THE FORMATION OF HABITS The implicit supervision of the basal ganglia

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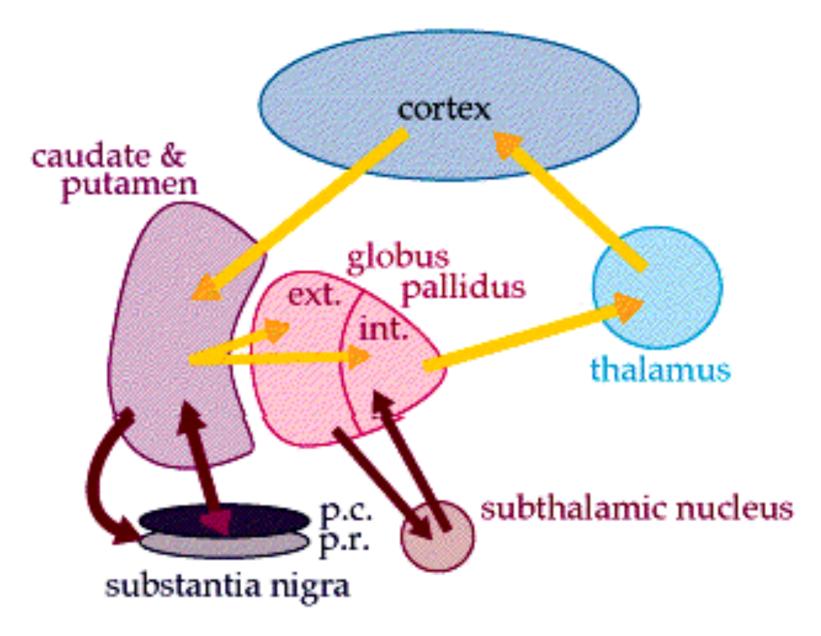
Goal-Directed Actions VS Habits



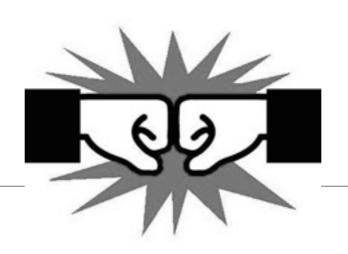
→ behavior adjusts to **reflect** the **new value** of the **outcome** that the action would obtain \rightarrow habits **persist** even if the **reward** becomes **less attra-ctive** or there is no reward at all.

Belin et al. (2008), Yin (2008), Foerde & Shohamy (2011), Doll et al. (2012)

Basal Ganglia



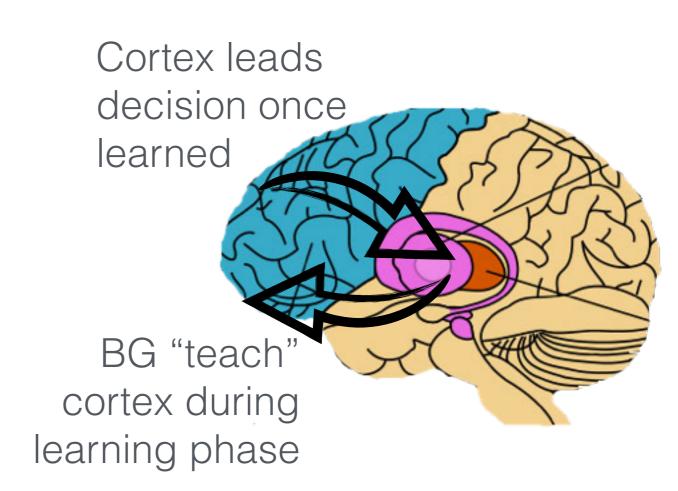
Cortex



Basal Ganglia

Goal Directed actions go here

Habits go there



Daw, Niv & Dayan (2005)

Ashby, Turner & Horvitz (2010)

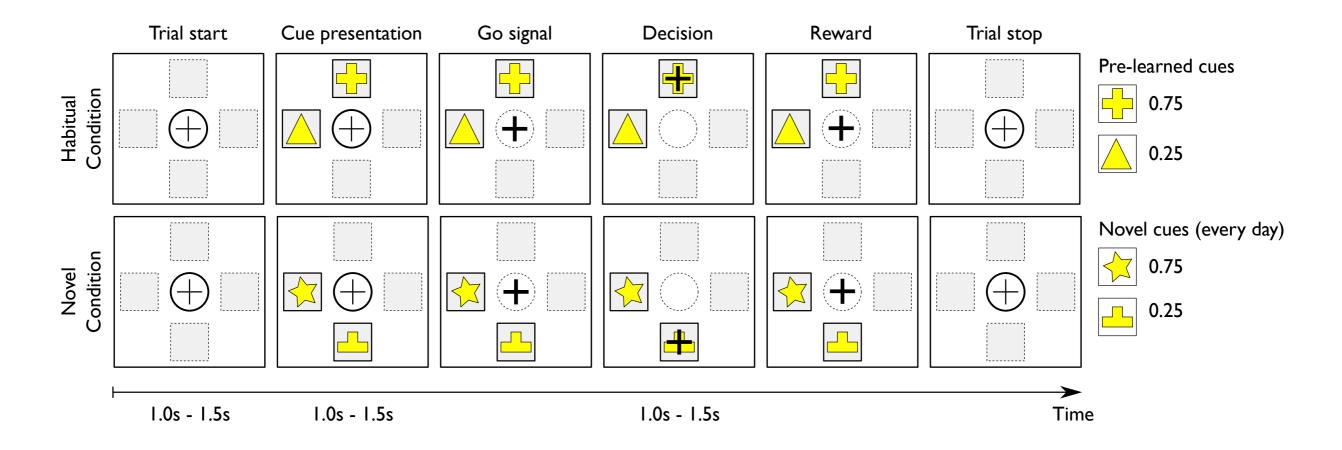
Outline

- Experiment
- Computational model
- Results

Experimental setup

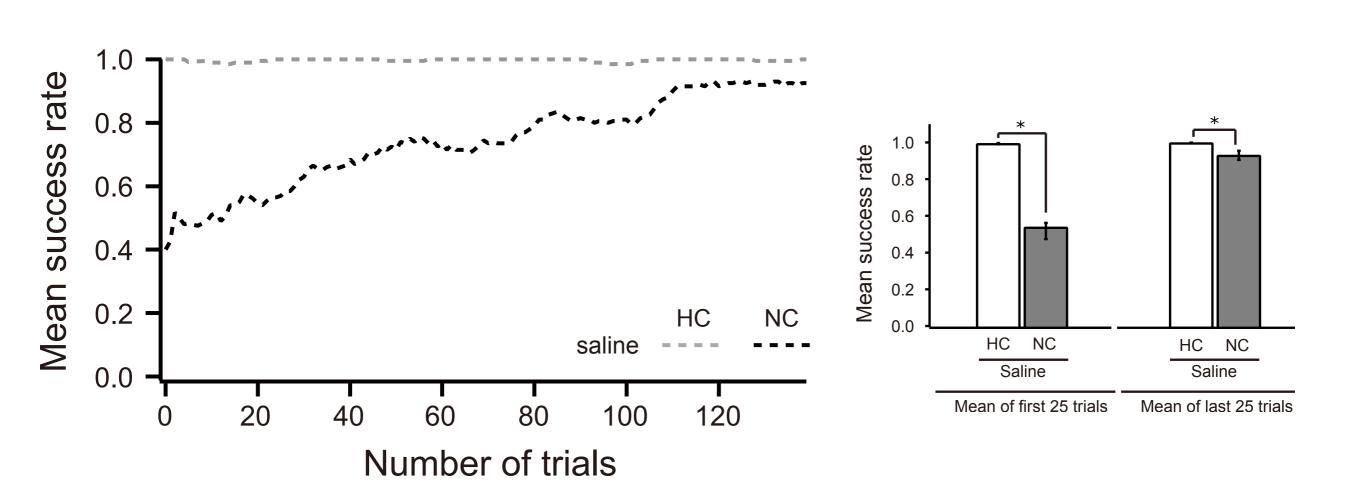
Two monkeys, simple two-armed bandit task with P=0.75 and P=0.25.

- → Habitual condition (known stimuli pair, same every day)
- → Novel condition (unfamiliar stimuli pair, new every day)



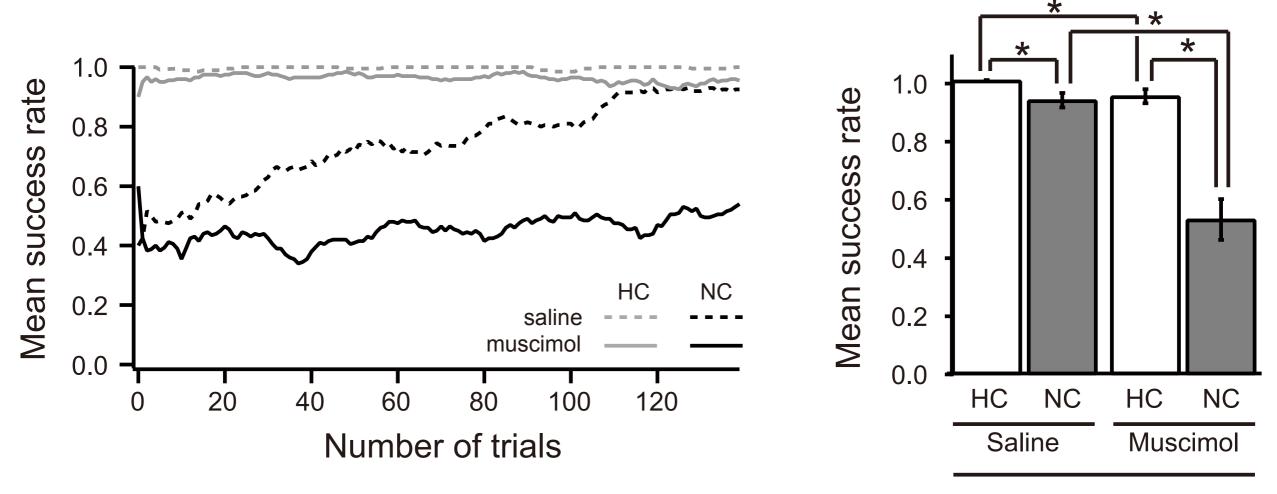
Piron et al. (submitted)

Experimental results



Experimental results

Muscimol injection in GPi disrupts learning in novel conditions (NC) but performances remains intact (but slower) in habitual conditions (HC).

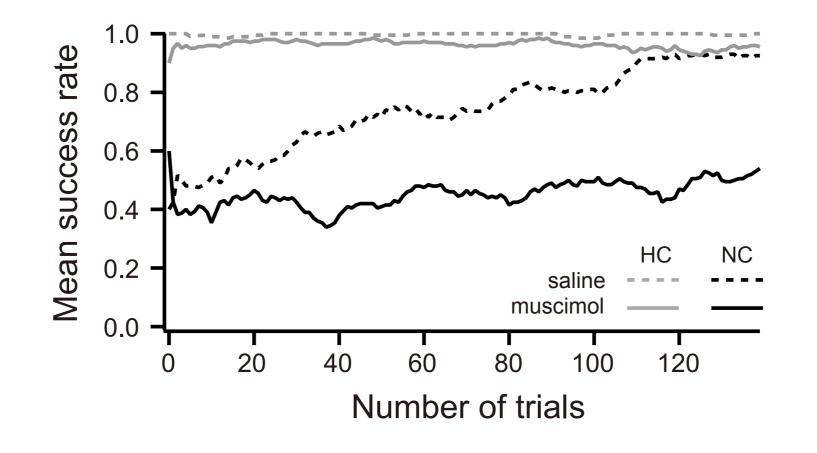


Mean of last 25 trials

Piron et al. (submitted)

If habits were stored in basal ganglia, monkeys would not achieve peak performances in muscimol conditions for familiar stimuli.

If habits were learned in cortex, monkeys would be able to reach peak performances in muscimol conditions for unfamiliar stimuli.



Piron et al. (submitted)

Computational model

Two segregated loops:

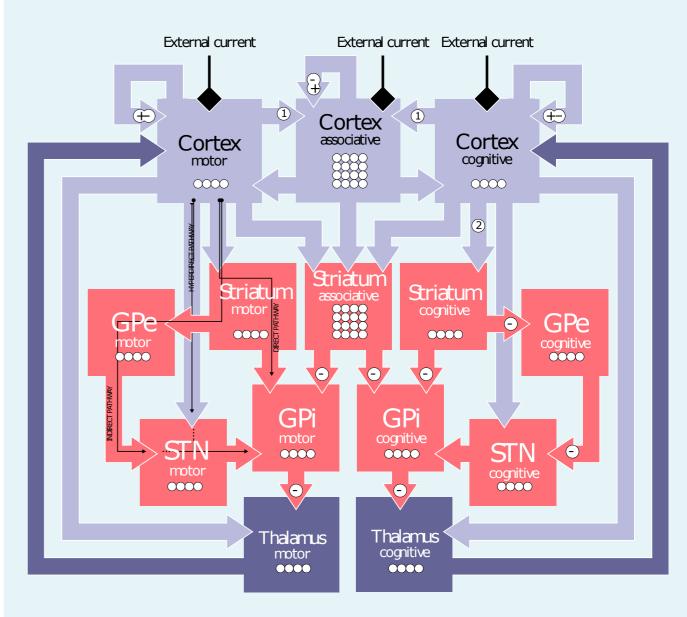
- → Cognitive loop allows to choose a shape
- → Motor loop allows to reach a shape

Cognitive decision has to **intervene** in motor decision.

Neural Network

Neuron Rate model

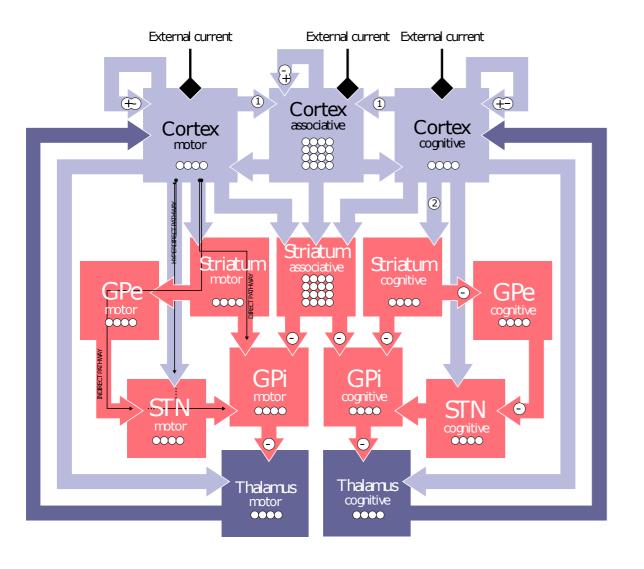
 $\tau \frac{dm}{dt} = -m + I_s - T$



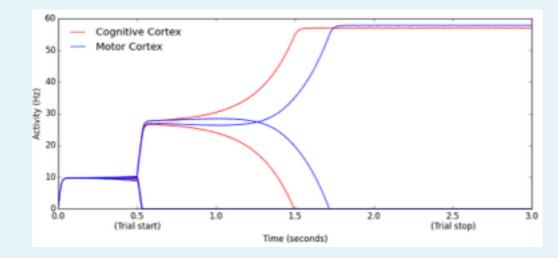
Topalidou et al. (in prep.)

Cortico-basal competition

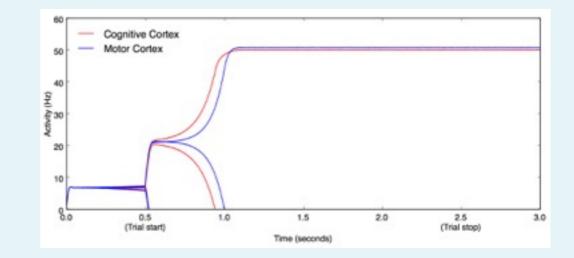
Thanks to lateral competition, cortex can make a decision without interaction with BG.



Cortical decision



Cortico-Basal decision



Topalidou et al. (in prep.)

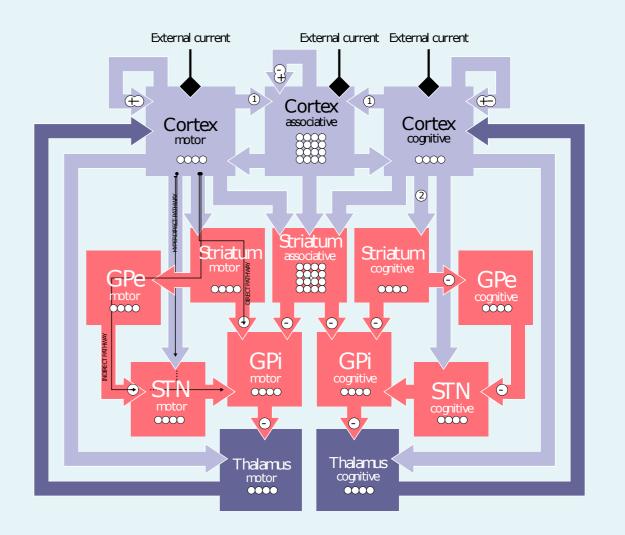
Acting is learning

Learning occurs at three different places simultaneously.

- 1 Hebbian learning
- ② Reinforcement learning

Cortex learns to reproduce previous repertories, regardless of whether are appropriate or not (HL).

Fast basal ganglia trial-and-error learning (RL) biases **slow** cortical one (HL) ensuring that the correct behavior is produced. $\begin{aligned} \tau \frac{dV}{dt} &= -V + I_{ext} + I_{syn}, U = f(V) \\ I_{syn}^{A \to B} &= \text{gain} \sum \times W_{A \to B} \times U_{A} \\ \text{Hebbian} (1) : \Delta W_{A \to B} &= U_{A} \times U_{B} \times (W_{A \to B} - W_{min}) \times (W_{max} - W_{A \to B}) \\ \text{Reinforcement} (2) : \Delta W_{A \to B} &= \alpha \times PE \times U_{B} \\ PE &= \text{Reward} - V_{i} \end{aligned}$



Barto (1995), Hélie et al. (2014), Topalidou et al. (in prep.)

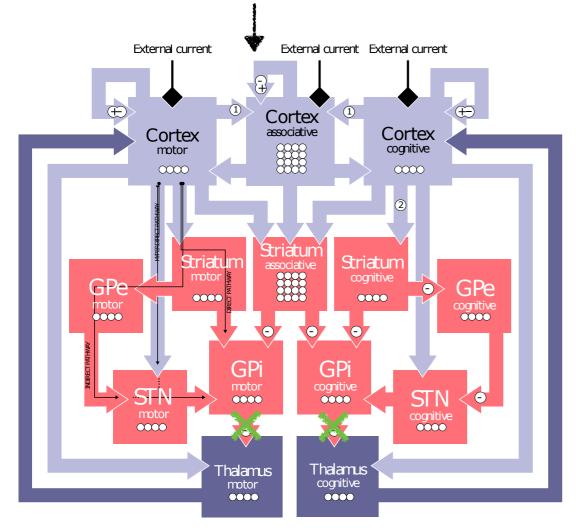
Computational results

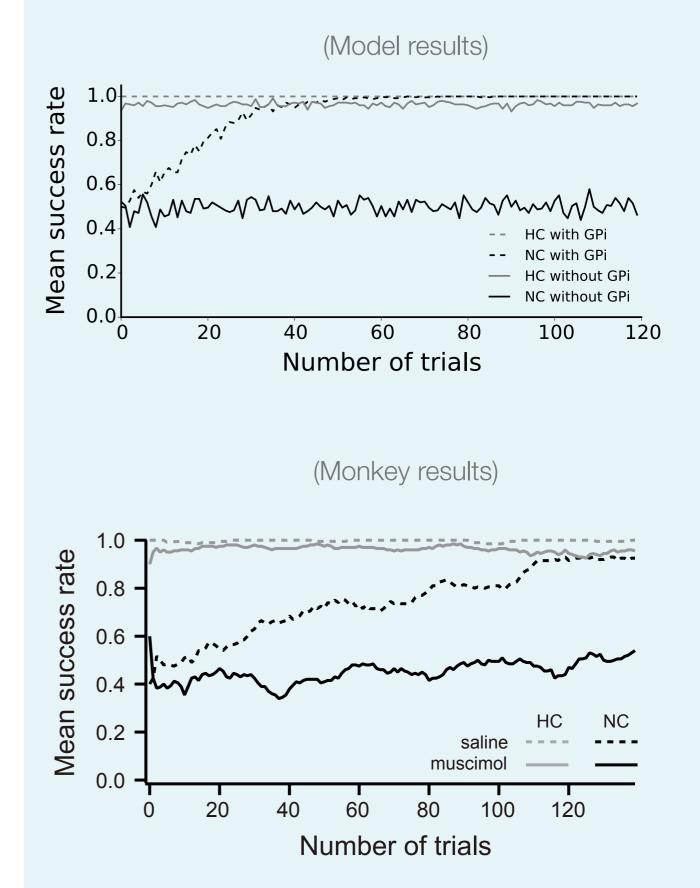
Intact model

- \rightarrow peak performances on familiar conditions
- → can learn novel conditions

Lesioned model (GPi)

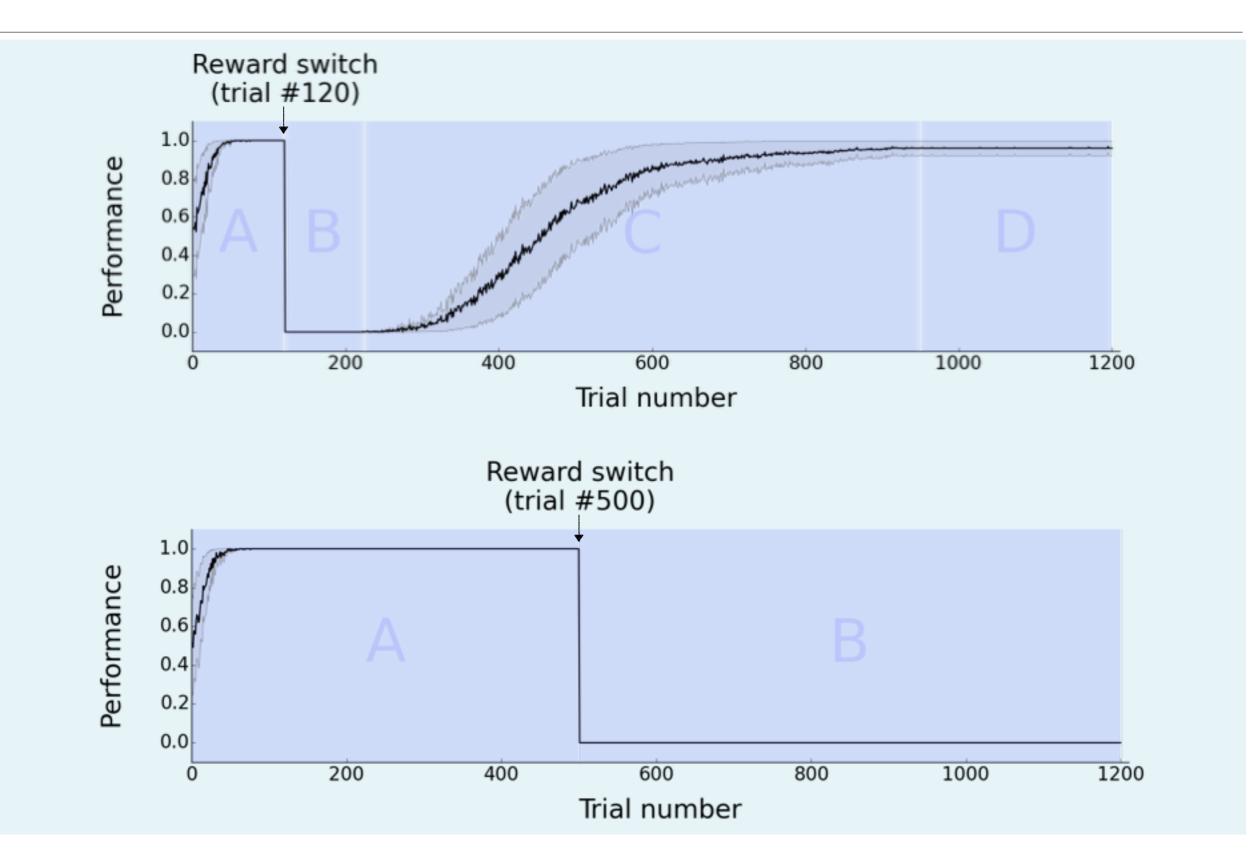
- \rightarrow peak performances on familiar conditions
- → cannot learn novel conditions





Topalidou et al. (in prep.)

Sensitivity to reward devaluation



Piron experiment sheds light on the nature of the interaction between the basal ganglia and the cortex and their respective role in the initial formation and the later expression of habits.

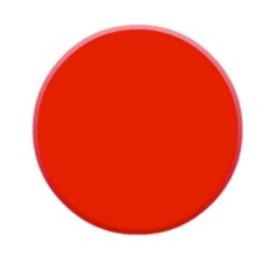
The model suggests that the basal ganglia implicitly supervises the learning in cortex where habits are actually stored, but the cortex cannot learn them on its own.

In the future, add more neurons per population, more complex motor cortex in order to include motor skill learning and test the model in a robot through Piron experiment and more complex tasks.

"We are what we repeatedly do; excellence, then, is not an act but a habit." - Aristotle.

Acknowledgments

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