

Refraction Wiggles for Measuring Fluid Depth and Velocity from Video

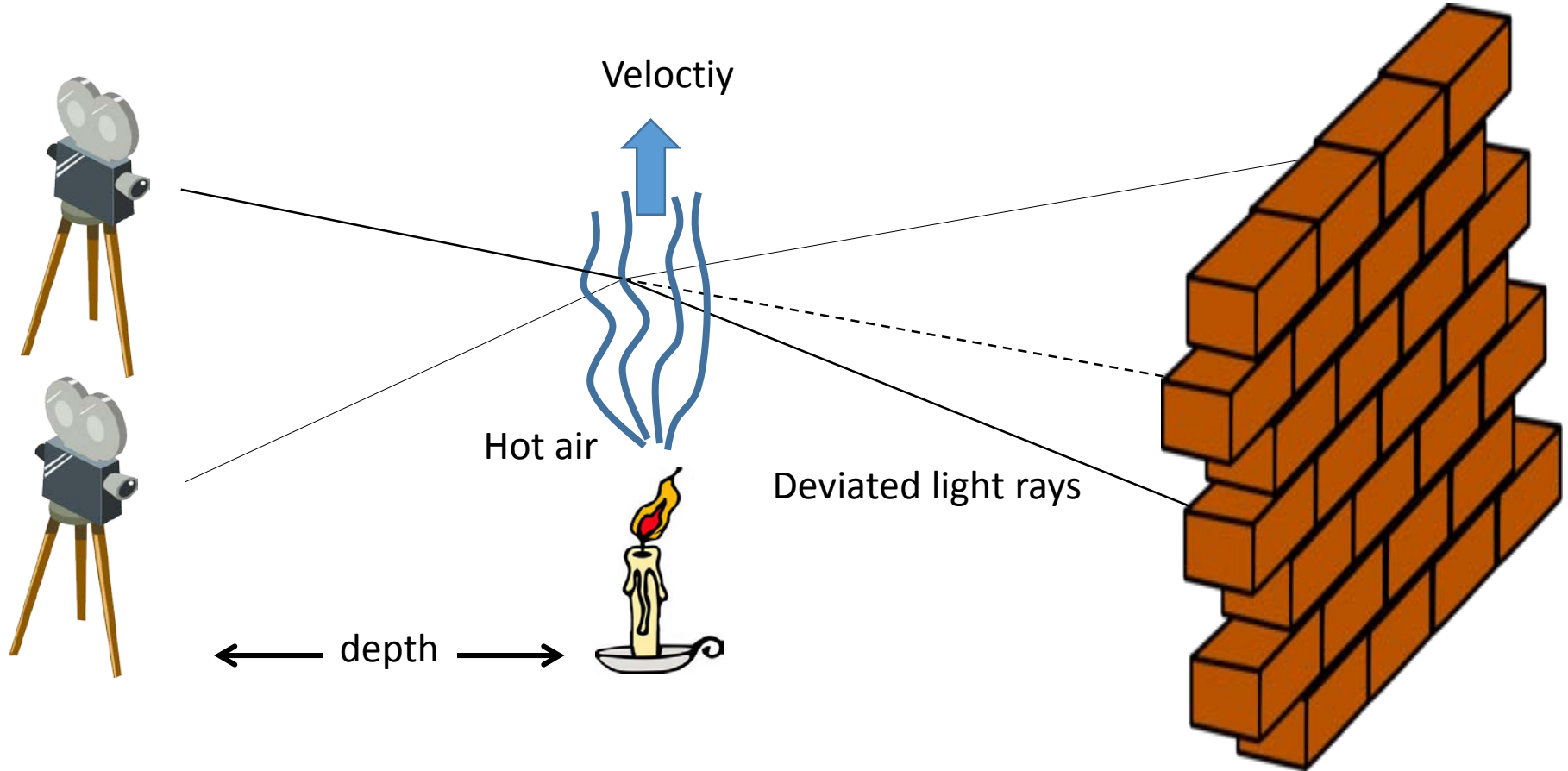
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²Microsoft Research

³Weizmann Institute

Measure refractive flow velocity and depth from natural videos



- **Single camera:** measure the velocity of air
- **Stereo camera:** measure the depth of air

Flow Velocity and Depth Recovered from Videos



Input (right view)



Input (left view)

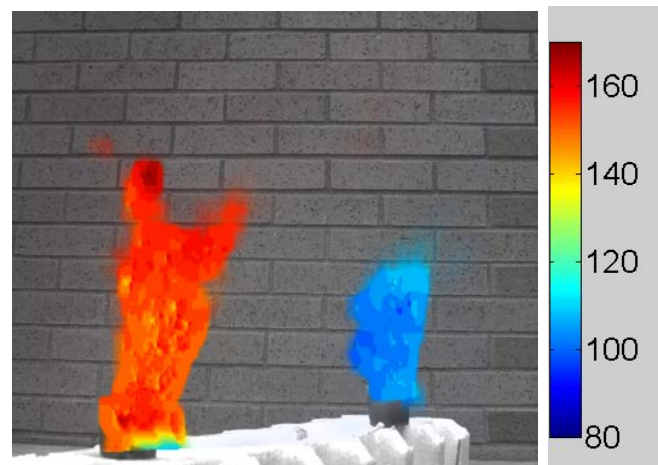
Refractive
flow



Refractive
Stereo



Motion of air (our result)



Disparity map of air (our result)

Outline

- **Introduction and related work**
- Algorithm:
 - Wiggle features
 - Measure fluid depth
 - Measure fluid velocity
 - Probabilistic formulation
- Experimental results

Potential Applications for fluid motion estimation



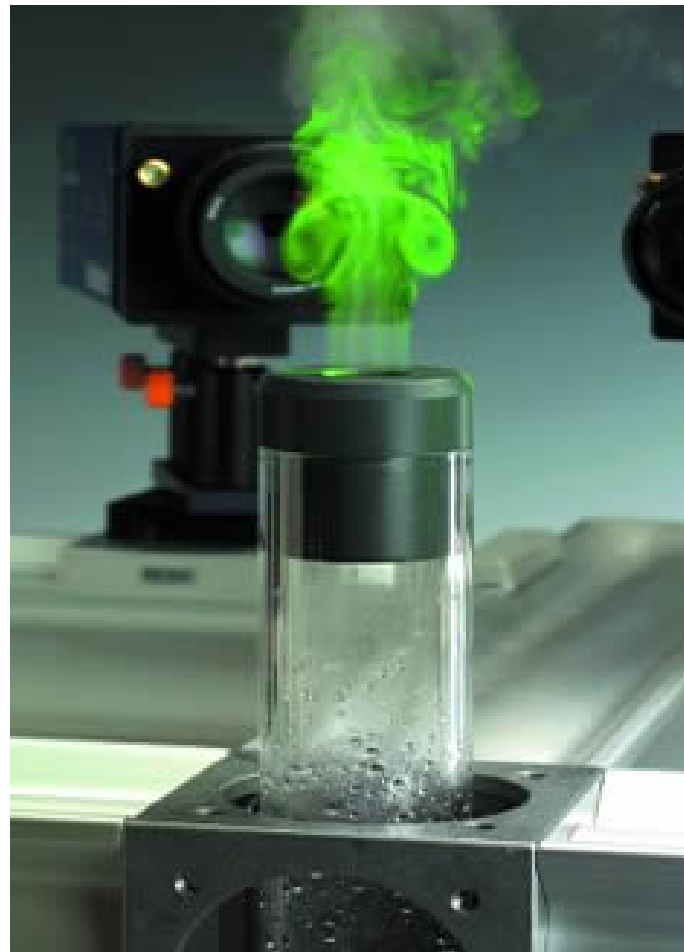
Aircraft scheduling



Toxic gas detection

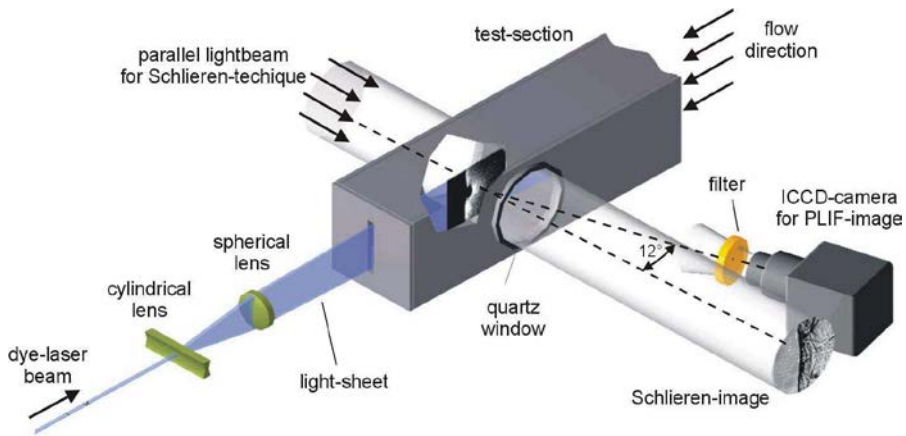
Related work

Particle Image Velocimetry (PIV)

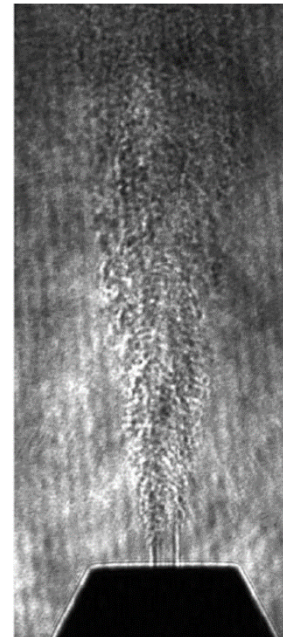


Related work

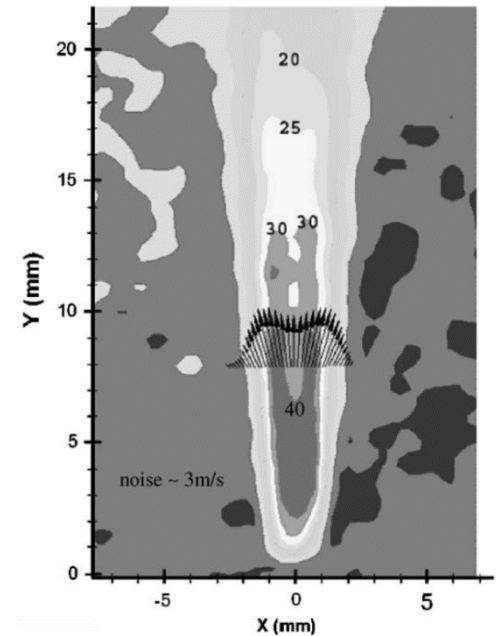
Tracer-based method (1): Schlieren photography



Schlieren setup



Schlieren image

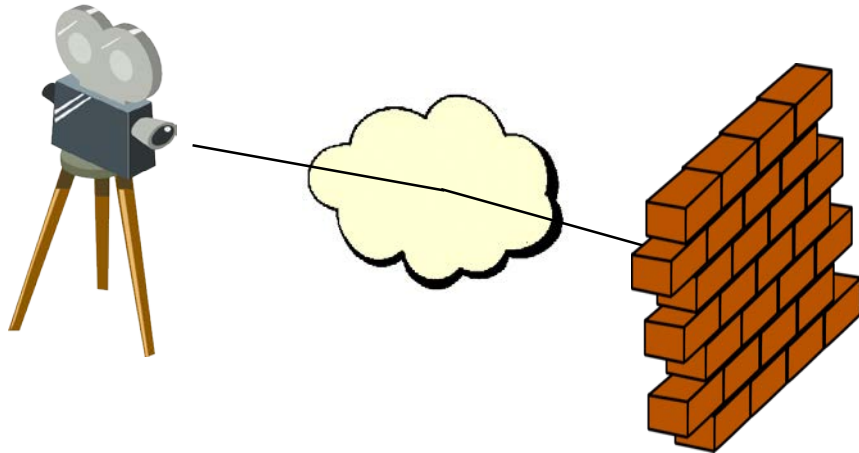


Schlieren PIV

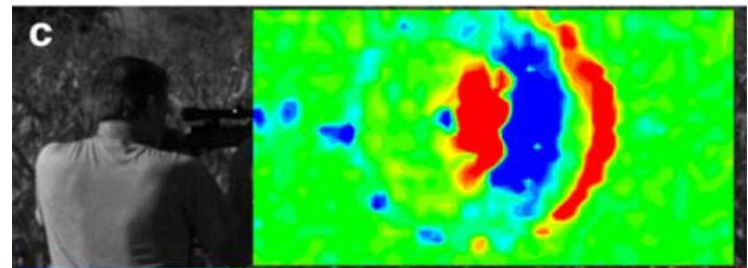
[Jonassen et al., *Schlieren PIV*, 2006]

Related work

Tracer-based method (2): Background Oriented Schlieren (BOS)



BOS setup

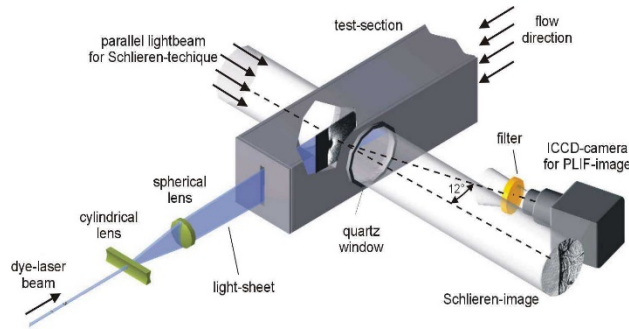


BOS image

Related works

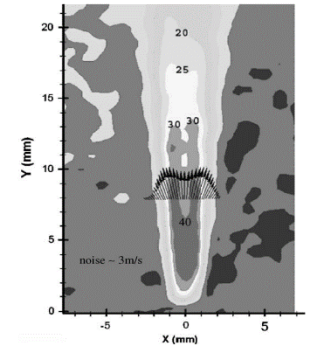
Visualization

Complicated Setup



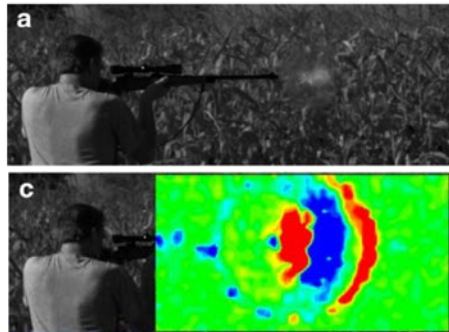
Schlieren

Visualization and Measurement

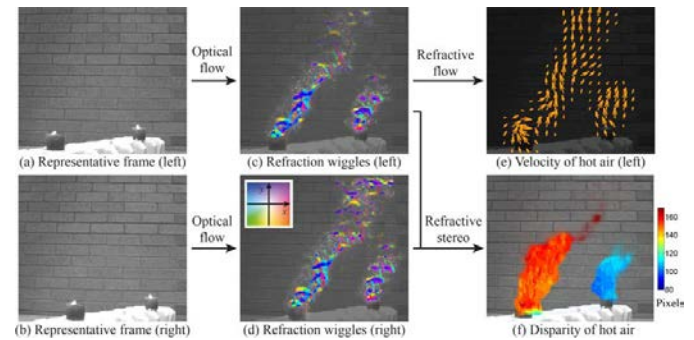


Particle Image Velocimetry (PIV) Schlieren PIV

Simple Setup



Background Oriented Schlieren (BOS)

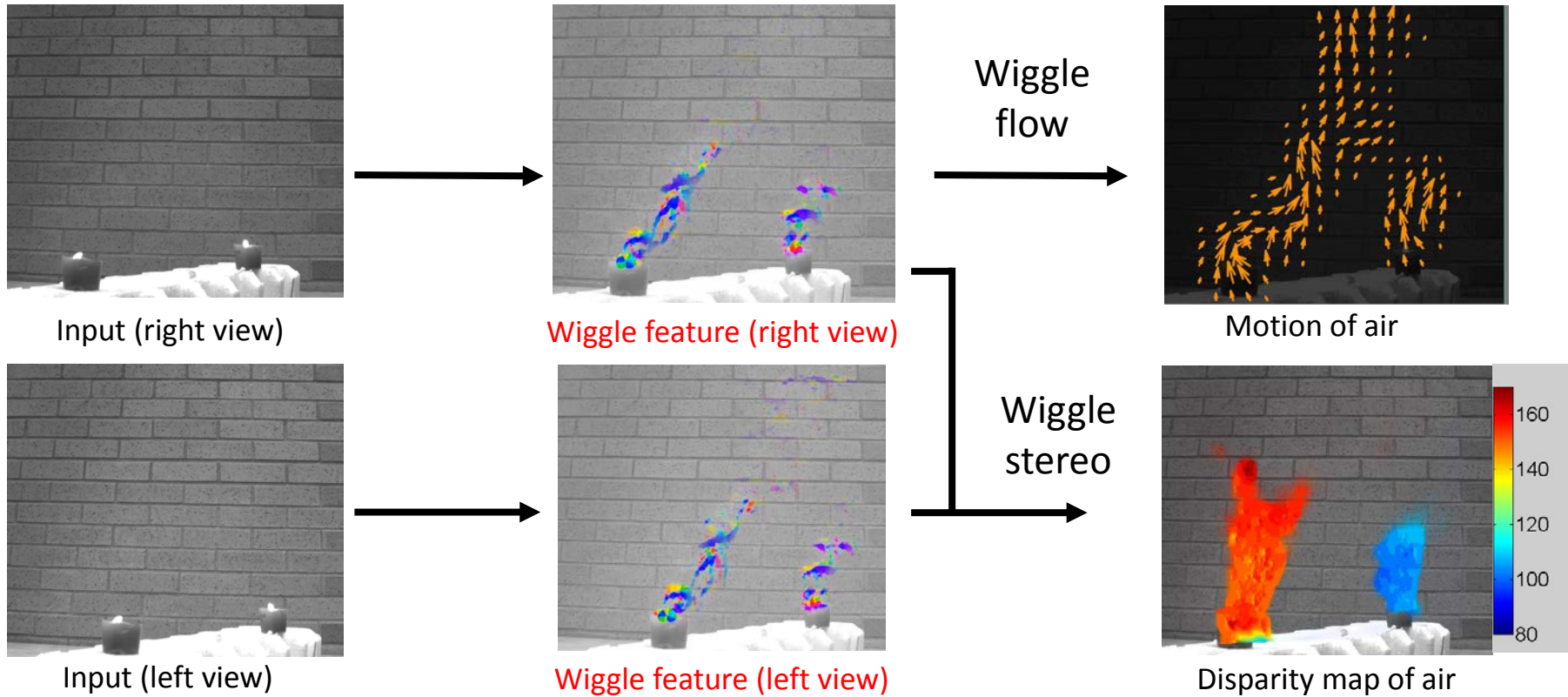


Wobble Stereo and Wobble Flow

Outline

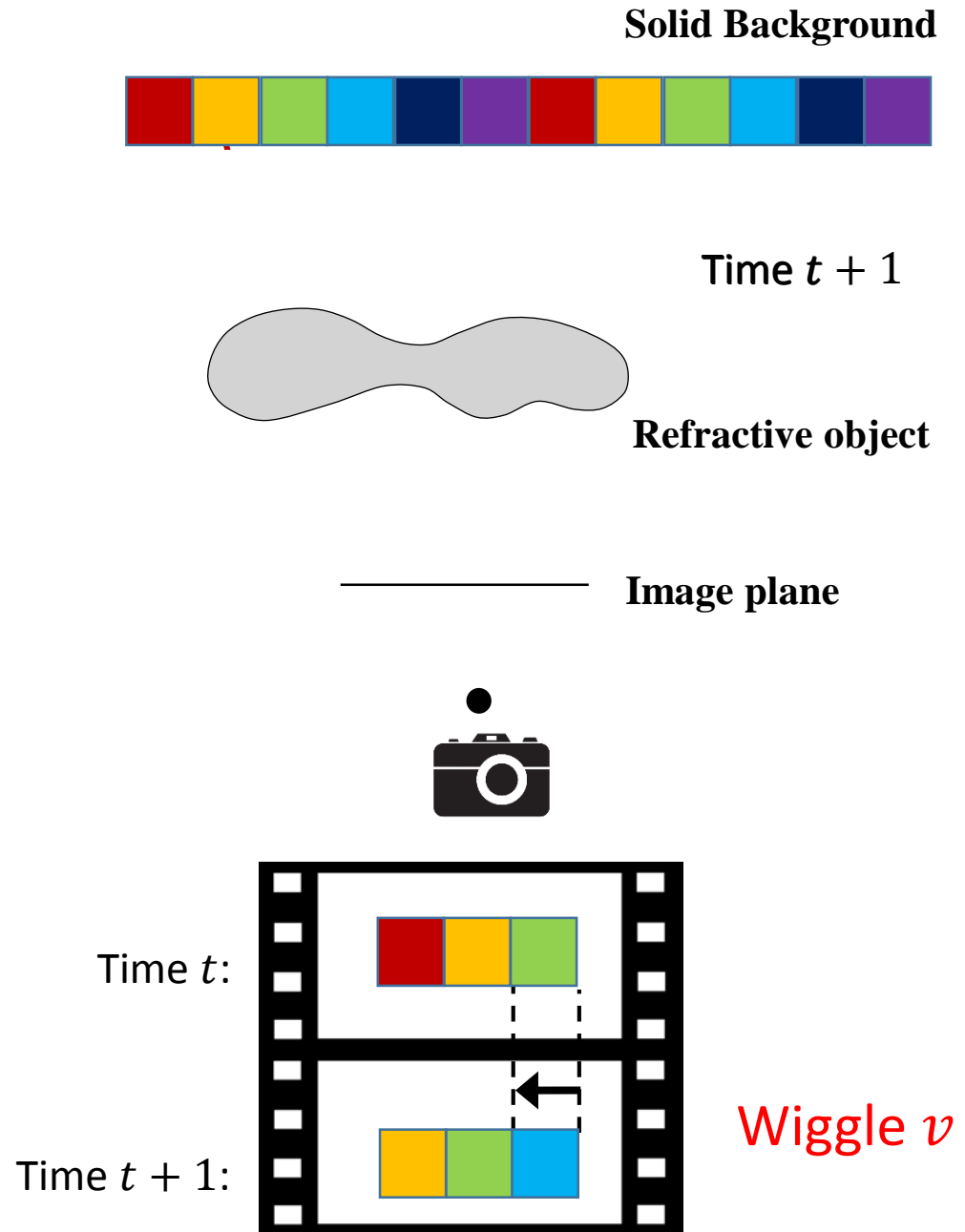
- Introduction and related work
- **Algorithm:**
 - **Wiggle features**
 - Measurement of fluid depth
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 - Probabilistic formulation
- Experimental result

Outline of the algorithm



Wiggle features

- Wiggle features are the distortion of background pattern due to the change of refraction

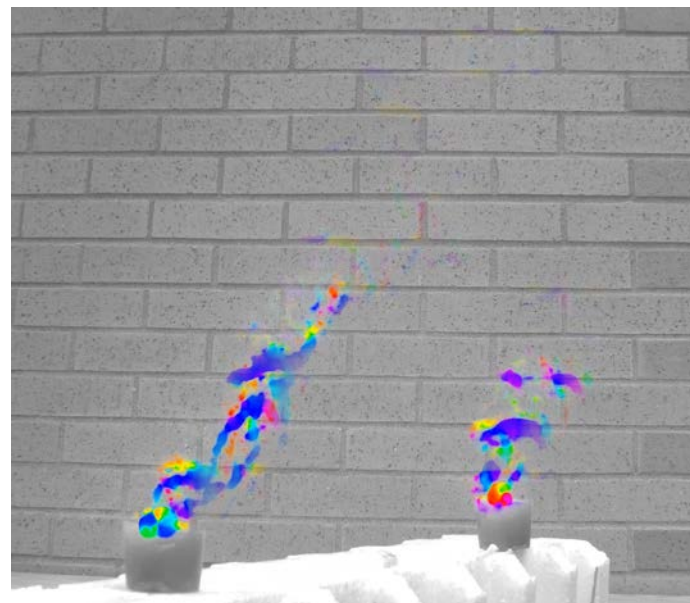


Example of Wiggle Features

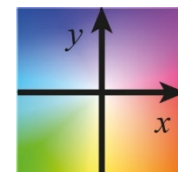


Input

Optical
flow
→



Wiggle feature



Outline

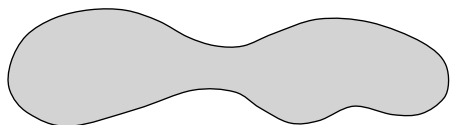
- Introduction and related works
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Fluid Stereo should fuse *wiggle motions*, not image intensities

Match intensities to find surface depths

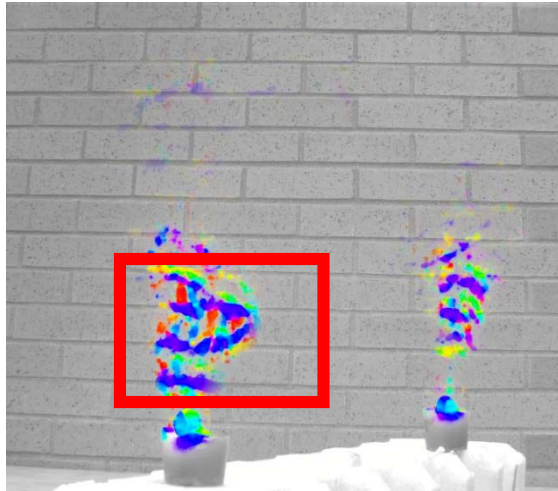


**Solid
Background**

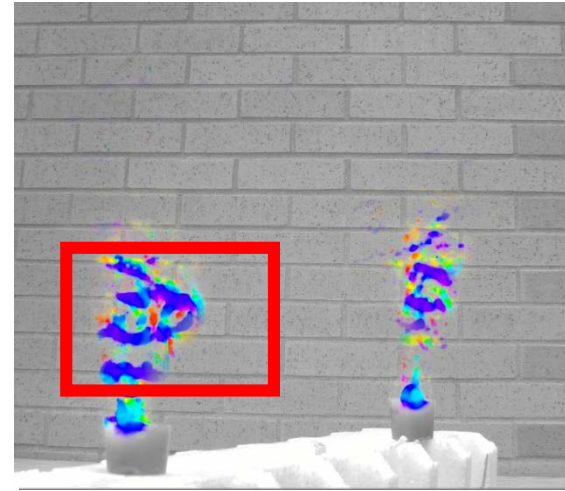


Please refer to our paper for the proof of wiggle constancy

Example of Refractive Stereo

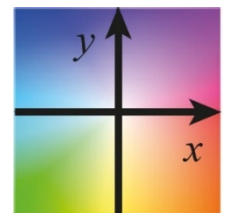
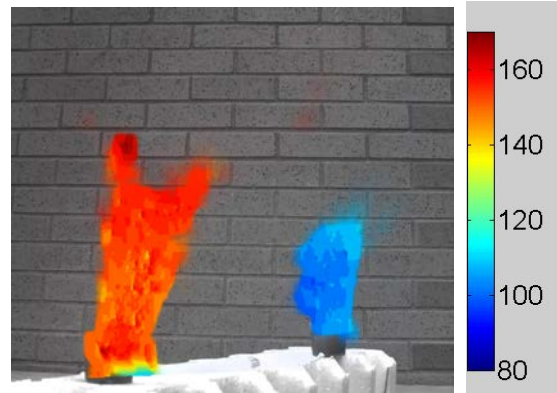


Refractive wiggle
(left view)



Refractive wiggle
(right view)

Disparity of Air
(from stereo fusing
wiggle features)



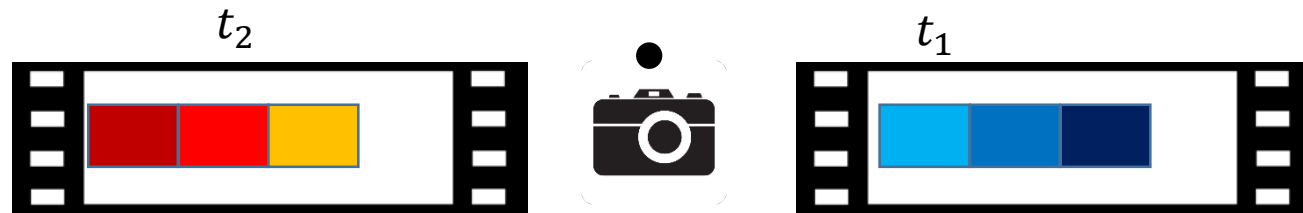
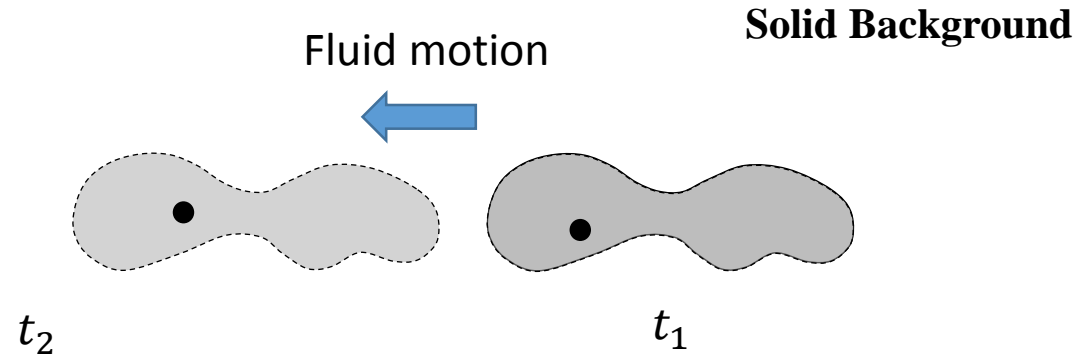
Outline

- Introduction and related work
- **Algorithm:**
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 - Measurement of fluid depth
 - **Measurement of fluid velocity**
 - Probabilistic formulation
- Experimental results

Fluid Flow should match of the wiggle features between neighboring frames (the flow of the flow)

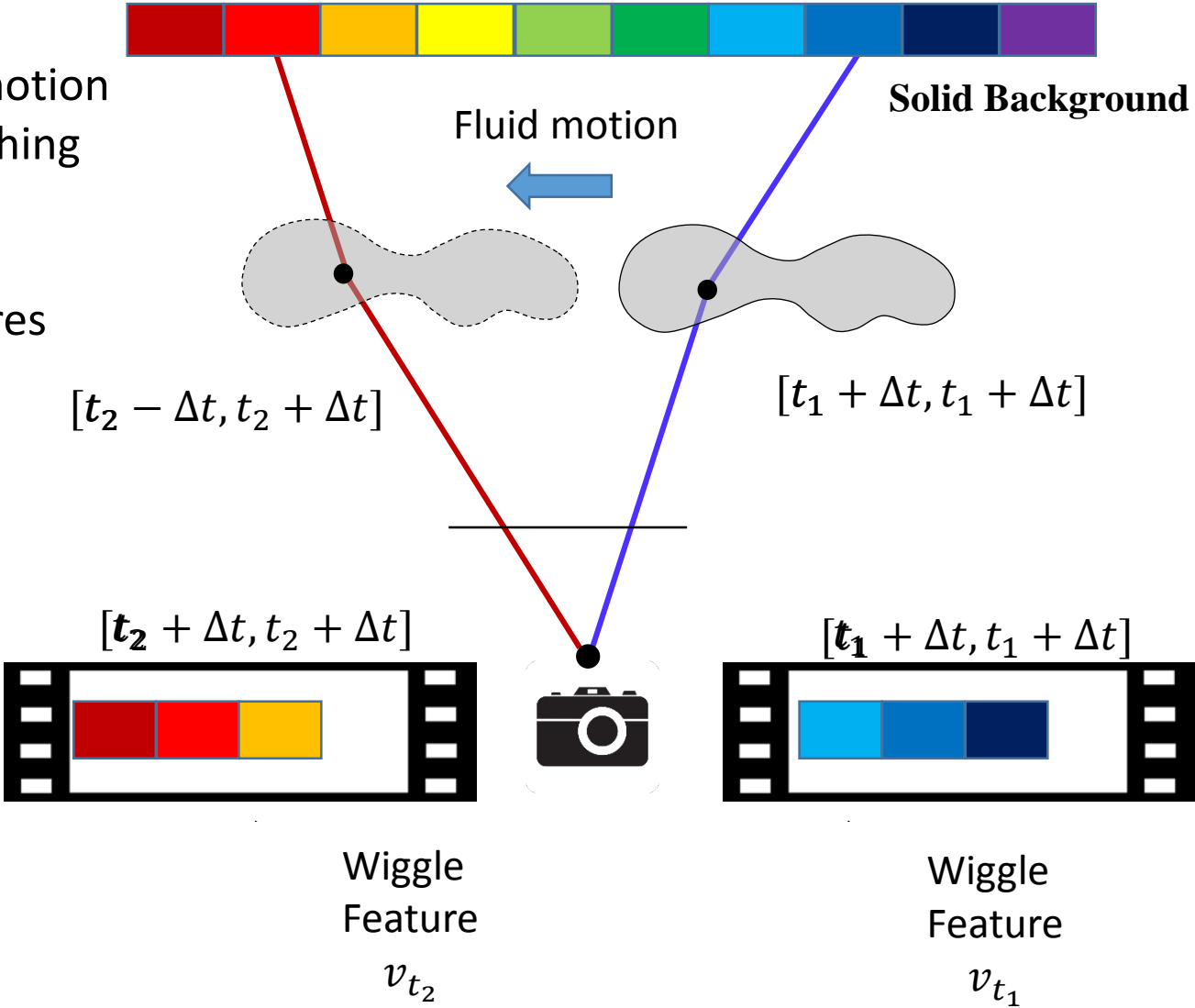


- We cannot find the motion from t_1 to t_2 by matching intensities

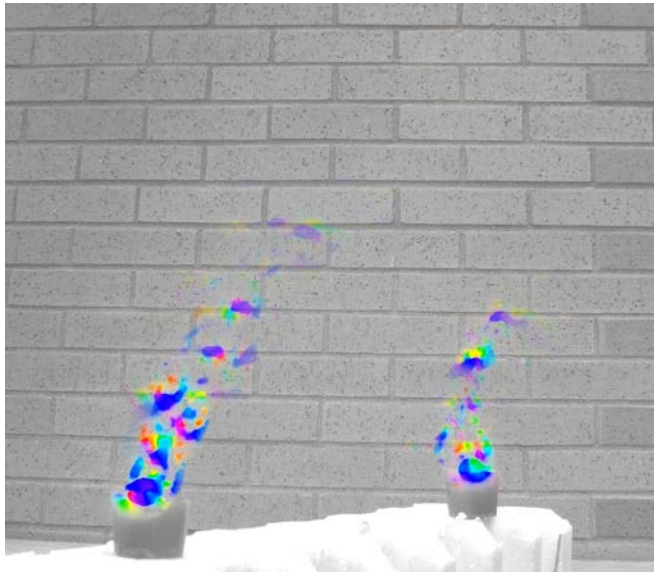


Fluid Flow should match the wiggle features between neighboring frames (the flow of the flow)

- We cannot find the motion from t_1 to t_2 by matching intensities
- But we can find it by tracking wiggle features

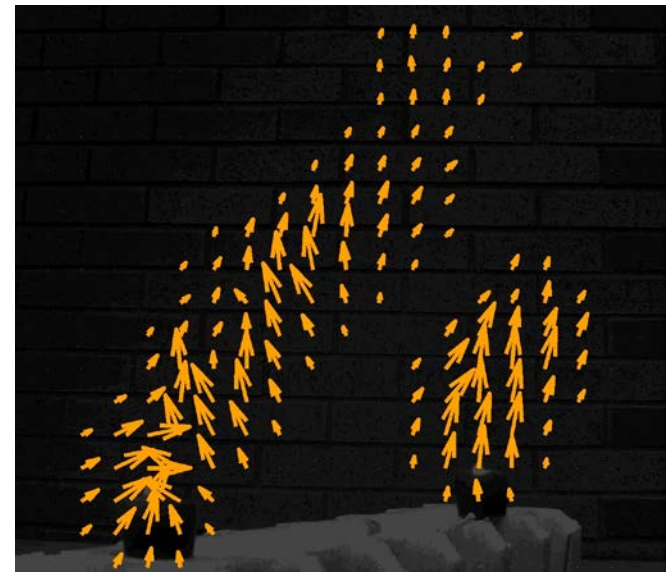


Example of Refractive Flow









Input video

Optical flow



Velocity of air flow

Brightness Constancy vs. Wiggle Constancy

	Brightness constancy	Wiggle constancy
Solid Object Stereo		
Solid Object Flow		
Refractive Object Stereo		
Refractive Object Flow		

Outline

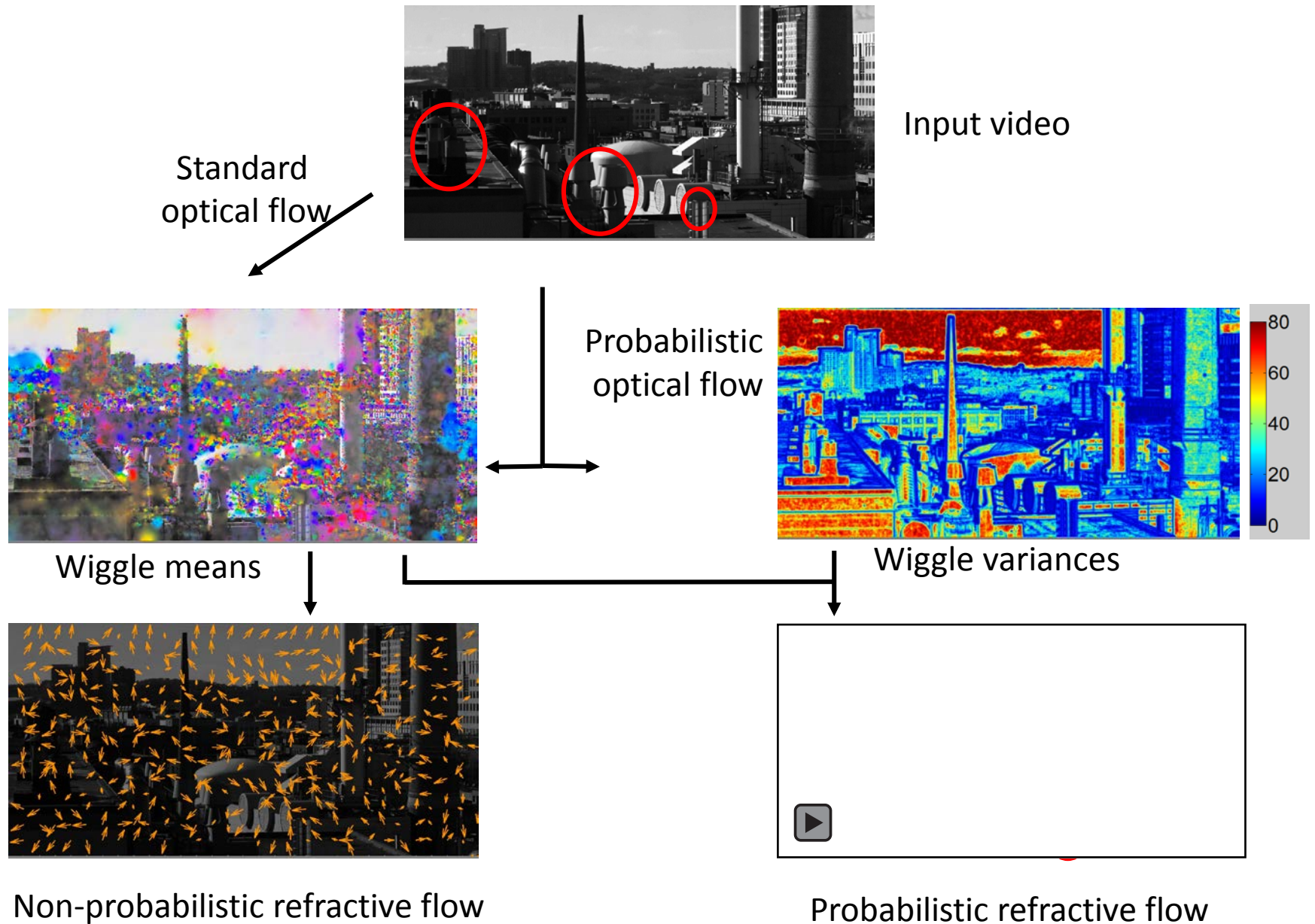
- Introduction and related work
- **Algorithm:**
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 - Measurement of fluid velocity
 - **Probabilistic formulation**
- Experimental Results

Probabilistic Optical Flow to Calculate Wiggle Features

Why a robust, probabilistic formulation is needed:

The wiggle feature is small (in the order of 0.1 pixel), so it is easily overwhelmed by the noise.

Probabilistic Refractive Flow:

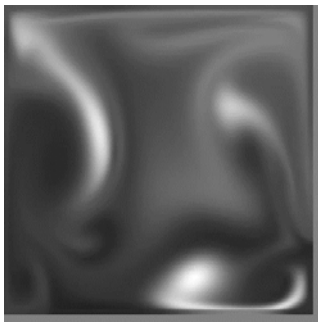


Outline

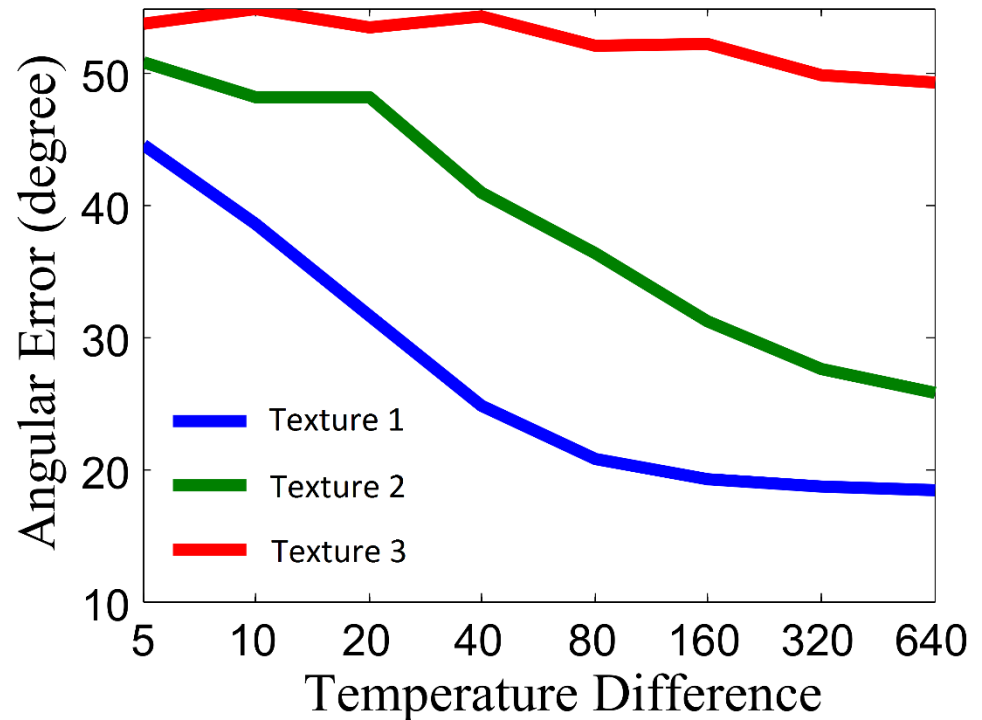
- Introduction and related work
- Algorithm:
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 - Measurement of fluid velocity
 - Probabilistic formulation
- **Experimental Results**

Evaluate the refractive flow on simulated sequence

- We simulate a fluid flow with known velocity, and test it on three different backgrounds.
- Error drops when temperature increases

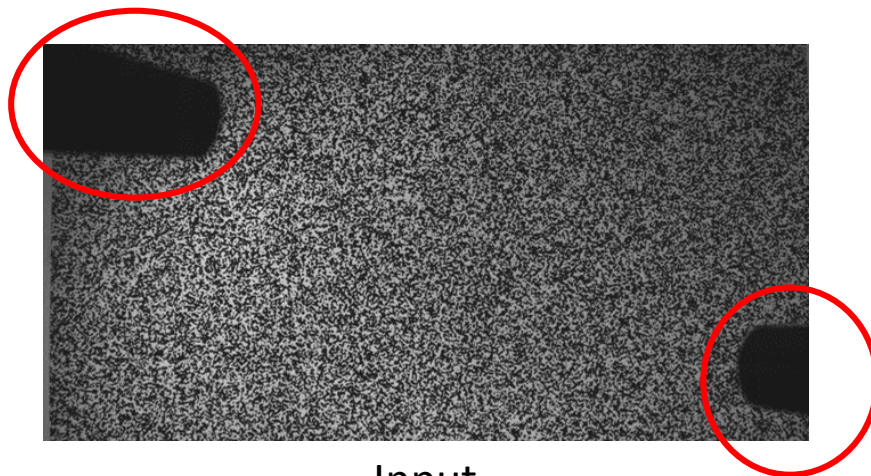


Simulated fluid density
[Stam et al. *Stable Fluid* 2004]

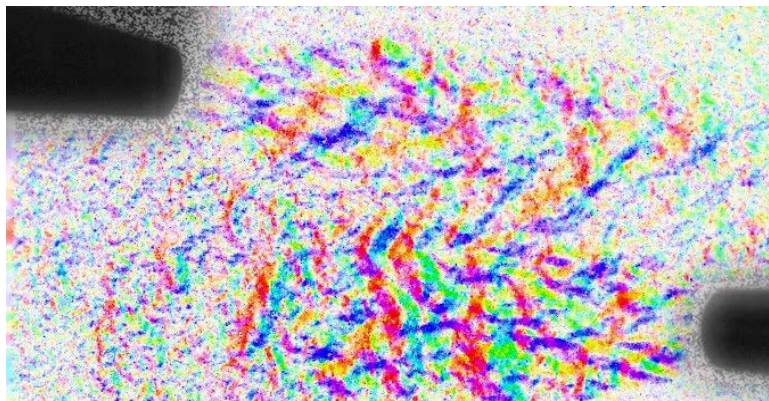


Background texture

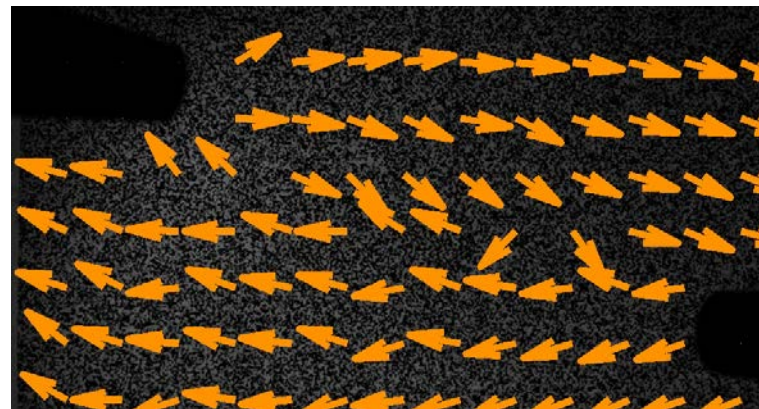
Real Sequence: Hairdryer (1000fps)



Input

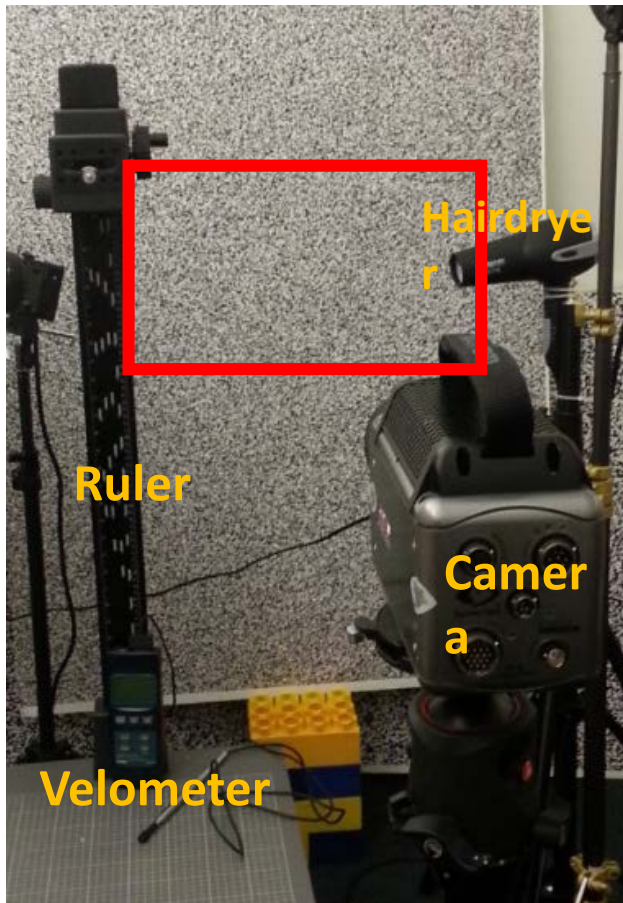


Wiggle feature

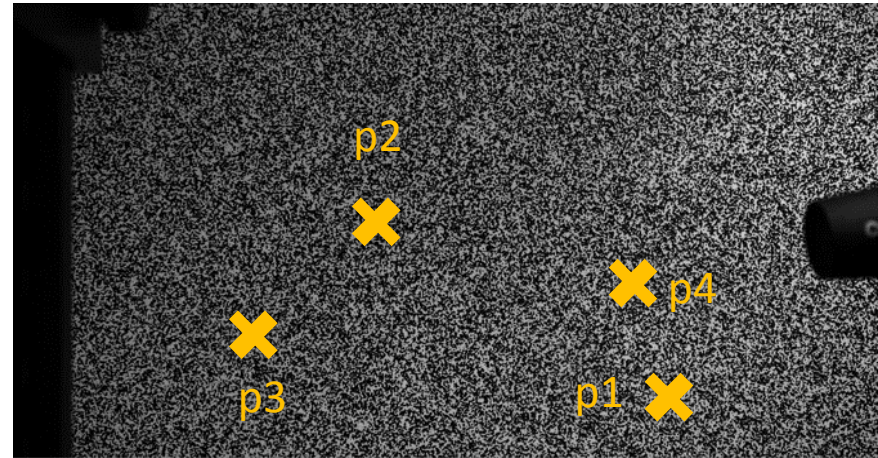


Flow field of air

Comparison with Velocimeter Measurements



Experiment Setup



Input Video

	p1	p2	p3	p4
By Algorithm (m/s)	0.8	1.4	3.2	12.0
By Velocimeter (m/s)	0.0	0.3	1.4	13.8

Comparison of fluid velocity measurements

Real Sequence: Lights



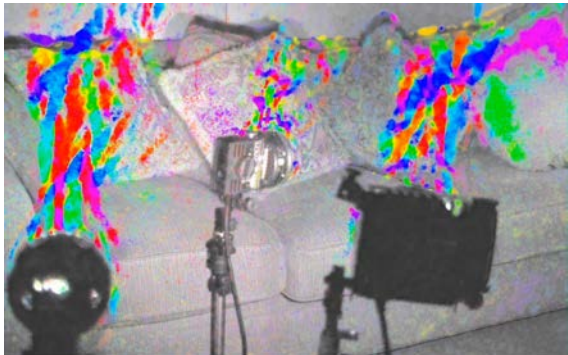
Input (Left view)



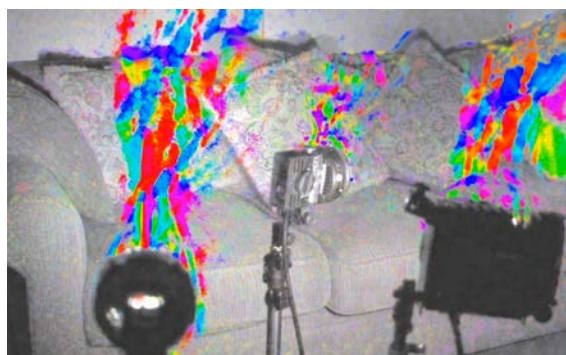
Input (Right view)



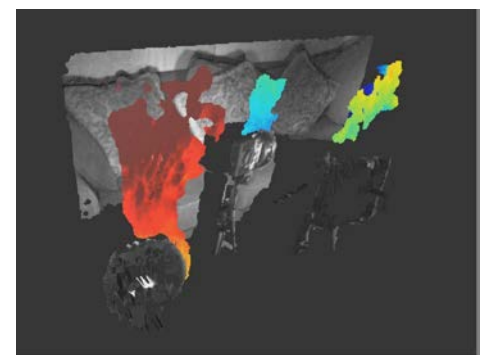
Disparity map of air flow



Wiggle feature (Left view)



Wiggle feature (Right view)

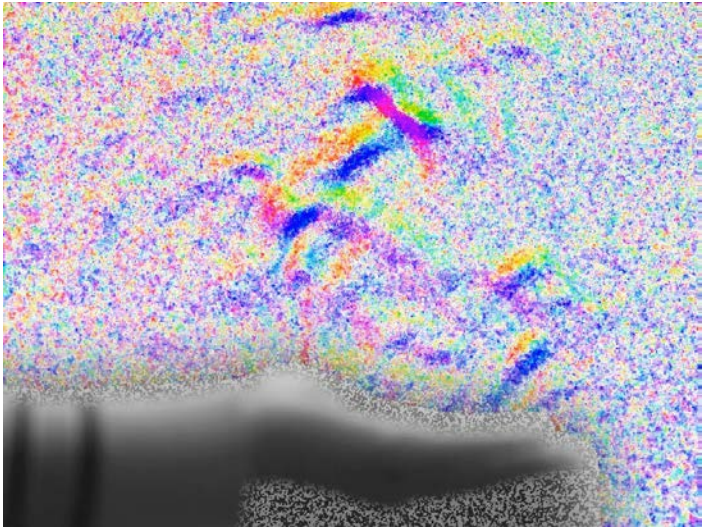


3D view of air flow

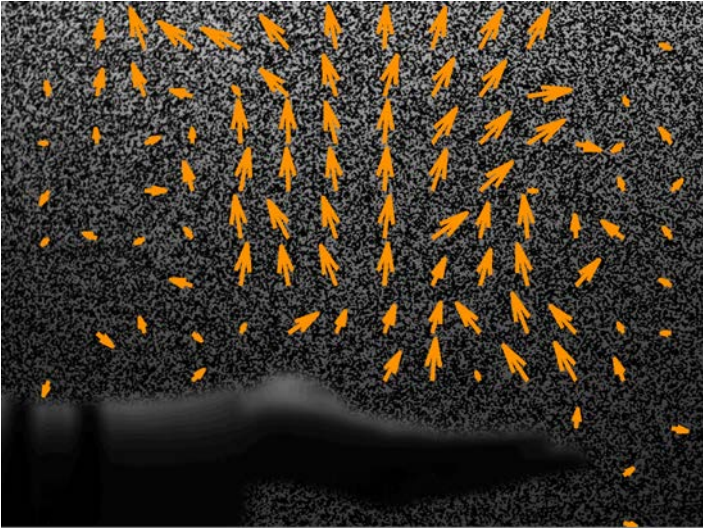
Real Sequence: Hand



Input Video



Wiggle feature



Flow field of air

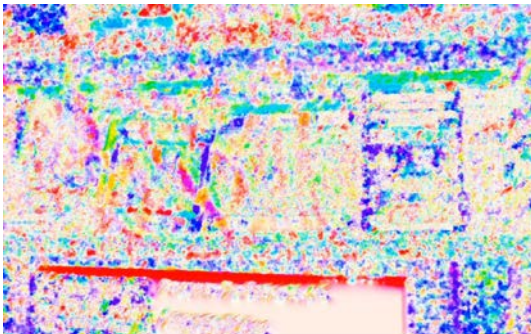
Wiggle features

- We introduce *wiggles* as a video image feature. These are small motions, here caused by the motion of turbulent air.
- These wiggles can be stereo-fused, revealing the depth of the turbulent flow.
- The wiggles can be tracked, revealing the motion of the turbulent flow.
- We introduce a probabilistic algorithm, using both mean and variance estimates, to reliably track the wiggle features, which can be small and noisy.

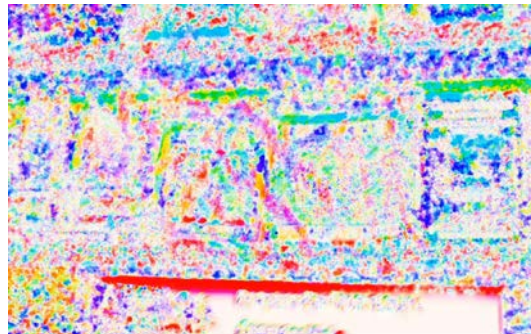
Thank you!

<http://people.csail.mit.edu/tfxue/proj/fluidflow/>

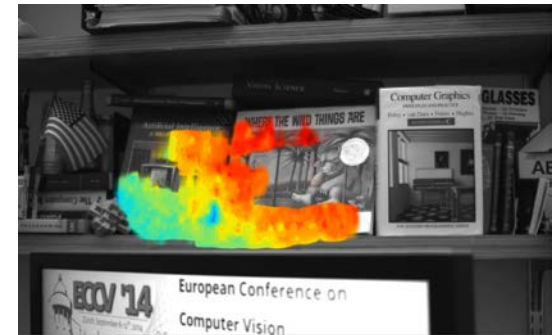
Or search for: “wiggle flow MIT”



Left view



Right view



Disparity of air