## Sharp analysis of low-rank kernel matrix approximations

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NIPS Optimization workshop - December 2012

## Don't forget kernels methods!

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## Don't forget kernels methods! Don't forget asymptotic analysis!

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## Supervised machine learning with convex optimization Linear vs. non-linear <br> Small scale vs. large scale

- 1990's - early 2000's
- Non-linear kernel methods
- Non-parametric statistics: convergence rates in $O\left(n^{-\alpha}\right)$
- Small-scale problems: complexity in $O\left(n^{2}\right)$ (or more)


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- late 2000's - early 2010's
- Linear methods with/without sparsity-inducing regularization
- Parametric statistics: convergence rates in $O\left(n^{-1}\right)$ or $O\left(n^{-1 / 2}\right)$
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- Large-scale problems: complexity in $O(n)$
- From naive optimization to naive statistical models


## Outline

- Introduction
- Supervised machine learning and convex optimization
- Critical review of worst-case analysis
- Efficient optimization with kernels
- Classical analysis of kernel ridge regression
- Bias / variance
- Degrees of freedom
- Sharp analysis of low-rank approximation for kernel methods
- Column sampling
- No loss in predictive performance
- Choice of regularization parameter


## Supervised machine learning

- Data: $n$ observations $\left(x_{i}, y_{i}\right) \in \mathcal{X} \times \mathcal{Y}, i=1, \ldots, n$, i.i.d.
- Prediction $\hat{y}=f(x)=\langle f, \Phi(x)\rangle, f \in \mathcal{F}=$ Hilbert space
- Regularized empirical risk minimization: find $\hat{f}$ solution of

$$
\begin{aligned}
& \min _{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i}, f\left(x_{i}\right)\right)+\frac{\lambda}{2}\|f\|^{2} \\
& \text { convex data fitting term }+ \text { regularizer }
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- Empirical risk: $\hat{R}(\theta)=\frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i}, f\left(x_{i}\right)\right) \quad$ training cost
- Expected risk: $R(\theta)=\mathbb{E}_{(x, y)} \ell(y, f(x)) \quad$ testing cost
- Two fundamental questions: (1) computing $\hat{f}$ and (2) analyzing $\hat{f}$


## Supervised machine learning Worst-case analysis

- Results from Sridharan et al. (2008). See also Boucheron and Massart (2011)
- Assumptions ( $R=$ expected risk, $\hat{R}=$ empirical risk)
$-\hat{f}=\arg \min _{f \in \mathcal{F}} \hat{R}(f)+\frac{\lambda}{2}\|f\|^{2}$
- $\|\Phi(x)\| \leqslant B$ almost surely
- L-Lipschitz loss, i.e., $R$ and $\hat{R}$ are $L B$-Lipschitz continuous
- With probability greater than $1-\delta$,

$$
R(\hat{f})+\frac{\lambda}{2}\|\hat{f}\|^{2}-\min _{f \in \mathcal{F}}\left\{R(f)+\frac{\lambda}{2}\|f\|^{2}\right\} \leqslant \frac{16 L^{2} B^{2}\left(32+\log \frac{1}{\delta}\right)}{\lambda n}
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$$

- $\lambda$ should tend to zero with $n$ !


## Supervised machine learning Worst-case analysis

- General result with squared norm regularization

$$
R(\hat{f})+\frac{\lambda}{2}\|\hat{f}\|^{2}-\min _{f \in \mathcal{F}}\left\{R(f)+\frac{\lambda}{2}\|f\|^{2}\right\} \leqslant O\left(\frac{1}{\lambda n}\right)
$$

- Worst-case: $\lambda=O\left(n^{-1 / 2}\right)$

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- For finite dimensional feature spaces $\mathcal{F}=\mathbb{R}^{p}$
- Rates achievable with algorithms of complexity $\mathbf{O}(\mathrm{pn})$
- Stochastic gradient and variants


## Supervised machine learning Worst-case analysis

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$$

- Taking into account the correlation structure of features
- All eigenvalues of the kernel matrix and the covariance matrix
- Between $O\left(n^{-1}\right)$ and $O\left(n^{-1 / 2}\right)$


## Why kernels?

- Finite-dimensional linear models
- Efficient optimization algorithms for a fixed $\lambda$
- Choice of $\lambda$ remains unclear
- Potential underfitting (parametric statistics)


## Why kernels?

- Finite-dimensional linear models
- Efficient optimization algorithms for a fixed $\lambda$
- Choice of $\lambda$ remains unclear
- Potential underfitting (parametric statistics)
- Infinite-dimensional linear models
- Few efficient optimization algorithms for a fixed $\lambda$
- Choice of $\lambda$ remains unclear
- Implicitly adapt the capacity of predictors as $n$ grows (non-parametric statistics)
- Higher risk of overfitting
- In many situations, high-dimensional models and infinite-dimensional models exhibit same issues


## Why kernels?

- Provides good abstraction of high-dimensional models
- Non-linear estimation
- Computer vision, bioinformatics, neuro-imaging
- Implicitly augment the number of features as $n$ grows
- Computational complexity
- Naive optimization above $O\left(n^{2}\right)$


## Why kernels?

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- Computational complexity
- Naive optimization above $O\left(n^{2}\right)$
- Lower and upper bounds on complexity
- Is it possible to avoid quadratic complexity with non-parametric kernel methods?
- Both theoretical and practical issues


## Supervised learning with kernels

- Regularized empirical risk minimization: find $\hat{f}$ solution of

$$
\min _{f \in \mathcal{F}} \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i},\left\langle f, \Phi\left(x_{i}\right)\right\rangle\right)+\frac{\lambda}{2}\|f\|^{2}
$$

- Representer theorem (Kimeldorf and Wahba, 1971): $f$ may be expressed as $\sum_{i=1}^{n} \alpha_{i} \Phi\left(x_{i}\right) \Rightarrow f(x)=\sum_{i=1}^{n} \alpha_{i} k\left(x, x_{i}\right)$
- Positive definite kernel $k\left(x, x^{\prime}\right)=\left\langle\Phi(x), \Phi\left(x^{\prime}\right)\right\rangle$
- Equivalent optimization problem
$-K=$ kernel matrix $\in \mathbb{R}^{n \times n}, K_{i j}=\left\langle\Phi\left(x_{i}\right), \Phi\left(x_{i}\right)\right\rangle=k\left(x_{i}, x_{j}\right)$

$$
\min _{\alpha \in \mathbb{R}^{n}} \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i},(K \alpha)_{i}\right)+\frac{\lambda}{2} \alpha^{\top} K \alpha
$$

## Efficient algorithms for kernel machines Subquadratic running-time complexity - I

- Forbidden to compute the kernel matrix
- Stochastic gradient with cost $O(t)$ at iteration $t$ leads to $O\left(n^{2}\right)$
- Hilbert space iteration: $f_{t}=\left(1-\lambda \gamma_{t}\right) f_{t-1}-\gamma_{t} \ell^{\prime}\left(y_{t}, f_{t-1}\left(x_{t}\right)\right) \Phi\left(x_{t}\right)$
- $f_{t}$ represented as $\sum_{i=1}^{t} \alpha_{t}^{i} \Phi\left(x_{i}\right)$
$-\alpha_{t}^{t}=-\gamma_{t} \ell^{\prime}\left(y_{t}, \sum_{i=1}^{t-1} \alpha_{t-1}^{i} k\left(x_{i}, x_{t}\right)\right)$ and $\alpha_{t}^{1: t-1}=\left(1-\lambda \gamma_{t}\right) \alpha_{t-1}^{1: t-1}$


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- Restricted budget of support vectors
- Forgetron (Dekel et al., 2005), Projectron (Orabona et al., 2008), BGSD (Wang et al., 2012)
- Worst-case guarantees
- Online selection of examples: LASVM (Bordes et al., 2005)


## Efficient algorithms for kernel machines Subquadratic running-time complexity - II

- Random features (Rahimi and Recht, 2007)
- For kernels of the form $k\left(x, x^{\prime}\right)=\mathbb{E}_{\omega}\left[\Phi_{\omega}(x)^{\top} \Phi_{\omega}\left(x^{\prime}\right)\right]$
- Use explicit features $\left(\Phi_{\omega_{i}}(x)\right)_{i}$ for samples $\omega_{i}, i=1, \ldots, p$
- Worst-case guarantees


## Efficient algorithms for kernel machines Subquadratic running-time complexity - II

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- Worst-case guarantees
- Column-sampling
- Low-rank approximation of kernel matrix from a subset of its columns/rows
- Nyström method (Williams and Seeger, 2001), sparse greedy approximations (Smola and Schölkopf, 2000), incomplete Cholesky decomposition (Fine and Scheinberg, 2001), Gram-Schmidt orthonormalization (Shawe-Taylor and Cristianini, 2004), CUR matrix decompositions (Mahoney and Drineas, 2009)


## Column sampling for kernel matrix approximation

- Given a positive semi-definite matrix $K \in \mathbb{R}^{n \times n}$, and $V=\{1, \ldots, n\}$
- Approximation for submatrix $K(V, I)$, where $I \subset V$
- Least-square optimal decomposition:

$$
L=K(V, I) K(I, I)^{-1} K(I, V)=k\left(x_{V}, x_{I}\right) k\left(x_{I}, x_{I}\right)^{-1} k\left(x_{I}, x_{V}\right)
$$



- $K(J, J)$ approximated by $K(J, I) K(I, I)^{-1} K(I, J)$


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$$

- Property: $K \succcurlyeq L$
- Corresponds to feature map $\tilde{\Phi}(x)=k\left(x_{I}, x_{I}\right)^{-1 / 2} k\left(x_{I}, x\right) \in \mathbb{R}^{I}$
- Computation in $O\left(|I|^{2} n\right)$ with incomplete Cholesky decomposition
- Main questions
- Choice of $I$ : pivoting or random sampling
- Cardinality of I


## Column sampling for kernel matrix approximation Previous work

- Bound on $\|K-L\|$
- Mahoney and Drineas (2009); S. Kumar (2012)
- Tools from matrix concentration inequalities
- Bound on prediction performance
- Non sharp two-step approaches
- Worst-case performance (Jin et al., 2011)
- Not taking into account potentially small $\lambda$ (Cortes et al., 2010)




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- Sharp analysis of low-rank approximation for kernel methods
- Column sampling
- No loss in predictive performance
- Choice of regularization parameter


## Kernel ridge regression

- Optimization problem obtained from representer theorem:

$$
\begin{array}{r}
\min _{\alpha \in \mathbb{R}^{n}} \frac{1}{2 n} \sum_{i=1}^{n}\left(y_{i}-(K \alpha)_{i}\right)^{2}+\frac{\lambda}{2} \alpha^{\top} K \alpha \\
\min _{\alpha \in \mathbb{R}^{n}} \frac{1}{2 n}\|y-K \alpha\|^{2}+\frac{\lambda}{2} \alpha^{\top} K \alpha
\end{array}
$$

- Solution: $\alpha=(K+n \lambda I)^{-1} y$
- Prediction on training data: $K \alpha=K(K+n \lambda I)^{-1} y=H y$
- Smoothing matrix $H$


## Fixed design analysis of kernel ridge regression

- $x_{1}, \ldots, x_{n}$ deterministic, $y_{i}=\mathbb{E} y_{i}+\varepsilon_{i}=z_{i}+\varepsilon_{i}, i=1, \ldots, n$
- $C$ covariance matrix of $\varepsilon$, prediction $\hat{z}=K(K+n \lambda I)^{-1} y=H y$
- Bias/variance decomposition of the in-sample prediction error (Wahba, 1990; Hastie and Tibshirani, 1990; Caponnetto and De Vito, 2007)

$$
\begin{aligned}
\frac{1}{n} \mathbb{E}_{\varepsilon}\|\hat{z}-z\|^{2} & =\frac{1}{n}\left\|\mathbb{E}_{\varepsilon} \hat{z}-z\right\|^{2}+\frac{1}{n} \operatorname{tr} \operatorname{var}_{\varepsilon}(\hat{z}) \\
& =\frac{1}{n}\|(H-I) z\|^{2}+\frac{1}{n} \operatorname{tr} C H^{2}
\end{aligned}
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& =\frac{1}{n}\|(H-I) z\|^{2}+\frac{1}{n} \operatorname{tr} C H^{2}
\end{aligned}
$$

which may be classically decomposed in two terms:

$$
\begin{aligned}
\operatorname{bias}(K) & =\frac{1}{n}\|(H-I) z\|^{2}=n \lambda^{2} z^{\top}(K+n \lambda I)^{-2} z \\
\operatorname{variance}(K) & =\frac{1}{n} \operatorname{tr} C H^{2}=\frac{1}{n} \operatorname{tr} C K^{2}(K+n \lambda I)^{-2}
\end{aligned}
$$

## Degrees of freedom

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$$

- When $C=\sigma^{2} I$, variance $(K)=\frac{\sigma^{2}}{n} \operatorname{tr} H^{2}=\frac{\sigma^{2}}{n} \operatorname{tr} K^{2}(K+n \lambda I)^{-2}$
- Degrees of freedom: $\operatorname{tr} K^{2}(K+n \lambda I)^{-2}$ or $\operatorname{tr} K(K+n \lambda I)^{-1}$
- Implicit number of param. of smoothing mat. $H=K(K+n \lambda I)^{-1}$
- Equal to $p$, if $\operatorname{rank}(K)=p$ and $\lambda=0$


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- Implicit number of param. of smoothing mat. $H=K(K+n \lambda I)^{-1}$
- Equal to $p$, if $\operatorname{rank}(K)=p$ and $\lambda=0$
- Definition: maximal marginal degrees of freedom

$$
d=n\|\operatorname{diag}(H)\|_{\infty}=n\left\|\operatorname{diag}\left(K(K+n \lambda I)^{-1}\right)\right\|_{\infty}
$$

Note: $\left.\left.\operatorname{tr} H^{2} \leqslant \operatorname{tr} H=\| \operatorname{diag}(H)\right)\left\|_{1} \leqslant n\right\| \operatorname{diag}(H)\right) \|_{\infty}=d$

## Degrees of freedom vs. rank of column sampling approximation

- Column-sampling leads to explicit p-dimensional features
- Degrees of freedom correspond to an implicit number $d$ of parameters
- What is the link between $p$ and $d$ ?
- same (or better) performance than full rank problem


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- Column-sampling leads to explicit p-dimensional features
- Degrees of freedom correspond to an implicit number $d$ of parameters
- What is the link between $p$ and $d$ ?
- same (or better) performance than full rank problem
- We "must" have $p \geqslant d$, if
(a) column sampling approximation obtained from held out data
(b) generalization error optimal
- Does $p=O(d)$ suffice?


## Generalization performance of column sampling (Bach, 2012)

- Assumptions
$-z \in \mathbb{R}^{n}, K \in \mathbb{R}^{n \times n}$ positive semidefinite, $\lambda>0$,
$-d=n\left\|\operatorname{diag}\left(K(K+n \lambda I)^{-1}\right)\right\|_{\infty}$ and $R^{2}=\|\operatorname{diag}(K)\|_{\infty}$
$-\varepsilon \in \mathbb{R}^{n}$ random vector with finite variance and zero mean
- $I$ uniform random subset of $p$ indices in $\{1, \ldots, n\}$
- Column sampling approximation $L=K(V, I) K(I, I)^{-1} K(I, V)$
- Estimate $\hat{z}_{K}=(K+n \lambda I)^{-1} K(z+\varepsilon)$ and $\hat{z}_{L}=(L+n \lambda I)^{-1} L(z+\varepsilon)$


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- For any $\delta \in(0,1)$, if $p \geqslant\left(\frac{32 d}{\delta}+2\right) \log \frac{n R^{2}}{\delta \lambda}$, then

$$
\frac{1}{n} \mathbb{E}_{I} \mathbb{E}_{\varepsilon}\left\|\hat{z}_{L}-z\right\|^{2} \leqslant \frac{1}{n}(1+4 \delta) \mathbb{E}_{\varepsilon}\left\|\hat{z}_{K}-z\right\|^{2} .
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$$

- Discussion
- Proof technique: approximation of subsampled covariance matrices (Tropp, 2011; Gittens, 2011)
- No assumptions on eigengap or on the noise
- Relative approximation guarantee
- Expectations, both with respect to the data (i.e., $\mathbb{E}_{\varepsilon}$ ) and the sampling of columns (i.e., $\mathbb{E}_{I}$ )
- Different from good approximation of $K$
- Sufficient lower-bound for required rank $p$
- Logarithmic term in $\lambda$


## Beyond least-square regression Self-concordant analysis of logistic regression

- Logistic loss $\ell(u)=\log \left(1+e^{-u}\right)$
- No closed-form expressions
- Self-concordance (Nesterov and Nemirovski, 1994)
$-g: \mathbb{R} \rightarrow \mathbb{R}$ is self-concordant iff $\forall u \in \mathbb{R},\left|g^{\prime \prime \prime}(u)\right| \leqslant 2 g^{\prime \prime}(u)^{3 / 2}$
- Extension for logistic loss (Bach, 2010): $\forall u \in \mathbb{R},\left|g^{\prime \prime \prime}(u)\right| \leqslant g^{\prime \prime}(u)$
- Allows non-asymptotic analysis of logistic regression
- With exact first-order term
- Replace covariance by Fisher information matrix


## Optimal choice of the regularization parameter $\lambda$

- Eigenvalues of $K=\Theta\left(n \mu_{i}\right), i=1, \ldots, n$, with $\sum_{i} \mu_{i}=\Theta(1)$ so that $\operatorname{tr} K=\Theta(n)$
- Coordinates of $z$ on eigenbasis of $K=\Theta\left(\sqrt{n \nu_{i}}\right)$ with $\sum_{i} \nu_{i}=\Theta(1)$ so that $\frac{1}{n} z^{\top} z=\Theta(1)$

| $\left(\mu_{i}\right)$ | $\left(\nu_{i}\right)$ | variance | bias | optimal $\lambda$ | pred. perf. | $d$ | condition |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  |  |  |  |  |  |  |  |
| $i^{-2 \beta}$ | $i^{-2 \delta}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{2}$ | $n^{-1 /(2+1 / 2 \beta)}$ | $n^{1 /(4 \beta+1)-1}$ | $n^{1 /(4 \beta+1)}$ | $2 \delta>4 \beta+1$ |
| $i^{-2 \beta}$ | $i^{-2 \delta}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{(2 \delta-1) / 2 \beta}$ | $n^{-\beta / \delta}$ | $n^{1 /(2 \delta)-1}$ | $n^{1 /(2 \delta)}$ | $2 \delta<4 \beta+1$ |
| $i^{-2 \beta}$ | $e^{-\kappa i}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{2}$ | $n^{-1 /(2+1 / 2 \beta)}$ | $n^{1 /(4 \beta+1)-1}$ | $n^{1 /(4 \beta+1)}$ |  |
| $e^{-\rho i}$ | $i^{-2 \delta}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\left(\log \frac{1}{\lambda}\right)^{1-2 \delta}$ | $\exp \left(-n^{1 /(2 \delta)}\right)$ | $n^{1 /(2 \delta)-1}$ | $n^{1 /(2 \delta)}$ |  |
| $e^{-\rho i}$ | $e^{-\kappa i}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\lambda^{2}$ | $n^{-1 / 2}$ | $\log n / n$ | $\log n$ | $\kappa>2 \rho$ |
| $e^{-\rho i}$ | $e^{-\kappa i}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\lambda^{\kappa / \rho}$ | $n^{-\rho / \kappa}$ | $\log n / n$ | $\log n$ | $\kappa<2 \rho$ |

- Always assume $\delta>1 / 2, \beta>1 / 2, \rho>0, \kappa>0$


## Optimal choice of the regularization parameter $\lambda$

| $\left(\mu_{i}\right)$ | $\left(\nu_{i}\right)$ | variance | bias | optimal $\lambda$ | pred. perf. | $d$ | condition |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $i^{-2 \beta}$ | $i^{-2 \delta}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{2}$ |  |  |  |  |
| $i^{-2 \beta}$ | $i^{-2 \delta}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{(2 \delta-1) / 2 \beta}$ | $n^{-\beta /(2+1 / 2 \beta)}$ | $n^{1 /(4 \beta+1)-1}$ | $n^{1 /(4 \beta+1)}$ | $2 \delta>4 \beta+1$ |
| $i^{-2 \beta}$ | $e^{-\kappa i}$ | $n^{-1} \lambda^{-1 / 2 \beta}$ | $\lambda^{2}$ | $n^{1 /(2 \delta)-1}$ | $n^{1 /(2 \delta)}$ | $2 \delta<4 \beta+1$ |  |
| $e^{-\rho i}$ | $i^{-2 \delta}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\left(\log \frac{1}{\lambda}\right)^{1-2 \delta}$ | $\exp \left(-n^{1 /(2 \delta)}\right)$ | $n^{1 /(2 \delta)-1}$ | $n^{1 /(2 \delta)}$ |  |
| $e^{-\rho i}$ | $e^{-\kappa i}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\lambda^{2}$ | $n^{-1 / 2}$ | $\log n / n$ | $\log n$ | $\kappa>2 \rho$ |
| $e^{-\rho i}$ | $e^{-\kappa i}$ | $n^{-1} \log \frac{1}{\lambda}$ | $\lambda^{\kappa / \rho}$ | $n^{-\rho / \kappa}$ | $\log n / n$ | $\log n$ | $\kappa<2 \rho$ |

- Best possible performance (Johnstone, 1994; Steinwart et al., 2009)
- if $\nu_{i}=O\left(i^{-2 \delta}\right): O\left(n^{1 / 2 \delta-1}\right)$
- if $\nu_{i}=O\left(e^{-\kappa i}\right): O(\log n / n)$
- Faster decay of components $\left(\nu_{i}\right)$ of $K \approx$ smoother functions
- Faster decay of eigenvalues $\left(\mu_{i}\right)$ of $K \approx$ smaller feature space
- Overfitting if feature space too large
- Numerical problems if feature space too small


## Optimization algorithms with column sampling Twice-differentiable losses

- Given rank $p$ and regularization parameter $\lambda$

1. Select at random $p$ columns of $K$ (without replacement)
2. Compute $\Phi \in \mathbb{R}^{n \times p}$ such that $\Phi \Phi^{\top}=K(V, I) K(I, I)^{-1} K(I, V)$ using incomplete Cholesky decomposition
3. Minimize $\min _{w \in \mathbb{R}^{p}} \frac{1}{n} \sum_{i=1}^{n} \ell\left(y_{i},(\Phi w)_{i}\right)+\frac{\lambda}{2}\|w\|^{2}$ using Newton's method (i.e., a single linear system for the square loss).

- Complexity $O\left(p^{2} n\right) \approx O\left(d^{2} n\right)$
- Robustness to ill-conditioning and in particular to small values of $\lambda$
- Choice of $p$ in practice?


## Simulations on synthetic examples

- Periodic smoothing splines on $[0,1]$ and points $x_{1}, \ldots, x_{n}$ uniformly spread over $[0,1]$
- $k(x, y)=\sum_{i=1}^{\infty} 2 \mu_{i} \cos 2 i \pi(x-y)$, and $f(x)=\sum_{i=1}^{\infty} 2 \nu_{i}^{1 / 2} \cos 2 i \pi x$
- $\nu_{i}=i^{-2 \delta}, \mu_{i}=i^{-2 \beta}, \delta=8, \beta=1,4,8$



- Left: regularization parameter $\lambda$, right: predictive performance
- Right: sufficient rank to obtain $1 \%$ worse predictive performance


## Simulations on pumadyn datasets

- Sufficient rank to obtain $1 \%$ worse predictive performance, over the degrees of freedom



- From left to right: pumadyn datasets $32 f h, 32 n h, 32 n m$


## Conclusions

- Analysis of column sampling for kernel least-squares regression
- Degrees of freedom: both statistical and computational roles
- Extensions
- Beyond uniform sampling (Boutsidis et al., 2009; S. Kumar, 2012)
- Random design using results from Hsu et al. (2011)
- Achieve $O(d n)$ running-time complexity
- Beyond least-squares regression, e.g., logistic regression (Bach, 2010), SVM (Blanchard et al., 2008)
- Online setting with properly decaying regularization parameter
- Relationship with averaged stochastic gradient (Polyak and Juditsky, 1992)


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