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A Dirty Model for Multitask Learning

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Motivation

- Modern Settings: **High-Dimensional** Problems
 - number of observations $n \ll$ number of variables p
 - Biology, Vision, Nanotechnology, Financial Analysis, ...
- **Low-Dimensional** Structure only hope for consistency?
 - Sparsity, Block Sparsity, Low-Rank, Graphical model Structure
- What if parameters do not have such clean structure?

This talk:

- Superposition of structures: still low-dimensional but surprisingly useful for “dirty” data



Multitask Learning

- Multiple tasks with some “shared” structure

Problem:

- Learn tasks **jointly** (as opposed to **separately**)
 - e.g. Optical Character Recognition (OCR)

Writer 1

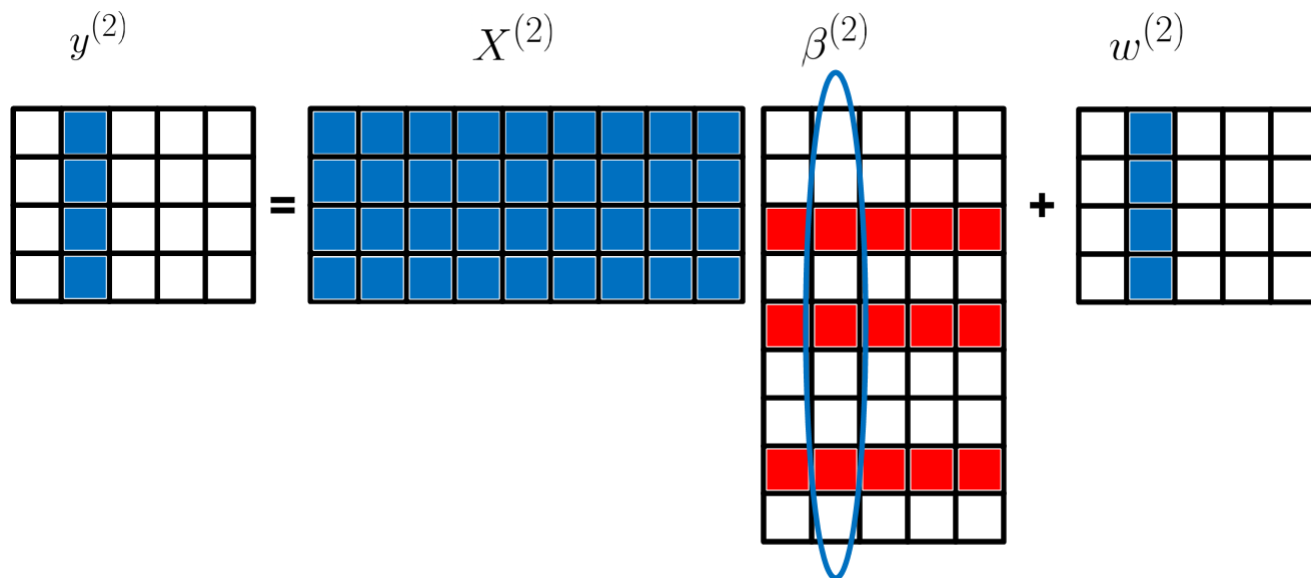
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Writer 2

A	A	A	A	A	A
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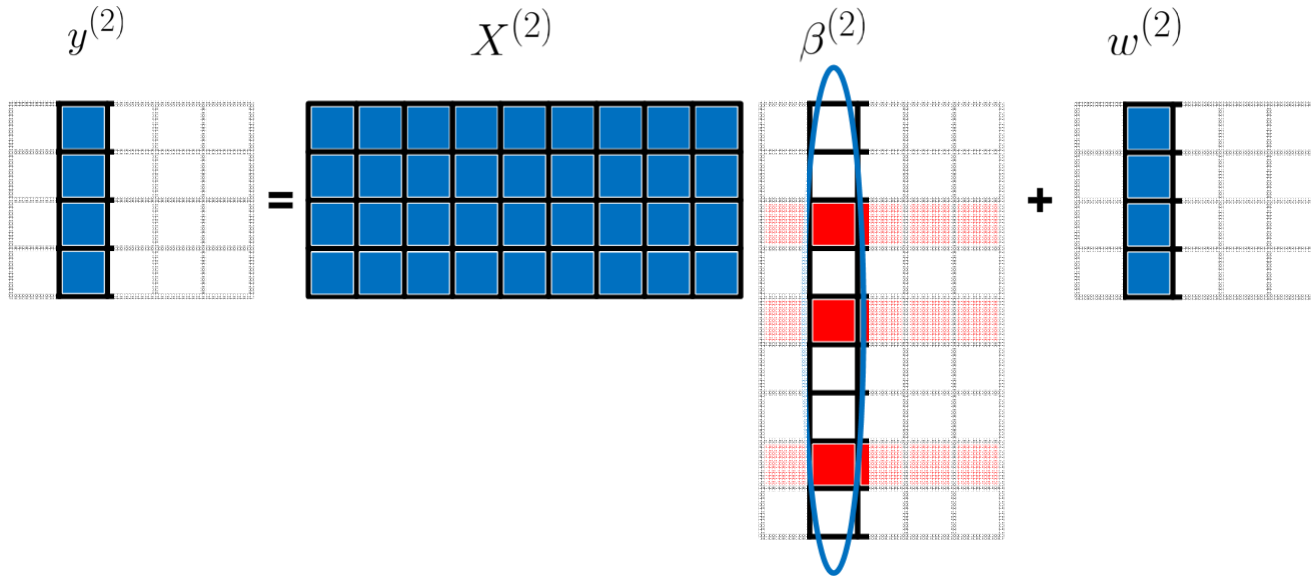
Multiple Linear Regressions



- Linear Model: $y^{(k)} = X^{(k)}\beta^{(k)} + w^{(k)}$ for all tasks $1 \leq k \leq r$
- **Problem:** Estimate β given n_k samples of $X_i^{(k)}$, $y_i^{(k)}$



Clean Model I: Sparsity

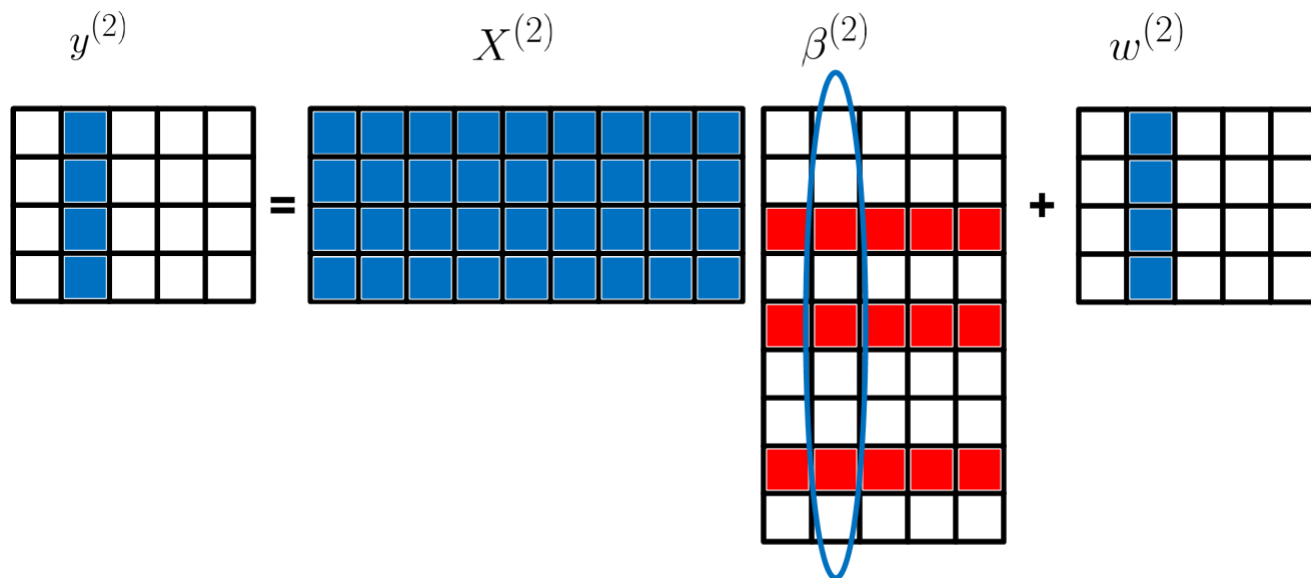


- Sparsity of each task modeled **independently**.
- LASSO [Tibshirani '96]

$$\min_{\beta^{(k)}} \frac{1}{n_k} \sum_{i=1}^{n_k} \left\| y_i^{(k)} - X_i^{(k)} \beta^{(k)} \right\|_2^2 + \lambda_k \left\| \beta^{(k)} \right\|_1$$



Clean Model II: Block-sparsity



- Block-sparse structure: shared sparsity
- Group LASSO [Obozinski et al; Negahban et al; Huang et al]

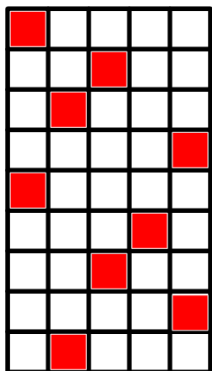
$$\min_{\beta} \sum_{k=1}^r \frac{1}{n_k} \sum_{i=1}^{n_k} \left\| y_i^{(k)} - X_i^{(k)} \beta^{(k)} \right\|_2^2 + \lambda \|\beta\|_{1,\infty}$$

where $\|\beta\|_{1,\infty} = \sum_j \max_k |\beta_j^{(k)}|$ (sum of maximum of rows)

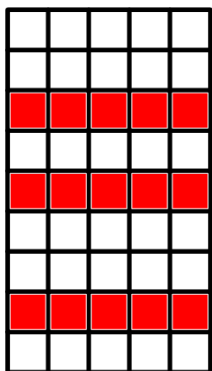


Existing Methods Performance

- LASSO
 - Does not model shared sparsity



- Group LASSO
 - Does not model individual sparsity

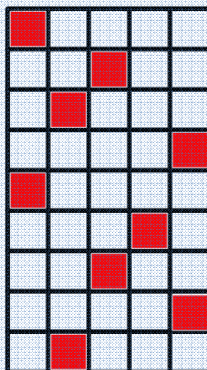




Existing Methods Performance

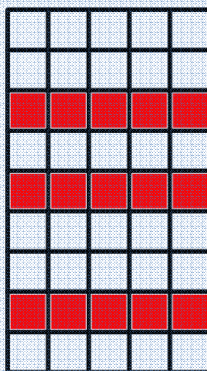
- LASSO

- Does not model shared sparsity

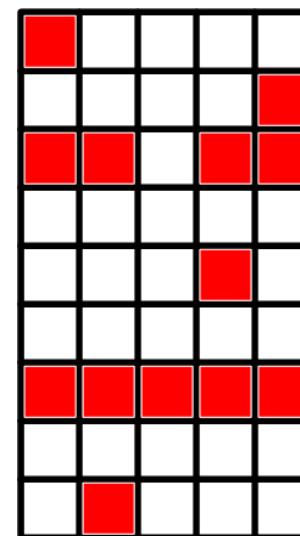


- Group LASSO

- Does not model individual sparsity



Realistic Data

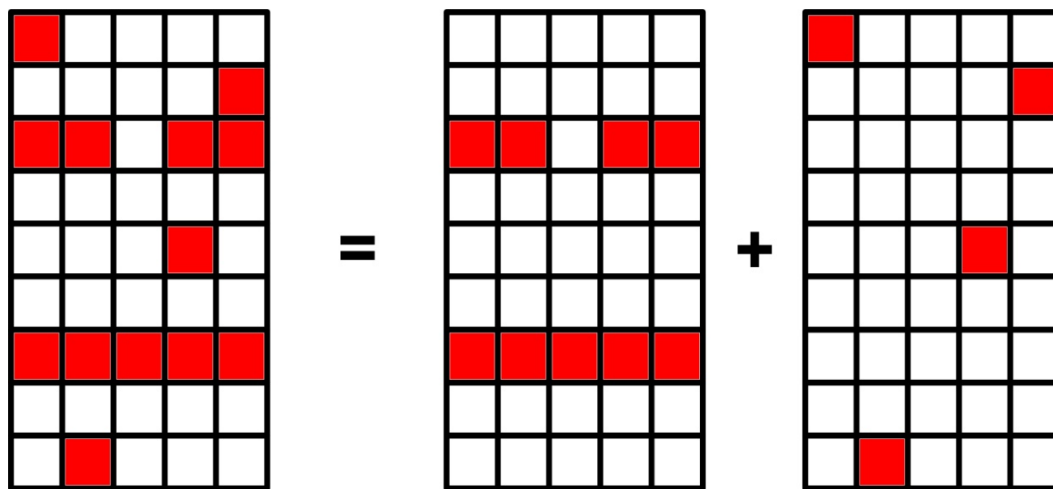


β



Dirty Statistical Model

- Superposition of parameters with diff. structures



$$\beta = B + S$$

$$\|B\|_{1,\infty}$$

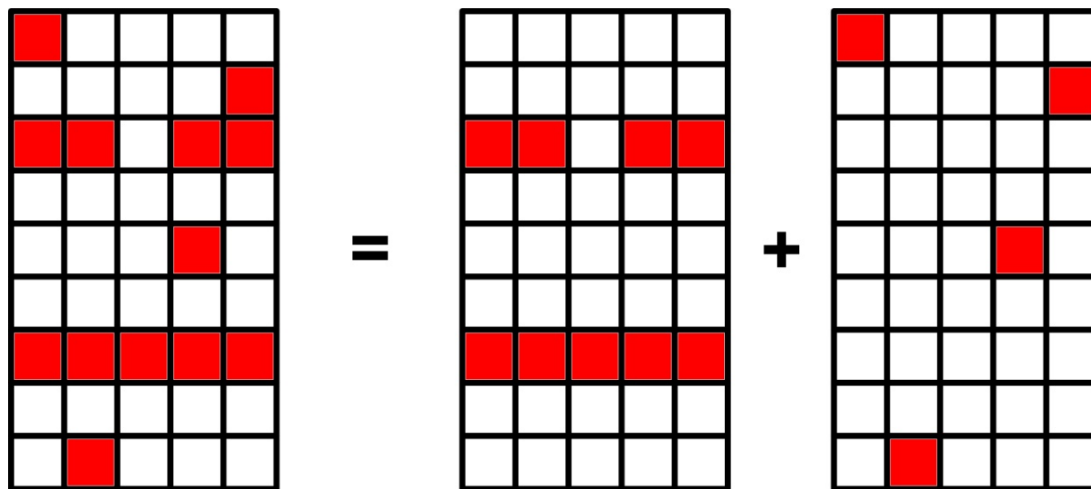
$$\|S\|_{1,1}$$

shared features

non-shared features



Dirty Statistical Model



$$\beta = B + S$$

Algorithm:

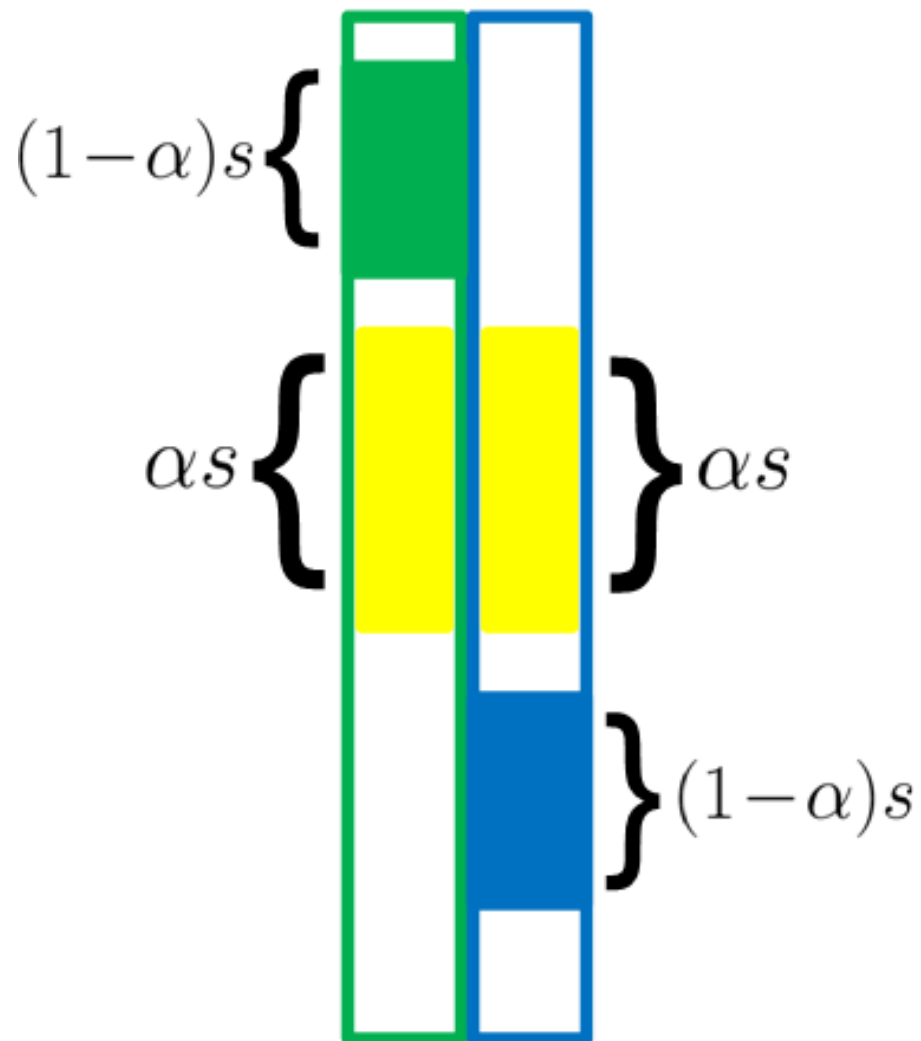
$$\min_{B,S} \sum_{k=1}^r \frac{1}{n_k} \sum_{i=1}^{n_k} \left\| y_i^{(k)} - X_i^{(k)} \left(B^{(k)} + S^{(k)} \right) \right\|_2^2 + \lambda_b \|B\|_{1,\infty} + \lambda_s \|S\|_{1,1}$$

output $\hat{\beta} = \hat{B} + \hat{S}$

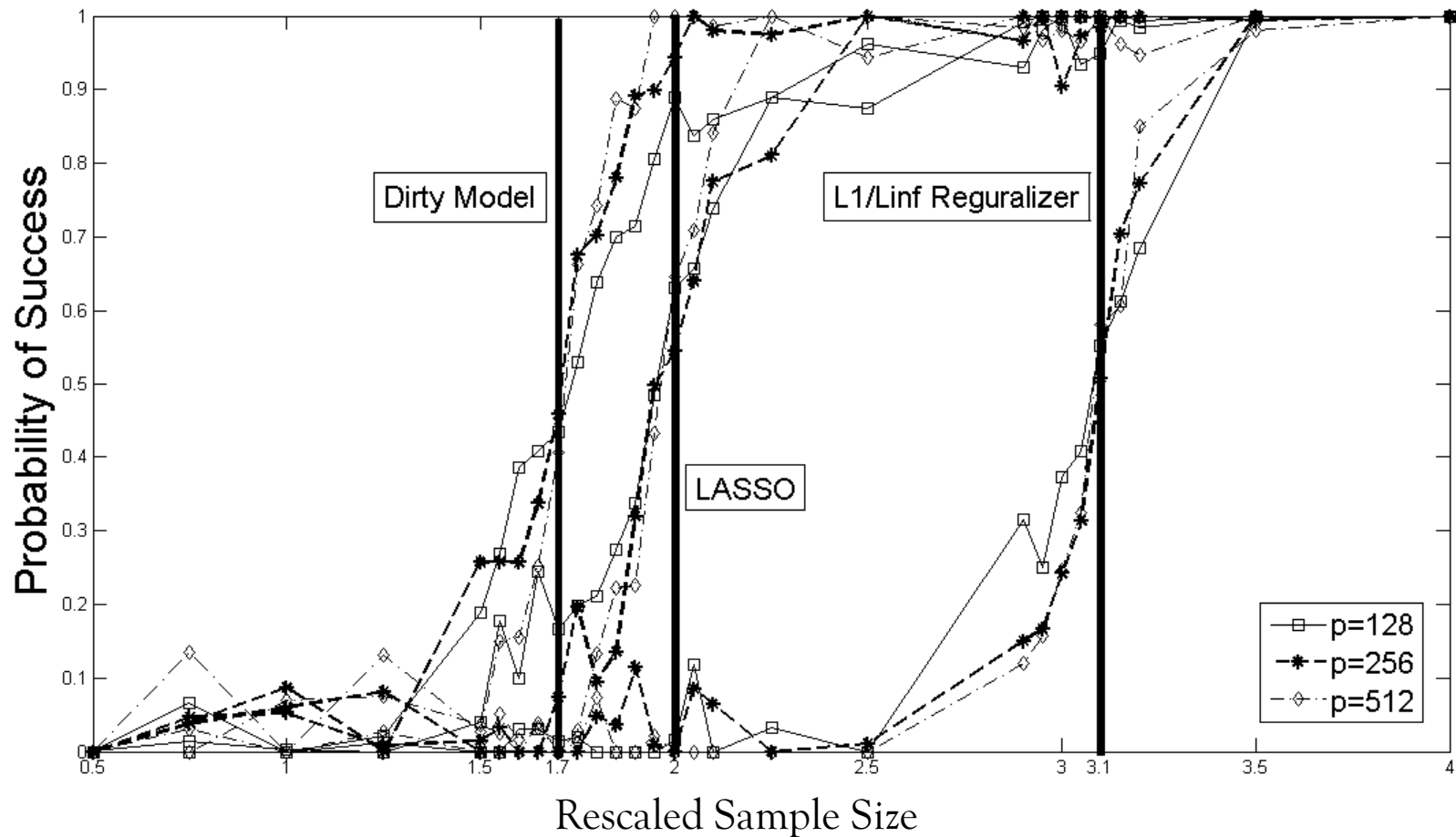


Two Tasks Case

- Each task depends on “s” features
- α -portion of the features overlaps



Little overlap: $\alpha = 0.3$





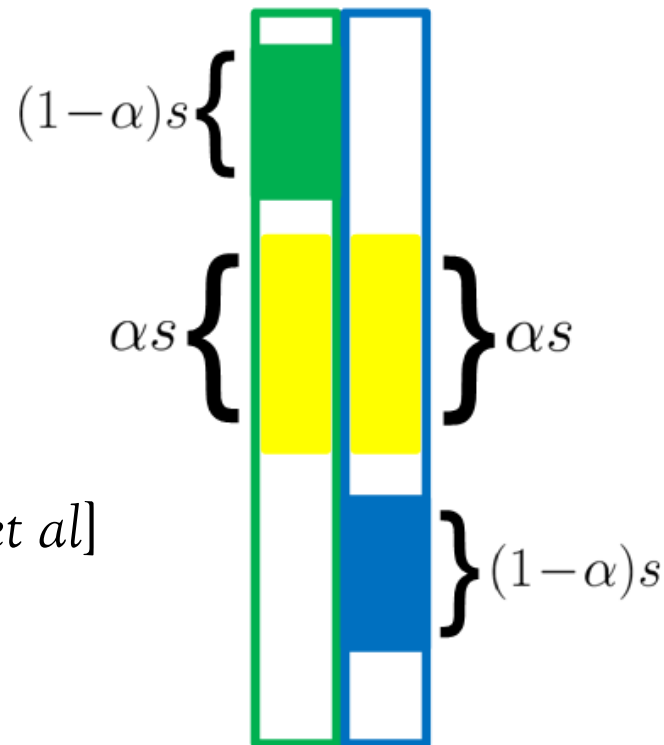
Phase Transition for Two Tasks

– LASSO:

$$\frac{n}{s \log(p)} \approx 2 \quad [\text{Wainwright}]$$

– Group LASSO:

$$\frac{n}{s \log(p)} \approx 4 - 3\alpha \quad [\text{Negahban et al}]$$





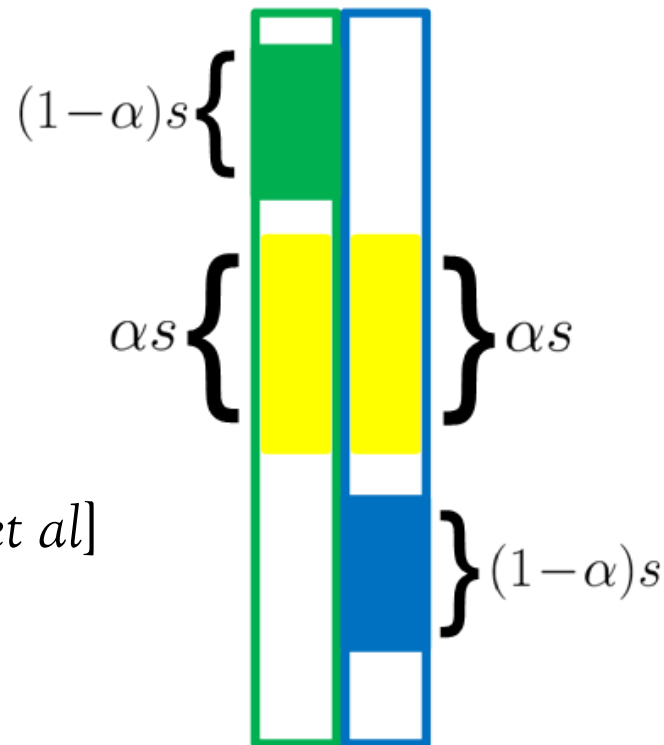
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Consequences:

$\alpha < 2/3$:: Lasso is better

$\alpha > 2/3$:: Group-Lasso is better



Phase Transition for Two Tasks

– LASSO:

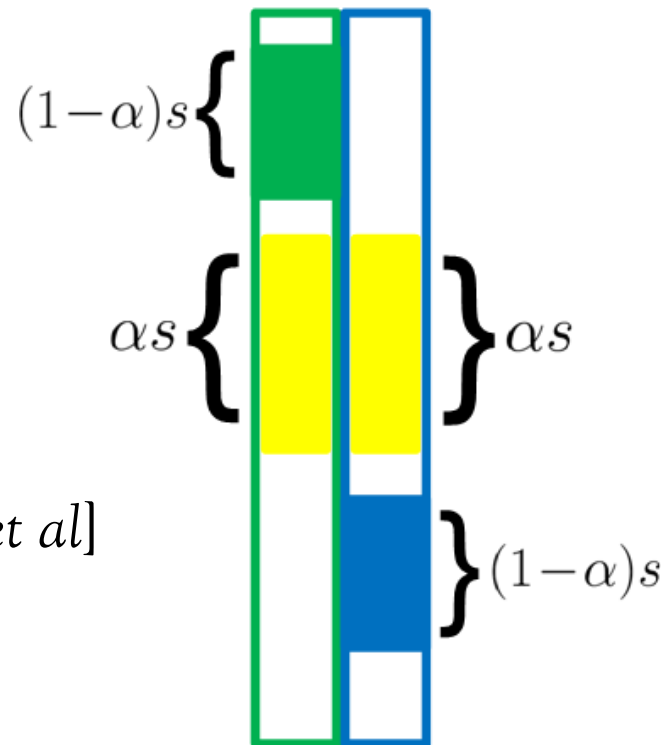
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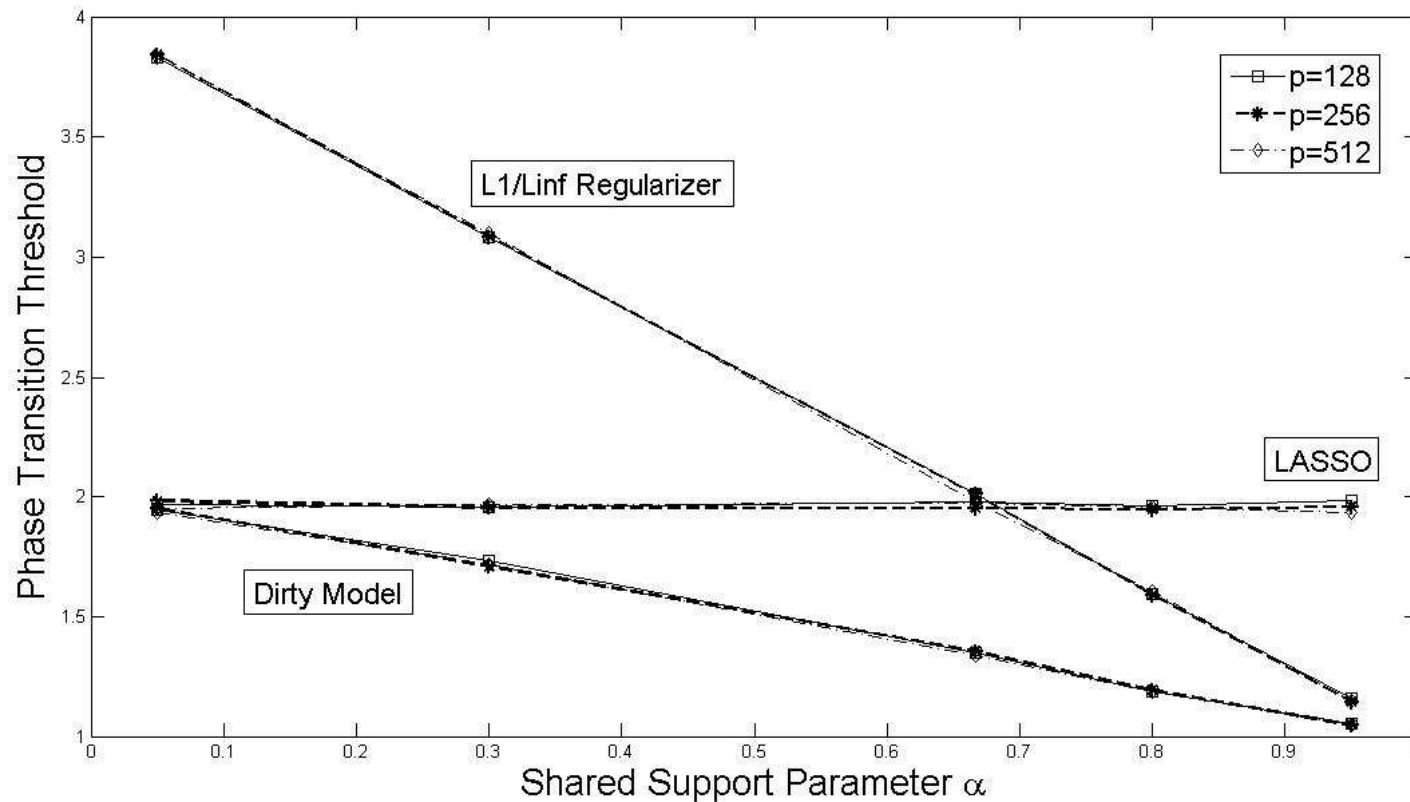
– Dirty Model:

$$\frac{n}{s \log(p)} \approx 2 - \alpha$$





Comparison



$$\text{Theorem. } \frac{n}{s \log(p)} \approx 2 - \alpha$$



Standard Assumptions

□ \mathcal{U}_k : Support of task k

$$\square \mathcal{U} = \bigcup_k \mathcal{U}_k$$

□ $X \sim N(0, \Sigma)$

$$\square s = \max_k |\mathcal{U}_k|$$

• Incoherence Condition

$$\max_{j \notin \mathcal{U}} \sum_{k=1}^r \left\| \Sigma_j \mathcal{U}_k \Sigma^{-1} \mathcal{U}_k \right\|_1 < 1$$

• Eigenvalue Condition

$$\min_{1 \leq k \leq r} \lambda_{\min} \left(\Sigma \mathcal{U}_k \mathcal{U}_k \right) > 0$$



General r -Task Case

Theorem (Gaussian Design): Under previous assumptions and

$$\lambda_b \asymp \sqrt{\frac{r \log(p)}{n}} \qquad \lambda_s \asymp \sqrt{\frac{\log(pr)}{n}}$$

If $n \geq K sr \log(p)$ then with probability at least $1 - C_1 \exp(-C_2 \log(p))$:

(a) There is no false exclusion:

$$\text{Supp}(\beta) \subseteq \text{Supp}(\hat{\beta}) \qquad \|\hat{\beta} - \beta\|_{\infty, \infty} = \mathcal{O}\left(\sqrt{\frac{s \log(pr)}{n}}\right)$$

(b) If $\beta_{\min} = \Omega\left(\sqrt{\frac{s \log(pr)}{n}}\right)$, there is no false inclusion:

$$\text{Supp}(\beta) = \text{Supp}(\hat{\beta})$$



Two-Task Case

Theorem (Phase Transition): Under previous assumptions, for two tasks with α -sharedness in the support, then with high probability:

(Success) The algorithm finds the true signed support of β provided

$$\frac{n}{s \log(p - (2 - \alpha)s)} > 2 - \alpha$$

(Failure) The algorithm will **NOT** find the true signed support of β if

$$\frac{n}{s \log(p - (2 - \alpha)s)} < 2 - \alpha$$



General Dirty Models

$$\beta = B + S$$

- **Dirty Models:** “Superposition of Simple Structures”
 - Sparse + Low-Rank
 - Latent Variables, Graph Clustering, PCA with corruptions, etc
 - Block-Sparse + Low-Rank
 - Collaborative Filtering, PCA with Outliers, etc
 - More Details in NIPS ‘10 Wkshp: [Robust Statistical Learning](#)



Summary

- Multi-task learning is challenging when there is partial overlap across tasks
 - relevant structure is neither sparsity nor block-sparsity
- A superposition of simple structures, i.e., dirty model surprisingly useful for modeling such “dirty” structure.
- For the multi-task learning problem, dirty model outperforms solo-structured lasso and group-lasso.