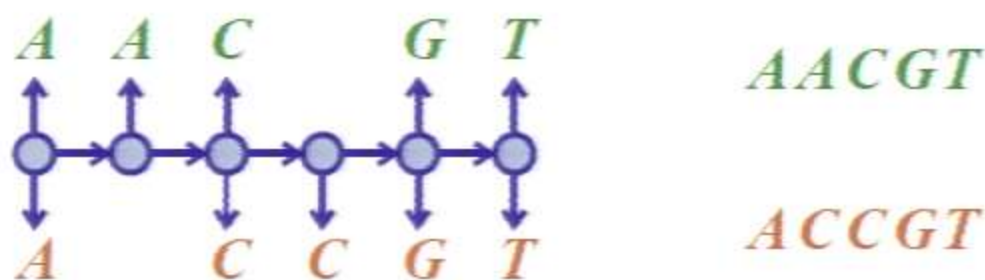


Unsupervised Learning of Finite State Transducers

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Spotlight session 1, December 6th, 2013, Poster Fri67



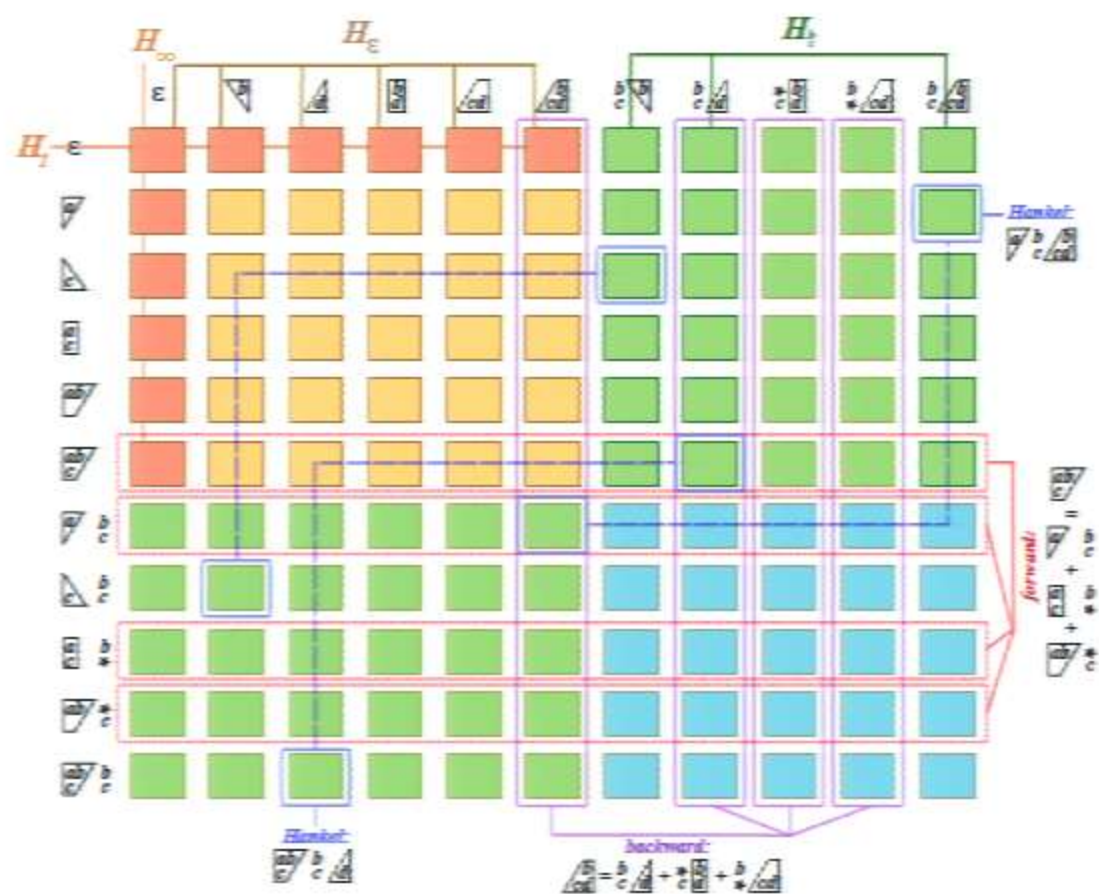
- Sequential graphical model with latent states
- Two types of observations : input / output

Unsupervised Learning :

- FST : $\alpha_1 \in \mathbb{R}^d$, $\beta_\infty \in \mathbb{R}^d$, $M_x \in \mathbb{R}^{d^2}$, $p\left(\begin{smallmatrix} x_1 x_2 x_3 \\ y_1 y_2 y_3 \end{smallmatrix}\right) = \alpha_1^T M_{y_1}^{x_1} M_{y_2}^{x_2} M_{y_3}^{x_3} \beta_\infty$
- Expectation-Maximization (*forward-backward*) : prone to local minimum

Spectral Method

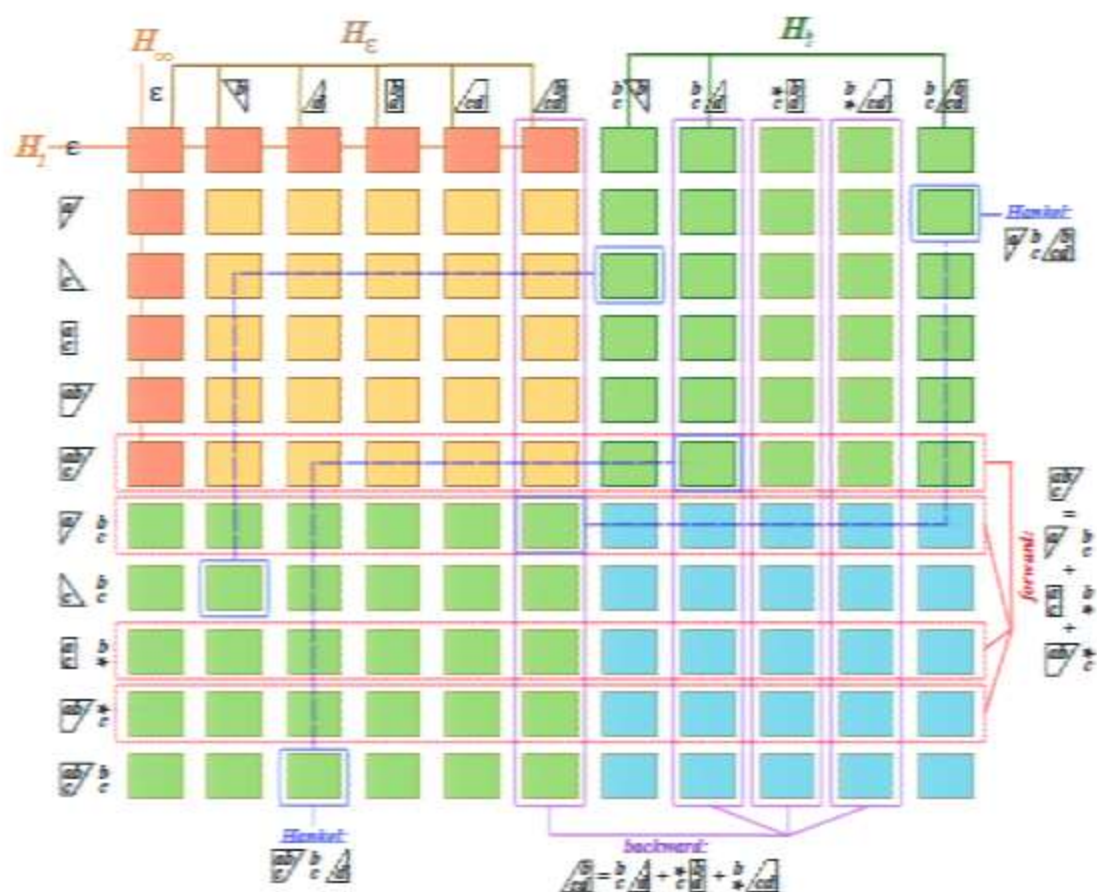
- Low-rank approximation of H_ϵ (SVD, ...)
- Computed FST : $\alpha_1^\top = H_1 H_\epsilon^+$, $\beta_\infty = H_\infty$, $M_x = H_x H_\epsilon^+$
- Statistical consistency



$$H(c, c^{bb}) = H(c^b, c^b) = p_S(c^b, c^b)$$

Unsupervised Spectral Method

- Observable statistics = top/left border coefficients of H_ϵ
- Completion : minimize $rk(H)$ such that H satisfies the constraints O, K, F, B
- Statistical consistency

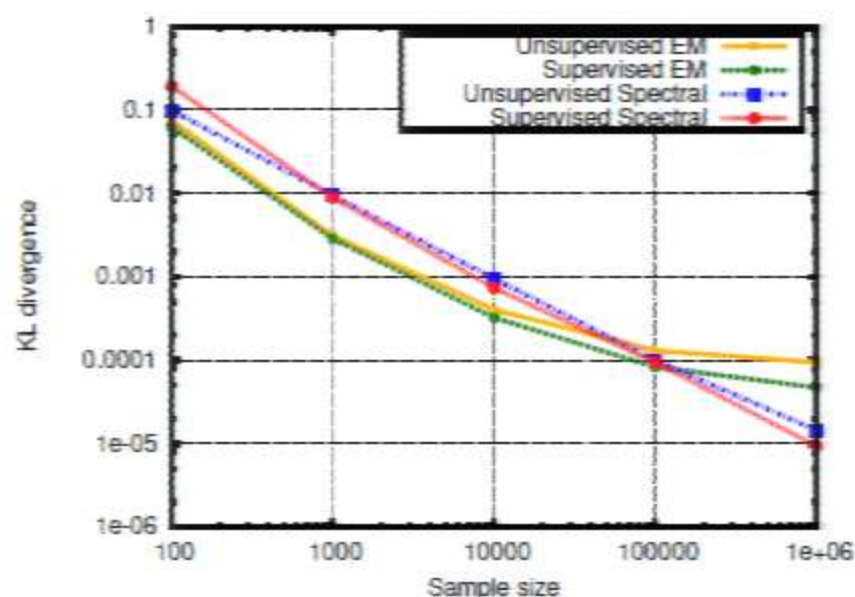
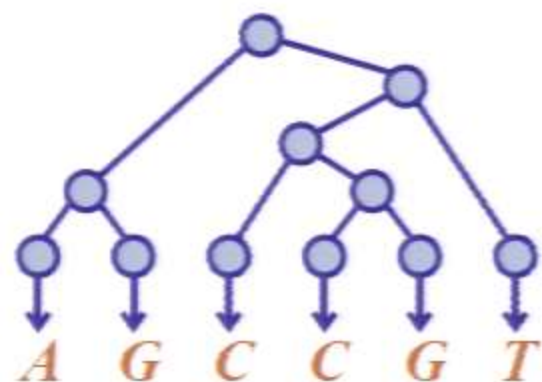


$$H\left(\begin{matrix} b & b \\ c & c \end{matrix}\right) = H\left(\begin{matrix} b & b \\ c & c \end{matrix}\right) = ?$$

Solving the rank minimization problem

- Convex relaxation $\|H\|_*$ of the objective $rk(H)$ (e.g. FISTA)
- Greedy algorithms

Other applications



- Nested sequences
- PCFGs (cf. **Spectral Learning Workshop** December 10, 2013)