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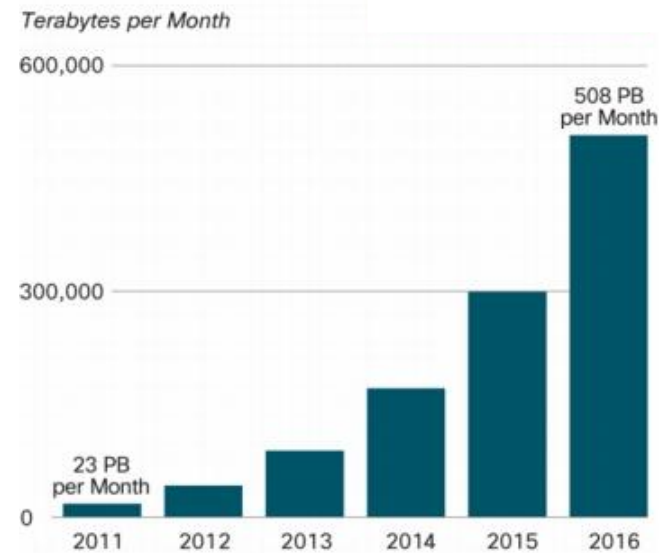
COLLECTING THE DOTS | CONNECTING THE DOTS



The Patient of the Future MIT Technology Review, 2012

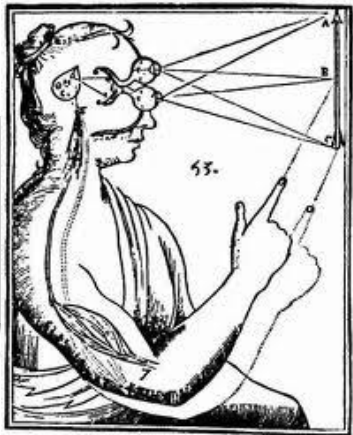


What if we could automate this *sense making* ability?



Source: Cisco VNI Mobile, 2012

... and do it *efficiently* and at *scale*



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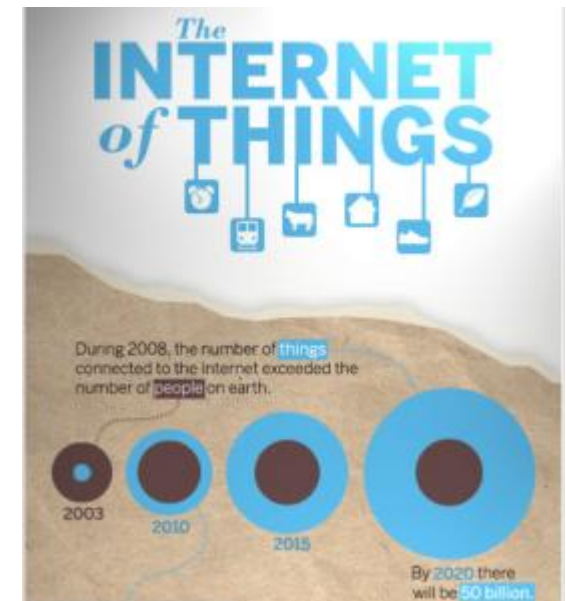
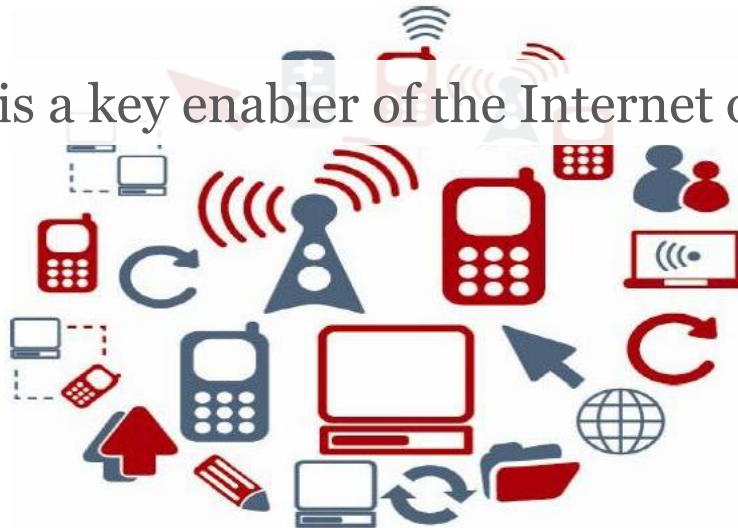
An Efficient Bit Vector Approach to Semantics-based Machine Perception in Resource-constrained Devices

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Cory Henson, Krishnaprasad Thirunarayan, Amit Sheth

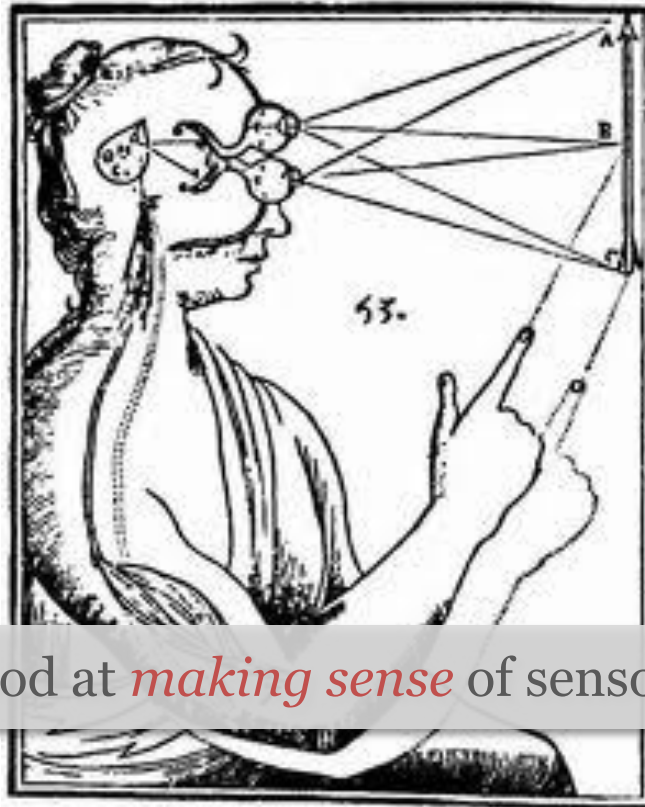
[Kno.e.sis](#) – Ohio Center of Excellence in Knowledge-enabled Computing
Wright State University, Dayton, OH, USA

Sensing is a key enabler of the Internet of Things



50 Billion Things by 2020 (Cisco)

BUT, how do we *make sense* of the resulting avalanche of sensor data?

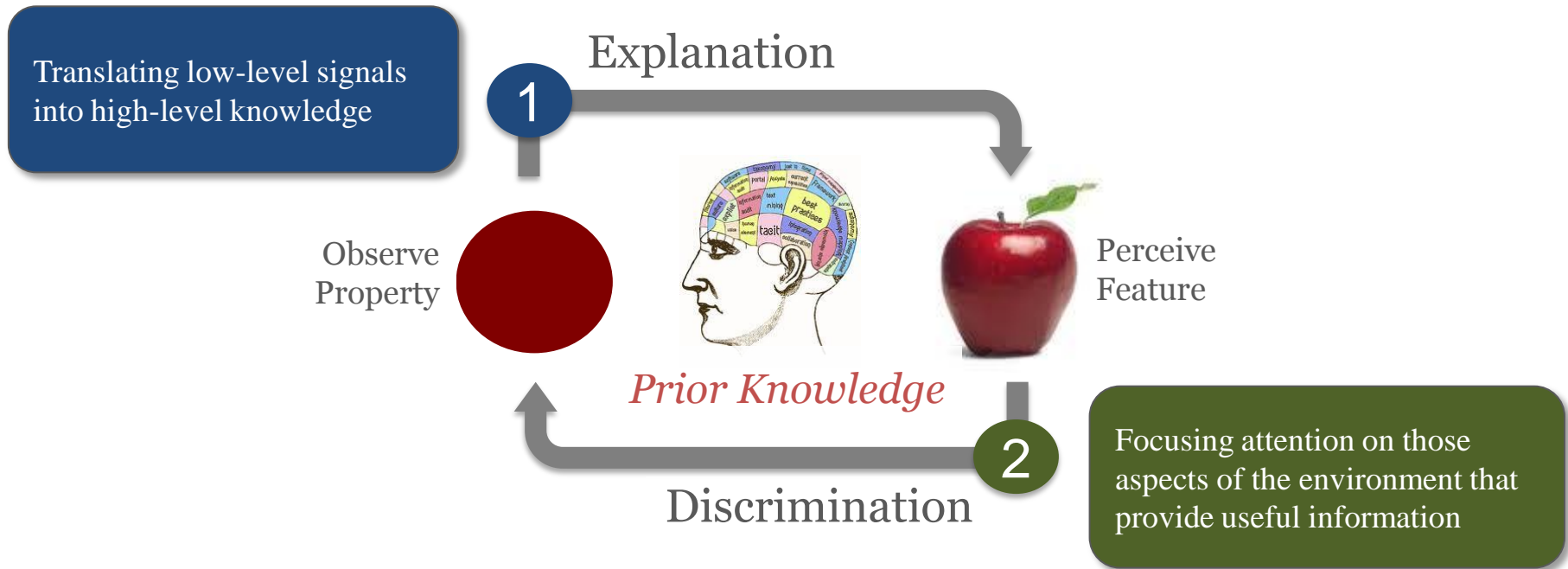


People are good at *making sense* of sensory input

What can we learn from cognitive models of perception?

- *The key ingredient is prior knowledge*

Perception Cycle*



* based on Neisser's cognitive model of perception

To enable machine perception,



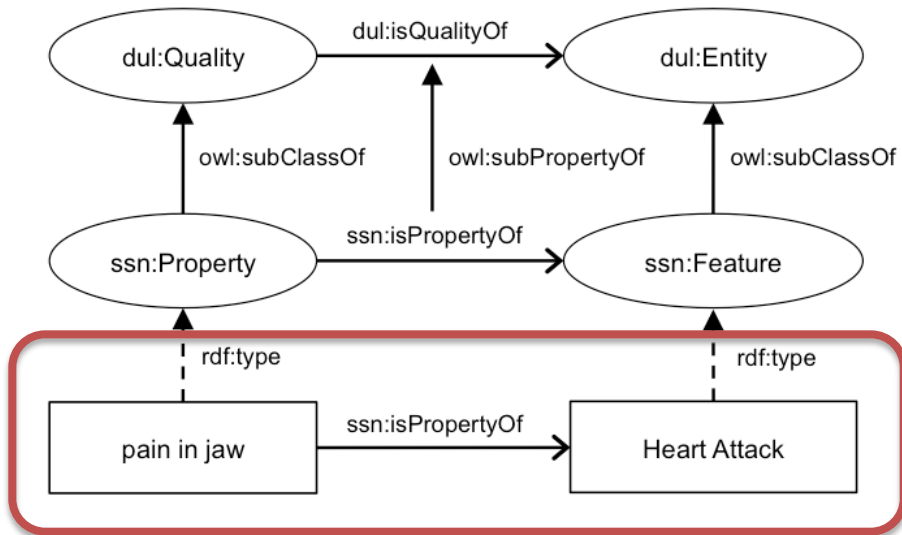
Semantic Web technology is used to integrate sensor data with prior knowledge on the Web

The Web is becoming a
global knowledge base

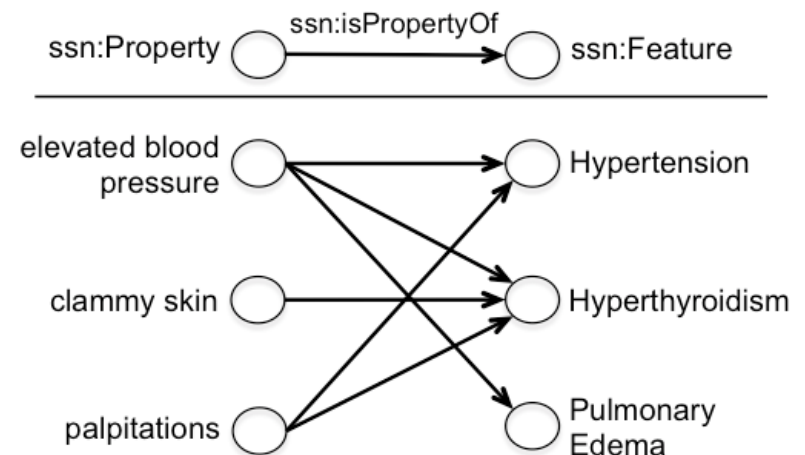


Prior knowledge on the Web

W3C Semantic Sensor Network (SSN) Ontology

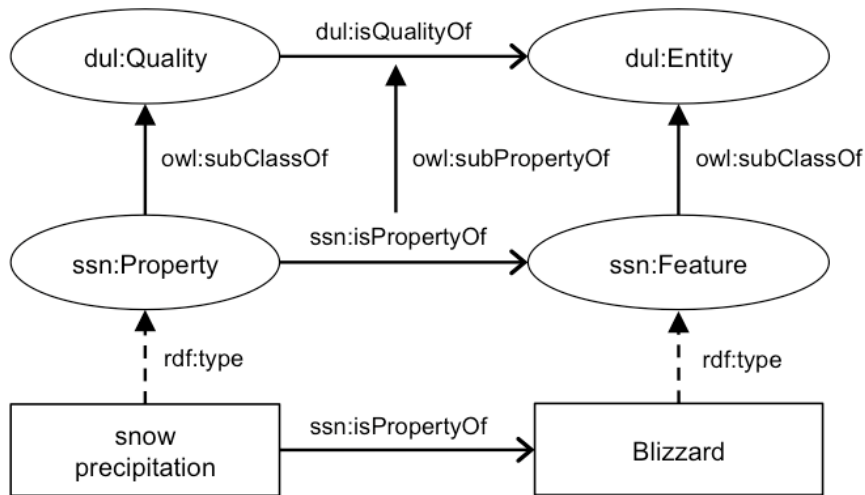


Bi-partite Graph

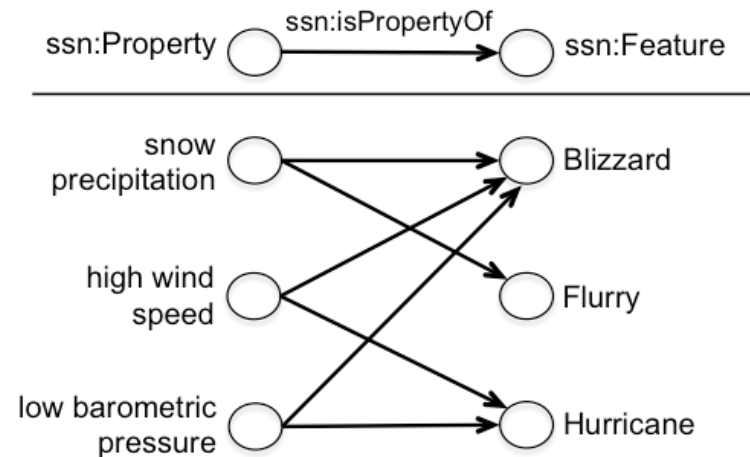


Prior knowledge on the Web

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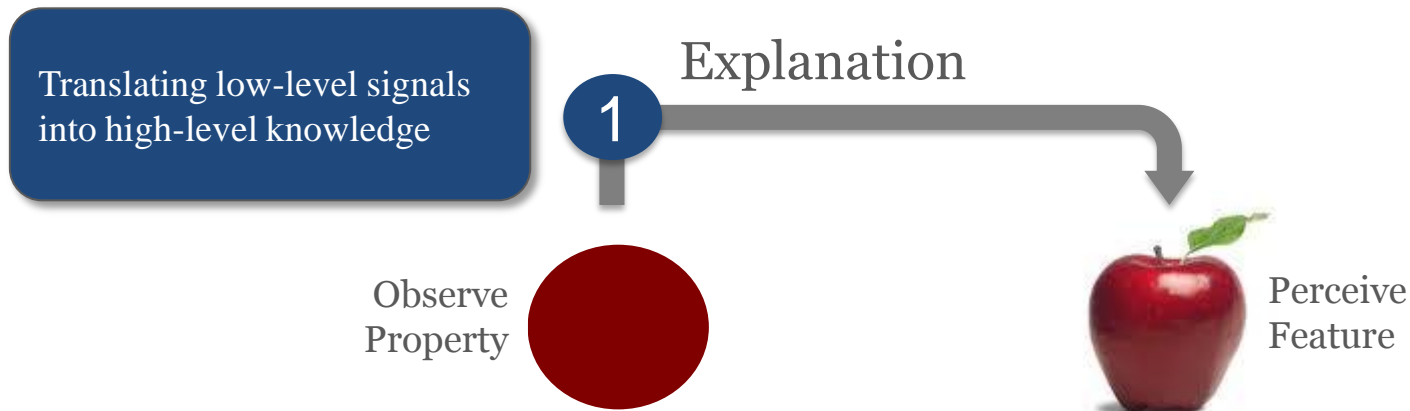


Bi-partite Graph



Explanation

Explanation is the act of choosing the objects or events that best account for a set of observations; often referred to as hypothesis building

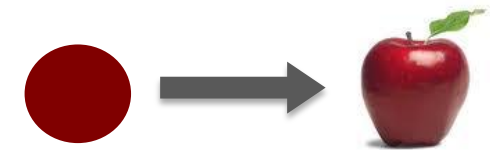


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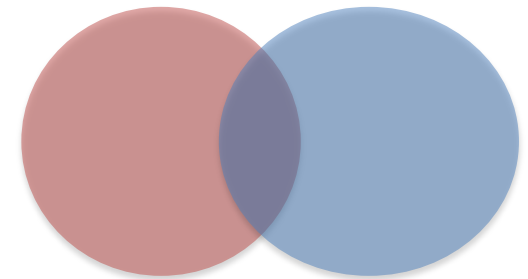
Inference to the best explanation

- In general, explanation is an **abductive** problem; and hard to compute



Finding the sweet spot between abduction and OWL

- **Single-feature assumption*** enables use of OWL-DL deductive reasoner

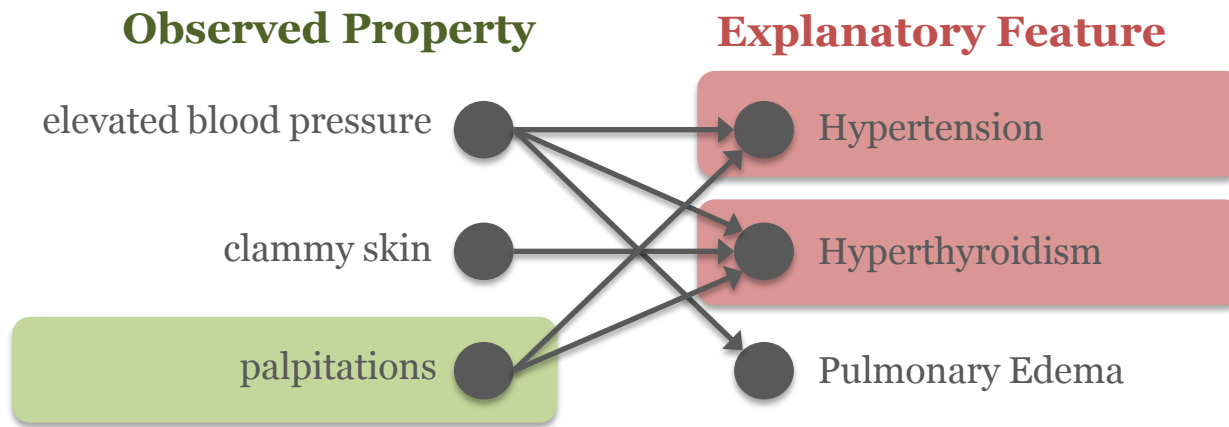


** An explanation must be a single feature which accounts for all observed properties*

Explanation

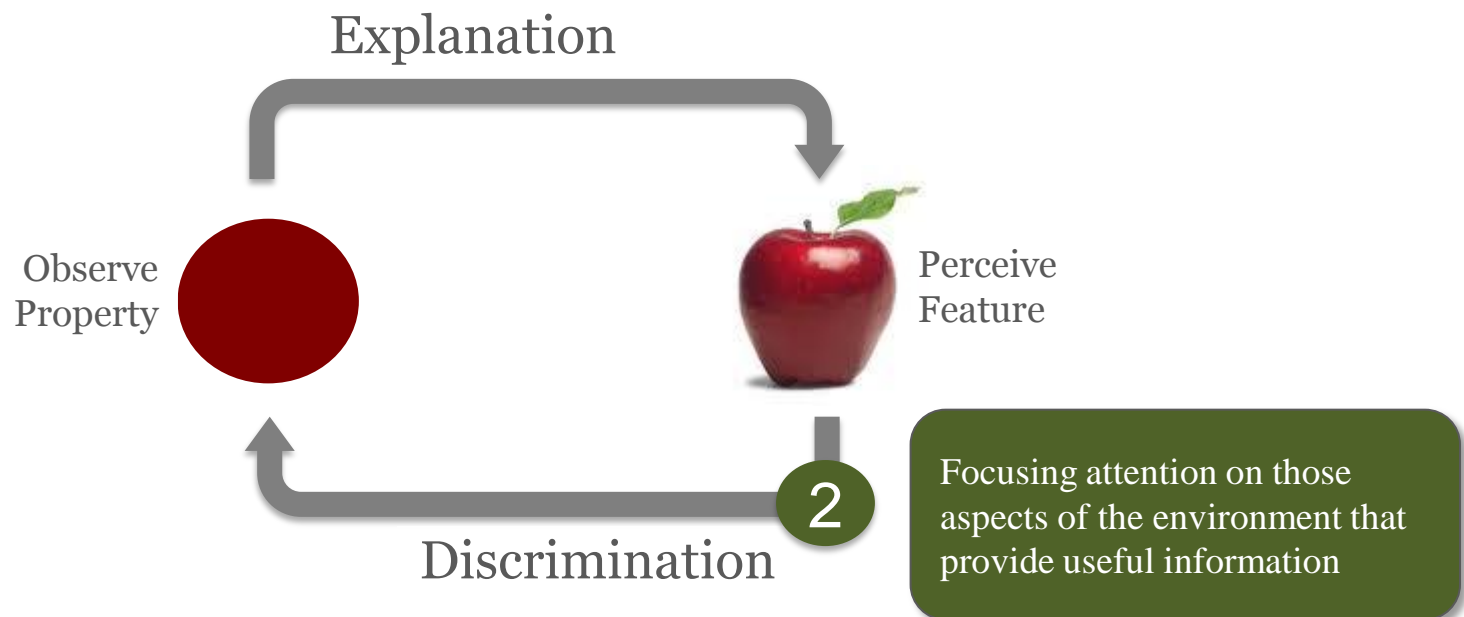
Explanatory Feature: *a feature that explains the set of observed properties*

$$\text{ExplanatoryFeature} \equiv \exists \text{ssn:isPropertyOf}^-. \{p_1\} \sqcap \dots \sqcap \exists \text{ssn:isPropertyOf}^-. \{p_n\}$$



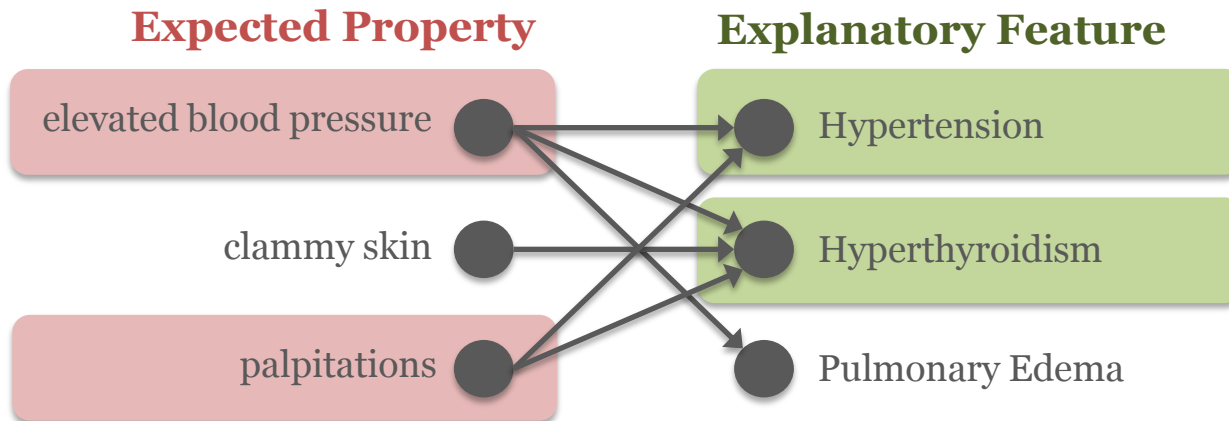
Discrimination

Discrimination is the act of finding those properties that, if observed, would help distinguish between multiple explanatory features



Discrimination

Expected Property: *would be explained by every explanatory feature*

$$\text{ExpectedProperty} \equiv \exists \text{ssn:isPropertyOf.}\{f_1\} \sqcap \dots \sqcap \exists \text{ssn:isPropertyOf.}\{f_n\}$$


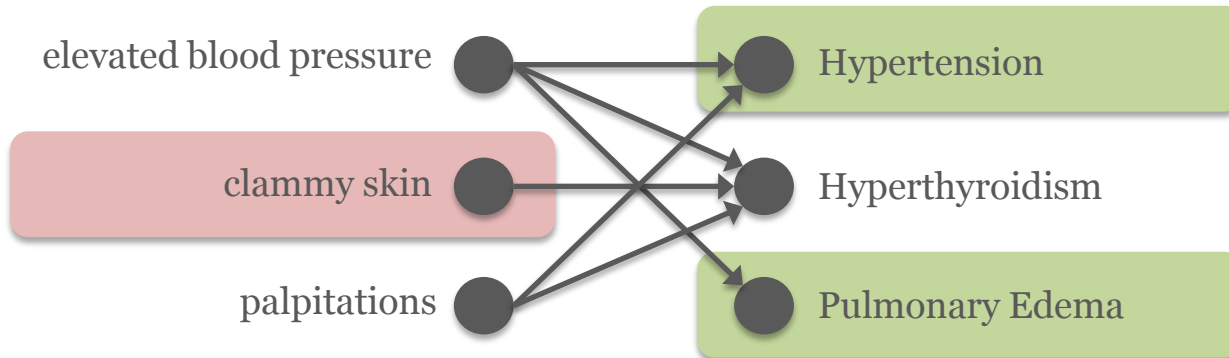
Discrimination

Not Applicable Property: *would not be explained by any explanatory feature*

$$\text{NotApplicableProperty} \equiv \neg \exists \text{sn} : \text{isPropertyOf} . \{f_1\} \sqcap \dots \sqcap \neg \exists \text{sn} : \text{isPropertyOf} . \{f_n\}$$

Not Applicable Property

Explanatory Feature



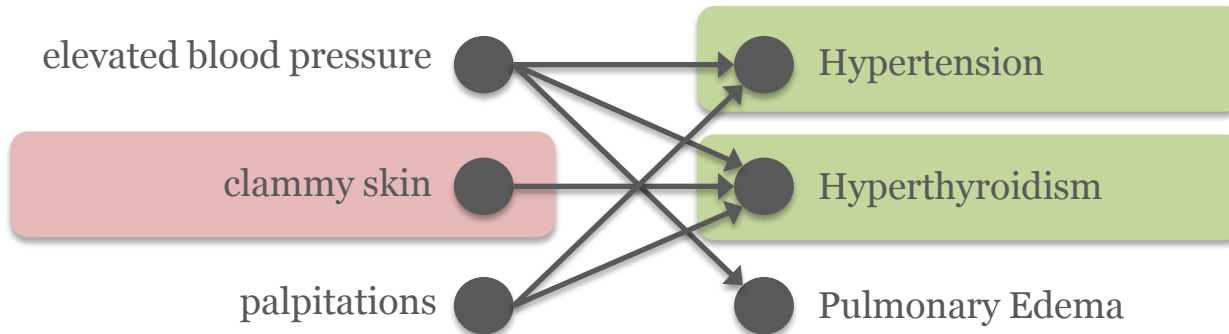
Discrimination

Discriminating Property: *is neither expected nor not-applicable*

$\text{DiscriminatingProperty} \equiv \neg \text{ExpectedProperty} \sqcap \neg \text{NotApplicableProperty}$

Discriminating Property

Explanatory Feature



Our Motivation

kHealth: knowledge-enabled healthcare

Through physical monitoring and analysis, our cellphones could act as an early warning system to detect serious health conditions



canary in a coal mine



How do we implement machine perception *efficiently* on a resource-constrained device?

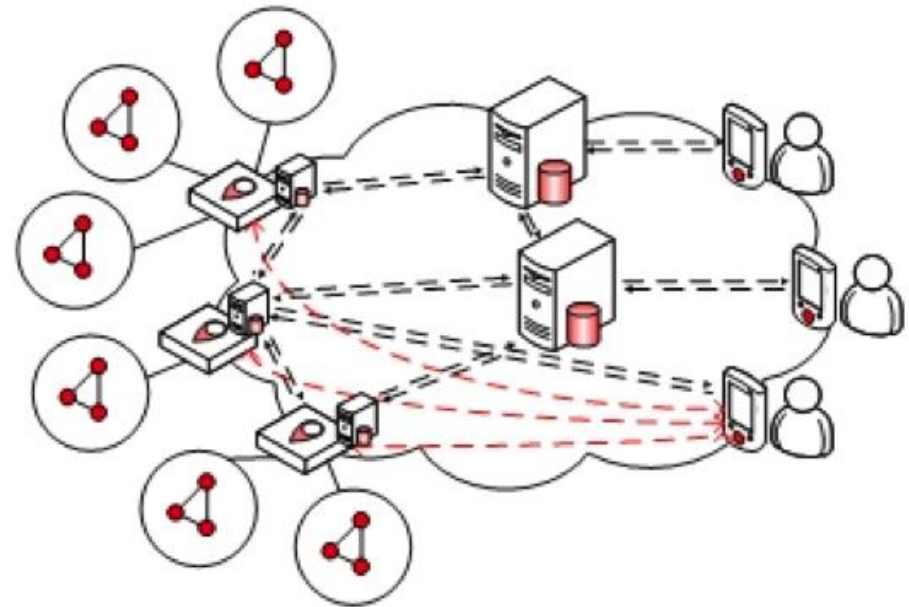


Use of OWL reasoner is resource intensive
(especially on resource-constrained devices),
in terms of both memory and time

- Runs out of resources with prior knowledge $\gg 15$ nodes
- Asymptotic complexity: $O(n^3)$

Approach 1: Send all sensor observations to the cloud for processing

Approach 2: downscale semantic processing so that each device is capable of machine perception

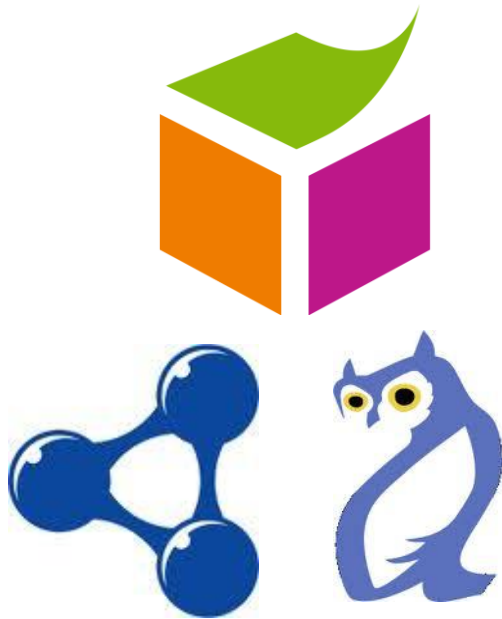


intelligence at the edge



Efficient execution of machine perception

Use *bit vector encodings and their operations* to encode prior knowledge and execute semantic reasoning



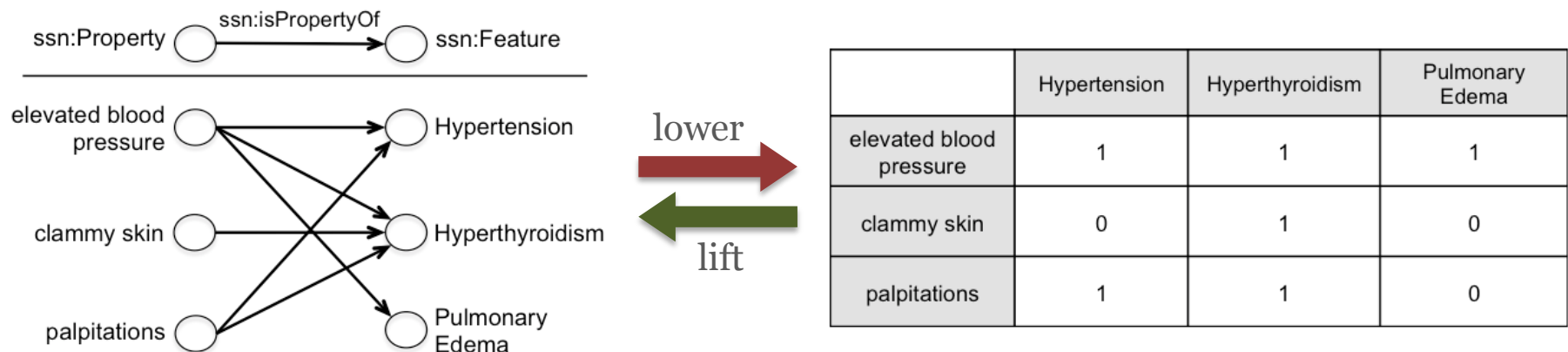
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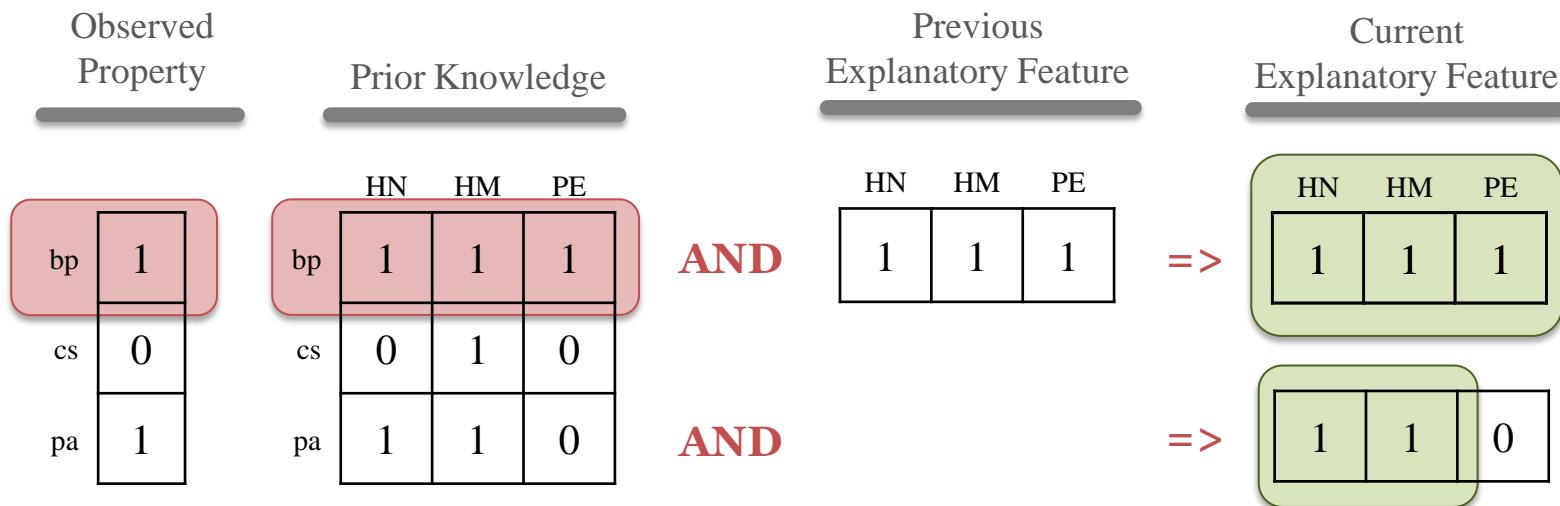
Lifting and lowering knowledge

Translate prior knowledge, observations, and explanations between SW and bit vector representation



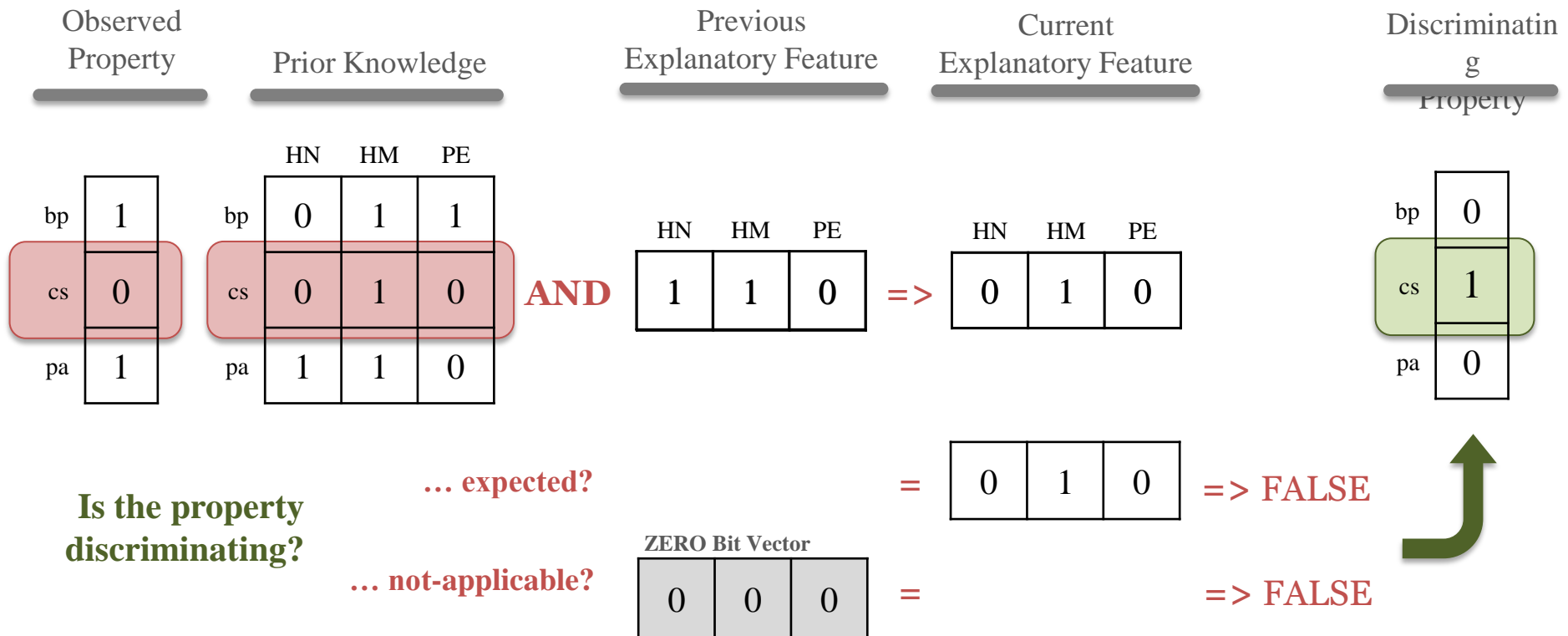
Explanation: efficient algorithm

INTUITION: The strategy employed relies on the use of the bit vector AND operation to discover and dismiss those features that cannot explain the set of observed properties.



Discrimination: efficient algorithm

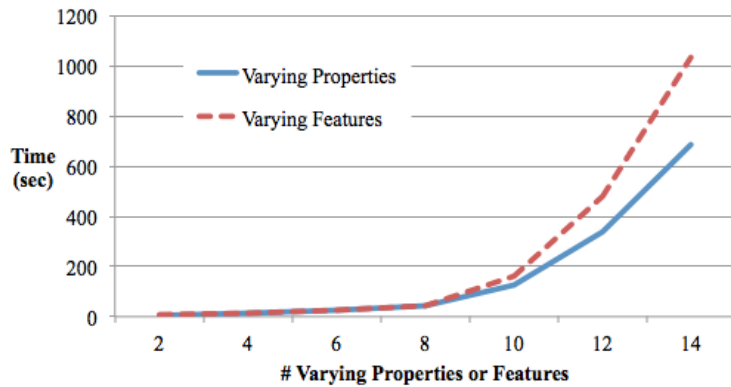
INTUITION: The strategy employed relies on the use of the bit vector AND operation to discover and assemble those features that discriminate between the explanatory features



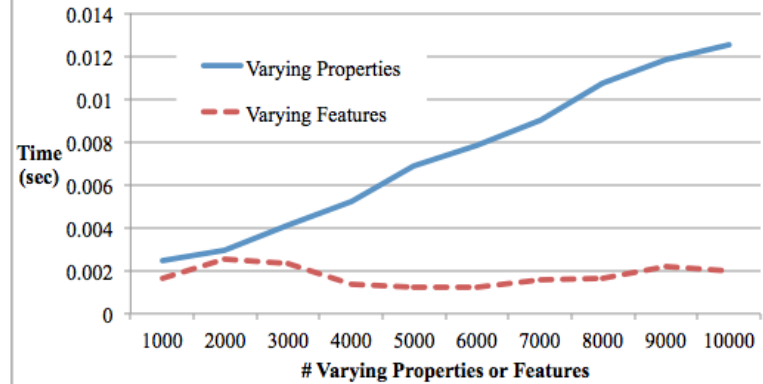
Evaluation on a mobile device



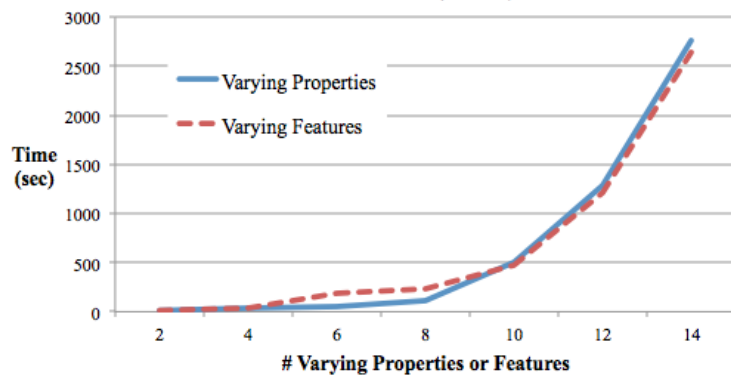
Explanation (OWL)



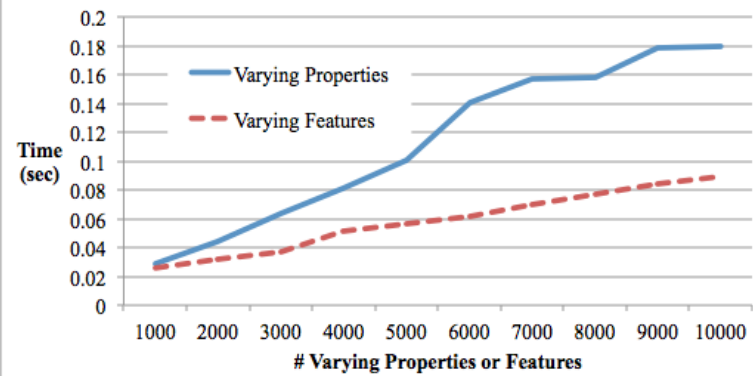
Explanation (Bit Vector)



Discrimination (OWL)



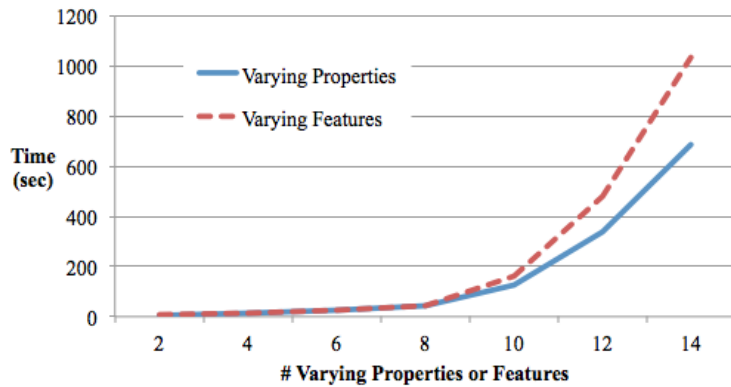
Discrimination (Bit Vector)



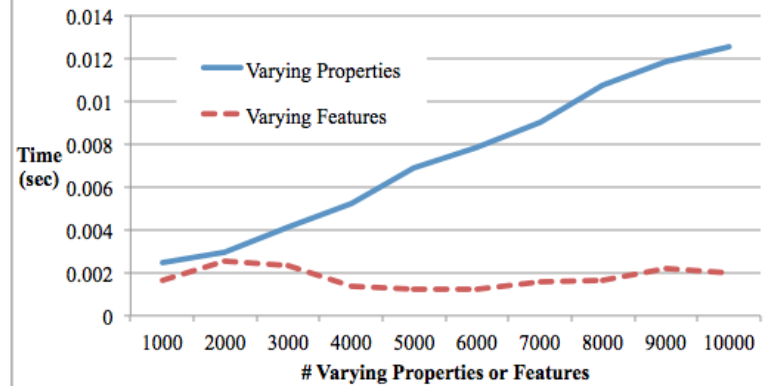
Evaluation on a mobile device



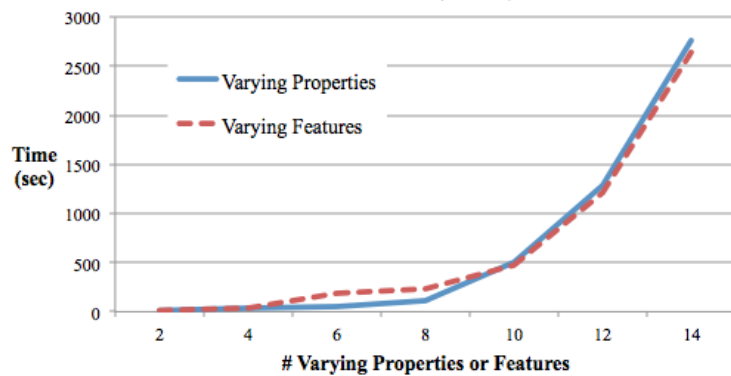
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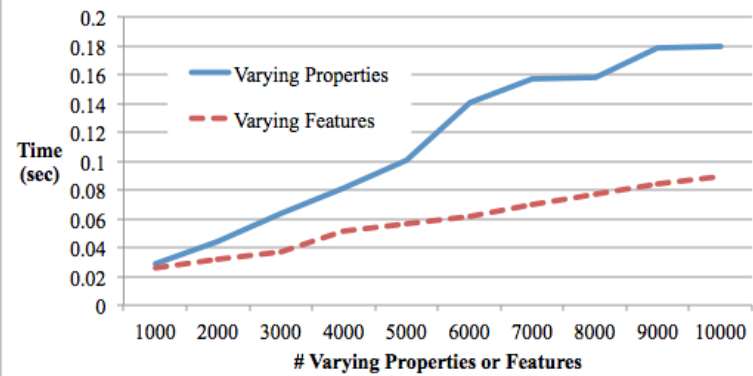
Explanation (Bit Vector)



Discrimination (OWL)



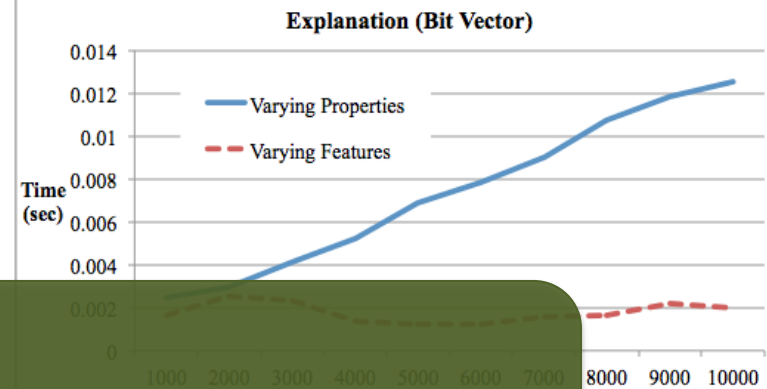
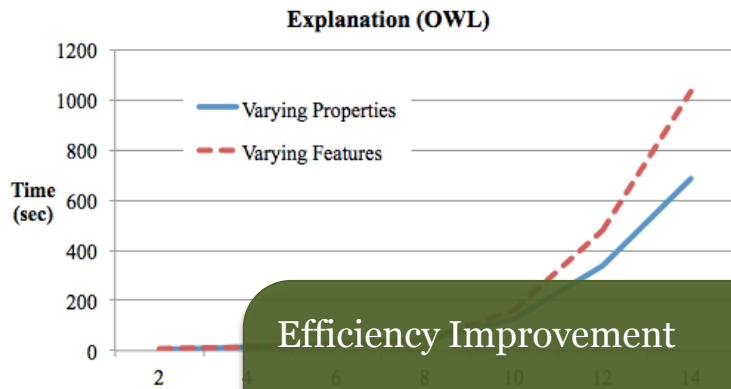
Discrimination (Bit Vector)



$O(n^3) < x < O(n^4)$

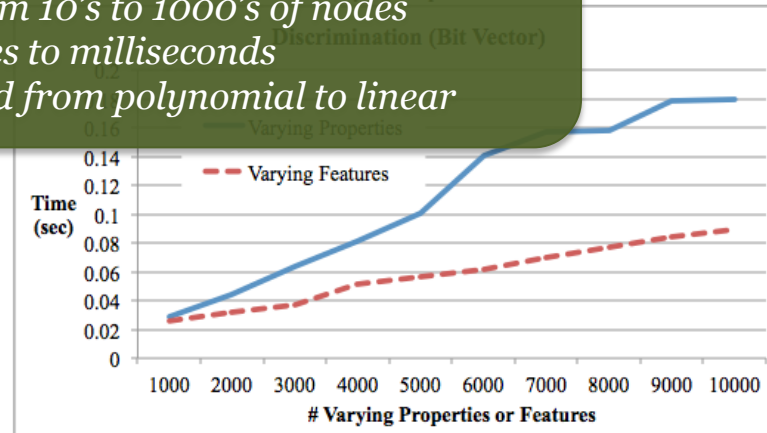
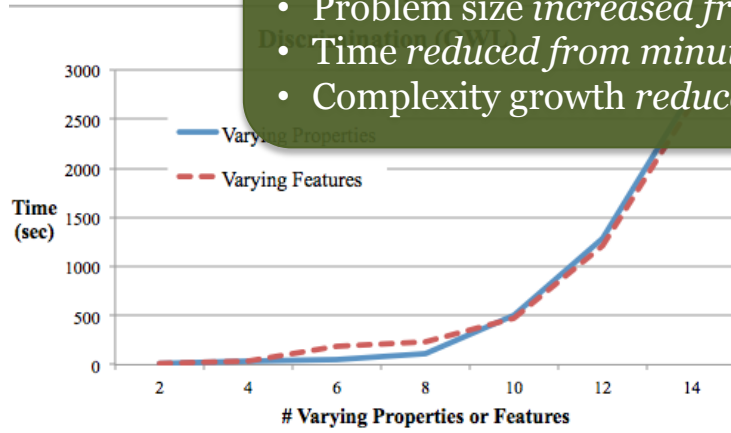
$O(n)$

Evaluation on a mobile device



Efficiency Improvement

- Problem size increased from 10's to 1000's of nodes
- Time reduced from minutes to milliseconds
- Complexity growth reduced from polynomial to linear



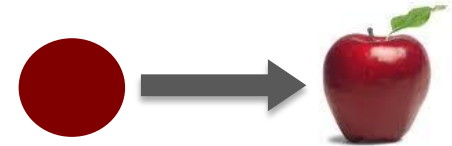
$O(n^3) < x < O(n^4)$

$O(n)$

3 ideas to takeaway

1 *Translate low-level data to high-level knowledge*

Machine perception can be used to convert low-level sensory signals into high-level knowledge useful for decision making



2 *Prior knowledge is the key to perception*

Using SW technologies, machine perception can be formalized and integrated with prior knowledge on the Web

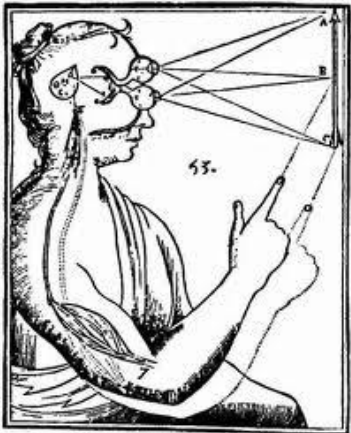


3 *Intelligence at the edge*

By downscaling semantic inference, machine perception can execute efficiently on resource-constrained devices



Thank you.



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