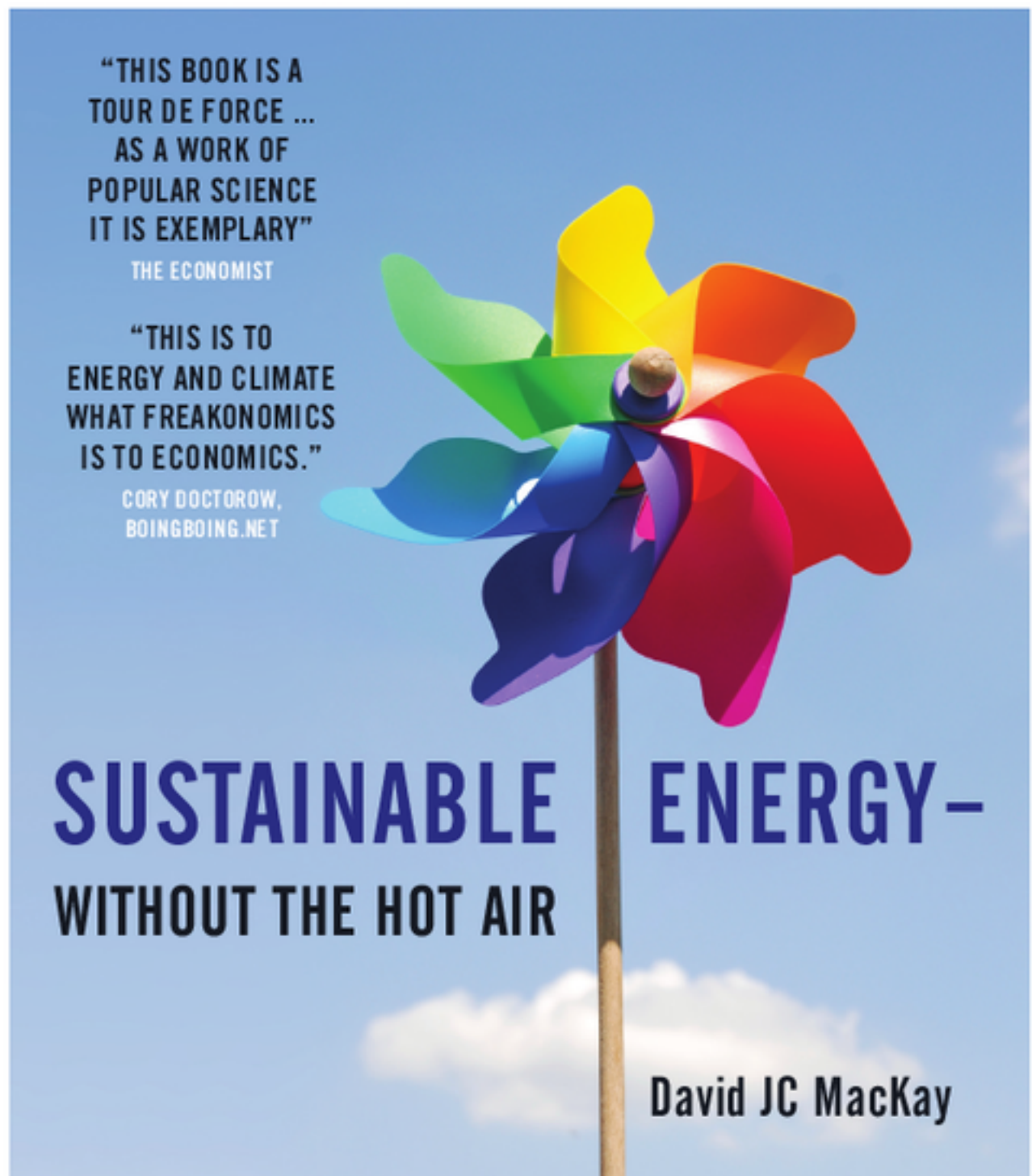
Sustainable Energy



Both available **free online**



www.inference.phy.cam.ac.uk/itila/



www.withouthotair.com