

Reconciling “priors” & “priors” without prejudice? NIPS Spotlight

Rémi Gribonval Pierre Machart

INRIA
Centre de Rennes - Bretagne Atlantique

pierre.machart@inria.fr



december, 6th

Motivation

Linear inverse problems: $y = \mathbf{A}z + b$, with Gaussian noise b



Let's use penalized
least-squares!

$$\operatorname{argmin}_z \frac{1}{2} \|y - \mathbf{A}z\|^2 + \phi(z) \quad (\text{PLS})$$



But that's just
MAP estimation!

Maximum A Posteriori with prior $e^{-\phi(z)}$

Is (PLS) specifically cut for unknowns with distribution $e^{-\phi}$?

Main Results

$$\operatorname{argmin}_z \frac{1}{2} \|y - \mathbf{A}z\|^2 + \phi(z) \quad (\text{PLS})$$

Theorem (Flavor of the main result)

$\forall P_Z, \mathbf{A}, \exists \phi_{\text{MMSE}}$ s.t. the *Minimum Mean Square Error estimator* $\mathbb{E}(Z|Y = y)$,
is the only minimizer of (PLS)

Corollary (On the multiple valid interpretations)

For a large class of penalties ϕ ,

MAP with prior $P_{\text{MAP}} \propto \exp(-\phi(z)) \Leftrightarrow (\text{PLS}) \Leftrightarrow \text{MMSE}$ with prior $P_{\text{MMSE}} \neq P_{\text{MAP}}$

\Rightarrow choosing a regularizer $\phi \neq$ designing for a specific $P_Z!$

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Forget the BatLasso,
my data clearly
isn't Lapla...

Shut up and come
see poster Fri34!!

