ACAI-05 ADVANCED COURSE ON KNOWLEDGE DISCOVERY

Evaluation Methodology

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Motivation

- evaluating performance of models
 - predictive error (most common)
 - complexity, comprehensibility, ...
- in order to perform tasks such as
 - model selection choose the best model
 - model comparison test how significant are differences
 - model assesment performance on new (future/unseen) data

Talk Outline

- predictive error/accuracy
 - how to estimate it?
 - bias-variance trade-off
 - comparison of models
- different settings/tasks
 - predicting probabilities
 - misclassification costs
 - regression
- other criteria
 - complexity, comprehensibility



Basic Notation

- Y target variable
 - numeric: regression task
 - discrete: classification task
- X vector of input variables
- D data set consisting of (x,y) pairs
- unknown function f(X): $Y = f(X) + \varepsilon$ – ε – intrinsic target noise
- prediction model f*(X)
- prediction $Y^* = f^*(X)$



1. predictive error (accuracy)

Loss Function

- loss function measures the error btw.
 - Y measured/observed target value
 - f*(X) predicted target value
- classification models
 - -0-1 loss: $L(Y,f^*(X)) = freq(Y \neq f^*(X))$
 - log-likelihood (later)
- regression models
 - squared error: $L(Y,f^*(X)) = (Y f^*(X))^2$
 - absolute error: $L(Y,f^*(X)) = |Y f^*(X)|$



Predictive Error (Accuracy)

- "true" predictive error
 - expected value of the loss function
 - over the whole population

$$Error(f^*) = E[L(Y,f^*(X))]$$

- for 0-1 loss function (classification)
 - the error is between 0 and 1
 - Accuracy(f*) = 1 Error(f*)
- How to estimate Error(f*)?



Sample Error

- sample predictive error

 - average loss over a data sample S
 consisting of N examples (x_i,y_i)

$$Error_{S}(f^{*}) = 1/N \cdot \sum_{(x_{i},y_{i}) \in S} L(y_{i},f^{*}(x_{i}))$$

- training error
 - error estimated on training data sample
- testing error
 - error estimated on test (unseen) data

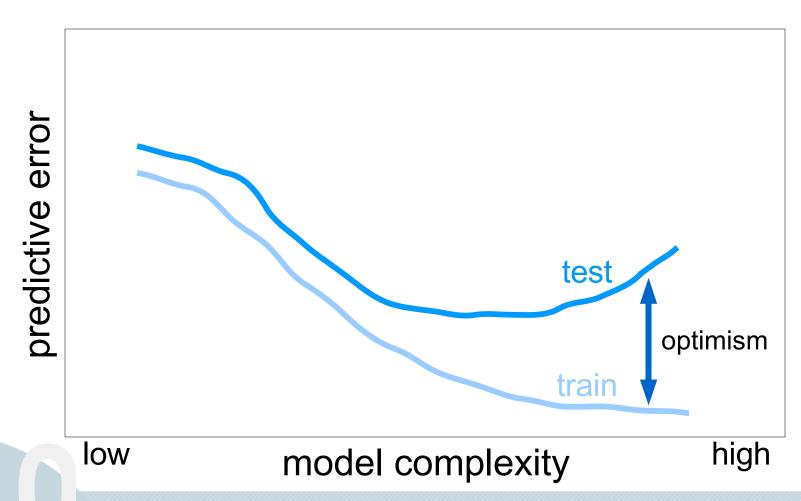


Training vs. Test Error (1)

- common mistake
 - estimate error on train data only
 - resubstitution error
 - too optimistic (lower error)
 - do not reveal the behavior of the model on new (unseen/future) data
- correct approach
 - estimate error on test data
 - unseen in training phase
- MHY IS THIS SO?

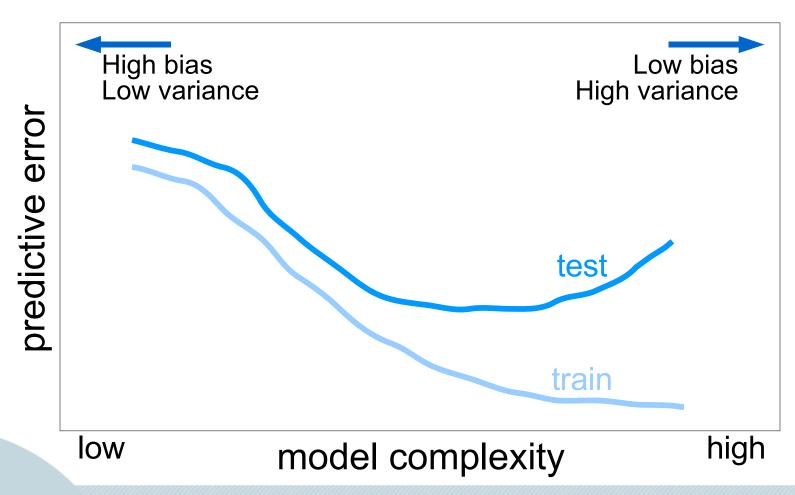


Training vs. Test Error (2)



2. bias-variance trade-off

Bias-Variance (B-V) Trade-Off



B-V Decomposition (1)

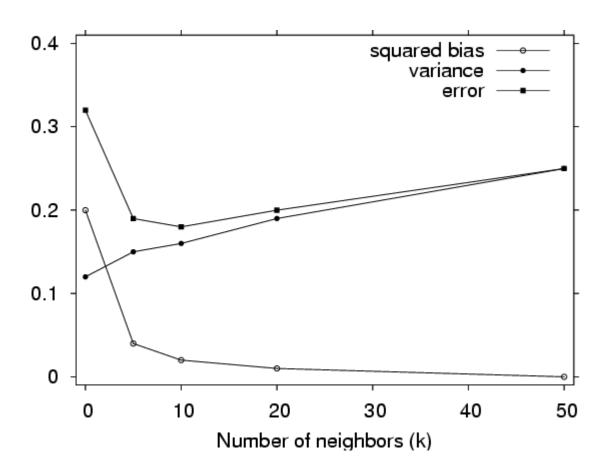
Error(x)
 = E[(y - f*(x))²]
 = E[(y - f(x) + f(x) - f*(x))²]
 = E[ε²] + E[(f(x) - f*(x))²]
 = E[ε²] + E[(f(x) - Ef*(x) + Ef*(x) - f*(X))²]
 = noise + bias² + variance

- bias² = $E[(f(x) Ef^*(x))^2]$
- variance = $E[(f^*(x) Ef^*(x))^2]$

B-V Decomposition (2)

- intrinsic target noise
- bias term
 - measures how close the average model produced by a particular learning algorithm will be to the target function
- variance term
 - measures how models produced by a learning algorithm vary

B-V: An Example



B-V Decomposition: Methods

- empirical B-V decomposition
 - on an arbitrary data set
 - performed by multiple runs of an algorithm
 - on different data samples
- description of methods (further reading):
 - squared loss function [Geman et al. 1992]
 - 0-1 loss function [Kohavi and Wolpert 1996]
 - unified [Domingos 2000]

3. estimating predictive error

Data Supply Problems

- all data samples
 - should be large (representative) enough
 - training: obtaining better model
 - test: obtaining better error estimate
- however, in real applications
 - amount of data limited
 - due to practical problems
- usual solution: holdout procedure
 - keep some data out of training sample
 - for testing purposes



Holdout Procedures (Typical)

model assessment

train (75%)

test (25%)

model selection and assessment

train (50%)

validation (25%)

test (25%)

Holdout Estimates: Reliability

- how reliable is the holdout estimate
 - we estimated error rate of 30%
 - (1) on a test sample of 1000 examples
 - (2) on a test sample of 40 examples
 - which is more reliable/confident?
- confidence intervals
- with 95% probability the error lies in
 - -(1) interval [30%-3%, 30%+3%] = [27%,33%]
 - (2) interval [30%-14%, 30%+14%] = [16%,44%]



Confidence Intervals

- different methods for calculating them
 - based on Bernoulli Processes
 - see further reading
- Weka Book
 - Section 5.2
 - Predicting Performance
- ML Book
 - Section 5.2.2
 - Confidence Intervals for Discrete-Valued
 Hypotheses



How to Improve Reliability?

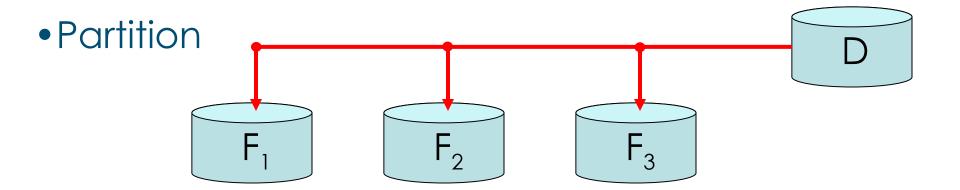
- repetitive holdout estimates
 - instead of running a single holdout
 - repeat it number of times
 - average the estimates obtained
- how to split into train/test samples?
 - cross validation (CV)
 - leave-one-out (special case of CV)
 - bootstrap sampling

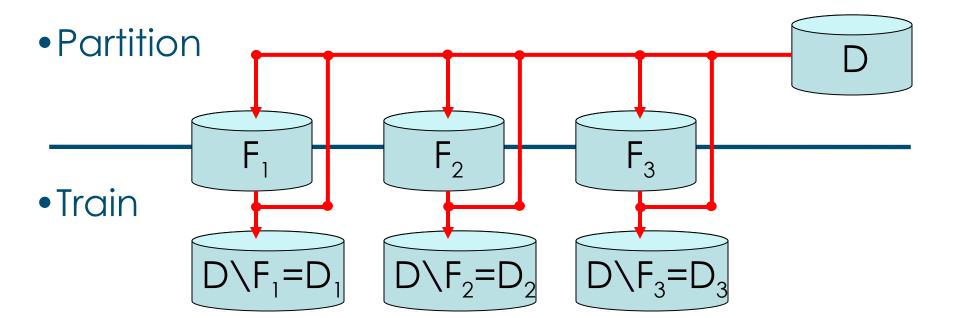


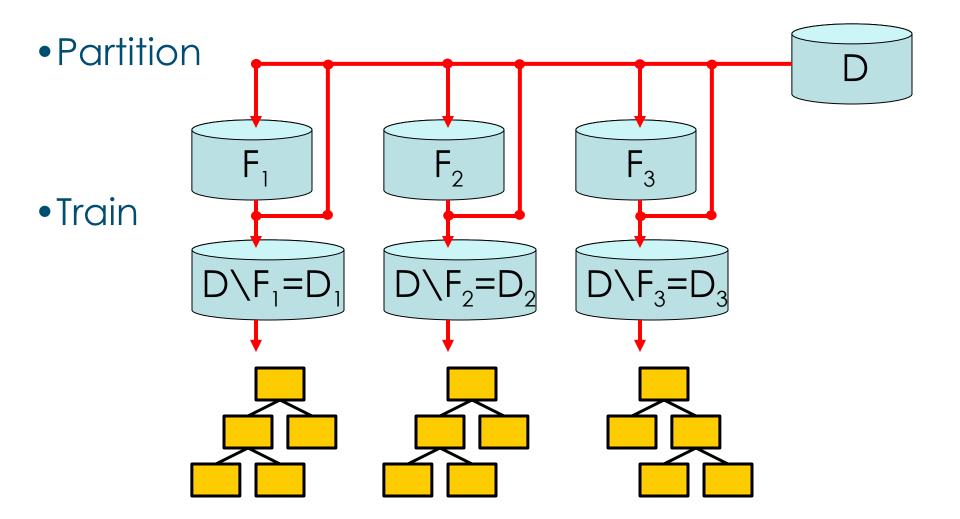
Cross Validation (CV)

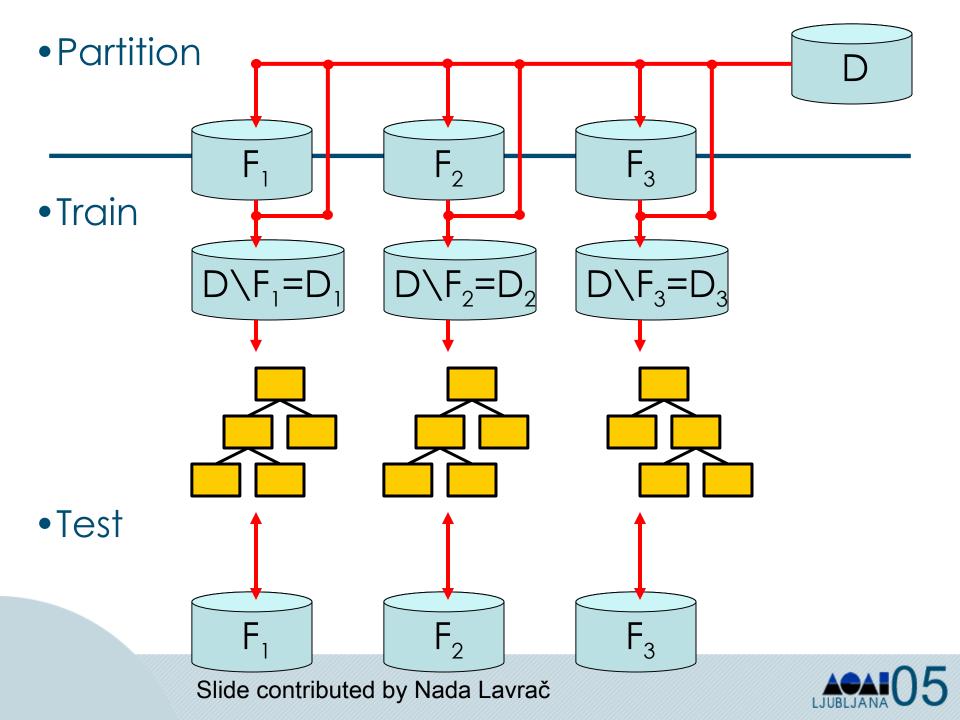
- three steps: partition, train, and test
- partition
 - _ randomly into k folds (F₁, F₂, ... F_k)
- repeat k times (once for each F_i)
 - train on D\F
 - test (estimate sample error) on F
- average error estimates











CV: Number of Folds

- large number of folds:
 - training sets very similar to each other
 - high variance of the estimate
 - maximal number of folds N: leave-one-out
 - illustrate high variance on an example
- small number of folds:
 - lower variance, but
 - training set might be too small
- recommended compromise: 5 or 10!



CV: Stratification

- folds sampling not completely random
 - "due to bad luck" we can end-up with non-representative data sample
 - distribution of target variable values vary
- stratified sampling
 - each fold has similar distribution of target variable values
- different stratification methods for
 - classification (similar distributions)
 - regression (similar average values)



Bootstrap Sampling

- three steps: sample, train and test
 - sample N examples from D with replacement (an example can be used more than once)
 - train on the (multi)set of sampled examples \$
 - test (estimate sample error) on D\S
- number of distinct training examples
 - -0.632·N (see ESL or Weka Book)
 - comparable to 2-fold CV: pessimistic estimate
 - combine estimated test error (Error_{D\s}) with the training error (Error_s)

$$Error_{0.632} = 0.632 \cdot Error_{D \setminus S} + 0.368 \cdot Error_{S}$$

Alternatives to Sampling

- in-sample estimates
 - Error_{TEST} = Error_{TRAIN} + Optimism
 - problem reduced to estimating "optimism"
- several in-sample estimates
 - Akaike information criterion (AIC)
 - Bayesian information criterion (BIC)
 - Minimum description length (MDL)
 - further details in the ESL book

MDL Principle

- the best model is the one that minimizes
 - the model size
 - the amount of information necessary to encode model errors
 - i.e., information necessary to reconstruct training data
- model estimate thus is a sum of
 - model size: L(M)
 - training data D w.r.t. M: L(D | M)
- coding method important

4. comparing predictive errors

Paired t-test

- perform CV for both models (M₁, M₂)
 - on same k data folds F_1 , F_2 , ... F_k
 - obtain estimates $Error_{Fi}(M_1)$ and $Error_{Fi}(M_2)$
 - calculate Diff_i = Error_{Fi} (M_1) Error_{Fi} (M_2)
 - t-statistic t = mean(Diff) / sqrt(var(Diff)/k)
- calculated t-statistic
 - follows Student's distribution
 - with k-1 degrees of freedom
 - see ML or Weka Book for details

Non-Paired t-test

- allows for comparison with models
 - estimated using different CV folds
 - or even different number of CV folds
- Different estimate of var(Diff) needed
 - see Weka book for details

Comparison: Open Issue

- comparing models on limited data
 - is still an open issue
- ongoing research work focus on
 - criticism of existing methods [Bengio and Grandvalet 2004]
 - comparing existing and proposing new alternatives [Diettrich 1998; Bouckaert 2004]

5. different settings/tasks

Predicting Probabilities (1)

- predicting distribution of Y values
 - instead of predicting Y value itself
 - example: weather forecast (sunny/rainy)
 - prediction: sunny 75%, rainy 25%
- 0-1 loss function not good
 - wrong prediction with 55% probability
 - is better than
 - wrong prediction with 75% probability
 - different loss function needed

Predicting Probabilities (2)

- Notation:
 - p_i predicted probability of j-th value of Y
 - p_k predicted probability of actual Y value
 - a actual probability of j-th value of Y
 - Note that only $a_k = 1$, rest are 0
- alternative loss-functions
 - quadratic $L(Y,p^*(X)) = \sum_j (a_j p_j)^2 = 1 2 p_k + \sum_j p_j^2$ log-likelihood $L(Y,p^*(X)) = -2 \sum_j a_j \cdot \log(p_j) = -2 \log(p_k)$

Errors of Regression Models

- mean squared error (MSE) correspond to
 - squared error loss function
 - $-L(Y,f^*(X)) = (Y f^*(X))^2$
- commonly used RMSE = sqrt(MSE)
- mean absolute error correspond to
 - absolute error loss function
 - $-L(Y,f^*(X)) = |Y f^*(X)|$
- these error measures are scale dependent



Relative and Scale Independent Errors

- relative squared error (RSE)
 - -RSE = MSE / var(Y)
 - error relative to the error of the simplest predictor (predicting mean(Y))
 - RSE value greater than 1 (one) means that the predictor performs worse than simplest
 - comparable across domains
- correlation coefficient (r²)
 - scale independent
 - see Weka book

Misclassification Costs

- binary classification problem
- two kind of errors
 - false positive negative example predicted as positive
 - false negative positive example predicted as negative
- different costs assigned to each
 - examples: loan decisions, diagnosis

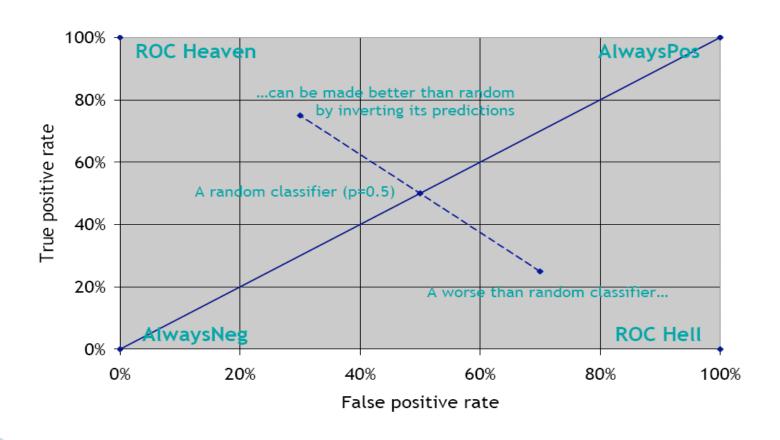
Confusion Matrix

	predicted class	
actual class	yes	no
yes	true positives	false negatives
no	false positives	true negatives

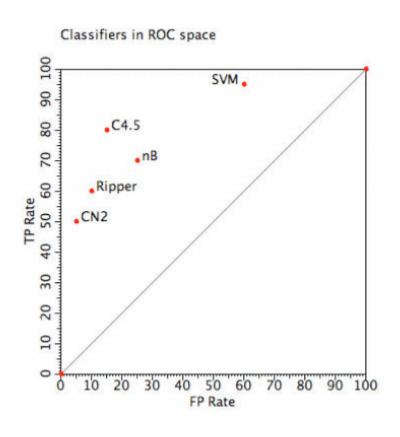
- Error = (FP + FN) / N
- Accuracy = (TP + TN) / N
- TPrate = Recall = TP / (TP + FN)
- FPrate = FP / (FP + TN)



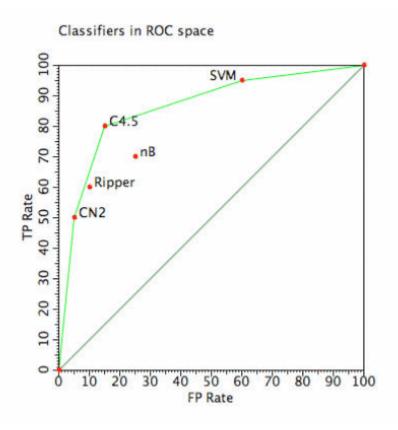
ROC Space



ROC Plot



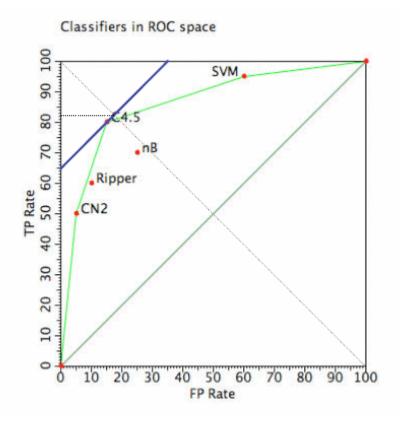
ROC Convex Hull



- classifiers on the CH achieve best accuracy for some class distributions
- classifiers not on the CH are always suboptimal

ASALO5

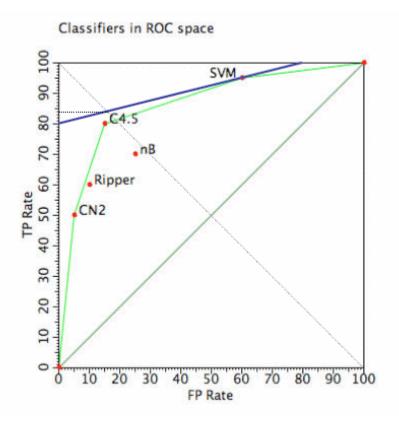
Optimal Classifier (1)



- C4.5 optimal for uniform class distribution (slope of the blue line)
- Accuracy: 82%

A9A!05

Optimal Classifier (2)



- SVM optimal for class distribution where we have 4 times as many positives as negatives (slope of the blue line)
- Accuracy: 84%



Incorporating Costs

- for skewed class distribution
 - slope equals neg/pos
- for misclassification costs
 - slope equals (neg*C(+/-))/(pos*C(-/+))
- further details
 - [Provost and Fawcett 2001]
 - [Flach 2003]



6. other performance measures

Model Complexity

- many different measures
 - model dependent
- decision trees
 - number of nodes, parameters in leaf nodes
- decision rules
 - number of rules, literals, coverage
- in general
 - number of parameters
 - encoding length (MDL like)



Model Comprehensibility

- difficult to assess
 - most methods involve manual work
 - can not be fully automated
- tests
 - can human expert understand the model?
 - can he/she use it for manual prediction?
 - how well?
- roughly related
 - rule interestigness [Fuernkranz and Flach 05]



7. further reading

Further Reading: Books

- Weka Book
 I.H.Witten and E.Frank (2000) Data Mining: Practical Machine Learning Tools and Techniques with Java Implementations. Morgan Kaufmann. [Chapter 5].
- ML Book
 T.M.Mitchell (1997) Machine Learning. McGraw-Hill.
 [Chapter 5].
- ESL Book
 T.Hastie, R. Tibshirani, and J. Friedman (2001) The Elements of Statistical Learning. Springer-Verlag.
 [Chapter 7].

Further Reading: Articles (1)

- Y.Bengio and Y.Grandvalet (2004) No unbiased estimator of the variance of k-fold cross-validation. Journal of Machine Learning Research 5: 1089-1105.
- R.R.Bouckaert (2004) Estimating Replicability of Classifier Learning Experiments. In Proceedings of Twenty-First International Conference on Machine Learning.
- T.Dietterich (1998) Approximate statistical tests for comparing supervised classification learning algorithms. Neural Computation 10(7): 1895-1924.

Further Reading: Articles (2)

- P.Domingos (2000) A unified bias-variance decomposition and its applications. In Proceedings of the Seventeenth International Conference on Machine Learning (ICML-2000), pages 231-238.
- S.Geman, G.Beinenstock, and R.Doursat (1992) Neural networks and the bias/variance dilemma. Neural Computation 4: 1-58.
- R. Kohavi and D.H.Wolpert (1996) Bias plus variance decomposition for zero-one loss functions. In Proceedings of the Thirteenth International Conference on Machine Learning (IMCL-1996), pages 275-283.

Further Reading: Articles (3)

- P.A.Flach (2003) The geometry of ROC space. In Proceedings of the Twentieth International Conference on Machine Learning (ICML-2003), pages 194-201.
- J.Fuernkranz and P.A.Flach (2005) ROC'n'Rule learning towards a better understanding of covering algorithms. *Machine Learning* 58(1): 39-77.
- F.J.Provost and T.Fawcett (2001) Robust classification analysis for performance evaluation. *Machine Learning* 42(3): 203-231.