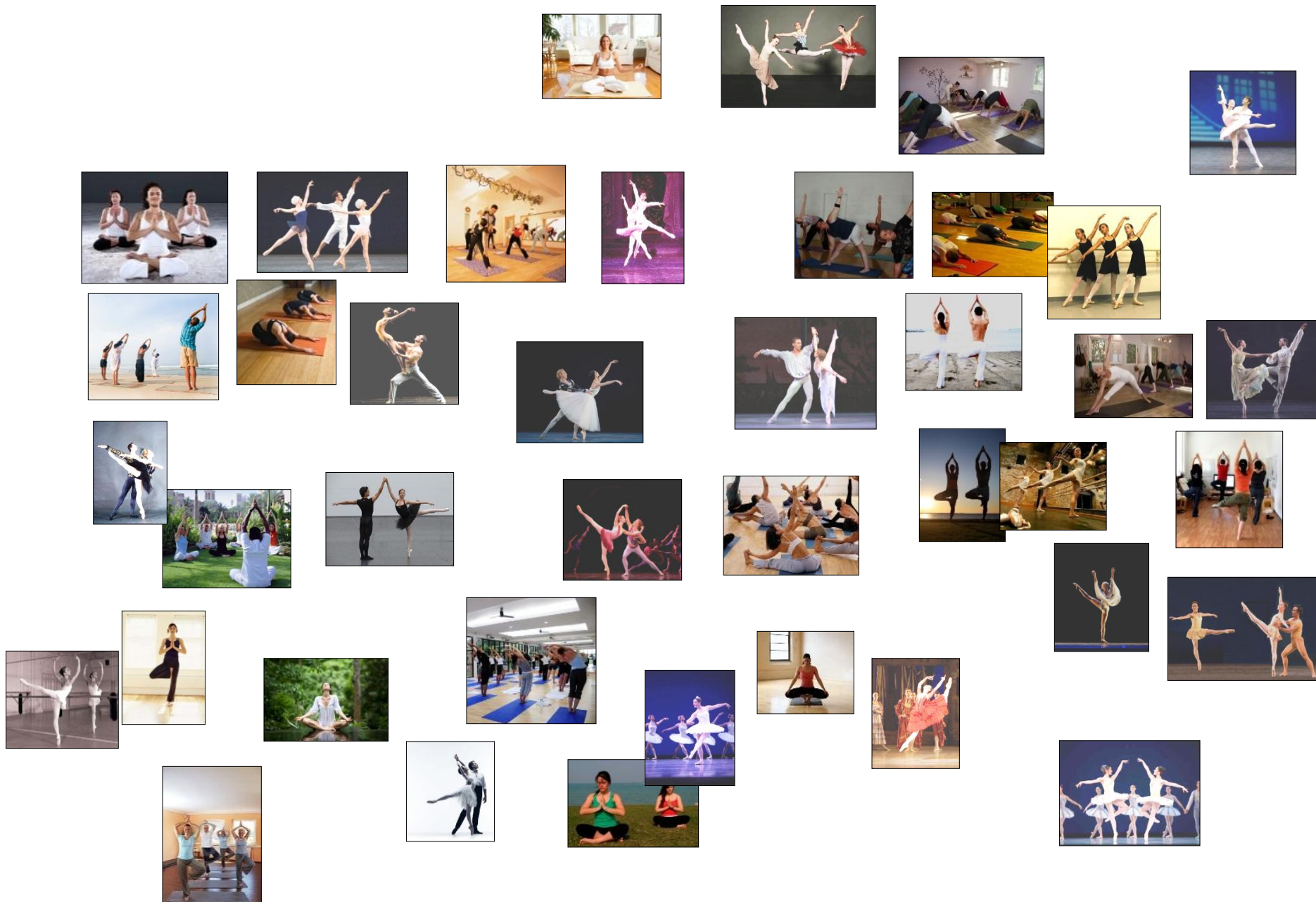
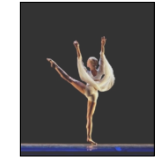


“Clustering by Composition”: **Unsupervised Discovery of Image Categories**

Alon Faktor & Michal Irani
The Weizmann Institute of Science





Goal: Separate into 2 clusters (Yoga & Ballet)

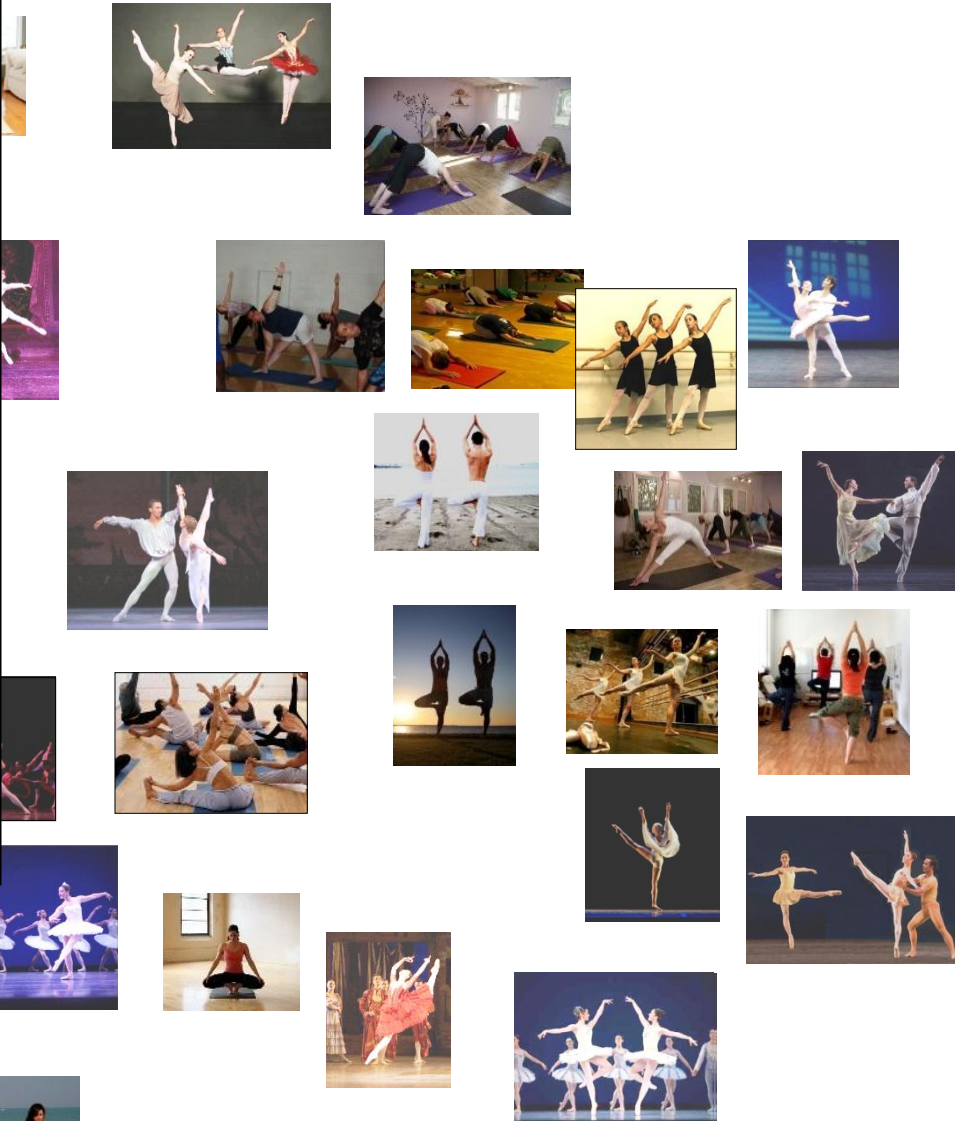
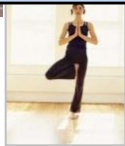
Previous Work:
Unsupervised Category Discovery

Simple pairwise affinities:

- Grauman & Darrell 2006 (Pyramid match kernel)

Discover common “cluster model”:

- Sivic et al 2005 (PLSA)
- Russell et al 2006 (segments)
- Kim et al 2008 (link analysis)
- Lee & Grauman 2009 (foreground)
- Payet & Todorovic 2010 (shape)
- ...



Goal: Separate into 2 clusters (Yoga & Ballet)

Overview of Our Approach:

- *“Affinity by composition”*



Low Affinity

High Affinity

“Good region” \neq “Good segment”

- 1) *“Rare” (low chance to occur at random).*
- 2) *Shared by 2 images.*

Goal: Separate into 2 clusters (Yoga & Ballet)

Overview of Our Approach:

- *“Affinity by composition”*

- Random Search process

+

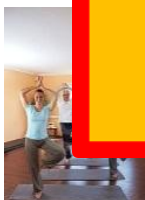
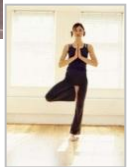
Image collaboration



Linear complexity

“Good region” \neq “Good segment”

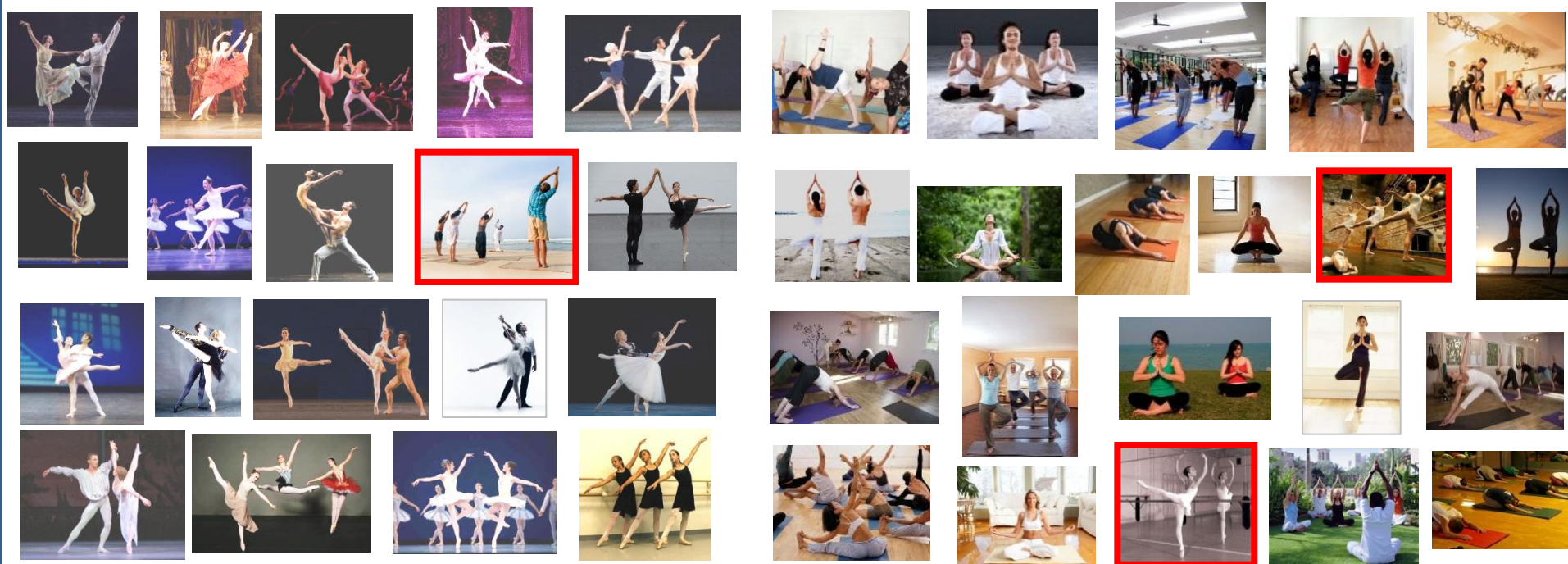
- 1) *“Rare” (low chance to occur at random).*
- 2) *Shared by 2 images.*



Goal: Separate into 2 clusters (Yoga & Ballet)

Cluster#1 (mostly Ballet images)

Cluster#2 (mostly Yoga images)



Purity = $18/19 = 95\%$

Purity = $19/21 = 90\%$

“Affinity by Composition”

extending [Boiman & Irani, NIPS'06]

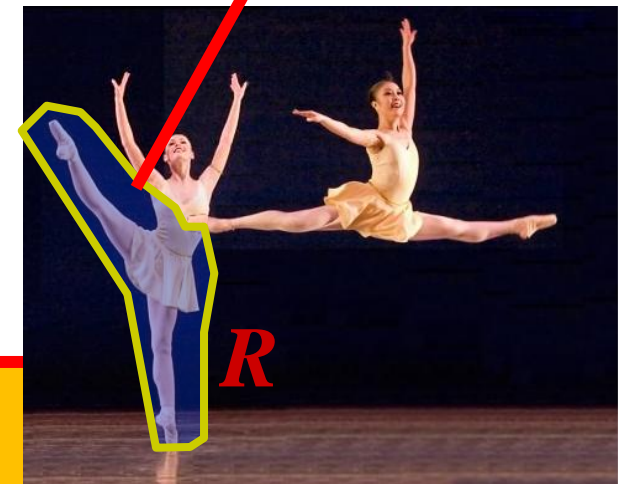


I_1

$$\frac{p(R | I_1, I_2)}{p(R | H_0)}$$

How good is the match

How rare is R



I_2

“Good region” R :

- 1) Shared by 2 images.
- 2) “Rare” (low chance to occur at random).

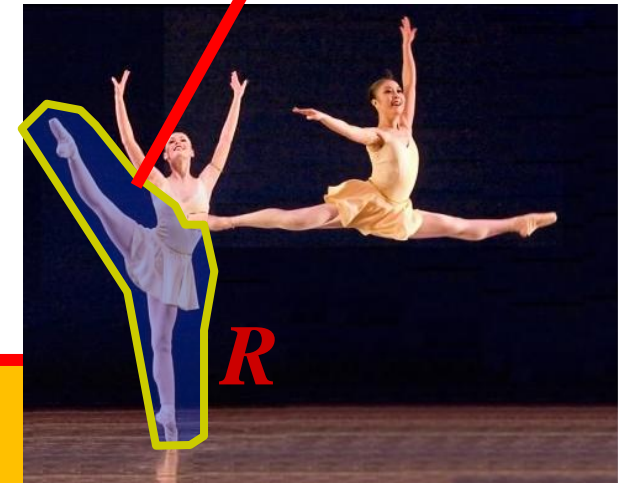
“Affinity by Composition”

extending [Boiman & Irani, NIPS'06]



I_1

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)} \rightarrow \text{contribution of } R \text{ to affinity}(I_1, I_2)$$



I_2

“Good region” R :

- 1) Shared by 2 images.
- 2) “Rare” (low chance to occur at random).

"Affinity by Composition"

extending [Boiman & Irani, NIPS'06]

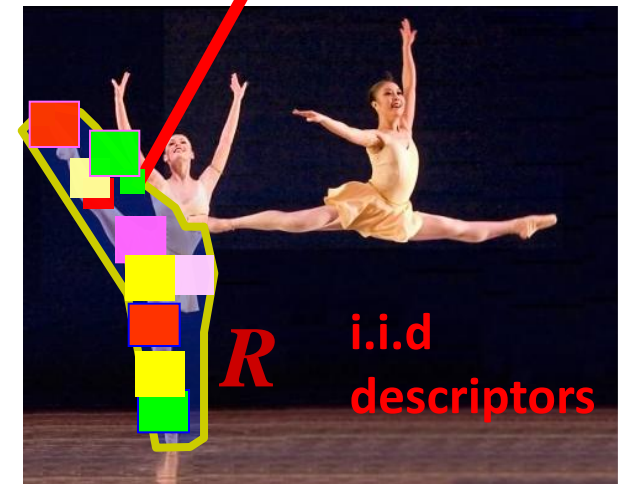


I_1

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)} =$$

$$\sum_{d_i \in R} \underbrace{[\log p(d_i | I_1, I_2) - \log p(d_i | H_0)]}$$

Quality of
descriptor match



I_2

R i.i.d
descriptors

"Affinity by Composition"

extending [Boiman & Irani, NIPS'06]



I_1

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)} =$$

$$\sum_{d_i \in R} \underbrace{[\log p(d_i | I_1, I_2) - \log p(d_i | H_0)]}$$

Quality of
descriptor match



I_2

R

i.i.d
descriptors

"Affinity by Composition"

extending [Boiman & Irani, NIPS'06]



I_1

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)} =$$

$$\sum_{d_i \in R} [\underbrace{\log p(d_i | I_1, I_2)}_{-Err(d_i | I_1, I_2)} - \underbrace{\log p(d_i | H_0)}_{\text{How rare is the descriptor?}}]$$

$-Err(d_i | I_1, I_2)$

How rare is
the descriptor?



I_2

R i.i.d
descriptors

Statistically Significant Descriptors

How rare is
each descriptor:

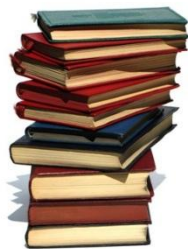
$$-\log p(d_i | H_0) = ?$$



Generate a "codebook" (quantized descriptors):

- *Frequent descriptors* → *Low error*
- *Rare descriptors* → *High error*

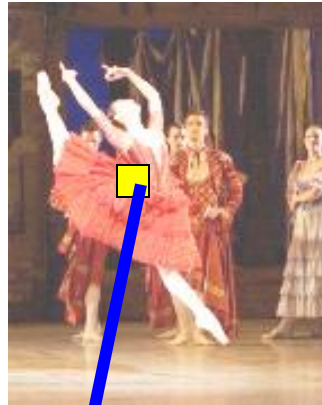
Codebook



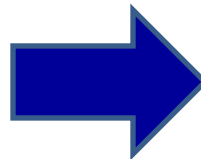
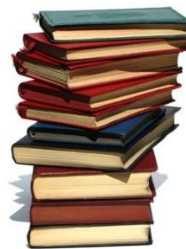
Statistically Significant Descriptors

How rare is
each descriptor:

$$-\log p(d_i | H_0) = ?$$



Codebook



Compute error
to *Nearest*
Codeword



Statistically Significant Descriptors

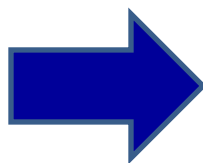
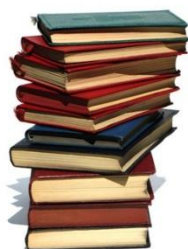
How rare is
each descriptor:

$$-\log p(d_i | H_0) = ?$$



$$-\log p(d_i | H_0) \approx \text{Err}(d_i | \text{Codebook})$$

Codebook



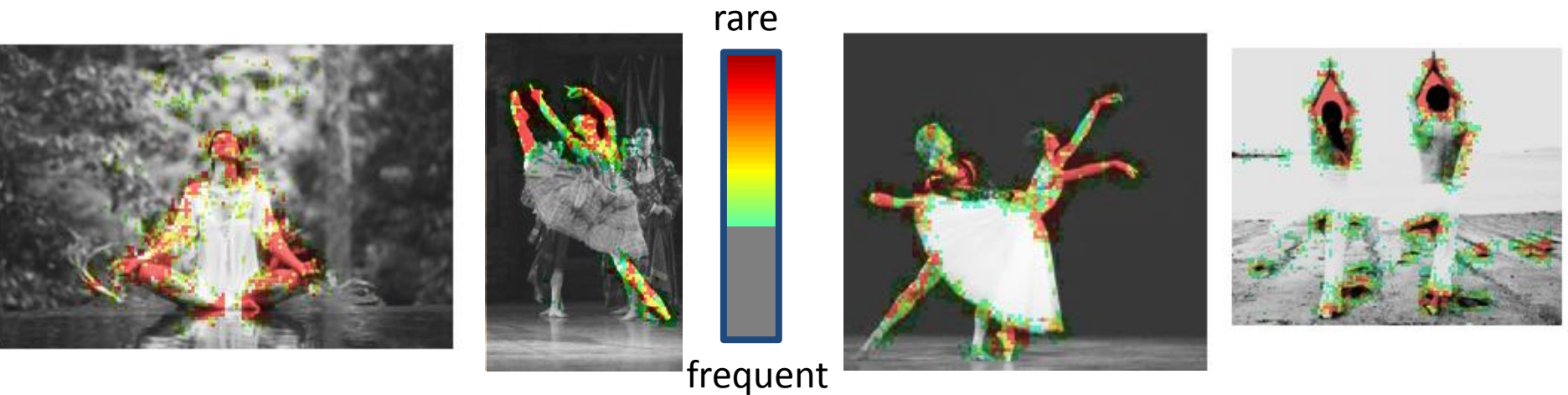
Compute error
to Nearest
Codeword



Statistically Significant Descriptors

How rare is each descriptor:

$$-\log p(d_i | H_0) = ?$$



$$-\log p(d_i | H_0) \approx \text{Err}(d_i | \text{Codebook})$$

The most informative descriptors are the rare ones !

"Affinity by Composition"

I_1



**Contribution of R
to affinity(I_1, I_2)**

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

**How good is
the match**

How rare is R



I_2

“Affinity by Composition”

I_1



**Contribution of R
to affinity(I_1, I_2)**

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

$$= \sum_{d_i \in R} [Err(d_i | codebook) - Err(d_i | I_1, I_2)]$$



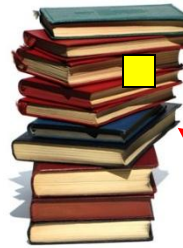
I_2

“Affinity by Composition”

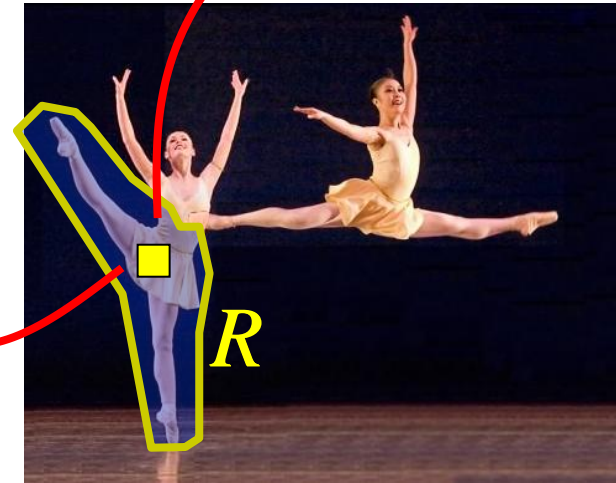
I_1



Codebook



Contribution of R
to affinity(I_1, I_2)



$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

$$= \sum_{d_i \in R} [Err(d_i | codebook) - Err(d_i | I_1, I_2)]$$

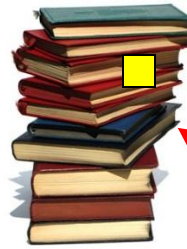
I_2

“Affinity by Composition”

I_1

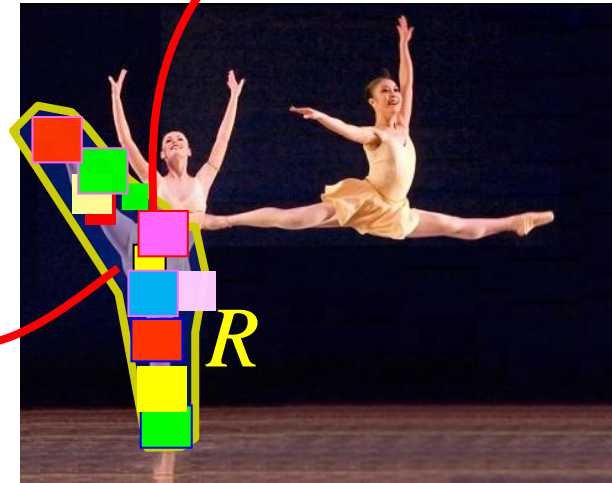


Codebook



Contribution of R
to affinity(I_1, I_2)

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

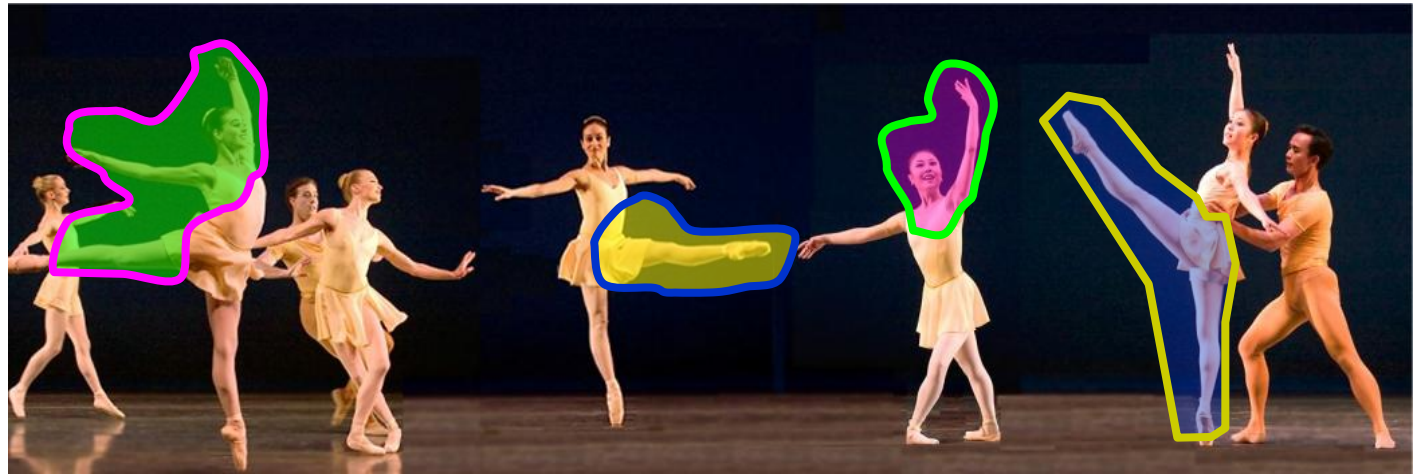


$$= \sum_{d_i \in R} [Err(d_i | codebook) - Err(d_i | I_1, I_2)]$$

I_2

“Affinity by Composition”

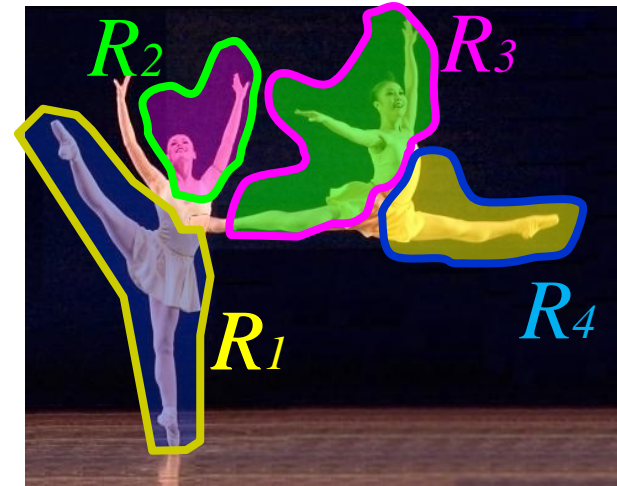
I_1



Contribution of R
to affinity(I_1, I_2)

$$\log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

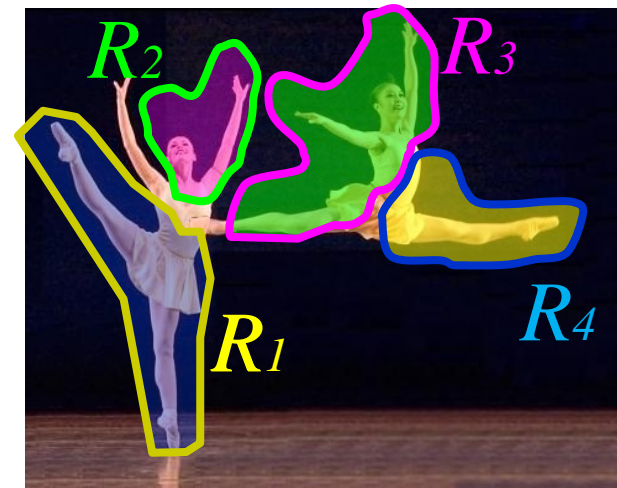
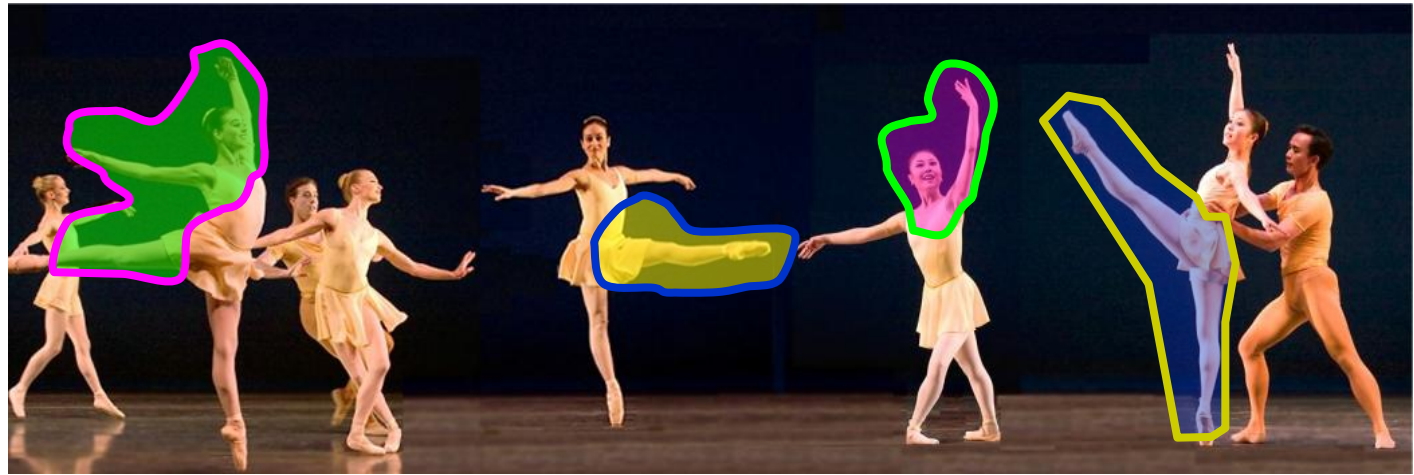
$$= \sum_{d_i \in R} [Err(d_i | codebook) - Err(d_i | I_1, I_2)]$$



I_2

“Affinity by Composition”

I_1



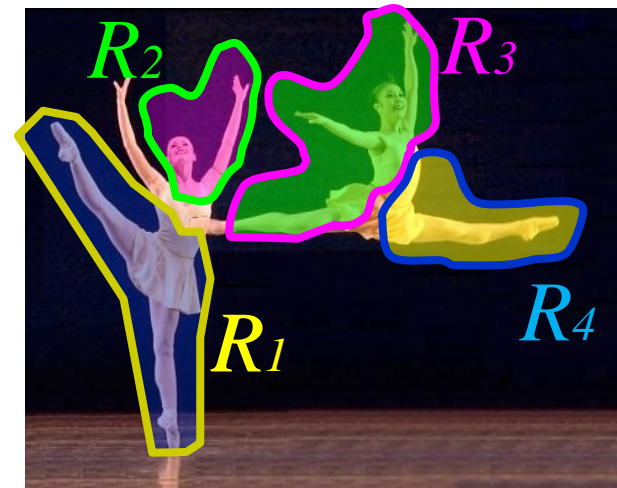
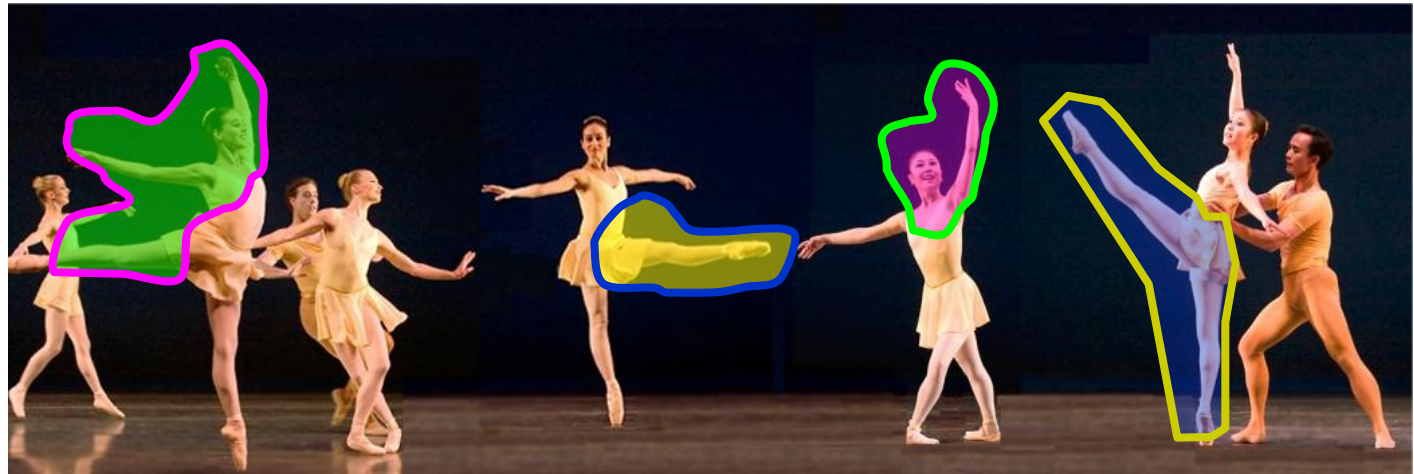
$$\sum_R \log \frac{p(R | I_1, I_2)}{p(R | H_0)}$$

$$= \sum_R \sum_{d_i \in R} [Err(d_i | codebook) - Err(d_i | I_1, I_2)]$$

I_2

"Affinity by Composition"

I_1



$$\text{Affinity}(I_1, I_2) = \sum_R \sum_{d_i \in R} [\text{Err}(d_i | \text{codebook}) - \text{Err}(d_i | I_1, I_2)]$$

I_2

“Region Match”

Using Randomized Search



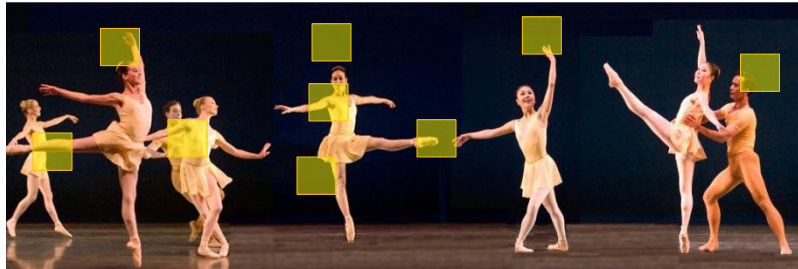
Extending “Patch Match”

[Barnes et al 2009]



“Region Match”

Using Randomized Search



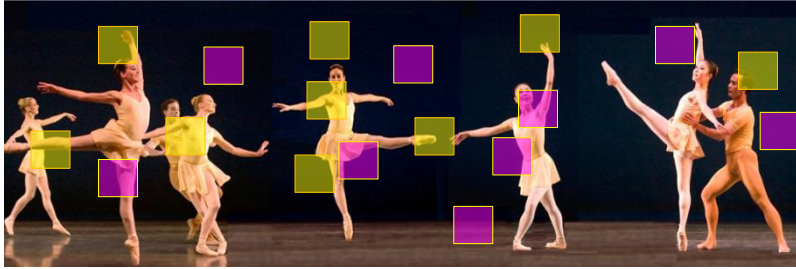
Extending “Patch Match”

[Barnes et al 2009]



“Region Match”

Using Randomized Search



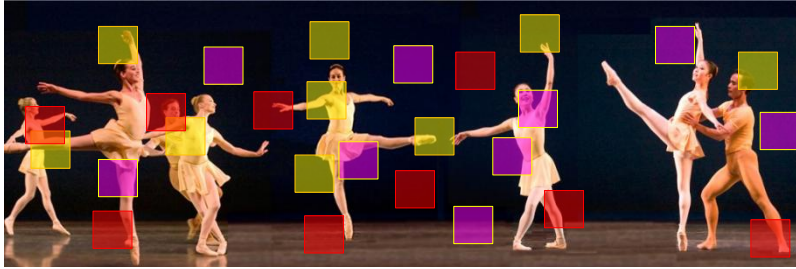
Extending “Patch Match”

[Barnes et al 2009]



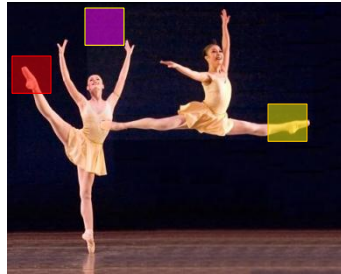
“Region Match”

Using Randomized Search



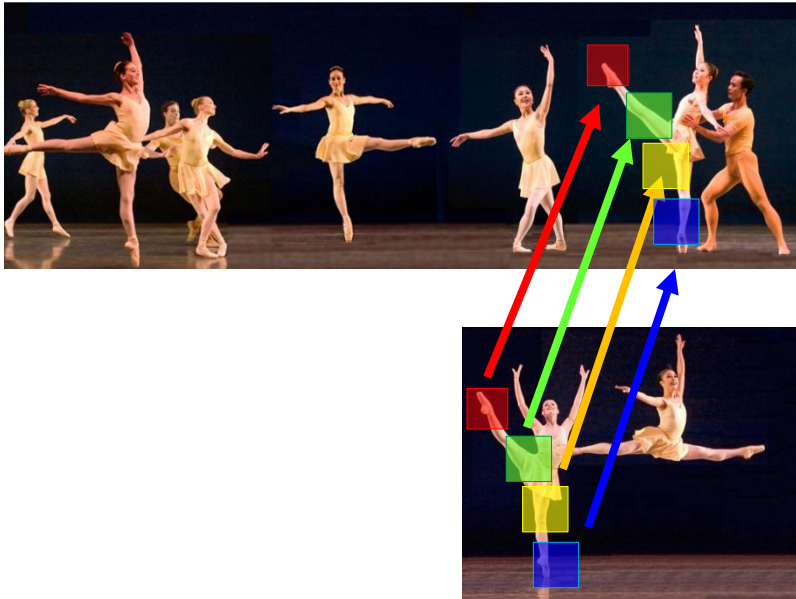
Extending “Patch Match”

[Barnes et al 2009]



“Region Match”

Using Randomized Search



Extending “Patch Match”

[Barnes et al 2009]

“Region Match”

Using Randomized Search

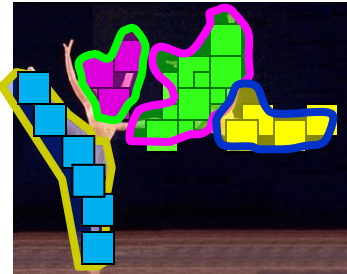
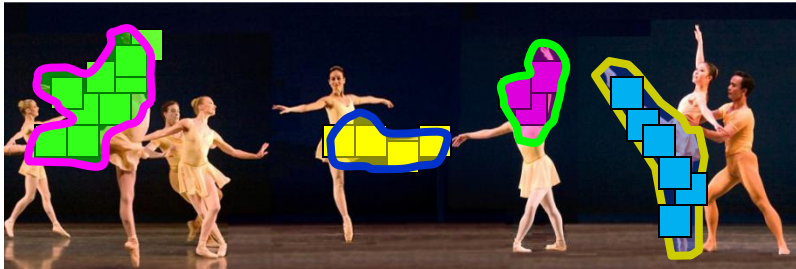


Coherently mapped descriptors
→ *Large shared regions*



“Region Match”

Using Randomized Search



CLAIM: *40 samples per descriptor*

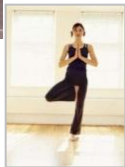
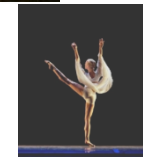
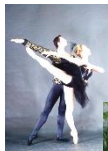
*Find shared regions $|R| \geq 10\%$
with very high probability $\geq 98\%$*

\rightarrow linear complexity $O(n)$

Explicit segmentation \rightarrow NO NEED !

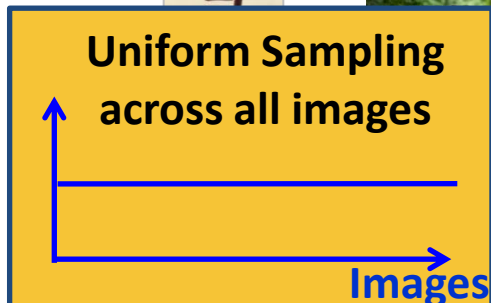
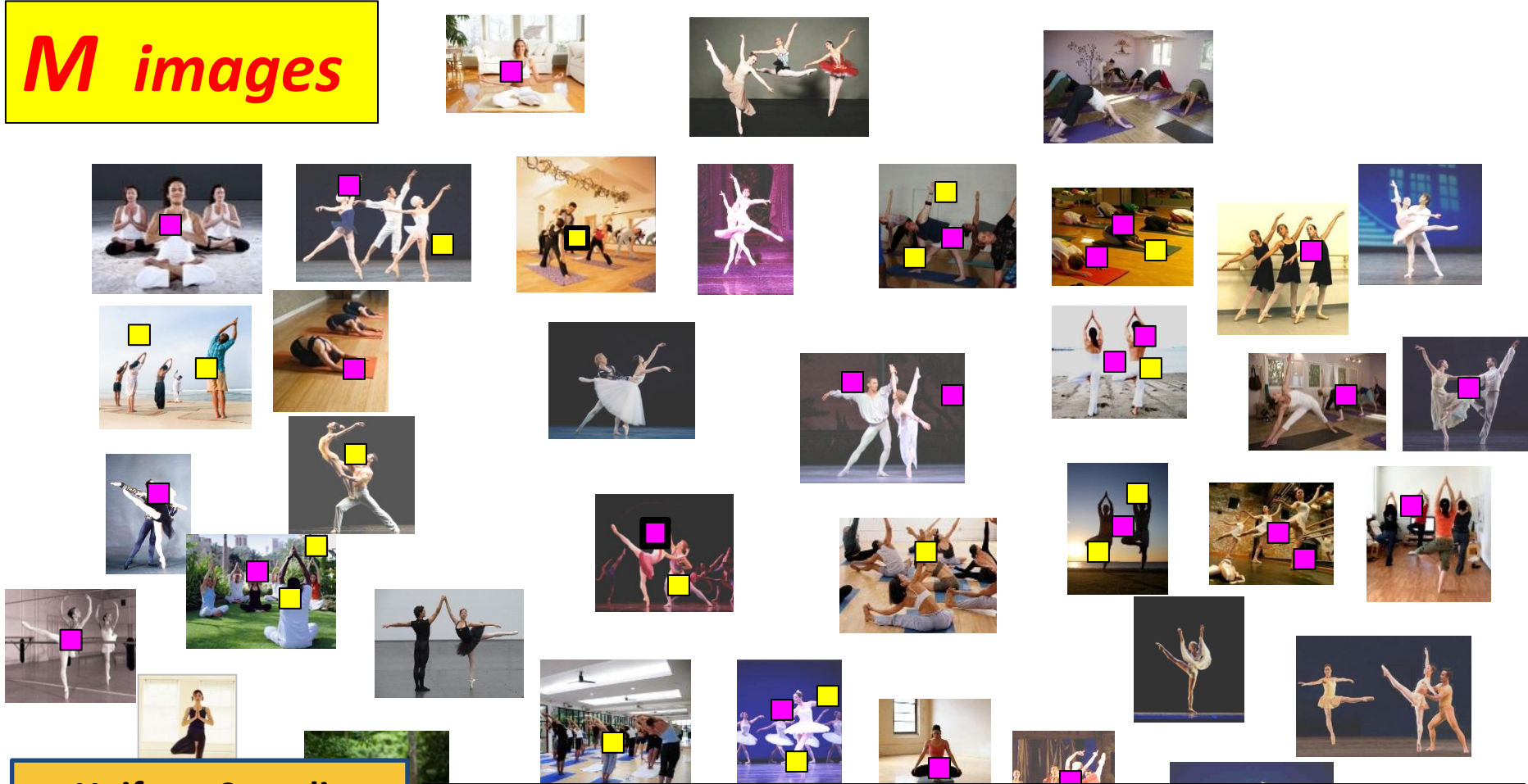
Going back to our Clustering problem...

M images



Going back to our Clustering problem...

M images

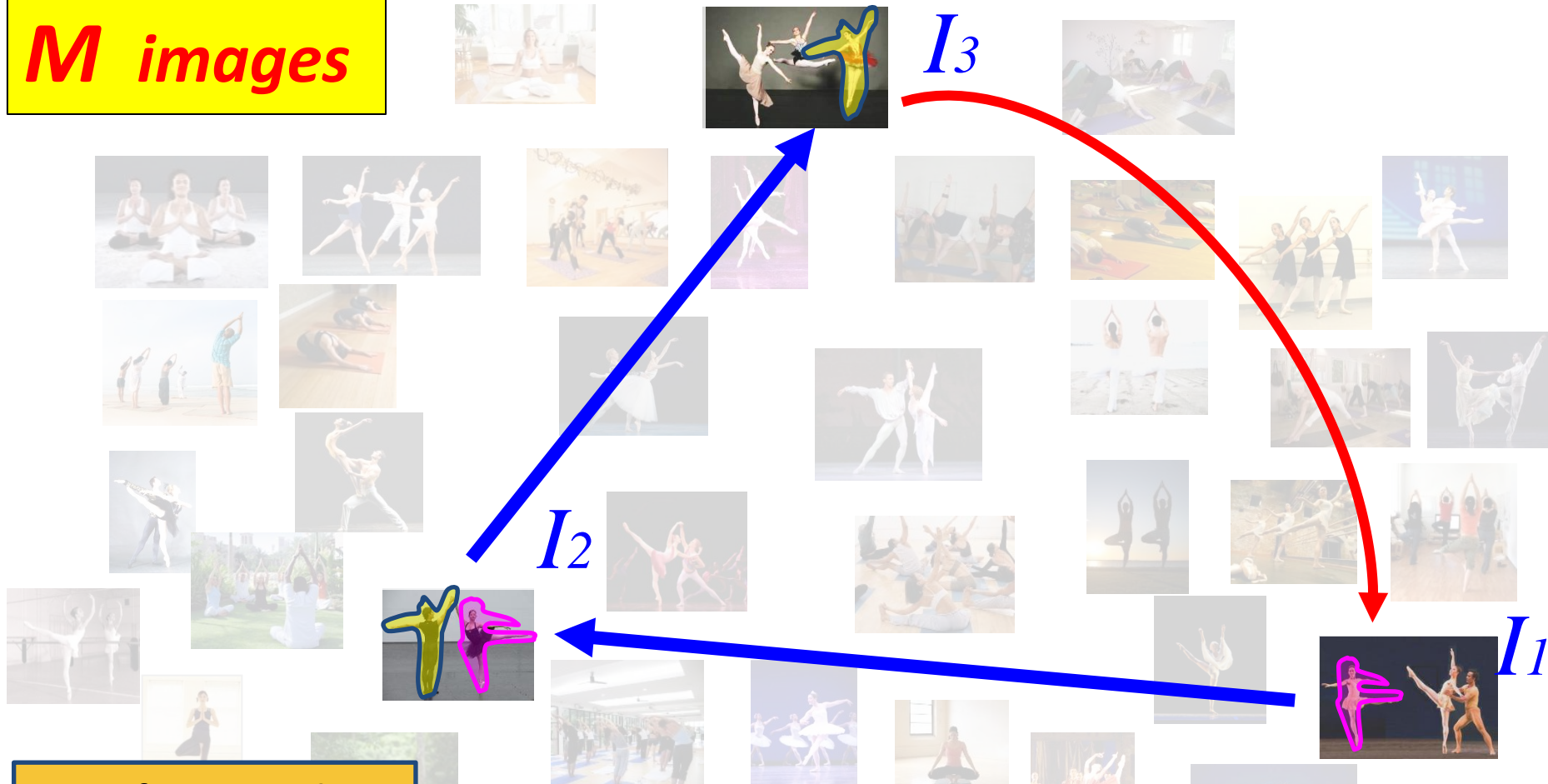


**CLAIM: 40 samples per descriptor
regardless of # images**

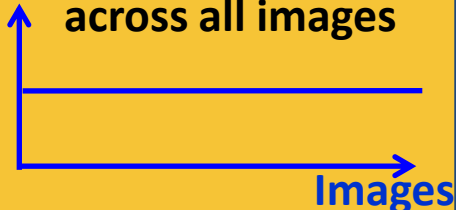
➔ At least one strong connection per image

Going back to our Clustering problem...

***M* images**



Uniform Sampling
across all images

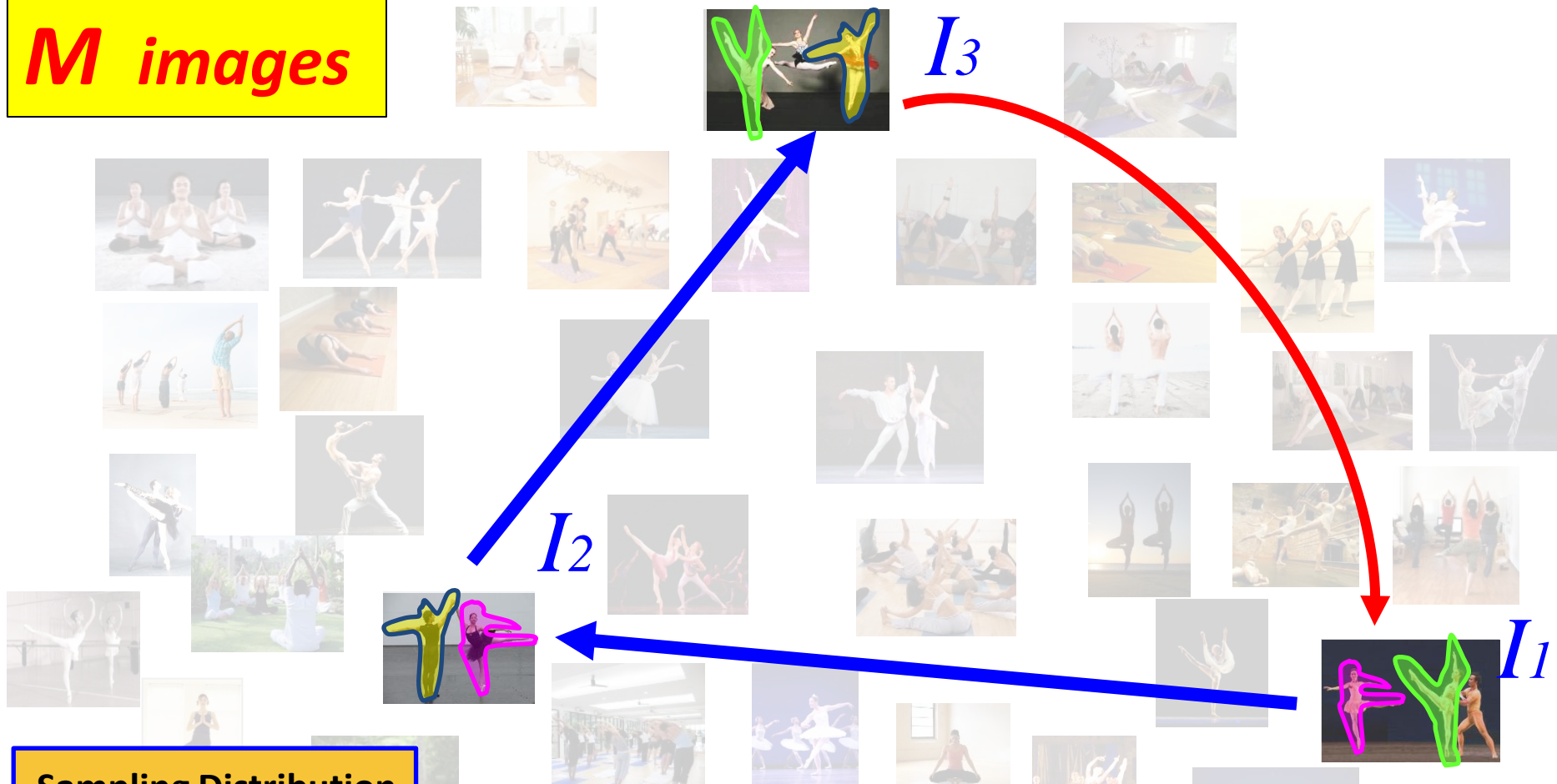


CLAIM: 40 samples per descriptor
regardless of # images

➔ At least one strong connection per image

Going back to our Clustering problem...

M images



Sampling Distribution

Guided sampling

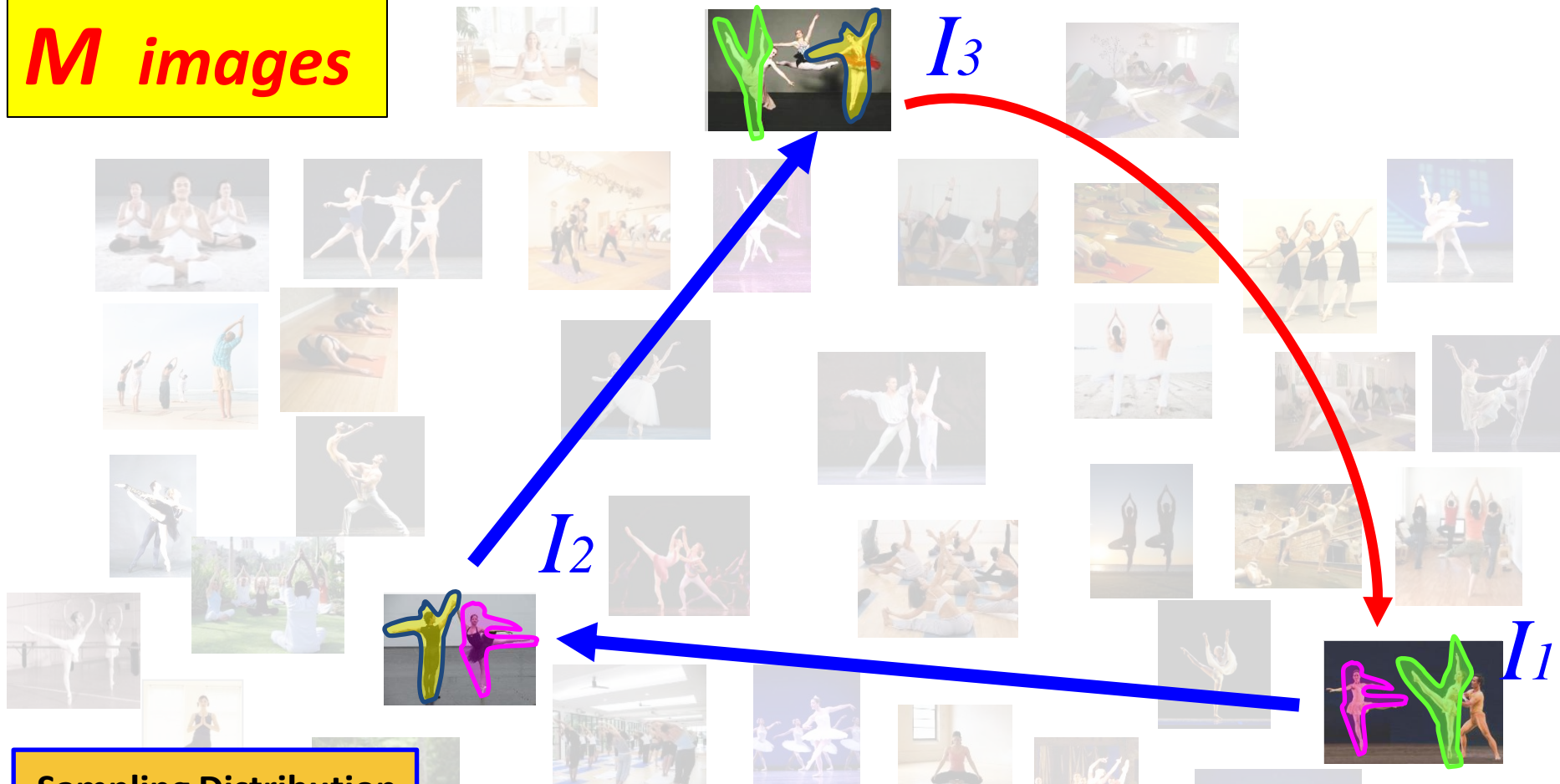


Image collaboration

- ➔ Sparse set of meaningful affinities
- ➔ Linear complexity (in size of dataset)

Going back to our Clustering problem...

M images



Sampling Distribution

Guided sampling



“Wisdom of crowds of images”

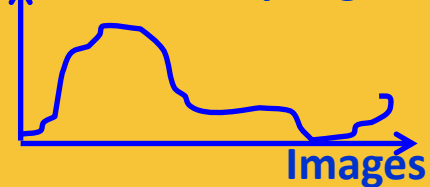
- ➔ Sparse set of meaningful affinities
- ➔ Linear complexity (in size of dataset)

Our Full Clustering Algorithm

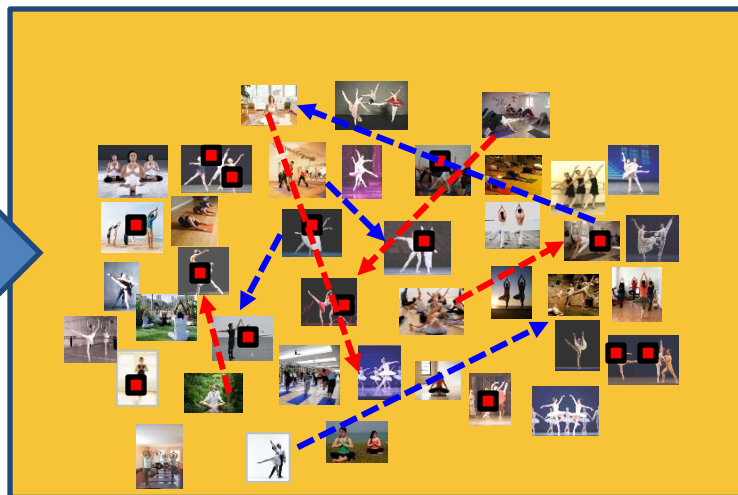
Sparse set of
meaningful affinities

Sampling Distribution

Guided sampling



Images



Update
Affinity Matrix

Normalized
Cuts

Update sampling distribution
“Wisdom of crowds of images”

Experiments

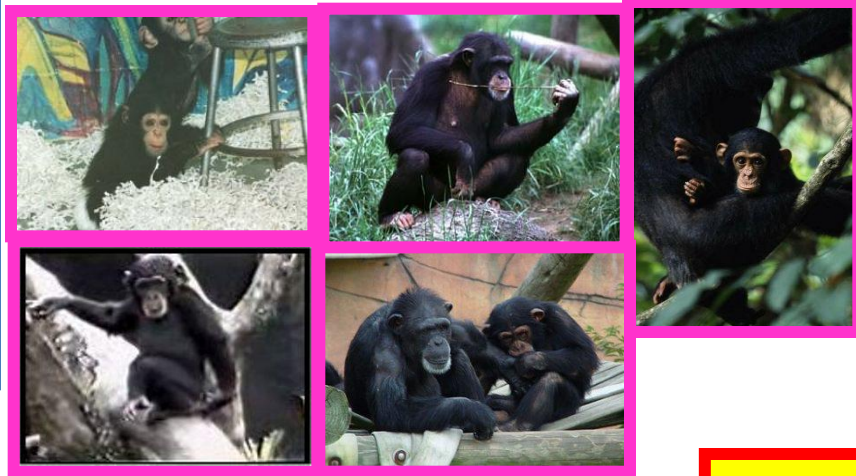
- *Comparisons on Benchmark Datasets (Caltech, ETHZ)*
 - ➔ Significant improvement over *state-of-the-art*
(up to 30%)
- *Experiments on more challenging datasets*
 - ➔ Tiny datasets
 - ➔ PASCAL-VOC

Experiments on Tiny Dataset

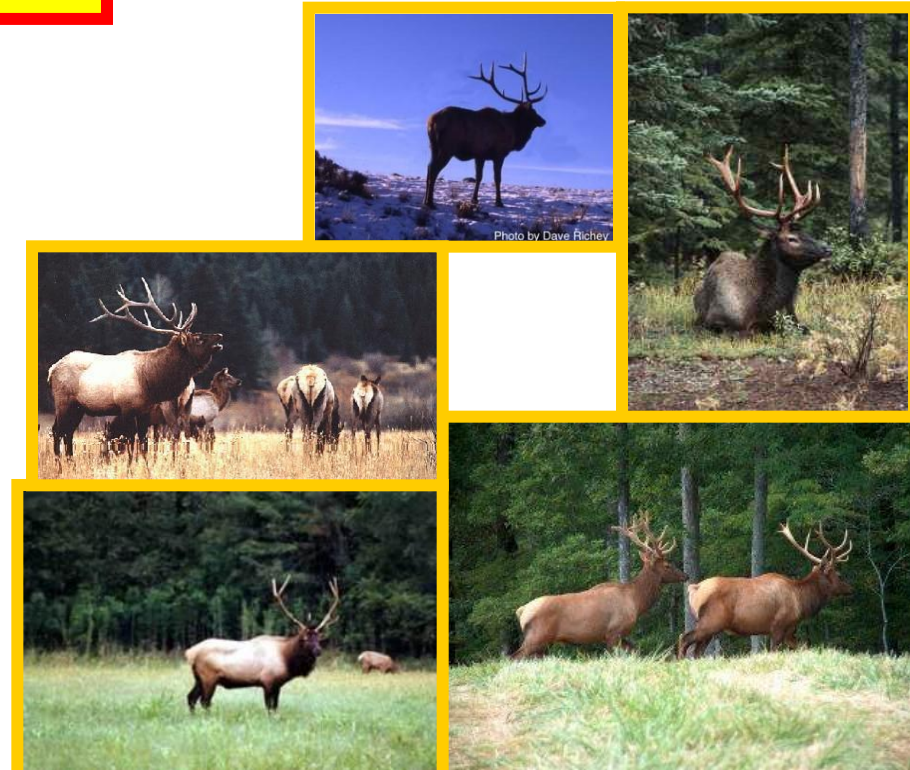
20 images (4 classes)



Experiments on Tiny Dataset



Purity = 100%



Experiments on Tiny Dataset

Statistically Significant Descriptors

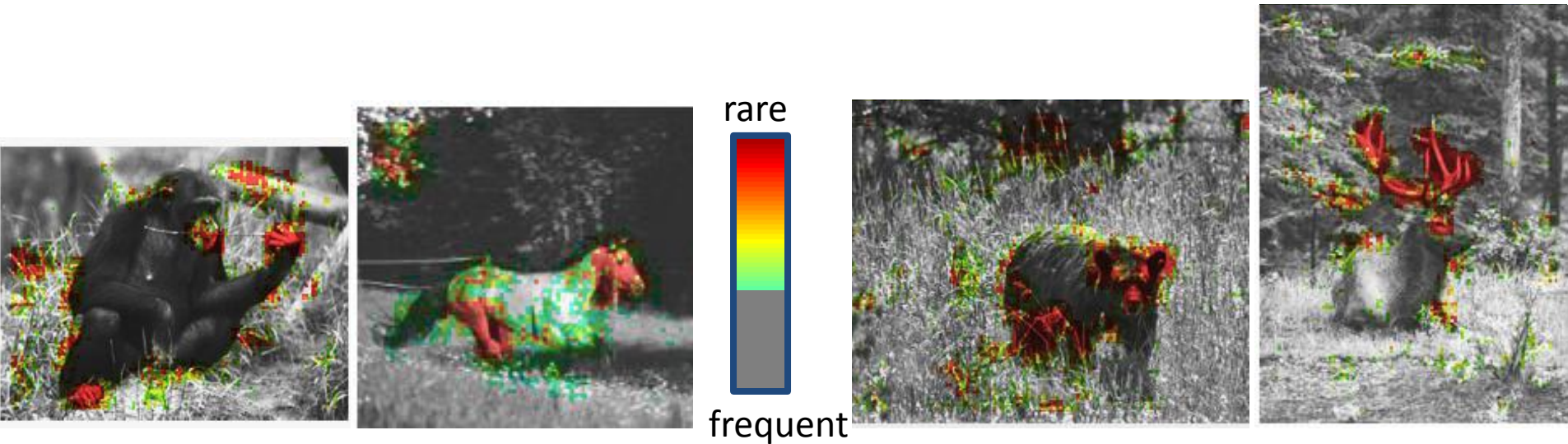
$$-\log p(d_i | H_0) \approx \text{Err}(d_i | \text{Codebook})$$



Experiments on Tiny Dataset

Statistically Significant Descriptors

$$-\log p(d_i | H_0) \approx \text{Err}(d_i | \text{Codebook})$$



The statistically significant descriptors → on the animals!

PASCAL subset (4 classes)

CARS, BICYCLES, CHAIRS, HORSES



PASCAL subset (4 classes)

CARS, BICYCLES, HORSES, CHAIRS



Thank you!

1. “Affinity by composition”

→ Look for RARE shared regions

2. Codebook Quantization Error

→ Estimate how rare a region is.

3. Randomized search using the “Wisdom of Crowds of images”

→ Find shared regions

→ Linear complexity

4. State of the art results

- Benchmark datasets
- New challenging datasets

