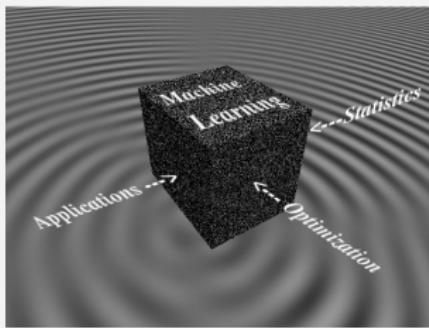


Clustering and Transductive Inference for Undirected Graphs

Kristiaan Pelckmans
Stability and Resampling Methods for Clustering

ESAT - SCD/sista
KULeuven, Leuven, Belgium

July, 2007



Overview of this talk

- (0) Clustering generalities
- (1) Clustering and Transductive Inference
- (2) Plausible Labeling Classes
- (3) Stability in Learning and Clustering
- (4) Graph Algorithms, MINCUT, and Regularization

Definition (An attempt)

For a set of n observations S and an hypothesis set \mathcal{H} ,

$$\max_{f \in \mathcal{H}} \mathcal{J}_\gamma(f|S) = \text{Falsifiable}(f) + \gamma \text{ Reproducible}_{S'_m \sim S}(f|S'_m)$$

- $(f|S)$ as 'f projected on the data S '
- Reproducibility \approx stability, robust evidence, ...
- Falsifiability \approx surprisingness, -entropy, ...
- Very general ...

Clustering Generalities

...thus specify

- VQ and compression
- Generative model
- (Image) Segmentation
- Multiple view prediction (2 - associative clustering; many - (Krupka, 2005))
- Organization and retrieval
- ...

→ What is a good taxonomy?

Clustering and Transductive Inference

Particular class of clustering



Clustering and Transductive Inference

Particular class of clustering

- Clustering as finding **Apparent Structure**
- ...or 'fast learnable hypothesis class'
- Clustering for deriving plausible hypothesis space
- But interpretable: clusterwise constant (independence)
- Clustering as stage before prediction...
- ... or as developing regularization (prior)
- Different from VQ (auto-regression)
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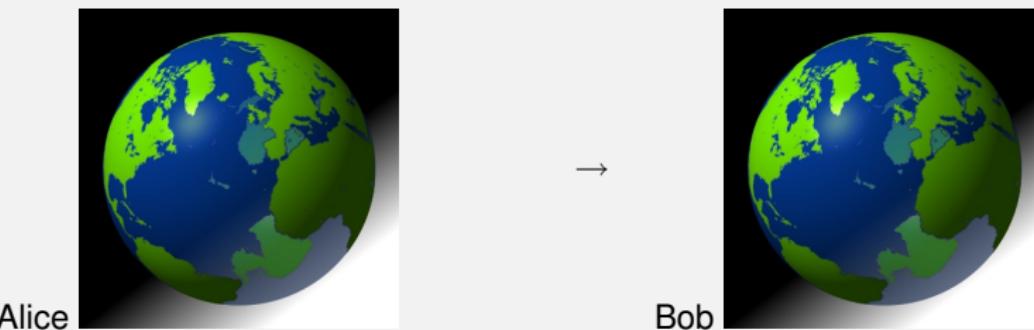
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- Alice knows a specific law in Europe/ USA/...
- ⇒ It would be easy to communicate this piece of information



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So what can be learned from results in transductive inference?

Transductive Inference for Weighted Graphs

Deterministic Weighted Undirected graphs

- Fixed amount of $n \in \mathbb{N}_0$ nodes (objects) $V = \{v_1, \dots, v_n\}$
- Organized in *deterministic* graph $\mathcal{G} = (V, E)$ with edges $E = \{x_{ij} \geq 0\}_{i \neq j}$ (symmetrical $x_{ij} = x_{ji}$, no loops $x_{ii} = 0$)
- Fixed label $y_i \in \{-1, 1\}$ for any node $i = 1, \dots, n$, but only *partially observed*:
 $\mathcal{S} \subset \{1, \dots, n\}$

$$y_{\mathcal{S}} = \{y_i \in \{-1, 1\}\}_{i \in \mathcal{S}}.$$

- Predict the remaining labels

$$y_{-\mathcal{S}} = \{y_i \in \{-1, 1\}\}_{i \notin \mathcal{S}}.$$

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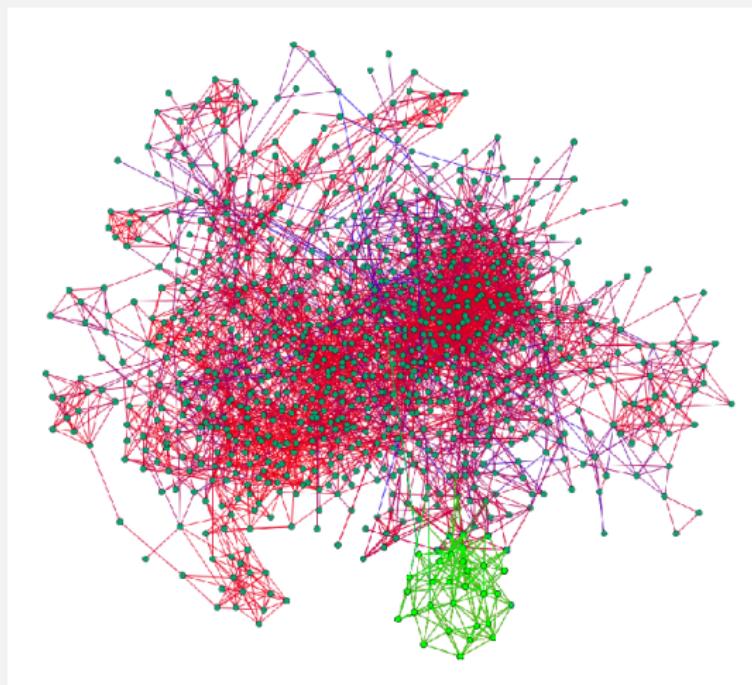
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Transductive Inference for Weighted Graphs (Ct'd)

Example



Gene coexpression:

Transductive Inference for Weighted Graphs (Ct'd)

Risk

- Hypothesis set:

$$\mathcal{H} = \{q \in \{-1, 1\}^n\}$$

with $|\mathcal{H}| = 2^n$

- Given a restricted hypothesis set $\mathcal{H}' \subset \mathcal{H}$ with $|\mathcal{H}'| \ll |\mathcal{H}|$, and a few observations y_S where S is uniform without replacement
- Actual risk

$$\mathcal{R}(q|\mathcal{G}) = E[I(y_J q_J < 0)] = \frac{1}{n} \sum_{i=1}^n I(y_i q_i < 0),$$

with E over uniform choice of j in $y_J \in \{y_i\}_i$.

- Empirical risk

$$\mathcal{R}_S(q|\mathcal{G}) = \frac{1}{m} \sum_{i \in S} I(y_i q_i < 0).$$

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why Empirical Risk Minimization works..

Theorem (Generalization Bound)

Let $S \subset \{1, \dots, n\}$ be uniformly sampled without replacement. Consider a set of hypothetical labelings $\mathcal{H}' \subset \mathcal{H}^n$ having a cardinality of $|\mathcal{H}'| \in \mathbb{N}$. Then the following inequality holds with probability higher than $(1 - \delta) < 1$.

$$\sup_{q \in \mathcal{H}'} \mathcal{R}(q|\mathcal{G}) - \mathcal{R}_S(q|\mathcal{G}) \leq \sqrt{\frac{2(n-m+1)}{mn} (\ln(|\mathcal{H}'|) - \ln(\delta))}. \quad (1)$$

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Which labelings $\mathcal{H}' = \{q\}$ are supported by a graph \mathcal{G} ? Can be formalized as e.g.

- Which labelings \mathcal{H}' can be *reconstructed* ('predicted') with a rule?
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Plausible Labeling Classes \mathcal{H}' (Ct'd)

Measuring the Richness of \mathcal{H}' ?

- ➊ Cardinality: $|\mathcal{H}'|$ (finite setting!)
- ➋ Covering balls (if many hypotheses in $q \in \mathcal{H}'$ similar)
- ➌ Kingdom Dimension (VC-dim) of \mathcal{H}' :

$$\max_{\mathcal{S}} |\mathcal{S}| \text{ s.t. } \forall p \in \{-1, 1\}^{|\mathcal{S}|}, \exists q \in \mathcal{H}' : p = q|_{\mathcal{S}}$$

where $q|_{\mathcal{S}}$ denotes q restricted to \mathcal{S} .

- ➍ Compression coefficient
- ➎ Rademacher complexity

$$R(\mathcal{H}') = E \left[\sup_{q \in \mathcal{H}'} \frac{2}{n} \left| \sum_{i=1}^n \sigma_i q_i \right| \right]$$

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Definition (Clusterwise constant hypothesis)

Assume a clustering $C^k = \{C_1, \dots, C_k\}$ such that $C_i \cap C_j = \emptyset$,

$$\mathcal{H}_{C^k} = \left\{ q \in \{-1, 1\}^n \mid q_{C_i} = \mathbf{1}_{|C_i|} \text{ or } q_{C_i} = -\mathbf{1}_{|C_i|} \quad \forall i, \text{ and } q_j = -1 \text{ elsewhere} \right\}$$

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The VC dim of \mathcal{G} ?

"For any vertex v of a graph \mathcal{G} , the closed neighborhood $N(v)$ of v is the set of all vertices of \mathcal{G} adjacent to v . We say that a set S of vertices is shattered if every subset $R \subset S$ can be realized as $R = S \cup N(v)$ for some vertex v of \mathcal{G} . The VCdim of \mathcal{G} is defined to be the largest cardinality of a shattered set of vertices." [Haussler and Welz, 1987]

- Let the neighbor-based labeling q corresponding to $v \in V$ be defined as q_v :

$$q_{v,j} = \begin{cases} 1 & \exists e(v, v_j) \\ -1 & \text{else} \end{cases}$$

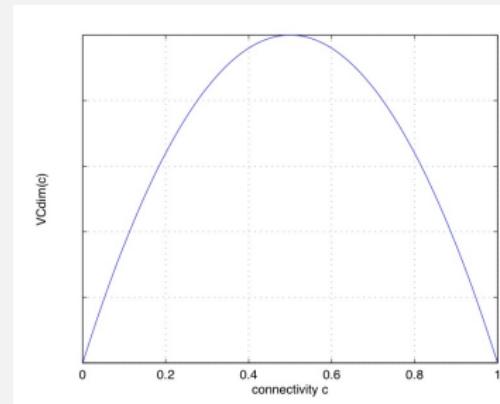
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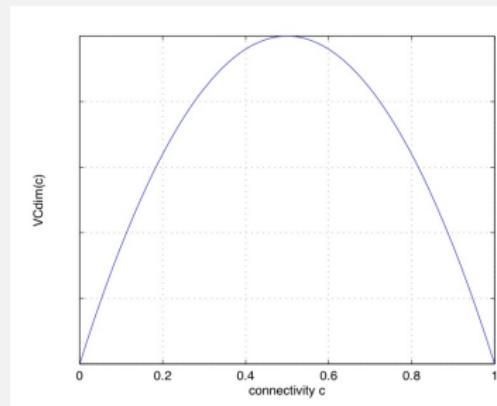
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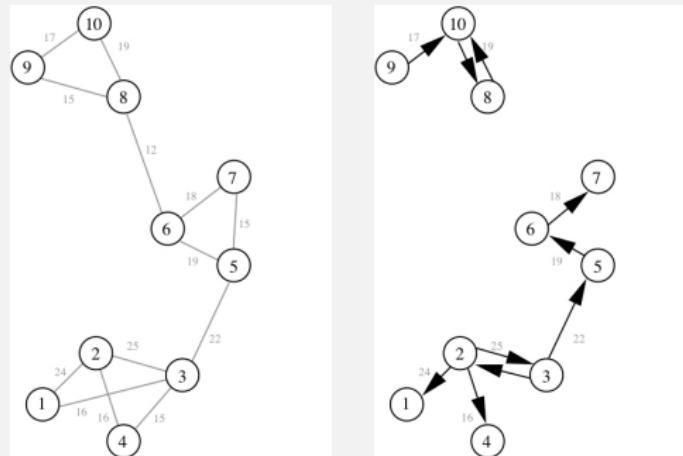
Consistent 1NN Rule

- 1NN Predictor rule:

$$f_q(v_i) = q_{(i)} \text{ where } (i) = \arg \max_{j \neq i} x_{ij}.$$

- Consistent predictor rule as restriction mechanism.

$$0 < q_i f_q(v_i) = q_i q_{(i)}, \quad \forall i = 1, \dots, n$$



→ Kruskal's MSP algorithm, $VCdim(1NN) = \#$ disconnected components.

Consider hypothesis set (Average Nearest Neighbors)

$$\mathcal{H}_k = \left\{ q \in \{-1, 1\}^n : q^T L q \leq k \right\}$$

Theorem (Cardinality of \mathcal{H}_k (Pelckmans, Shawe-Taylor, 2007))

Let $\{\sigma_i\}_{i=1}^n$ denote the eigenvalues of the graph Laplacian $L = D - W$ where $D = \text{diag}(d_1, \dots, d_n) \in \mathbb{R}^{n \times n}$. The cardinality of the set \mathcal{H}_k can then be bounded as

$$|\mathcal{H}_k| \leq \sum_{d=0}^{n_\sigma(k)} \binom{n}{d} \leq \left(\frac{en}{n_\sigma(k)} \right)^{n_\sigma(k)}, \quad (2)$$

where $n_\sigma(k)$ is defined as

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Lemma (Permutation Stability (R. El Yaniv, D. Pechyony, 2007))

Let $Z \in \mathcal{Z}$ be a random permutation vector. Let $f : \mathcal{Z} \rightarrow \mathbb{R}$ be an (m, n) symmetric permutation function satisfying $|f(Z) - f(Z^{ij})| \leq \beta$ for all (i, j) exchanging entries in $\mathcal{S}_m = \{1, \dots, m\}$ and $\mathcal{S}_n = \{m+1, \dots, n\}$. Then

$$P(f(Z) - E[f(Z)] \geq \epsilon) \leq \exp\left(-\frac{\epsilon^2}{2\beta^2 K(m, n)}\right)$$

with $K(m, n) = (n-m)^2(H(n) - H(n-m))$ and $H(k) = \sum_{i=1}^k \frac{1}{i^2}$ (and hence $1/K(m, n) \geq m$).

Stability in Learning (Ct'd)

Rademacher Complexity for Transductive Inference

Definition (Rademacher Complexity for TI)

Given hypothesis class \mathcal{H}' , one has

$$R(\mathcal{H}'|\mathcal{G}) = E \left[\sup_{q \in \mathcal{H}'} \frac{2}{n} \left| \sum_{i=1}^n \sigma_i q_i \right| \right]$$

with $\{\sigma_i\}_{i=1}^n$ Bernouilli random variables with $P(\sigma_i = -1) = P(\sigma_i = 1) = \frac{1}{2}$.

Assume further $\mathcal{H}' = -\mathcal{H}'$ (dropping $|\cdot|$).

Stability in Learning (Ct'd)

Rademacher Complexity for Transductive Inference

Theorem (Rademacher bound)

With probability exceeding $1 - \delta$ for $\delta > 0$, one has for all $q \in \mathcal{H}'$ that

$$\mathcal{R}_{\neg\mathcal{S}}(q|\mathcal{G}) \leq \mathcal{R}_{\mathcal{S}}(q|\mathcal{G}) + \left(\frac{n^2}{4m(n-m)} \right) R(\mathcal{H}'|\mathcal{G}) + \frac{n-2m}{2m(n-m)} + 2\sqrt{\left(\frac{n}{m(n-m)} \right) \log(1/\delta)}$$

Stability in Learning and Clustering

Back to the clustering story...

Definition (Stability for Clustering)

Consider an algorithm $A : \mathcal{X} \rightarrow \mathcal{C}$. If $\exists \beta$ such that

$$d(A(S_m), A(S'_m)) \leq \beta, \quad \forall S_m, S'_m \subset \{1, \dots, n\}$$

then for any $\epsilon > 0$, one has

$$P(d(A(S_m), E[A(S_m)]) \geq \epsilon) \leq \delta(\epsilon)$$

for an appropriate $\delta : \mathbb{R}_0^+ \rightarrow]0, 1]$.

Stability in Clustering

Idea: encode $d(A(S_m), A(S'_m))$ as

$$|c(A(S_m)) - c(A(S'_m))|_1,$$

for an appropriate encoding function $c : \mathcal{C} \rightarrow \{0, 1\}^{n_c}$, and $S_m = D(Z|m)$, or shortly as $Z|m$, then

Corollary (Stability for Clustering)

Consider an algorithm $A : \mathcal{X} \rightarrow \mathcal{C}$. If $\exists \beta(A, m)$ such that

$$\frac{1}{n_c} |c(A(Z|m)) - c(A(Z'|m))|_1 \leq \beta(A, m), \quad \forall S_m, S'_m \sim \{1, \dots, n\}$$

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$$P\left(\frac{1}{n_c} |c(A(Z|m)) - E_Z[c(A(Z|m))]|_1 \geq \epsilon\right) \leq 2 \exp\left(-\frac{\epsilon^2}{2\beta^2(A, m)K(m, n)}\right)$$

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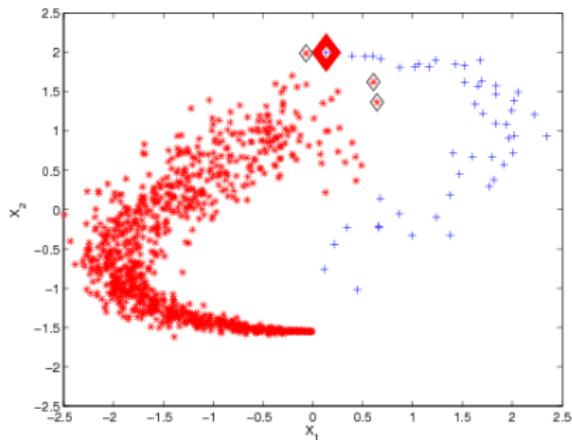
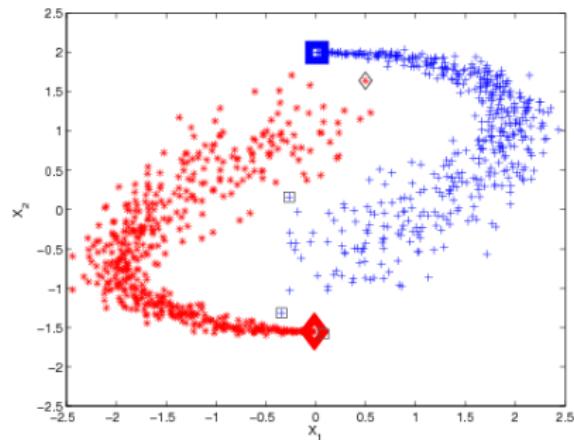
Remarks

- Natural encoding by mapping points on canonical 'cluster identity'.
- McDiarmid inequality...
- Notions of weak stability
- Norm $\|\cdot\|_1$? Better choices with \sup_{n_c}
- Does k comes in only via $\beta(A, m)$?

Graph Algorithms, MINCUT, and Regularization

Application

Can be recast as a convex graph flow algorithm!



Incorporating prior knowledge by relaxing as an LP/QP - e.g. $\sum_{i=1}^n (1 - q_i) \geq B$ for $B \approx n$.

- ! Learning in finite universes!
- ! Clustering as setting the stage for prediction (particular sense)
- ! Clusterwise constant hypothesis class
- ! Stability results in Learning
- ? Cluster-ability and Learnability
- ? Falsifiable vs. Reproducible
- ? Need for a taxonomy?