Distributed and Scalable OWL EL Reasoning

¹Raghava Mutharaju ¹Pascal Hitzler ¹Prabhaker Mateti ²Freddy Lécué

¹Wright State University, OH, USA.

²Smarter Cities Technology Centre, IBM Research, Dublin, Ireland.

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 - Normalization
 - Classification

3 Approach

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- Existing reasoners run on a single machine.
- They are constrained by the resources available to a single machine.
- Automatic generation of axioms result in very large ontologies.
 - streaming data (sensors, tweets)
 - text
- Additional axioms are generated during the reasoning process.
- Existing reasoners are overwhelmed by these large ontologies.

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- Most of description logic \mathcal{EL}^{++} is supported, which underlies OWL 2 EL profile.
- Axioms can have one of the following forms
 - $C \sqsubseteq D$, where C and D are defined by the grammar

$$C ::= A \mid \top \mid \bot \mid C \sqcap C \mid \exists r.C \mid \{a\}$$
$$D ::= A \mid \top \mid \bot \mid D \sqcap D \mid \exists r.D \mid \exists r.\{a\}$$

• $r_1 \circ \cdots \circ r_n \sqsubseteq r$

where A is a concept, r, r_i are roles, and a an individual.

• Axioms of the form $C \sqsubseteq \{a\}$ are **not** supported.



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All concept inclusions have one of the forms

- $A_1 \sqsubseteq B$
- $A_1 \sqcap \cdots \sqcap A_n \sqsubseteq B$
- $A_1 \sqsubseteq \exists r.A_2$
- $\exists r.A_1 \sqsubseteq B$

All role inclusions have one of the forms

• $r_1 \circ r_2 \sqsubseteq r_3$

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- We focus on the reasoning task called *classification*.
- It is the computation of the complete subsumption hierarchy,
 i.e. all logical consequences of the form A ⊑ B involving all concept names and nominals A and B.

• We use a set of rules to classify a given \mathcal{EL}^{++} ontology.

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Rn	Input	Action
R1	$A \sqsubseteq B$	$U[B] \cup = U[A]$
R2	$A_1 \sqcap \cdots \sqcap A_n \sqsubseteq B$	$U[B] \cup = U[A_1] \cap \cdots \cap U[A_n]$
R3	$A \sqsubseteq \exists r.B$	$R[r] \cup = \{(X,B) \mid X \in U[A]\}$
R4	$\exists r.A \sqsubseteq B$	$Q[r] \cup = \{(Y,B) \mid Y \in U[A]\}$
R5	R[r], Q[r]	$U[B] \cup = \{X \mid (X, Y) \in R[r]\}$
		and $(Y, B) \in Q[r]$ }
R6	R[r]	$U[\bot] \ \cup= \ \{X \mid (X,Y) \in R[r]$
		and $B \in U[\perp]$
R7	$r \sqsubseteq s$	$R[s] \cup = R[r]$
R8	$r \circ s \sqsubseteq t$	$R[t] \cup = \{(X,Z) \mid (X,Y) \in R[r]$
		and $(Y, Z) \in R[s]$ }

Table: Completion Rules

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- Input ontology \mathcal{O} can be partitioned into eight mutually disjoint ontologies, $\mathcal{O} = \mathcal{O}_1 \cup \cdots \cup \mathcal{O}_8$
- Ontology \mathcal{O}_i is assigned to a subcluster (subset of machines in the cluster) SC_i
- Rule Ri must be applied only on \mathcal{O}_i
- From the available machines, eight subclusters are created, one for each rule.
- O_i is further divided up among the machines in the subcluster (not duplicated).

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Rule Pr	ocesses					

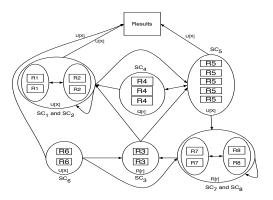


Figure: Node assignment to rules and dependency among the completion rules. For simplicity, only one node is shown to hold results.

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repeat

```
K_i := apply Ri on O_i once;
broadcast(K_i);
nUpdates := barrier-sum-of K_i;
until nUpdates = 0;
Algorithm 1: Wrapper for Ri
```

- K_i is associated with each Rule Ri.
- *K_i* is the number of updates made to result/intermediate sets.
- Barrier synchronization is used in waiting for K_i from all Ri
- If no rule process made an update, they quit; otherwise, they continue with another iteration.

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- **Dynamic Load Balancing:** Idle nodes take (steal) work from busy nodes.
- **Rule Dependencies:** Rule Ri need not be triggered again if the output from rules it is depending on does not change.
- Data Partitioning Strategy: Most of the data required for rule application is available locally on each node.

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- Implemented in Java and is called DistEL
- Redis is the key-value store that was used
- Available from http://github.com/raghavam/DistEL
- Amazon's EC2 m3.xlarge instances are used (4 cores, 15GB RAM). 5GB given to JVM.
- Machine configuration meant to reflect commodity hardware.

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Ontology	Before	After
GO	87,137	868,996
SNOMED	1,038,481	14,796,555
SNOMEDx2	2,076,962	29,593,106
SNOMED _x 3	3,115,443	44,389,657
SNOMED _{x5}	5,192,405	73,982,759
Traffic	7,151,328	21,840,440

Table: Number of axioms, before and after classification, in ontologies.

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Ontology	ELK	jCEL	Snorocket	Pellet	HermiT	FaCT++
GO	23.5	57.4	40.3	231.4	91.7	367.89
SNOMED	31.8	126.6	52.34	620.46	1273.7	1350.5
SNOMED _x 2	77.3	OOMª	OOMª	OOM ^a	OOMª	OOMª
SNOMED _x 3	OOM ^a	OOMª	OOMª	OOM ^a	OOMª	OOMª
SNOMED _{×5}	OOMª	OOMª	OOMª	OOM ^a	OOMª	OOMª
Traffic	OOM ^b	OOMc	OOMc	OOM ^b	OOM ^b	OOMc

Table: Classification times in seconds. OOM^a: reasoner runs out of memory. OOM^b: reasoner runs out of memory during incremental classification. OOM^c: ontology too big for OWL API to load in memory.

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Ontology	8 nodes	16 nodes	24 nodes	32 nodes	64 nodes
GO	134.49	114.66	109.46	156.04	137.31
SNOMED	544.38	435.79	407.38	386.00	444.19
SNOMEDx2	954.17	750.81	717.41	673.08	799.07
SNOMED _x 3	1362.88	1007.16	960.46	928.41	1051.80
SNOMED _{x5}	2182.16	1537.63	1489.34	1445.30	1799.13
Traffic	60004.54	41729.54	39719.84	38696.48	34200.17

Table: Classification time (in seconds) of DistEL

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Node	MB
R1	186.72
R2	0.81
R3	257.47
R4	0.79
R5	1970
R6	380.61
R7	0.79
R8	1470.00
Result	654.53
Total	4921.72

Table: Memory taken by Redis on each node for traffic data

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Nodes	Runtime	Speedup
8	544.38	1.00
16	435.79	1.24
24	407.38	1.33
32	386.00	1.41
64	444.19	1.22

Table: Speedup achieved by DistEL on SNOMED CT

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- This is a work-in-progress and more work needs to be done w.r.t performance improvements.
- Explore other ontology partitioning strategies as well as rule sets (ELK etc.).
- Fine grained analysis on larger datasets with higher number of nodes in the cluster.

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- Use multi-threading
- Alternatives to Redis including custom data structures.

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- Existing reasoners were not able to classify traffic data and other large ontologies.
- DistEL, a distributed reasoner is able to classify the large ontologies.

• It shows good speedup with increase in the number of machines in the cluster.

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