Video Pop-up:
Monocular 3D Reconstruction of Dynamic Scenes

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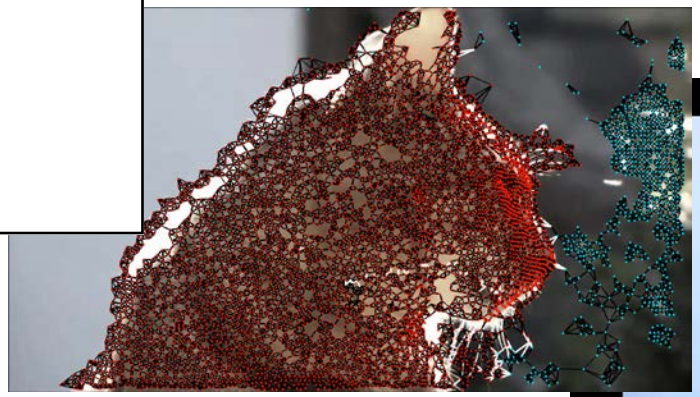
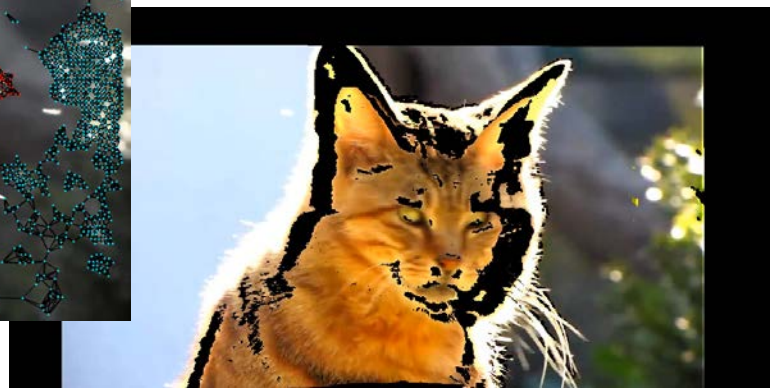
† JOINT FIRST AUTHORSHIP

Aim

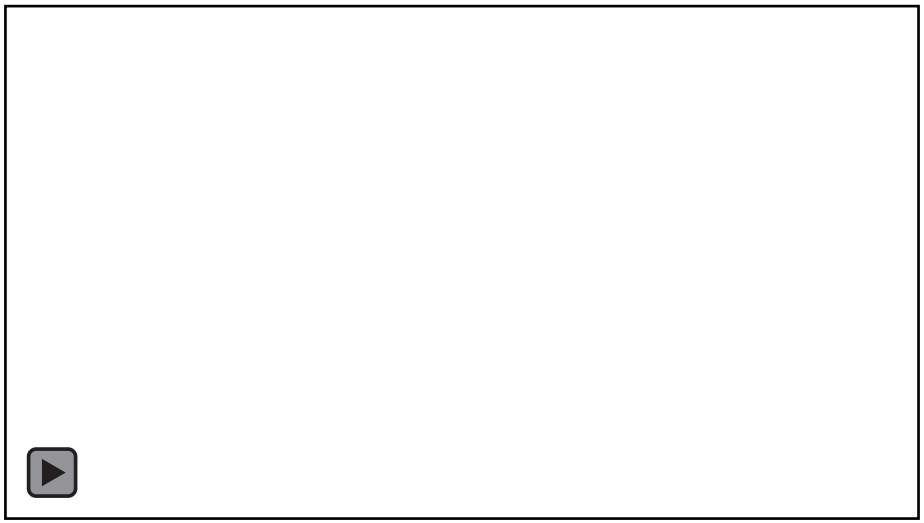




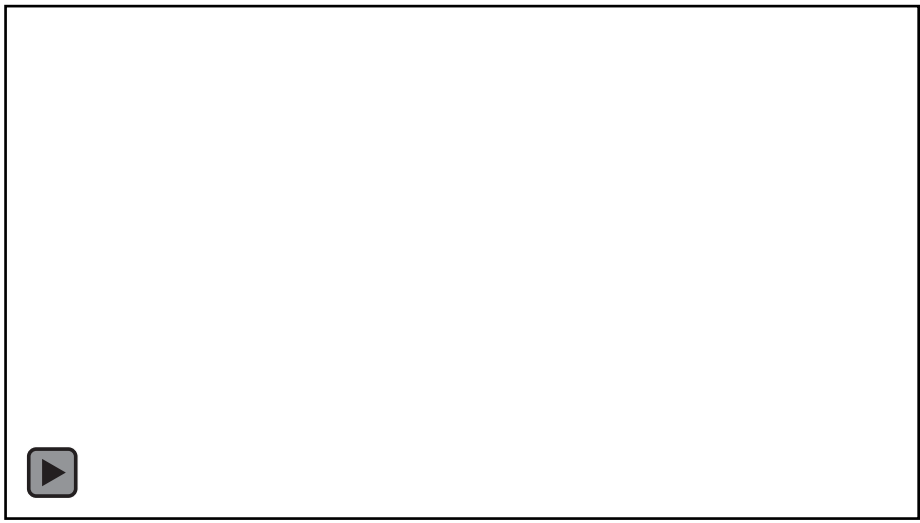
Raw video → Segment objects + Reconstruction

Completely Unsupervised

Our approach

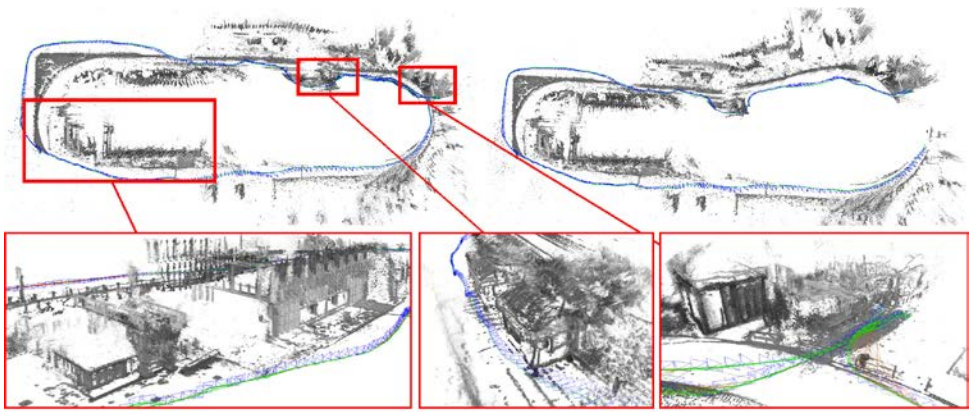


Rigid Parts



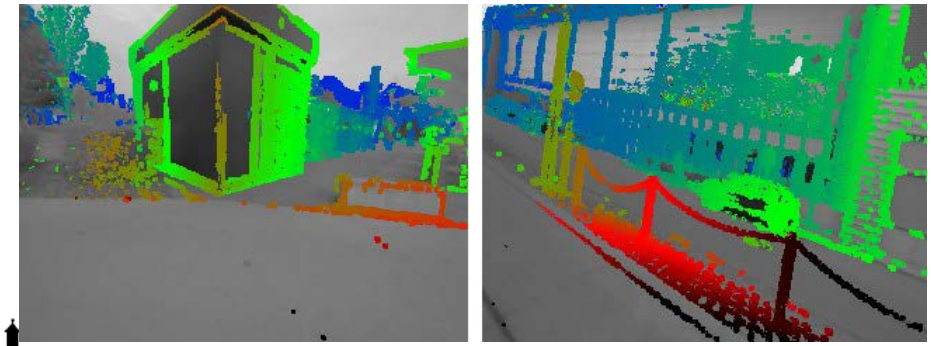
Piecewise rigid Objects

Rigid reconstruction as gold standard



Fast, reliable, low powered

e.g. LSD-SLAM



Recovers background rather than object of interest in most videos

Non-rigid Structure from Motion

Single object

Presegmented

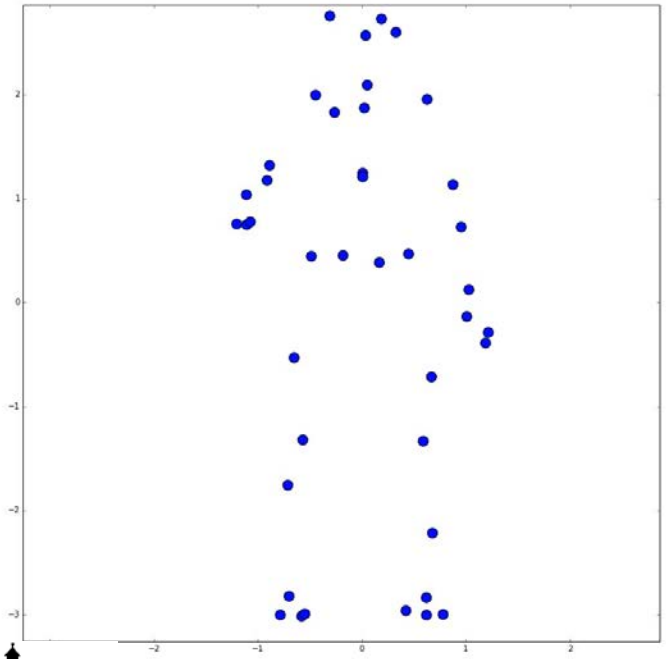
Additional training data for best results

What about the whole world?

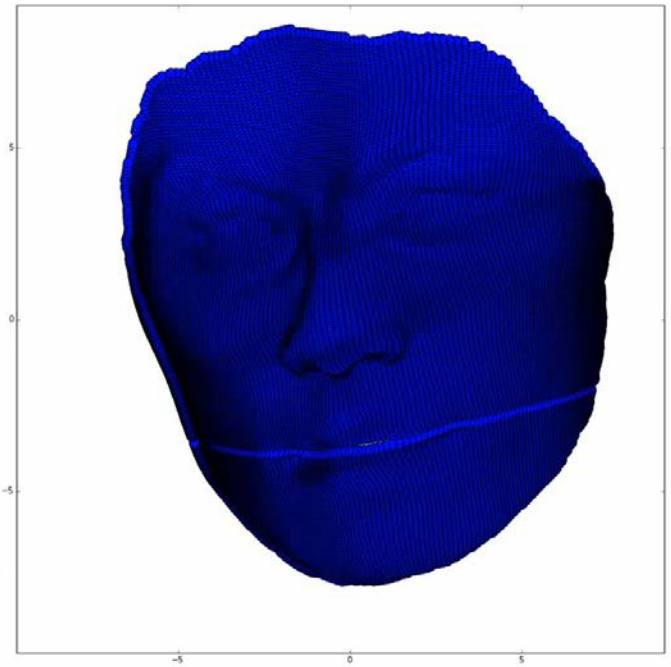
Suwajanakorn et al.

Generic Non-rigid – Synthetic Inputs

DAI ET AL.



GARG ET AL.

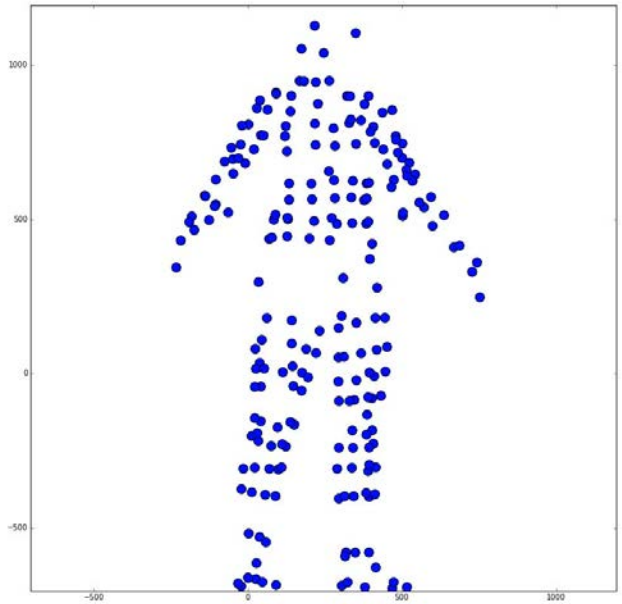


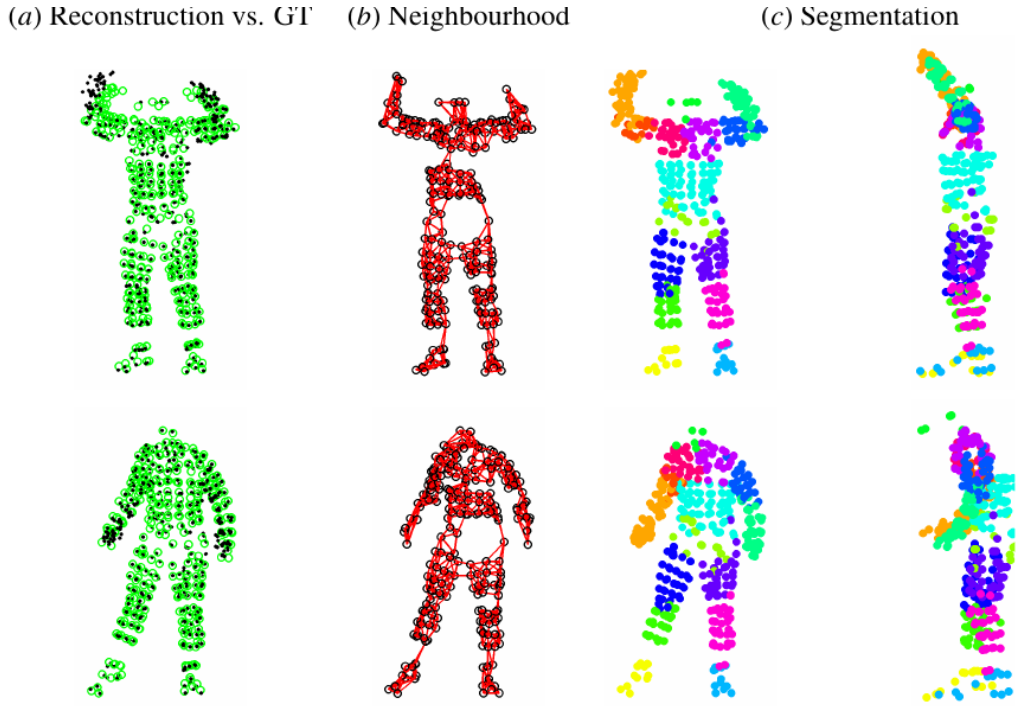
Reconstruction without rotation

SPLIT OBJECT INTO SIMPLE OVERLAPPING PARTS

RUSSELL ET AL. CVPR'11

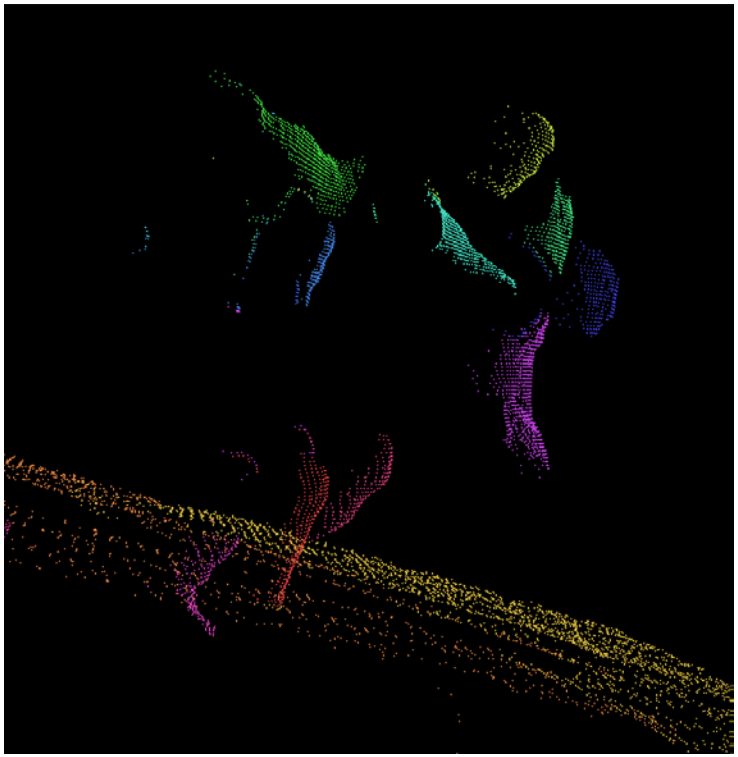
FAYAD ET AL. ICCV '11



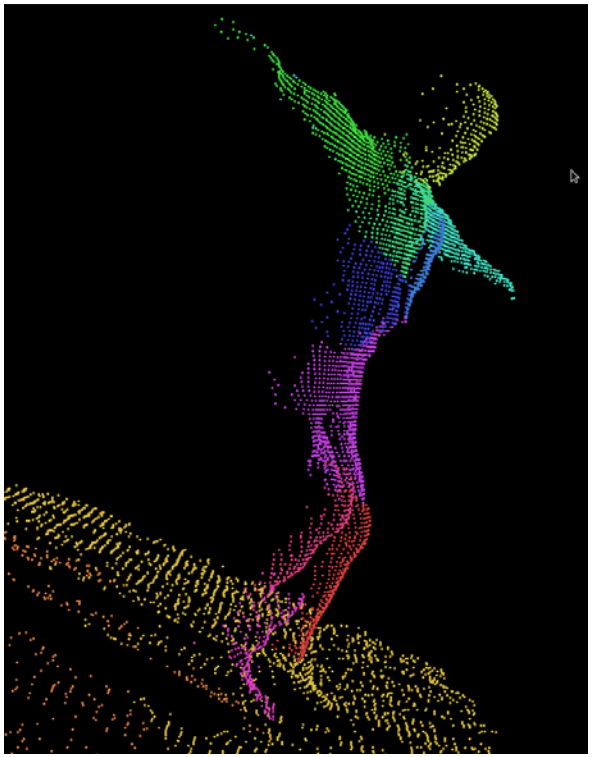


Part Stitching using overlap

WITHOUT OVERLAP

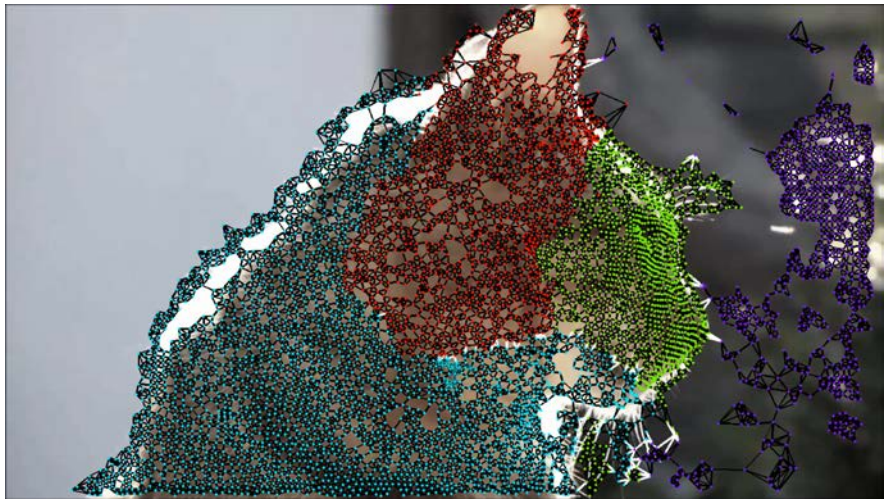


WITH OVERLAP

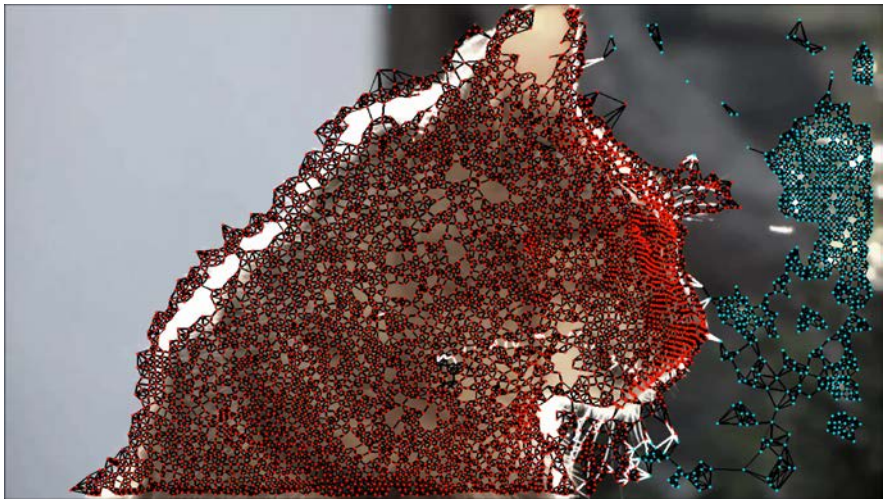


Multi-object reconstruction

Parts from different objects must not overlap



Parts

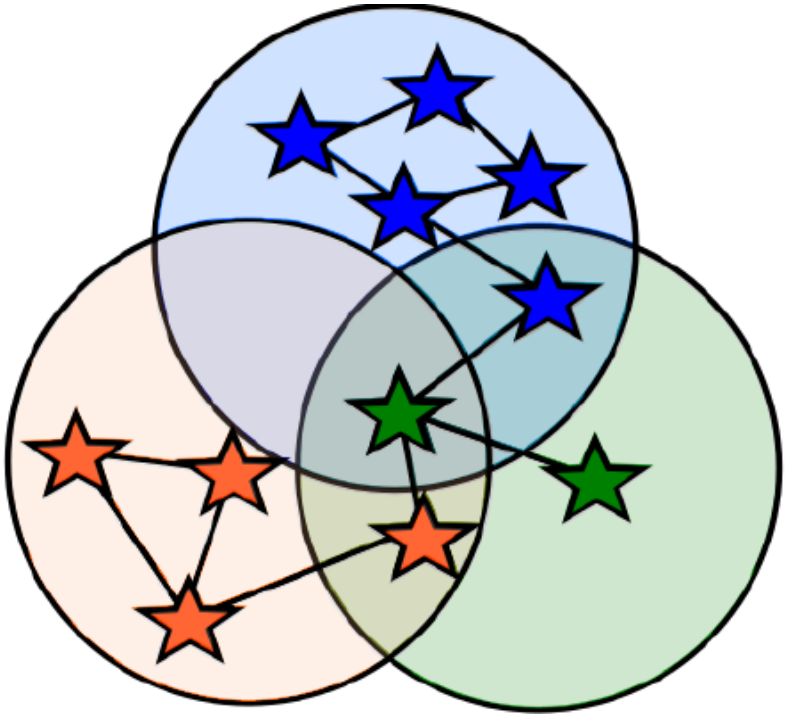


Objects

The formulation

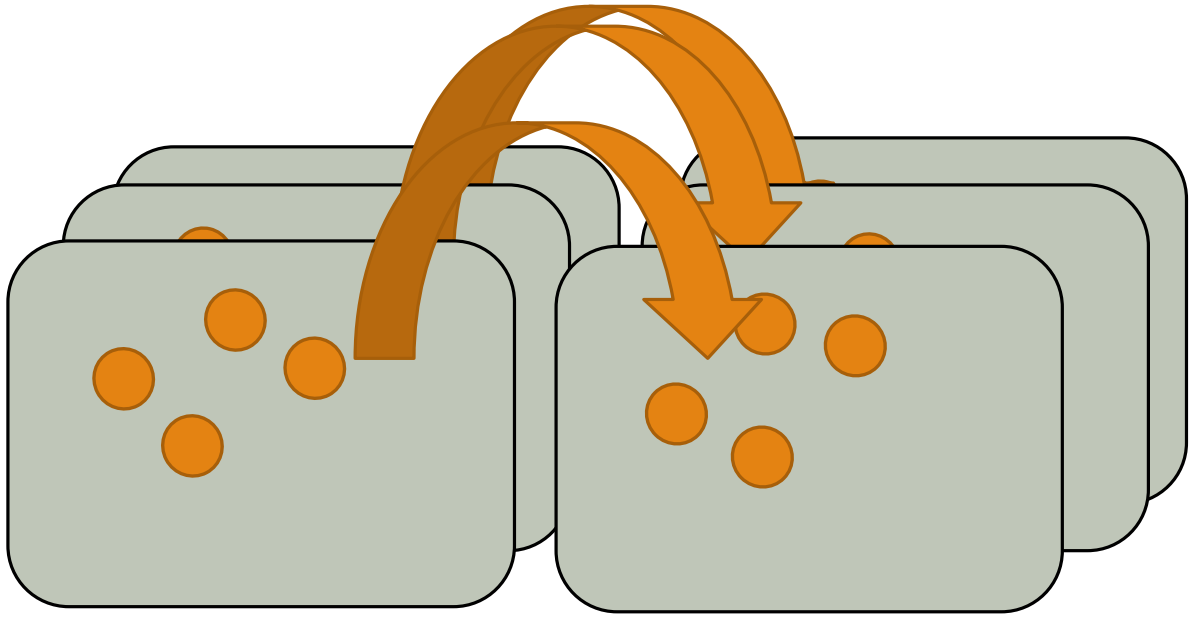
$$C(\mathbf{x}) = \sum_{m \in i \in \mathcal{T}} U_i(m)$$

Part assignment cost



Subject to overlap constraints

Unary Motion Costs



$$U_i(m) = \sum_f \gamma^{-1} (u_i^{f+1^T} F_m^f u_i^f)^2$$

The formulation

$$C(\mathbf{x}) = \sum_{m \in i \in \mathcal{T}} U_i(m)$$

Part assignment cost

Edge drop cost

Overlap Sparsity prior

Part Sparsity prior

Subject to overlap constraints

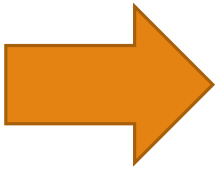
New

Difficult to optimise

Novel alpha expansion formulation

Without Graph Breaking

Parts



Objects

Graphs leak on object boundaries

Tracks on the edges of objects appear for a few frames and drift

With Graph Breaking

Parts

Objects

Drop edges that cause a high-cost overlap

Sparsity prior to discard small regions of overlap

The formulation

$$C(\mathbf{x}) = \sum_{m \in i \in \mathcal{T}} U_i(m)$$

Part assignment cost

$$+ \sum_{(i,j) \in \mathcal{G}} d_{i,j} \Delta(j \notin N_i)$$

Edge drop cost

$$+ \sum_{m,n \in \mathcal{P}} \Delta(\exists i \in I_m \wedge i \in n)$$

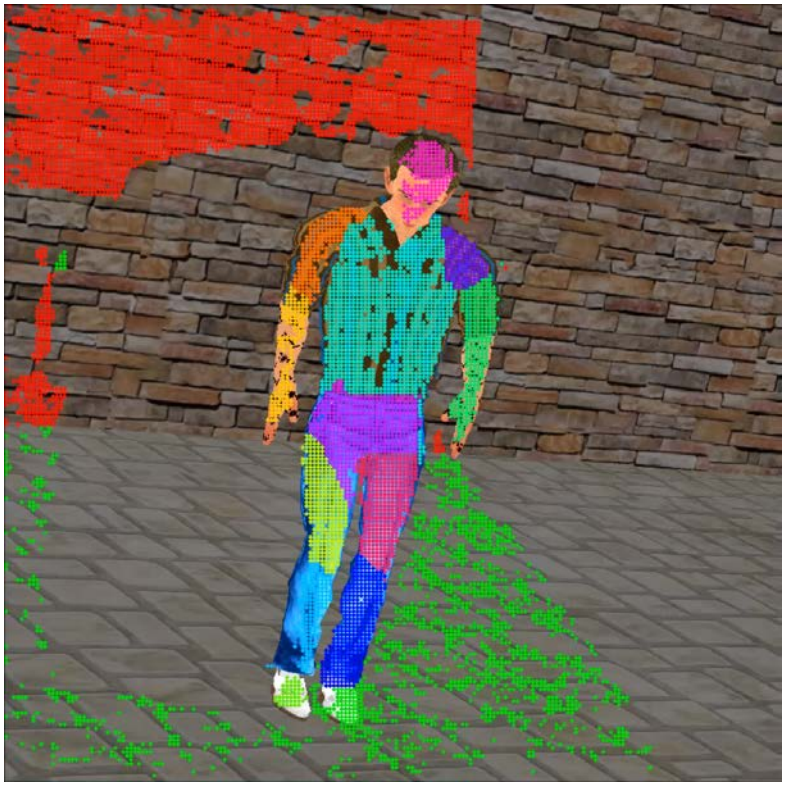
Overlap Sparsity

$$+ \mathrm{MDL}(\mathbf{x})$$

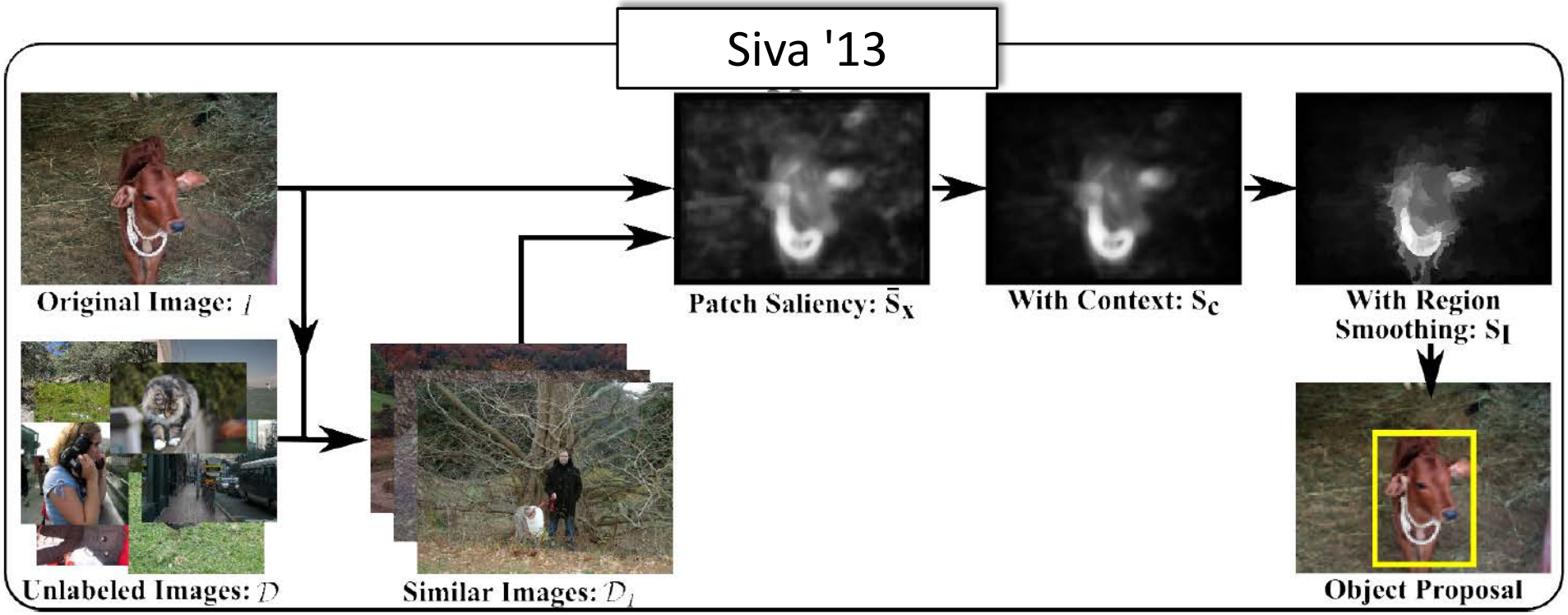
Part Sparsity

Subject to overlap constraints

Separating objects with weak motion cues



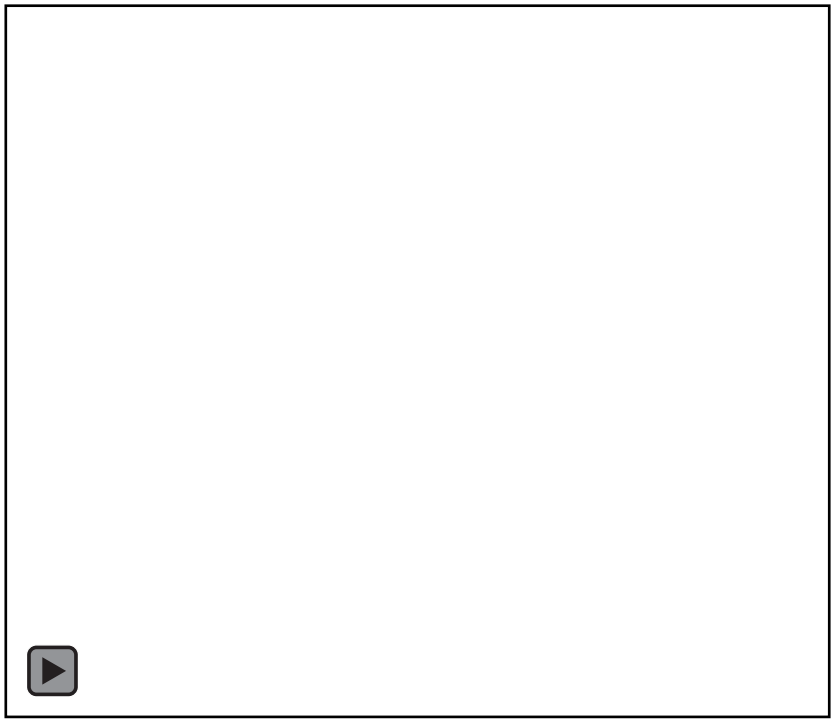
Using Appearance models in Parts

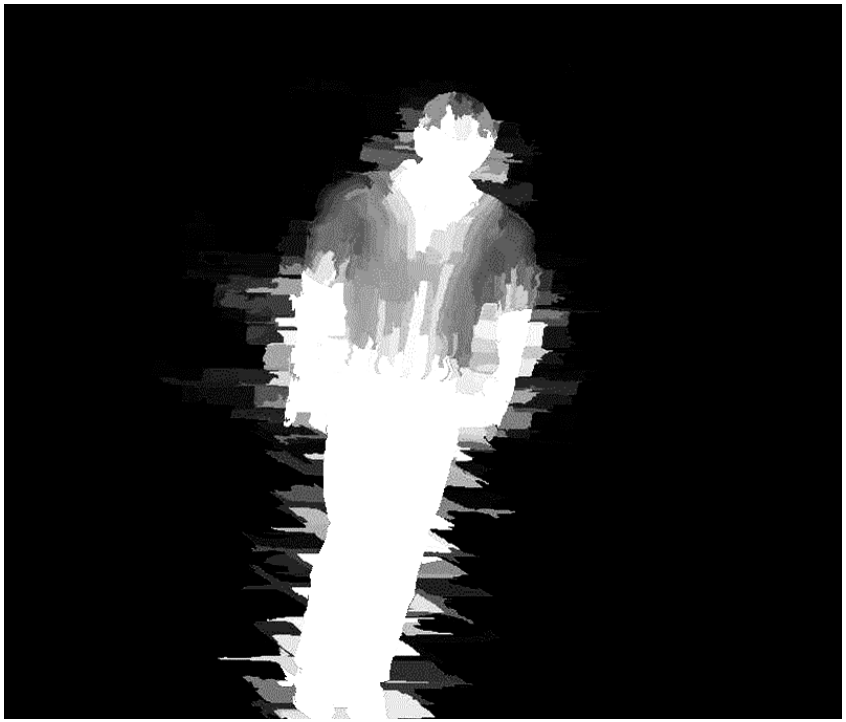


Approach finds uncommon regions that don't occur in similar images

Separating objects with weak motion cues

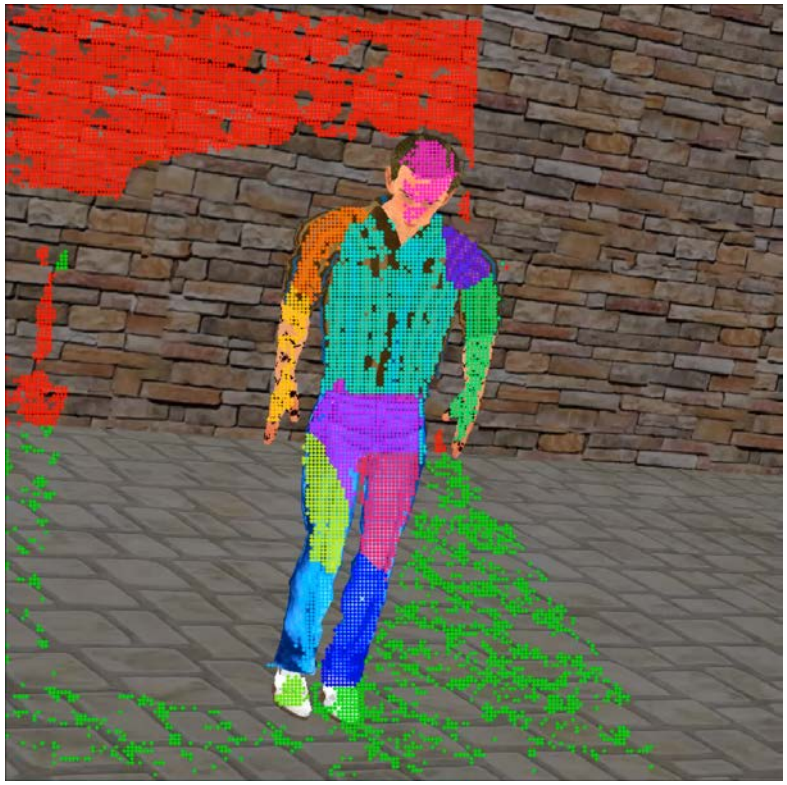
Siva et al CVPR'13



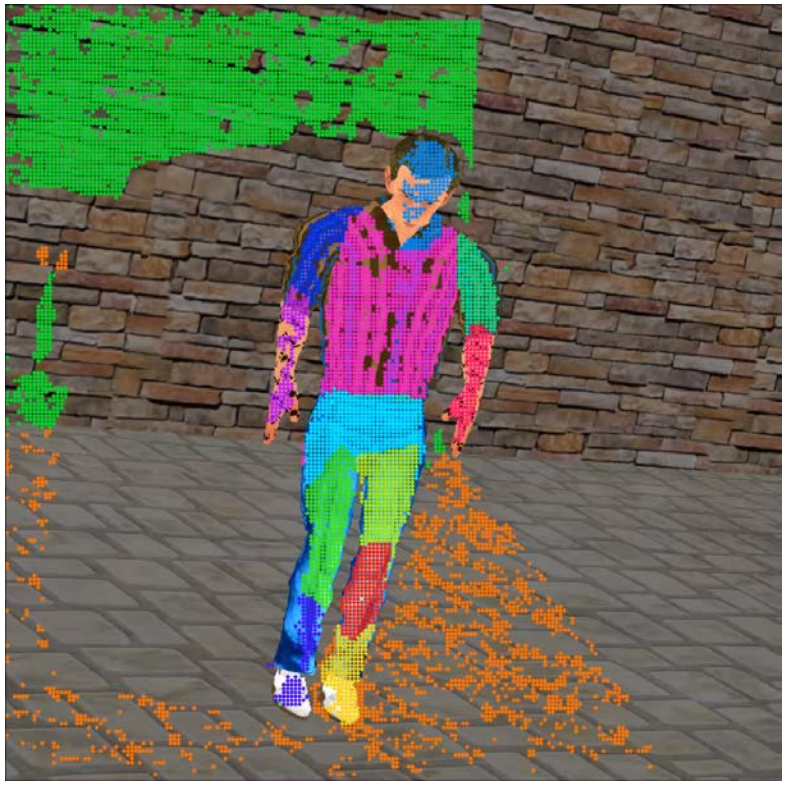


Separating objects with weak motion cues

Siva et al CVPR'13

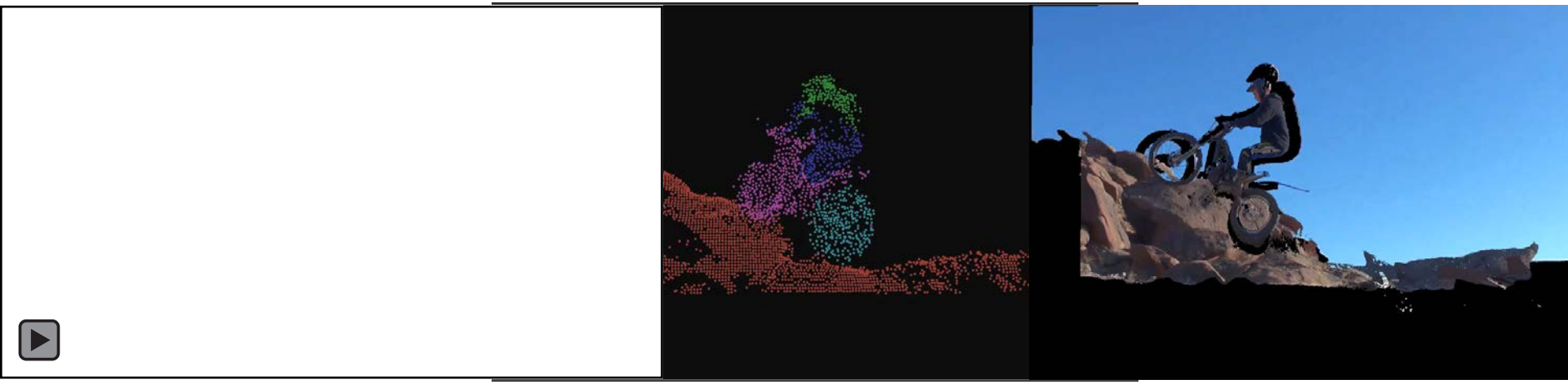


Without Saliency



With Saliency

Reconstruction



Parts → Metric Upgrade → Densify (Blur in xyRGB)

Conclusion

Works on real footage taken from youtube

UCL