

Photo Sequencing

Tali Basha

Yael Moses

Shai Avidan



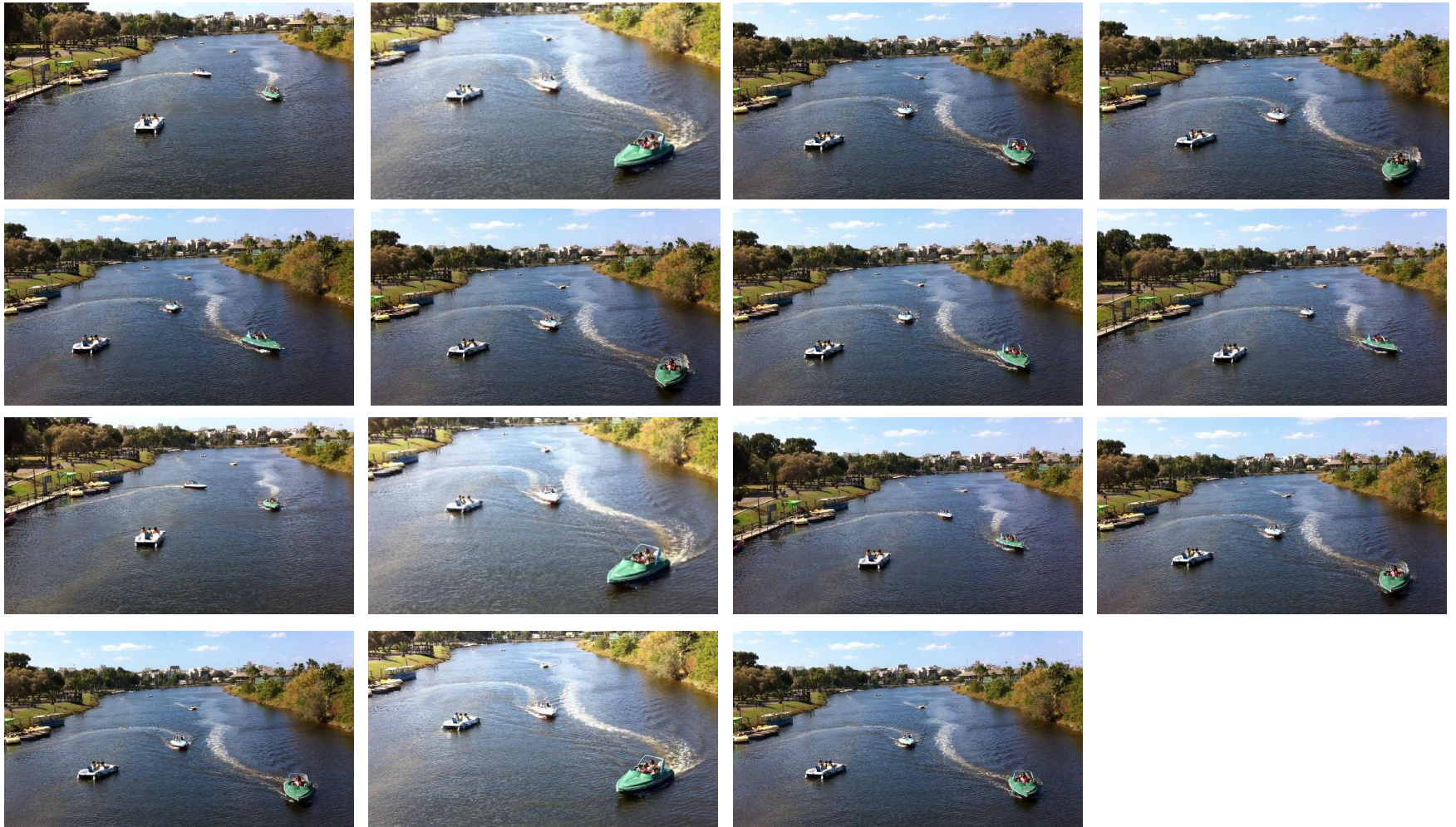
ECCV2012

Tel Aviv



The Input

N images taken from **different** locations at **different** time steps



Random Order



Our Result



But Who Cares?

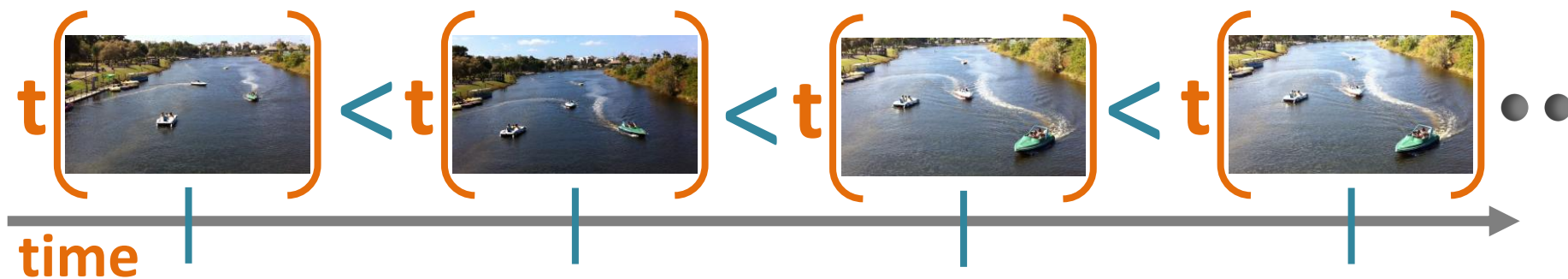


- Capturing the highlights of a **dynamic** event
- Analyzing/Visualizing the **dynamic** content using **still** images

Photo Sequencing

Problem definition:

Given N still images, determine their temporal order:



$N!$ possible permutations...

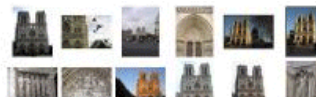
$15! \sim 10^{12}$

Photo Sequencing is **Not** ...

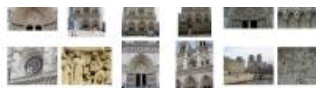
Video Synchronization



Photo Tourism



Static



4D City Reconstruction



years

Inferring Temporal Order of Images From 3D Structure,
Schindler at al., CVPR 2007

Assumptions

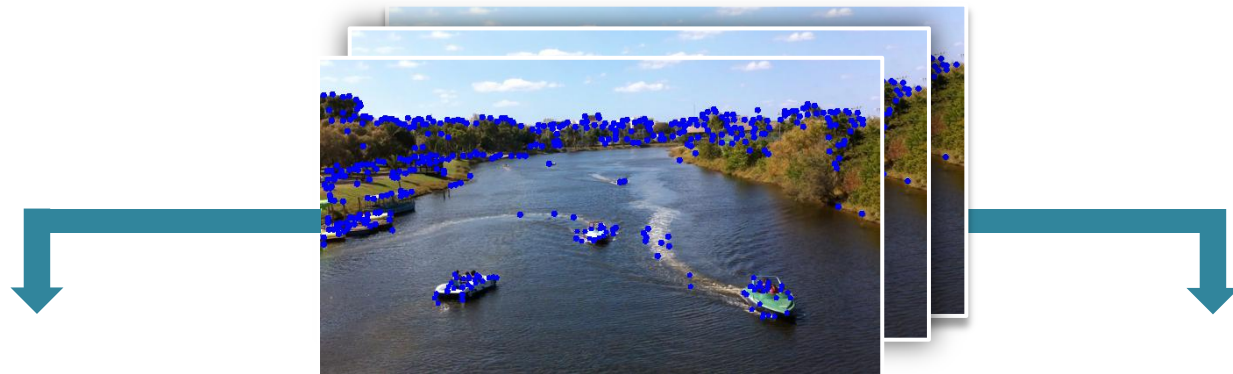
Short time interval



Two images taken roughly from the same position

Static & Dynamic Features

Detect features & match to the reference



Static Features

Dynamic Features



Epipolar Geometry

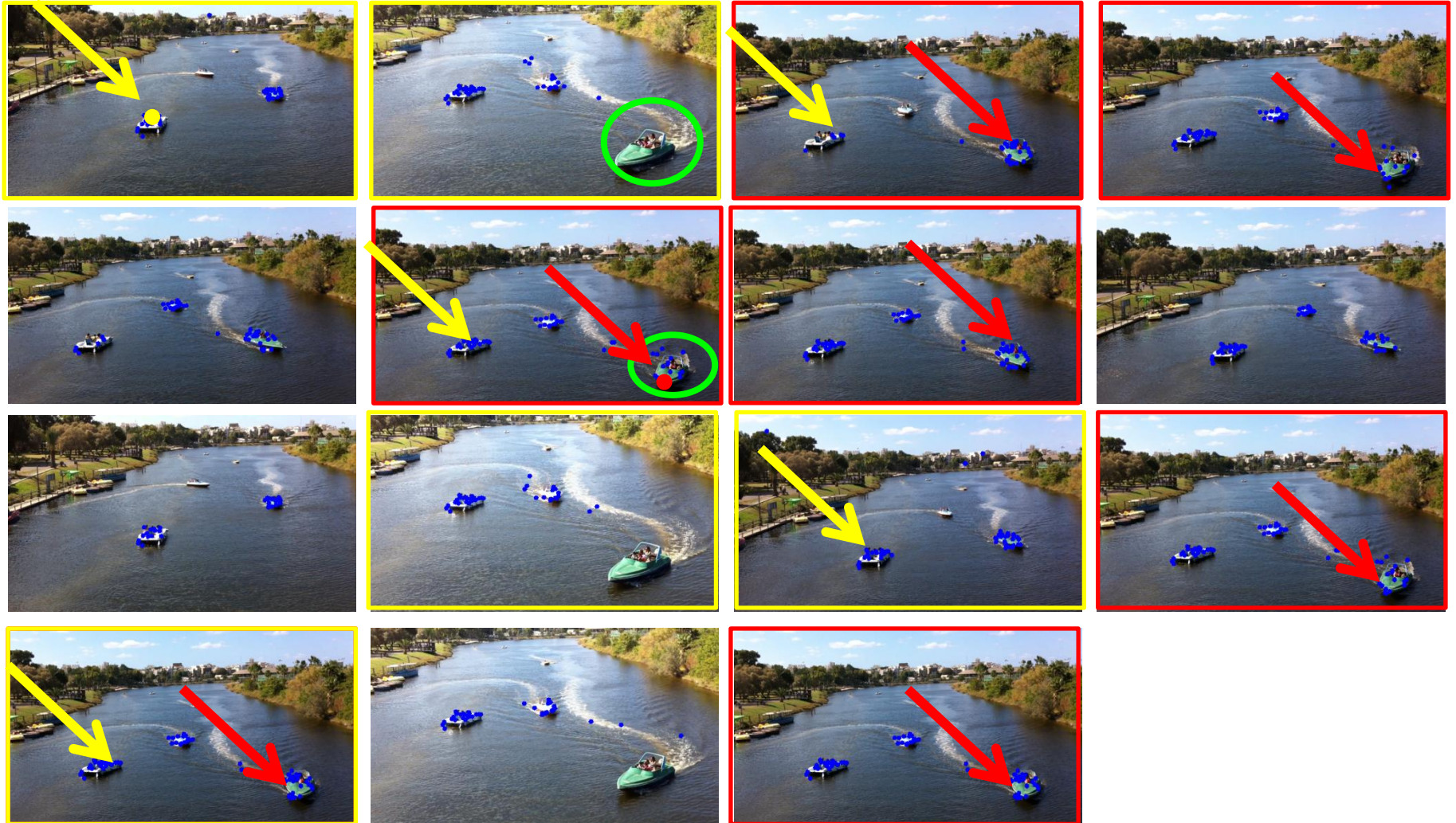
Fundamental matrices w.r.t.
the reference image



Temporal Order

Provide the temporal
information

Dynamic Features



Algorithm Outline

Dynamic Features

Detect & Match w.r.t the reference



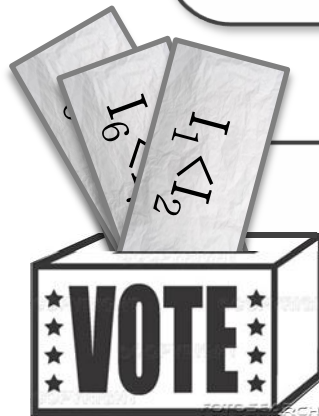
Partial Order from a Corresponding Dynamic Features



Based on Epipolar Geometry



Aggregate Partial Orders

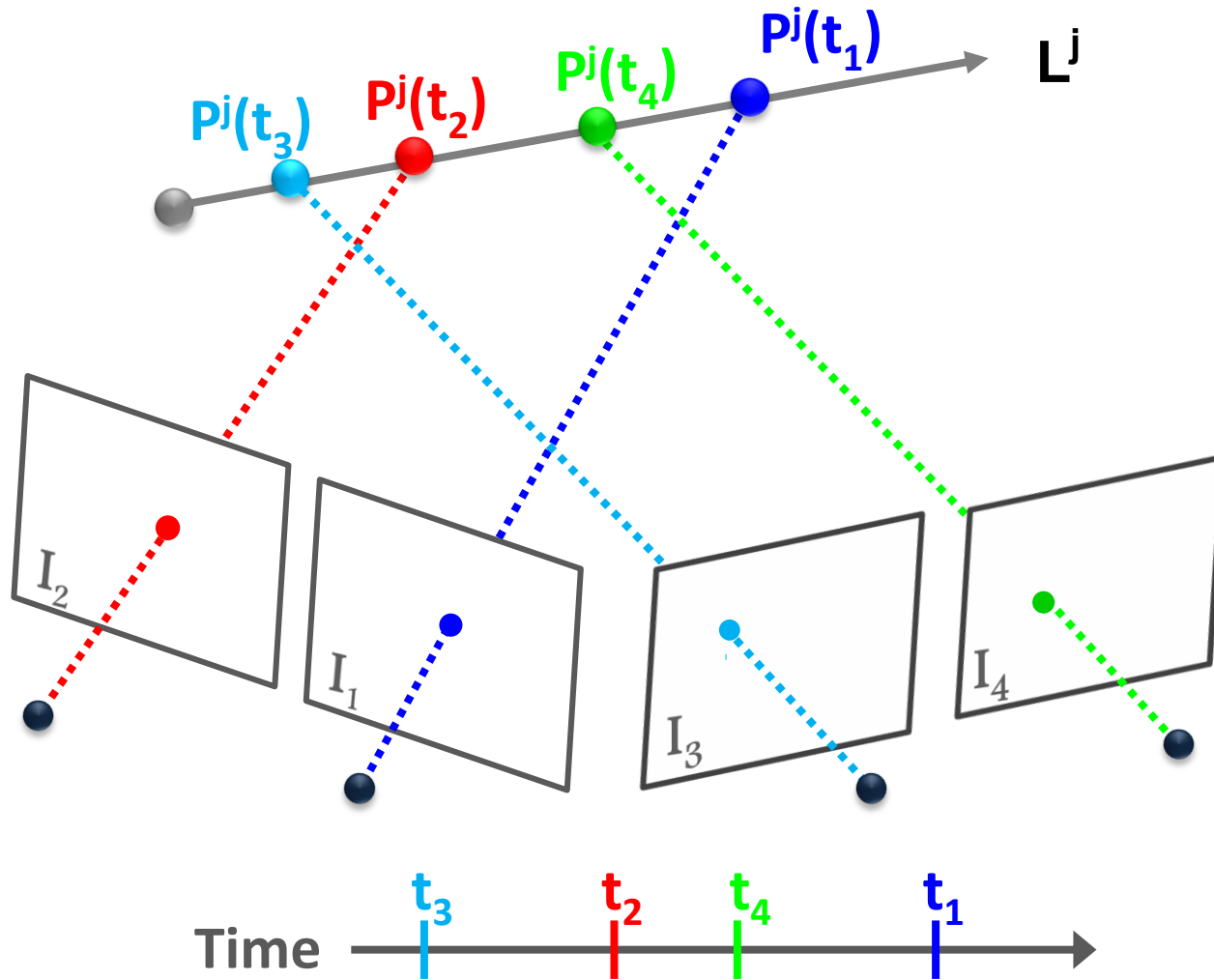


$I_3 < I_5 < I_7 < I_4 < I_1 < I_2$

Rank Aggregation Solution

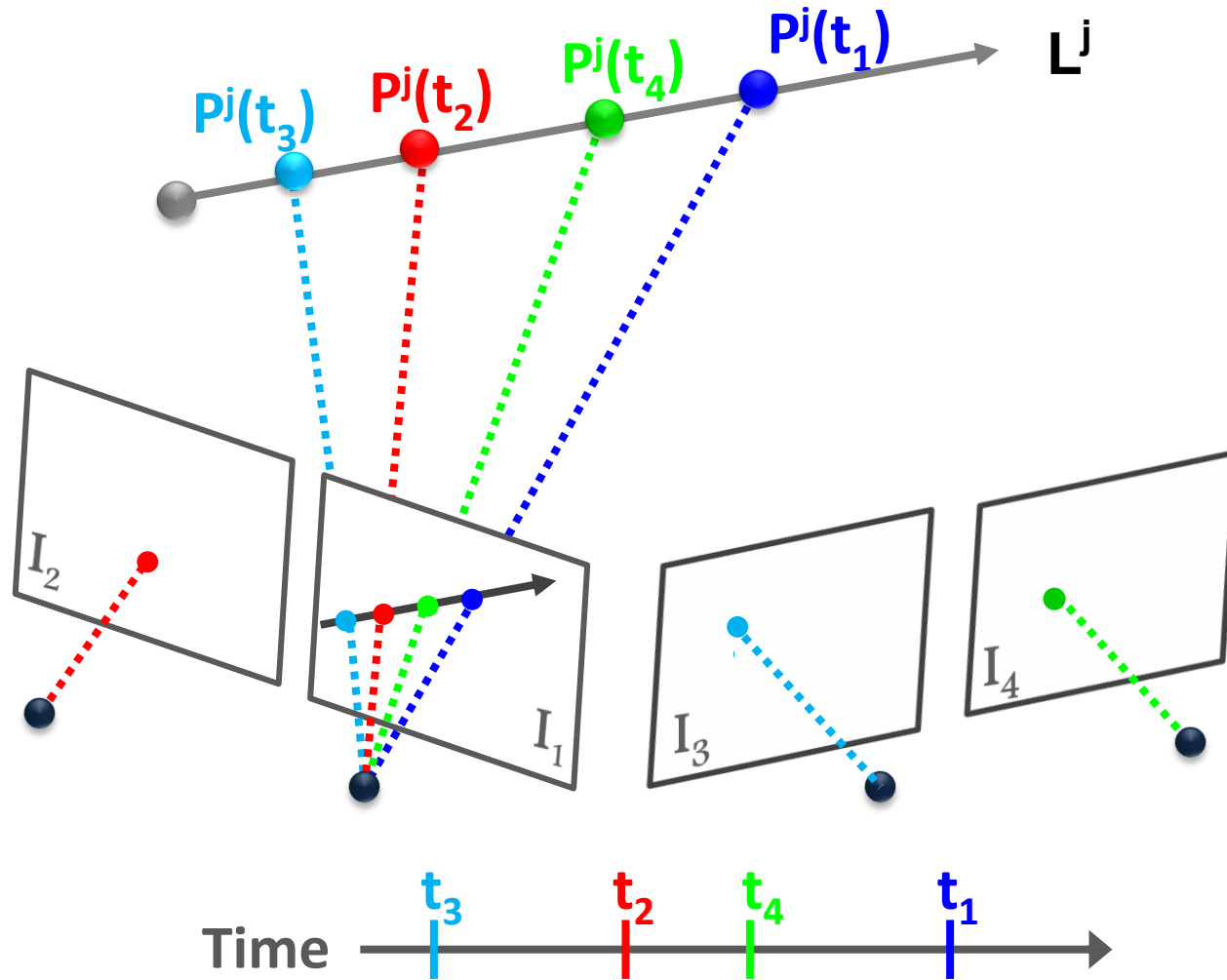
Order from a Single Feature Set

Spatial order in 3D \rightarrow Temporal order



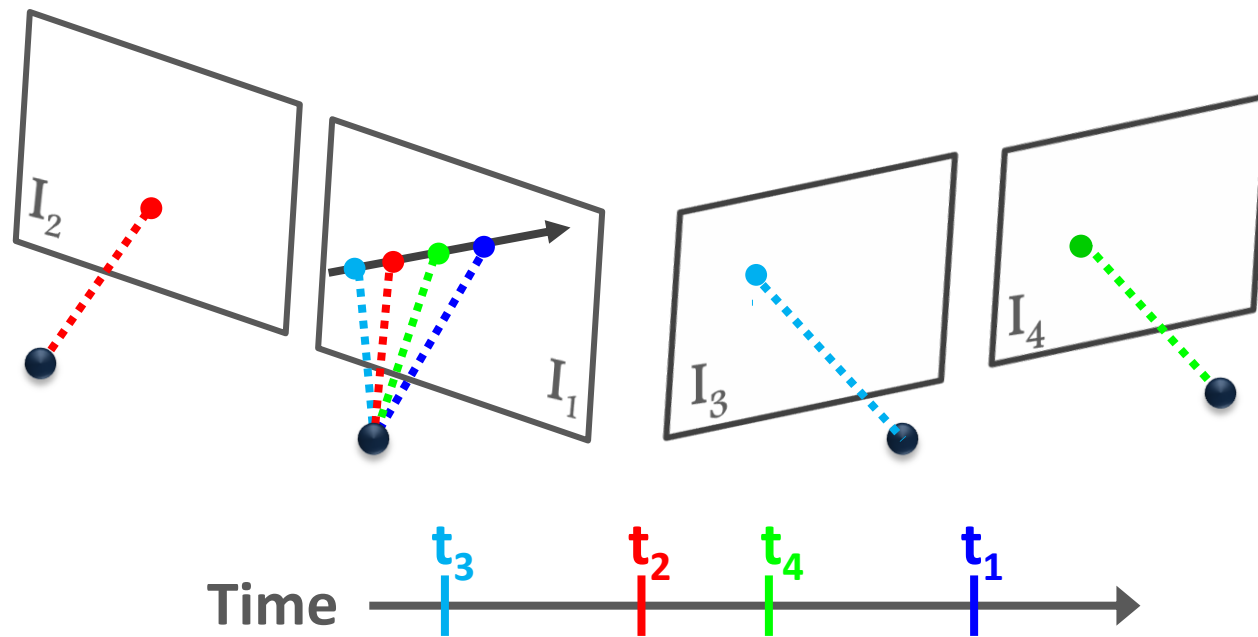
Order from a Single Feature Set

Spatial order in 2D \rightarrow Temporal order

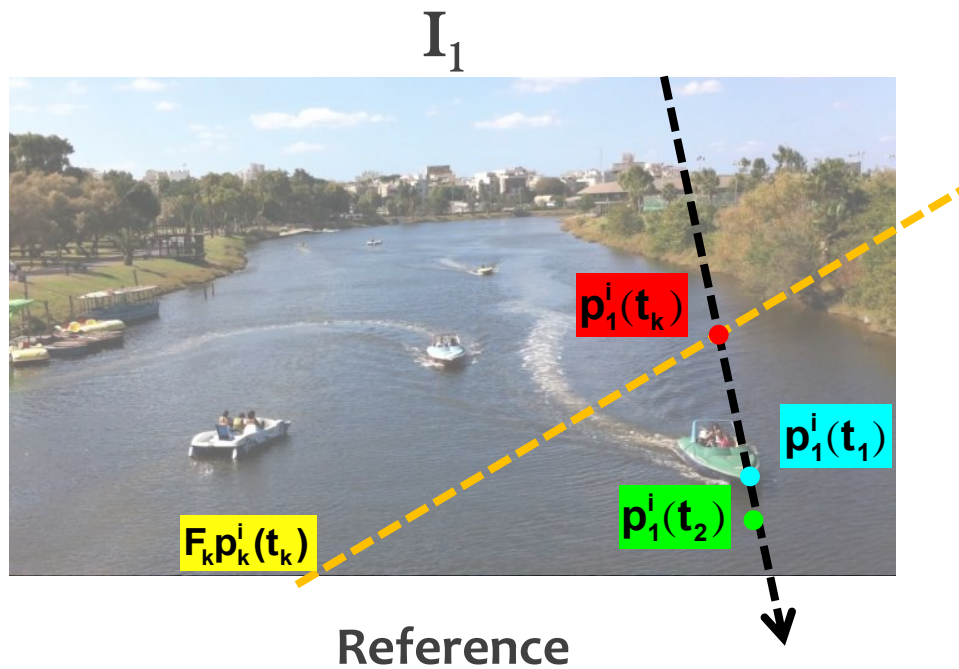


Order from a Single Feature Set

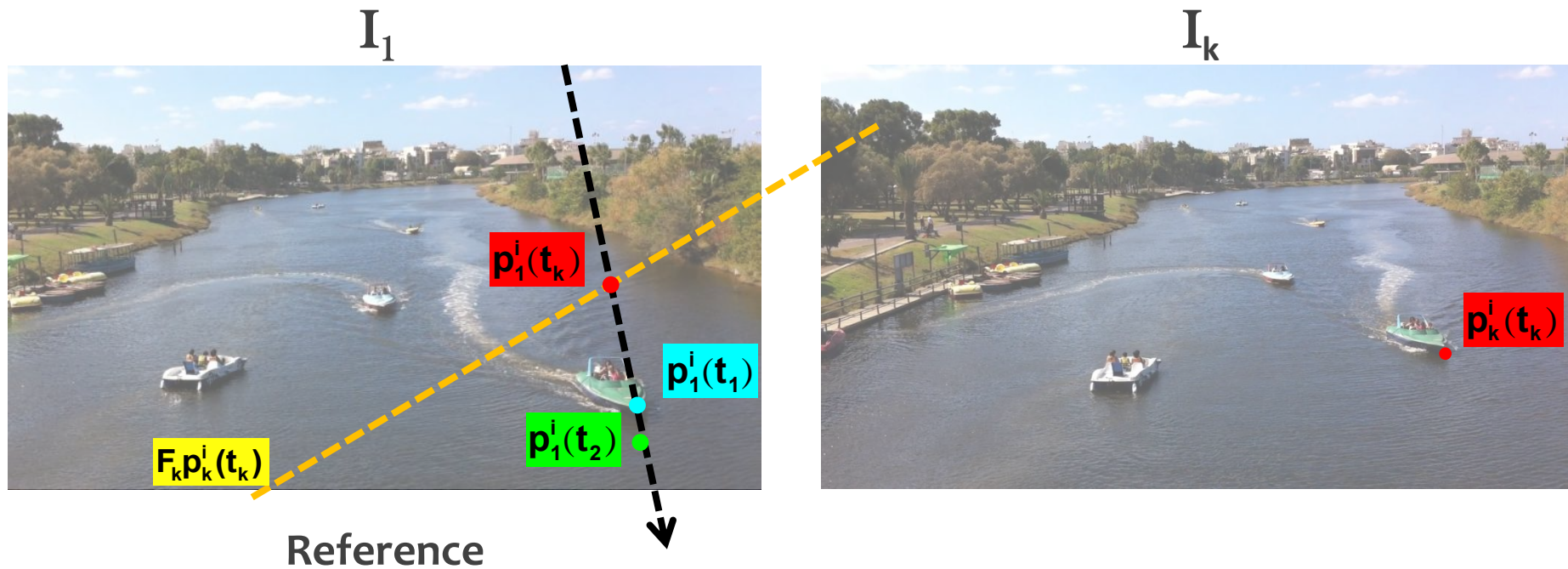
Map all features to the reference image



Mapping to The Reference



Mapping to The Reference



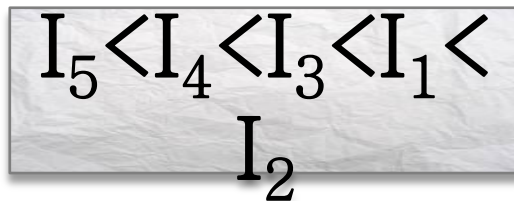
Mapping to The Reference

I_1



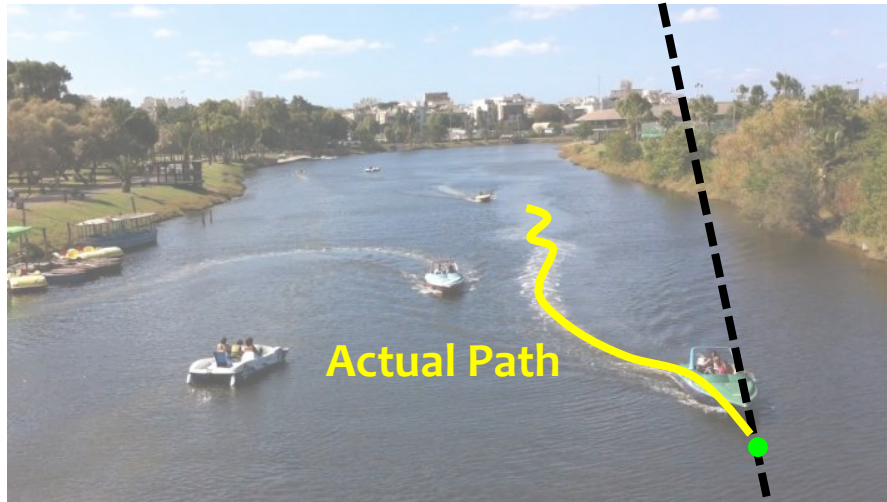
Reference

I_k



Mapping to The Reference

I_1



Actual Path

Reference

I_k



$p_k^i(t_k)$

Algorithm Outline

Dynamic Features

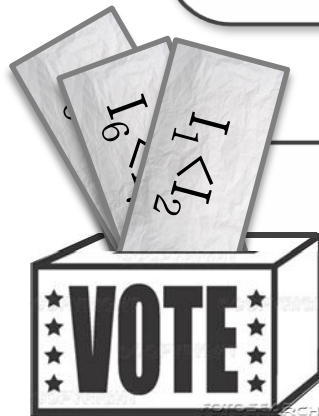
Detect & Match w.r.t the reference



Partial Order from a Corresponding Dynamic Features



Based on Epipolar Geometry

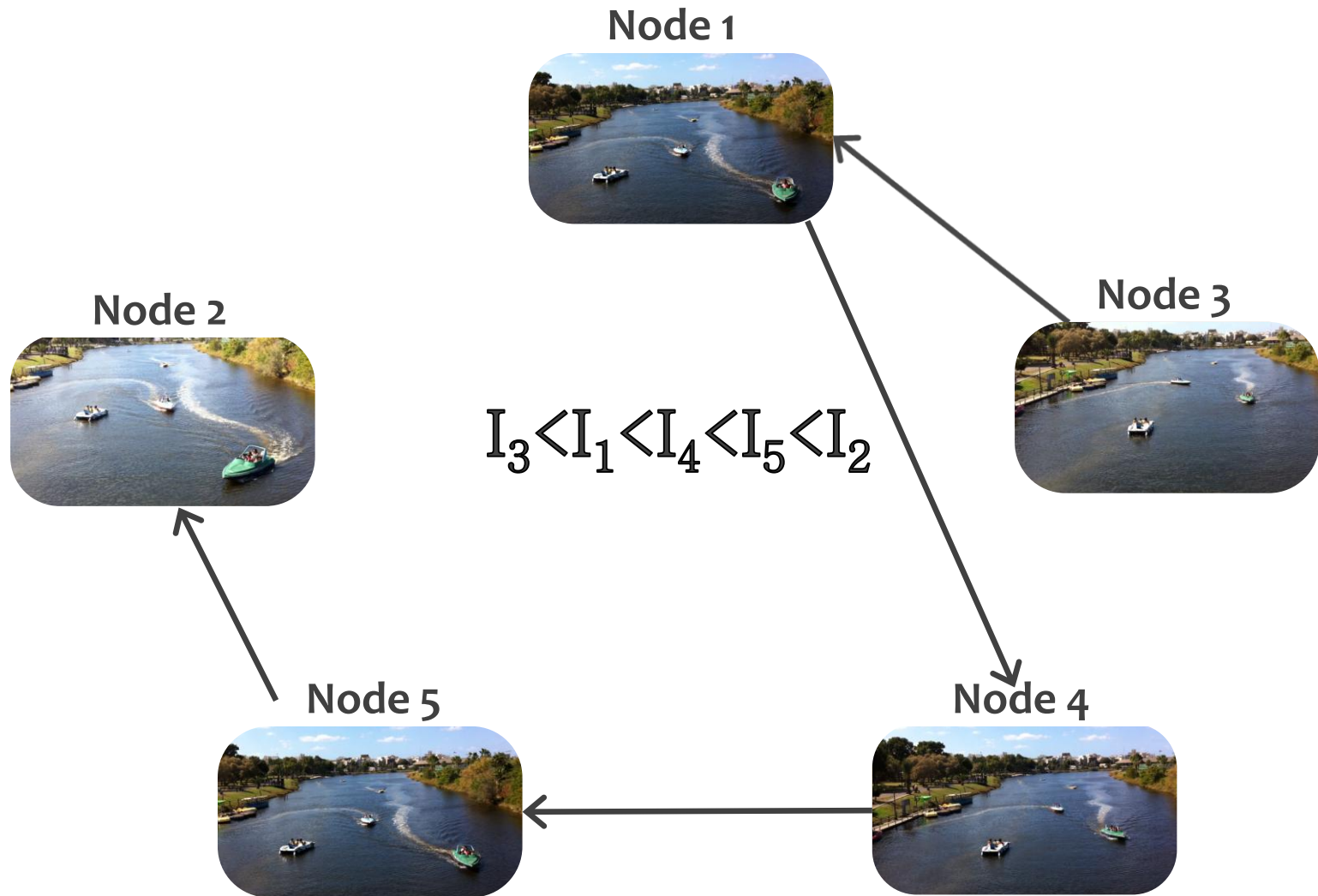


Aggregate Partial Orders

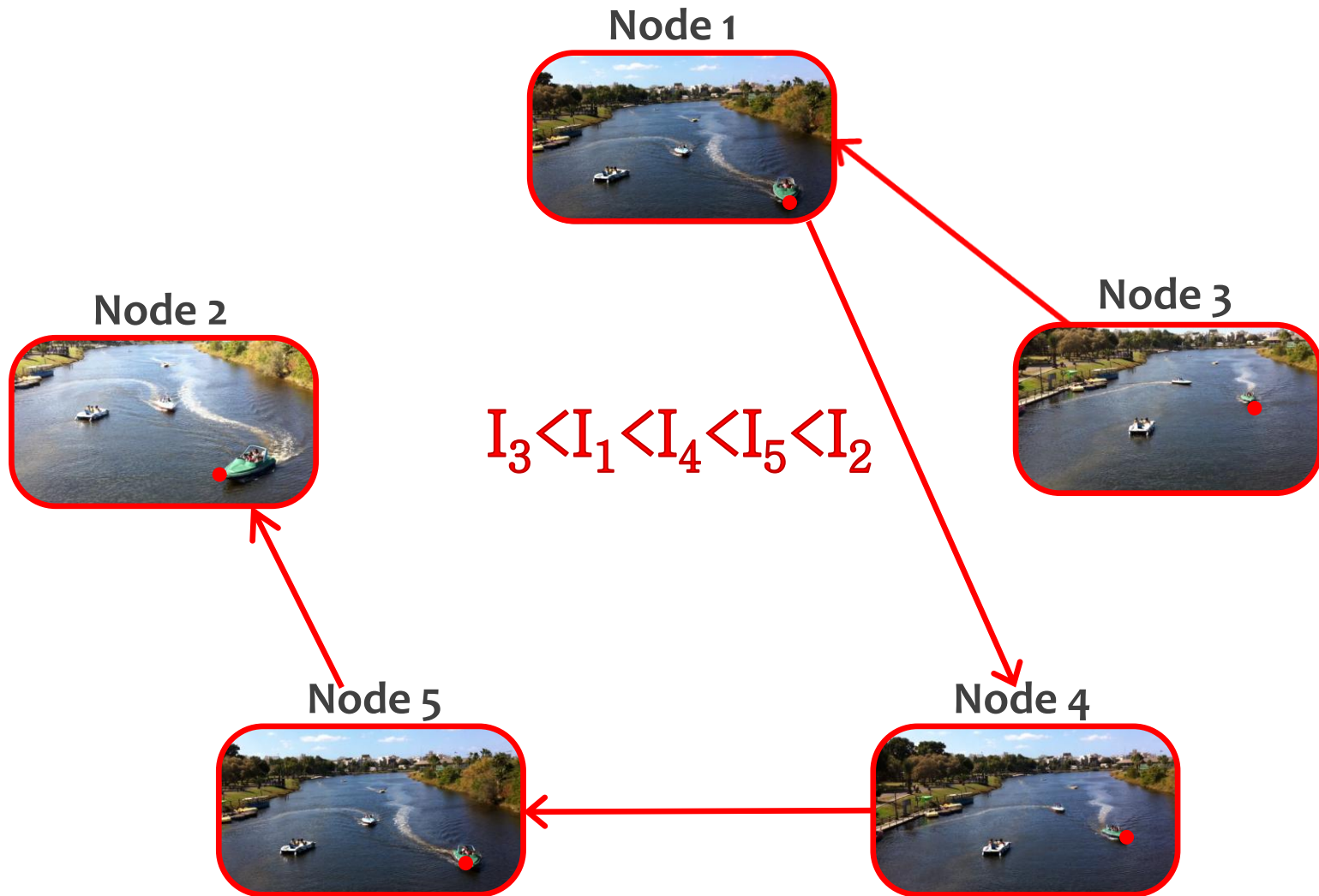
$I_3 < I_5 < I_7 < I_4 < I_1 < I_2$

Rank Aggregation Solution

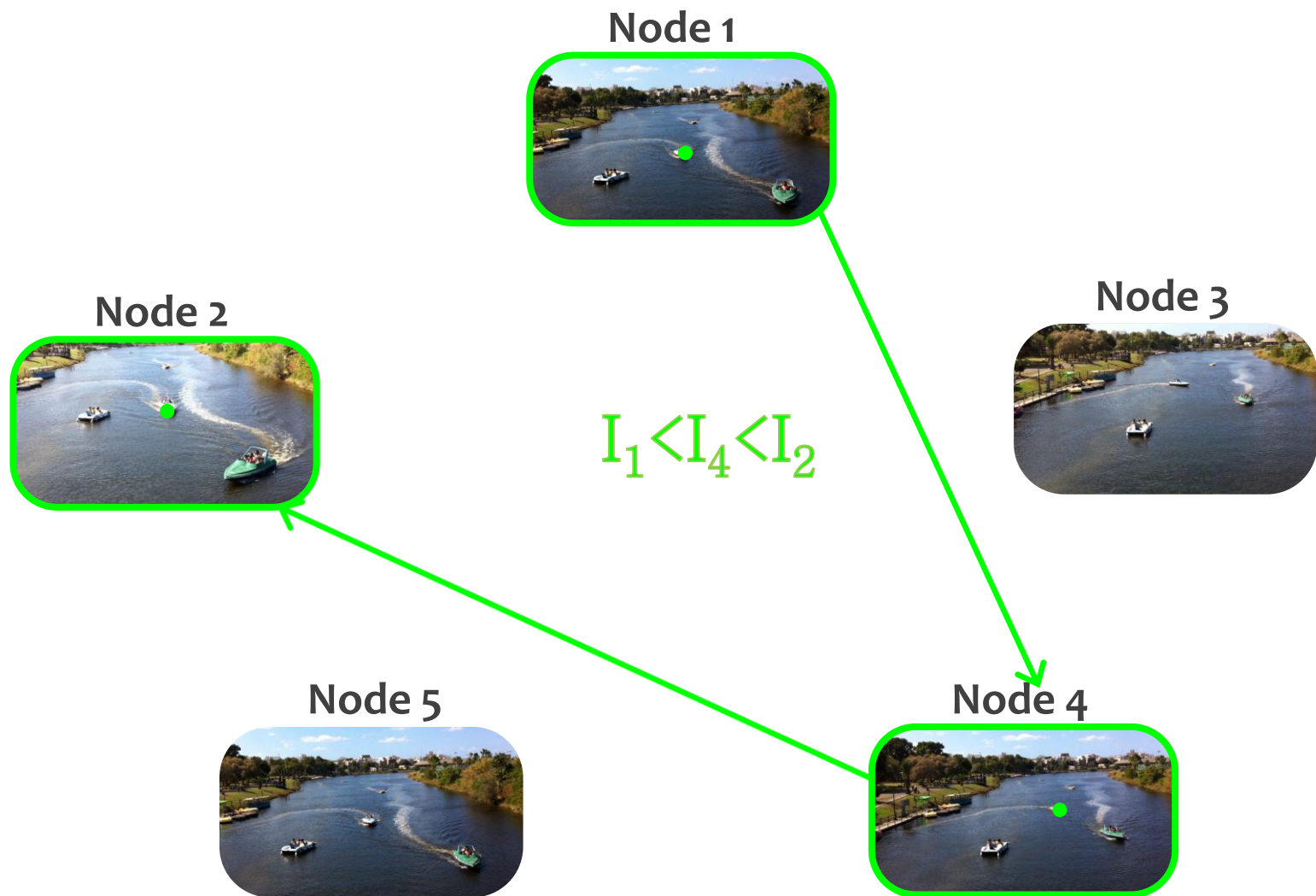
Order Representation



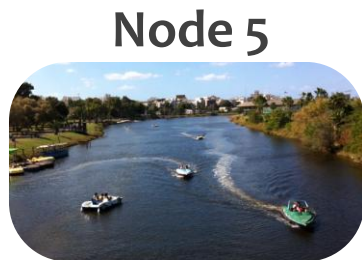
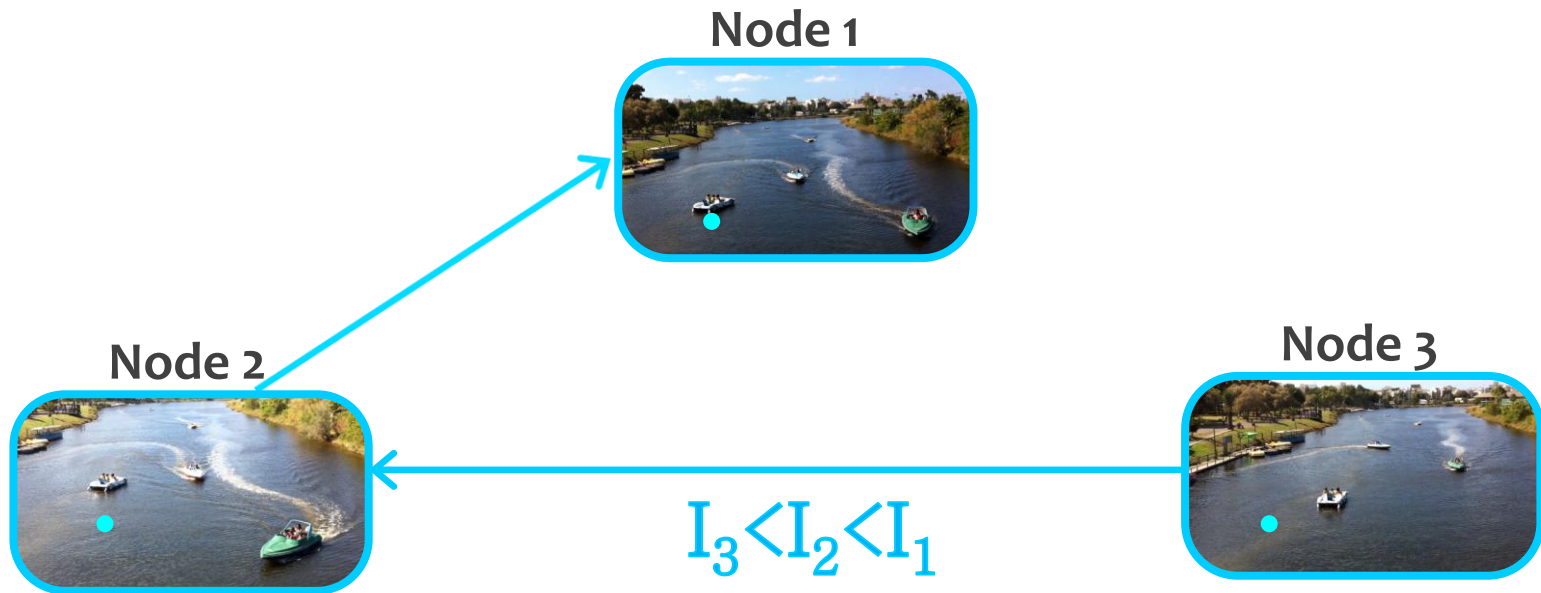
Order Representation



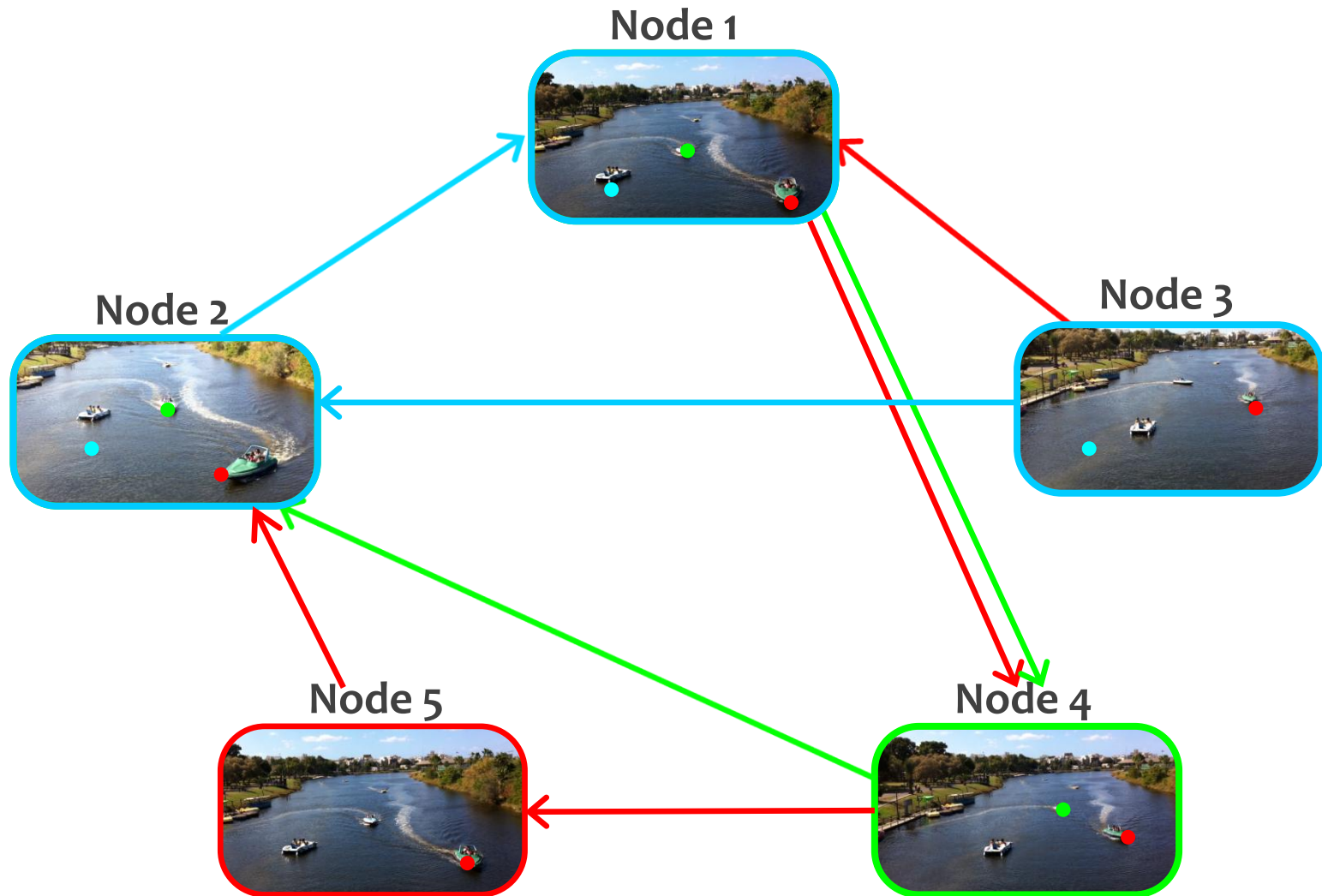
Order Representation



Order Representation

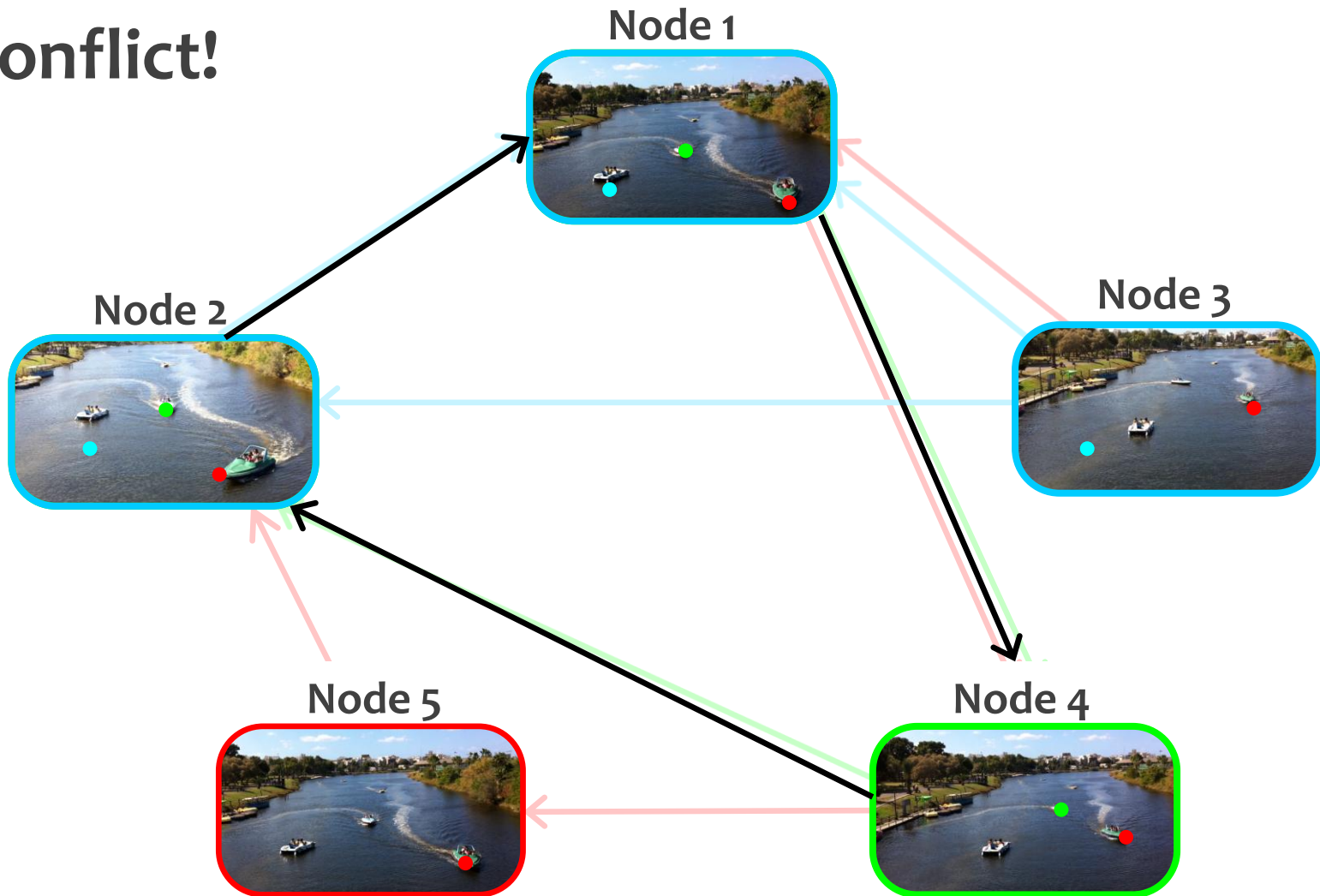


Order Representation



Order Representation

Conflict!

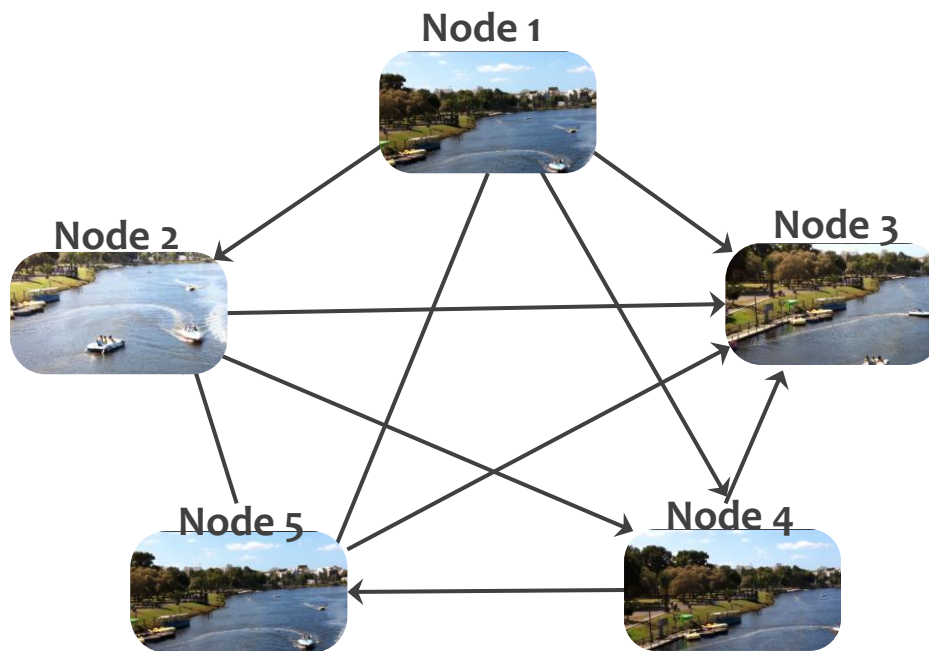


Rank Aggregation

Input: Possibly conflicting partial orders, $\{\sigma_i\}$

Goal: Compute a “consensus” full order, σ :

$$\sigma^* = \underset{\sigma}{\operatorname{argmin}} \sum_i^{N_D} K(\sigma, \sigma_i)$$



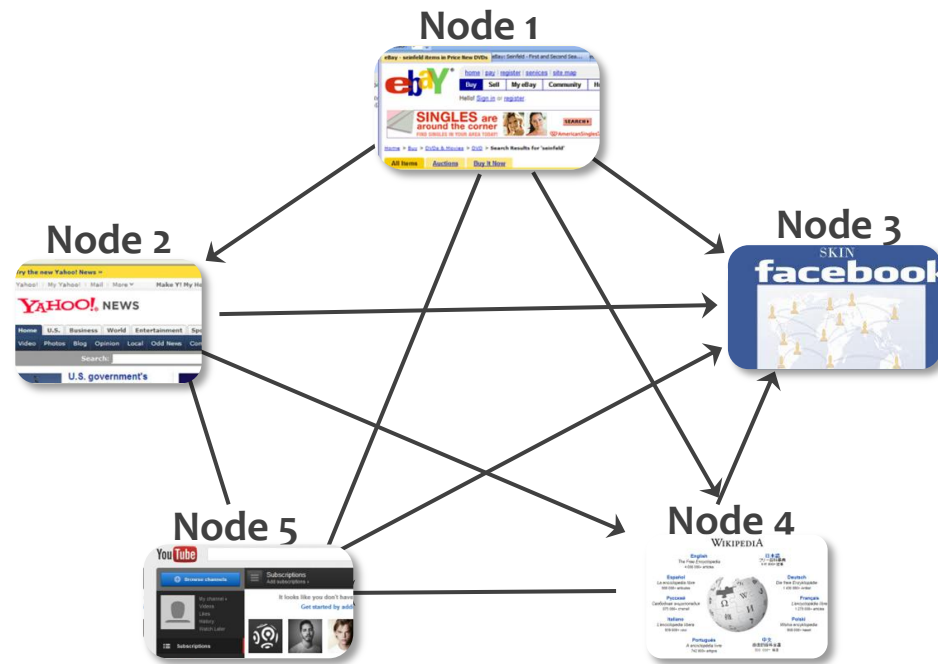
Rank Aggregation

Rank Aggregation Methods for The Web, Dwork et al. 2001

Markov Chain Approximation

$$\sigma^* = \operatorname{argmin}_{\sigma} \sum_i^{N_D} K(\sigma, \sigma_i)$$

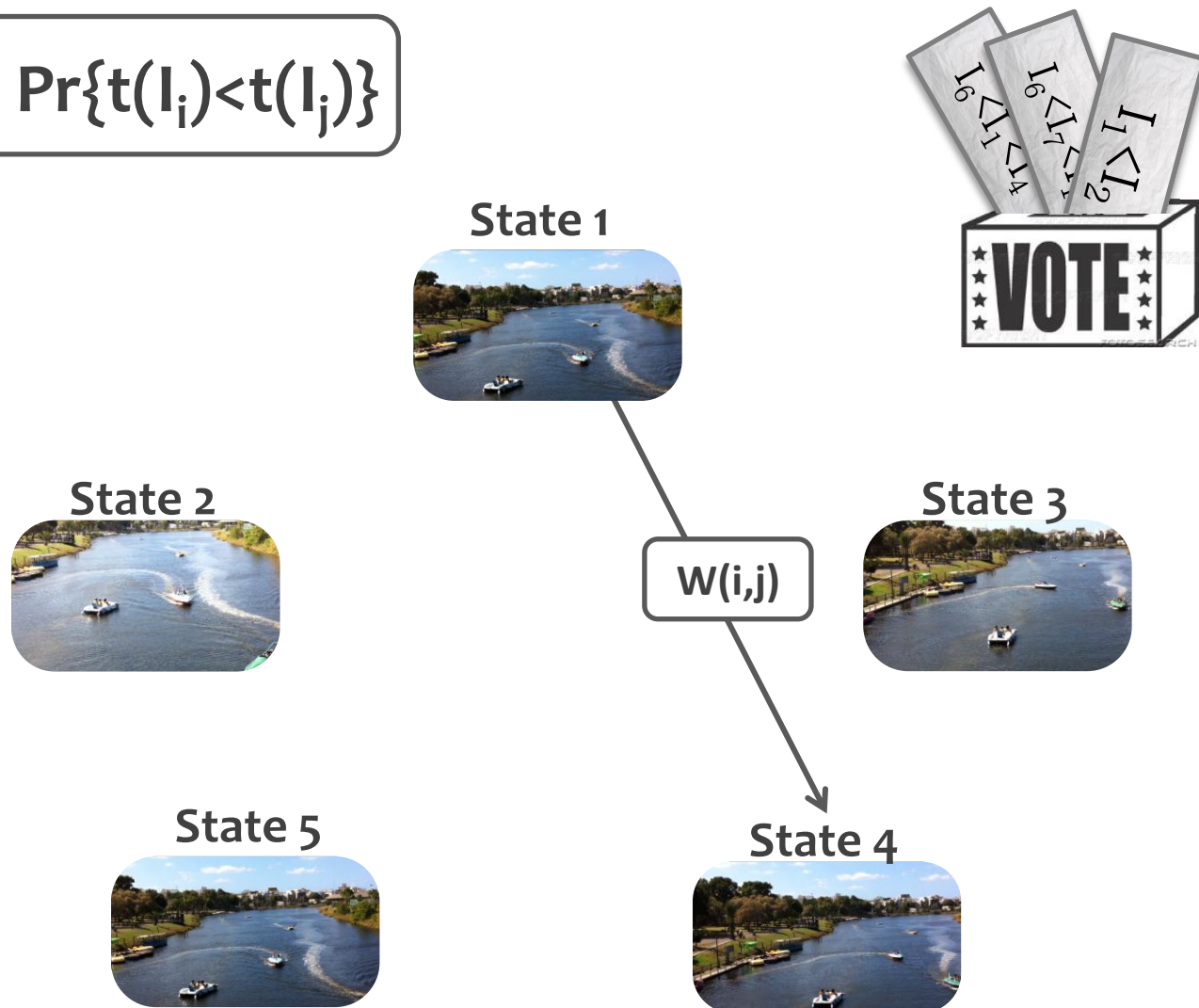
Web
Applications



Web Rank	Domain
1	google.com
2	youtube.com
3	facebook.com
4	yahoo.com
5	wikipedia.org
6	twitter.com
7	msn.com
8	live.com
9	blogspot.com
10	amazon.com

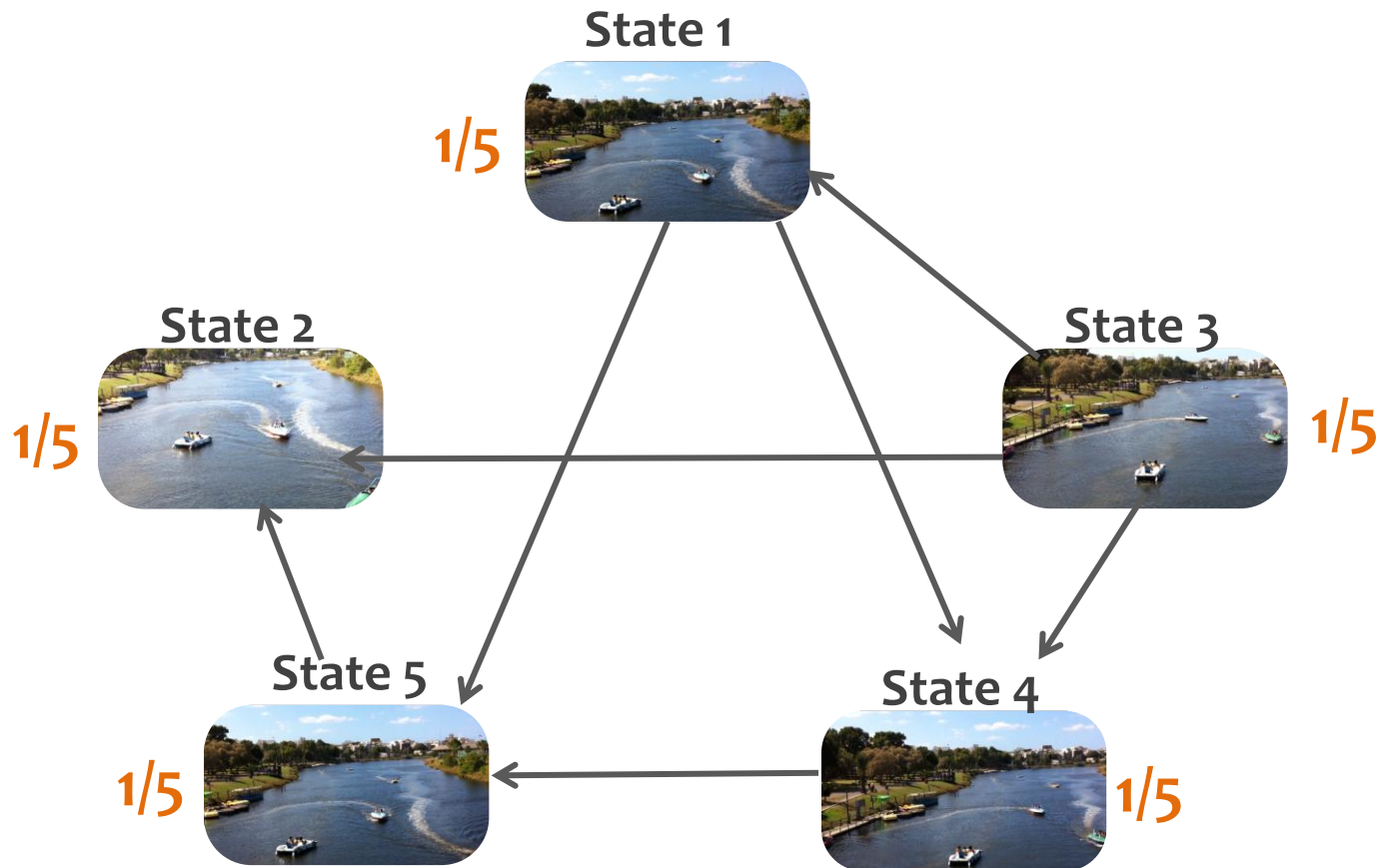
Markov Chain

$$W(i,j) = \Pr\{t(I_i) < t(I_j)\}$$



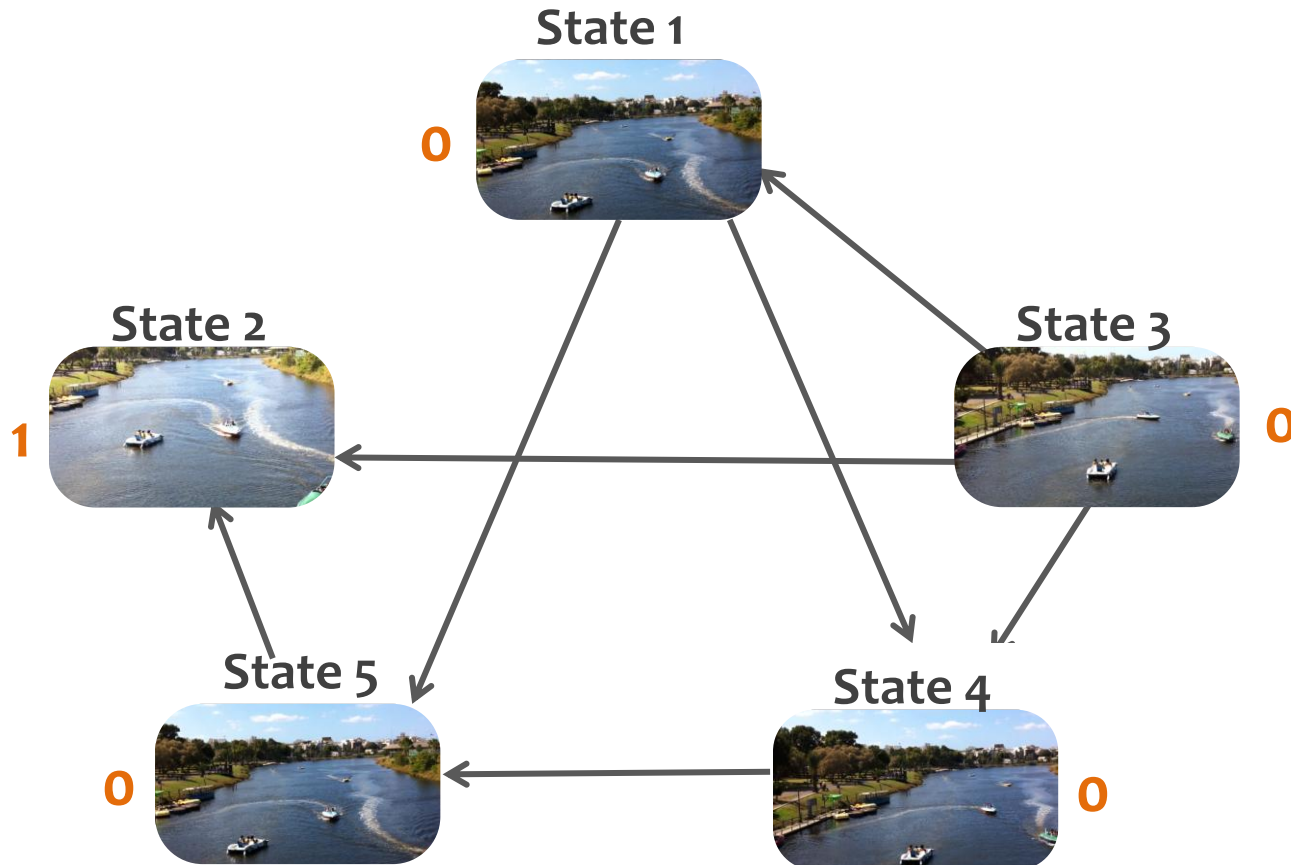
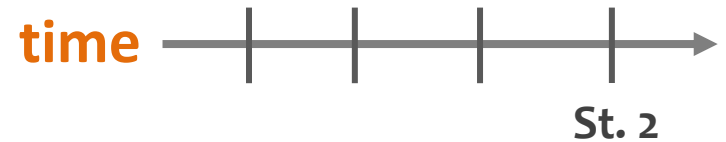
Markov Chain – Initial State

Random walk: start from a uniform distribution



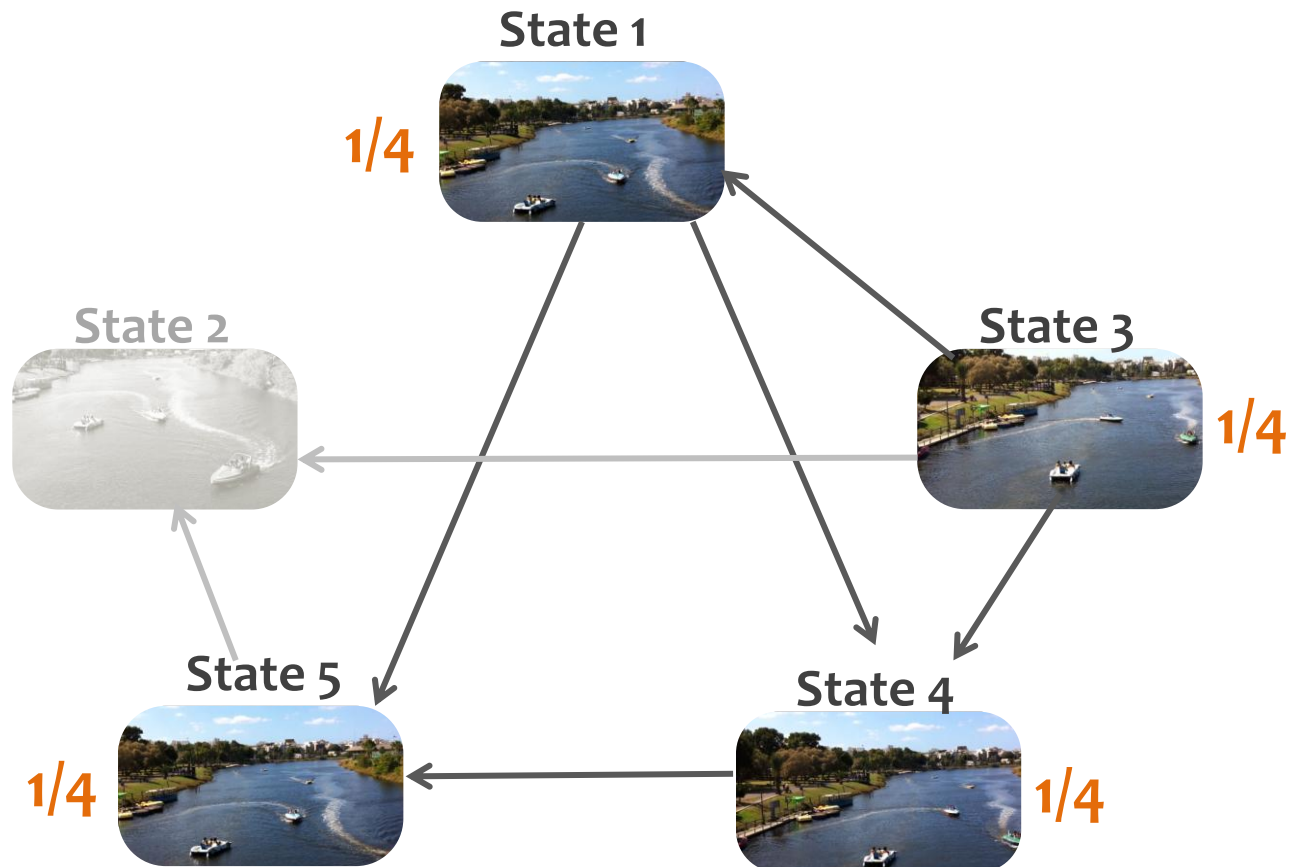
Markov Chain – Steady State

Ends at the sink



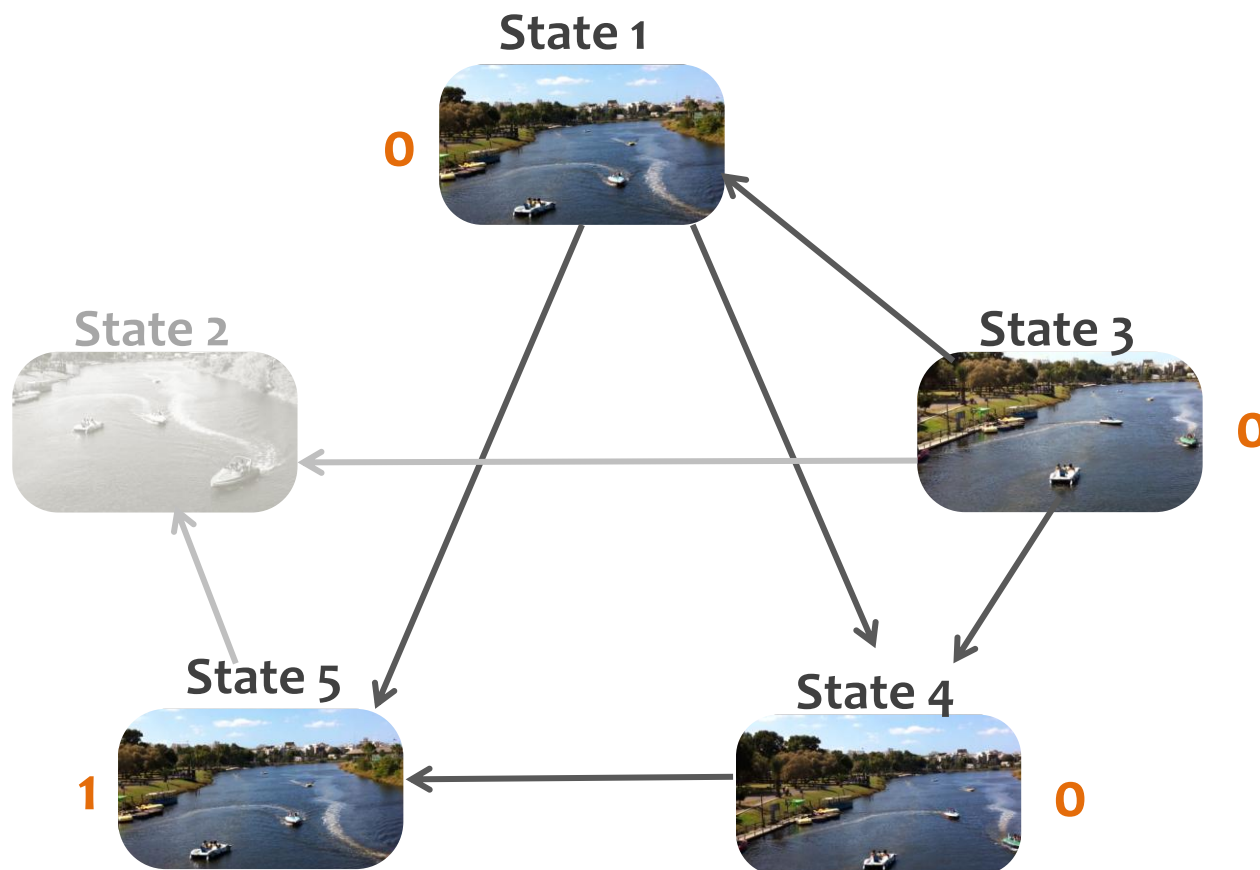
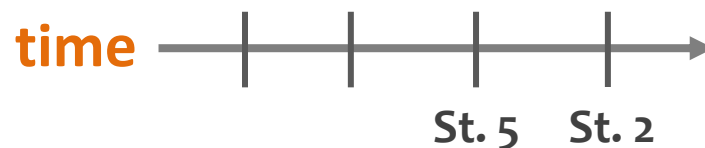
Markov Chain – Initial State

Remove the sink & repeat



Markov Chain – Steady State

Ends at the sink



Results

Skateboard - Input

9 still images



Note the different viewpoints and camera parameters

Skateboard - Input



Skateboard - Input

Here are the input images in a random order:



Skateboard - Results

The aligned images ordered by our method

1st Image



The man is skating from left to right

Skateboard - Results

The aligned images ordered by our method

2nd Image



The man is skating from left to right

Skateboard - Results

The aligned images ordered by our method

3rd Image

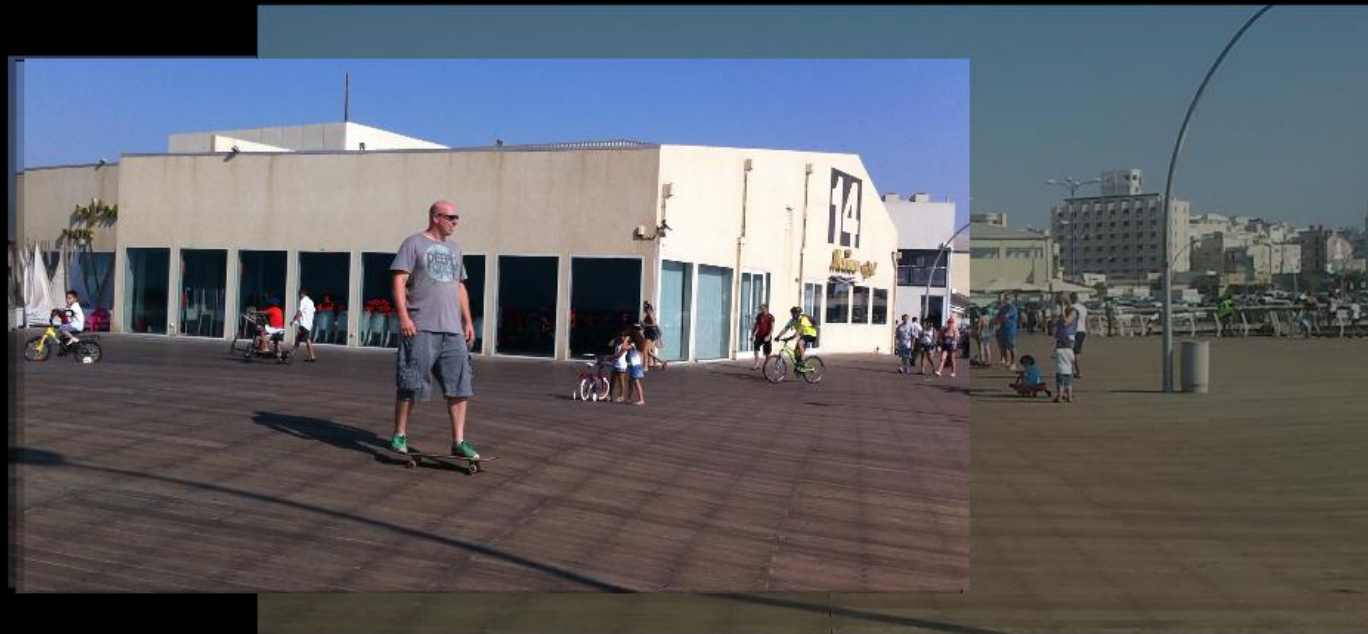


The man is skating from left to right

Skateboard - Results

The aligned images ordered by our method

4th Image



The man is skating from left to right

Skateboard - Results

The aligned images ordered by our method

5th Image



The man is skating from left to right

Skateboard - Results

6th Image



The man is skating from left to right

Skateboard - Results

7th Image



The man is skating from left to right

Skateboard - Results

8th Image



The man is skating from left to right

Skateboard - Results

9th Image



The man is skating from left to right

Slide - Input



Slide - Results

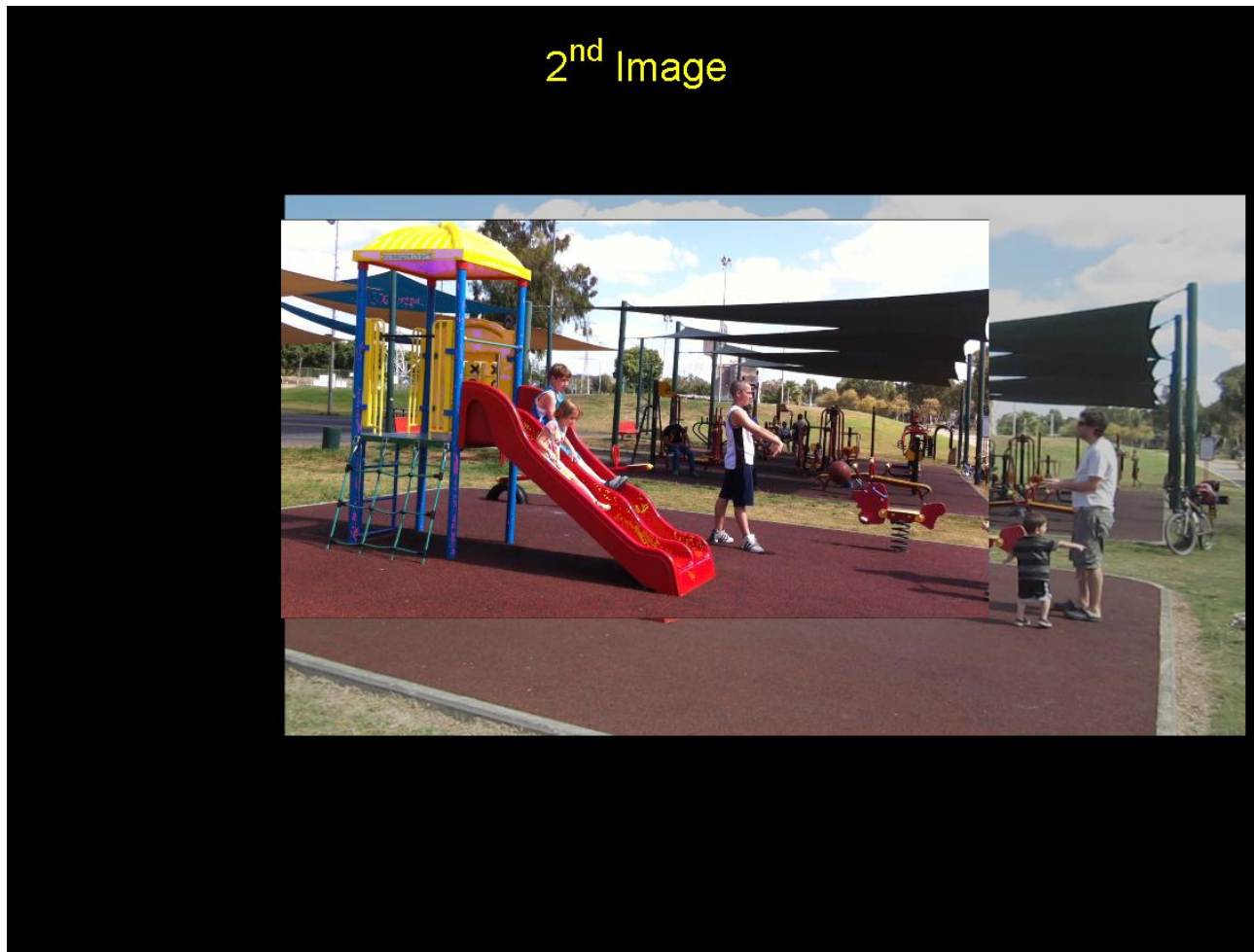
The aligned images ordered by our method

1st Image



Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method

3rd Image



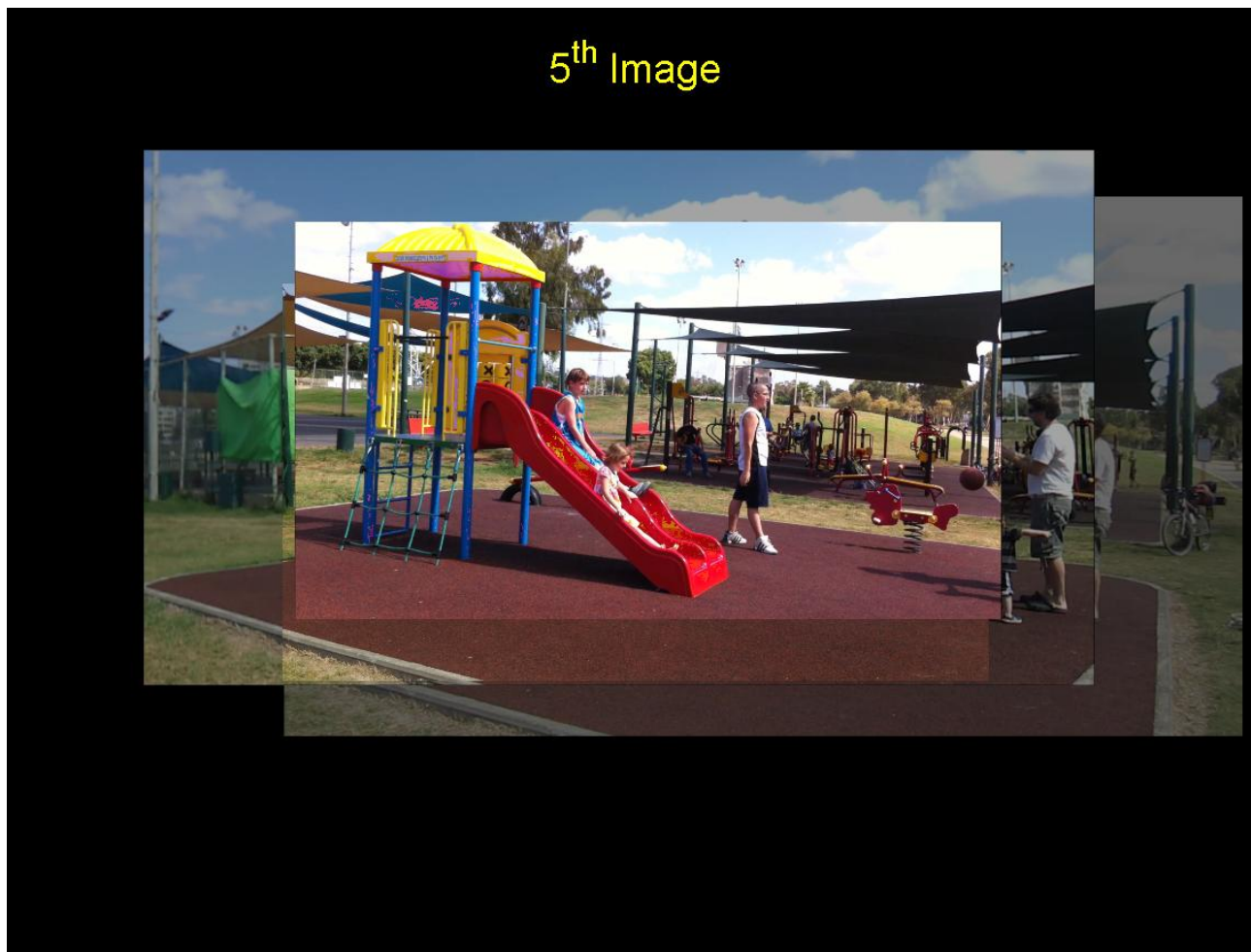
Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method



Slide - Results

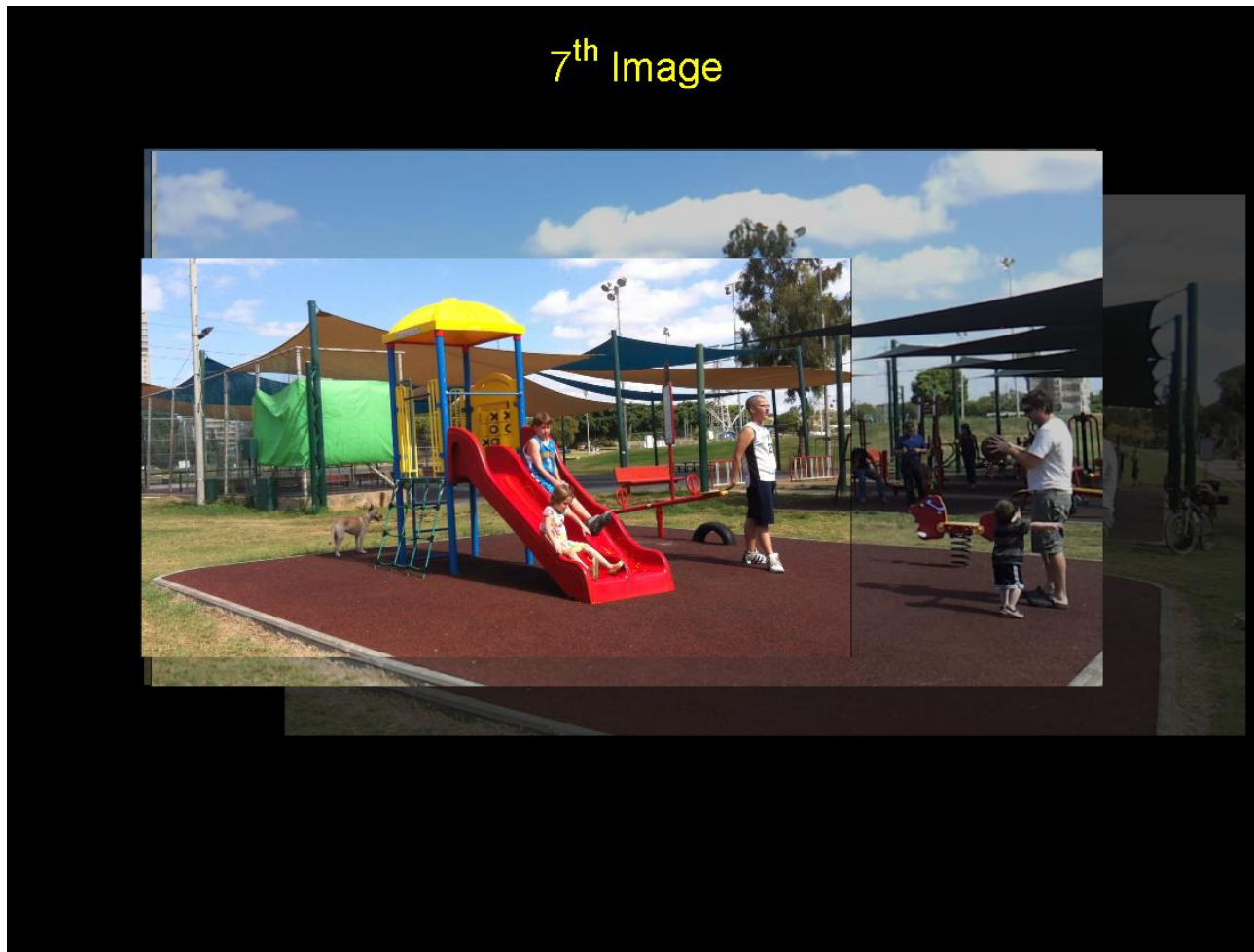
The aligned images ordered by our method

6th Image



Slide - Results

The aligned images ordered by our method



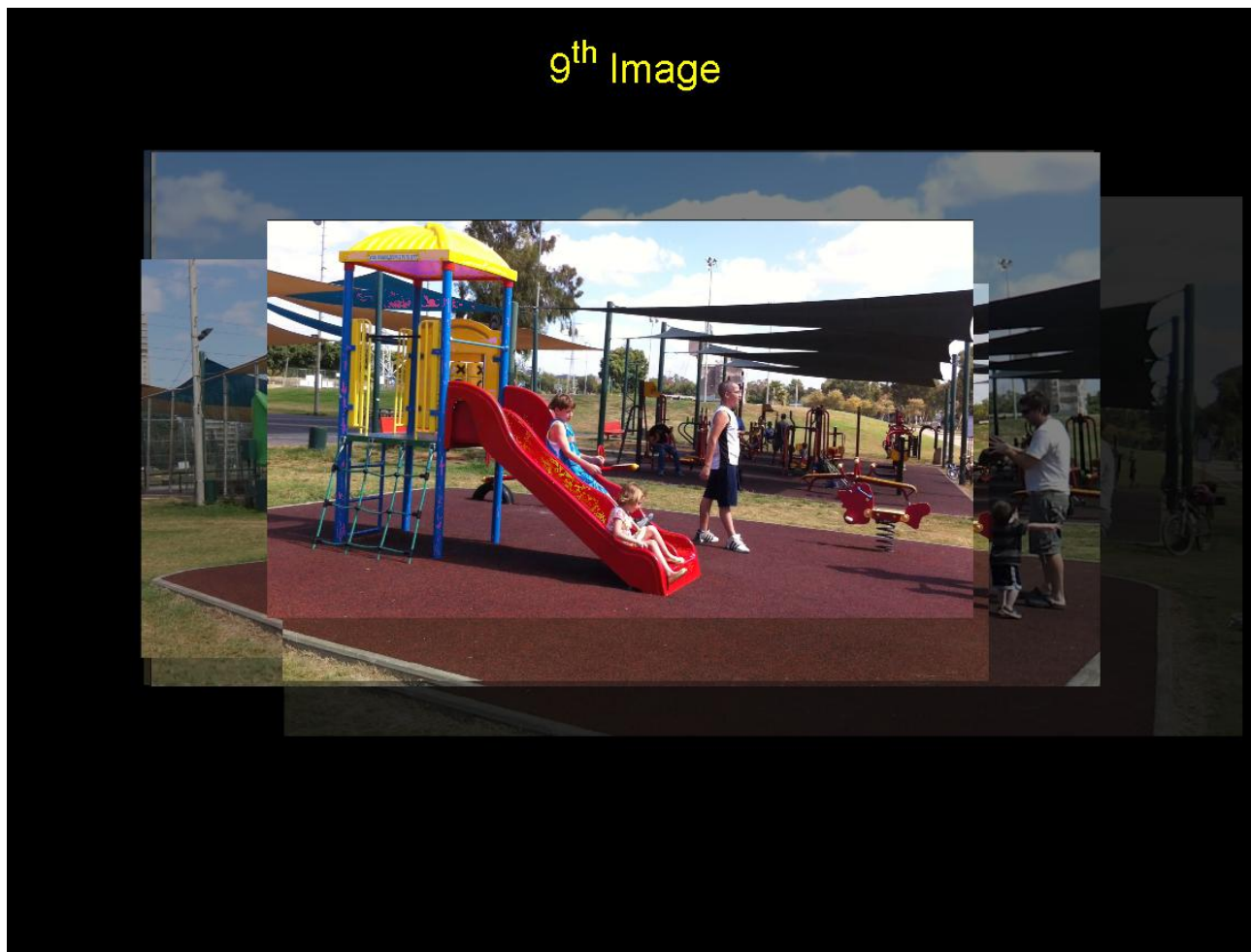
Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method



Slide - Results

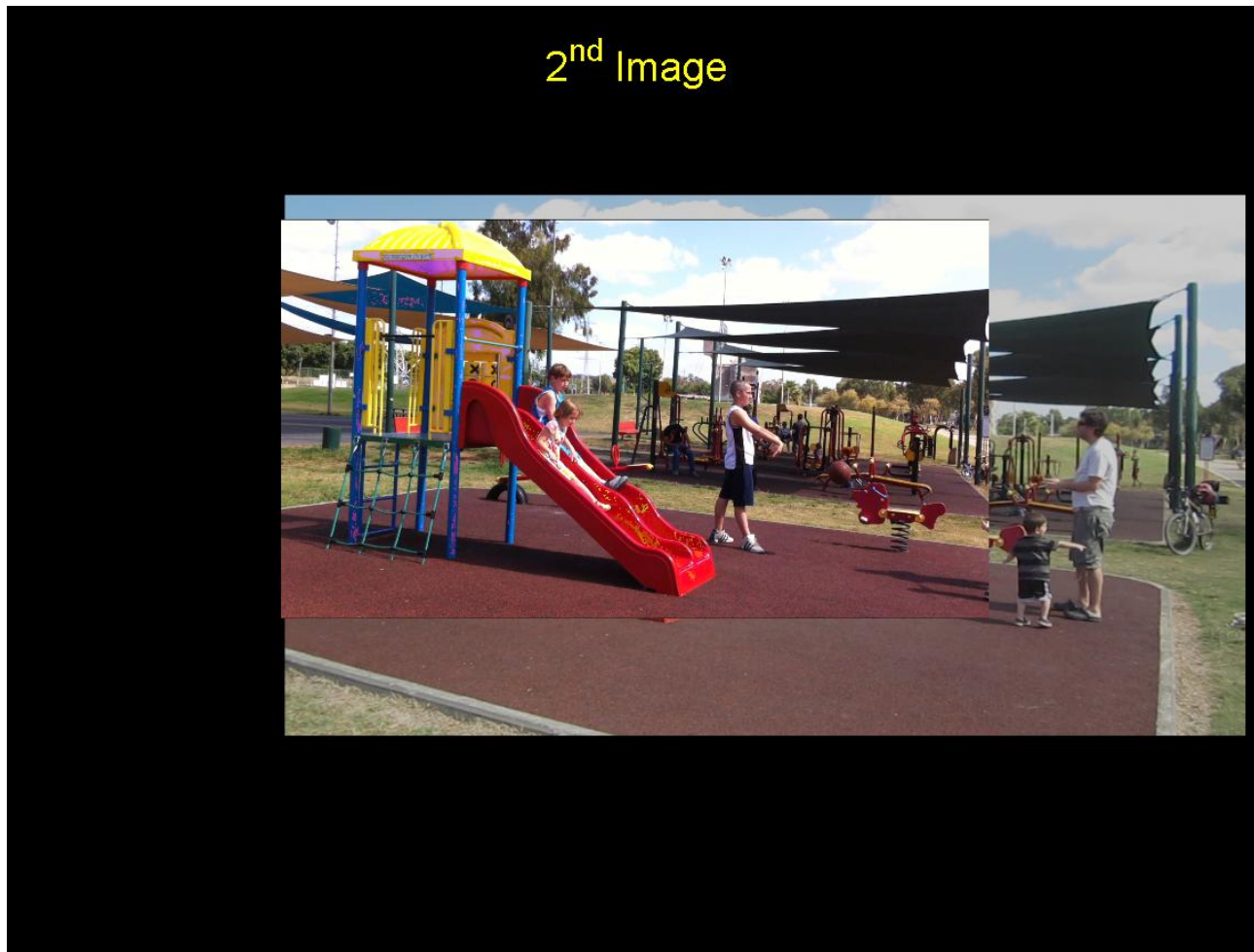
The aligned images ordered by our method

1st Image



Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method

3rd Image



Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method



Slide - Results

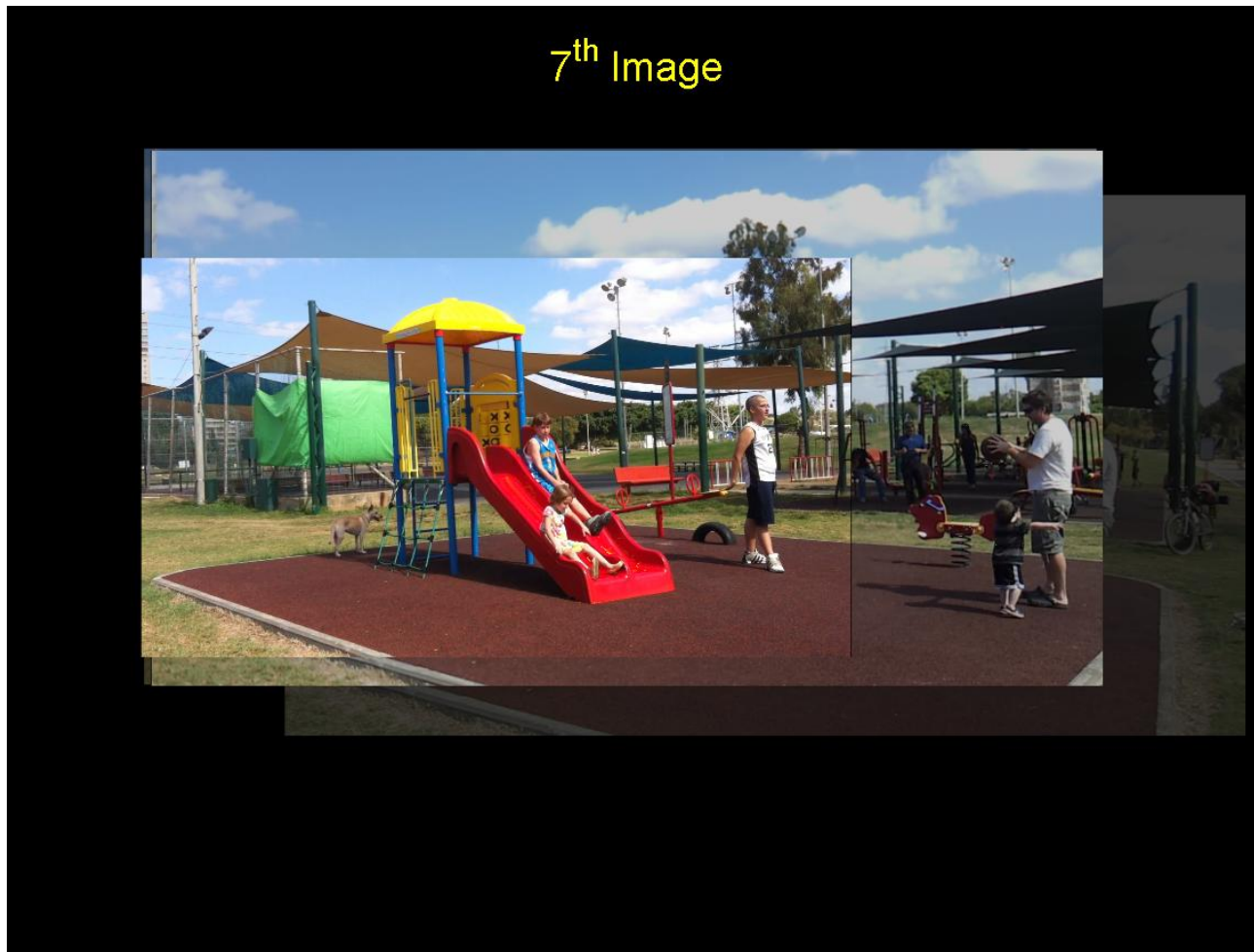
The aligned images ordered by our method

6th Image



Slide - Results

The aligned images ordered by our method



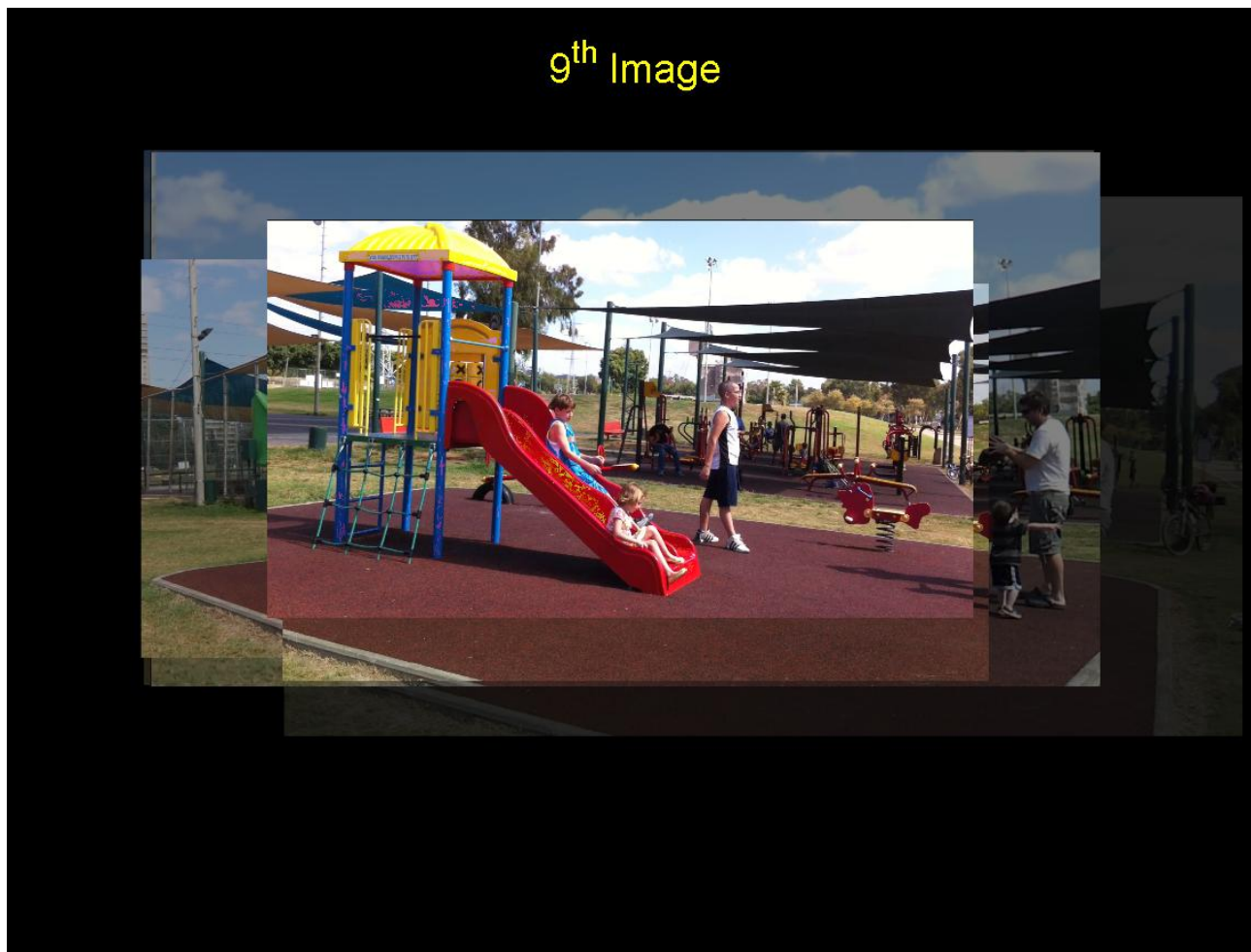
Slide - Results

The aligned images ordered by our method



Slide - Results

The aligned images ordered by our method



More Results - Beach



More Results - Beach



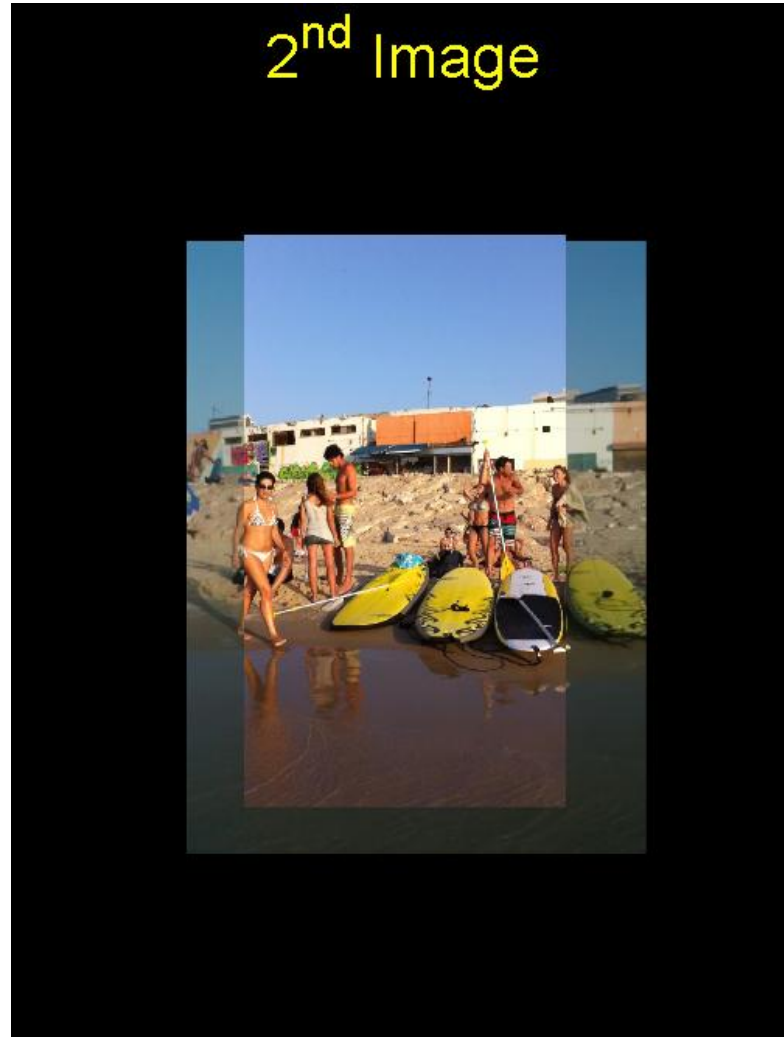
Beach Results

The aligned images ordered by our method



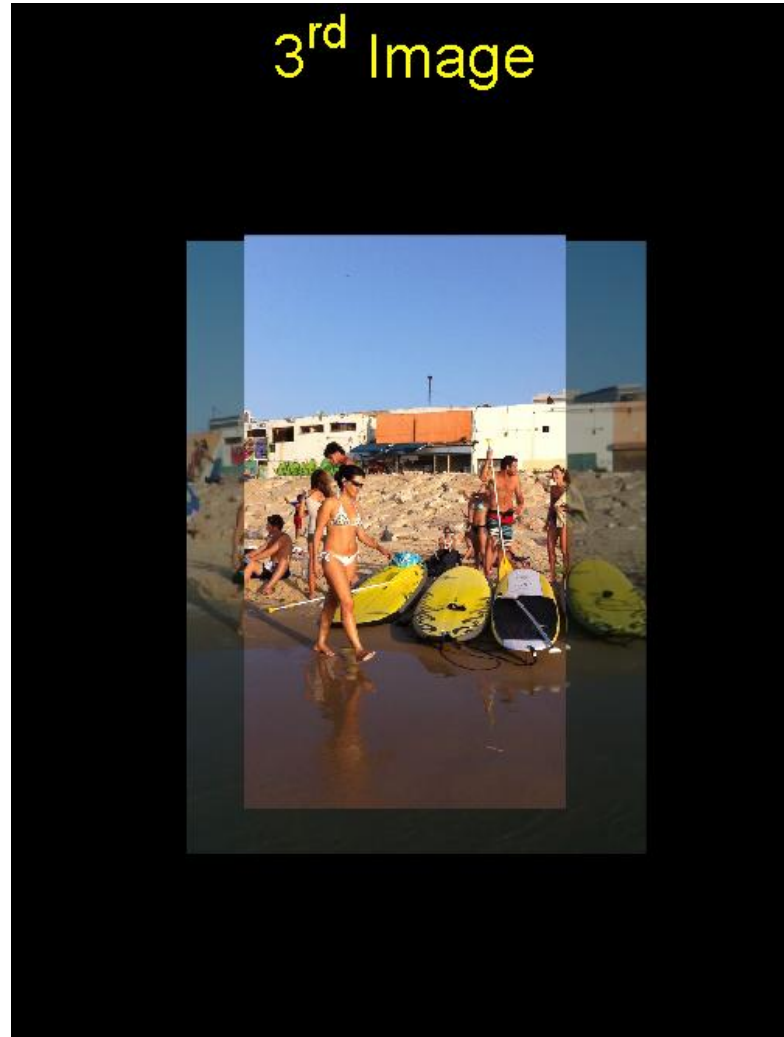
Beach Results

The aligned images ordered by our method



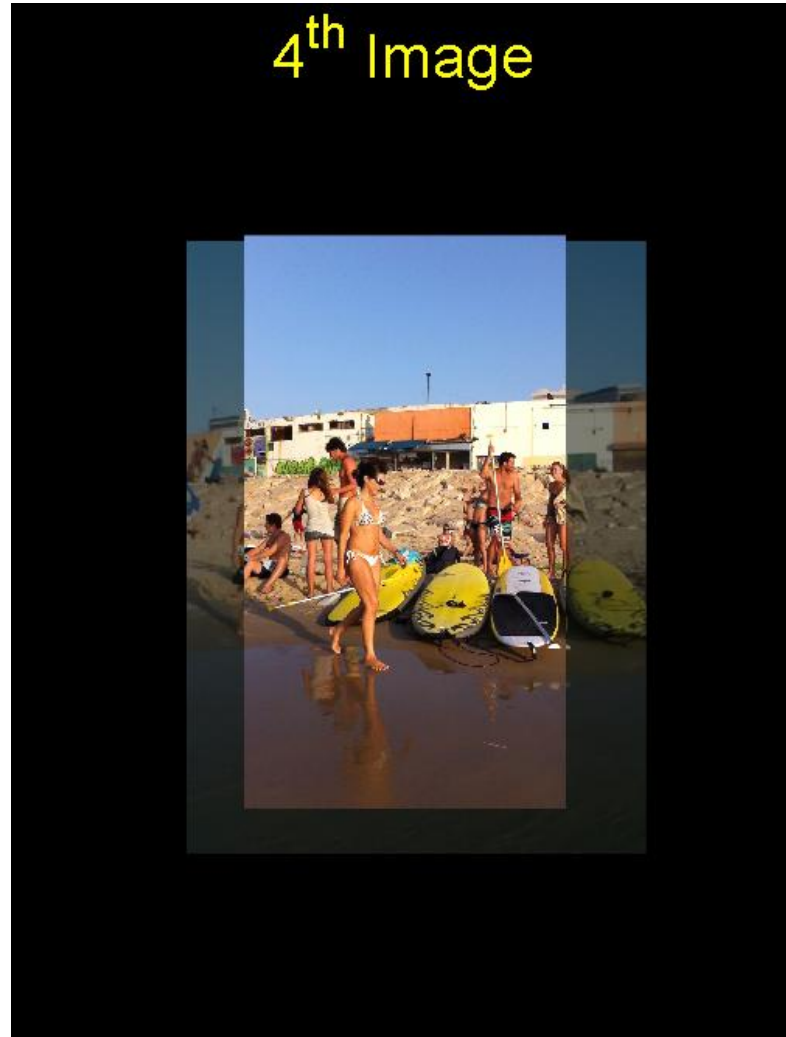
Beach Results

The aligned images ordered by our method



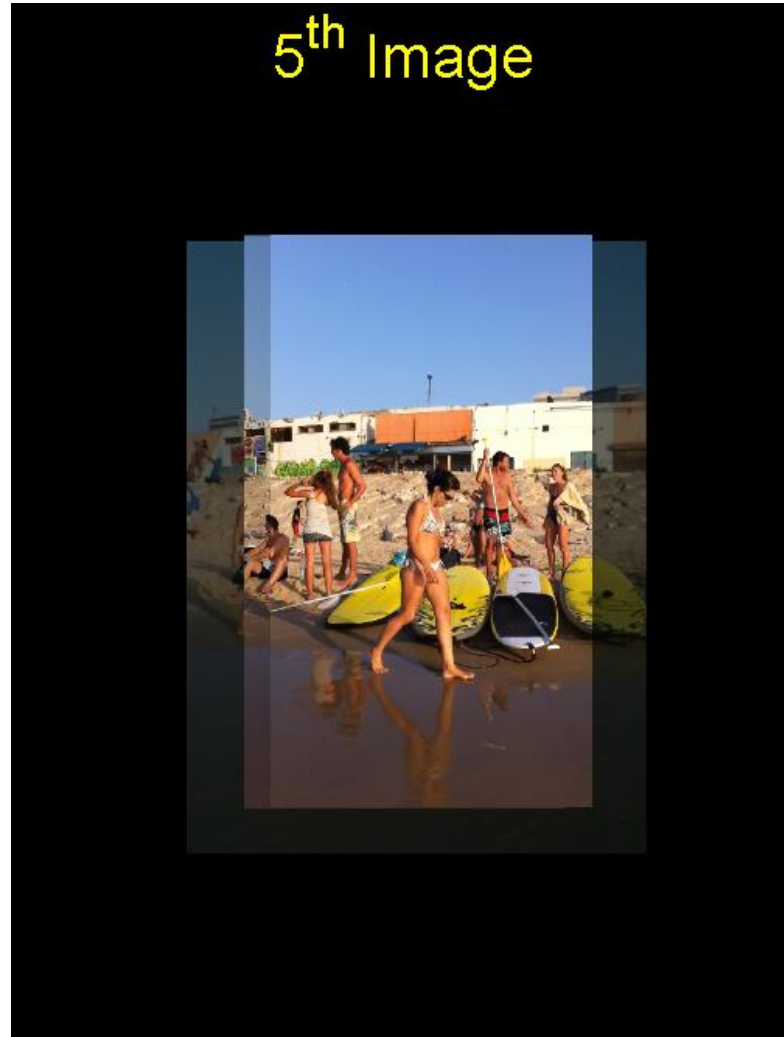
Beach Results

The aligned images ordered by our method



Beach Results

The aligned images ordered by our method



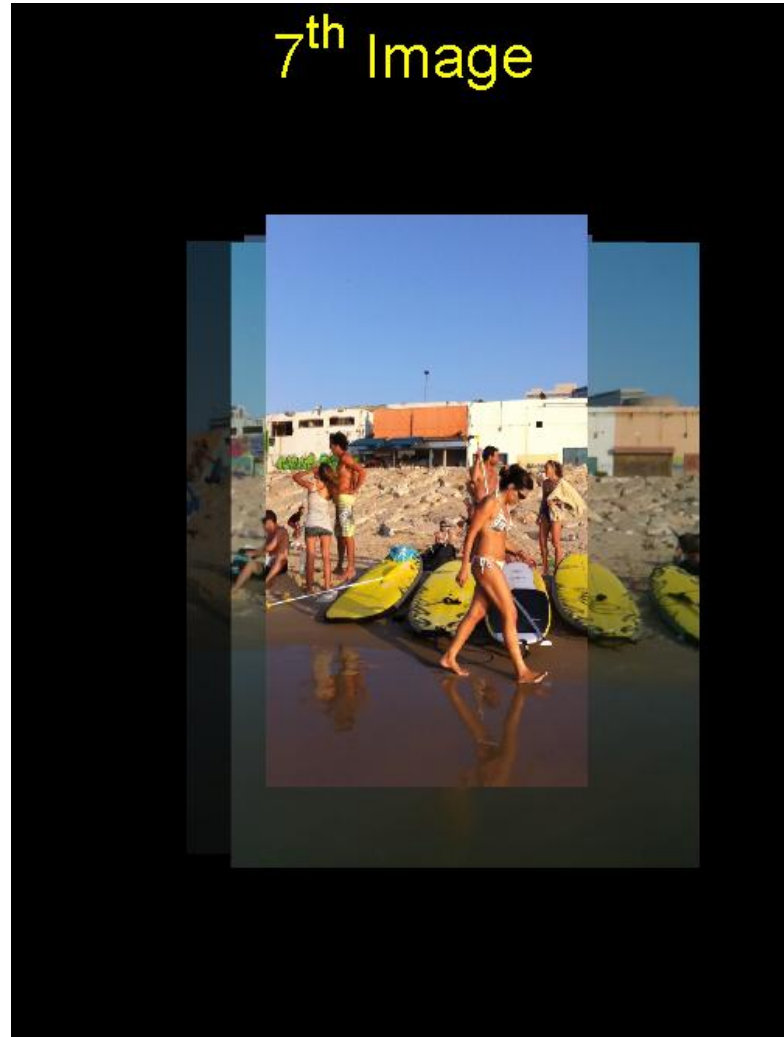
Beach Results

The aligned images ordered by our method



Beach Results

The aligned images ordered by our method



Beach Results

The aligned images ordered by our method



Conclusions & Future Work

- Photo Sequencing – Geometry based solution
- Rank Aggregation

Short Term Future work:

- Matching
- Relaxing the assumptions
- Scalability

Long Term Future work:

- Can still images replace monocular videos ?